

### CHANGE OF BASIS AND SIMILARITY

$$T: \mathbb{R}^2 \rightarrow \mathbb{R}^2 : T \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} x+3y \\ 2x+2y \end{bmatrix}$$

Is it possible to find a basis  $B$  for  $\mathbb{R}^2$  such that the transformation matrix  $T$  is diagonal with respect to  $B$ ?

With respect to a standard basis,  $T_E = \begin{bmatrix} 1 & 3 \\ 2 & 2 \end{bmatrix}$ .

We can show that  $T_E = \begin{bmatrix} 1 & 3 \\ 2 & 2 \end{bmatrix}$  is diagonalizable into  $T_E = S\Lambda S^{-1}$ , in which  $\Lambda$  is a diagonal matrix.

$$\Lambda = \begin{bmatrix} 4 & 0 \\ 0 & -1 \end{bmatrix} \quad \text{and} \quad S = \begin{bmatrix} 1 & 3 \\ 1 & -2 \end{bmatrix}$$

If  $T_E = S\Lambda S^{-1}$ , then  $\Lambda = S^{-1} T_E S$ . Let  $B$  be the basis in  $\mathbb{R}^2$  consisting of the columns of  $S$ , then  $S$  is the change-of-basis matrix from  $B$  to  $E$ . Then

$$T_B = S^{-1} T_E S = \Lambda$$

Therefore the transformation matrix  $T$  with respect to the basis  $B = \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 3 \\ -2 \end{bmatrix} \right\}$  is diagonal.

$$T \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 4 \\ 4 \end{bmatrix} = 4 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + 0 \begin{bmatrix} 3 \\ -2 \end{bmatrix} \quad \text{and} \quad T \begin{bmatrix} 3 \\ -2 \end{bmatrix} = \begin{bmatrix} -3 \\ 2 \end{bmatrix} = 0 \begin{bmatrix} 1 \\ 1 \end{bmatrix} - 1 \begin{bmatrix} 3 \\ -2 \end{bmatrix}$$

So the vectors that form the columns of  $T_B$  are

$$\left[ T \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right]_B = \begin{bmatrix} 4 \\ 0 \end{bmatrix} \quad \text{and} \quad \left[ T \begin{bmatrix} 3 \\ -2 \end{bmatrix} \right]_B = \begin{bmatrix} 0 \\ -1 \end{bmatrix}$$

$T_E \sim T_B$  because when  $T:V \rightarrow W$ , changing a basis for  $V$  of transformation matrix  $A$  would require multiplication  $AM$  (multiply by  $M$  on the right to come first). Changing the basis for  $W$  would change  $A$  to  $M^{-1}A$  (to come last). Therefore, to change both bases the same way, the new matrix is  $B = M^{-1}AM$ . The good basis vectors are thus the eigenvectors of  $A$ , and  $B = M^{-1}AM$  becomes  $B = S^{-1}AS$ .

#### WORKING WITHIN A NON-STANDARD OR NON-EIGEN BASIS

$$T: P_2 \rightarrow P_2 : T(p(x)) = p(2x-1)$$

Find  $T$  with respect to basis  $B = 1+x, 1-x, x^2$

With respect to a standard basis :

$$T(1) = 1, T(x) = 2x-1, T(x^2) = (2x-1)^2 = 1-4x+4x^2$$

$$T(1)_E = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, T(x)_E = \begin{bmatrix} -1 \\ 2 \\ 0 \end{bmatrix}, [T(x^2)]_E = \begin{bmatrix} 1 \\ -4 \\ 4 \end{bmatrix}$$

$$\text{Therefore } T_E = \begin{bmatrix} 1 & -1 & 1 \\ 0 & 2 & -4 \\ 0 & 0 & 4 \end{bmatrix}$$

$$\text{The change of basis matrix from } B \text{ to } E \text{ is } \begin{bmatrix} 1 & 1 & 0 \\ 1 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Therefore it follows that  $T_B = M^{-1} T_E M$

$$= \begin{bmatrix} \frac{1}{2} & \frac{1}{2} & 0 \\ \frac{1}{2} & -\frac{1}{2} & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & -1 & 1 \\ 0 & 2 & -4 \\ 0 & 0 & 4 \end{bmatrix} \begin{bmatrix} 1 & 1 & 0 \\ 1 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & -\frac{3}{2} \\ -1 & 2 & \frac{5}{2} \\ 0 & 0 & 4 \end{bmatrix}$$

Find a basis  $C$  for  $P_2$  such that  $T_C$  is a diagonal matrix.

$T_E$  has eigenvalues 1, 2, and 4 with eigenvectors  $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}$

$$S = \begin{bmatrix} 1 & -1 & 1 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{bmatrix} \quad \text{and} \quad \Lambda = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 4 \end{bmatrix}$$

$S^{-1} T_E S = \Lambda$ , and therefore  $S$  is a change of basis matrix from a basis  $C$  to  $E$ .

Therefore  $C = 1, -1+x, 1-2x+x^2$