

### 3 Operations on Forms

From Guillemin and Haine (2018).

#### Chapter 2

5/9: **2.4.i.** Compute the exterior derivatives of the following differential forms.

(1)  $x_1 dx_2 \wedge dx_3$ .

*Proof.* We have that

$$\begin{aligned} d(x_1 dx_2 \wedge dx_3) &= d(x_1 dx_2) \wedge dx_3 + (-1)^1 x_1 dx_2 \wedge d(dx_3) \\ &= dx_1 \wedge dx_2 \wedge dx_3 - x_1 dx_2 \wedge 0 \end{aligned}$$

$$\boxed{d(x_1 dx_2 \wedge dx_3) = dx_1 \wedge dx_2 \wedge dx_3}$$

□

(2)  $x_1 dx_2 - x_2 dx_1$ .

*Proof.* We have that

$$\begin{aligned} d(x_1 dx_2 - x_2 dx_1) &= d(x_1 dx_2) - d(x_2 dx_1) \\ &= dx_1 \wedge dx_2 - dx_2 \wedge dx_1 \\ &= dx_1 \wedge dx_2 + dx_1 \wedge dx_2 \end{aligned}$$

$$\boxed{d(x_1 dx_2 - x_2 dx_1) = 2 dx_1 \wedge dx_2}$$

□

(3)  $e^{-f} df$  where  $f = \sum_{i=1}^n x_i^2$ .

*Proof.* We state as a lemma first that

$$\begin{aligned} df &= \sum_{i=1}^n d(x_i^2) \\ &= 2 \sum_{i=1}^n x_i dx_i \end{aligned}$$

It follows that

$$\begin{aligned} d(e^{-f} df) &= d(e^{-f}) \wedge df \\ &= e^{-f} d(-f) \wedge df \\ &= -4e^{-f} \sum_{i=1}^n x_i dx_i \wedge \sum_{i=1}^n x_i dx_i \\ &= -4e^{-f} \sum_I x_{i_1} x_{i_2} dx_{i_1} \wedge dx_{i_2} \end{aligned}$$

where we sum over the multi-indices  $I$  of  $n$  of length 2. However, since all repeating multi-indices equal zero, we can eliminate those terms from the sum. Additionally, we can pair up all strictly increasing and strictly decreasing terms with the same two numbers (e.g.,  $(1, 2) \sim (2, 1)$ ,  $(1, 3) \sim (3, 1)$ , etc.). Invoking the anticommutative property, we can rewrite the sum such that we only sum over the non-repeating, strictly increasing multi-indices of  $n$  of length 2.

$$\boxed{d(e^{-f} df) = -4e^{-f} \sum_{1 \leq i_1 < i_2 \leq n} (x_{i_1} x_{i_2} - x_{i_2} x_{i_1}) dx_{i_1} \wedge dx_{i_2}}$$

□

(4)  $\sum_{i=1}^n x_i dx_i$ .

*Proof.* We have that

$$d\left(\sum_{i=1}^n x_i dx_i\right) = \sum_{i=1}^n d(x_i dx_i)$$

$$\boxed{d\left(\sum_{i=1}^n x_i dx_i\right) = \sum_{i=1}^n dx_i \wedge dx_i}$$

□

(5)  $\sum_{i=1}^n (-1)^i x_i dx_1 \wedge \cdots \wedge \widehat{dx_i} \wedge \cdots \wedge dx_n$ .

*Proof.* We have that

$$\begin{aligned} d\left(\sum_{i=1}^n (-1)^i x_i dx_1 \wedge \cdots \wedge \widehat{dx_i} \wedge \cdots \wedge dx_n\right) &= \sum_{i=1}^n (-1)^i d\left(x_i dx_1 \wedge \cdots \wedge \widehat{dx_i} \wedge \cdots \wedge dx_n\right) \\ &= \sum_{i=1}^n (-1)^i dx_i \wedge dx_1 \wedge \cdots \wedge \widehat{dx_i} \wedge \cdots \wedge dx_n \end{aligned}$$

$$\boxed{d\left(\sum_{i=1}^n (-1)^i x_i dx_1 \wedge \cdots \wedge \widehat{dx_i} \wedge \cdots \wedge dx_n\right) = -n dx_1 \wedge \cdots \wedge dx_n}$$

Note that we get from the second to the third line as follows: The  $i = 1$  term is

$$(-1)^1 dx_1 \wedge \widehat{dx_1} \wedge dx_2 \wedge \cdots \wedge dx_n = -dx_1 \wedge \cdots \wedge dx_n$$

