

Chapter 9

Functions of Several Variables

9.1 Notes

2/14:

- Plan:
 1. Warm-up with matrices.
 2. The total derivatives of $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ ($n = m = 2$, i.e., $f : \mathbb{C} \rightarrow \mathbb{C}$).
 3. Basic properties: Chain rule, relation with partial derivatives, implicit function theorem.
- Let V, W be finite-dimensional vector spaces over \mathbb{R} . We let $L(V, W)$ be the vector space of all linear transformations $\phi : V \rightarrow W$.
- If we pick bases $\mathbf{v}_1, \dots, \mathbf{v}_n$ of V and $\mathbf{w}_1, \dots, \mathbf{w}_m$ of W , then $V \cong \mathbb{R}^n$ and $W \cong \mathbb{R}^m$. It follows that $L(V, W) \cong \mathbb{R}^{mn}$.
- $L(V, W) \times L(W, U) \xrightarrow{\text{compose}} L(V, U)$, i.e., $\mathbb{R}^{mn} \times \mathbb{R}^{nl} \xrightarrow[\text{mult.}]{\text{matrix}} \mathbb{R}^{ml}$.
- Sup norm: If A is an $m \times n$ real matrix, then $\|A\| = \sup_{\substack{\mathbf{x} \in \mathbb{R}^n \\ |\mathbf{x}|=1}} |A\mathbf{x}|$.
 - Basic properties:
 1. $|A\mathbf{x}| \leq \|A\| |\mathbf{x}|$.
 2. $\|A\| < \infty$ and all $A : \mathbb{R}^n \rightarrow \mathbb{R}^m$ are uniformly continuous.
 3. $\|A\| = 0 \iff A = 0$.
 4. $\|cA\| = |c| \|A\|$.
 5. $\|A + B\| \leq \|A\| + \|B\|$.
 6. $\|AB\| \leq \|A\| \|B\|$.
 - Note that we get a metric space structure on $L(V, W)$ by defining $d(A, B) = \|A - B\|$.
- Proves that 1 and 2 imply the uniform continuity of all A (via Lipschitz continuity).
- **Differentiable** (function \mathbf{f} at \mathbf{x}_0): A function $\mathbf{f} : U \rightarrow \mathbb{R}^m$ ($U \subset \mathbb{R}^n$) such that to $\mathbf{x}_0 \in U$ there corresponds some linear transformation $A : \mathbb{R}^n \rightarrow \mathbb{R}^m$ such that
$$\lim_{\mathbf{h} \rightarrow \mathbf{0}} \frac{|\mathbf{f}(\mathbf{x}_0 + \mathbf{h}) - \mathbf{f}(\mathbf{x}_0) - A\mathbf{h}|}{|\mathbf{h}|} = 0$$
- **Total derivative** (of \mathbf{f} at \mathbf{x}_0): The linear transformation A in the above definition. Denoted by $\mathbf{f}'(\mathbf{x}_0)$, $D\mathbf{f}(\mathbf{x}_0)$, $d\mathbf{f}(\mathbf{x}_0)$.
- “An proof and progress in mathematics” - Thurston.

- Relating to the old one dimensional derivative.
- A paper we'd find rather impressionistic right now.

- Propositions ahead of us.

- Proposition: Suppose that \mathbf{f} is differentiable at $\mathbf{x}_0 \in U$ and A, B are both derivatives of \mathbf{f} at \mathbf{x}_0 . Then $A = B$.
- Proposition: Differentiable implies continuous.
- Proposition: Sum rule, product rule, quotient rule.

2/16:

- Plan: Derivatives of functions $\mathbf{f} : U \rightarrow \mathbb{R}^m$ where $U \subset \mathbb{R}^n$.

- Basic properties: Differentiability implies continuity, $(\mathbf{f} + \mathbf{g})' = \mathbf{f}' + \mathbf{g}'$, $(c\mathbf{f})' = c\mathbf{f}'$, chain rule, $\mathbf{f}' = 0$ iff \mathbf{f} is constant.
- Relationship with partial derivatives (how we compute everything and anything).
- When is \mathbf{f} differentiable?
- Inverse function theorem.
- Implicit function theorem.

- **Continuously differentiable** (function \mathbf{f}): A function $\mathbf{f} : U \rightarrow \mathbb{R}^m$ that is differentiable for all $\mathbf{x}_0 \in U$ and such that $\mathbf{f}' : U \rightarrow L(\mathbb{R}^n, \mathbb{R}^m)$ is continuous. *Also known as \mathcal{C}^1 .*

- Proposition: Let $\mathbf{f} : U \rightarrow \mathbb{R}^m$ be differentiable at $\mathbf{x}_0 \in U$. Then \mathbf{f} is continuous at \mathbf{x}_0 .

- The proof makes use of the fact that $\mathbf{f}(\mathbf{x}_0 + \mathbf{h}) - \mathbf{f}(\mathbf{x}_0) = \mathbf{f}'(\mathbf{x}_0)\mathbf{h} + \mathbf{r}(\mathbf{h})$.

- Proposition: Given $\mathbf{f}, \mathbf{g} : U \rightarrow \mathbb{R}^m$ both differentiable at $\mathbf{x}_0 \in U$, then $\mathbf{f} + \mathbf{g}$ is also differentiable at \mathbf{x}_0 with

$$(\mathbf{f} + \mathbf{g})'(\mathbf{x}_0) = \mathbf{f}'(\mathbf{x}_0) + \mathbf{g}'(\mathbf{x}_0)$$

- The proof is immediate via the triangle inequality.

- Theorem (Chain Rule): Given $\mathbf{f} : U \rightarrow \mathbb{R}^m$ and $\mathbf{g} : V \rightarrow \mathbb{R}^k$, where $U \subset \mathbb{R}^n$ and $\mathbf{f}(U) \subset V \subset \mathbb{R}^m$, with \mathbf{f} differentiable at $\mathbf{x}_0 \in U$ and \mathbf{g} differentiable at $\mathbf{f}(\mathbf{x}_0)$, the composition $\mathbf{g} \circ \mathbf{f}$ is differentiable at \mathbf{x}_0 with

$$(\mathbf{g} \circ \mathbf{f})'(\mathbf{x}_0) = \mathbf{g}'(\mathbf{f}(\mathbf{x}_0)) \cdot \mathbf{f}'(\mathbf{x}_0)$$

- The proof is rather subtle.

