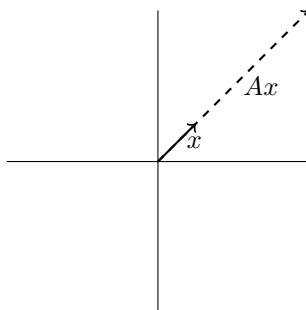


1/28: Introduction to Eigenvalues and Eigenvectors

- $Ax = b = \lambda x$
- $Ax = \lambda x, \lambda \in \mathbb{F}, x \in \mathbb{R}^n$
- λ is an eigenvalue. λx is an eigenvector.

$$A = \begin{bmatrix} 3 & 1 \\ 1 & 3 \end{bmatrix}$$

- $x = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ is an eigenvector of A with corresponding eigenvalue of 4.
- $\begin{bmatrix} 3 & 1 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 4 \\ 4 \end{bmatrix} = 4 \begin{bmatrix} 1 \\ 1 \end{bmatrix}$



$$Ax = \lambda x$$

$$Ax - \lambda x = 0$$

$$Ax - \lambda Ix = 0$$

$$(A - \lambda I)x = 0$$

- $(A - \lambda I)x = 0 \Rightarrow x \in N(A - \lambda I)^{[1]} \Rightarrow |A - \lambda I| = 0$

- $\begin{bmatrix} 3 & 1 \\ 1 & 3 \end{bmatrix} - \begin{bmatrix} \lambda & 0 \\ 0 & \lambda \end{bmatrix} = \begin{bmatrix} 3 - \lambda & 1 \\ 1 & 3 - \lambda \end{bmatrix}$

- $\begin{vmatrix} 3 - \lambda & 1 \\ 1 & 3 - \lambda \end{vmatrix} = 0$

$$\begin{aligned} 0 &= (3 - \lambda)^2 - 1^2 \\ &= 3^2 - 6\lambda + \lambda^2 - 1 \\ &= \lambda^2 - 6\lambda + 8 \\ &= (\lambda - 4)(\lambda - 2) \end{aligned}$$

- $\lambda = 4, 2$.
- $\lambda^2 - 6\lambda + 8$ is the **characteristic polynomial** of A .
- $A - 2I = \begin{bmatrix} -1 & 1 \\ 1 & -1 \end{bmatrix}, x = \begin{bmatrix} 1 \\ -1 \end{bmatrix} \in N(A - 2I)$.
- $A - 4I = \begin{bmatrix} -1 & 1 \\ 1 & -1 \end{bmatrix}, x = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \in N(A - 4I)$.

¹To have a null space, $A - \lambda I$ has free columns.

- “Eigenspace” is not \mathbb{R}^2 , but two lines in \mathbb{R}^2 , specifically $y = \pm x$.

$$- y = \pm x \text{ comes from } c_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} \text{ and } c_2 \begin{bmatrix} 1 \\ -1 \end{bmatrix}.$$

1/29:

$$A = \begin{bmatrix} 2 & -2 & 3 \\ 0 & 3 & -2 \\ 0 & -1 & 2 \end{bmatrix}$$

$$\begin{aligned} P(\lambda) &= |A - \lambda I| \\ &= \begin{vmatrix} 2-\lambda & -2 & 3 \\ 0 & 3-\lambda & -2 \\ 0 & -1 & 2-\lambda \end{vmatrix} \\ &= -1 \begin{vmatrix} 2-\lambda & 3 \\ 0 & -2 \end{vmatrix} (-1)^{3+2} + (2-\lambda) \begin{vmatrix} 2-\lambda & -2 \\ 0 & 3-\lambda \end{vmatrix} (-1)^{3+3} \\ &= ((2-\lambda)(-2)) + (2-\lambda)((2-\lambda)(3-\lambda)) \\ &= -4 + 2\lambda + (2-\lambda)^2(3-\lambda) \\ &= -4 + 2\lambda + (4 - 4\lambda + \lambda^2)(3-\lambda) \\ &= -4 + 2\lambda + 12 - 4\lambda - 12\lambda + 4\lambda^2 + 3\lambda^2 - \lambda^3 \\ &= -\lambda^3 + 7\lambda^2 - 14\lambda + 8 \\ &= -(\lambda - 1)(\lambda - 2)(\lambda - 4) \end{aligned}$$

$$A - I = \begin{bmatrix} 1 & -2 & 3 \\ 0 & 2 & -2 \\ 0 & -1 & 1 \end{bmatrix} \quad A - 2I = \begin{bmatrix} 0 & -2 & 3 \\ 0 & 1 & -2 \\ 0 & -1 & 0 \end{bmatrix} \quad A - 4I = \begin{bmatrix} -2 & -2 & 3 \\ 0 & -1 & -2 \\ 0 & -1 & -2 \end{bmatrix}$$

