Chapter 9

Functions of Several Variables

9.1 Notes

2/14:

- Plan:
  1. Warm-up with matrices.
  2. The total derivatives of $f : \mathbb{R}^n \to \mathbb{R}^m$ ($n = m = 2$, i.e., $f : \mathbb{C} \to \mathbb{C}$).
  3. Basic properties: Chain rule, relation with partial derivatives, implicit function theorem.
- Let V, W be finite-dimensional vector spaces over $\mathbb{R}$. We let $L(V, W)$ be the vector space of all linear transformations $\phi : V \to W$.
- If we pick bases $\mathbf{v}_1, \dots, \mathbf{v}_n$ of V and $\mathbf{w}_1, \dots, \mathbf{w}_m$ of W, then $V \cong \mathbb{R}^n$ and $W \cong \mathbb{R}^m$. It follows that $L(V, W) \cong \mathbb{R}^{mn}$.
- $L(V, W) \times L(W, U) \xrightarrow{\text{compose}} L(V, U)$, i.e., $\mathbb{R}^{mn} \times \mathbb{R}^{nl} \xrightarrow[\text{mult.}]{\text{matrix}} \mathbb{R}^{ml}$.
- Sup norm: If A is an $m \times n$ real matrix, then $\|A\| = \sup_{\substack{\mathbf{x} \in \mathbb{R}^n \\ |\mathbf{x}|=1}} |A\mathbf{x}|$.
  - Basic properties:
    1. $|A\mathbf{x}| \leq \|A\||x|$.
    2. $\|A\| < \infty$ and all $A : \mathbb{R}^n \to \mathbb{R}^m$ are uniformly continuous.
    3. $\|A\| = 0 \iff A = 0$.
    4. $\|cA\| = |c|\|A\|$.
    5. $\|A + B\| \leq \|A\| + \|B\|$.
    6. $\|AB\| \leq \|A\|\|B\|$.
  - Note that we get a metric space structure on $L(V, W)$ by defining $d(A, B) = \|A - B\|$.
- Proves that 1 and 2 imply the uniform continuity of all A (via Lipschitz continuity).
- **Differentiable** (function $\mathbf{f}$ at $\mathbf{x}_0$): A function $\mathbf{f} : U \to \mathbb{R}^m$ ($U \subset \mathbb{R}^n$) such that to $\mathbf{x}_0 \in U$ there corresponds some linear transformation $A : \mathbb{R}^n \to \mathbb{R}^m$ such that

$$\lim_{\mathbf{h} \to \mathbf{0}} \frac{|\mathbf{f}(\mathbf{x}_0 - \mathbf{h}) - \mathbf{f}(\mathbf{x}_0) - A\mathbf{h}|}{|\mathbf{h}|} = 0$$

- **Total derivative** (of $\mathbf{f}$ at $\mathbf{x}_0$): The linear transformation A in the above definition. *Denoted by* $\mathbf{f'(x_0)}$, $\boldsymbol{D}\mathbf{f(x_0)}$, $\boldsymbol{d}\mathbf{f(x_0)}$.
- "An proof and progress in mathematics" - Thurston.

- Relating to the old one dimensional derivative.
- A paper we'd find rather impressionistic right now.

- Propositions ahead of us.
  - Proposition: Suppose that $\mathbf{f}$ is differentiable at $\mathbf{x}_0 \in U$ and A, B are both derivatives of $\mathbf{f}$ at $\mathbf{x}_0$. Then $A = B$.
  - Proposition: Differentiable implies continuous.
  - Proposition: Sum rule, product rule, quotient rule.

2/16: • Plan: Derivatives of functions $\mathbf{f} : U \to \mathbb{R}^m$ where $U \subset \mathbb{R}^n$.
  - Basic properties: Differentiability implies continuity, $(\mathbf{f}+\mathbf{g})' = \mathbf{f}' + \mathbf{g}'$, $(c\mathbf{f})' = c\mathbf{f}'$, chain rule, $\mathbf{f}' = 0$ iff $\mathbf{f}$ is constant.
  - Relationship with partial derivatives (how we compute everything and anything).
  - When is $\mathbf{f}$ differentiable?
  - Inverse function theorem.
  - Implicit function theorem.

- **Continuously differentiable** (function $\mathbf{f}$): A function $\mathbf{f} : U \to \mathbb{R}^m$ that is differentiable for all $\mathbf{x}_0 \in U$ and such that $\mathbf{f}' : U \to L(\mathbb{R}^n, \mathbb{R}^m)$ is continuous. *Also known as* $\boldsymbol{\mathscr{C}^1}$.

- Proposition: Let $\mathbf{f} : U \to \mathbb{R}^m$ be differentiable at $\mathbf{x}_0 \in U$. Then $\mathbf{f}$ is continuous at $\mathbf{x}_0$.
  - The proof makes use of the fact that $\mathbf{f}(\mathbf{x}_0 + \mathbf{h}) - \mathbf{f}(\mathbf{x}_0) = \mathbf{f}'(\mathbf{x}_0)\mathbf{h} + \mathbf{r}(\mathbf{h})$.

- Proposition: Given $\mathbf{f}, \mathbf{g} : U \to \mathbb{R}^m$ both differentiable at $\mathbf{x}_0 \in U$, then $\mathbf{f} + \mathbf{g}$ is also differentiable at $\mathbf{x}_0$ with
$$(\mathbf{f}+\mathbf{g})'(\mathbf{x}_0) = \mathbf{f}'(\mathbf{x}_0) + \mathbf{g}'(\mathbf{x}_0)$$
  - The proof is immediate via the triangle inequality.

- Theorem (Chain Rule): Given $\mathbf{f} : U \to \mathbb{R}^m$ and $\mathbf{g} : V \to \mathbb{R}^k$, where $U \subset \mathbb{R}^n$ and $\mathbf{f}(U) \subset V \subset \mathbb{R}^m$, with $\mathbf{f}$ differentiable at $\mathbf{x}_0 \in U$ and $\mathbf{g}$ differentiable at $\mathbf{f}(\mathbf{x}_0)$, the composition $\mathbf{g} \circ \mathbf{f}$ is differentiable at $\mathbf{x}_0$ with
$$(\mathbf{g} \circ \mathbf{f})'(\mathbf{x}_0) = \mathbf{g}'(\mathbf{f}(\mathbf{x}_0)) \cdot \mathbf{f}'(\mathbf{x}_0)$$
  - The proof is rather subtle.

- **Partial derivative** (of f_i wrt. x_j at $\mathbf{x}_0$): The following limit, if it exists, where $f_i : \mathbb{R}^n \to \mathbb{R}$, $1 \leq i \leq m$, and $1 \leq j \leq n$. *Denoted by* $\boldsymbol{(\partial f_i / \partial x_j)(\mathbf{x}_0)}$, $\boldsymbol{(D_j f_i)(\mathbf{x}_0)}$. *Given by*
$$\frac{\partial f_i}{\partial x_j}(\mathbf{x_0}) = \lim_{t \to 0} \frac{f_i(\mathbf{x}_0 + t\mathbf{e}_j) - f_i(\mathbf{x}_0)}{t}$$

- **Directional derivative** (of f_i toward $\mathbf{u} \in \mathbb{R}^n$): The following limit, if it exists, where $f_i : \mathbb{R}^n \to \mathbb{R}$ and $1 \leq i \leq m$. *Denoted by* $\boldsymbol{D_{\mathbf{u}} f_i}$. *Given by*
$$D_{\mathbf{u}} f_i = \lim_{t \to 0} \frac{f_i(\mathbf{x}_0 + t\mathbf{u}) - f_i(\mathbf{x}_0)}{t}$$

- **Jacobian**: The following matrix. *Given by*
$$\left[\frac{\partial f_i}{\partial x_j}(\mathbf{x}_0) \right]$$

- Theorem: Let $\mathbf{f} = (f_1, \dots, f_m) : U \to \mathbb{R}^m$, where $U \subset \mathbb{R}^n$, be differentiable at some $\mathbf{x}_0 \in U$. Then the partial derivatives $\partial f_i / \partial x_j$ ($1 \leq i \leq m$; $1 \leq j \leq n$) exist at $\mathbf{x}_0$ and, with respect to the usual choice of bases,

$$\mathbf{f}'(\mathbf{x}_0) = \left[\frac{\partial f_i}{\partial x_j}(\mathbf{x}_0)\right]$$

