

# Chapter 9

## Functions of Several Variables

### 9.1 Notes

2/14:

- Plan:
  1. Warm-up with matrices.
  2. The total derivatives of  $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$  ( $n = m = 2$ , i.e.,  $f : \mathbb{C} \rightarrow \mathbb{C}$ ).
  3. Basic properties: Chain rule, relation with partial derivatives, implicit function theorem.
- Let  $V, W$  be finite-dimensional vector spaces over  $\mathbb{R}$ . We let  $L(V, W)$  be the vector space of all linear transformations  $\phi : V \rightarrow W$ .
- If we pick bases  $N_1, \dots, N_n$  of  $V$  and  $w_1, \dots, w_m$  of  $W$ , then  $V \cong \mathbb{R}^n$  and  $W \cong \mathbb{R}^m$ . It follows that  $L(V, W) \cong \mathbb{R}^{mn}$ .
- $L(V, W) \times L(W, U) \xrightarrow{\text{compose}} L(V, U)$ , i.e.,  $\mathbb{R}^{mn} \times \mathbb{R}^{nl} \xrightarrow[\text{mult.}]{\text{matrix}} \mathbb{R}^{ml}$ .
- Sup norm: If  $A$  is an  $m \times n$  real matrix, then  $\|A\| = \sup_{\substack{\mathbf{x} \in \mathbb{R}^n \\ |\mathbf{x}|=1}} |A\mathbf{x}|$ .
  - Basic properties:
    1.  $|A\mathbf{x}| \leq \|A\| |\mathbf{x}|$ .
    2.  $\|A\| < \infty$  and all  $A : \mathbb{R}^n \rightarrow \mathbb{R}^m$  are uniformly continuous.
    3.  $\|A\| = 0 \iff A = 0$ .
    4.  $\|cA\| = |c| \|A\|$ .
    5.  $\|A + B\| \leq \|A\| + \|B\|$ .
    6.  $\|AB\| \leq \|A\| \|B\|$ .
  - Note that we get a metric space structure on  $L(V, W)$  by defining  $d(A, B) = \|A - B\|$ .
- Proves that 1 and 2 imply the uniform continuity of all  $A$  (via Lipschitz continuity).
- **Differentiable** (multivariate function  $f$  at  $\mathbf{x}_0$ ): A function  $f : U \rightarrow \mathbb{R}^m$  ( $U \subset \mathbb{R}^n$ ) such that to  $\mathbf{x}_0 \in U$  there corresponds some linear transformation  $A : \mathbb{R}^n \rightarrow \mathbb{R}^m$  such that
$$\lim_{\mathbf{h} \rightarrow \mathbf{0}} \frac{|f(\mathbf{x}_0 + \mathbf{h}) - f(\mathbf{x}_0) - A\mathbf{h}|}{|\mathbf{h}|} = 0$$
- **Total derivative** (of  $f$  multivariate at  $\mathbf{x}_0$ ): The linear transformation  $A$  in the above definition. Denoted by  $\mathbf{f}'(\mathbf{x}_0)$ .
- “An proof and progress in mathematics” - Thurston.

- Relating to the old one dimensional derivative.
- A paper we'd find rather impressionistic right now.
- Propositions ahead of us.
  - Proposition: Suppose that  $f$  is differentiable at  $\mathbf{x}_0 \in U$  and  $A, B$  are both derivatives of  $f$  at  $\mathbf{x}_0$ . Then  $A = B$ .
  - Proposition: Differentiable implies continuous.
  - Proposition: Sum rule, product rule, quotient rule.

## 9.2 Chapter 9: Functions of Several Variables

From Rudin (1976).

