

Week 2

???

2.1 Separable ODEs

10/3: • Do not sit on the left side of the classroom: The sun sucks!

- **Separable** (ODE): An ODE of the form

$$\frac{dy}{dt} = f(t)g(y)$$

where y is a real^[1], unknown, scalar function of t .

- Solving separable ODEs: Formally, evaluate

$$\int \frac{dy}{g(y)} = \int f(t) dt$$

- Rearrange the initial separable ODE to $dy/dt \cdot 1/g = f$ and invoke the law of composite differentiation to get

$$\frac{d}{dt} \left[\int_{y_0}^{y(t)} \frac{dw}{g(w)} - \int_{t_0}^t f(\tau) d\tau \right] = 0$$

- It follows that

$$\int_{y_0}^{y(t)} \frac{dw}{g(w)} = \int_{t_0}^t f(\tau) d\tau$$

- Examples:

1. Exponential growth.

- We have that

$$\frac{dy}{dt} = ky$$

for $k > 0$ and $y(0) = y_0 > 0$.

- The solution is

$$\begin{aligned} \frac{1}{y} \cdot \frac{dy}{dt} &= k \\ \log y(t) - \log y_0 &= kt \\ y(t) &= y_0 e^{kt} \end{aligned}$$

¹We'll deal with complex functions later.

2. Logistic growth.

- We have that

$$\frac{dy}{dt} = ky \left(1 - \frac{y}{M}\right)$$

for $k, M > 0$ and $y(0) = y_0 > 0$.

- The solution is

$$\begin{aligned} \frac{M dy}{y(M-y)} &= k dt \\ \log \frac{y}{M-y} - \log \frac{y_0}{M-y_0} &= kt \\ \frac{y(M-y_0)}{y_0(M-y)} &= e^{kt} \\ y \cdot \frac{M-y_0}{y_0} &= (M-y)e^{kt} \\ y \cdot \frac{M-y_0}{y_0} + ye^{kt} &= Me^{kt} \\ y \left(\frac{M-y_0}{y_0} + e^{kt} \right) &= Me^{kt} \\ y \left(\frac{M-y_0+y_0e^{kt}}{y_0} \right) &= Me^{kt} \\ y \left(\frac{M+y_0(e^{kt}-1)}{y_0} \right) &= Me^{kt} \\ y(t) &= \frac{My_0e^{kt}}{M+y_0(e^{kt}-1)} \end{aligned}$$

- Sketches the graph of logistic growth and discusses the turning point (for which there is a formula; zero of the second derivative) as well as general trends.
- If $y_0 < 0$, the solution is not physically meaningful, but it is mathematically insightful.
 - When we integrate, the arguments of our logarithms now have absolute values.

$$\log \left| \frac{y}{M-y} \right| - \log \left| \frac{y_0}{M-y_0} \right| = kt$$

- We need to make sure that the denominator of the final logistic form is never equal to zero, but now that y_0 is negative, as t increases, the denominator will approach zero exponentially. It reaches zero when

$$\begin{aligned} M + y_0(e^{kt} - 1) &= 0 \\ e^{kt} &= -\frac{M}{y_0} + 1 \end{aligned}$$

In other words, $t_{\max} = (1/k) \log(1 - M/y_0)$ because when $t = t_{\max}$, the equation blows up.

- This is an example of **finite lifespan**.

- If $y_0 > M$, then you will exponentially decrease to M .

3. Lotka-Volterra predator-prey model.

- We have that

$$r' = k_1 r - a w r \qquad w' = -k_2 w + b w r$$

where r is rabbits and w is wolves.

- We can rename the variables to

$$\begin{cases} x' = Ax - Bxy \\ y' = -Cy + Dxy \end{cases}$$

- Dividing, we get

$$\frac{x'}{y'} = \frac{Ax - Bxy}{-Cy + Dxy}$$

$$\frac{By - A}{y}y' + \frac{Dx - C}{x}x' = 0$$

- Use the fact that x, y are independent variables, so both terms in the above equation are equal to zero?
- Invoke the law of composite differentiation twice and, from the above, know that $0 + 0 = 0$, so we can add the two solutions:

$$\frac{d}{dt}(By(t) - A \log y(t)) + \frac{d}{dt}(Dx(t) - C \log x(t)) = 0$$

$$By(t) - A \log y(t) + Dx(t) - C \log x(t) = E$$

- Sketches some of the trajectories (they're all closed curves in the xy -plane).