2/18:
  - We have that
$$\mathbf{f}(\mathbf{x}_0 + t\mathbf{e}_j) - \mathbf{f}(\mathbf{x}_0) = \mathbf{f}'(\mathbf{x}_0)(t\mathbf{e}_j) + \mathbf{r}(t\mathbf{e}_j)$$
  - Since $\mathbf{f}$ is differentiable at $\mathbf{x}_0$, $\mathbf{f}(t\mathbf{e}_j)/t \to 0$ as $t \to 0$.
  - Additionally, $\mathbf{f}'(\mathbf{x}_0)(t\mathbf{e}_j)/t = \mathbf{f}'(\mathbf{x}_0)(\mathbf{e}_j)$.
  - Therefore,
$$\lim_{t \to 0} \frac{\mathbf{f}(\mathbf{x}_0 + t\mathbf{e}_j) - \mathbf{f}(\mathbf{x}_0)}{t} = \lim_{t \to 0} \frac{\mathbf{f}'(\mathbf{x}_0)(t\mathbf{e}_j) - \mathbf{r}(t\mathbf{e}_j)}{t} = \mathbf{f}'(\mathbf{x}_0)(\mathbf{e}_j) - \lim_{t \to 0} \frac{\mathbf{r}(t\mathbf{e}_j)}{t} = \mathbf{f}'(\mathbf{x}_0)(\mathbf{e}_j)$$
    as desired.
  - Unpacking the definition of the linear transformation as a matrix gives the rest of the proof.
- Today:
  - More on differentiation (recall the Jacobian).
  - Sufficient condition for differentiability.
  - $\mathbf{f}' = 0$ iff $\mathbf{f}$ is constant.
  - State the inverse function theorem.
- It is not true that having all partials exist implies that $\mathbf{f}$ is differentiable at $\mathbf{x}_0$.
- Theorem: $\mathbf{f}$ continuously differentiable at $\mathbf{x}_0$ iff all partials exist and are continuous at $\mathbf{x}_0$.

2/21:
- Contraction mapping theorem.

2/23:
- Plan.
  1. Proof of the inverse function theorem.
  2. Commuting partials.
- Theorem (Inverse function theorem): If $E \subset \mathbb{R}^n$ open, $\mathbf{f} : E \to \mathbb{R}^n$ is differentiable at $\mathbf{x}_0 \in E$, and $\mathbf{f}'(\mathbf{x}_0)$ is invertible, then there exist $U \subset E$ open with $\mathbf{x}_0 \in U$ and $V \subset \mathbb{R}^n$ open with $\mathbf{f}(\mathbf{x}_0) \in V$ such that $\mathbf{f}|_U : U \to V$ is a bijection and $(\mathbf{f}|_U)^{-1}$ is continuously differentiable.
- Idea.
  1. Find U and prove one-to-one restricted to U.
  2. $\mathbf{f}(U)$ is open.
  3. Prove the inverse is continuously differentiable (left as an exercise to us).
  - There is a trick for 1-2: We introduce an auxiliary function $\varphi_{\mathbf{y}}$ and apply the contraction mapping theorem.
- Proof.
  - Let $A = \mathbf{f}'(\mathbf{x}_0)$.
  - Since $\mathbf{f}'$ is continuous, there is an open ball $U \subset E$ with center $\mathbf{x}_0$ such that $\|\mathbf{f}'(\mathbf{x}) - A\| < \lambda$ for all $\mathbf{x} \in U$.
    - We'll pick $\lambda = 1/(2\|A^{-1}\|)$ without motivation for now.

- Note that if you need to pick a U (for an example function), this criterion gives you one (not necessarily the best one, but it gives you a one).

- Trick: For all $\mathbf{y} \in \mathbb{R}^n$, consider $\varphi_{\mathbf{y}} : U \to \mathbb{R}^n$ defined by

$$\varphi_{\mathbf{y}}(\mathbf{x}) = \mathbf{x} + A^{-1}(\mathbf{y} - \mathbf{f}(\mathbf{x}))$$

  - Important property of this function: $\mathbf{f}(\mathbf{x}) = \mathbf{y}$ iff $\varphi_{\mathbf{y}}(\mathbf{x}) = \mathbf{x}$.

- Plan: Show that for all $\mathbf{y} \in \mathbf{f}(U)$ that $\varphi_{\mathbf{y}}$ is a contraction. Therefore, by the contraction mapping theorem, $\mathbf{f}$ has exactly 1 fixed point, so $\mathbf{f}|_U$ is injective.
- Proving that $\varphi_{\mathbf{y}}$ is a contraction. Claim: $|\varphi_{\mathbf{y}}(\mathbf{x}_1) - \varphi_{\mathbf{y}}(\mathbf{x}_2)| \leq \frac{1}{2}|\mathbf{x}_1 - \mathbf{x}_2|$. Use the Chain Rule, MVT, and the fact that $\|AB\| \leq \|A\|\|B\|$.
  - Using the chain rule, we have that

$$\begin{aligned}\varphi'_{\mathbf{y}} &= I - A^{-1}\mathbf{f}'(\mathbf{x}) \\ &= A^{-1}(A - \mathbf{f}'(\mathbf{x}))\end{aligned}$$

  - Thus,

$$\|\varphi_{\mathbf{y}}(\mathbf{x})\| \leq \left\|A^{-1}\right\|\|A - \mathbf{f}'(\mathbf{x})\| < \frac{1}{2}$$

    for all $\mathbf{x}$.
  - It follows by the MVT that

$$|\varphi_{\mathbf{y}}(\mathbf{x}_1) - \varphi_{\mathbf{y}}(\mathbf{x}_2)| \leq \frac{1}{2}|\mathbf{x}_1 - \mathbf{x}_2|$$

  - Therefore, $\varphi_{\mathbf{y}}$ is a contraction.
- We now prove that $\mathbf{f}(U)$ is open.
- Let $\mathbf{y}_0 \in f(U)$ be such that $\mathbf{y}_0 = f(\mathbf{p}_0)$.
- Pick $B_r(\mathbf{p}_0) \subset U$ such that $\overline{B} \subset U$.
- Claim: For all $\mathbf{y} \in \mathbb{R}^n$ with $|\mathbf{y} - \mathbf{y}_0| < \lambda r$, we have that $\mathbf{y} \in \mathbf{f}(U)$.
  - We are going to show that $\varphi_{\mathbf{y}}(\overline{B}) \subset \overline{B}$ and therefore $\varphi_{\mathbf{y}} : \overline{B} \to \overline{B}$ is a contraction and therefore by the contraction mapping theorem, there exists a fixed point $\mathbf{x}_{\mathbf{y}}$ of $\varphi_{\mathbf{y}}$ in $\overline{B}$. Therefore, $\mathbf{f}(\mathbf{x}_{\mathbf{y}}) = \mathbf{y}$ and so $\mathbf{f}(U)$ is open.

- φ_y is derived from Newton's method. The contraction mapping thing then is what substitutes for convergence. You have to start in the right area though, the chosen U!

2/25:

- Plan:
  1. A point on the IFT.
  2. Commuting partials.
  3. Implicit function theorem.
- Subtle point: Last time, in the proof of the IFT, we first found the $U \subset E$ and prove that $\mathbf{f}|_U$ is injective, and then we proved that $\mathbf{f}(U)$ is open.
- The properties of $\varphi_{\mathbf{y}}$.
  - $\varphi_{\mathbf{y}}(U) \subset U$.
  - $\varphi_{\mathbf{y}}$ is a contraction since $|\varphi_{\mathbf{y}}(\mathbf{x}_1) - \varphi_{\mathbf{y}}(\mathbf{x}_2)| \leq \frac{1}{2}|\mathbf{x}_1 - \mathbf{x}_2|$.
  - $\mathbf{f}(\mathbf{x}) = \mathbf{y}$ iff $\varphi_{\mathbf{y}}(\mathbf{x}) = \mathbf{x}$ (fixed points for this contraction mapping).
- Commuting partials.