- 2/15:
- Defines a vector space by the closure of its elements under addition and scalar multiplication.
  - Defines a linear combination, span, independence and dependence, dimension, basis, coordinates, and the standard basis.
  - Theorem 9.2: If  $X$  is spanned by  $r$  vectors,  $\dim X \leq r$ .
  - Corollary:  $\dim \mathbb{R}^n = n$ .
  - Theorem 9.3: Let  $X$  a vector space with  $\dim X = n$ .
    - (a)  $E \subset X$  containing  $n$  vectors spans  $X$  iff  $E$  is independent.
    - (b)  $X$  has a basis, and every basis contains  $n$  vectors.
    - (c) If  $1 \leq r \leq n$  and  $\{\mathbf{y}_1, \dots, \mathbf{y}_r\}$  is independent in  $X$ , then  $X$  has a basis containing  $\{\mathbf{y}_1, \dots, \mathbf{y}_r\}$ .
  - Defines linear transformation, linear operator.
  - Notes that  $A\mathbf{0} = \mathbf{0}$  if  $A$  is a linear transformation, and that  $A$  is completely determined by its action on any basis.
  - **Invertible** (linear operator): A linear operator  $A$  that is one-to-one and onto.
  - Theorem 9.5:  $A$  a linear operator on  $X$  finite-dimensional is one-to-one iff it is onto.
  - Defines  $L(X, Y)$ ,  $L(X)$ , the product  $BA$  of two linear transformations, and the supremum norm of a linear transformation.
  - Theorem 9.7:
    - (a)  $A \in L(\mathbb{R}^n, \mathbb{R}^m)$  implies  $\|A\| < \infty$  and  $A : \mathbb{R}^n \rightarrow \mathbb{R}^m$  uniformly continuous.
    - (b)  $A, B \in L(\mathbb{R}^n, \mathbb{R}^m)$  and  $c \in \mathbb{C}$  implies
 
$$\|A + B\| \leq \|A\| + \|B\| \qquad \|cA\| = |c|\|A\|$$
  - Defining  $d(A, B) = \|A - B\|$  makes  $L(\mathbb{R}^n, \mathbb{R}^m)$  a metric space.
  - (c)  $A \in L(\mathbb{R}^n, \mathbb{R}^m)$  and  $B \in L(\mathbb{R}^m, \mathbb{R}^k)$  implies
 
$$\|BA\| \leq \|B\|\|A\|$$
  - Theorem 9.8: Let  $\Omega$  be the set of all invertible linear operators on  $\mathbb{R}^n$ .
    - (a)  $A \in \Omega$ ,  $B \in L(\mathbb{R}^n)$ , and  $\|B - A\| \cdot \|A^{-1}\| < 1$  implies  $B \in \Omega$ .

*Proof.* Let  $\|A^{-1}\| = 1/\alpha$ , and let  $\|B - A\| = \beta$ . Then

$$\begin{aligned}\|B - A\| \cdot \|A^{-1}\| &< 1 \\ \beta \cdot \frac{1}{\alpha} &< 1 \\ \beta &< \alpha\end{aligned}$$

To prove that  $B \in \Omega$ , the definition of invertibility and Theorem 9.5 tell us that it will suffice to show that  $B$  is 1-1. To do so, it will suffice to show that  $B\mathbf{x} = \mathbf{0}$  iff  $\mathbf{x} = \mathbf{0}$ . Let's begin. Let  $\mathbf{x} \in \mathbb{R}^n$  be arbitrary. Then

$$\begin{aligned}\alpha|\mathbf{x}| &= \alpha\|A^{-1}A\mathbf{x}\| \leq \alpha\|A^{-1}\| \cdot \|A\mathbf{x}\| = \|A\mathbf{x}\| \leq \|(A - B)\mathbf{x}\| + \|B\mathbf{x}\| \leq \beta|\mathbf{x}| + \|B\mathbf{x}\| \\ (\alpha - \beta)|\mathbf{x}| &\leq \|B\mathbf{x}\|\end{aligned}$$

It follows that if  $\mathbf{x} \neq \mathbf{0}$ , then  $\|B\mathbf{x}\| > 0$ . This combined with the fact that  $B\mathbf{0} = \mathbf{0}$  implies the desired result.  $\square$

(b)  $\Omega$  is open in  $L(\mathbb{R}^n)$  and  $A \mapsto A^{-1}$  is continuous on  $\Omega$ .

*Proof.* To prove that  $\Omega$  is open in  $L(\mathbb{R}^n)$ , it will suffice to show that for all  $A \in \Omega$ , there exists  $N_r(A)$  such that if  $\|B - A\| < r$ , then  $B \in \Omega$ . Let's begin. Let  $A \in \Omega$  be arbitrary. Choose  $N_\alpha(A)$  to be our neighborhood, where  $\alpha$  is defined as in part (a). Let  $B \in L(\mathbb{R}^n)$  satisfy  $\|B - A\| < \alpha$ . Then  $\|B - A\| \cdot \|A^{-1}\| < 1$ , so  $B \in \Omega$  by part (a), as desired.