- $P(\lambda)$ is positive when $n \in 2\mathbb{N}$, negative otherwise.
 - Signs flip term to term (think about binomial expansion).
- Coefficients of the $n - 1$ degree term is the sum of the diagonal entries.
- Coefficient of the 0th degree term is $|A|$.
 - $P_\lambda(0) = |A - 0 \cdot I| = |A|$.
- Product of the eigenvalues is $|A|$.
 - Think about expanding the factorization.
- Eigenvalues of U are the diagonal values.
 - $\lambda_1 \lambda_2 \cdots \lambda_n = |A|$, which is the product of the diagonal entries.
 - $\lambda_1 + \cdots + \lambda_n = \text{trace}(A)$, which is the sum of the diagonal entries.
- $Ax = \lambda x$
 - $A^2x = AAx = A\lambda x = \lambda Ax = \lambda \lambda x = \lambda^2 x$

Similarity

1/30: • $A \sim B^{[2]}$ iff $\exists S : A = SBS^{-1}, B = S^{-1}AS$.

1. If $A \sim B$, then $|A| = |B|$.

$$\begin{aligned} B &= S^{-1}AS \\ |B| &= |S^{-1}AS| \\ |B| &= |S^{-1}||A||S| \\ |B| &= \frac{1}{|S|}|A||S| \\ |B| &= |A| \end{aligned}$$

2. If $A \sim B$, then they share the same characteristic polynomial.

$$\begin{aligned} B &= S^{-1}AS \\ |B - \lambda I| &= |S^{-1}AS - \lambda I| \\ &= |S^{-1}AS - \lambda S^{-1}IS| \\ &= |S^{-1}S(A - \lambda I)| \\ &= |I(A - \lambda I)| \\ |B - \lambda I| &= |A - \lambda I| \end{aligned}$$

– If they have the same characteristic polynomial, $\therefore A$ and B have the same eigenvalues.

• What is the best possible B if $A \sim B$?

- Sparse.
- Diagonal.

$$- A = [\text{ugly}] \rightarrow B = \begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix} = \Lambda$$

• **Diagonalization:**

$$\begin{aligned} A &= S\Lambda S^{-1} \\ AS &= S\Lambda \\ \Lambda &= S^{-1}AS \end{aligned}$$

• $A = S\Lambda S^{-1}$

$$- A^2 = AA = S\Lambda S^{-1}S\Lambda S^{-1} = S\Lambda\Lambda S^{-1} = S\Lambda^2 S^{-1}$$

$$- A^k = S\Lambda^k S^{-1}$$

$$- A^k = S \begin{bmatrix} \lambda_1^k & & 0 \\ & \ddots & \\ 0 & & \lambda_n^k \end{bmatrix} S^{-1}$$

• Diagonalize the following matrix A .

$$A = \begin{bmatrix} -1 & 0 & 1 \\ 3 & 0 & -3 \\ 1 & 0 & -1 \end{bmatrix}$$

² A “is similar to” B

- Find the characteristic polynomial.

$$\begin{aligned}
 |A - \lambda I| &= \begin{vmatrix} -1 - \lambda & 0 & 1 \\ 3 & 0 - \lambda & -3 \\ 1 & 0 & -1 - \lambda \end{vmatrix} \\
 &= (-1 - \lambda)((-\lambda)(-1 - \lambda)) + (-1)(-\lambda) \\
 &= -\lambda(-1 - \lambda)^2 + \lambda \\
 &= -\lambda(1 + 2\lambda + \lambda^2) + \lambda \\
 &= -\lambda^3 - 2\lambda^2 \\
 &= -\lambda^2(\lambda + 2)
 \end{aligned}$$

- Find the eigenvalues: $\lambda_1 = \lambda_2 = 0$, $\lambda_3 = -2$

- **Algebraic multiplicity** of λ_1, λ_2 is 2.

- A.M. of λ_3 is 1.

$$- A - 0I = \begin{bmatrix} -1 & 0 & 1 \\ 3 & 0 & -3 \\ 1 & 0 & -1 \end{bmatrix}$$

- $\text{rank}(A - 0I) = 1 \Rightarrow \dim(N(A - 0I)) = 2$

- The 2 directly above is the **geometric multiplicity**.

- A is diagonalizable iff A.M. of $\lambda_i = \text{G.M.}$

1/31:

$$- \text{Eigenvectors are } x_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \text{ and } x_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}.$$

$$- A + 2I = \begin{bmatrix} 1 & 0 & 1 \\ 3 & 2 & -3 \\ 1 & 0 & 1 \end{bmatrix}$$

$$- \text{Eigenvector is } x_3 = \begin{bmatrix} 1 \\ -3 \\ -1 \end{bmatrix}$$

- Use an S matrix of eigenvectors.

$$- A = SAS^{-1} = \frac{1}{2} \begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & -3 \\ 0 & 1 & -1 \end{bmatrix} \begin{bmatrix} 0 & & \\ & 0 & \\ & & -2 \end{bmatrix} \begin{bmatrix} 3 & 2 & -3 \\ 1 & 0 & 1 \\ 1 & 0 & -1 \end{bmatrix}$$

$$- \text{Note that } A^{9752} = \frac{1}{2} \begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & -3 \\ 0 & 1 & -1 \end{bmatrix} \begin{bmatrix} 0 & & \\ & 0 & \\ & & (-2)^{9752} \end{bmatrix} \begin{bmatrix} 3 & 2 & -3 \\ 1 & 0 & 1 \\ 1 & 0 & -1 \end{bmatrix}$$

