## Chapter 1

## Multilinear Algebra

## 1.1 Notes

• Plan:

3/30:

3/28: • Motivation for the course and an overview of Guillemin and Haine (2018).

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- More (multi)linear algebra.

• Dual spaces.

ullet Let V be an n-dimensional real vector space.

• Hom  $(V,\mathbb{R})$ : The set of all homomorphisms (i.e., linear maps) from V to  $\mathbb{R}$ . Also known as  $V^*$ .

• Dual basis (for  $V^*$ ): The set of linear transformations from V to  $\mathbb{R}$  defined by

$$e_j \mapsto \begin{cases} 1 & j = i \\ 0 & j \neq i \end{cases}$$

where  $e_1, \ldots, e_n$  is a basis of V. Denoted by  $e_1^*, \ldots, e_n^*$ .

• Check:  $e_1^*, \ldots, e_n^*$  are a basis for  $V^*$ .

– Are they linearly independent? Let  $c_1e_1^* + \cdots + c_ne_n^* = 0 \in \text{Hom}(V, \mathbb{R})$ . Then

$$c_i = (c_1 e_1^* + \dots + c_n e_n^*)(e_i) = 0 \in \mathbb{R}$$

as desired.

- Span? Let  $\varphi \in \text{Hom}(V, \mathbb{R})$ . Then we can verify that

$$\varphi(e_1)e_1^* + \cdots + \varphi(e_n)e_n^* = \varphi$$

- $\blacksquare$  We prove this by verifying the previous statement on the basis of V (if two linear transformations have the same action on the basis of a vector space, they are equal).
- With a choice of basis for V, we obtain an isomorphism  $\varepsilon: V \to V^*$  with the mapping  $e_i \mapsto e_i^*$  for all i.
- The dual space is known as such because  $(V^*)^* \cong V$ , where  $\cong$  is **canonical** (no choice of basis is needed).
- One more property of dual spaces: functoriality.

- Given a linear transformation  $A: V \to W$ , we know that  $A^*: W^* \to V^*$  where  $A^*$  is the transpose of A. In particular, if  $\varphi \in W^*$ , then  $\varphi \circ A: V \to \mathbb{R}$ .
- Claim:  $A^*$  is linear.
- Functoriality: If  $A: V \to W$  and  $B: W \to U$ , then  $B^*: U^* \to W^*$  and  $A^*: W^* \to V^*$ . The functoriality statement is that  $(B \circ A)^* = A^* \circ B^*$ .
- $A^*$  is the **pullback** (or transpose) of A.
- Let  $v_1, \ldots, v_n$  be a basis for V and  $w_1, \ldots, w_m$  be a basis for W. Then  $[A]_{v_1, \ldots, v_n}^{w_1, \ldots, w_m} = A$  is the matrix of the linear transformation A with respect to these bases. Then if  $v_1^*, \ldots, v_n^*$  and  $w_1^*, \ldots, w_m^*$  are the corresponding dual bases, then  $[A^*]_{v_1^*, \ldots, v_n^*}^{w_1^*, \ldots, w_m^*} = A^T$ . We can and should verify this for ourselves.
- This is over the real numbers, so  $A^*$  is just the transpose because there are no complex numbers of which to take the conjugate!
- A generalization: Tensors.
- k-tensor: A multilinear map

$$T: \underbrace{V \times \cdots \times V}_{k \text{ times}} \to \mathbb{R}$$

• Multilinear (map T): A function T such that

$$T(v_1, \dots, v_i^1 + v_i^2, \dots, v_k) = T(v_1, \dots, v_i^1, \dots, v_k) + T(v_1, \dots, v_i^2, \dots, v_k)$$
$$T(v_1, \dots, \lambda v_i, \dots, v_k) = \lambda T(v_1, \dots, v_i, \dots, v_k)$$

for all  $(v_1, \ldots, v_k) \in V^k$ .