  - When does the following hold?
$$\frac{\partial^2 f}{\partial x_j \partial x_i} = \frac{\partial^2 f}{\partial x_j \partial x_i}$$
  - Simple answer: Not often, but with enough regularity, yes.
- Theorem: Given $f : E \to \mathbb{R}$ where $E \subset \mathbb{R}^n$, we say that f is C^2 (or of class C^2)
- **Class $\boldsymbol{C^2}$** (function f): A function $f : E \to \mathbb{R}$ (where $E \subset \mathbb{R}^n$) such that all partials $\partial^2 f / \partial x_j \partial x_i$ exist and are continuous for all points in E. *Denoted by* $\boldsymbol{f \in C^2}$.
- Lemma (MVT): If $E \subset \mathbb{R}^2$ open, $f : E \to \mathbb{R}$, $\partial f/\partial x$, $\partial^2 f/\partial y \partial x$ exist for all $(x, y) \in E$, $Q = [a, a + h] \times [b, b + k] \subset E$, and
$$\Delta(f, Q) = f(a + h, b + k) - f(a + h, b) + f(a, b + k) - f(a, b)$$
then there exists $(x_0, y_0) \in Q$ such that
$$\Delta(f, Q) = hk \frac{\partial^2}{\partial y \partial x}(x_0, y_0)$$
  - Proof idea: We reduce to the goal of the 1D MVT.
  - Define $u(t) = f(t, b + k) - f(t, b)$. Then u is differentiable by the sum and scalar multiple rules.
  - It follows that
$$\begin{aligned}\Delta(f, Q) &= u(a + h) - u(a) \\ &= hu'(x_0) \\ &= h\left[\frac{\partial f}{\partial x} - \frac{\partial f}{\partial x}\right] \\ &= hk \frac{\partial^2}{\partial y \partial x}(x_0, y_0)\end{aligned}$$
- Theorem: If $f \in C^2$, then
$$\frac{\partial^2 f}{\partial x_j \partial x_i} = \frac{\partial^2 f}{\partial x_j \partial x_i}$$
for all $1 \leq i, j \leq n$.
- Idea.
  - To make life easy, take $n = 2$. Then we just need the right kind of mean value theorem (the one in the lemma).
- Proof.
  - Follows from the lemma as $h, k \to 0$.
  - See Theorem 15.3 in Labalme (2021).

2/28:
- Plan:
  1. Implicit function theorem (end of Chapter 9).
  2. Sharkovsky's theorem.
  3. Go back and talk about Chapter 8 material.

- Theorem (Implicit Function Theorem; informal): Given a nice system of equations

$$\begin{aligned} f_1(c_1,\dots,x_n,y_1,\dots,y_m) &= 0 \\ &\vdots \\ f_n(x_1,\dots,x_n,y_1,\dots,y_m) &= 0 \end{aligned}$$

  and a particular solution $(\mathbf{a},\mathbf{b})$, we can solve for $\mathbf{y}=(y_1,\dots,y_m)$ locally at $(\mathbf{a},\mathbf{b})$.

- Theorem (Implicit Function Theorem): If $E\subset\mathbb{R}^{n+m}$, $\mathbf{f}:E\to\mathbb{R}^n$ continuously differentiable, $(\mathbf{a},\mathbf{b})\in E$ with $\mathbf{f}(\mathbf{a},\mathbf{b})=\mathbf{0}$, $A=\mathbf{f}'(\mathbf{a},\mathbf{b})$, $A_{\mathbf{x}}:\mathbb{R}^n\to\mathbb{R}^n$ defined by $\mathbf{x}\mapsto\mathbf{f}'(\mathbf{a},\mathbf{b})(\mathbf{x},\mathbf{0})$ invertible, and $A_{\mathbf{y}}:\mathbb{R}^m\to\mathbb{R}^n$ defined by $\mathbf{y}\mapsto\mathbf{f}'(\mathbf{a},\mathbf{b})(\mathbf{0},\mathbf{y})$, then there exists $U\subset\mathbb{R}^{n+m}$, $W\subset\mathbb{R}^m$ with $(\mathbf{a},\mathbf{b})\in U$, $\mathbf{b}\in W$ such that:
  1. For every $\mathbf{y}\in W$, there exists a unique $\mathbf{x}\in\mathbb{R}^n$ such that $(\mathbf{x},\mathbf{y})\in U$ and $\mathbf{f}(\mathbf{x},\mathbf{y})=\mathbf{0}$.
  2. There is a continuously differentiable function $\mathbf{g}:W\to\mathbb{R}^n$ such that

     $$\mathbf{f}(\mathbf{g}(\mathbf{y}),\mathbf{y})=\mathbf{0}$$

     for all $\mathbf{y}\in W$ and

     $$\mathbf{g}'(\mathbf{b})=-(A_{\mathbf{x}})^{-1}A_{\mathbf{y}}$$

- Example: Consider $f:\mathbb{R}^{1+1}\to\mathbb{R}$ defined by $(x,y)\mapsto x^2+y^2-1$.
  - Then $f^{-1}(\{0\})$ is the unit circle.
  - $Df=\begin{bmatrix}2x & 2y\end{bmatrix}$, $A_x=\begin{bmatrix}2x\end{bmatrix}$, and $A_y=\begin{bmatrix}2y\end{bmatrix}$.
- Idea:
  - Use the inverse function theorem, and apply it to $A_{\mathbf{x}}$.
  - Goal: Find U and W; from this, $\mathbf{g}$ follows uniquely (though you also technically need to show continuous differentiability).
  - Define $F:E\to\mathbb{R}^{n+m}$ by $F(\mathbf{x},\mathbf{y})=(\mathbf{f}(\mathbf{x},\mathbf{y}),\mathbf{y})$. Claim: $F'(\mathbf{a},\mathbf{b})$ is invertible. Apply the inverse function theorem to F.
- Proof left to us.
- The goal of Sharkovsky's theorem is to understand the iterates of f, i.e., $x,f(x),f^2(x),f^3(x),\dots$. This fits in thematically with the contraction mapping theorem.
- **Periodic** (point $p\in I$): A point $p\in I$ for which $f^m(p)=p$ for some $m\in\mathbb{N}$.
- **Period** (of $p\in I$ periodic): The least number m such that $f^m(p)=p$.
- **Fixed point**: A periodic point of period 1.
- Example: $f:[0,1]\to[0,1]$ defined by $f(x)=1-x$ has periodic points of period 2 everywhere on its domain save 1/2, which has period 1.
- Theorem: If f has a point p of period 3, then f has points of all other periods.
- **Sharkovsky ordering**: All of the odd numbers, then 2^1 times the odd numbers, then 2^2 times the odd numbers, then continuing for $n\to\infty$, and then 2^n as large as possible all the way down to 1.
  - If n comes before m in the Sharkovsky ordering, we write $n\triangleright m$.
- Sharkovsky's theorem: If $A\subset\mathbb{R}$, $f:A\to\mathbb{R}$ continuous satisfies $f(A)\subset A$ and has a period m point with $m\triangleright l$, then f has a period l point.
- Example: Logistic maps $g_b:[0,1]\to[0,1]$ defined by $x\mapsto bx(1-x)$ for $b\in[1,4]$.

3/2:

- Theorem (Li & Yorke): If f has a period 3 point, then there exists an uncountable set $S \subset A$ such that for all $p, q \in S$,

$$\liminf_{n\to\infty} |f^n(p) - f^n(q)| = 0 \qquad \limsup_{n\to\infty} |f^n(p) - f^n(q)| > 0$$

- Plan:
  1. Prove the warm-up to Sharkovsky.
- Theorem: If f continuous has a period 3 point, then f has points of all other periods.
- Notation.
  - We say "I covers J" and write $I \to J$ when $I, J \subset A$ are closed intervals with $f(I) \supset J$.
- Lemma 1: If $[a,b] \to [a,b]$, then f continuous has a fixed point in $[a,b]$.
  - Consider $f(x) - x$ on $[a,b]$.
  - Either $f(a) = a$, $f(b) = b$, or we can invoke the IVT.
  - Alternatively, since $[a,b] \subset f([a,b])$, there exist a_0, b_0 with $f(a_0) = a$ and $f(b_0) = b$. Thus, $f(a_0) - a_0 \leq 0$ and $f(b_0) - b_0 \geq 0$, so by the IVT, there is some zero of $f(x) - x$ on $[a,b]$, as desired.
- Lemma 2: p has period m iff p is a fixed point of f^m and not a fixed point of f^i for $i < m$.
- Lemma 3: Suppose we have a loop of intervals $J_0 \to J_1 \to J_2 \to \cdots \to J_{n-1} \to J_0 \to \cdots$. Then there is a fixed point $p \in J_0$ of f^n such that $f^i(p) \in J_i$ for all $0 \leq i < n$.

