Operations Research III: Theory

Case Study: Regression Models and Support Vector Machine

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Applications of Operations Research theories

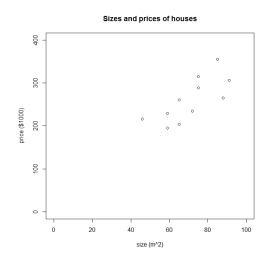
- ► The theory of Operations Research has been used to develop models in many fields.
 - ▶ The doctoral degree obtained by George Dantzig (the inventor of the simplex method) is Statistics.
- ▶ We will introduce some models in **Statistics** and **Machine Learning** developed with Operations Research.
 - ► More specifically, Nonlinear Programming.

Road map

- ► Regression models.
- ► Support Vector Machine.

Linear regression

- Consider a set of data $(x_i, y_i), i = 1, ..., n$.
- ▶ If we believe that x_i and y_i has a linear relationship, we may apply **simple linear** regression to fit these data.

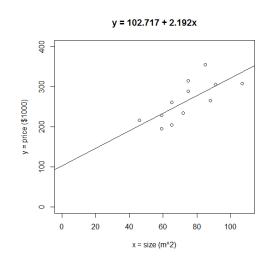


Linear regression

• We try to find α and β such that a line $y = \alpha + \beta x$ to minimize the sum of squared errors for all the data points:

$$\min_{\alpha,\beta} \sum_{i=1}^{n} \left[y_i - (\alpha + \beta x_i) \right]^2.$$

- Note that this is to solve a nonlinear program:
 - ► Is this a convex program?
 - ► May we solve it?



Linear regression: convexity

▶ Let $f(\alpha, \beta) = \sum_{i=1}^{n} [y_i - (\alpha + \beta x_i)]^2$ be the objective function. We have

$$\nabla f = \begin{bmatrix} -2\sum_{i=1}^{n} [y_i - (\alpha + \beta x_i)] \\ -2\sum_{i=1}^{n} [y_i - (\alpha + \beta x_i)]x_i \end{bmatrix} \text{ and } \nabla^2 f = \begin{bmatrix} 2n & 2\sum_{i=1}^{n} x_i \\ 2\sum_{i=1}^{n} x_i & 2\sum_{i=1}^{n} x_i^2 \end{bmatrix}.$$

▶ The objective function is convex as n > 0 and

$$|\nabla^2 f| = n \sum_{i=1}^n x_i^2 - \sum_{i=1}^n x_i \sum_{i=1}^n x_i = (n-1) \sum_{i=1}^n x_i - 2 \sum_{i=1}^{n-1} \sum_{j=i+1}^n x_i x_j$$
$$= \sum_{i=1}^{n-1} \sum_{j=i+1}^n (x_i - x_j)^2 \ge 0.$$

Linear regression: convexity

▶ Alternatively, we may denote

$$f(\alpha, \beta) = \sum_{i=1}^{n} [y_i - (\alpha + \beta x_i)]^2 = \sum_{i=1}^{n} f_i(\alpha, \beta)$$

and see that

$$f_i(\alpha, \beta) = y_i^2 + \alpha^2 + \beta^2 x_i^2 - 2\alpha y_i - 2\beta x_i y_i + 2\alpha \beta x_i.$$

▶ We then have

$$\nabla^2 f_i(\alpha, \beta) = \begin{bmatrix} 2 & 2x_i \\ 2x_i & 2x_i^2 \end{bmatrix},$$

which means f_i is a convex function.

 \triangleright As the summation of convex functions is also convex, f is convex.

Linear regression: solution

- ➤ Simple linear regression is to solve an unconstrained convex program.
- ▶ Numerical algorithms may be used to solve for the optimal α and β .
- ▶ Nevertheless, analysis gives us a **closed-form formula**:
- $\triangleright \nabla f(\alpha, \beta) = 0$ requires

$$-2\sum_{i=1}^{n} [y_i - (\alpha + \beta x_i)] = 0 \text{ and } -2\sum_{i=1}^{n} [y_i - (\alpha + \beta x_i)]x_i = 0$$

which implies

$$n\alpha + \left(\sum_{i=1}^{n} x_i\right)\beta = \sum_{i=1}^{n} y_i$$
 and $\left(\sum_{i=1}^{n} x_i\right)\alpha + \left(\sum_{i=1}^{n} x_i^2\right)\beta = \sum_{i=1}^{n} x_i y_i$.