- **Partial derivative** (of f_i wrt. x_j at \mathbf{x}_0): The following limit, if it exists, where $f_i : \mathbb{R}^n \rightarrow \mathbb{R}$, $1 \leq i \leq m$, and $1 \leq j \leq n$. Denoted by $(\partial \mathbf{f}_i / \partial x_j)(\mathbf{x}_0)$, $(D_j \mathbf{f}_i)(\mathbf{x}_0)$. Given by

$$\frac{\partial f_i}{\partial x_j}(\mathbf{x}_0) = \lim_{t \rightarrow 0} \frac{f_i(\mathbf{x}_0 + t\mathbf{e}_j) - f_i(\mathbf{x}_0)}{t}$$

- **Directional derivative** (of f_i toward $\mathbf{u} \in \mathbb{R}^n$): The following limit, if it exists, where $f_i : \mathbb{R}^n \rightarrow \mathbb{R}$ and $1 \leq i \leq m$. Denoted by $D_{\mathbf{u}} \mathbf{f}_i$. Given by

$$D_{\mathbf{u}} f_i = \lim_{t \rightarrow 0} \frac{f_i(\mathbf{x}_0 + t\mathbf{u}) - f_i(\mathbf{x}_0)}{t}$$

- **Jacobian**: The following matrix. Given by

$$\left[\frac{\partial f_i}{\partial x_j}(\mathbf{x}_0) \right]$$

- Theorem: Let $\mathbf{f} = (f_1, \dots, f_m) : U \rightarrow \mathbb{R}^m$, where $U \subset \mathbb{R}^n$, be differentiable at some $\mathbf{x}_0 \in U$. Then the partial derivatives $\partial f_i / \partial x_j$ ($1 \leq i \leq m$; $1 \leq j \leq n$) exist at \mathbf{x}_0 and, with respect to the usual choice of bases,

$$\mathbf{f}'(\mathbf{x}_0) = \left[\frac{\partial f_i}{\partial x_j}(\mathbf{x}_0) \right]$$

2/18: – We have that

$$\mathbf{f}(\mathbf{x}_0 + t\mathbf{e}_j) - \mathbf{f}(\mathbf{x}_0) = \mathbf{f}'(\mathbf{x}_0)(t\mathbf{e}_j) + \mathbf{r}(t\mathbf{e}_j)$$

- Since \mathbf{f} is differentiable at \mathbf{x}_0 , $\mathbf{f}(t\mathbf{e}_j)/t \rightarrow 0$ as $t \rightarrow 0$.
- Additionally, $\mathbf{f}'(\mathbf{x}_0)(t\mathbf{e}_j)/t = \mathbf{f}'(\mathbf{x}_0)(\mathbf{e}_j)$.
- Therefore,

$$\lim_{t \rightarrow 0} \frac{\mathbf{f}(\mathbf{x}_0 + t\mathbf{e}_j) - \mathbf{f}(\mathbf{x}_0)}{t} = \lim_{t \rightarrow 0} \frac{\mathbf{f}'(\mathbf{x}_0)(t\mathbf{e}_j) - \mathbf{r}(t\mathbf{e}_j)}{t} = \mathbf{f}'(\mathbf{x}_0)(\mathbf{e}_j) - \lim_{t \rightarrow 0} \frac{\mathbf{r}(t\mathbf{e}_j)}{t} = \mathbf{f}'(\mathbf{x}_0)(\mathbf{e}_j)$$

as desired.

- Unpacking the definition of the linear transformation as a matrix gives the rest of the proof.

- Today:

- More on differentiation (recall the Jacobian).
- Sufficient condition for differentiability.
- $\mathbf{f}' = 0$ iff \mathbf{f} is constant.
- State the inverse function theorem.

- It is not true that having all partials exist implies that \mathbf{f} is differentiable at \mathbf{x}_0 .

- Theorem: \mathbf{f} continuously differentiable at \mathbf{x}_0 iff all partials exist and are continuous at \mathbf{x}_0 .

2/21: • Contraction mapping theorem.

2/23: • Plan.

1. Proof of the inverse function theorem.
2. Commuting partials.

- Theorem (Inverse function theorem): If $E \subset \mathbb{R}^n$ open, $\mathbf{f} : E \rightarrow \mathbb{R}^n$ is differentiable at $\mathbf{x}_0 \in E$, and $\mathbf{f}'(\mathbf{x}_0)$ is invertible, then there exist $U \subset E$ open with $\mathbf{x}_0 \in U$ and $V \subset \mathbb{R}^n$ open with $\mathbf{f}(\mathbf{x}_0) \in V$ such that $\mathbf{f}|_U : U \rightarrow V$ is a bijection and $(\mathbf{f}|_U)^{-1}$ is continuously differentiable.

- Idea.

1. Find U and prove one-to-one restricted to U .
2. $\mathbf{f}(U)$ is open.
3. Prove the inverse is continuously differentiable (left as an exercise to us).

- There is a trick for 1-2: We introduce an auxiliary function $\varphi_{\mathbf{y}}$ and apply the contraction mapping theorem.

- Proof.

- Let $A = \mathbf{f}'(\mathbf{x}_0)$.
- Since \mathbf{f}' is continuous, there is an open ball $U \subset E$ with center \mathbf{x}_0 such that $\|\mathbf{f}'(\mathbf{x}) - A\| < \lambda$ for all $\mathbf{x} \in U$.
 - We'll pick $\lambda = 1/(2\|A^{-1}\|)$ without motivation for now.

- Note that if you need to pick a U (for an example function), this criterion gives you one (not necessarily the best one, but it gives you a one).
- Trick: For all $\mathbf{y} \in \mathbb{R}^n$, consider $\varphi_{\mathbf{y}} : U \rightarrow \mathbb{R}^n$ defined by

$$\varphi_{\mathbf{y}}(\mathbf{x}) = \mathbf{x} + A^{-1}(\mathbf{y} - \mathbf{f}(\mathbf{x}))$$

- Important property of this function: $\mathbf{f}(\mathbf{x}) = \mathbf{y}$ iff $\varphi_{\mathbf{y}}(\mathbf{x}) = \mathbf{x}$.
- Plan: Show that for all $\mathbf{y} \in \mathbf{f}(U)$ that $\varphi_{\mathbf{y}}$ is a contraction. Therefore, by the contraction mapping theorem, \mathbf{f} has exactly 1 fixed point, so $\mathbf{f}|_U$ is injective.
- Proving that $\varphi_{\mathbf{y}}$ is a contraction. Claim: $|\varphi_{\mathbf{y}}(\mathbf{x}_1) - \varphi_{\mathbf{y}}(\mathbf{x}_2)| \leq \frac{1}{2}|\mathbf{x}_1 - \mathbf{x}_2|$. Use the Chain Rule, MVT, and the fact that $\|AB\| \leq \|A\|\|B\|$.
- Using the chain rule, we have that

$$\begin{aligned}\varphi'_{\mathbf{y}} &= I - A^{-1}\mathbf{f}'(\mathbf{x}) \\ &= A^{-1}(A - \mathbf{f}'(\mathbf{x}))\end{aligned}$$

- Thus,

$$\|\varphi_{\mathbf{y}}(\mathbf{x})\| \leq \|A^{-1}\| \|A - \mathbf{f}'(\mathbf{x})\| < \frac{1}{2}$$

for all \mathbf{x} .