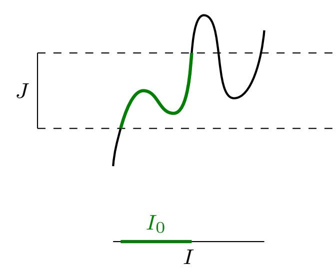

Figure 9.1: Loop mapping.

  - Isn't this obvious? No – there's an issue, namely that $f(J_i) \not\subset J_{i+1}$. We can solve this though by noting that if $I \to J$, then there exists some subinterval $I_0 \subset I$ such that $f(I_0) \subset J$ and $I_0 \to J$ (i.e., $f(I_0) = J$).
  - You can use this idea to pull a J_i' out of each J_i for which set equality holds.
  - Then by the previous lemma, there exists a fixed point p of f^n in J_0'. Then $f(p) \in J_1' \subset J_1, \dots, f^{n-1}(p) \in J_{n-1}' \subset J_{n-1}$.
- Notation.
  - In the case of Lemma 3, we say that p is **following** the cycle $J_0 \to \cdots \to J_{n-1} \to J_0 \to \cdots$.
  - We call $J_0 \to \cdots \to J_{n-1} \to J_0 \to \cdots$ **elementary** if it is only followed by points of period n.
- Lemma: Let q have period m and let $\mathcal{O} = \{q, f(q), \dots, f^{m-1}(q)\}$. Let $J_0 \to \cdots \to J_{n-1} \to J_0 \to \cdots$ and suppose
  (i) all endpoints of the J_i are in $\mathcal{O}$;

(ii) the loop is not followed by any point in $\mathcal{O}$;

(iii) The interior of J_0, $\operatorname{int}(J_0)$ is disjoint from the other J_i.

Then the loop is elementary, and so f has a period n point.

- Suppose p follows the loop.
- Then by (i) and (ii), p is not an endpoint of J_0, so if $f^i(p) = p \in J_0$ for $i < n$, then $\operatorname{int}(J_0) \cap J_i$, contradicting (iii).

3/4:

- Plan:
  1. Finish 3 implies all $m \in \mathbb{N}$.
  2. Hint at the rest of Sharkovsky.
  3. Power series/fun with the exponential function (Chapter 8).
- Theorem (warm-up Sharkovsky): If $f : I \to \mathbb{R}$ continuous, $f(I) \subset I$, and f has a period 3 point, then f has a period n point for all $n \in \mathbb{N}$.
  - Consider the three point loop.
  - Let I_1 be the interval from p_0 to p_1, and let I_2 be the interval from p_1 to p_2. We can choose p_0, p_1, p_2 WLOG such that $I_1 \cap I_2 = \{p_1\}$.
  - We have $I_1 \to I_2$, $I_2 \to I_2$, and $I_2 \to I_1$.
  - We may construct
  $$I_1 \underbrace{\to I_2}_{\substack{m-1\\\text{times}}} \to I_1$$
  to yield a point of period m by the last lemma.
  - Period 1 point: $I_2 \to I_2$ apply Lemma 1.

9.2 Chapter 9: Functions of Several Variables

From Rudin (1976).

2/15:

- Defines a vector space by the closure of its elements under addition and scalar multiplication.
- Defines a linear combination, span, independence and dependence, dimension, basis, coordinates, and the standard basis.
- Theorem 9.2: If X is spanned by r vectors, $\dim X \leq r$.
- Corollary: $\dim \mathbb{R}^n = n$.
- Theorem 9.3: Let X a vector space with $\dim X = n$.
  (a) $E \subset X$ containing n vectors spans X iff E is independent.
  (b) X has a basis, and every basis contains n vectors.
  (c) If $1 \leq r \leq n$ and $\{\mathbf{y}_1, \dots, \mathbf{y}_r\}$ is independent in X, then X has a basis containing $\{\mathbf{y}_1, \dots, \mathbf{y}_r\}$.
- Defines linear transformation, linear operator.
- Notes that $A\mathbf{0} = \mathbf{0}$ if A is a linear transformation, and that A is completely determined by its action on any basis.
- **Invertible** (linear operator): A linear operator A that is one-to-one and onto.
- Theorem 9.5: A a linear operator on X finite-dimensional is one-to-one iff it is onto.

- Defines $L(X,Y)$, $L(X)$, the product BA of two linear transformations, and the supremum norm of a linear transformation.
- Theorem 9.7:
  (a) $A \in L(\mathbb{R}^n, \mathbb{R}^m)$ implies $\|A\| < \infty$ and $A : \mathbb{R}^n \to \mathbb{R}^m$ uniformly continuous.
  (b) $A, B \in L(\mathbb{R}^n, \mathbb{R}^m)$ and $c \in \mathbb{C}$ implies
  $$\|A+B\| \leq \|A\| + \|B\| \qquad\qquad \|cA\| = |c|\|A\|$$
  Defining $d(A,B) = \|A - B\|$ makes $L(\mathbb{R}^n, \mathbb{R}^m)$ a metric space.
  (c) $A \in L(\mathbb{R}^n, \mathbb{R}^m)$ and $B \in L(\mathbb{R}^m, \mathbb{R}^k)$ implies
  $$\|BA\| \leq \|B\|\|A\|$$
- Theorem 9.8: Let Ω be the set of all invertible linear operators on $\mathbb{R}^n$.
  (a) $A \in \Omega$, $B \in L(\mathbb{R}^n)$, and $\|B - A\| \cdot \left\|A^{-1}\right\| < 1$ implies $B \in \Omega$.

  Proof. Let $\left\|A^{-1}\right\| = 1/\alpha$, and let $\|B - A\| = \beta$. Then
  $$\begin{aligned} \|B - A\| \cdot \left\|A^{-1}\right\| &< 1 \\ \beta \cdot \frac{1}{\alpha} &< 1 \\ \beta &< \alpha \end{aligned}$$
  To prove that $B \in \Omega$, the definition of invertibility and Theorem 9.5 tell us that it will suffice to show that B is 1-1. To do so, it will suffice to show that $B\mathbf{x} = \mathbf{0}$ iff $\mathbf{x} = \mathbf{0}$. Let's begin. Let $\mathbf{x} \in \mathbb{R}^n$ be arbitrary. Then
  $$\begin{aligned} \alpha|\mathbf{x}| = \alpha|A^{-1}A\mathbf{x}| \leq \alpha\left\|A^{-1}\right\| \cdot |Ax| = |A\mathbf{x}| \leq |(A-B)\mathbf{x}| + |B\mathbf{x}| \leq \beta|\mathbf{x}| + |B\mathbf{x}| \\ (\alpha - \beta)|\mathbf{x}| \leq |B\mathbf{x}| \end{aligned}$$
  It follows that if $\mathbf{x} \neq \mathbf{0}$, then $|B\mathbf{x}| > 0$. This combined with the fact that $B\mathbf{0} = \mathbf{0}$ implies the desired result. ☐

  (b) Ω is open in $L(\mathbb{R}^n)$ and $A \mapsto A^{-1}$ is continuous on Ω.

  Proof. To prove that Ω is open in $L(\mathbb{R}^n)$, it will suffice to show that for all $A \in \Omega$, there exists $N_r(A)$ such that if $\|B - A\| < r$, then $B \in \Omega$. Let's begin. Let $A \in \Omega$ be arbitrary. Choose $N_\alpha(A)$ to be our neighborhood, where α is defined as in part (a). Let $B \in L(\mathbb{R}^n)$ satisfy $\|B - A\| < \alpha$. Then $\|B - A\| \cdot \left\|A^{-1}\right\| < 1$, so $B \in \Omega$ by part (a), as desired.

