

Operations Research I: Models & Applications

Integer Programming

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Road map

- ▶ **Introduction to integer programming.**
- ▶ Integer programming formulation.
- ▶ Facility location problems.
- ▶ Machine scheduling problems.
- ▶ Vehicle routing problems.

Integer programming

- ▶ We have worked with LPs.
- ▶ In some cases, variables must only take **integer values**.
- ▶ The subject of formulating and solving models with integer variables is **Integer Programming** (IP).
 - ▶ An IP is typically a linear IP (LIP).
 - ▶ If the objective function or any functional constraint is nonlinear, it is a nonlinear IP (NLIP).
 - ▶ We will focus on linear IP.

Personnel scheduling (again)



- ▶ We know that United Airline developed an LP to determine the number of staffs in each of their service locations.
- ▶ The same problem is faced by Taco Bell.
 - ▶ It has more than 6500 restaurants in the US.
 - ▶ It asks how many staffs to have at each restaurant in each shift.
- ▶ Taco Bell developed an Integer Program (i.e., an LP with integer variables) to solve its workforce scheduling problem.
 - ▶ The number of staffs is typically **small**! Rounding is very inaccurate.
- ▶ \$13 million are saved per year. ¹

¹Hueter, J., & Swart, W. (1998). An Integrated Labor-Management System for Taco Bell. *Interfaces*, 28(1), 75-91.

Route selection



- ▶ Waste Management Inc. operates an recycling network with 293 landfill sites, 16 waste-to-energy plants, 72 gas-to-energy facilities, 146 recycling plants, 346 transfer stations, and 435 collection depots.
 - ▶ 20000 routes must be go through by its vehicles in each day.
- ▶ How to determine a route?
 - ▶ Construct a network with nodes and edges.
 - ▶ Give each edge a **binary** variable: 1 if included and 0 otherwise.
 - ▶ Constraints are required to make sure that selected edges are really forming a route.
- ▶ A huge IP is constructed to save the company \$498 million in operational expenses over a 5-year period.²

²Sahoo, S., Kim, S., Kim, B., Kraas, B., & Popov, A. (2005). Routing Optimization for Waste Management. *Interfaces*, 35(1), 24-36.

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The knapsack problem

- ▶ We start our illustration with the classic **knapsack** problem.
- ▶ There are four items to select:

Item	1	2	3	4
Value (\$)	16	22	12	8
Weight(kg)	5	7	4	3

- ▶ The knapsack capacity is 10 kg.
- ▶ We maximize the total value without exceeding the knapsack capacity.
- ▶ The complete formulation is

$$\begin{array}{ll} \max & 16x_1 + 22x_2 + 12x_3 + 8x_4 \\ \text{s.t.} & 5x_1 + 7x_2 + 4x_3 + 3x_4 \leq 10 \\ & x_i \in \{0, 1\} \quad \forall i = 1, \dots, 4. \end{array}$$

Requirements on selecting variables

- ▶ Integer programming allows us to implement some selection rules.
- ▶ At least/most some items:
 - ▶ Suppose we must select **at least** one item among items 2, 3, and 4:

$$x_2 + x_3 + x_4 \geq 1.$$

- ▶ Suppose we must select **at most** two items among items 1, 3, and 4:

$$x_1 + x_3 + x_4 \leq 2.$$

Requirements on selecting variables

► Or:

- Select item 2 or item 3:

$$x_2 + x_3 \geq 1.$$

- Select item 2; otherwise, items 3 and 4 together:

$$2x_2 + x_3 + x_4 \geq 2.$$

► If-else:

- If item 2 is selected, select item 3:

$$x_2 \leq x_3.$$

- If item 1 is selected, do not select items 3 and 4:

$$2(1 - x_1) \geq x_3 + x_4.$$

At least/most some constraints

- ▶ Using a similar technique, we may **flexibly** select constraints.
- ▶ Suppose satisfying one of the two constraints

$$g_1(x) \leq b_1 \quad \text{and} \quad g_2(x) \leq b_2.$$

is enough. How to formulate this situation?