The  $i = 2$  term is

$$\begin{aligned} (-1)^2 dx_2 \wedge dx_1 \wedge \widehat{dx_2} \wedge dx_3 \wedge \cdots \wedge dx_n &= (1) \cdot (-1)_{1,2}^T dx_1 \wedge \cdots \wedge dx_n \\ &= -dx_1 \wedge \cdots \wedge dx_n \end{aligned}$$

where we have used Claim 1.6.8<sup>[1]</sup> and the odd permutation  $\tau_{1,2}$  to rearrange the term. The  $i = 3$  term is

$$\begin{aligned} (-1)^3 dx_3 \wedge dx_1 \wedge dx_2 \wedge \widehat{dx_3} \wedge dx_4 \wedge \cdots \wedge dx_n &= (-1) \cdot (-1)^{\tau_{1,2}\tau_{2,3}} dx_1 \wedge \cdots \wedge dx_n \\ &= -dx_1 \wedge \cdots \wedge dx_n \end{aligned}$$

From here, we should be able to see that all  $n$  terms will evaluate to  $-dx_1 \wedge \cdots \wedge dx_n$ , so we can simply add them up and stick  $n$  out front as a coefficient. This intuitive justification can be formalized with an induction argument. □

**2.4.ii.** Solve the equation  $d\mu = \omega$  for  $\mu \in \Omega^1(\mathbb{R}^3)$ , where  $\omega$  is the 2-form...

*General Solution.* The following is a derivation of the general solution to the equation  $d\mu = \omega$ , where  $\omega$  is a two-form with the structure

$$\omega = f dx_i \wedge dx_j$$

Let  $\omega \in \Omega^2(U)$  be a two-form on  $U$  with the above structure. Notice that if we take  $\mu = g dx_j$  by inspection, then  $d\mu = dg \wedge dx_j$ . By comparing this equation with the definition of  $\omega$ , we can determine that

$$\begin{aligned} dg &= f dx_i \\ g &= \int f dx_i \end{aligned}$$

<sup>1</sup>Technically, we use the natural extension of Claim 1.6.8 to the wedge product of one-forms.

Therefore, the solution to  $d\mu = \omega$  is the one-form

$$\mu = \left( \int f \, dx_i \right) dx_j$$

□

(1)  $dx_2 \wedge dx_3$ .

*Proof.* Using the above formula, we have

$$\mu = \left( \int dx_2 \right) dx_3$$

$$\mu = x_2 \, dx_3$$

□

(2)  $x_2 \, dx_2 \wedge dx_3$ .

*Proof.* Using the above formula, we have

$$\mu = \left( \int x_2 \, dx_2 \right) dx_3$$

$$\mu = \frac{1}{2} x_2^2 \, dx_3$$

□

(3)  $(x_1^2 + x_2^2) \, dx_1 \wedge dx_2$ .

*Proof.* Using the above formula, we have

$$\mu = \left( \int (x_1^2 + x_2^2) \, dx_1 \right) dx_2$$

$$\mu = \left( \frac{1}{3} x_1^3 + x_1 x_2^2 \right) dx_2$$

□

(4)  $\cos(x_1) \, dx_1 \wedge dx_3$ .

*Proof.* Using the above formula, we have

$$\mu = \left( \int \cos(x_1) \, dx_1 \right) dx_3$$

$$\mu = \sin(x_1) \, dx_3$$

□

**2.4.iii.** Let  $U$  be an open subset of  $\mathbb{R}^n$ .

(1) Show that if  $\mu \in \Omega^k(U)$  is exact and  $\omega \in \Omega^\ell(U)$  is closed then  $\mu \wedge \omega$  is exact. *Hint:* See the second desired property of the exterior derivative.

*Proof.* To prove that  $\mu \wedge \omega$  is exact, it will suffice to show that there exists some  $\eta \in \Omega^{k+\ell-1}(U)$  such that  $d\eta = \mu \wedge \omega$ . Since  $\mu$  is exact, we know that there exists  $\tilde{\mu} \in \Omega^{k-1}(U)$  such that  $d\tilde{\mu} = \mu$ . Since  $\omega$  is closed, we know that  $d\omega = 0$ . Working off of a principle similar to the general proof in Exercise 2.4.ii, we can discover by inspection that taking

$$\eta = \tilde{\mu} \wedge \omega$$

makes it so that

$$\begin{aligned} d\eta &= d(\tilde{\mu} \wedge \omega) \\ &= d\tilde{\mu} \wedge \omega + (-1)^{k-1} \tilde{\mu} \wedge d\omega \\ &= \mu \wedge \omega + (-1)^{k-1} \tilde{\mu} \wedge 0 \\ &= \mu \wedge \omega \end{aligned}$$

as desired. □

(2) In particular,  $dx_1$  is exact, so if  $\omega \in \Omega^\ell(U)$  is closed, then  $dx_1 \wedge \omega = d\mu$ . What is  $\mu$ ?