- **Algebraic multiplicity:** The number of repeated roots to a polynomial. For all of the roots, it adds up to n (n -square matrix). *Also known as A.M.*
- **Geometric multiplicity:** The number of eigenvectors produced from each root. For all of the roots, it may not add up to n (n -square matrix). $\dim(N(A - \lambda I))$. *Also known as G.M.*
- A nondiagonalizable example:

$$A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 4 \end{bmatrix}$$

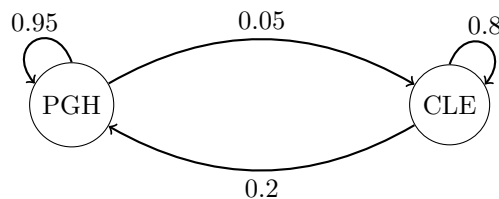
- $\lambda_1 = \lambda_2 = 1$ and $\lambda_3 = 4$.
- λ_1 and λ_2 have A.M. = 2.

- λ_3 has A.M. = 1.
- $A - I = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 3 \end{bmatrix}$
- $\text{rank}(A - I) = 2 \Rightarrow \dim(N(A - I)) = 1 \Rightarrow \text{G.M.} = \textcolor{red}{1}$.
- $x_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$
- $A - 4I = \begin{bmatrix} -3 & 1 & 0 \\ 0 & -3 & 1 \\ 0 & 0 & 0 \end{bmatrix}$
- $x_2 = \begin{bmatrix} 1 \\ 3 \\ 9 \end{bmatrix}$
- S would be 3×2 and, thus, not square, so $\nexists S^{-1}$ ^[3].

- **Canonical** (form): An accepted way of expressing something.

Markov Chains

2/3:



- $u_0 = \begin{bmatrix} 500,000 \\ 500,000 \end{bmatrix}$
- $Au_0 = u_1$.
- $Au_1 = u_2, A(Au_0) = u_2, A^2u_0 = u_2, A^k u_0 = u_k, (S\Lambda S^{-1})^k u_0 = u_k, S\Lambda^k S^{-1} u_0 = u_k$.

$$A = \begin{bmatrix} 0.95 & 0.20 \\ 0.05 & 0.80 \end{bmatrix} \quad u_k = \begin{bmatrix} \text{PGH} \\ \text{CLE} \end{bmatrix}$$

- A is a **Markov matrix**, where all columns and rows add to 1.
- $Au_0 = \begin{bmatrix} 0.95 & 0.20 \\ 0.05 & 0.80 \end{bmatrix} \begin{bmatrix} 500,000 \\ 500,000 \end{bmatrix} = u_1$

$$\begin{aligned}
 |A - \lambda I| &= \begin{vmatrix} 0.95 - \lambda & 0.20 \\ 0.05 & 0.80 - \lambda \end{vmatrix} \\
 &= (0.95 - \lambda)(0.80 - \lambda) - (0.20)(0.05) \\
 &= (\lambda - 1)(\lambda - 0.75)
 \end{aligned}$$

- $\lambda_1 = 1, \lambda_2 = 0.75$.

³At a later date, we will look at an analogy of projections to diagonalization that finds the “best possible” diagonalization (which may not be perfectly diagonal).

- $A - I = \begin{bmatrix} -0.05 & 0.2 \\ 0.05 & -0.2 \end{bmatrix} \Rightarrow x = \begin{bmatrix} 4 \\ 1 \end{bmatrix}$
- $A - 0.75I = \begin{bmatrix} 0.2 & 0.2 \\ 0.05 & 0.05 \end{bmatrix} \Rightarrow x = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$

$$\begin{aligned}
 A^k u_0 &= \frac{1}{5} \begin{bmatrix} 4 & -1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 0.75 \end{bmatrix}^k \begin{bmatrix} 1 & 1 \\ -1 & 4 \end{bmatrix} \begin{bmatrix} 500,000 \\ 500,000 \end{bmatrix} \\
 &= \begin{bmatrix} 4 & -1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 0.75^k \end{bmatrix} \begin{bmatrix} 200,000 \\ 300,000 \end{bmatrix} \\
 &= \begin{bmatrix} 4 \\ 1 \end{bmatrix} (200,000) + \begin{bmatrix} -1 \\ 1 \end{bmatrix} (0.75)^k (300,000)
 \end{aligned}$$

- $\begin{bmatrix} 800,000 \\ 200,000 \end{bmatrix}$ is the steady-state vector.
- $\begin{bmatrix} -(0.75)^k (300,000) \\ (0.75)^k (300,000) \end{bmatrix}$ is the dynamically changing vector.
- $\lim_{k \rightarrow \infty} A^k u_0 = \begin{bmatrix} 800,000 \\ 200,000 \end{bmatrix} = \begin{bmatrix} \text{PGH} \\ \text{CLE} \end{bmatrix}$