- ▶ Let's define a binary variable

$$z = \begin{cases} 0 & \text{if } g_1(x) \leq b_1 \text{ is satisfied,} \\ 1 & \text{if } g_2(x) \leq b_2 \text{ is satisfied.} \end{cases}$$

- ▶ With M_i being an upper bound of each LHS, the following two constraints implement what we need:

$$\begin{aligned} g_1(x) - b_1 &\leq M_1 z \\ g_2(x) - b_2 &\leq M_2(1 - z). \end{aligned}$$

At least/most some constraints

- ▶ Suppose at least two of the three constraints

$$g_i(x) \leq b_i, \quad i = 1, 2, 3.$$

must be satisfied. How to play the same trick?

- ▶ Let

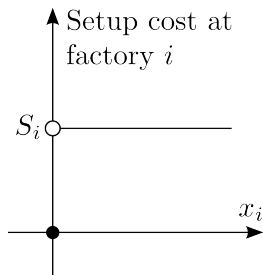
$$z_i = \begin{cases} 1 & \text{if } g_i(x) \leq b_i \text{ is satisfied,} \\ 0 & \text{if } g_i(x) \leq b_i \text{ may be unsatisfied.} \end{cases}$$

- ▶ With M_i being an upper bound of each LHS, the following constraints are what we need:

$$\begin{aligned} g_i(x) - b_i &\leq M_i(1 - z_i) \quad \forall i = 1, \dots, 3 \\ z_1 + z_2 + z_3 &\geq 2. \end{aligned}$$

Fixed-charge constraints

- ▶ Consider the following example:
- ▶ n factories, 1 market, 1 product.
 - ▶ K_i is the capacity of factory i .
 - ▶ C_i is unit production cost at factory i .
 - ▶ D is the demand of the product.
 - ▶ We want to satisfy the demand with the minimum cost.
- ▶ **Setup cost** at factory i : S_i .
 - ▶ One needs to pay the setup cost as long as any **positive** amount of products is produced.



Basic formulation

- ▶ Let the decision variables be

x_i = production quantity at factory i , $i = 1, \dots, n$,

$$y_i = \begin{cases} 1 & \text{if some products are produced at factory } i, i = 1, \dots, n, \\ 0 & \text{o/w.} \end{cases}$$

- ▶ Objective function:

$$\min \sum_{i=1}^n C_i x_i + \sum_{i=1}^n S_i y_i.$$

- ▶ Capacity limitation:

$$x_i \leq K_i \quad \forall i = 1, \dots, n.$$

- ▶ Demand fulfillment:

$$\sum_{i=1}^n x_i \geq D.$$

Setup costs

- ▶ How may we know whether we need to pay the setup cost at factory i ?
 - ▶ If $x_i > 0$, y_i must be 1; if $x_i = 0$, y_i should be 0.
- ▶ So the relationship between x_i and y_i should be:

$$x_i \leq K_i y_i \quad \forall i = 1, \dots, n.$$

- ▶ If $x_i > 0$, y_i cannot be 0.
 - ▶ If $x_i = 0$, y_i can be 0 or 1. Why y_i will always be 0 when $x_i = 0$?
- ▶ Finally, binary and nonnegative constraints:

$$x_i \geq 0, y_i \in \{0, 1\} \quad \forall i = 1, \dots, n.$$

Fixed-charge constraints

- ▶ The constraint $x_i \leq K_i y_i$ is known as a **fixed-charge constraint**.
- ▶ In general, a fixed-charge constraint is

$$x \leq My.$$

- ▶ Both x and y are decision variables.
- ▶ $y \in \{0, 1\}$ is determined by x .
- ▶ M must be set to be an **upper bound** of x .
- ▶ When x is binary, $x \leq y$ is sufficient.
- ▶ We need to make M an upper bound of x .
 - ▶ For example, K_i is an upper bound of x_i in the factory example. Why?
 - ▶ What if there is no capacity limitation?

Road map

- ▶ Introduction to integer programming.
- ▶ Integer programming formulation.
- ▶ **Facility location problems.**
- ▶ Machine scheduling problems.
- ▶ Vehicle routing problems.

