

Chapter 9

Functions of Several Variables

9.1 Notes

2/14:

- Plan:
 1. Warm-up with matrices.
 2. The total derivatives of $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ ($n = m = 2$, i.e., $f : \mathbb{C} \rightarrow \mathbb{C}$).
 3. Basic properties: Chain rule, relation with partial derivatives, implicit function theorem.
- Let V, W be finite-dimensional vector spaces over \mathbb{R} . We let $L(V, W)$ be the vector space of all linear transformations $\phi : V \rightarrow W$.
- If we pick bases $\mathbf{v}_1, \dots, \mathbf{v}_n$ of V and $\mathbf{w}_1, \dots, \mathbf{w}_m$ of W , then $V \cong \mathbb{R}^n$ and $W \cong \mathbb{R}^m$. It follows that $L(V, W) \cong \mathbb{R}^{mn}$.
- $L(V, W) \times L(W, U) \xrightarrow{\text{compose}} L(V, U)$, i.e., $\mathbb{R}^{mn} \times \mathbb{R}^{nl} \xrightarrow[\text{mult.}]{\text{matrix}} \mathbb{R}^{ml}$.
- Sup norm: If A is an $m \times n$ real matrix, then $\|A\| = \sup_{\substack{\mathbf{x} \in \mathbb{R}^n \\ |\mathbf{x}|=1}} |A\mathbf{x}|$.
 - Basic properties:
 1. $|A\mathbf{x}| \leq \|A\| |\mathbf{x}|$.
 2. $\|A\| < \infty$ and all $A : \mathbb{R}^n \rightarrow \mathbb{R}^m$ are uniformly continuous.
 3. $\|A\| = 0 \iff A = 0$.
 4. $\|cA\| = |c| \|A\|$.
 5. $\|A + B\| \leq \|A\| + \|B\|$.
 6. $\|AB\| \leq \|A\| \|B\|$.
 - Note that we get a metric space structure on $L(V, W)$ by defining $d(A, B) = \|A - B\|$.
- Proves that 1 and 2 imply the uniform continuity of all A (via Lipschitz continuity).
- **Differentiable** (function \mathbf{f} at \mathbf{x}_0): A function $\mathbf{f} : U \rightarrow \mathbb{R}^m$ ($U \subset \mathbb{R}^n$) such that to $\mathbf{x}_0 \in U$ there corresponds some linear transformation $A : \mathbb{R}^n \rightarrow \mathbb{R}^m$ such that
$$\lim_{\mathbf{h} \rightarrow \mathbf{0}} \frac{|\mathbf{f}(\mathbf{x}_0 + \mathbf{h}) - \mathbf{f}(\mathbf{x}_0) - A\mathbf{h}|}{|\mathbf{h}|} = 0$$
- **Total derivative** (of \mathbf{f} at \mathbf{x}_0): The linear transformation A in the above definition. Denoted by $\mathbf{f}'(\mathbf{x}_0)$, $D\mathbf{f}(\mathbf{x}_0)$, $d\mathbf{f}(\mathbf{x}_0)$.
- “An proof and progress in mathematics” - Thurston.

- Relating to the old one dimensional derivative.
- A paper we'd find rather impressionistic right now.

- Propositions ahead of us.

- Proposition: Suppose that \mathbf{f} is differentiable at $\mathbf{x}_0 \in U$ and A, B are both derivatives of \mathbf{f} at \mathbf{x}_0 . Then $A = B$.
- Proposition: Differentiable implies continuous.
- Proposition: Sum rule, product rule, quotient rule.

2/16:

- Plan: Derivatives of functions $\mathbf{f} : U \rightarrow \mathbb{R}^m$ where $U \subset \mathbb{R}^n$.

- Basic properties: Differentiability implies continuity, $(\mathbf{f} + \mathbf{g})' = \mathbf{f}' + \mathbf{g}'$, $(c\mathbf{f})' = c\mathbf{f}'$, chain rule, $\mathbf{f}' = 0$ iff \mathbf{f} is constant.
- Relationship with partial derivatives (how we compute everything and anything).
- When is \mathbf{f} differentiable?
- Inverse function theorem.
- Implicit function theorem.

- **Continuously differentiable** (function \mathbf{f}): A function $\mathbf{f} : U \rightarrow \mathbb{R}^m$ that is differentiable for all $\mathbf{x}_0 \in U$ and such that $\mathbf{f}' : U \rightarrow L(\mathbb{R}^n, \mathbb{R}^m)$ is continuous. *Also known as \mathcal{C}^1 .*

- Proposition: Let $\mathbf{f} : U \rightarrow \mathbb{R}^m$ be differentiable at $\mathbf{x}_0 \in U$. Then \mathbf{f} is continuous at \mathbf{x}_0 .

