

MATH 20800 (Honors Analysis in \mathbb{R}^n II) Notes

Steven Labalme

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Chapter 1

The Algebra and Topology of \mathbb{R}^n

1.1 Notes

1/10:

- Syllabus.
 - In his mind, homework is the main setting where learning takes place.
- We're going to be studying analysis, or calculus, on **manifolds** this quarter.
- **Manifold**: A “space” that looks like Euclidean space \mathbb{R}^n locally.
 - The surfaces of a sphere and torus are common examples of 2-dimensional manifolds.
 - With regard to the above definition, think about how people in ancient times didn't think the Earth was a sphere because it looked like a plane locally.
- This class will look much like a calculus course, in that we first talk about limits, then differentiation, then integration, and culminating in the fundamental theory of calculus.
- Last quarter, we primarily developed linear algebra and basic topology on metric spaces.
 - Chapter 1 of Munkres (1991) is a review of what's needed from last quarter.
 - This is all basically continuity.
- Thus, we can start right up with differentiation.

Chapter 2

Differentiation

2.1 Notes

1/10:

- Since manifolds look like Euclidean spaces locally, we basically only need to study differentiation on Euclidean spaces.
- Set up: Let $U \subset \mathbb{R}^n$ be open, and $f : U \rightarrow \mathbb{R}^m$ be a function.
- Idea: The derivative of f at some point $\mathbf{a} \in U$ is “the best linear approximation” to f at \mathbf{a} .
- **Differentiable** (function f at \mathbf{a}): A function f for which there exists a linear transformation $A : \mathbb{R}^n \rightarrow \mathbb{R}^m$ such that

$$\lim_{\mathbf{h} \rightarrow \mathbf{0}} \frac{f(\mathbf{a} + \mathbf{h}) - f(\mathbf{a}) - A\mathbf{h}}{\|\mathbf{h}\|} = \mathbf{0}$$

- **Total derivative** (of f at \mathbf{a}): The linear transformation A corresponding to a differentiable function f . Denoted by $Df(\mathbf{a})$.
- Questions to ask:
 1. When does the total derivative exist?
 2. When it does exist, can there be multiple?
 3. When it exists and is unique, how do I calculate it?
- Proposition: If A, B are linear transformations that both satisfy the definition, then $A = B$.
 - We have

$$\lim_{\mathbf{h} \rightarrow \mathbf{0}} \frac{f(\mathbf{a} + \mathbf{h}) - f(\mathbf{a}) - A\mathbf{h}}{\|\mathbf{h}\|} = \mathbf{0} \qquad \lim_{\mathbf{h} \rightarrow \mathbf{0}} \frac{f(\mathbf{a} + \mathbf{h}) - f(\mathbf{a}) - B\mathbf{h}}{\|\mathbf{h}\|} = \mathbf{0}$$

- It follows by subtracting the right equation above from the left one that

$$\lim_{\mathbf{h} \rightarrow \mathbf{0}} \frac{A\mathbf{h} - B\mathbf{h}}{\|\mathbf{h}\|} = \mathbf{0}$$

- Apply linearity: For $\mathbf{v} \in \mathbb{R}^n$ and $t \in \mathbb{R}, t > 0$, we have

$$\frac{A(t\mathbf{v}) - B(t\mathbf{v})}{t} = A\mathbf{v} - B\mathbf{v}$$

- Therefore, since $t\mathbf{v} \rightarrow \mathbf{0}$ as $t \rightarrow 0$, we have by the above that

$$\begin{aligned}\mathbf{0} &= \lim_{t \rightarrow 0} \frac{A(t\mathbf{v}) - B(t\mathbf{v})}{\|t\mathbf{v}\|} \\ &= \lim_{t \rightarrow 0} \frac{A\mathbf{v} - B\mathbf{v}}{\|\mathbf{v}\|} \\ \mathbf{0} \cdot \|\mathbf{v}\| &= \lim_{t \rightarrow 0} (A\mathbf{v} - B\mathbf{v}) \\ \mathbf{0} &= A\mathbf{v} - B\mathbf{v} \\ B\mathbf{v} &= A\mathbf{v}\end{aligned}$$

- Example: Let $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be linear, i.e., $f(\mathbf{v}) = A\mathbf{v}$ for some linear transformation A . Then for all $\mathbf{a} \in \mathbb{R}^n$, $Df(\mathbf{a}) = A$ is constant.