- The determinant is an *n*-tensor!
- ullet 1-tensors are just covectors.
- $L^k(V)$ : The vector space of all k-tensors on V.
- Calculating dim  $L^k(V)$ . (Answer not given in this class.)
- Let  $A: V \to W$ . Then  $A^*: L^k(W) \to L^k(V)$ .
  - Check  $(A \circ B)^* = B^* \circ A^*$ .
- Multi-index of n of length k: A k-tuple  $(i_1, \ldots, i_k)$  where each  $i_j \in \mathbb{N}$  satisfies  $1 \leq i_j \leq n$   $(j = 1, \ldots, k)$ . Denoted by I.
- Let  $e_1, \ldots, e_n$  be a basis for V.
- **Tensor product** (of  $T_1 \in L^k(V)$ ,  $T_2 \in L^l(V)$ ): The function from  $V^{k+l}$  to  $\mathbb{R}$  defined by

$$(v_1, \ldots, v_{k+l}) \mapsto T_1(v_1, \ldots, v_k) T_2(v_{k+1}, \ldots, v_{k+l})$$

Denoted by  $T_1 \otimes T_2$ .

- Claims:
  - 1.  $T_1 \otimes T_2 \in L^{k+l}(V)$ .
  - 2.  $A^*(T_1 \otimes T_2) = A^*(T_1) \otimes A^*(T_2)$ .
- $e_I^*$ : The function  $e_{i_1}^* \otimes \cdots \otimes e_{i_k}^*$ , where  $I = (i_1, \dots, i_k)$  is a multi-index of n of length k.
- Claim: Letting I range over all  $n^k$  multi-indices of n of length k, the  $e_I^*$  are a basis for  $L^k(V)$ .
- If  $V = \mathbb{R}$ , then  $V = \mathbb{R}e_1$ . If  $V = \mathbb{R}^2$ , then  $V = \mathbb{R}e_1 \oplus \mathbb{R}e_2$ .
- We know that  $L^1(V) = V^* = Re_1^*$ . Thus,  $e_1^* \otimes e_2^* : V \times V \to \mathbb{R}$ . Thus, for example,

$$(e_1^* \otimes e_2^*)((1,2),(3,4)) = e_1^*(1,2) \cdot e_2^*(3,4) = 1 \cdot 4 = 4$$

## 1.2 Chapter 1: Multilinear Algebar

From Guillemin and Haine (2018).

- 3/31: Guillemin and Haine (2018) defines real vector spaces, the operations on them, their basic properties, and the zero vector.
  - Linearly independent (vectors  $v_1, \ldots, v_k$ ): A finite set of vectors  $v_1, \ldots, v_k \in V$  such that the map from  $\mathbb{R}^k$  to V defined by  $(c_1, \ldots, c_k) \mapsto c_1 v_1 + \cdots + c_k v_k$  is injective.
  - Spanning (vectors  $v_1, \ldots, v_k$ ): We require that the above map is surjective.
  - Guillemin and Haine (2018) defines basis, finite-dimensional vector space, dimension, subspace, linear map, and kernel.
  - Image (of  $A: V \to W$ ): The range space of A, a subspace of W. Also known as im (A).
  - Guillemin and Haine (2018) defines the matrix of a linear map.
  - Inner product (on V): A map  $B: V \times V \to \mathbb{R}$  with the following three properties.
    - Bilinearity: For vectors  $v, v_1, v_2, w \in V$  and  $\lambda \in \mathbb{R}$ , we have

$$B(v_1 + v_2, w) = B(v_1, w) + B(v_2, w)$$

and

$$B(\lambda v, w) = \lambda B(v, w)$$

- Symmetry: For vectors  $v, w \in V$ , we have B(v, w) = B(w, v).
- Positivity: For every vector  $v \in V$ , we have  $B(v,v) \geq 0$ . Moreover, if  $v \neq 0$ , then B(v,v) > 0.
- **W-coset**: A set of the form  $\{v + w \mid w \in W\}$ , where W is a subspace V and  $v \in V$ . Denoted by v + W.
  - If  $v_1 v_2 \in W$ , then  $v_1 + W = v_2 + W$ .
  - It follows that the distinct W-cosets decompose V into a disjoint collection of subsets of V.
- Quotient space (of V by W): The set of distinct W-cosets in V, along with the following definitions of vector addition and scalar multiplication.

$$(v_1 + W) + (v_2 + W) = (v_1 + v_2) + W$$
  $\lambda(v + W) = (\lambda v) + W$ 

Denoted by V/W.