To prove that  $A \mapsto A^{-1}$  is continuous, it will suffice to show that  $\|B^{-1} - A^{-1}\| \rightarrow 0$  as  $B \rightarrow A$ . First off, we have by part (a) and the substitution  $\mathbf{x} = B^{-1}\mathbf{y}$  ( $\mathbf{y} \in \mathbb{R}^n$ ) that

$$\begin{aligned}(\alpha - \beta)\|B^{-1}\mathbf{y}\| &\leq \|B B^{-1}\mathbf{y}\| = \|\mathbf{y}\| \\ \left\| B^{-1} \left( \frac{\mathbf{y}}{\|\mathbf{y}\|} \right) \right\| &\leq (\alpha - \beta)^{-1}\end{aligned}$$

Thus, since  $\|B^{-1}\mathbf{u}\|$  is bounded by  $(\alpha - \beta)^{-1}$  for every unit vector  $\mathbf{u} \in \mathbb{R}^n$ ,  $\|B^{-1}\|$  is bounded by  $(\alpha - \beta)^{-1}$ . This combined with the fact that

$$\begin{aligned}B^{-1} - A^{-1} &= B^{-1}I - IA^{-1} \\ &= B^{-1}AA^{-1} - B^{-1}BA^{-1} \\ &= B^{-1}(A - B)A^{-1}\end{aligned}$$

implies by Theorem 9.7c that

$$\|B^{-1} - A^{-1}\| \leq \|B^{-1}\| \|A - B\| \|A^{-1}\| \leq (\alpha - \beta)^{-1} \cdot \beta \cdot \frac{1}{\alpha} = \frac{\beta}{\alpha(\alpha - \beta)}$$

Therefore, since  $\beta \rightarrow 0$  as  $B \rightarrow A$ , the above inequality establishes the desired result.  $\square$

- Note that the mapping  $A \mapsto A^{-1}$  defined in Theorem 9.8b is a 1-1 mapping of  $\Omega$  onto  $\Omega$  and its own inverse.
- Defines matrices, column vectors, and matrix multiplication.
- From the Schwarz inequality, we can show that

$$\|A\| \leq \left( \sum_{i,j} a_{i,j}^2 \right)^{1/2}$$

- “If  $S$  is a metric space, if  $a_{11}, \dots, a_{mn}$  are real continuous functions on  $S$ , and if for each  $p \in S$ ,  $A_p$  is the linear transformation of  $\mathbb{R}^n$  into  $\mathbb{R}^m$  whose matrix has entries  $a_{ij}(p)$ , then the mapping  $p \rightarrow A_p$  is a continuous mapping of  $S$  into  $L(\mathbb{R}^n, \mathbb{R}^m)$ ” (Rudin, 1976, p. 211).

- Rudin (1976) spends some time motivating the definition of the total derivative. He also discusses the natural 1-1 correspondence between  $\mathbb{R}^1$  and  $L(\mathbb{R}^1)$ .
- Defines differentiability in  $\mathbb{R}^n$ .
- Theorem 9.12:  $A_1, A_2$  the derivative of  $\mathbf{f}$  at  $\mathbf{x}$  implies  $A_1 = A_2$ .
- If  $\mathbf{f} : E \rightarrow \mathbb{R}^m$  where  $E \subset \mathbb{R}^n$ , then  $\mathbf{f}' : E \rightarrow L(\mathbb{R}^n, \mathbb{R}^m)$ .
- $\mathbf{f}$  differentiable implies  $\mathbf{f}$  continuous.
- Example ( $\mathbf{f}$  is linear):
  - If  $A \in L(\mathbb{R}^n, \mathbb{R}^m)$ , then  $A'(\mathbf{x}) = A$  for all  $\mathbf{x} \in \mathbb{R}^n$ . Note that this means that  $A' : \mathbb{R}^n \rightarrow L(\mathbb{R}^n, \mathbb{R}^m)$ , as expected.
- Theorem 9.15 (Chain Rule):  $E$  open in  $\mathbb{R}^n$ ,  $\mathbf{f} : E \rightarrow \mathbb{R}^m$  differentiable at  $\mathbf{x}_0 \in E$ ,  $I \supset \mathbf{f}(E)$  open in  $\mathbb{R}^m$ , and  $\mathbf{g} : I \rightarrow \mathbb{R}^k$  differentiable at  $\mathbf{f}(\mathbf{x}_0)$  implies  $\mathbf{F} : E \rightarrow \mathbb{R}^k$  defined by