- The proof makes use of the fact that $\mathbf{f}(\mathbf{x}_0 + \mathbf{h}) - \mathbf{f}(\mathbf{x}_0) = \mathbf{f}'(\mathbf{x}_0)\mathbf{h} + \mathbf{r}(\mathbf{h})$.

- Proposition: Given $\mathbf{f}, \mathbf{g} : U \rightarrow \mathbb{R}^m$ both differentiable at $\mathbf{x}_0 \in U$, then $\mathbf{f} + \mathbf{g}$ is also differentiable at \mathbf{x}_0 with

$$(\mathbf{f} + \mathbf{g})'(\mathbf{x}_0) = \mathbf{f}'(\mathbf{x}_0) + \mathbf{g}'(\mathbf{x}_0)$$

- The proof is immediate via the triangle inequality.

- Theorem (Chain Rule): Given $\mathbf{f} : U \rightarrow \mathbb{R}^m$ and $\mathbf{g} : V \rightarrow \mathbb{R}^k$, where $U \subset \mathbb{R}^n$ and $\mathbf{f}(U) \subset V \subset \mathbb{R}^m$, with \mathbf{f} differentiable at $\mathbf{x}_0 \in U$ and \mathbf{g} differentiable at $\mathbf{f}(\mathbf{x}_0)$, the composition $\mathbf{g} \circ \mathbf{f}$ is differentiable at \mathbf{x}_0 with

$$(\mathbf{g} \circ \mathbf{f})'(\mathbf{x}_0) = \mathbf{g}'(\mathbf{f}(\mathbf{x}_0)) \cdot \mathbf{f}'(\mathbf{x}_0)$$

- The proof is rather subtle.

- **Partial derivative** (of f_i wrt. x_j at \mathbf{x}_0): The following limit, if it exists, where $f_i : \mathbb{R}^n \rightarrow \mathbb{R}$, $1 \leq i \leq m$, and $1 \leq j \leq n$. Denoted by $(\partial \mathbf{f}_i / \partial x_j)(\mathbf{x}_0)$, $(D_j \mathbf{f}_i)(\mathbf{x}_0)$. Given by

$$\frac{\partial f_i}{\partial x_j}(\mathbf{x}_0) = \lim_{t \rightarrow 0} \frac{f_i(\mathbf{x}_0 + t\mathbf{e}_j) - f_i(\mathbf{x}_0)}{t}$$

- **Directional derivative** (of f_i toward $\mathbf{u} \in \mathbb{R}^n$): The following limit, if it exists, where $f_i : \mathbb{R}^n \rightarrow \mathbb{R}$ and $1 \leq i \leq m$. Denoted by $D_{\mathbf{u}} \mathbf{f}_i$. Given by

$$D_{\mathbf{u}} f_i = \lim_{t \rightarrow 0} \frac{f_i(\mathbf{x}_0 + t\mathbf{u}) - f_i(\mathbf{x}_0)}{t}$$

- **Jacobian**: The following matrix. Given by

$$\left[\frac{\partial f_i}{\partial x_j}(\mathbf{x}_0) \right]$$

- Theorem: Let $\mathbf{f} = (f_1, \dots, f_m) : U \rightarrow \mathbb{R}^m$, where $U \subset \mathbb{R}^n$, be differentiable at some $\mathbf{x}_0 \in U$. Then the partial derivatives $\partial f_i / \partial x_j$ ($1 \leq i \leq m$; $1 \leq j \leq n$) exist at \mathbf{x}_0 and, with respect to the usual choice of bases,

$$\mathbf{f}'(\mathbf{x}_0) = \left[\frac{\partial f_i}{\partial x_j}(\mathbf{x}_0) \right]$$

2/18: – We have that

$$\mathbf{f}(\mathbf{x}_0 + t\mathbf{e}_j) - \mathbf{f}(\mathbf{x}_0) = \mathbf{f}'(\mathbf{x}_0)(t\mathbf{e}_j) + \mathbf{r}(t\mathbf{e}_j)$$