- ▶ Solving the linear system results in a direct way to optimize α and β .
- ➤ Complete this and compare your result with your Statistics textbook!

Linear regression: remarks

▶ The same idea applies to multiple linear regression: Given a data set $\{x_1^i, x_2^i, ..., x_p^i, y_i\}_{i=1,...,n}$, find $\alpha, \beta_1, \beta_2, ...$, and β_p to solve

$$\min_{\alpha,\beta} \sum_{i=1}^{n} \left[y_i - (\alpha + \sum_{j=1}^{p} \beta_j x_j^i) \right]^2 = \min_{\alpha,\beta} \sum_{i=1}^{n} \left[y_i - (\alpha + \beta^T x^i) \right]^2.$$

- ▶ There are many perspectives to consider linear regression:
 - ▶ As solving a nonlinear optimization problem.
 - ► As projecting a vector to a vector space.
 - ► And others.
- ▶ One reason to define fitting error as the sum of **squared** errors rather than the sum of absolute errors is to reduce the **difficulty of optimization**.

Some other regression models

- ▶ When one applies linear regression for prediction and hopes to avoid overfitting, one may apply **regularization**. Let $\lambda > 0$ be the given penalty of "using variables," we have:
 - ► Ridge regression:

$$\min_{\alpha,\beta} \sum_{i=1}^{n} \left[y_i - (\alpha + \beta^{\mathrm{T}} x^i) \right]^2 + \lambda \sum_{j=1}^{p} \beta_j^2.$$

► LASSO regression:

$$\min_{\alpha,\beta} \sum_{i=1}^{n} \left[y_i - (\alpha + \beta^{\mathrm{T}} x^i) \right]^2 + \lambda \sum_{i=1}^{p} |\beta_i|.$$

▶ Both the above two models are solving unconstrained convex programs.

Road map

- ► Regression models.
- ► Support vector machine.

11/30

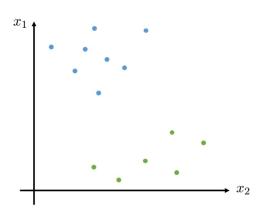
Classification

- ► Classification is an important subject in Machine Learning.
- ▶ We are given a data set $\{x_1^i, x_2^i, ..., x_n^i, y_i\}_{i=1,...,m}$, where $y_i \in \{1, -1\}$ labels some kind of success and failure.
- We want to find a **classifier** to assign data point i a **class** according to x^i to minimize the total number of classification error.¹
- ► General classification is difficult. Let's do linear classification.

¹It will be better if we state as classification problem as a prediction problem with a slightly different statement. Nevertheless, as this is an optimization course, let's keep things as simple as possible.

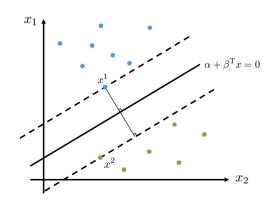
Linear classification

- Let's start with an example.
- Linear classification: How to draw a straight line to separate blue dots and green dots?
 - $ightharpoonup \mathbb{R}^2$: a line.
 - $ightharpoonup \mathbb{R}^3$: a plane.
 - $ightharpoonup \mathbb{R}^n$ for n > 3: a hyperplane.
- ▶ While (infinitely) many lines may do the separation in this example, which one is the "best"?



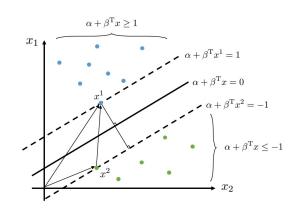
Support vector machine

- ► The line that is the **farthest** from both groups is the best.
- The two dashed lines are called **supporting hyperplanes**, one for each group.
- The two points x^1 and x^2 (or vectors in general) are called **support vectors**.
- ► A support vector machine (SVM) finds the best separating hyperplane $\alpha + \beta^{T}x = 0$.