*Proof.* Since  $dx_1 = d(x_1)$ , we have by part (1) that

$$\boxed{\mu = x_1 \omega}$$

□

**2.4.iv.** Let  $Q$  be the rectangle  $(a_1, b_1) \times \cdots \times (a_n, b_n)$ . Show that if  $\omega$  is in  $\Omega^n(Q)$ , then  $\omega$  is exact. *Hint:* Let  $\omega = f dx_1 \wedge \cdots \wedge dx_n$  with  $f \in C^\infty(Q)$  and let  $g$  be the function defined by

$$g(x_1, \dots, x_n) = \int_{a_1}^{x_1} f(t, x_2, \dots, x_n) dt$$

Show that  $\omega = d(g dx_2 \wedge \cdots \wedge dx_n)$ .

*Proof.* Let  $\omega \in \Omega^n(Q)$  be arbitrary. Then  $\omega = f dx_1 \wedge \cdots \wedge dx_n$  for some  $f \in C^\infty(Q)$ . To prove that  $\omega$  is exact, it will suffice to show that  $\omega = d\mu$  for some  $\mu \in \Omega^{n-1}(Q)$ .

Let  $g$  be defined as in the hint. If we take  $\mu = g dx_2 \wedge \cdots \wedge dx_n$ , then

$$\begin{aligned} d\mu &= d(g dx_2 \wedge \cdots \wedge dx_n) \\ &= dg \wedge dx_2 \wedge \cdots \wedge dx_n \\ &= f(x_1, x_2, \dots, x_n) dx_1 \wedge dx_2 \wedge \cdots \wedge dx_n \\ &= f dx_1 \wedge \cdots \wedge dx_n \\ &= \omega \end{aligned}$$

as desired, where we get from the second to the third line above with the Fundamental Theorem of Calculus. □

**2.5.i.** Verify the following properties of the interior product, where  $U \subset \mathbb{R}^n$  open,  $\mathbf{v}, \mathbf{w}$  are vector fields on  $U$ ,  $\omega_1, \omega_2, \omega \in \Omega^k(U)$ , and  $\mu \in \Omega^\ell(U)$ .

(1) *Linearity in the form:* We have

$$\iota_{\mathbf{v}}(\omega_1 + \omega_2) = \iota_{\mathbf{v}}\omega_1 + \iota_{\mathbf{v}}\omega_2$$

*Proof.* To prove that the above two forms are equal, it will suffice to show that they evaluate to identical elements of  $\Lambda^{k-1}(V^*)$  for all  $p \in U$ . Let  $p \in U$  be arbitrary. Then

$$\begin{aligned} [\iota_{\mathbf{v}}(\omega_1 + \omega_2)]_p &= \iota_{\mathbf{v}(p)}[(\omega_1 + \omega_2)_p] \\ &= \iota_{\mathbf{v}(p)}[(\omega_1)_p + (\omega_2)_p] \\ &= \iota_{\mathbf{v}(p)}(\omega_1)_p + \iota_{\mathbf{v}(p)}(\omega_2)_p \\ &= (\iota_{\mathbf{v}}\omega_1 + \iota_{\mathbf{v}}\omega_2)_p \end{aligned}$$

where we get from the first to the second line and the third to the fourth line using the definition of the interior product, and from the second to the third line using the linearity of the interior product operation.  $\square$

(2) *Linearity in the vector field:* We have

$$\iota_{\mathbf{v}+\mathbf{w}}\omega = \iota_{\mathbf{v}}\omega + \iota_{\mathbf{w}}\omega$$

*Proof.* As in the previous part, we have that

$$\begin{aligned} [\iota_{\mathbf{v}+\mathbf{w}}\omega]_p &= \iota_{(\mathbf{v}+\mathbf{w})(p)}\omega_p \\ &= \iota_{\mathbf{v}(p)+\mathbf{w}(p)}\omega_p \\ &= \iota_{\mathbf{v}(p)}\omega_p + \iota_{\mathbf{w}(p)}\omega_p \\ &= [\iota_{\mathbf{v}}\omega]_p + [\iota_{\mathbf{w}}\omega]_p \\ &= [\iota_{\mathbf{v}}\omega + \iota_{\mathbf{w}}\omega]_p \end{aligned}$$

$\square$

(3) *Derivation property:* We have

$$\iota_{\mathbf{v}}(\omega \wedge \mu) = \iota_{\mathbf{v}}\omega \wedge \mu + (-1)^k \omega \wedge \iota_{\mathbf{v}}\mu$$