- Since \mathbf{f} is differentiable at \mathbf{x}_0 , $\mathbf{f}(t\mathbf{e}_j)/t \rightarrow 0$ as $t \rightarrow 0$.
- Additionally, $\mathbf{f}'(\mathbf{x}_0)(t\mathbf{e}_j)/t = \mathbf{f}'(\mathbf{x}_0)(\mathbf{e}_j)$.
- Therefore,

$$\lim_{t \rightarrow 0} \frac{\mathbf{f}(\mathbf{x}_0 + t\mathbf{e}_j) - \mathbf{f}(\mathbf{x}_0)}{t} = \lim_{t \rightarrow 0} \frac{\mathbf{f}'(\mathbf{x}_0)(t\mathbf{e}_j) - \mathbf{r}(t\mathbf{e}_j)}{t} = \mathbf{f}'(\mathbf{x}_0)(\mathbf{e}_j) - \lim_{t \rightarrow 0} \frac{\mathbf{r}(t\mathbf{e}_j)}{t} = \mathbf{f}'(\mathbf{x}_0)(\mathbf{e}_j)$$

as desired.

- Unpacking the definition of the linear transformation as a matrix gives the rest of the proof.

- Today:
 - More on differentiation (recall the Jacobian).
 - Sufficient condition for differentiability.
 - $\mathbf{f}' = 0$ iff \mathbf{f} is constant.
 - State the inverse function theorem.
- It is not true that having all partials exist implies that \mathbf{f} is differentiable at \mathbf{x}_0 .
- Theorem: \mathbf{f} continuously differentiable at \mathbf{x}_0 iff all partials exist and are continuous at \mathbf{x}_0 .
- Theorem (Inverse function theorem): If $E \subset \mathbb{R}^n$ open, $\mathbf{f} : E \rightarrow \mathbb{R}^n$ is differentiable at $\mathbf{x}_0 \in E$, and $\mathbf{f}'(\mathbf{x}_0)$ is invertible, then there exist $U \subset E$ open with $\mathbf{x}_0 \in U$ and $V \subset \mathbb{R}^n$ open with $\mathbf{f}(\mathbf{x}_0) \in V$ such that $\mathbf{f}|_U : U \rightarrow V$ is a bijection and $(\mathbf{f}|_U)^{-1}$ is continuously differentiable.

9.2 Chapter 9: Functions of Several Variables

From Rudin (1976).

- 2/15:
- Defines a vector space by the closure of its elements under addition and scalar multiplication.
 - Defines a linear combination, span, independence and dependence, dimension, basis, coordinates, and the standard basis.
 - Theorem 9.2: If X is spanned by r vectors, $\dim X \leq r$.
 - Corollary: $\dim \mathbb{R}^n = n$.
 - Theorem 9.3: Let X a vector space with $\dim X = n$.
 - (a) $E \subset X$ containing n vectors spans X iff E is independent.
 - (b) X has a basis, and every basis contains n vectors.
 - (c) If $1 \leq r \leq n$ and $\{\mathbf{y}_1, \dots, \mathbf{y}_r\}$ is independent in X , then X has a basis containing $\{\mathbf{y}_1, \dots, \mathbf{y}_r\}$.
 - Defines linear transformation, linear operator.
 - Notes that $A\mathbf{0} = \mathbf{0}$ if A is a linear transformation, and that A is completely determined by its action on any basis.

- **Invertible** (linear operator): A linear operator A that is one-to-one and onto.
- Theorem 9.5: A a linear operator on X finite-dimensional is one-to-one iff it is onto.
- Defines $L(X, Y)$, $L(X)$, the product BA of two linear transformations, and the supremum norm of a linear transformation.
- Theorem 9.7:
 - (a) $A \in L(\mathbb{R}^n, \mathbb{R}^m)$ implies $\|A\| < \infty$ and $A : \mathbb{R}^n \rightarrow \mathbb{R}^m$ uniformly continuous.
 - (b) $A, B \in L(\mathbb{R}^n, \mathbb{R}^m)$ and $c \in \mathbb{C}$ implies

$$\|A + B\| \leq \|A\| + \|B\| \qquad \|cA\| = |c|\|A\|$$

Defining $d(A, B) = \|A - B\|$ makes $L(\mathbb{R}^n, \mathbb{R}^m)$ a metric space.

- (c) $A \in L(\mathbb{R}^n, \mathbb{R}^m)$ and $B \in L(\mathbb{R}^m, \mathbb{R}^k)$ implies

$$\|BA\| \leq \|B\|\|A\|$$

- Theorem 9.8: Let Ω be the set of all invertible linear operators on \mathbb{R}^n .

- (a) $A \in \Omega$, $B \in L(\mathbb{R}^n)$, and $\|B - A\| \cdot \|A^{-1}\| < 1$ implies $B \in \Omega$.