  To prove that $A \mapsto A^{-1}$ is continuous, it will suffice to show that $\left\|B^{-1} - A^{-1}\right\| \to 0$ as $B \to A$. First off, we have by part (a) and the substitution $\mathbf{x} = B^{-1}\mathbf{y}$ ($\mathbf{y} \in \mathbb{R}^n$) that
  $$\begin{aligned} (\alpha - \beta)|B^{-1}\mathbf{y}| \leq |BB^{-1}\mathbf{y}| = |\mathbf{y}| \\ \left|B^{-1}\left(\frac{\mathbf{y}}{|\mathbf{y}|}\right)\right| \leq (\alpha - \beta)^{-1} \end{aligned}$$
  Thus, since $|B^{-1}\mathbf{u}|$ is bounded by $(\alpha - \beta)^{-1}$ for every unit vector $\mathbf{u} \in \mathbb{R}^n$, $\left\|B^{-1}\right\|$ is bounded by $(\alpha - \beta)^{-1}$. This combined with the fact that
  $$\begin{aligned} B^{-1} - A^{-1} &= B^{-1}I - IA^{-1} \\ &= B^{-1}AA^{-1} - B^{-1}BA^{-1} \\ &= B^{-1}(A - B)A^{-1} \end{aligned}$$

implies by Theorem 9.7c that

$$\|B^{-1} - A^{-1}\| \leq \|B^{-1}\|\|A - B\|\|A^{-1}\| \leq (\alpha - \beta)^{-1} \cdot \beta \cdot \frac{1}{\alpha} = \frac{\beta}{\alpha(\alpha - \beta)}$$

Therefore, since $\beta \to 0$ as $B \to A$, the above inequality establishes the desired result. □

- Note that the mapping $A \mapsto A^{-1}$ defined in Theorem 9.8b is a 1-1 mapping of Ω onto Ω and its own inverse.
- Defines matrices, column vectors, and matrix multiplication.
- From the Schwarz inequality, we can show that

$$\|A\| \leq \left(\sum_{i,j} a_{i,j}^2 \right)^{1/2}$$

- "If S is a metric space, if $a_{11}, \dots, a_{mn}$ are real continuous functions on S, and if for each $p \in S$, A_p is the linear transformation of $\mathbb{R}^n$ into $\mathbb{R}^m$ whose matrix has entries $a_{ij}(p)$, then the mapping $p \to A_p$ is a continuous mapping of S into $L(\mathbb{R}^n, \mathbb{R}^m)$" (Rudin, 1976, p. 211).
- Rudin (1976) spends some time motivating the definition of the total derivative. He also discusses the natural 1-1 correspondence between $\mathbb{R}^1$ and $L(\mathbb{R}^1)$.
- Defines differentiability in $\mathbb{R}^n$.
- Theorem 9.12: A_1, A_2 the derivative of $\mathbf{f}$ at $\mathbf{x}$ implies $A_1 = A_2$.
- If $\mathbf{f} : E \to \mathbb{R}^m$ where $E \subset \mathbb{R}^n$, then $\mathbf{f}' : E \to L(\mathbb{R}^n, \mathbb{R}^m)$.
- $\mathbf{f}$ differentiable implies $\mathbf{f}$ continuous.
- Example ($\mathbf{f}$ is linear):
  - If $A \in L(\mathbb{R}^n, \mathbb{R}^m)$, then $A'(\mathbf{x}) = A$ for all $\mathbf{x} \in \mathbb{R}^n$. Note that this means that $A' : \mathbb{R}^n \to L(\mathbb{R}^n, \mathbb{R}^m)$, as expected.
- Theorem 9.15 (Chain Rule): E open in $\mathbb{R}^n$, $\mathbf{f} : E \to \mathbb{R}^m$ differentiable at $\mathbf{x}_0 \in E$, $I \supset \mathbf{f}(E)$ open in $\mathbb{R}^m$, and $\mathbf{g} : I \to \mathbb{R}^k$ differentiable at $\mathbf{f}(\mathbf{x}_0)$ implies $\mathbf{F} : E \to \mathbb{R}^k$ defined by

$$\mathbf{F}(\mathbf{x}) = \mathbf{g}(\mathbf{f}(\mathbf{x}))$$

is differentiable at $\mathbf{x}_0$ with

$$\mathbf{F}'(\mathbf{x}_0) = \mathbf{g}'(\mathbf{f}(\mathbf{x}_0))\mathbf{f}'(\mathbf{x}_0)$$ [1]

Proof. Largely symmetric to that of the one-dimensional chain rule in Chapter 5. □

- **Components** (of $\mathbf{f} : \mathbb{R}^n \to \mathbb{R}^m$): The real functions $f_1, \dots, f_m$ defined by

$$\mathbf{f}(\mathbf{x}) = \sum_{i=1}^{m} f_i(\mathbf{x})\mathbf{u}_i$$

for all $\mathbf{x} \in E$ or, equivalently, by $f_i(\mathbf{x}) = f(\mathbf{x}) \cdot \mathbf{u}_i$ ($1 \leq i \leq m$), where $\mathbf{u}_1, \dots, \mathbf{u}_m$ is the standard basis of $\mathbb{R}^m$.

[1] Note that the right-hand side of this equation contains the product of two linear transformations.

- Defines partial derivatives.
- Theorem 9.17: $E \subset \mathbb{R}^n$ open and $\mathbf{f} : E \to \mathbb{R}^m$ differentiable at $\mathbf{x} \in E$ imply the partial derivatives $(D_j f_i)(\mathbf{x})$ exist and
$$\mathbf{f}'(\mathbf{x})\mathbf{e}_j = \sum_{i=1}^{m} (D_j f_i)(\mathbf{x})\mathbf{u}_i$$
for $1 \leq j \leq n$.
- It follows that
$$[\mathbf{f}'(\mathbf{x})] = \begin{bmatrix} (D_1 f_1)(\mathbf{x}) & \cdots & (D_n f_1)(\mathbf{x}) \\ \vdots & & \vdots \\ (D_1 f_m)(\mathbf{x}) & \cdots & (D_n f_m)(\mathbf{x}) \end{bmatrix}$$
- Discusses the gradient and the directional derivative.
- Theorem 9.19: $E \subset \mathbb{R}^n$ convex and open, $\mathbf{f} : E \to \mathbb{R}^m$ differentiable in E, and there exists M such that
$$\|\mathbf{f}'(\mathbf{x})\| \leq M$$
for all $\mathbf{x} \in E$ implies
$$|\mathbf{f}(\mathbf{b}) - \mathbf{f}(\mathbf{a})| \leq M|\mathbf{b} - \mathbf{a}|$$
for all $\mathbf{a}, \mathbf{b} \in E$.
- Corollary: If, in addition, $\mathbf{f}'(\mathbf{x}) = \mathbf{0}$ for all $\mathbf{x} \in E$, then $\mathbf{f}$ is constant.
- **Continuously differentiable** (mapping $\mathbf{f} : E \to \mathbb{R}^m$): A function $\mathbf{f} : E \to \mathbb{R}^m$ such that $\mathbf{f}' : E \to L(\mathbb{R}^n, \mathbb{R}^m)$ is continuous. *Also known as* $\boldsymbol{\mathscr{C}^1}$**-mapping**. *Denoted by* $\mathbf{f} \in \boldsymbol{\mathscr{C}^1(E)}$.
- Theorem 9.21: Let $E \subset \mathbb{R}^n$ open and $\mathbf{f} : E \to \mathbb{R}^m$. Then $\mathbf{f} \in \mathscr{C}^1(E)$ iff the partial derivatives $D_j f_i$ $(1 \leq i \leq m;\ 1 \leq j \leq n)$ exist and are continuous on E.

2/20:

- **Contraction** (of X into X): A function $\varphi : X \to X$ for which there exists a number $c < 1$ such that
$$d(\varphi(x), \varphi(y)) \leq c \cdot d(x, y)$$
for all $x, y \in X$, where X is a metric space with metric d.
- Theorem 9.23: X a complete metric space and ϕ a contraction of X into X implies there exists a unique $x \in X$ such that $\varphi(x) = x$.