*Proof.* As in the previous parts, we have that

$$\begin{aligned} [\iota_{\mathbf{v}}(\omega \wedge \mu)]_p &= \iota_{\mathbf{v}(p)}(\omega \wedge \mu)_p \\ &= \iota_{\mathbf{v}(p)}(\omega_p \wedge \mu_p) \\ &= \iota_{\mathbf{v}(p)}\omega_p \wedge \mu_p + (-1)^k \omega_p \wedge \iota_{\mathbf{v}(p)}\mu_p \\ &= (\iota_{\mathbf{v}}\omega)_p \wedge \mu_p + (-1)^k \omega_p \wedge (\iota_{\mathbf{v}}\mu)_p \\ &= (\iota_{\mathbf{v}}\omega \wedge \mu)_p + (-1)^k (\omega_p \wedge \iota_{\mathbf{v}}\mu)_p \\ &= [\iota_{\mathbf{v}}\omega \wedge \mu + (-1)^k \omega \wedge \iota_{\mathbf{v}}\mu]_p \end{aligned}$$

$\square$

(4) The identity

$$\iota_{\mathbf{v}}(\iota_{\mathbf{w}}\omega) = -\iota_{\mathbf{w}}(\iota_{\mathbf{v}}\omega)$$

*Proof.* As in the previous parts, we have that

$$\begin{aligned} [\iota_{\mathbf{v}}(\iota_{\mathbf{w}}\omega)]_p &= \iota_{\mathbf{v}(p)}(\iota_{\mathbf{w}}\omega)_p \\ &= \iota_{\mathbf{v}(p)}(\iota_{\mathbf{w}(p)}\omega_p) \\ &= -\iota_{\mathbf{v}(p)}(\iota_{\mathbf{w}(p)}\omega_p) \\ &= -\iota_{\mathbf{v}(p)}(\iota_{\mathbf{w}}\omega)_p \\ &= -[\iota_{\mathbf{v}}(\iota_{\mathbf{w}}\omega)]_p \\ &= [-\iota_{\mathbf{v}}(\iota_{\mathbf{w}}\omega)]_p \end{aligned}$$

$\square$

(5) The identity, as a special case of (4),

$$\iota_{\mathbf{v}}(\iota_{\mathbf{v}}\omega) = 0$$

*Proof.* We have that

$$\begin{aligned}\iota_{\mathbf{v}}(\iota_{\mathbf{v}}\omega) &= -\iota_{\mathbf{v}}(\iota_{\mathbf{v}}\omega) \\ 2\iota_{\mathbf{v}}(\iota_{\mathbf{v}}\omega) &= 0 \\ \iota_{\mathbf{v}}(\iota_{\mathbf{v}}\omega) &= 0\end{aligned}$$

□

(6) If  $\omega = \mu_1 \wedge \cdots \wedge \mu_k$  (i.e., if  $\omega$  is **decomposable**), then

$$\iota_{\mathbf{v}}\omega = \sum_{r=1}^k (-1)^{r-1} \iota_{\mathbf{v}}(\mu_r) \mu_1 \wedge \cdots \wedge \widehat{\mu_r} \wedge \cdots \wedge \mu_k$$

*Proof.* To prove that the above two forms are equal, it will suffice to show that they evaluate to identical elements of  $\Lambda^{k-1}(V^*)$  for all  $p \in U$ . Let  $p \in U$  be arbitrary. Also let  $(\mu_i)_p = \pi(\ell_i)$  for  $i = 1, \dots, k$  and, thus,  $\omega_p = \pi(\ell_1 \otimes \cdots \otimes \ell_k)$ . Then

$$\begin{aligned}[\iota_{\mathbf{v}}\omega]_p &= \iota_{\mathbf{v}(p)}\omega_p \\ &= \pi[\iota_{\mathbf{v}(p)}(\ell_1 \otimes \cdots \otimes \ell_k)] \\ &= \pi\left[\sum_{r=1}^k (-1)^{r-1} \ell_r(\mathbf{v}(p)) \ell_1 \otimes \cdots \otimes \widehat{\ell_r} \otimes \cdots \otimes \ell_k\right] && \text{Lemma 1.7.4} \\ &= \sum_{r=1}^k (-1)^{r-1} \pi\left[\iota_{\mathbf{v}(p)}(\ell_r) \ell_1 \otimes \cdots \otimes \widehat{\ell_r} \otimes \cdots \otimes \ell_k\right] \\ &= \sum_{r=1}^k (-1)^{r-1} \iota_{\mathbf{v}(p)}(\mu_r)_p (\mu_1)_p \wedge \cdots \wedge \widehat{(\mu_r)_p} \wedge \cdots \wedge (\mu_k)_p \\ &= \left[\sum_{r=1}^k (-1)^{r-1} \iota_{\mathbf{v}}(\mu_r) \mu_1 \wedge \cdots \wedge \widehat{\mu_r} \wedge \cdots \wedge \mu_k\right]_p\end{aligned}$$