- It follows by the MVT that

$$|\varphi_{\mathbf{y}}(\mathbf{x}_1) - \varphi_{\mathbf{y}}(\mathbf{x}_2)| \leq \frac{1}{2}|\mathbf{x}_1 - \mathbf{x}_2|$$

- Therefore, $\varphi_{\mathbf{y}}$ is a contraction.
 - We now prove that $\mathbf{f}(U)$ is open.
 - Let $\mathbf{y}_0 \in \mathbf{f}(U)$ be such that $\mathbf{y}_0 = \mathbf{f}(\mathbf{p}_0)$.
 - Pick $B_r(\mathbf{p}_0) \subset U$ such that $\overline{B} \subset U$.
 - Claim: For all $\mathbf{y} \in \mathbb{R}^n$ with $|\mathbf{y} - \mathbf{y}_0| < \lambda r$, we have that $\mathbf{y} \in \mathbf{f}(U)$.
 - We are going to show that $\varphi_{\mathbf{y}}(\overline{B}) \subset \overline{B}$ and therefore $\varphi_{\mathbf{y}} : \overline{B} \rightarrow \overline{B}$ is a contraction and therefore by the contraction mapping theorem, there exists a fixed point $\mathbf{x}_{\mathbf{y}}$ of $\varphi_{\mathbf{y}}$ in \overline{B} . Therefore, $\mathbf{f}(\mathbf{x}_{\mathbf{y}}) = \mathbf{y}$ and so $\mathbf{f}(U)$ is open.
- $\varphi_{\mathbf{y}}$ is derived from Newton's method. The contraction mapping thing then is what substitutes for convergence. You have to start in the right area though, the chosen U !

2/25:

- Plan:
 1. A point on the IFT.
 2. Commuting partials.
 3. Implicit function theorem.
- Subtle point: Last time, in the proof of the IFT, we first found the $U \subset E$ and prove that $\mathbf{f}|_U$ is injective, and then we proved that $\mathbf{f}(U)$ is open.
- The properties of $\varphi_{\mathbf{y}}$.
 - $\varphi_{\mathbf{y}}(U) \subset U$.
 - $\varphi_{\mathbf{y}}$ is a contraction since $|\varphi_{\mathbf{y}}(\mathbf{x}_1) - \varphi_{\mathbf{y}}(\mathbf{x}_2)| \leq \frac{1}{2}|\mathbf{x}_1 - \mathbf{x}_2|$.
 - $\mathbf{f}(\mathbf{x}) = \mathbf{y}$ iff $\varphi_{\mathbf{y}}(\mathbf{x}) = \mathbf{x}$ (fixed points for this contraction mapping).
- Commuting partials.

- When does the following hold?

$$\frac{\partial^2 f}{\partial x_j \partial x_i} = \frac{\partial^2 f}{\partial x_i \partial x_j}$$

- Simple answer: Not often, but with enough regularity, yes.

- Theorem: Given $f : E \rightarrow \mathbb{R}$ where $E \subset \mathbb{R}^n$, we say that f is C^2 (or of class C^2)
- **Class C^2** (function f): A function $f : E \rightarrow \mathbb{R}$ (where $E \subset \mathbb{R}^n$) such that all partials $\partial^2 f / \partial x_j \partial x_i$ exist and are continuous for all points in E . Denoted by $\mathbf{f} \in C^2$.
- Lemma (MVT): If $E \subset \mathbb{R}^2$ open, $f : E \rightarrow \mathbb{R}$, $\partial f / \partial x$, $\partial^2 f / \partial y \partial x$ exist for all $(x, y) \in E$, $Q = [a, a+h] \times [b, b+k] \subset E$, and

$$\Delta(f, Q) = f(a+h, b+k) - f(a+h, b) + f(a, b+k) - f(a, b)$$

then there exists $(x_0, y_0) \in Q$ such that

$$\Delta(f, Q) = hk \frac{\partial^2}{\partial y \partial x}(x_0, y_0)$$

- Proof idea: We reduce to the goal of the 1D MVT.
- Define $u(t) = f(t, b+k) - f(t, b)$. Then u is differentiable by the sum and scalar multiple rules.
- It follows that

$$\begin{aligned} \Delta(f, Q) &= u(a+h) - u(a) \\ &= hu'(x_0) \\ &= h \left[\frac{\partial f}{\partial x} - \frac{\partial f}{\partial x} \right] \\ &= hk \frac{\partial^2}{\partial y \partial x}(x_0, y_0) \end{aligned}$$

- Theorem: If $f \in C^2$, then

$$\frac{\partial^2 f}{\partial x_j \partial x_i} = \frac{\partial^2 f}{\partial x_i \partial x_j}$$

for all $1 \leq i, j \leq n$.

- Idea.
 - To make life easy, take $n = 2$. Then we just need the right kind of mean value theorem (the one in the lemma).
- Proof.
 - Follows from the lemma as $h, k \rightarrow 0$.
 - See Theorem 15.3 in Labalme (2021).

2/28:

- Plan:
 1. Implicit function theorem (end of Chapter 9).
 2. Sharkovsky's theorem.
 3. Go back and talk about Chapter 8 material.

- Theorem (Implicit Function Theorem; informal): Given a nice system of equations

$$\begin{aligned} f_1(c_1, \dots, x_n, y_1, \dots, y_m) &= 0 \\ &\vdots \\ f_n(x_1, \dots, x_n, y_1, \dots, y_m) &= 0 \end{aligned}$$

and a particular solution (\mathbf{a}, \mathbf{b}) , we can solve for $\mathbf{y} = (y_1, \dots, y_m)$ locally at (\mathbf{a}, \mathbf{b}) .