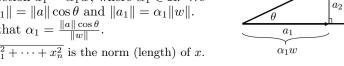
Problem formulation

- Let's classify a point as blue if $\alpha + \beta^T x \ge 1$ or green if $\alpha + \beta^T x \le -1$.
 - ▶ It is equivalent to use k and -k instead of 1 and -1 as we may scale α and β in any way we like.
- The distance between the two supporting hyperplanes is the length of the **projection** of $x^1 - x^2$ onto the normal vector of the separating hyperplane (which is β).



Vector projection

- \blacktriangleright What is the projection of $a \in \mathbb{R}^n$ onto $w \in \mathbb{R}^n$?
- Let the projection $a_1 = \alpha_1 w$, where $\alpha_1 \in \mathbb{R}$. We then have $||a_1|| = ||a|| \cos \theta$ and $||a_1|| = \alpha_1 ||w||$. They imply that $\alpha_1 = \frac{\|a\| \cos \theta}{\|a\|}$.
 - $||x|| = \sqrt{x_1^2 + \cdots + x_n^2}$ is the norm (length) of x.



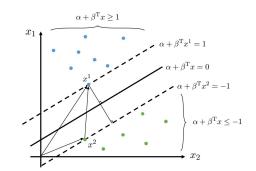
▶ It then follows that

$$a_1 = \alpha_1 w = \frac{\|a\| \cos \theta}{\|w\|} w = \frac{\|a\| \frac{a^T w}{\|a\| \|w\|}}{\|w\|} w = \frac{a^T w}{\|w\|^2} w$$
$$\Rightarrow \|a_1\| = \frac{a^T w}{\|w\|^2} \|w\| = \frac{a^T w}{\|w\|}.$$

Problem formulation

- The length of the projection of a onto w is $\frac{a^{\mathrm{T}}w}{\|w\|}$.
- For $x^1 x^2$ and β , that length is $\frac{(x^1 x^2)^{\mathrm{T}} \beta}{\|\beta\|}$.
- ► The objective function is thus

$$\max_{\alpha,\beta} \ \frac{(x^1 - x^2)^{\mathrm{T}} \beta}{\|\beta\|}.$$



 $ightharpoonup \alpha$ and β should ensure that, for all i = 1, ..., m, we have

$$y_i(\alpha + \beta^{\mathrm{T}} x^i) \ge 1.$$

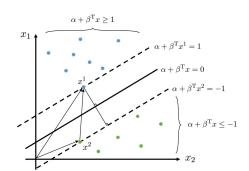
Simplifying the objective function

▶ The objective function is

$$\max_{\alpha,\beta} \ \frac{(x^1 - x^2)^{\mathrm{T}} \beta}{\|\beta\|}.$$

- ► However, given n data points, how may we know which two are supporting?
- Luckily, as x^1 and x^2 are supporting, we have $(x^1 x^2)^T \beta = 2$.
- ▶ The objective function becomes

$$\max_{\alpha,\beta} \ \frac{2}{\|\beta\|}$$



The SVM problem (version 1)

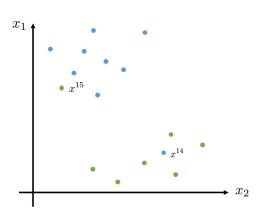
- ▶ No one is happy to have decision variables in a denominator.
- ► Rather than maximizing $\frac{2}{\|\beta\|}$, let's minimize $\frac{1}{2}\|\beta\|$, which is equivalent to minimize $\frac{1}{2}\sum_{k=1}^{n}\beta_k^2$.
- ▶ The SVM problem is finally formulated as

$$\begin{aligned} & \min_{\alpha,\beta} & \frac{1}{2} \sum_{k=1}^{n} \beta_k^2 \\ & \text{s.t.} & y_i(\alpha + \beta^T x^i) \ge 1 \qquad \forall i = 1, ..., m. \end{aligned}$$

▶ Note that this is a **convex program!** We may apply numerical algorithms for (constrained) convex programs to solve it.

Imperfect separation

- ► In many case **perfect separation** (with no classification error) is impossible.
- ► In this case, we allow errors but add the "degree of errors" into the objective function.