Facility location problems

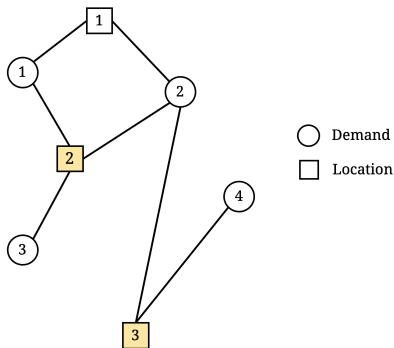
- ▶ One typical managerial decision is “where to build my facilities?”
 - ▶ Where to open convenience stores?
 - ▶ Where to build warehouses or distribution centers?
 - ▶ Where to build factories?
 - ▶ Where to build power stations, fire stations, or police stations?
- ▶ A similar question is “where to locate a scarce resource?”
 - ▶ Where to put a limited number of fire engines or ambulances?
 - ▶ Where to put a limited number of police officers?
 - ▶ Where to put a limited number of ice cream machines?
- ▶ These problems are **facility location problems**.
 - ▶ In this lecture, we focus on **discrete** facility location problems: We choose a subset of locations from a set of finite locations.

Facility location problems

- ▶ In general, there are some **demand nodes** and some **potential locations**.
 - ▶ We build facilities at locations to serve demands.
 - ▶ E.g., build distribution centers to ship to retail stores.
 - ▶ E.g., build fire stations to cover cities, towns, and villages.
- ▶ Facility location problems are typically categorized based on their objective functions.
- ▶ In this lecture, we introduce three types of facility location problems:
 - ▶ **Set covering problems**: Build a minimum number of facilities to cover all demands.
 - ▶ **Maximum covering problems**: Build a given number of facilities to cover as many demands as possible.
 - ▶ **Fixed charge location problems**: Finding a balance between benefit of covering demands and cost of building facilities.

Set covering problems

- ▶ Consider a set of demands I and a set of locations J .
- ▶ The distance (or traveling time) between demand i and location j is $d_{ij} > 0$, $i \in I$, $j \in J$.
- ▶ A service level $s > 0$ is given: Demand i is said to be “covered” by location j if $d_{ij} < s$.
- ▶ Question: How to allocate as few facilities as possible to cover all demands?

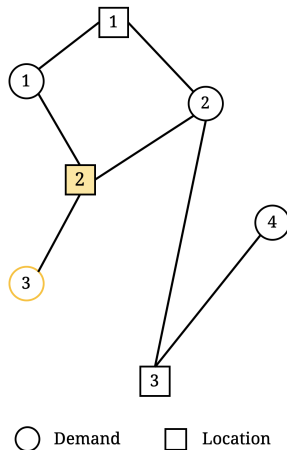


Set covering problems

- ▶ Let's define the following parameter:
 $a_{ij} = 1$ if $d_{ij} < s$ or 0 otherwise, $i \in I$,
 $j \in J$.
- ▶ Let's define the following variables:
 $x_j = 1$ if a facility is built at location
 $j \in J$ or 0 otherwise.
- ▶ The complete formulation is

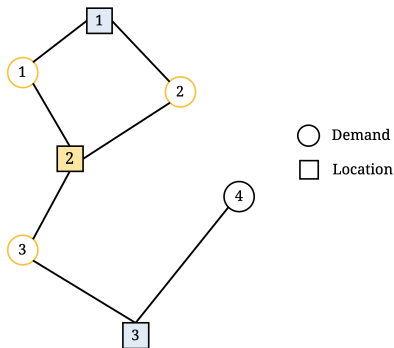
$$\begin{aligned} \min \quad & \sum_{j \in J} x_j \\ \text{s.t.} \quad & \sum_{j \in J} a_{ij} x_j \geq 1 \quad \forall i \in I \\ & x_j \in \{0, 1\} \quad \forall j \in J. \end{aligned}$$

- ▶ The weighted version: $\min \sum_{j \in J} w_j x_j$.



Maximum covering problems

- ▶ Consider a set of demands I and a set of locations J .
- ▶ The distances d_{ij} , service level s , and the covering coefficient a_{ij} are also given.
- ▶ We are restricted to build at most $p \in \mathbb{N}$ facilities.
- ▶ Question: How to allocate at most p facilities to cover as many demands as possible?