$$\mathbf{F}(\mathbf{x}) = \mathbf{g}(\mathbf{f}(\mathbf{x}))$$

is differentiable at  $\mathbf{x}_0$  with

$$\mathbf{F}'(\mathbf{x}_0) = \mathbf{g}'(\mathbf{f}(\mathbf{x}_0))\mathbf{f}'(\mathbf{x}_0)^{[1]}$$

*Proof.* Largely symmetric to that of the one-dimensional chain rule in Chapter 5. □

- **Components** (of  $\mathbf{f} : \mathbb{R}^n \rightarrow \mathbb{R}^m$ ): The real functions  $f_1, \dots, f_m$  defined by

$$\mathbf{f}(\mathbf{x}) = \sum_{i=1}^m f_i(\mathbf{x})\mathbf{u}_i$$

for all  $\mathbf{x} \in E$  or, equivalently, by  $f_i(\mathbf{x}) = \mathbf{f}(\mathbf{x}) \cdot \mathbf{u}_i$  ( $1 \leq i \leq m$ ), where  $\mathbf{u}_1, \dots, \mathbf{u}_m$  is the standard basis of  $\mathbb{R}^m$ .

- Defines partial derivatives.
- Theorem 9.17:  $E \subset \mathbb{R}^n$  open and  $\mathbf{f} : E \rightarrow \mathbb{R}^m$  differentiable at  $\mathbf{x} \in E$  imply the partial derivatives  $(D_j f_i)(\mathbf{x})$  exist and

$$\mathbf{f}'(\mathbf{x})\mathbf{e}_j = \sum_{i=1}^m (D_j f_i)(\mathbf{x})\mathbf{u}_i$$

for  $1 \leq j \leq n$ .

- It follows that

$$[\mathbf{f}'(\mathbf{x})] = \begin{bmatrix} (D_1 f_1)(\mathbf{x}) & \cdots & (D_n f_1)(\mathbf{x}) \\ \vdots & & \vdots \\ (D_1 f_m)(\mathbf{x}) & \cdots & (D_n f_m)(\mathbf{x}) \end{bmatrix}$$

- Discusses the gradient and the directional derivative.
- Theorem 9.19:  $E \subset \mathbb{R}^n$  convex and open,  $\mathbf{f} : E \rightarrow \mathbb{R}^m$  differentiable in  $E$ , and there exists  $M$  such that

$$\|\mathbf{f}'(\mathbf{x})\| \leq M$$

for all  $\mathbf{x} \in E$  implies

$$|\mathbf{f}(\mathbf{b}) - \mathbf{f}(\mathbf{a})| \leq M|\mathbf{b} - \mathbf{a}|$$

for all  $\mathbf{a}, \mathbf{b} \in E$ .

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<sup>1</sup>Note that the right-hand side of this equation contains the product of two linear transformations.

- Corollary: If, in addition,  $\mathbf{f}'(\mathbf{x}) = \mathbf{0}$  for all  $\mathbf{x} \in E$ , then  $\mathbf{f}$  is constant.
- **Continuously differentiable** (mapping  $\mathbf{f} : E \rightarrow \mathbb{R}^m$ ): A function  $\mathbf{f} : E \rightarrow \mathbb{R}^m$  such that  $\mathbf{f}' : E \rightarrow L(\mathbb{R}^n, \mathbb{R}^m)$  is continuous. *Also known as  $\mathcal{C}'$ -mapping. Denoted by  $\mathbf{f} \in \mathcal{C}'(E)$ .*
- Theorem 9.21: Let  $E \subset \mathbb{R}^n$  open and  $\mathbf{f} : E \rightarrow \mathbb{R}^m$ . Then  $\mathbf{f} \in \mathcal{C}'(E)$  iff the partial derivatives  $D_j f_i$  ( $1 \leq i \leq m$ ;  $1 \leq j \leq n$ ) exist and are continuous on  $E$ .