- Theorem (Implicit Function Theorem): If $E \subset \mathbb{R}^{n+m}$, $\mathbf{f} : E \rightarrow \mathbb{R}^n$ continuously differentiable, $(\mathbf{a}, \mathbf{b}) \in E$ with $\mathbf{f}(\mathbf{a}, \mathbf{b}) = \mathbf{0}$, $A = \mathbf{f}'(\mathbf{a}, \mathbf{b})$, $A_{\mathbf{x}} : \mathbb{R}^n \rightarrow \mathbb{R}^n$ defined by $\mathbf{x} \mapsto \mathbf{f}'(\mathbf{a}, \mathbf{b})(\mathbf{x}, \mathbf{0})$ invertible, and $A_{\mathbf{y}} : \mathbb{R}^m \rightarrow \mathbb{R}^n$ defined by $\mathbf{y} \mapsto \mathbf{f}'(\mathbf{a}, \mathbf{b})(\mathbf{0}, \mathbf{y})$, then there exists $U \subset \mathbb{R}^{n+m}$, $W \subset \mathbb{R}^m$ with $(\mathbf{a}, \mathbf{b}) \in U$, $\mathbf{b} \in W$ such that:

1. For every $\mathbf{y} \in W$, there exists a unique $\mathbf{x} \in \mathbb{R}^n$ such that $(\mathbf{x}, \mathbf{y}) \in U$ and $\mathbf{f}(\mathbf{x}, \mathbf{y}) = \mathbf{0}$.
2. There is a continuously differentiable function $\mathbf{g} : W \rightarrow \mathbb{R}^n$ such that

$$\mathbf{f}(\mathbf{g}(\mathbf{y}), \mathbf{y}) = \mathbf{0}$$

for all $\mathbf{y} \in W$ and

$$\mathbf{g}'(\mathbf{b}) = -(A_{\mathbf{x}})^{-1}A_{\mathbf{y}}$$

- Example: Consider $f : \mathbb{R}^{1+1} \rightarrow \mathbb{R}$ defined by $(x, y) \mapsto x^2 + y^2 - 1$.
 - Then $f^{-1}(\{0\})$ is the unit circle.
 - $Df = [2x \quad 2y]$, $A_x = [2x]$, and $A_y = [2y]$.
- Idea:
 - Use the inverse function theorem, and apply it to $A_{\mathbf{x}}$.
 - Goal: Find U and W ; from this, \mathbf{g} follows uniquely (though you also technically need to show continuous differentiability).
 - Define $F : E \rightarrow \mathbb{R}^{n+m}$ by $F(\mathbf{x}, \mathbf{y}) = (\mathbf{f}(\mathbf{x}, \mathbf{y}), \mathbf{y})$. Claim: $F'(\mathbf{a}, \mathbf{b})$ is invertible. Apply the inverse function theorem to F .
- Proof left to us.
- The goal of Sharkovsky's theorem is to understand the iterates of f , i.e., $x, f(x), f^2(x), f^3(x), \dots$. This fits in thematically with the contraction mapping theorem.
- **Periodic** (point $p \in I$): A point $p \in I$ for which $f^m(p) = p$ for some $m \in \mathbb{N}$.
- **Period** (of $p \in I$ periodic): The least number m such that $f^m(p) = p$.
- **Fixed point**: A periodic point of period 1.
- Example: $f : [0, 1] \rightarrow [0, 1]$ defined by $f(x) = 1 - x$ has periodic points of period 2 everywhere on its domain save $1/2$, which has period 1.
- Theorem: If f has a point p of period 3, then f has points of all other periods.
- **Sharkovsky ordering**: All of the odd numbers, then 2^1 times the odd numbers, then 2^2 times the odd numbers, then continuing for $n \rightarrow \infty$, and then 2^n as large as possible all the way down to 1.
 - If n comes before m in the Sharkovsky ordering, we write $n \triangleright m$.
- Sharkovsky's theorem: If $A \subset \mathbb{R}$, $f : A \rightarrow \mathbb{R}$ continuous satisfies $f(A) \subset A$ and has a period m point with $m \triangleright l$, then f has a period l point.
- Example: Logistic maps $g_b : [0, 1] \rightarrow [0, 1]$ defined by $x \mapsto bx(1 - x)$ for $b \in [1, 4]$.

- 3/2:
- Theorem (Li & Yorke): If f has a period 3 point, then there exists an uncountable set $S \subset A$ such that for all $p, q \in S$,

$$\liminf_{n \rightarrow \infty} |f^n(p) - f^n(q)| = 0 \qquad \limsup_{n \rightarrow \infty} |f^n(p) - f^n(q)| > 0$$

- Plan:

1. Prove the warm-up to Sharkovsky.

- Theorem: If f continuous has a period 3 point, then f has points of all other periods.
- Notation.
 - We say “ I covers J ” and write $I \rightarrow J$ when $I, J \subset A$ are closed intervals with $f(I) \supset J$.
- Lemma 1: If $[a, b] \rightarrow [a, b]$, then f continuous has a fixed point in $[a, b]$.
 - Consider $f(x) - x$ on $[a, b]$.
 - Either $f(a) = a$, $f(b) = b$, or we can invoke the IVT.
 - Alternatively, since $[a, b] \subset f([a, b])$, there exist a_0, b_0 with $f(a_0) = a$ and $f(b_0) = b$. Thus, $f(a_0) - a_0 \leq 0$ and $f(b_0) - b_0 \geq 0$, so by the IVT, there is some zero of $f(x) - x$ on $[a, b]$, as desired.
- Lemma 2: p has period m iff p is a fixed point of f^m and not a fixed point of f^i for $i < m$.
- Lemma 3: Suppose we have a loop of intervals $J_0 \rightarrow J_1 \rightarrow J_2 \rightarrow \cdots \rightarrow J_{n-1} \rightarrow J_0 \rightarrow \cdots$. Then there is a fixed point $p \in J_0$ of f^n such that $f^i(p) \in J_i$ for all $0 \leq i < n$.

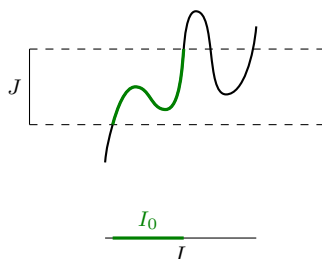


Figure 9.1: Loop mapping.