Maximum covering problems

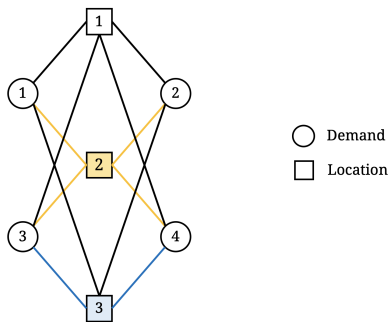
- ▶ Still let $x_j = 1$ if a facility is built at location $j \in J$ or 0 otherwise.
- ▶ Also let $y_i = 1$ if demand $i \in I$ is covered by any facility or 0 otherwise.
- ▶ The complete formulation is

$$\begin{aligned} \max \quad & \sum_{i \in I} y_i \\ \text{s.t.} \quad & \sum_{j \in J} a_{ij} x_j \geq y_i \quad \forall i \in I \\ & \sum_{j \in J} x_j \leq p \\ & x_j \in \{0, 1\} \quad \forall j \in J \\ & y_i \in \{0, 1\} \quad \forall i \in I. \end{aligned}$$

- ▶ The weighted version: $\max \sum_{i \in I} w_i y_i$.

Fixed charge location problems

- ▶ Consider a set of demands I and a set of locations J .
- ▶ At demand i , the demand size is $h_i > 0$.
- ▶ The unit shipping cost from location j to demand i is $d_{ij} > 0$.
- ▶ The fixed construction cost at location j is $f_j > 0$.
- ▶ Question: How to allocate some facilities to minimize the total shipping and construction costs?



Fixed charge location problems

- ▶ We still need x_j : $x_j = 1$ if a facility is built at location $j \in J$ or 0 otherwise.
- ▶ We now need y_{ij} : $y_{ij} = 1$ if demand $i \in I$ is served by facility at location $j \in J$ or 0 otherwise.
- ▶ The complete formulation is

$$\begin{aligned} \min \quad & \sum_{i \in I} \sum_{j \in J} h_i d_{ij} y_{ij} + \sum_{j \in J} f_j x_j \\ \text{s.t.} \quad & y_{ij} \leq x_j \quad \forall i \in I, j \in J \\ & \sum_{j \in J} y_{ij} = 1 \quad \forall i \in I \\ & x_j \in \{0, 1\} \quad \forall j \in J \\ & y_i \in \{0, 1\} \quad \forall i \in I. \end{aligned}$$

Fixed charge location problems

- ▶ The previous model is the **uncapacitated** version.
 - ▶ A facility can serve any amount of demand.
- ▶ If facility at location j has a limited capacity $K_j > 0$, we may add the capacity constraint

$$\sum_{i \in I} h_i y_{ij} \leq K_j \quad \forall j \in J.$$

- ▶ The **capacitated** version is usually called the capacitated facility location problem (abbreviated as CFL). The uncapacitated one is abbreviated as UFL.

Remarks

- ▶ When to use set covering?
 - ▶ When we are required to take care of (almost) everyone.
 - ▶ E.g., fire stations and police stations.
- ▶ When to use maximum covering?
 - ▶ When budgets are limited.
 - ▶ E.g., cellular data networks.
- ▶ When to use fixed charge location?
 - ▶ When service costs depends on distances.
 - ▶ E.g., distribution centers.

Road map

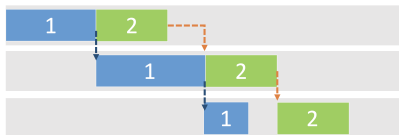
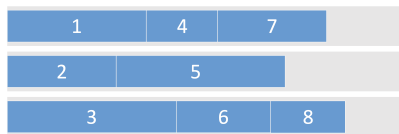
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Machine scheduling problems

- ▶ In many cases, **jobs/tasks** must be assigned to **machines/agents**.
- ▶ As an example, consider a factory producing one product for n customers.
 - ▶ Serial production: Only one job can be processed at one time.
 - ▶ Each job has its due date.
 - ▶ How to schedule the n jobs to minimize the total number of delayed jobs?
- ▶ In this example, scheduling is nothing but **sequencing**.
 - ▶ Splitting jobs is not helpful.
 - ▶ There are $n!$ ways to sequence the n jobs.
 - ▶ Is there a way to formulate this problem (so that a solution may be obtained by solving the model)?
- ▶ The problems of scheduling jobs/tasks to machines/agents are **machine scheduling problems**.