The SVM problem (final version)

- ▶ Given a separating hyperplane $\alpha + \beta^{\mathrm{T}}x = 0$, ideally we have $y_i(\alpha + \beta^{\mathrm{T}}x^i) \geq 1$ for data point i.
- ▶ When this is violated, let $\gamma_i \geq 0$ be the **degree of violation**.
- ▶ The SVM problem that allows imperfect separation is

$$\min_{\alpha,\beta,\gamma} \quad \frac{1}{2} \sum_{k=1}^{n} \beta_k^2 + C \sum_{i=1}^{m} \gamma_i$$
s.t.
$$y_i (\alpha + \beta^T x^i) \ge 1 - \gamma_i \quad \forall i = 1, ..., m$$

$$\gamma_i \ge 0 \quad \forall i = 1, ..., m,$$

where $C \geq 0$ is a given parameter.

- ightharpoonup A larger C means a larger **penalty** is incurred with classification errors.
- ► This is still a **convex program!**

Dualization for the SVM problem

- ► To solve this constrained convex program, let's find its **Lagrange** dual program.
- ▶ Let $\lambda_i \geq 0$ and $\mu_i \geq 0$ be the Lagrange multipliers, the Lagrangian is

$$\mathcal{L}(\alpha, \beta, \gamma | \lambda, \mu) = \frac{1}{2} \sum_{k=1}^{n} \beta_k^2 + C \sum_{i=1}^{m} \gamma_i$$
$$- \sum_{i=1}^{m} \lambda_i \left[y_i \left(\alpha + \sum_{k=1}^{n} x_k^i \beta_k \right) - 1 + \gamma_i \right] - \sum_{i=1}^{m} \mu_i \gamma_i.$$

The Lagrange dual program is

$$\max_{\lambda > 0, \mu > 0} \min_{\alpha, \beta, \gamma} \mathcal{L}(\alpha, \beta, \gamma | \lambda, \mu).$$

Analyzing the inner program

▶ To choose α , β_k , and γ_i to minimize

$$\frac{1}{2} \sum_{k=1}^{n} \beta_k^2 + C \sum_{i=1}^{m} \gamma_i - \sum_{i=1}^{m} \lambda_i \left[y_i \left(\alpha + \sum_{k=1}^{n} x_k^i \beta_k \right) - 1 + \gamma_i \right] - \sum_{i=1}^{m} \mu_i \gamma_i,$$

the first-order condition is necessary and sufficient:

$$\sum_{i=1}^{m} \lambda_i y_i = 0, \quad \beta_k = \sum_{i=1}^{m} \lambda_i y_i x_k^i \ \forall k, \text{ and } \quad C = \lambda_i + \mu_i \ \forall i.$$

► The first and third sets of constraints do not have any primal variable involved. They will become **constraints** of the Lagrangian dual program for the **dual variables** to satisfy.

Analyzing the inner program

► For any $\lambda \geq 0$ and $\mu \geq 0$ satisfying $\sum_{i=1}^{m} \lambda_i y_i = 0$ and $C = \lambda_i + \mu_i$ for all i = 1, ..., m, the Lagrangian can be simplified:

$$\frac{1}{2} \sum_{k=1}^{n} \beta_k^2 + C \sum_{i=1}^{m} \gamma_i - \sum_{i=1}^{m} \lambda_i \left[y_i \left(\alpha + \sum_{k=1}^{n} x_k^i \beta_k \right) - 1 + \gamma_i \right] - \sum_{i=1}^{m} \mu_i \gamma_i \right]$$

$$= \frac{1}{2} \sum_{k=1}^{n} \beta_k^2 - \sum_{i=1}^{m} \lambda_i \left[y_i \sum_{k=1}^{n} x_k^i \beta_k \right] + \sum_{i=1}^{m} \lambda_i.$$

▶ Plugging $\beta_k = \sum_{j=1}^m \lambda_j y_j x_k^j$ into the Lagrangian results in

$$\frac{1}{2} \sum_{k=1}^{n} \left(\sum_{j=1}^{m} \lambda_{j} y_{j} x_{k}^{j} \right)^{2} - \sum_{i=1}^{m} \lambda_{i} y_{i} \sum_{k=1}^{n} \left(\sum_{j=1}^{m} \lambda_{j} y_{j} x_{k}^{j} \right) x_{k}^{i} + \sum_{i=1}^{m} \lambda_{i}$$

$$= -\frac{1}{2} \sum_{i=1}^{m} \sum_{j=1}^{m} \lambda_{i} \lambda_{j} y_{i} y_{j} (x^{i})^{T} x^{j} + \sum_{j=1}^{m} \lambda_{i}.$$