- Isn't this obvious? No – there's an issue, namely that $f(J_i) \not\subset J_{i+1}$. We can solve this though by noting that if $I \rightarrow J$, then there exists some subinterval $I_0 \subset I$ such that $f(I_0) \subset J$ and $I_0 \rightarrow J$ (i.e., $f(I_0) = J$).
- You can use this idea to pull a J'_i out of each J_i for which set equality holds.
- Then by the previous lemma, there exists a fixed point p of f^n in J'_0 . Then $f(p) \in J'_1 \subset J_1, \dots, f^{n-1}(p) \in J'_{n-1} \subset J_{n-1}$.
- Notation.
 - In the case of Lemma 3, we say that p is **following** the cycle $J_0 \rightarrow \cdots \rightarrow J_{n-1} \rightarrow J_0 \rightarrow \cdots$.
 - We call $J_0 \rightarrow \cdots \rightarrow J_{n-1} \rightarrow J_0 \rightarrow \cdots$ **elementary** if it is only followed by points of period n .
- Lemma: Let q have period m and let $\mathcal{O} = \{q, f(q), \dots, f^{m-1}(q)\}$. Let $J_0 \rightarrow \cdots \rightarrow J_{n-1} \rightarrow J_0 \rightarrow \cdots$ and suppose
 - (i) all endpoints of the J_i are in \mathcal{O} ;

- (ii) the loop is not followed by any point in \mathcal{O} ;
- (iii) The interior of J_0 , $\text{int}(J_0)$ is disjoint from the other J_i .

Then the loop is elementary, and so f has a period n point.

- Suppose p follows the loop.
- Then by (i) and (ii), p is not an endpoint of J_0 , so if $f^i(p) = p \in J_0$ for $i < n$, then $\text{int}(J_0) \cap J_i$, contradicting (iii).

9.2 Chapter 9: Functions of Several Variables

From Rudin (1976).

- 2/15:
- Defines a vector space by the closure of its elements under addition and scalar multiplication.
 - Defines a linear combination, span, independence and dependence, dimension, basis, coordinates, and the standard basis.
 - Theorem 9.2: If X is spanned by r vectors, $\dim X \leq r$.
 - Corollary: $\dim \mathbb{R}^n = n$.
 - Theorem 9.3: Let X a vector space with $\dim X = n$.
 - (a) $E \subset X$ containing n vectors spans X iff E is independent.
 - (b) X has a basis, and every basis contains n vectors.
 - (c) If $1 \leq r \leq n$ and $\{\mathbf{y}_1, \dots, \mathbf{y}_r\}$ is independent in X , then X has a basis containing $\{\mathbf{y}_1, \dots, \mathbf{y}_r\}$.
 - Defines linear transformation, linear operator.
 - Notes that $A\mathbf{0} = \mathbf{0}$ if A is a linear transformation, and that A is completely determined by its action on any basis.
 - **Invertible** (linear operator): A linear operator A that is one-to-one and onto.
 - Theorem 9.5: A a linear operator on X finite-dimensional is one-to-one iff it is onto.
 - Defines $L(X, Y)$, $L(X)$, the product BA of two linear transformations, and the supremum norm of a linear transformation.
 - Theorem 9.7:
 - (a) $A \in L(\mathbb{R}^n, \mathbb{R}^m)$ implies $\|A\| < \infty$ and $A : \mathbb{R}^n \rightarrow \mathbb{R}^m$ uniformly continuous.
 - (b) $A, B \in L(\mathbb{R}^n, \mathbb{R}^m)$ and $c \in \mathbb{C}$ implies

$$\|A + B\| \leq \|A\| + \|B\| \qquad \|cA\| = |c|\|A\|$$
 - Defining $d(A, B) = \|A - B\|$ makes $L(\mathbb{R}^n, \mathbb{R}^m)$ a metric space.
 - (c) $A \in L(\mathbb{R}^n, \mathbb{R}^m)$ and $B \in L(\mathbb{R}^m, \mathbb{R}^k)$ implies

$$\|BA\| \leq \|B\|\|A\|$$
 - Theorem 9.8: Let Ω be the set of all invertible linear operators on \mathbb{R}^n .
 - (a) $A \in \Omega$, $B \in L(\mathbb{R}^n)$, and $\|B - A\| \cdot \|A^{-1}\| < 1$ implies $B \in \Omega$.

Proof. Let $\|A^{-1}\| = 1/\alpha$, and let $\|B - A\| = \beta$. Then

$$\begin{aligned}\|B - A\| \cdot \|A^{-1}\| &< 1 \\ \beta \cdot \frac{1}{\alpha} &< 1 \\ \beta &< \alpha\end{aligned}$$

To prove that $B \in \Omega$, the definition of invertibility and Theorem 9.5 tell us that it will suffice to show that B is 1-1. To do so, it will suffice to show that $B\mathbf{x} = \mathbf{0}$ iff $\mathbf{x} = \mathbf{0}$. Let's begin. Let $\mathbf{x} \in \mathbb{R}^n$ be arbitrary. Then

$$\begin{aligned}\alpha|\mathbf{x}| &= \alpha\|A^{-1}A\mathbf{x}\| \leq \alpha\|A^{-1}\| \cdot \|A\mathbf{x}\| = \|A\mathbf{x}\| \leq \|(A - B)\mathbf{x}\| + \|B\mathbf{x}\| \leq \beta|\mathbf{x}| + \|B\mathbf{x}\| \\ (\alpha - \beta)|\mathbf{x}| &\leq \|B\mathbf{x}\|\end{aligned}$$

It follows that if $\mathbf{x} \neq \mathbf{0}$, then $\|B\mathbf{x}\| > 0$. This combined with the fact that $B\mathbf{0} = \mathbf{0}$ implies the desired result. \square

(b) Ω is open in $L(\mathbb{R}^n)$ and $A \mapsto A^{-1}$ is continuous on Ω .

Proof. To prove that Ω is open in $L(\mathbb{R}^n)$, it will suffice to show that for all $A \in \Omega$, there exists $N_r(A)$ such that if $\|B - A\| < r$, then $B \in \Omega$. Let's begin. Let $A \in \Omega$ be arbitrary. Choose $N_\alpha(A)$ to be our neighborhood, where α is defined as in part (a). Let $B \in L(\mathbb{R}^n)$ satisfy $\|B - A\| < \alpha$. Then $\|B - A\| \cdot \|A^{-1}\| < 1$, so $B \in \Omega$ by part (a), as desired.