Proof. Let $x_0 \in X$ be arbitrary. Define $\{x_n\}$ recursively by
$$x_{n+1} = \phi(x_n)$$
for $n = 0, 1, 2, \ldots$. Let $c < 1$ be the number corresponding to the contraction φ. Then for $n \geq 1$, we have
$$d(x_{n+1}, x_n) = d(\varphi(x_n), \varphi(x_{n-1})) \leq c \cdot d(x_n, x_{n-1})$$
or, for $n \geq 0$,
$$d(x_{n+1}, x_n) \leq c^n d(x_1, x_0)$$
by induction. Now to prove that $\{x_n\}$ is Cauchy, it will suffice to show that for all $\epsilon > 0$, there exists N such that $m \geq n \geq N$ implies $d(x_n, x_m) < \epsilon$. But since
$$\begin{aligned} d(x_n, x_m) &\leq \sum_{i=n+1}^{m} d(x_i, x_{i-1}) \\ &\leq (c^n + c^{n+1} + \cdots + c^{m-1}) d(x_1, x_0) \\ &\leq [(1-c)^{-1} d(x_1, x_0)] c^n \end{aligned}$$

we can simply choose N large enough that $[(1-c)^{-1}d(x_1,x_0)]c^N < \epsilon$. Thus, since $\{x_n\}$ is Cauchy and X is complete, there exists $x \in X$ such that $\lim_{n\to\infty} x_n = x$. Therefore, since φ is Lipschitz continuous, we have that

$$\varphi(x) = \lim_{n\to\infty} \varphi(x_n) = \lim_{n\to\infty} x_{n+1} = x$$

as desired.

Now suppose for the sake of contradiction that there exists $y \neq x$ such that $\varphi(y) = y$. Then since φ is a contraction,

$$d(y,x) = d(\varphi(y),\varphi(x)) \leq c \cdot d(y,x) < d(y,x)$$

a contradiction. □

- Theorem 9.24 (Inverse Function Theorem): $E \subset \mathbb{R}^n$ open, $\mathbf{f} : E \to \mathbb{R}^n$ a $\mathscr{C}^1$-mapping, $\mathbf{f}'(\mathbf{a})$ invertible for some $\mathbf{a} \in E$, and $\mathbf{b} = \mathbf{f}(\mathbf{a})$ implies
  (a) There exist $U, V \subset \mathbb{R}^n$ open with $\mathbf{a} \in U$, $\mathbf{b} \in V$ such that $\mathbf{f}$ is 1-1 on U and $\mathbf{f}(U) = V$.

Proof. Let $A = \mathbf{f}'(\mathbf{a})$. Choose λ such that

$$2\lambda\left\|A^{-1}\right\| = 1$$

Define[2] for each $\mathbf{y} \in \mathbb{R}^n$ a function φ by

$$\varphi(\mathbf{x}) = \mathbf{x} + A^{-1}(\mathbf{y} - \mathbf{f}(\mathbf{x}))$$

for all $\mathbf{x} \in E$. (Note that a key property of φ is that as defined, $\mathbf{f}(\mathbf{x}) = \mathbf{y}$ iff $\mathbf{x}$ is a fixed point of $\mathbf{y}$.) Now since $\mathbf{f} \in \mathscr{C}^1$ and hence $\mathbf{f}'$ is continuous at $\mathbf{a}$, there exists an open ball $B_r(\mathbf{a}) \subset E$ such that

$$\|\mathbf{f}'(\mathbf{x}) - A\| < \lambda$$

for all $\mathbf{x} \in B_r(\mathbf{a})$. Let $U = B_r(\mathbf{a})$. Clearly it follows that U is open. Thus, since each $\varphi'(\mathbf{x}) = I - A^{-1}\mathbf{f}'(\mathbf{x}) = A^{-1}(A - \mathbf{f}'(\mathbf{x}))$, we have that

$$\|\varphi'(\mathbf{x})\| \leq \left\|A^{-1}\right\|\|A - \mathbf{f}'(\mathbf{x})\| < \frac{1}{2\lambda} \cdot \lambda = \frac{1}{2}$$

Consequently, we have by Theorem 9.19 that for all $\mathbf{x}_1, \mathbf{x}_2 \in U$,

$$|\varphi(\mathbf{x}_1) - \varphi(\mathbf{x}_2)| \leq \frac{1}{2}|\mathbf{x}_1 - \mathbf{x}_2|$$

Thus, by the uniqueness argument in the proof of Theorem 9.23, φ has at most one fixed point in U, so $\mathbf{f}(\mathbf{x}) = \mathbf{y}$ for at most one $\mathbf{x} \in U$. Therefore, $\mathbf{f}$ is 1-1 on U.

Let $V = \mathbf{f}(U)$. To prove that V is open, it will suffice to show that for all $\mathbf{y}_0 \in V$, there exists an open subset of V containing $\mathbf{y}_0$ such that. Let $\mathbf{y}_0 \in V$ be arbitrary. By the definition of V as the image of U under $\mathbf{f}$, there exists $\mathbf{x}_0 \in U$ such that $\mathbf{f}(\mathbf{x}_0) = \mathbf{y}_0$. As such, choose $B_r(\mathbf{x}_0)$ such that $\overline{B} \subset U$. Pick $\mathbf{y}$ satisfying $|\mathbf{y} - \mathbf{y}_0| < \lambda r$. Then

$$|\varphi(\mathbf{x}_0) - \mathbf{x}_0| = |A^{-1}(\mathbf{y} - \mathbf{y}_0)| < \|A\|\lambda r = \frac{r}{2}$$

so for all $\mathbf{x} \in \overline{B}$,

$$\begin{aligned}
|\varphi(\mathbf{x}) - \mathbf{x}_0| &\leq |\varphi(\mathbf{x}) - \varphi(\mathbf{x}_0)| + |\varphi(\mathbf{x}_0) - \mathbf{x}_0| \\
&< \frac{1}{2}|\mathbf{x} - \mathbf{x}_0| + \frac{r}{2} \\
&\leq \frac{1}{2} \cdot r + \frac{r}{2} \\
&= r
\end{aligned}$$

[2]How do we motivate this definition?

Thus, $\varphi(\mathbf{x}_0) \in B$. Moreover, since $|\varphi(\mathbf{x}_1) - \varphi(\mathbf{x}_2)| \leq \frac{1}{2}|\mathbf{x}_1 - \mathbf{x}_2|$ naturally holds for all $\mathbf{x}_1, \mathbf{x}_2 \in \overline{B} \subset U$, we have that φ is a contraction of $\overline{B}$ into $\overline{B}$. Additionally, since $\overline{B} \subset \mathbb{R}^n$ is closed, it is a complete metric space under the Euclidean metric. Thus, Theorem 9.23 implies that φ has a fixed point $\mathbf{x} \in \overline{B}$. In particular, $\mathbf{f}(\mathbf{x}) = \mathbf{y}$. Therefore, $\mathbf{y} \in f(\overline{B}) \subset \mathbf{f}(U) = V$, as desired. $\square$

(b) If $\mathbf{g}$ is the inverse of $\mathbf{f}$ on V [which exists by (a)], i.e.,

$$\mathbf{g}(\mathbf{f}(\mathbf{x})) = \mathbf{x}$$

for all $\mathbf{x} \in U$, then $\mathbf{g} \in \mathscr{C}^1(V)$.