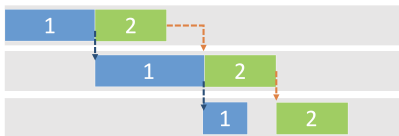
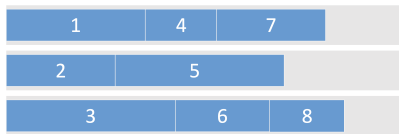
Machine scheduling problems

- ▶ Machine scheduling problems may be categorized in multiple ways:
- ▶ Production mode:
 - ▶ Single machine serial production.
 - ▶ Multiple parallel machines.
 - ▶ Flow shop problems.
 - ▶ Job shop problems.



Machine scheduling problems

- ▶ Job splitting:
 - ▶ Non-preemptive problems.
 - ▶ Preemptive problems.
- ▶ Performance measurement:
 - ▶ Makespan (the time that all jobs are completed).
 - ▶ (Weighted) total completion time.
 - ▶ (Weighted) number of delayed jobs.
 - ▶ (Weighted) total lateness.
 - ▶ (Weighted) total tardiness.
 - ▶ And more.



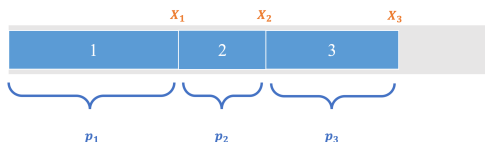
Minimizing single-machine total completion time

- ▶ Consider scheduling n jobs on a single machine.
- ▶ Job $j \in J = \{1, 2, \dots, n\}$ has **processing time** p_j .
- ▶ Different schedules give these jobs different **completion times**. The completion time of job j is denoted as x_j .
- ▶ The machine can process only one job at a time.
- ▶ We aim to schedule all the jobs to minimize the total completion time

$$\sum_{j \in J} x_j.$$

Minimizing single-machine total completion time

- ▶ Let's use x_j to be our decision variables.
- ▶ Suppose we schedule jobs 1, 2, ..., and n in this order, we will have $x_1 = p_1$, $x_2 = p_1 + p_2$, ..., and $x_n = \sum_{i=1}^n p_i$.
- ▶ A **Gantt chart** is helpful to illustrate a schedule.



- ▶ Obviously, splitting jobs does not help for this problem (Why?).
- ▶ Because the machine can start job 2 only after job 1 is completed, we have $x_2 \geq x_1 + p_2$ as a constraint. But what if job 2 should be scheduled before job 1?

Minimizing single-machine total completion time

- ▶ In a feasible schedule, job i is either before or after job j , for all $j \neq i$.
- ▶ Therefore, we need to satisfy at least one of the following two constraints:

$$x_j \geq x_i + p_j \quad \text{and} \quad x_i \geq x_j + p_i.$$

- ▶ Let $z_{ij} = 1$ if job j is before job i or 0 otherwise, $i \in J, j \in J, i < j$.
- ▶ The constraints we need:

$$x_i + p_j - x_j \leq M z_{ij}$$

$$x_j + p_i - x_i \leq M(1 - z_{ij}).$$

- ▶ What value of M works?
 - ▶ How about $M = \sum_{j \in J} p_j$?

Minimizing single-machine total completion time

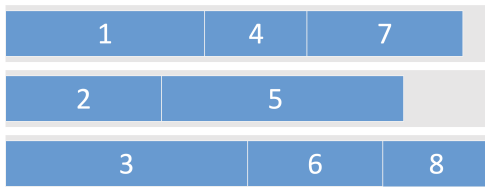
- ▶ The complete formulation is

$$\begin{aligned} \min \quad & \sum_{j \in J} x_j \\ \text{s.t.} \quad & x_i + p_j - x_j \leq M z_{ij} & \forall i \in J, j \in J, i < j \\ & x_j + p_i - x_i \leq M(1 - z_{ij}) & \forall i \in J, j \in J, i < j \\ & x_j \geq p_j & \forall j \in J \\ & x_j \geq 0 & \forall j \in J \\ & z_{ij} \in \{0, 1\} & \forall i \in J, j \in J, i < j. \end{aligned}$$

- ▶ While there is a way to optimize the schedule (how?), the problem becomes much harder if a job may be processed only after it is released.
- ▶ Let R_j be the **release time** of job j . How to add this into the model?

Minimizing makespan on parallel machines

- ▶ Consider scheduling n jobs on m **parallel** machines.
- ▶ Job $j \in J = \{1, 2, \dots, n\}$ has processing time p_j .
- ▶ A job can be processed at any machine. However, it can be processed only on one machine.