- We have from the definition that

$$\begin{aligned}\lim_{\mathbf{h} \rightarrow \mathbf{0}} \frac{f(\mathbf{a} + \mathbf{h}) - f(\mathbf{a}) - A\mathbf{h}}{\|\mathbf{h}\|} &= \lim_{\mathbf{h} \rightarrow \mathbf{0}} \frac{f(\mathbf{a}) + f(\mathbf{h}) - f(\mathbf{a}) - f(\mathbf{h})}{\|\mathbf{h}\|} \\ &= \lim_{\mathbf{h} \rightarrow \mathbf{0}} \frac{\mathbf{0}}{\|\mathbf{h}\|} \\ &= \mathbf{0}\end{aligned}$$

- Theorem: If f is differentiable at \mathbf{a} , then f is continuous at \mathbf{a} .

- By definition, there exists a linear transformation A such that

$$\lim_{\mathbf{h} \rightarrow \mathbf{0}} \frac{f(\mathbf{a} + \mathbf{h}) - f(\mathbf{a}) - A\mathbf{h}}{\|\mathbf{h}\|} = \mathbf{0}$$

- Additionally, we have that

$$f(\mathbf{a} + \mathbf{h}) = f(\mathbf{a}) + A\mathbf{h} + \|\mathbf{h}\| \left(\frac{f(\mathbf{a} + \mathbf{h}) - f(\mathbf{a}) - A\mathbf{h}}{\|\mathbf{h}\|} \right)$$

- As $\mathbf{h} \rightarrow \mathbf{0}$, the right-hand side of the above equation goes to $f(\mathbf{a})$.

- As a linear transformation, $A\mathbf{h} \rightarrow \mathbf{0}$ as $\mathbf{h} \rightarrow \mathbf{0}$.

- Clearly $\|\mathbf{h}\| \rightarrow \mathbf{0}$ as $\mathbf{h} \rightarrow \mathbf{0}$.

- And we have by definition that the last term goes to $\mathbf{0}$ as $\mathbf{h} \rightarrow \mathbf{0}$.

- Therefore, f is continuous at \mathbf{a} .

- Observation: A function $f : U \rightarrow \mathbb{R}^m$ is given by an m -tuple of functions $f_1 : U \rightarrow \mathbb{R}$ known as components. $f = (f_1, \dots, f_m)$.

- Proposition: f is differentiable at $\mathbf{a} \in U$ iff each component function f_i is differentiable at \mathbf{a} . In this case,

$$Df(\mathbf{a}) = (Df_1(\mathbf{a}), \dots, Df_m(\mathbf{a}))$$

- We know that

$$\lim_{\mathbf{h} \rightarrow \mathbf{0}} \frac{f(\mathbf{a} + \mathbf{h}) - f(\mathbf{a}) - A\mathbf{h}}{\|\mathbf{h}\|} \in \mathbb{R}^m$$

- Thus, the limit is zero iff the limit of each component is zero.

- We have that the i^{th} component of the vector on the left below is equal to the number on the right; we call the common value $L_i(\mathbf{h})$.

$$\left(\frac{f(\mathbf{a} + \mathbf{h}) - f(\mathbf{a}) - A\mathbf{h}}{\|\mathbf{h}\|} \right)_i = \frac{f_i(\mathbf{a} + \mathbf{h}) - f_i(\mathbf{a}) - (A\mathbf{h})_i}{\|\mathbf{h}\|}$$

- The upshot is that f is differentiable at \mathbf{a} iff $\lim_{\mathbf{h} \rightarrow \mathbf{0}} L_i(\mathbf{h}) = \mathbf{0}$ iff the linear transformation $\mathbf{h} \mapsto (A\mathbf{h})_i : \mathbb{R}^m \rightarrow \mathbb{R}$ is the total derivative of f_i .

- Now, each f_i is a function of n variables, i.e., $f_i(x_1, \dots, x_n)$ where x_1, \dots, x_n are coordinates on \mathbb{R}^n .

References

Munkres, J. R. (1991). *Analysis on manifolds*. Addison-Wesley.