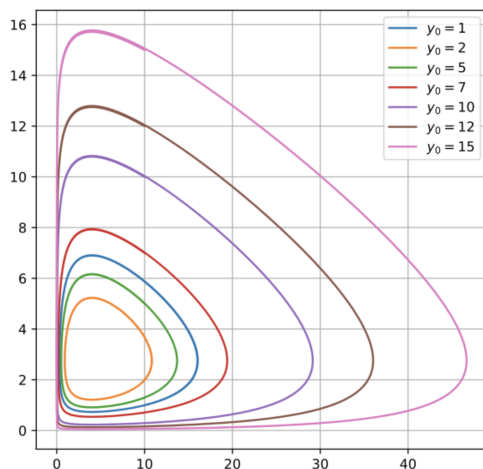


Figure 2.1: Lotka-Volterra solution curves.

- Properties of the curves:

■ The implicit relation which determines them: By the implicit function theorem, the y derivative of the LHS is $B - A/y$ and the x -derivative of the LHS is $D - C/x$. When the partial derivatives are equal to zero, $(C/D, A/B)$ becomes interesting. Turning points happen when the y -coordinate is A/B or the x -coordinate is C/D .

- **Finite lifespan:** Even if the RHS of $dy/dt = f(t, y)$ is very regular, the solution can still blow up at some finite time.
- Consider the following variation on the E-L equation from the Brachistochrone problem.

$$\frac{dy}{dx} = \sqrt{\frac{B-y}{y}}$$

- Finding the **primitives**.

■ What are these “primitives” Shao keeps talking about?

– We should have

$$\int \sqrt{\frac{y}{B-y}} dy = x$$

– Change of variables: $y = B \sin^2 \phi$ and $dy = 2B \cos \phi \sin \phi d\phi$. Thus,

$$\int \sqrt{\frac{y}{B-y}} dy = \int \frac{\sin \phi}{\cos \phi} \cdot 2B \cos \phi \sin \phi d\phi = 2B \int \sin^2 \phi d\phi$$

– The solution is

$$\begin{cases} x = B\phi - \frac{B}{2} \sin(2\phi) + C \\ y = B \sin^2 \phi \end{cases}$$

■ This is a parameterization of a cycloid.

- Later in the week, we will do the SHM, the pendulum, the Kepler 2-body problem, and the Michaelis-Menten equation.
- Separable ODEs are a subset of ODEs of **exact form**.
- ODEs of exact form are of the form

$$g(x, y) \frac{dy}{dx} + f(x, y) = 0$$

where for some $F(x, y)$, $g = \partial F / \partial y$, $f = \partial F / \partial x$, and partials commute. Equivalently,

$$\frac{\partial g}{\partial x} = \frac{\partial f}{\partial y}$$

is our necessary and sufficient condition.

- By the law of composite differentiation,

$$\begin{aligned} \frac{d}{dx} [F(x, y(x))] &= \frac{\partial F}{\partial x} + \frac{\partial F}{\partial y} \cdot y'(x) \\ &= f(x, y(x)) + g(x, y(x))y'(x) \\ &= 0 \end{aligned}$$

– We solve these with an integrating factor $\mu \neq 0$ such that $(\mu g, \mu f)$ satisfy the constraint.

2.2 Office Hours (Shao)

- **Primitive:** An antiderivative.
- **Law of composite differentiation:** The chain rule.
- Went over how Shao has been applying the law of composite differentiation with respect to separable ODEs:
 - Rearrange the initial separable ODE as follows.

$$\frac{1}{g(y)} \cdot \frac{dy}{dt} = f(t)$$

- Define $dH/dy = 1/g(y)$. Then, continuing from the above, we have by the law of composite differentiation that

$$\begin{aligned}\frac{dH}{dy} \cdot \frac{dy}{dt} &= f(t) \\ \frac{dH}{dt} &= f(t)\end{aligned}$$

- From the definition of H , we know that $H(y) = \int_{y_0}^y dw/g(w)$. We also have from the FTC that $f(t) = \frac{d}{dt} \int_{t_0}^t f(\tau) d\tau$. Thus, continuing from the above, we have that

$$\begin{aligned}\frac{d}{dt}(H) &= f(t) \\ \frac{d}{dt} \left[\int_{y_0}^y \frac{dw}{g(w)} \right] &= \frac{d}{dt} \int_{t_0}^t f(\tau) d\tau \\ \frac{d}{dt} \left[\int_{y_0}^{y(t)} \frac{dw}{g(w)} - \int_{t_0}^t f(\tau) d\tau \right] &= 0\end{aligned}$$

as desired.

- It follows since $y(t_0) = y_0$ that $C = H(y_0) = 0$, so we can take the above to

$$\int_{y_0}^{y(t)} \frac{dw}{g(w)} = \int_{t_0}^t f(\tau) d\tau$$

knowing that our constant of integration is zero.

- Take away from Brachistochrone problem: Just an example of a BDE; we won't have to answer questions on it.