To prove that $A \mapsto A^{-1}$ is continuous, it will suffice to show that $\|B^{-1} - A^{-1}\| \rightarrow 0$ as $B \rightarrow A$. First off, we have by part (a) and the substitution $\mathbf{x} = B^{-1}\mathbf{y}$ ($\mathbf{y} \in \mathbb{R}^n$) that

$$\begin{aligned}(\alpha - \beta)\|B^{-1}\mathbf{y}\| &\leq \|B B^{-1}\mathbf{y}\| = \|\mathbf{y}\| \\ \left\| B^{-1} \left(\frac{\mathbf{y}}{\|\mathbf{y}\|} \right) \right\| &\leq (\alpha - \beta)^{-1}\end{aligned}$$

Thus, since $\|B^{-1}\mathbf{u}\|$ is bounded by $(\alpha - \beta)^{-1}$ for every unit vector $\mathbf{u} \in \mathbb{R}^n$, $\|B^{-1}\|$ is bounded by $(\alpha - \beta)^{-1}$. This combined with the fact that

$$\begin{aligned}B^{-1} - A^{-1} &= B^{-1}I - IA^{-1} \\ &= B^{-1}AA^{-1} - B^{-1}BA^{-1} \\ &= B^{-1}(A - B)A^{-1}\end{aligned}$$

implies by Theorem 9.7c that

$$\|B^{-1} - A^{-1}\| \leq \|B^{-1}\| \|A - B\| \|A^{-1}\| \leq (\alpha - \beta)^{-1} \cdot \beta \cdot \frac{1}{\alpha} = \frac{\beta}{\alpha(\alpha - \beta)}$$

Therefore, since $\beta \rightarrow 0$ as $B \rightarrow A$, the above inequality establishes the desired result. \square

- Note that the mapping $A \mapsto A^{-1}$ defined in Theorem 9.8b is a 1-1 mapping of Ω onto Ω and its own inverse.
- Defines matrices, column vectors, and matrix multiplication.
- From the Schwarz inequality, we can show that

$$\|A\| \leq \left(\sum_{i,j} a_{i,j}^2 \right)^{1/2}$$

- “If S is a metric space, if a_{11}, \dots, a_{mn} are real continuous functions on S , and if for each $p \in S$, A_p is the linear transformation of \mathbb{R}^n into \mathbb{R}^m whose matrix has entries $a_{ij}(p)$, then the mapping $p \rightarrow A_p$ is a continuous mapping of S into $L(\mathbb{R}^n, \mathbb{R}^m)$ ” (Rudin, 1976, p. 211).

- Rudin (1976) spends some time motivating the definition of the total derivative. He also discusses the natural 1-1 correspondence between \mathbb{R}^1 and $L(\mathbb{R}^1)$.
- Defines differentiability in \mathbb{R}^n .
- Theorem 9.12: A_1, A_2 the derivative of \mathbf{f} at \mathbf{x} implies $A_1 = A_2$.
- If $\mathbf{f} : E \rightarrow \mathbb{R}^m$ where $E \subset \mathbb{R}^n$, then $\mathbf{f}' : E \rightarrow L(\mathbb{R}^n, \mathbb{R}^m)$.
- \mathbf{f} differentiable implies \mathbf{f} continuous.
- Example (\mathbf{f} is linear):
 - If $A \in L(\mathbb{R}^n, \mathbb{R}^m)$, then $A'(\mathbf{x}) = A$ for all $\mathbf{x} \in \mathbb{R}^n$. Note that this means that $A' : \mathbb{R}^n \rightarrow L(\mathbb{R}^n, \mathbb{R}^m)$, as expected.
- Theorem 9.15 (Chain Rule): E open in \mathbb{R}^n , $\mathbf{f} : E \rightarrow \mathbb{R}^m$ differentiable at $\mathbf{x}_0 \in E$, $I \supset \mathbf{f}(E)$ open in \mathbb{R}^m , and $\mathbf{g} : I \rightarrow \mathbb{R}^k$ differentiable at $\mathbf{f}(\mathbf{x}_0)$ implies $\mathbf{F} : E \rightarrow \mathbb{R}^k$ defined by

$$\mathbf{F}(\mathbf{x}) = \mathbf{g}(\mathbf{f}(\mathbf{x}))$$

is differentiable at \mathbf{x}_0 with

$$\mathbf{F}'(\mathbf{x}_0) = \mathbf{g}'(\mathbf{f}(\mathbf{x}_0))\mathbf{f}'(\mathbf{x}_0)^{[1]}$$

Proof. Largely symmetric to that of the one-dimensional chain rule in Chapter 5. □

- **Components** (of $\mathbf{f} : \mathbb{R}^n \rightarrow \mathbb{R}^m$): The real functions f_1, \dots, f_m defined by

$$\mathbf{f}(\mathbf{x}) = \sum_{i=1}^m f_i(\mathbf{x})\mathbf{u}_i$$

for all $\mathbf{x} \in E$ or, equivalently, by $f_i(\mathbf{x}) = \mathbf{f}(\mathbf{x}) \cdot \mathbf{u}_i$ ($1 \leq i \leq m$), where $\mathbf{u}_1, \dots, \mathbf{u}_m$ is the standard basis of \mathbb{R}^m .

- Defines partial derivatives.
- Theorem 9.17: $E \subset \mathbb{R}^n$ open and $\mathbf{f} : E \rightarrow \mathbb{R}^m$ differentiable at $\mathbf{x} \in E$ imply the partial derivatives $(D_j f_i)(\mathbf{x})$ exist and

$$\mathbf{f}'(\mathbf{x})\mathbf{e}_j = \sum_{i=1}^m (D_j f_i)(\mathbf{x})\mathbf{u}_i$$

for $1 \leq j \leq n$.

- It follows that

$$[\mathbf{f}'(\mathbf{x})] = \begin{bmatrix} (D_1 f_1)(\mathbf{x}) & \cdots & (D_n f_1)(\mathbf{x}) \\ \vdots & & \vdots \\ (D_1 f_m)(\mathbf{x}) & \cdots & (D_n f_m)(\mathbf{x}) \end{bmatrix}$$

- Discusses the gradient and the directional derivative.
- Theorem 9.19: $E \subset \mathbb{R}^n$ convex and open, $\mathbf{f} : E \rightarrow \mathbb{R}^m$ differentiable in E , and there exists M such that

$$\|\mathbf{f}'(\mathbf{x})\| \leq M$$

for all $\mathbf{x} \in E$ implies

$$|\mathbf{f}(\mathbf{b}) - \mathbf{f}(\mathbf{a})| \leq M|\mathbf{b} - \mathbf{a}|$$

for all $\mathbf{a}, \mathbf{b} \in E$.

¹Note that the right-hand side of this equation contains the product of two linear transformations.