as desired. □

**2.5.ii.** Show that if  $\omega$  is the  $k$ -form  $dx_I$  and  $\mathbf{v}$  is the vector field  $\partial/\partial x_r$ , then  $\iota_{\mathbf{v}}\omega$  is given by

$$\iota_{\mathbf{v}}\omega = \sum_{j=1}^k (-1)^{j-1} \delta_{r,i_j} dx_{I_j}$$

where

$$\delta_{r,i_j} = \begin{cases} 1 & r = i_j \\ 0 & r \neq i_j \end{cases} \quad I_j = (i_1, \dots, \widehat{i_j}, \dots, i_k)$$

In the above, 1 represents the identity function on  $U$ , and 0 represents the zero function on  $U$ .

*Proof.* We have that  $\omega = dx_I = dx_{i_1} \wedge \cdots \wedge dx_{i_k}$ . Therefore, by Properties 2.5.3(6),

$$\begin{aligned}\iota_{\mathbf{v}}\omega &= \sum_{j=1}^k (-1)^{j-1} \iota_{\mathbf{v}}(dx_{i_j}) dx_{i_1} \wedge \cdots \wedge \widehat{dx_{i_j}} \wedge \cdots \wedge dx_{i_k} \\ &= \sum_{j=1}^k (-1)^{j-1} dx_{i_j} (\partial/\partial x_r) dx_{i_1} \wedge \cdots \wedge \widehat{dx_{i_j}} \wedge \cdots \wedge dx_{i_k} \\ &= \sum_{j=1}^k (-1)^{j-1} \delta_{r,i_j} dx_{I_j}\end{aligned}$$

as desired.  $\square$

**2.5.iii.** Show that if  $\omega$  is the  $n$ -form  $dx_1 \wedge \cdots \wedge dx_n$  and  $\mathbf{v}$  is the vector field  $\sum_{i=1}^n f_i \partial/\partial x_i$ , then  $\iota_{\mathbf{v}}\omega$  is given by

$$\iota_{\mathbf{v}}\omega = \sum_{r=1}^n (-1)^{r-1} f_r dx_1 \wedge \cdots \wedge \widehat{dx_r} \wedge \cdots \wedge dx_n$$

*Proof.* Let  $I_j = (1, \dots, \hat{j}, \dots, n)$ . Then we have that

$$\begin{aligned} \iota_{\mathbf{v}}\omega &= \sum_{r=1}^n f_r \iota_{\partial/\partial x_r} \omega && \text{Properties 2.5.3(2)} \\ &= \sum_{r=1}^n f_r \left( \sum_{j=1}^n (-1)^{j-1} \delta_{r,j} dx_{I_j} \right) && \text{Exercise 2.5.ii} \\ &= \sum_{r=1}^n f_r ((-1)^{r-1} \delta_{r,r} dx_{I_r}) \\ &= \sum_{r=1}^n (-1)^{r-1} f_r dx_1 \wedge \cdots \wedge \widehat{dx_r} \wedge \cdots \wedge dx_n \end{aligned}$$

as desired.  $\square$

**2.5.iv.** Let  $U \subset \mathbb{R}^n$  open and  $\mathbf{v}$  a  $C^\infty$  vector field on  $U$ . Show that for  $\omega \in \Omega^k(U)$ ,

$$d(L_{\mathbf{v}}\omega) = L_{\mathbf{v}}(d\omega) \qquad \qquad \iota_{\mathbf{v}}(L_{\mathbf{v}}\omega) = L_{\mathbf{v}}(\iota_{\mathbf{v}}\omega)$$

*Hint:* Deduce the first of these identities using the identity  $d(d\mu) = 0$  and the second using the identity  $\iota_{\mathbf{v}}(\iota_{\mathbf{v}}\mu) = 0$ .