Proof. We first show that for all $\mathbf{y} \in V$, $\mathbf{g}'(\mathbf{y}) = [\mathbf{f}'(\mathbf{g}(\mathbf{y}))]^{-1}$. Let $\mathbf{y} \in V$ be arbitrary, and choose $\mathbf{k}$ such that $(\mathbf{y} + \mathbf{k}) \in V$. It follows by part (a) that there exist $\mathbf{x}, \mathbf{x} + \mathbf{h} \in U$ such that $\mathbf{y} = \mathbf{f}(\mathbf{x})$ and $\mathbf{y} + \mathbf{k} = \mathbf{f}(\mathbf{x} + \mathbf{h})$. Thus,

$$\varphi(\mathbf{x} + \mathbf{h}) - \varphi(\mathbf{x}) = \mathbf{h} + A^{-1}[\mathbf{f}(\mathbf{x}) - \mathbf{f}(\mathbf{x} + \mathbf{h})] = \mathbf{h} - A^{-1}\mathbf{k}$$

so

$$|\mathbf{h} - A^{-1}\mathbf{k}| = |\varphi(\mathbf{x} + \mathbf{h}) - \varphi(\mathbf{x})| \leq \frac{1}{2}|\mathbf{x} + \mathbf{h} - \mathbf{x}| = \frac{1}{2}|\mathbf{h}|$$

Consequently, $|A^{-1}\mathbf{k}| \geq \frac{1}{2}|\mathbf{h}|$, so

$$|\mathbf{h}| \leq 2\|A^{-1}\||\mathbf{k}| = \frac{|\mathbf{k}|}{\lambda}$$

Additionally, we know that $\|\mathbf{f}'(\mathbf{x}) - A\|\|A^{-1}\| = 1/2 < 1$, so Theorem 9.8a implies that $\mathbf{f}'(\mathbf{x})$ is invertible with an inverse that we may call T. Thus, since

$$\begin{aligned}\mathbf{g}(\mathbf{y} + \mathbf{k}) - \mathbf{g}(\mathbf{y}) - T\mathbf{k} = \mathbf{h} - T\mathbf{k}& \\ &= -T[(\mathbf{y} + \mathbf{k}) - \mathbf{y}] + T\mathbf{f}'(\mathbf{x})\mathbf{h} \\ &= -T[\mathbf{f}(\mathbf{x} + \mathbf{h}) - \mathbf{f}(\mathbf{x}) - \mathbf{f}'(\mathbf{x})\mathbf{h}]\end{aligned}$$

we have that

$$\frac{|\mathbf{g}(\mathbf{y} + \mathbf{k}) - \mathbf{g}(\mathbf{y}) - T\mathbf{k}|}{|\mathbf{k}|} \leq \frac{\|T\||\mathbf{f}(\mathbf{x} + \mathbf{h}) - \mathbf{f}(\mathbf{x}) - \mathbf{f}'(\mathbf{x})\mathbf{h}|}{\lambda|\mathbf{h}|}$$

Consequently, $\mathbf{k} \to \mathbf{0}$ implies that $\mathbf{h} \to \mathbf{0}$, which implies that the right side of the above inequality goes to zero, which implies that the left side of the above inequality goes to zero. Thus, $\mathbf{g}'(\mathbf{y}) = T$, so

$$\mathbf{g}'(\mathbf{y}) = [\mathbf{f}'(\mathbf{g}(\mathbf{y}))]^{-1}$$

for all $\mathbf{y} \in V$, as desired.

To prove that $\mathbf{g}'$ is continuous on V, Theorem 4.7 and the above equation tell us that it will suffice to show that $\mathbf{g} : V \to U$ is continuous, $\mathbf{f}' : U \to L(\mathbb{R}^n)$ is continuous, and $M \mapsto M^{-1} : L(\mathbb{R}^n) \to L(\mathbb{R}^n)$ is continuous. But we have the first condition since differentiability implies continuity and $\mathbf{g}$ is differentiable, we have the second condition since $\mathbf{f} \in \mathscr{C}^1$ by hypothesis, and we have the third condition by Theorem 9.8b, as desired. $\square$

- Theorem 9.25: $E \subset \mathbb{R}^n$ open, $\mathbf{f} :: E \to \mathbb{R}^n$ a $\mathscr{C}^1$-mapping, and $\mathbf{f}'(\mathbf{x})$ invertible for all $\mathbf{x} \in E$ implies $\mathbf{f}(W)$ open in $\mathbb{R}^n$ for every open $W \subset E$.
  - Note that the hypotheses of this theorem guarantee that $\mathbf{f}$ is locally 1-1 at each $\mathbf{x} \in E$, but it may not be 1-1 in E under these conditions (see Exercise 9.17).

3/7:

- Motivating the Implicit Function Theorem.
  - Suppose $f : \mathbb{R}^2 \to \mathbb{R}$ is continuously differentiable.
  - Consider the equation $f(x, y) = 0$. If (a, b) satisfies $f(a, b) = 0$ and $\partial f/\partial y \neq 0$, then we can solve for y in terms of x near (a, b).

- Why we must require that $\partial f/\partial y \neq 0$:
  - Suppose that $f(x,y)$ is constant in some neighborhood of (a,b). Then there are infinitely many values of y for each x. Consider the line in the plane $x = b$. Since f is constant in a neighborhood of b, the intersection of this line with $\{(x,y) : f(x,y) = 0\}$ will be a segment.
  - As another example, consider $f(x,y) = x^2+y^2-1$. $(1,0)$ satisfies $f(1,0) = 0$, but $\mathrm{d}f/\mathrm{d}y = 2y$, so $(\mathrm{d}f/\mathrm{d}y)|_{(x,y)=(1,0)} = 0$. And indeed, for any x slightly less than 1, there are two values of y (those on the upper and lower hemicircles) for which $f(x,y) = 0$, i.e., there is no one-to-one mapping.

- $(\mathbf{x},\mathbf{y})$: The vector $(x_1,\dots,x_n,y_1,\dots,y_m) \in \mathbb{R}^{n+m}$, where $\mathbf{x} = (x_1,\dots,x_n) \in \mathbb{R}^n$ and $\mathbf{y} = (y_1,\dots,y_m) \in \mathbb{R}^m$.

- Every $A \in L(\mathbb{R}^{n+m},\mathbb{R}^n)$ can be split into two linear transformations A_x, A_y defined by

$$A_x\mathbf{h} = A(\mathbf{h},\mathbf{0}) \qquad\qquad A_y\mathbf{k} = A(\mathbf{0},\mathbf{k})$$

  for all $\mathbf{h} \in \mathbb{R}^n$, $\mathbf{k} \in \mathbb{R}^m$.

  - It follows that

$$A(\mathbf{h},\mathbf{k}) = A_x\mathbf{h} + A_y\mathbf{k}$$

- Theorem 9.27: If $A \in L(\mathbb{R}^{n+m},\mathbb{R}^n)$ and A_x invertible, then to every $\mathbf{k} \in \mathbb{R}^m$ there corresponds a unique $\mathbf{h} \in \mathbb{R}^n$ such that $A(\mathbf{h},\mathbf{k}) = \mathbf{0}$. This $\mathbf{h}$ can be computed from $\mathbf{k}$ via the formula

$$\mathbf{h} = -(A_x)^{-1}A_y\mathbf{k}$$

  Proof. Let $\mathbf{k} \in \mathbb{R}^m$ be arbitrary. Since $A - x$ is invertible, the vector $\mathbf{h} = -(A_x)^{-1}A_y\mathbf{k}$ is well-defined and unique. It follows that

$$A(\mathbf{h},\mathbf{k}) = A_x\mathbf{h} + A_y\mathbf{k} = \mathbf{0}$$

  as desired. □

- Theorem 9.28 (Implicit Function Theorem): If $E \subset \mathbb{R}^{n+m}$ is open, $\mathbf{f} : E \to \mathbb{R}^n \in \mathscr{C}^1$, $(\mathbf{a},\mathbf{b}) \in E$ satisfies $\mathbf{f}(\mathbf{a},\mathbf{b}) = 0$, $A = \mathbf{f}'(\mathbf{a},\mathbf{b})$, and A_x is invertible, then there exist

$$U \subset \mathbb{R}^{n+m} \qquad\qquad W \subset \mathbb{R}^m$$

  open with $(\mathbf{a},\mathbf{b}) \in U$ and $\mathbf{b} \in W$ such that to every $\mathbf{y} \in W$ there corresponds a unique $\mathbf{x}$ such that

$$(\mathbf{x},\mathbf{y}) \in U \qquad\qquad \mathbf{f}(\mathbf{x},\mathbf{y}) = \mathbf{0}$$

  and if $\mathbf{g}(\mathbf{y}) = \mathbf{x}$, then $\mathbf{g} : W \to \mathbb{R}^n \in \mathscr{C}^1$, $\mathbf{g}(\mathbf{b}) = \mathbf{a}$, $\mathbf{f}(\mathbf{g}(\mathbf{y}),\mathbf{y}) = \mathbf{0}$ for all $\mathbf{y} \in W$, and $\mathbf{g}'(\mathbf{b}) = -(A_x)^{-1}A_y$.