Dualization for the SVM problem

▶ The Lagrangian dual program now becomes

$$\max_{\lambda,\mu} -\frac{1}{2} \sum_{i=1}^{m} \sum_{j=1}^{m} \lambda_i \lambda_j y_i y_j (x^i)^T x^j + \sum_{i=1}^{m} \lambda_i$$
s.t.
$$\sum_{i=1}^{m} \lambda_i y_i = 0$$

$$C = \lambda_i + \mu_i \quad \forall i = 1, ..., m$$

$$\lambda_i > 0, \ \mu_i > 0 \quad \forall i = 1, ..., m.$$

- ▶ To further simplify this program, note that μ_i does not exist in the objective function.
- ▶ In fact, it simply tells us that λ_i cannot be greater than C.

The dual program of the SVM problem

▶ The dual program of is finally derived as

$$\max_{\lambda} -\frac{1}{2} \sum_{i=1}^{m} \sum_{j=1}^{m} \lambda_i \lambda_j y_i y_j (x^i)^{\mathrm{T}} x^j + \sum_{i=1}^{m} \lambda_i$$
s.t.
$$\sum_{i=1}^{m} \lambda_i y_i = 0$$

$$0 \le \lambda_i \le C \quad \forall i = 1, ..., m.$$

- ▶ This is another constrained nonlinear program.
 - ▶ The number of variables and constraints are m and 1 + 2m. Those for the primal are 1 + n + m and 2m.
 - ▶ Most of the dual constraints are "simple".
 - ▶ Nevertheless, is it really a convex program (those the theory tells us so)?

Convexity of the dual program

► Let

$$f(\lambda) = \frac{1}{2} \sum_{i=1}^{m} \sum_{j=1}^{m} \lambda_i \lambda_j y_i y_j (x^i)^{\mathrm{T}} x^j - \sum_{i=1}^{m} \lambda_i$$

be the negation of the objective function, we have

$$\nabla^{2} f(\lambda) = \begin{bmatrix} y_{1} y_{1}(x^{1})^{\mathrm{T}} x^{1} & y_{1} y_{2}(x^{1})^{\mathrm{T}} x^{2} & \cdots & y_{1} y_{m}(x^{1})^{\mathrm{T}} x^{m} \\ y_{2} y_{1}(x^{2})^{\mathrm{T}} x^{1} & & & \ddots & \vdots \\ \vdots & & & \ddots & \vdots \\ y_{m} y_{1}(x^{m})^{\mathrm{T}} x^{1} & \cdots & & y_{m} y_{m}(x^{m})^{\mathrm{T}} x^{m} \end{bmatrix}$$

$$= \begin{bmatrix} y_{1} x_{1}^{\mathrm{T}} \\ \vdots \\ y_{m} x_{m}^{\mathrm{T}} \end{bmatrix} [y_{1} x_{1} & \cdots & y_{m} x_{m}] = Z^{\mathrm{T}} Z,$$

where $Z = \begin{bmatrix} y_1 x_1 & \cdots & y_m x_m \end{bmatrix} \in \mathbb{R}^{n \times m}$.

Convexity of the dual program

➤ To show that the Hessian is positive semidefinite, we use the definition. Because

$$x^{\mathrm{T}} \nabla^2 f(\lambda) x = x^{\mathrm{T}} Z^{\mathrm{T}} Z x = (Zx)^{\mathrm{T}} Z x = \|Zx\|^2 \ge 0 \quad \forall x \in \mathbb{R}^m,$$

the proof is complete.

Remarks

- ▶ In this lecture, we show how the theory of Operations Research may be utilized to develop **models** in related fields.
 - ► There are much more!
 - We choose the examples from Statistics and Machine Learning not because these are the most important.
 - We do so because at this moment many students want to learn these subjects.
 - ▶ A **solid foundation** is needed for us to get deeper understanding.
- ▶ There are still a lot of interesting things to learn.
 - Now you have a not-so-bad foundation.
 - Go and explore the fascinating world!

That's all. Thank you!