Proof. Let $\|A^{-1}\| = 1/\alpha$, and let $\|B - A\| = \beta$. Then

$$\begin{aligned} \|B - A\| \cdot \|A^{-1}\| &< 1 \\ \beta \cdot \frac{1}{\alpha} &< 1 \\ \beta &< \alpha \end{aligned}$$

To prove that $B \in \Omega$, the definition of invertibility and Theorem 9.5 tell us that it will suffice to show that B is 1-1. To do so, it will suffice to show that $B\mathbf{x} = \mathbf{0}$ iff $\mathbf{x} = \mathbf{0}$. Let's begin. Let $\mathbf{x} \in \mathbb{R}^n$ be arbitrary. Then

$$\begin{aligned} \alpha|\mathbf{x}| &= \alpha|A^{-1}A\mathbf{x}| \leq \alpha\|A^{-1}\| \cdot |A\mathbf{x}| = |A\mathbf{x}| \leq |(A - B)\mathbf{x}| + |B\mathbf{x}| \leq \beta|\mathbf{x}| + |B\mathbf{x}| \\ (\alpha - \beta)|\mathbf{x}| &\leq |B\mathbf{x}| \end{aligned}$$

It follows that if $\mathbf{x} \neq \mathbf{0}$, then $|B\mathbf{x}| > 0$. This combined with the fact that $B\mathbf{0} = \mathbf{0}$ implies the desired result. \square

- (b) Ω is open in $L(\mathbb{R}^n)$ and $A \mapsto A^{-1}$ is continuous on Ω .

Proof. To prove that Ω is open in $L(\mathbb{R}^n)$, it will suffice to show that for all $A \in \Omega$, there exists $N_r(A)$ such that if $\|B - A\| < r$, then $B \in \Omega$. Let's begin. Let $A \in \Omega$ be arbitrary. Choose $N_\alpha(A)$ to be our neighborhood, where α is defined as in part (a). Let $B \in L(\mathbb{R}^n)$ satisfy $\|B - A\| < \alpha$. Then $\|B - A\| \cdot \|A^{-1}\| < 1$, so $B \in \Omega$ by part (a), as desired.

To prove that $A \mapsto A^{-1}$ is continuous, it will suffice to show that $\|B^{-1} - A^{-1}\| \rightarrow 0$ as $B \rightarrow A$. First off, we have by part (a) and the substitution $\mathbf{x} = B^{-1}\mathbf{y}$ ($\mathbf{y} \in \mathbb{R}^n$) that

$$\begin{aligned} (\alpha - \beta)|B^{-1}\mathbf{y}| &\leq |BB^{-1}\mathbf{y}| = |\mathbf{y}| \\ \left| B^{-1} \left(\frac{\mathbf{y}}{|\mathbf{y}|} \right) \right| &\leq (\alpha - \beta)^{-1} \end{aligned}$$

Thus, since $|B^{-1}\mathbf{u}|$ is bounded by $(\alpha - \beta)^{-1}$ for every unit vector $\mathbf{u} \in \mathbb{R}^n$, $\|B^{-1}\|$ is bounded by $(\alpha - \beta)^{-1}$. This combined with the fact that

$$\begin{aligned} B^{-1} - A^{-1} &= B^{-1}I - IA^{-1} \\ &= B^{-1}AA^{-1} - B^{-1}BA^{-1} \\ &= B^{-1}(A - B)A^{-1} \end{aligned}$$

implies by Theorem 9.7c that

$$\|B^{-1} - A^{-1}\| \leq \|B^{-1}\| \|A - B\| \|A^{-1}\| \leq (\alpha - \beta)^{-1} \cdot \beta \cdot \frac{1}{\alpha} = \frac{\beta}{\alpha(\alpha - \beta)}$$

Therefore, since $\beta \rightarrow 0$ as $B \rightarrow A$, the above inequality establishes the desired result. \square