*Proof.* Let  $\omega \in \Omega^k(U)$  be arbitrary. Then

$$\begin{aligned} d(L_{\mathbf{v}}\omega) &= d(\iota_{\mathbf{v}}(d\omega) + d(\iota_{\mathbf{v}}\omega)) && \iota_{\mathbf{v}}(L_{\mathbf{v}}\omega) = \iota_{\mathbf{v}}(\iota_{\mathbf{v}}(d\omega) + d(\iota_{\mathbf{v}}\omega)) \\ &= d(\iota_{\mathbf{v}}(d\omega)) + d(d(\iota_{\mathbf{v}}\omega)) && = \iota_{\mathbf{v}}(\iota_{\mathbf{v}}(d\omega)) + \iota_{\mathbf{v}}(d(\iota_{\mathbf{v}}\omega)) \\ &= d(\iota_{\mathbf{v}}(d\omega)) + 0 && = 0 + \iota_{\mathbf{v}}(d(\iota_{\mathbf{v}}\omega)) \\ &= 0 + d(\iota_{\mathbf{v}}(d\omega)) && = \iota_{\mathbf{v}}(d(\iota_{\mathbf{v}}\omega)) + 0 \\ &= \iota_{\mathbf{v}}(0) + d(\iota_{\mathbf{v}}(d\omega)) && = \iota_{\mathbf{v}}(d(\iota_{\mathbf{v}}\omega)) + d(0) \\ &= \iota_{\mathbf{v}}(d(d\omega)) + d(\iota_{\mathbf{v}}(d\omega)) && = \iota_{\mathbf{v}}(d(\iota_{\mathbf{v}}\omega)) + d(\iota_{\mathbf{v}}(\iota_{\mathbf{v}}\omega)) \\ &= L_{\mathbf{v}}(d\omega) && = L_{\mathbf{v}}(\iota_{\mathbf{v}}\omega) \end{aligned}$$

as desired.  $\square$

**2.5.v.** Given  $\omega_i \in \Omega^{k_i}(U)$  for  $i = 1, 2$ , show that

$$L_{\mathbf{v}}(\omega_1 \wedge \omega_2) = L_{\mathbf{v}}\omega_1 \wedge \omega_2 + \omega_1 \wedge L_{\mathbf{v}}\omega_2$$

*Hint:* Plug  $\omega = \omega_1 \wedge \omega_2$  into the definition of the Lie derivative and use the second desired property of exterior differentiation along with the derivation property of the interior product to evaluate the resulting expression.