• Quotient map: The linear map  $\pi: V \to V/W$  defined by

$$\pi(v) = v + W$$

- $-\pi$  is surjective.
- Note that  $\ker(\pi) = W$  since for all  $w \in W$ ,  $\pi(w) = w + W = 0 + W$ , which is the zero vector in V/W.
- If V, W are finite dimensional, then

$$\dim(V/W) = \dim(V) - \dim(W)$$

- Proposition 1.2.9: Let  $A:V\to U$  be a linear map. If  $W\subset \ker(A)$ , then there exists a unique linear map  $A^{\sharp}:V/W\to U$  with the property that  $A=A^{\sharp}\circ\pi$ , where  $\pi:V\to V/W$  is the quotient map.
  - This proposition rephrases in terms of quotient spaces the fact that if  $w \in W$ , then A(v+w) = Av.

• Dual space (of V): The set of all linear functions  $\ell: V \to \mathbb{R}$ , along with the following definitions of vector addition and scalar multiplication.

$$(\ell_1 + \ell_2)(v) = \ell_1(v) + \ell_2(v) \qquad (\lambda \ell)(v) = \lambda \cdot \ell(v)$$

Denoted by  $V^*$ .

• **Dual basis** (of  $e_1, \ldots, e_n$  a basis of V): The basis of  $V^*$  consisting of the n functions that take every  $v = c_1 e_1 + \cdots + c_n e_n$  to one of the  $c_i$ . Denoted by  $e_1^*, \ldots, e_n^*$ . Given by

$$e_i^*(v) = c_i$$

for all  $v \in V$ .

• Claim 1.2.12: If V is an n-dimensional vector space with basis  $e_1, \ldots, e_n$ , then  $e_1^*, \ldots, e_n^*$  is a basis of  $V^*$ .

*Proof.* We will first prove that  $e_1^*, \ldots, e_n^*$  spans  $V^*$ . Let  $\ell \in V^*$  be arbitrary. Set  $\lambda_i = \ell(e_i)$  for all  $i \in [n]$ . Define  $\ell' = \sum_{i=1}^n \lambda_i e_i^*$ . Then

$$\ell'(e_j) = \sum_{i=1}^{n} \lambda_i e_i^*(e_j) = \lambda_j \cdot 1 = \ell(e_j)$$

for all  $j \in [n]$ . Therefore, since  $\ell, \ell'$  take identical values on the basis of  $V, \ell = \ell'$ , as desired.

We now prove that  $e_1^*, \ldots, e_n^*$  spans  $V^*$ . Let  $\sum_{i=1}^n \lambda_i e_i^* = 0$ . Then for all  $j \in [n]$ ,

$$\lambda_j = (\sum_{i=1}^n \lambda_i e_i^*)(e_j) = 0$$

as desired.  $\Box$ 

- Transpose (of A): The map from  $W^*$  to  $V^*$  defined by  $\ell \mapsto A^*\ell = \ell \circ A$  for all  $\ell \in W^*$ .
- Claim 1.2.15: If  $e_1, \ldots, e_n$  is a basis of  $V, f_1, \ldots, f_m$  is a basis of  $W, e_1^*, \ldots, e_n^*$  and  $f_1^*, \ldots, f_m^*$  are the corresponding dual bases, and  $[a_{i,j}]$  is the  $m \times n$  matrix of A with respect to  $\{e_i\}, \{f_i\}$ , then the linear map  $A^*$  is defined in terms of  $\{f_i^*\}, \{e_i^*\}$  by the transpose matrix  $(a_{j,i})$ .

Labalme 4