- Note that the mapping $A \mapsto A^{-1}$ defined in Theorem 9.8b is a 1-1 mapping of Ω onto Ω and its own inverse.
- Defines matrices, column vectors, and matrix multiplication.
- From the Schwarz inequality, we can show that

$$\|A\| \leq \left(\sum_{i,j} a_{i,j}^2 \right)^{1/2}$$

- “If S is a metric space, if a_{11}, \dots, a_{mn} are real continuous functions on S , and if for each $p \in S$, A_p is the linear transformation of \mathbb{R}^n into \mathbb{R}^m whose matrix has entries $a_{ij}(p)$, then the mapping $p \rightarrow A_p$ is a continuous mapping of S into $L(\mathbb{R}^n, \mathbb{R}^m)$ ” (Rudin, 1976, p. 211).
- Rudin (1976) spends some time motivating the definition of the total derivative. He also discusses the natural 1-1 correspondence between \mathbb{R}^1 and $L(\mathbb{R}^1)$.
- Defines differentiability in \mathbb{R}^n .
- Theorem 9.12: A_1, A_2 the derivative of \mathbf{f} at \mathbf{x} implies $A_1 = A_2$.
- If $\mathbf{f} : E \rightarrow \mathbb{R}^m$ where $E \subset \mathbb{R}^n$, then $\mathbf{f}' : E \rightarrow L(\mathbb{R}^n, \mathbb{R}^m)$.
- \mathbf{f} differentiable implies \mathbf{f} continuous.
- Example (\mathbf{f} is linear):

– If $A \in L(\mathbb{R}^n, \mathbb{R}^m)$, then $A'(\mathbf{x}) = A$ for all $\mathbf{x} \in \mathbb{R}^n$. Note that this means that $A' : \mathbb{R}^n \rightarrow L(\mathbb{R}^n, \mathbb{R}^m)$, as expected.

- Theorem 9.15 (Chain Rule): E open in \mathbb{R}^n , $\mathbf{f} : E \rightarrow \mathbb{R}^m$ differentiable at $\mathbf{x}_0 \in E$, $I \supset \mathbf{f}(E)$ open in \mathbb{R}^m , and $\mathbf{g} : I \rightarrow \mathbb{R}^k$ differentiable at $\mathbf{f}(\mathbf{x}_0)$ implies $\mathbf{F} : E \rightarrow \mathbb{R}^k$ defined by

$$\mathbf{F}(\mathbf{x}) = \mathbf{g}(\mathbf{f}(\mathbf{x}))$$

is differentiable at \mathbf{x}_0 with

$$\mathbf{F}'(\mathbf{x}_0) = \mathbf{g}'(\mathbf{f}(\mathbf{x}_0))\mathbf{f}'(\mathbf{x}_0)^{[1]}$$

Proof. Largely symmetric to that of the one-dimensional chain rule in Chapter 5. \square

- **Components** (of $\mathbf{f} : \mathbb{R}^n \rightarrow \mathbb{R}^m$): The real functions f_1, \dots, f_m defined by

$$\mathbf{f}(\mathbf{x}) = \sum_{i=1}^m f_i(\mathbf{x}) \mathbf{u}_i$$

for all $\mathbf{x} \in E$ or, equivalently, by $f_i(\mathbf{x}) = \mathbf{f}(\mathbf{x}) \cdot \mathbf{u}_i$ ($1 \leq i \leq m$), where $\mathbf{u}_1, \dots, \mathbf{u}_m$ is the standard basis of \mathbb{R}^m .

¹Note that the right-hand side of this equation contains the product of two linear transformations.

- Defines partial derivatives.
- Theorem 9.17: $E \subset \mathbb{R}^n$ open and $\mathbf{f} : E \rightarrow \mathbb{R}^m$ differentiable at $\mathbf{x} \in E$ imply the partial derivatives $(D_j f_i)(\mathbf{x})$ exist and

$$\mathbf{f}'(\mathbf{x})\mathbf{e}_j = \sum_{i=1}^m (D_j f_i)(\mathbf{x})\mathbf{u}_i$$

for $1 \leq j \leq n$.

- It follows that

$$[\mathbf{f}'(\mathbf{x})] = \begin{bmatrix} (D_1 f_1)(\mathbf{x}) & \cdots & (D_n f_1)(\mathbf{x}) \\ \vdots & & \vdots \\ (D_1 f_m)(\mathbf{x}) & \cdots & (D_n f_m)(\mathbf{x}) \end{bmatrix}$$

- Discusses the gradient and the directional derivative.
- Theorem 9.19: $E \subset \mathbb{R}^n$ convex and open, $\mathbf{f} : E \rightarrow \mathbb{R}^m$ differentiable in E , and there exists M such that

$$\|\mathbf{f}'(\mathbf{x})\| \leq M$$

for all $\mathbf{x} \in E$ implies

$$|\mathbf{f}(\mathbf{b}) - \mathbf{f}(\mathbf{a})| \leq M|\mathbf{b} - \mathbf{a}|$$

for all $\mathbf{a}, \mathbf{b} \in E$.