*Proof.* Let  $\omega = \omega_1 \wedge \omega_2$ . Then

$$\begin{aligned}
 L_{\mathbf{v}}(\omega_1 \wedge \omega_2) &= L_{\mathbf{v}}\omega \\
 &= \iota_{\mathbf{v}}(d\omega) + d(\iota_{\mathbf{v}}\omega) \\
 &= \iota_{\mathbf{v}}(d(\omega_1 \wedge \omega_2)) + d(\iota_{\mathbf{v}}(\omega_1 \wedge \omega_2)) \\
 &= \iota_{\mathbf{v}}(d\omega_1 \wedge \omega_2 + (-1)^{k_1}\omega_1 \wedge d\omega_2) + d(\iota_{\mathbf{v}}(\omega_1 \wedge \omega_2)) \\
 &= \iota_{\mathbf{v}}(d\omega_1 \wedge \omega_2 + (-1)^{k_1}\omega_1 \wedge d\omega_2) + d(\iota_{\mathbf{v}}\omega_1 \wedge \omega_2 + (-1)^{k_1}\omega_1 \wedge \iota_{\mathbf{v}}\omega_2) \\
 &= \iota_{\mathbf{v}}(d\omega_1 \wedge \omega_2) \\
 &\quad + (-1)^{k_1}\iota_{\mathbf{v}}(\omega_1 \wedge d\omega_2) \\
 &\quad + d(\iota_{\mathbf{v}}\omega_1 \wedge \omega_2) \\
 &\quad + (-1)^{k_1}d(\omega_1 \wedge \iota_{\mathbf{v}}\omega_2) \\
 &= \iota_{\mathbf{v}}(d\omega_1) \wedge \omega_2 + (-1)^{k_1+1}d\omega_1 \wedge \iota_{\mathbf{v}}\omega_2 \\
 &\quad + (-1)^{k_1}(\iota_{\mathbf{v}}\omega_1 \wedge d\omega_2 + (-1)^{k_1}\omega_1 \wedge \iota_{\mathbf{v}}(d\omega_2)) \\
 &\quad + d(\iota_{\mathbf{v}}\omega_1) \wedge \omega_2 + (-1)^{k_1-1}\iota_{\mathbf{v}}\omega_1 \wedge d\omega_2 \\
 &\quad + (-1)^{k_1}(d\omega_1 \wedge \iota_{\mathbf{v}}\omega_2 + (-1)^{k_1}\omega_1 \wedge d(\iota_{\mathbf{v}}\omega_2)) \\
 &= \iota_{\mathbf{v}}(d\omega_1) \wedge \omega_2 + (-1)^{k_1+1}d\omega_1 \wedge \iota_{\mathbf{v}}\omega_2 \\
 &\quad + (-1)^{k_1}\iota_{\mathbf{v}}\omega_1 \wedge d\omega_2 + (-1)^{2k_1}\omega_1 \wedge \iota_{\mathbf{v}}(d\omega_2) \\
 &\quad + d(\iota_{\mathbf{v}}\omega_1) \wedge \omega_2 + (-1)^{k_1-1}\iota_{\mathbf{v}}\omega_1 \wedge d\omega_2 \\
 &\quad + (-1)^{k_1}d\omega_1 \wedge \iota_{\mathbf{v}}\omega_2 + (-1)^{2k_1}\omega_1 \wedge d(\iota_{\mathbf{v}}\omega_2) \\
 &= \iota_{\mathbf{v}}(d\omega_1) \wedge \omega_2 - (-1)^{k_1}d\omega_1 \wedge \iota_{\mathbf{v}}\omega_2 \\
 &\quad + (-1)^{k_1}\iota_{\mathbf{v}}\omega_1 \wedge d\omega_2 + \omega_1 \wedge \iota_{\mathbf{v}}(d\omega_2) \\
 &\quad + d(\iota_{\mathbf{v}}\omega_1) \wedge \omega_2 - (-1)^{k_1}\iota_{\mathbf{v}}\omega_1 \wedge d\omega_2 \\
 &\quad + (-1)^{k_1}d\omega_1 \wedge \iota_{\mathbf{v}}\omega_2 + \omega_1 \wedge d(\iota_{\mathbf{v}}\omega_2) \\
 &= \iota_{\mathbf{v}}(d\omega_1) \wedge \omega_2 \\
 &\quad + \omega_1 \wedge \iota_{\mathbf{v}}(d\omega_2) \\
 &\quad + d(\iota_{\mathbf{v}}\omega_1) \wedge \omega_2 \\
 &\quad + \omega_1 \wedge d(\iota_{\mathbf{v}}\omega_2) \\
 &= \iota_{\mathbf{v}}(d\omega_1) \wedge \omega_2 + d(\iota_{\mathbf{v}}\omega_1) \wedge \omega_2 + \omega_1 \wedge \iota_{\mathbf{v}}(d\omega_2) + \omega_1 \wedge d(\iota_{\mathbf{v}}\omega_2) \\
 &= (\iota_{\mathbf{v}}(d\omega_1) + d(\iota_{\mathbf{v}}\omega_1)) \wedge \omega_2 + \omega_1 \wedge (\iota_{\mathbf{v}}(d\omega_2) + d(\iota_{\mathbf{v}}\omega_2)) \\
 &= L_{\mathbf{v}}\omega_1 \wedge \omega_2 + \omega_1 \wedge L_{\mathbf{v}}\omega_2
 \end{aligned}$$

as desired. □

**2.6.i.** Let  $f : \mathbb{R}^3 \rightarrow \mathbb{R}^3$  be the map

$$f(x_1, x_2, x_3) = (x_1x_2, x_2x_3^2, x_3^3)$$

Compute the pullback  $f^*\omega$  for the following forms.

(1)  $\omega = x_2 dx_3$ .

*Proof.* We have that

$$\begin{aligned}
 f^*\omega &= f^*x_2 \cdot df_3 \\
 &= x_2(x_1x_2, x_2x_3^2, x_3^3) \cdot 3x_3^2 dx_3
 \end{aligned}$$

$$\boxed{f^*\omega = 3x_2x_3^4 dx_3}$$

□



(2)  $\omega = x_1 dx_1 \wedge dx_3.$

*Proof.* We have that

$$\begin{aligned} f^*\omega &= f^*x_1 \cdot df_1 \wedge df_3 \\ &= x_1(x_1x_2, x_2x_3^2, x_3^3) \cdot (x_1 dx_2 + x_2 dx_1) \wedge 3x_3^2 dx_3 \\ \boxed{f^*\omega &= 3x_1^2x_2x_3^2 dx_2 \wedge dx_3 + 3x_1x_2^2x_3^2 dx_1 \wedge dx_3} \end{aligned}$$

□

(3)  $\omega = x_1 dx_1 \wedge dx_2 \wedge dx_3.$

*Proof.* We have that

$$\begin{aligned} f^*\omega &= f^*x_1 \cdot df_1 \wedge df_2 \wedge df_3 \\ &= x_1(x_1x_2, x_2x_3^2, x_3^3) \cdot (x_1 dx_2 + x_2 dx_1) \wedge (2x_2x_3 dx_3 + x_3^2 dx_2) \wedge 3x_3^2 dx_3 \\ \boxed{f^*\omega &= 3x_1x_2^2x_3^4 dx_1 \wedge dx_2 \wedge dx_3} \end{aligned}$$

where, from the second to the third line, we cancel all wedge products with repeats. □

**2.6.ii.** Let  $f : \mathbb{R}^2 \rightarrow \mathbb{R}^3$  be the map

$$f(x_1, x_2) = (x_1^2, x_2^2, x_1x_2)$$

Compute the pullback  $f^*\omega$  for the following forms.