3/8: *Proof.* Define $\mathbf{F} : E \to \mathbb{R}^{n+m}$ by

$$\mathbf{F}(\mathbf{x},\mathbf{y}) = (\mathbf{f}(\mathbf{x},\mathbf{y}),\mathbf{y})$$

for all $(\mathbf{x},\mathbf{y}) \in E$. Since $\mathbf{f} \in \mathscr{C}^1$ and $\mathbf{y} \mapsto \mathbf{y}$ is a $\mathscr{C}^1$-mapping as the identity function, $\mathbf{F} \in \mathscr{C}^1$.

To prove that $\mathbf{F}'(\mathbf{a},\mathbf{b}) = B$ is invertible, Theorem 9.5 tells us that it will suffice to show that it is 1-1. To do so, we will verify that $B(\mathbf{x},\mathbf{y}) = \mathbf{0}$ iff $(\mathbf{x},\mathbf{y}) = \mathbf{0}$. The forward case follows since B is a linear transformation. For the reverse case, however, we must first note that $B(\mathbf{x},\mathbf{y}) = (A(\mathbf{x},\mathbf{y}),\mathbf{y})$, which follows from the fact that $\mathbf{F}$ acts like $\mathbf{f}$ on its first n dimensions and then like the identity transformation thereafter (recall that the total derivative of a linear transformation is itself). With this established, the equation $B(\mathbf{x},\mathbf{y}) = \mathbf{0}$ tells us that $A(\mathbf{x},\mathbf{y}) = \mathbf{0}$ and $\mathbf{y} = \mathbf{0}$. Combining these two results, we have that $A(\mathbf{x},\mathbf{0}) = \mathbf{0}$. But by Theorem 9.27, it follows that $\mathbf{x} = -(A_x)^{-1}A_y\mathbf{0} = \mathbf{0}$. Therefore, $(\mathbf{x},\mathbf{y}) = \mathbf{0}$, as desired.

Having established that $E \subset \mathbb{R}^{n+m}$ is open, $\mathbf{F} : E \to \mathbb{R}^{n+m} \in \mathscr{C}^1$, $\mathbf{F}'(\mathbf{a}, \mathbf{b})$ is invertible, and $(\mathbf{0}, \mathbf{b}) = \mathbf{F}(\mathbf{a}, \mathbf{b})$, we have by Inverse Function Theorem that there exist open sets $U, V \in \mathbb{R}^{n+m}$ with $(\mathbf{a}, \mathbf{b}) \in U$ and $(\mathbf{0}, \mathbf{b}) \in V$ such that $\mathbf{F}$ is 1-1 on U and $\mathbf{F}(U) = V$. Let

$$W = \{\mathbf{y} \in \mathbb{R}^m : (\mathbf{0}, \mathbf{y}) \in V\}$$

The openness of W follows from the fact that V is open (and, technically, that the projection operator is continuous). It also clearly follows from the definition of W and the fact that $(\mathbf{0}, \mathbf{b}) \in V$ that $\mathbf{b} \in W$. Now let $\mathbf{y} \in W$ be arbitrary. Since $\mathbf{F}$ is 1-1 on U and $\mathbf{F}(U) = V$, there exists a unique $(\mathbf{x}, \mathbf{y}) \in U$ such that $\mathbf{F}(\mathbf{x}, \mathbf{y}) = (\mathbf{0}, \mathbf{y})$. Since $\mathbf{F}(\mathbf{x}, \mathbf{y}) = (\mathbf{f}(\mathbf{x}, \mathbf{y}), \mathbf{y})$, it follows that $\mathbf{f}(\mathbf{x}, \mathbf{y}) = \mathbf{0}$.

We formalize the notion that to every $\mathbf{y} \in W$ we can identify a unique $\mathbf{x} \in \mathbb{R}^n$ by the above rule by defining the function $\mathbf{g} : W \to \mathbb{R}^n$ such that $\mathbf{g}(\mathbf{y}) = \mathbf{x}$ for all $\mathbf{y} \in W$. It clearly follows by the definition of the function that $\mathbf{g}(\mathbf{b}) = \mathbf{a}$ and that $\mathbf{f}(\mathbf{g}(\mathbf{y}), \mathbf{y}) = \mathbf{0}$ for all $\mathbf{y} \in W$.

To verify that $\mathbf{g} \in \mathscr{C}^1$, note that the IVT also implies that if $\mathbf{G} : V \to U$ is such that $\mathbf{G}(\mathbf{F}(\mathbf{x}, \mathbf{y})) = (\mathbf{x}, \mathbf{y})$, then $\mathbf{G} \in \mathscr{C}^1$. Since $\mathbf{G}(\mathbf{0}, \mathbf{y}) = (\mathbf{g}(\mathbf{y}), \mathbf{y})$, it follows that $\mathbf{g} \in \mathscr{C}^1$.

Since $\mathbf{g} \in \mathscr{C}^1$, we know that $\mathbf{g}'(\mathbf{b})$ is well-defined.

By the definition of $\mathbf{f}$ and $\mathbf{G}$, we know that $\mathbf{f}(\mathbf{G}(\mathbf{0}, \mathbf{y})) = \mathbf{0}$ for all $\mathbf{y} \in W$. To take the derivative of the above expression with respect to changes in $\mathbf{y}$ only, define $\mathbf{\Phi} : W \to \mathbb{R}^{n+m}$ by $\mathbf{\Phi}(\mathbf{y}) = \mathbf{G}(\mathbf{0}, \mathbf{y})$. Thus, since $\mathbf{f} \circ \mathbf{\Phi}$ is constant on its domain, the chain rule implies that

$$\mathbf{f}'(\mathbf{\Phi}(\mathbf{y})) \cdot \mathbf{\Phi}'(\mathbf{y}) = 0$$

for all $\mathbf{y} \in W$. In particular,

$$\begin{aligned} 0 &= \mathbf{f}'(\mathbf{\Phi}(\mathbf{b})) \cdot \mathbf{\Phi}'(\mathbf{b}) \\ &= \mathbf{f}'(\mathbf{a}, \mathbf{b}) \cdot (\mathbf{g}(\mathbf{b}), \mathbf{b})' \\ &= A \cdot (\mathbf{g}'(\mathbf{b}), I) \\ &= A_x \mathbf{g}'(\mathbf{b}) + A_y I \\ \mathbf{g}'(\mathbf{b}) &= -(A_x)^{-1} A_y \end{aligned}$$

as desired. □

- Rudin (1976) discusses a number of topics from linear algebra.
- **Second-order partial derivative** (of f): A partial derivative of one of the partial derivatives of f, if it exists. *Denoted by* $\boldsymbol{D_{ij} f}$. *Given by*

$$D_{ij} f = D_i D_j f$$

- **Class $\mathscr{C}^2$** (function f): A function f for which $D_{ij} f$ is continuous on E for all $1 \leq i, j \leq n$.
- Theorem 9.40: If $E \subset \mathbb{R}^2$ open, $f : E \to \mathbb{R}$, $D_1 f, D_{21} f$ exist at every $(x, y) \in E$, $Q \subset E$ a closed rectangle with sides parallel to the coordinate axes having (a, b) and $(a + h, b + k)$ as opposite vertices (for $h, k \neq 0$), and

$$\Delta(f, Q) = f(a + h, b + k) - f(a + h, b) - f(a, b + k) + f(a, b)$$

then there exists $(x, y) \in \operatorname{int} Q$ such that

$$\Delta(f, Q) = hk(D_{21} f)(x, y)$$

- Theorem 9.41: If $E \subset \mathbb{R}^2$ is open, $f : E \to \mathbb{R}$, $D_1 f, D_{21} f, D_2 f$ exist on E, and $D_{21} f$ is continuous at $(a, b) \in E$, then $D_{12} f$ exists at (a, b) and

$$(D_{12} f)(a, b) = (D_{21} f)(a, b)$$

- Corollary: $D_{21} f = D_{12} f$ if $f \in \mathscr{C}^2(E)$.