- Corollary: If, in addition, $\mathbf{f}'(\mathbf{x}) = \mathbf{0}$ for all $\mathbf{x} \in E$, then \mathbf{f} is constant.
- **Continuously differentiable** (mapping $\mathbf{f} : E \rightarrow \mathbb{R}^m$): A function $\mathbf{f} : E \rightarrow \mathbb{R}^m$ such that $\mathbf{f}' : E \rightarrow L(\mathbb{R}^n, \mathbb{R}^m)$ is continuous. *Also known as \mathcal{C}^1 -mapping. Denoted by $\mathbf{f} \in \mathcal{C}^1(E)$.*
- Theorem 9.21: Let $E \subset \mathbb{R}^n$ open and $\mathbf{f} : E \rightarrow \mathbb{R}^m$. Then $\mathbf{f} \in \mathcal{C}^1(E)$ iff the partial derivatives $D_j f_i$ ($1 \leq i \leq m; 1 \leq j \leq n$) exist and are continuous on E .

2/20:

- **Contraction** (of X into X): A function $\varphi : X \rightarrow X$ for which there exists a number $c < 1$ such that

$$d(\varphi(x), \varphi(y)) \leq c \cdot d(x, y)$$

for all $x, y \in X$, where X is a metric space with metric d .

- Theorem 9.23: X a complete metric space and ϕ a contraction of X into X implies there exists a unique $x \in X$ such that $\varphi(x) = x$.

Proof. Let $x_0 \in X$ be arbitrary. Define $\{x_n\}$ recursively by

$$x_{n+1} = \phi(x_n)$$

for $n = 0, 1, 2, \dots$. Let $c < 1$ be the number corresponding to the contraction φ . Then for $n \geq 1$, we have

$$d(x_{n+1}, x_n) = d(\varphi(x_n), \varphi(x_{n-1})) \leq c \cdot d(x_n, x_{n-1})$$

or, for $n \geq 0$,

$$d(x_{n+1}, x_n) \leq c^n d(x_1, x_0)$$

by induction. Now to prove that $\{x_n\}$ is Cauchy, it will suffice to show that for all $\epsilon > 0$, there exists N such that $m \geq n \geq N$ implies $d(x_n, x_m) < \epsilon$. But since

$$\begin{aligned} d(x_n, x_m) &\leq \sum_{i=n+1}^m d(x_i, x_{i-1}) \\ &\leq (c^n + c^{n+1} + \cdots + c^{m-1})d(x_1, x_0) \\ &\leq [(1-c)^{-1}d(x_1, x_0)]c^n \end{aligned}$$

we can simply choose N large enough that $[(1-c)^{-1}d(x_1, x_0)]c^N < \epsilon$. Thus, since $\{x_n\}$ is Cauchy and X is complete, there exists $x \in X$ such that $\lim_{n \rightarrow \infty} x_n = x$. Therefore, since φ is Lipschitz continuous, we have that

$$\varphi(x) = \lim_{n \rightarrow \infty} \varphi(x_n) = \lim_{n \rightarrow \infty} x_{n+1} = x$$

as desired.

Now suppose for the sake of contradiction that there exists $y \neq x$ such that $\varphi(y) = y$. Then since φ is a contraction,

$$d(y, x) = d(\varphi(y), \varphi(x)) \leq c \cdot d(y, x) < d(y, x)$$

a contradiction. \square

- Theorem 9.24 (Inverse Function Theorem): $E \subset \mathbb{R}^n$ open, $\mathbf{f} : E \rightarrow \mathbb{R}^n$ a \mathcal{C}^1 -mapping, $\mathbf{f}'(\mathbf{a})$ invertible for some $\mathbf{a} \in E$, and $\mathbf{b} = \mathbf{f}(\mathbf{a})$ implies

- (a) There exist $U, V \subset \mathbb{R}^n$ open with $\mathbf{a} \in U$, $\mathbf{b} \in V$ such that \mathbf{f} is 1-1 on U and $\mathbf{f}(U) = V$.

