## Chapter 4

## Continuity

## 4.1 Notes

11/8:

- Consider a function  $f: X \to Y$  whose domain and codomain are, respectively, the metric spaces  $(X, d_X)$  and  $(Y, d_Y)$ .
- **Limit** (of f at p): A point  $q \in Y$  such that for all  $\epsilon > 0$ , there exists  $\delta$  such that  $d_X(x, p) < \delta$  implies  $d_Y(q, f(x)) < \epsilon$ , where p is a limit point of X (otherwise,  $x \nrightarrow p$ ).
- Continuous (function f at p): A function f such that  $\lim_{x\to p} f(x) = f(p)$ .
- f is continuous on X if it is continuous at every  $p \in X$ .
- Uniformly continuous (function f): A function f such that for every  $\epsilon > 0$ , there exists a  $\delta > 0$  such that  $d_X(x,y) < \delta$  implies  $d_Y(f(x),f(y)) < \epsilon$  for all  $x,y \in X$ .

11/10:

- f, g continuous implies f + g, fg, and f/g continuous, the latter where  $g(x) \neq 0$ .
- If f, g continuous, then  $h = g \circ f$  is continuous.
- Theorem:  $f: X \to Y$  is continuous iff  $f^{-1}(V)$  is open in X for every  $V \subset Y$  open.

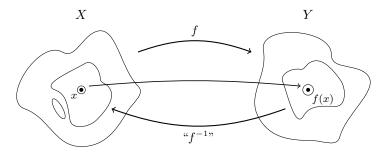


Figure 4.1: Set theoretic definition of continuity.

- This works in a general topological space, too, not just a metric space.
- Note that  $f^{-1}(V)$  is not a function defined on V; it's a specifically defined set  $\{x \in X : f(x) \in V\}$ .
- f being continuous means that open circular neighborhood of a point x in the domain maps to an area of the range encompassed by a circular neighborhood of f(x).
- The other condition means that every open set surrounding f(x) maps to an open set of the domain surrounding x. Indeed, going off of this definition, if an open set containing f(x) maps to an open set containing x, then we can choose a neighborhood subset of the open set surrounding x and know that it will map into a neighborhood subset of the open set surrounding f(x).

- Corollary:  $f: X \to Y$  continuous iff  $f^{-1}(C)$  closed for every  $C \subset Y$  closed.
  - We use the property that  $f^{-1}(X \subset C) = X \subset f^{-1}(C)$ .
- Let  $f_1: X_1 \to Y_1$  and  $f_2: X_2 \to Y_2$ . Suppose  $f: X_1 \times X_2 \to Y_1 \times Y_2$  is defined by  $f(x_1, x_2) = (f_1(x_1), f_2(x_2))$ . Then f is continuous iff  $f_1, f_2$  are continuous, under appropriately defined metrics.
- Continuity and compactness.
- Theorem:  $f: X \to Y$  continuous and X compact imply f(X) compact.
  - Let  $\{V_{\alpha}\}$  be an open cover of f(X).
  - Then  $\{f^{-1}(V_{\alpha})\}$  is an open cover of X..
  - Choose a finite subcover of  $\{f^{-1}(V_{\alpha})\}$ . Then the corresponding  $V_{\alpha}$ 's form a finite subcover of f(X).
- If  $f: X \to \mathbb{R}^k$  is continuous and X is compact, f(X) is compact and closed/bounded.
- If  $f: X \to \mathbb{R}$  is continuous and X is compact, then  $M = \sup_{x \in X} |f(x)| = |f(\bar{x})|$  and  $m = \inf x \in X |f(x)| = |f(\underline{x})|$  where  $\bar{x}, \underline{x} \in X$ .
  - There is a subsequence  $\{x_m\}$  such that  $|f(x_m)| \to M$ . Since f(X) is compact, the limit of this sequence is in f(X).
- If  $f: X \to Y$  is continuous, bijective, and X, Y are compact,  $f^{-1}: Y \to X$  is continuous.
- Uniform continuity.
- Examples.
  - Linear functions are uniformly continuous.
  - $-f:(0,1)\to\mathbb{R}$  defined by  $f(x)=x^2$  is uniformly continuous.
  - $-f:(a,\infty)\to\mathbb{R}$  defined by  $f(x)=x^2$  is not uniformly continuous.
  - $-f:(a,\infty)\to\mathbb{R}$  defined by f(x)=1/x is uniformly continuous if a>0.
  - $-f:(0,\infty)\to\mathbb{R}$  defined by f(x)=1/x is not uniformly continuous.
- Lipschitz continuous (function f on  $E \subset X$ ): A function such that  $|f(x) f(y)| \le L|x y|$  for each  $x, y \in E$ .
- Theorem:  $f: X \to Y$  continuous and X compact implies f is uniformly continuous.
  - Fix  $\epsilon > 0$ . There exists  $\delta = \delta(p) > 0$ .
  - Def. of continuity:  $q \in N_{\delta(p)}(p)$  implies  $f(q) \in N_{\epsilon}(f(p))$ .
  - $\{N_{\delta(p)/2}(p): p \in X\}$  is an open cover of X. Choose a finite subcover. Let  $\delta = \min(\delta(p_1)/2, \dots, \delta(p_n)/2)$ .
- 11/12:  $f: X \to Y$  continuous and  $E \subset X$  connected implies f(E) connected.
  - Suppose  $f(E) = A \cup B$ , A, B nonempty, separated subsets of Y.
  - Let  $G = E \cap f^{-1}(A)$ ,  $H = E \cap f^{-1}(B)$ . It follows that  $E = G \cup H$ , where G, H nonempty.
  - $-A \subset \bar{A}$  implies  $G \subset f^{-1}(\bar{A})$  implies (inverse image def. of continuity)  $\bar{G} \subset f^{-1}(A)$  implies  $f(\bar{G}) \subset \bar{A}$ .
  - -f(H)=B and  $\bar{A}\cap B=\emptyset$  yields  $\bar{G}\cap H=\emptyset$ . Symmetrically,  $G\cap \bar{H}=\emptyset$ . This contradicts our assumption that E is connected.
  - Introduces monotone functions.
  - Theorem: If f is monotonic on (a, b), then the set of points of (a, b) at which f is discontinuous is at most countable.