- Corollary: If, in addition, $\mathbf{f}'(\mathbf{x}) = \mathbf{0}$ for all $\mathbf{x} \in E$, then \mathbf{f} is constant.
- **Continuously differentiable** (mapping $\mathbf{f} : E \rightarrow \mathbb{R}^m$): A function $\mathbf{f} : E \rightarrow \mathbb{R}^m$ such that $\mathbf{f}' : E \rightarrow L(\mathbb{R}^n, \mathbb{R}^m)$ is continuous. Also known as \mathcal{C}^1 -mapping. Denoted by $\mathbf{f} \in \mathcal{C}^1(E)$.
- Theorem 9.21: Let $E \subset \mathbb{R}^n$ open and $\mathbf{f} : E \rightarrow \mathbb{R}^m$. Then $\mathbf{f} \in \mathcal{C}^1(E)$ iff the partial derivatives $D_j f_i$ ($1 \leq i \leq m; 1 \leq j \leq n$) exist and are continuous on E .

2/20:

- **Contraction** (of X into X): A function $\varphi : X \rightarrow X$ for which there exists a number $c < 1$ such that

$$d(\varphi(x), \varphi(y)) \leq c \cdot d(x, y)$$

for all $x, y \in X$, where X is a metric space with metric d .

- Theorem 9.23: X a complete metric space and ϕ a contraction of X into X implies there exists a unique $x \in X$ such that $\varphi(x) = x$.

Proof. Let $x_0 \in X$ be arbitrary. Define $\{x_n\}$ recursively by

$$x_{n+1} = \phi(x_n)$$

for $n = 0, 1, 2, \dots$. Let $c < 1$ be the number corresponding to the contraction φ . Then for $n \geq 1$, we have

$$d(x_{n+1}, x_n) = d(\varphi(x_n), \varphi(x_{n-1})) \leq c \cdot d(x_n, x_{n-1})$$

or, for $n \geq 0$,

$$d(x_{n+1}, x_n) \leq c^n d(x_1, x_0)$$

by induction. Now to prove that $\{x_n\}$ is Cauchy, it will suffice to show that for all $\epsilon > 0$, there exists N such that $m \geq n \geq N$ implies $d(x_n, x_m) < \epsilon$. But since

$$\begin{aligned} d(x_n, x_m) &\leq \sum_{i=n+1}^m d(x_i, x_{i-1}) \\ &\leq (c^n + c^{n+1} + \dots + c^{m-1})d(x_1, x_0) \\ &\leq [(1-c)^{-1}d(x_1, x_0)]c^n \end{aligned}$$

we can simply choose N large enough that $[(1-c)^{-1}d(x_1, x_0)]c^N < \epsilon$. Thus, since $\{x_n\}$ is Cauchy and X is complete, there exists $x \in X$ such that $\lim_{n \rightarrow \infty} x_n = x$. Therefore, since φ is Lipschitz continuous, we have that

$$\varphi(x) = \lim_{n \rightarrow \infty} \varphi(x_n) = \lim_{n \rightarrow \infty} x_{n+1} = x$$

as desired.

Now suppose for the sake of contradiction that there exists $y \neq x$ such that $\varphi(y) = y$. Then since φ is a contraction,

$$d(y, x) = d(\varphi(y), \varphi(x)) \leq c \cdot d(y, x) < d(y, x)$$

a contradiction. □

- Theorem 9.24 (Inverse Function Theorem): $E \subset \mathbb{R}^n$ open, $\mathbf{f} : E \rightarrow \mathbb{R}^n$ a \mathcal{C}^1 -mapping, $\mathbf{f}'(\mathbf{a})$ invertible for some $\mathbf{a} \in E$, and $\mathbf{b} = \mathbf{f}(\mathbf{a})$ implies

- (a) There exist $U, V \subset \mathbb{R}^n$ open with $\mathbf{a} \in U$, $\mathbf{b} \in V$ such that \mathbf{f} is 1-1 on U and $\mathbf{f}(U) = V$.

Proof. Let $A = \mathbf{f}'(\mathbf{a})$. Choose λ such that

$$2\lambda \|A^{-1}\| = 1$$

Define^[2] for each $\mathbf{y} \in \mathbb{R}^n$ a function φ by

$$\varphi(\mathbf{x}) = \mathbf{x} + A^{-1}(\mathbf{y} - \mathbf{f}(\mathbf{x}))$$

for all $\mathbf{x} \in E$. (Note that a key property of φ is that as defined, $\mathbf{f}(\mathbf{x}) = \mathbf{y}$ iff \mathbf{x} is a fixed point of \mathbf{y} .) Now since $\mathbf{f} \in \mathcal{C}^1$ and hence \mathbf{f}' is continuous at \mathbf{a} , there exists an open ball $B_r(\mathbf{a}) \subset E$ such that

$$\|\mathbf{f}'(\mathbf{x}) - A\| < \lambda$$

for all $\mathbf{x} \in B_r(\mathbf{a})$. Let $U = B_r(\mathbf{a})$. Clearly it follows that U is open. Thus, since each $\varphi'(\mathbf{x}) = I - A^{-1}\mathbf{f}'(\mathbf{x}) = A^{-1}(A - \mathbf{f}'(\mathbf{x}))$, we have that

$$\|\varphi'(\mathbf{x})\| \leq \|A^{-1}\| \|A - \mathbf{f}'(\mathbf{x})\| < \frac{1}{2\lambda} \cdot \lambda = \frac{1}{2}$$

Consequently, we have by Theorem 9.19 that for all $\mathbf{x}_1, \mathbf{x}_2 \in U$,

$$|\varphi(\mathbf{x}_1) - \varphi(\mathbf{x}_2)| \leq \frac{1}{2} |\mathbf{x}_1 - \mathbf{x}_2|$$

Thus, by the uniqueness argument in the proof of Theorem 9.23, φ has at most one fixed point in U , so $\mathbf{f}(\mathbf{x}) = \mathbf{y}$ for at most one $\mathbf{x} \in U$. Therefore, \mathbf{f} is 1-1 on U .