(1)  $\omega = x_2 dx_2 + x_3 dx_3.$

*Proof.* We have that

$$\begin{aligned} f^*\omega &= f^*x_2 \cdot df_2 + f^*x_3 \cdot df_3 \\ &= x_2(x_1^2, x_2^2, x_1x_2) \cdot 2x_2 dx_2 + x_3(x_1^2, x_2^2, x_1x_2) \cdot (x_1 dx_2 + x_2 dx_1) \\ \boxed{f^*\omega &= x_1x_2^2 dx_1 + (2x_2^3 + x_1^2x_2) dx_2} \end{aligned}$$

□

(2)  $\omega = x_1 dx_2 \wedge dx_3.$

*Proof.* We have that

$$\begin{aligned} f^*\omega &= f^*x_1 \cdot df_2 \wedge df_3 \\ &= x_1(x_1^2, x_2^2, x_1x_2) \cdot 2x_2 dx_2 \wedge (x_1 dx_2 + x_2 dx_1) \\ &= 2x_1^2x_2^2 dx_2 \wedge dx_1 \\ \boxed{f^*\omega &= -2x_1^2x_2^2 dx_1 \wedge dx_2} \end{aligned}$$

□

(3)  $\omega = dx_1 \wedge dx_2 \wedge dx_3.$

*Proof.* We have that

$$\begin{aligned} f^*\omega &= df_1 \wedge df_2 \wedge df_3 \\ &= 2x_1 dx_1 \wedge 2x_2 dx_2 \wedge (x_1 dx_2 + x_2 dx_1) \\ \boxed{f^*\omega &= 0} \end{aligned}$$

where 0 denotes the zero element of  $\Omega^3(\mathbb{R}^2).$  □

**2.6.iii.** Let  $U \subset \mathbb{R}^n$  open,  $V \subset \mathbb{R}^m$  open,  $f : U \rightarrow V$  a  $C^\infty$  map, and  $\gamma : [a, b] \rightarrow U$  a  $C^\infty$  curve. Show that for  $\omega \in \Omega^1(V)$ ,

$$\int_\gamma f^* \omega = \int_\eta \omega$$

where  $\eta : [a, b] \rightarrow V$  is the curve  $\eta(t) = f(\gamma(t))$ . (See Exercise 2.1.vii.)

*Proof.* Since  $\omega \in \Omega^1(V)$ , we know that

$$\omega = \sum_{j=1}^m g_j dx_j$$

for some  $g_i \in C^\infty(V)$ . It follows that

$$\begin{aligned} f^* \omega &= \sum_{j=1}^m f^* g_j df_j \\ &= \sum_{j=1}^m f^* g_j \left( \sum_{i=1}^n \frac{\partial f_j}{\partial x_i} dx_i \right) \\ &= \sum_{i=1}^n \left( \sum_{j=1}^m f^* g_j \frac{\partial f_j}{\partial x_i} \right) dx_i \end{aligned}$$

Additionally, let  $\gamma_1, \dots, \gamma_n$  be the coordinate functions of  $\gamma$ , let  $\eta_1, \dots, \eta_m$  be the coordinate functions of  $\eta$ , and let  $f_1, \dots, f_m$  be the coordinate functions of  $f$ . It follows that

$$\begin{aligned} \int_\gamma f^* \omega &= \sum_{i=1}^n \int_a^b \left[ \sum_{j=1}^m f^* g_j \frac{\partial f_j}{\partial x_i} \right] (\gamma(t)) \frac{d\gamma_i}{dt} dt \\ &= \sum_{i=1}^n \sum_{j=1}^m \int_a^b [f^* g_j](\gamma(t)) \frac{\partial f_j}{\partial x_i} \frac{d\gamma_i}{dt} dt \\ &= \sum_{j=1}^m \int_a^b [g_j \circ f](\gamma(t)) \left( \sum_{i=1}^n \frac{\partial f_j}{\partial x_i} \frac{d\gamma_i}{dt} \right) dt \\ &= \sum_{j=1}^m \int_a^b g_j(f(\gamma(t))) \frac{d(f_j \circ \gamma)}{dt} dt \\ &= \sum_{j=1}^m \int_a^b g_j(\eta(t)) \frac{d\eta_j}{dt} dt \\ &= \int_\eta \omega \end{aligned}$$

□