Proof. Let $A = \mathbf{f}'(\mathbf{a})$. Choose λ such that

$$2\lambda\|A^{-1}\| = 1$$

Define^[2] for each $\mathbf{y} \in \mathbb{R}^n$ a function φ by

$$\varphi(\mathbf{x}) = \mathbf{x} + A^{-1}(\mathbf{y} - \mathbf{f}(\mathbf{x}))$$

for all $\mathbf{x} \in E$. (Note that a key property of φ is that as defined, $\mathbf{f}(\mathbf{x}) = \mathbf{y}$ iff \mathbf{x} is a fixed point of φ .) Now since $\mathbf{f} \in \mathcal{C}^1$ and hence \mathbf{f}' is continuous at \mathbf{a} , there exists an open ball $B_r(\mathbf{a}) \subset E$ such that

$$\|\mathbf{f}'(\mathbf{x}) - A\| < \lambda$$

for all $\mathbf{x} \in B_r(\mathbf{a})$. Let $U = B_r(\mathbf{a})$. Clearly it follows that U is open. Thus, since each $\varphi'(\mathbf{x}) = I - A^{-1}\mathbf{f}'(\mathbf{x}) = A^{-1}(A - \mathbf{f}'(\mathbf{x}))$, we have that

$$\|\varphi'(\mathbf{x})\| \leq \|A^{-1}\| \|A - \mathbf{f}'(\mathbf{x})\| < \frac{1}{2\lambda} \cdot \lambda = \frac{1}{2}$$

Consequently, we have by Theorem 9.19 that for all $\mathbf{x}_1, \mathbf{x}_2 \in U$,

$$|\varphi(\mathbf{x}_1) - \varphi(\mathbf{x}_2)| \leq \frac{1}{2}|\mathbf{x}_1 - \mathbf{x}_2|$$

Thus, by the uniqueness argument in the proof of Theorem 9.23, φ has at most one fixed point in U , so $\mathbf{f}(\mathbf{x}) = \mathbf{y}$ for at most one $\mathbf{x} \in U$. Therefore, \mathbf{f} is 1-1 on U .

Let $V = \mathbf{f}(U)$. To prove that V is open, it will suffice to show that for all $\mathbf{y}_0 \in V$, there exists an open subset of V containing \mathbf{y}_0 such that. Let $\mathbf{y}_0 \in V$ be arbitrary. By the definition of V as the image of U under \mathbf{f} , there exists $\mathbf{x}_0 \in U$ such that $\mathbf{f}(\mathbf{x}_0) = \mathbf{y}_0$. As such, choose $B_r(\mathbf{x}_0)$ such that $\overline{B} \subset U$. Pick \mathbf{y} satisfying $|\mathbf{y} - \mathbf{y}_0| < \lambda r$. Then

$$|\varphi(\mathbf{x}_0) - \mathbf{x}_0| = |A^{-1}(\mathbf{y} - \mathbf{y}_0)| < \|A\|\lambda r = \frac{r}{2}$$

so for all $\mathbf{x} \in \overline{B}$,

$$\begin{aligned} |\varphi(\mathbf{x}) - \mathbf{x}_0| &\leq |\varphi(\mathbf{x}) - \varphi(\mathbf{x}_0)| + |\varphi(\mathbf{x}_0) - \mathbf{x}_0| \\ &< \frac{1}{2}|\mathbf{x} - \mathbf{x}_0| + \frac{r}{2} \\ &\leq \frac{1}{2} \cdot r + \frac{r}{2} \\ &= r \end{aligned}$$

²How do we motivate this definition?

Thus, $\varphi(\mathbf{x}_0) \in B$. Moreover, since $|\varphi(\mathbf{x}_1) - \varphi(\mathbf{x}_2)| \leq \frac{1}{2}|\mathbf{x}_1 - \mathbf{x}_2|$ naturally holds for all $\mathbf{x}_1, \mathbf{x}_2 \in \overline{B} \subset U$, we have that φ is a contraction of \overline{B} into \overline{B} . Additionally, since $\overline{B} \subset \mathbb{R}^n$ is closed, it is a complete metric space under the Euclidean metric. Thus, Theorem 9.23 implies that φ has a fixed point $\mathbf{x} \in \overline{B}$. In particular, $\mathbf{f}(\mathbf{x}) = \mathbf{y}$. Therefore, $\mathbf{y} \in f(\overline{B}) \subset \mathbf{f}(U) = V$, as desired. \square

(b) If \mathbf{g} is the inverse of \mathbf{f} on V [which exists by (a)], i.e.,

$$\mathbf{g}(\mathbf{f}(\mathbf{x})) = \mathbf{x}$$

for all $\mathbf{x} \in U$, then $\mathbf{g} \in \mathcal{C}^1(V)$.