Let $V = \mathbf{f}(U)$. To prove that V is open, it will suffice to show that for all $\mathbf{y}_0 \in V$, there exists an open subset of V containing \mathbf{y}_0 such that. Let $\mathbf{y}_0 \in V$ be arbitrary. By the definition of V as the image of U under \mathbf{f} , there exists $\mathbf{x}_0 \in U$ such that $\mathbf{f}(\mathbf{x}_0) = \mathbf{y}_0$. As such, choose $B_r(\mathbf{x}_0)$ such that $\overline{B} \subset U$. Pick \mathbf{y} satisfying $|\mathbf{y} - \mathbf{y}_0| < \lambda r$. Then

$$|\varphi(\mathbf{x}_0) - \mathbf{x}_0| = |A^{-1}(\mathbf{y} - \mathbf{y}_0)| < \|A\| \lambda r = \frac{r}{2}$$

so for all $\mathbf{x} \in \overline{B}$,

$$\begin{aligned} |\varphi(\mathbf{x}) - \mathbf{x}_0| &\leq |\varphi(\mathbf{x}) - \varphi(\mathbf{x}_0)| + |\varphi(\mathbf{x}_0) - \mathbf{x}_0| \\ &< \frac{1}{2} |\mathbf{x} - \mathbf{x}_0| + \frac{r}{2} \\ &\leq \frac{1}{2} \cdot r + \frac{r}{2} \\ &= r \end{aligned}$$

Thus, $\varphi(\mathbf{x}_0) \in B$. Moreover, since $|\varphi(\mathbf{x}_1) - \varphi(\mathbf{x}_2)| \leq \frac{1}{2} |\mathbf{x}_1 - \mathbf{x}_2|$ naturally holds for all $\mathbf{x}_1, \mathbf{x}_2 \in \overline{B} \subset U$, we have that φ is a contraction of \overline{B} into \overline{B} . Additionally, since $\overline{B} \subset \mathbb{R}^n$ is closed, it is a complete metric space under the Euclidean metric. Thus, Theorem 9.23 implies that φ has a fixed point $\mathbf{x} \in \overline{B}$. In particular, $\mathbf{f}(\mathbf{x}) = \mathbf{y}$. Therefore, $\mathbf{y} \in f(\overline{B}) \subset \mathbf{f}(U) = V$, as desired. \square

(b) If \mathbf{g} is the inverse of \mathbf{f} on V [which exists by (a)], i.e.,

$$\mathbf{g}(\mathbf{f}(\mathbf{x})) = \mathbf{x}$$

for all $\mathbf{x} \in U$, then $\mathbf{g} \in \mathcal{C}^1(V)$.

Proof. We first show that for all $\mathbf{y} \in V$, $\mathbf{g}'(\mathbf{y}) = [\mathbf{f}'(\mathbf{g}(\mathbf{y}))]^{-1}$. Let $\mathbf{y} \in V$ be arbitrary, and choose \mathbf{k} such that $(\mathbf{y} + \mathbf{k}) \in V$. It follows by part (a) that there exist $\mathbf{x}, \mathbf{x} + \mathbf{h} \in U$ such that $\mathbf{y} = \mathbf{f}(\mathbf{x})$ and $\mathbf{y} + \mathbf{k} = \mathbf{f}(\mathbf{x} + \mathbf{h})$. Thus,

$$\varphi(\mathbf{x} + \mathbf{h}) - \varphi(\mathbf{x}) = \mathbf{h} + A^{-1}[\mathbf{f}(\mathbf{x}) - \mathbf{f}(\mathbf{x} + \mathbf{h})] = \mathbf{h} - A^{-1}\mathbf{k}$$

so

$$|\mathbf{h} - A^{-1}\mathbf{k}| = |\varphi(\mathbf{x} + \mathbf{h}) - \varphi(\mathbf{x})| \leq \frac{1}{2} |\mathbf{x} + \mathbf{h} - \mathbf{x}| = \frac{1}{2} |\mathbf{h}|$$

²How do we motivate this definition?

Consequently, $|A^{-1}\mathbf{k}| \geq \frac{1}{2}|\mathbf{h}|$, so

$$|\mathbf{h}| \leq 2\|A^{-1}\|\|\mathbf{k}\| = \frac{\|\mathbf{k}\|}{\lambda}$$

Additionally, we know that $\|\mathbf{f}'(\mathbf{x}) - A\|\|A^{-1}\| = 1/2 < 1$, so Theorem 9.8a implies that $\mathbf{f}'(\mathbf{x})$ is invertible with an inverse that we may call T . Thus, since

$$\begin{aligned} \mathbf{g}(\mathbf{y} + \mathbf{k}) - \mathbf{g}(\mathbf{y}) - T\mathbf{k} &= \mathbf{h} - T\mathbf{k} \\ &= -T[(\mathbf{y} + \mathbf{k}) - \mathbf{y}] + T\mathbf{f}'(\mathbf{x})\mathbf{h} \\ &= -T[\mathbf{f}(\mathbf{x} + \mathbf{h}) - \mathbf{f}(\mathbf{x}) - \mathbf{f}'(\mathbf{x})\mathbf{h}] \end{aligned}$$

we have that

$$\frac{|\mathbf{g}(\mathbf{y} + \mathbf{k}) - \mathbf{g}(\mathbf{y}) - T\mathbf{k}|}{\|\mathbf{k}\|} \leq \frac{\|T\|\|\mathbf{f}(\mathbf{x} + \mathbf{h}) - \mathbf{f}(\mathbf{x}) - \mathbf{f}'(\mathbf{x})\mathbf{h}\|}{\lambda|\mathbf{h}|}$$

Consequently, $\mathbf{k} \rightarrow \mathbf{0}$ implies that $\mathbf{h} \rightarrow \mathbf{0}$, which implies that the right side of the above inequality goes to zero, which implies that the left side of the above inequality goes to zero. Thus, $\mathbf{g}'(\mathbf{y}) = T$, so

$$\mathbf{g}'(\mathbf{y}) = [\mathbf{f}'(\mathbf{g}(\mathbf{y}))]^{-1}$$

for all $\mathbf{y} \in V$, as desired.

To prove that \mathbf{g}' is continuous on V , Theorem 4.7 and the above equation tell us that it will suffice to show that $\mathbf{g} : V \rightarrow U$ is continuous, $\mathbf{f}' : U \rightarrow L(\mathbb{R}^n)$ is continuous, and $M \mapsto M^{-1} : L(\mathbb{R}^n) \rightarrow L(\mathbb{R}^n)$ is continuous. But we have the first condition since differentiability implies continuity and \mathbf{g} is differentiable, we have the second condition since $\mathbf{f} \in \mathcal{C}^1$ by hypothesis, and we have the third condition by Theorem 9.8b, as desired. \square

- Theorem 9.25: $E \subset \mathbb{R}^n$ open, $\mathbf{f} : E \rightarrow \mathbb{R}^n$ a \mathcal{C}^1 -mapping, and $\mathbf{f}'(\mathbf{x})$ invertible for all $\mathbf{x} \in E$ implies $\mathbf{f}(W)$ open in \mathbb{R}^n for every open $W \subset E$.
 - Note that the hypotheses of this theorem guarantee that \mathbf{f} is locally 1-1 at each $\mathbf{x} \in E$, but it may not be 1-1 in E under these conditions (see Exercise 9.17).