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## 4.2 Chapter 4: Continuity

From Rudin (1976).

- 11/8:
- **Limit** (of f at p): The point  $q \in Y$ , if it exists, such that for every  $\epsilon > 0$ , there exists a  $\delta > 0$  such that  $d_Y(f(x), q) < \epsilon$  for all points  $x \in E$  for which  $0 < d_X(x, p) < \delta$ , where  $(X, d_X), (Y, d_Y)$  are metric spaces,  $E \subset X$ ,  $f : E \to Y$ , and  $p \in E'$ . Denoted by  $\lim_{x \to p} f(x)$ .
  - Note that we do not require that  $p \in E$ ; only that some elements of the domain E approach p.
  - We also write  $f(x) \to q$  as  $x \to p$ .
- Theorem 4.2: Let X, Y, E, f, and p be as specified above. Then  $\lim_{x\to p} f(x) = q$  iff  $\lim_{n\to\infty} f(p_n) = q$  for every sequence  $\{p_n\}$  in E such that  $p_n \neq p$  for any n and  $\lim_{n\to\infty} p_n = p$ .
- Rudin (1976) proves the sum, product, and quotient rules of limits from the analogous properties of series.
- Continuity is defined.
  - Note that f does have to be defined at p to be continuous at p (in comparison to the fact that it can have a limit at a point p' at which it is not defined).
    - Thus, for proofs concerning continuity (as opposed to limits), we will consider functions f the domains of which are metric spaces, not subsets of metric spaces.
  - It follows from the definition that if  $p \in E$  is isolated, then every possible f defined on E is continuous at p.
- Theorem 4.7: Compositions of continuous functions are continuous.
- Theorem 4.8: Preimage definition of continuity.
- Theorem 4.9: If f, g are complex continuous functions on X, f + g, fg, and f/g are continuous on X.
- Theorem 4.10: **f** continuous implies  $f_1, \ldots, f_k$  continuous. Also,  $\mathbf{f}, \mathbf{g} : X \to \mathbb{R}^k$  continuous implies  $\mathbf{f} + \mathbf{g}$  and  $\mathbf{f} \cdot \mathbf{g}$  continuous.
- 11/9:
- Theorem 4.14: f continuous and X compact implies f(X) compact.
- Theorem 4.15:  $\mathbf{f}: X \to \mathbb{R}^k$  continuous and X compact implies f(X) closed and bounded.
- Theorem 4.16: f continuous and X compact implies f attains its minimum and maximum.
- Theorem 4.17:  $f: X \to Y$  continuous, 1-1 for X, Y compact implies  $f^{-1}: Y \to X$  continuous.
- Theorem 4.19: f continuous and X compact implies f uniformly continuous.
- Theorem 4.20: Compactness is a necessary condition in Theorems 4.14, 4.15, 4.16, and 4.19.
- Theorem 4.22:  $f: X \to Y$  continuous and  $E \subset X$  connected implies f(E) connected.
- Theorem 4.23: Intermediate value theorem.
- Right-hand limit (of f at x): Denoted by f(x+).
- Left-hand limit (of f at x): Denoted by f(x-).
- Discontinuity of the first kind (of f at x): A discontinuity of f at x such that f(x+) and f(x-) exist. Also known as simple discontinuity.
- Discontinuity of the second kind (of f at x): A discontinuity of f at x that is not of the first kind (i.e., a discontinuity such that at least one of f(x+) and f(x-) does not exist).

- Theorem 4.29: If f is monotonic on (a, b), then f(x+), f(x-) exist at every  $x \in (a, b)$ .
- Corollary: Monotonic functions have no discontinuities of the second kind.
- Theorem 4.30: If f is monotonic on (a, b), then the set of points of (a, b) at which f is discontinuous is at most countable.