Proof. We first show that for all $\mathbf{y} \in V$, $\mathbf{g}'(\mathbf{y}) = [\mathbf{f}'(\mathbf{g}(\mathbf{y}))]^{-1}$. Let $\mathbf{y} \in V$ be arbitrary, and choose \mathbf{k} such that $(\mathbf{y} + \mathbf{k}) \in V$. It follows by part (a) that there exist $\mathbf{x}, \mathbf{x} + \mathbf{h} \in U$ such that $\mathbf{y} = \mathbf{f}(\mathbf{x})$ and $\mathbf{y} + \mathbf{k} = \mathbf{f}(\mathbf{x} + \mathbf{h})$. Thus,

$$\varphi(\mathbf{x} + \mathbf{h}) - \varphi(\mathbf{x}) = \mathbf{h} + A^{-1}[\mathbf{f}(\mathbf{x}) - \mathbf{f}(\mathbf{x} + \mathbf{h})] = \mathbf{h} - A^{-1}\mathbf{k}$$

so

$$|\mathbf{h} - A^{-1}\mathbf{k}| = |\varphi(\mathbf{x} + \mathbf{h}) - \varphi(\mathbf{x})| \leq \frac{1}{2}|\mathbf{x} + \mathbf{h} - \mathbf{x}| = \frac{1}{2}|\mathbf{h}|$$

Consequently, $|A^{-1}\mathbf{k}| \geq \frac{1}{2}|\mathbf{h}|$, so

$$|\mathbf{h}| \leq 2\|A^{-1}\|\|\mathbf{k}\| = \frac{\|\mathbf{k}\|}{\lambda}$$

Additionally, we know that $\|\mathbf{f}'(\mathbf{x}) - A\|\|A^{-1}\| = 1/2 < 1$, so Theorem 9.8a implies that $\mathbf{f}'(\mathbf{x})$ is invertible with an inverse that we may call T . Thus, since

$$\begin{aligned} \mathbf{g}(\mathbf{y} + \mathbf{k}) - \mathbf{g}(\mathbf{y}) - T\mathbf{k} &= \mathbf{h} - T\mathbf{k} \\ &= -T[(\mathbf{y} + \mathbf{k}) - \mathbf{y}] + T\mathbf{f}'(\mathbf{x})\mathbf{h} \\ &= -T[\mathbf{f}(\mathbf{x} + \mathbf{h}) - \mathbf{f}(\mathbf{x}) - \mathbf{f}'(\mathbf{x})\mathbf{h}] \end{aligned}$$

we have that

$$\frac{|\mathbf{g}(\mathbf{y} + \mathbf{k}) - \mathbf{g}(\mathbf{y}) - T\mathbf{k}|}{\|\mathbf{k}\|} \leq \frac{\|T\|\|\mathbf{f}(\mathbf{x} + \mathbf{h}) - \mathbf{f}(\mathbf{x}) - \mathbf{f}'(\mathbf{x})\mathbf{h}\|}{\lambda|\mathbf{h}|}$$

Consequently, $\mathbf{k} \rightarrow \mathbf{0}$ implies that $\mathbf{h} \rightarrow \mathbf{0}$, which implies that the right side of the above inequality goes to zero, which implies that the left side of the above inequality goes to zero. Thus, $\mathbf{g}'(\mathbf{y}) = T$, so

$$\mathbf{g}'(\mathbf{y}) = [\mathbf{f}'(\mathbf{g}(\mathbf{y}))]^{-1}$$

for all $\mathbf{y} \in V$, as desired.

To prove that \mathbf{g}' is continuous on V , Theorem 4.7 and the above equation tell us that it will suffice to show that $\mathbf{g} : V \rightarrow U$ is continuous, $\mathbf{f}' : U \rightarrow L(\mathbb{R}^n)$ is continuous, and $M \mapsto M^{-1} : L(\mathbb{R}^n) \rightarrow L(\mathbb{R}^n)$ is continuous. But we have the first condition since differentiability implies continuity and \mathbf{g} is differentiable, we have the second condition since $\mathbf{f} \in \mathcal{C}^1$ by hypothesis, and we have the third condition by Theorem 9.8b, as desired. \square

- Theorem 9.25: $E \subset \mathbb{R}^n$ open, $\mathbf{f} : E \rightarrow \mathbb{R}^n$ a \mathcal{C}^1 -mapping, and $\mathbf{f}'(\mathbf{x})$ invertible for all $\mathbf{x} \in E$ implies $\mathbf{f}(W)$ open in \mathbb{R}^n for every open $W \subset E$.
 - Note that the hypotheses of this theorem guarantee that \mathbf{f} is locally 1-1 at each $\mathbf{x} \in E$, but it may not be 1-1 in E under these conditions (see Exercise 9.17).