- ▶ Different schedules give these machines different **completion times**.
- ▶ The **makespan** of a schedule is the maximum completion time.
- ▶ How may we minimize the makespan?

Minimizing makespan on parallel machines

- ▶ As long as some jobs are assigned to a machine, the sequence on that machine does not matter.
- ▶ The problem of minimizing makespan is just to **assign** jobs to machines.
- ▶ Let $x_{ij} = 1$ if job $j \in J$ is assigned to machine $i \in I$ or 0 otherwise.
- ▶ On machine $i \in I$, the last job is completed at

$$\sum_{j \in J} p_j x_{ij}.$$

- ▶ The makespan w is the maximum completion time among all machines. We have

$$w \geq \sum_{j \in J} p_j x_{ij} \quad \forall i \in I.$$

Minimizing makespan on parallel machines

- ▶ The complete formulation is

$$\begin{aligned} \min \quad & w \\ \text{s.t.} \quad & w \geq \sum_{j \in J} p_j x_{ij} \quad \forall i \in I \\ & \sum_{i \in I} x_{ij} = 1 \quad \forall j \in J \\ & x_{ij} \in \{0, 1\} \quad \forall i \in I, j \in J. \end{aligned}$$

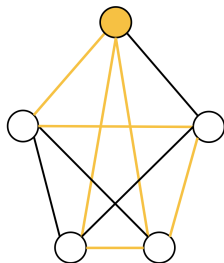
- ▶ How may we ensure that w is indeed the makespan?

Road map

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- ▶ **Vehicle routing problems.**

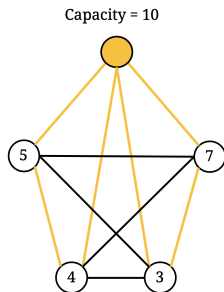
Vehicle routing problems

- ▶ In many cases, we need to deliver/collect items to/from customers in the most efficient way.
- ▶ E.g., consider a post officer who needs to deliver to four addresses.
- ▶ The shortest path between any pair of two addresses can be obtained.
- ▶ This is a **routing** problem: To choose a route starting from the office, passing each address exactly once, and then returning to the office.
- ▶ This is a sequencing problem; in total there are $4! = 24$ feasible routes.
- ▶ Which route minimizes the total distance (or travel time)?



Vehicle routing problems

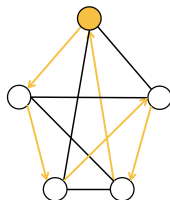
- ▶ The problem described above is the famous **traveling salesperson problem**.
 - ▶ It assumes that the truck has ample capacity.
- ▶ Consider the truck towing bicycles in NTU. It must start at the car pound, pass several locations in NTU, and then return to the origin.
 - ▶ However, the truck capacity is quite limited (because too many people violate the parking regulation).
 - ▶ The driver needs to find **multiple** routes to cover all the locations.
- ▶ The traveling salesperson problem (TSP) is a special case of **vehicle routing problems**.



Traveling salesperson problem

- ▶ How to formulate the TSP into an integer program?
- ▶ Let's consider a directed complete network $G = (V, E)$.
 - ▶ There are n nodes and $n(n-1)$ arcs.
 - ▶ The arc weight for arc (i, j) is $d_{ij} > 0$.
- ▶ We select a few arcs in E to form a **tour**.
 - ▶ To form a tour, we need to select n arcs.
 - ▶ These n arcs should form a cycle passing all nodes.
- ▶ Let $x_{ij} = 1$ if arc $(i, j) \in E$ is selected or 0 otherwise.
 - ▶ The objective:

$$\min \sum_{(i,j) \in E} d_{ij} x_{ij}.$$



- ▶ How to ensure the routing requirement?
- ▶ Is $\sum_{(i,j) \in E} d_{ij} x_{ij} = n$ enough?

Traveling salesperson problem

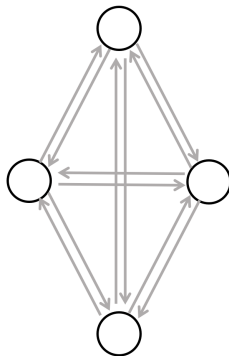
- ▶ For node $k \in V$:
 - ▶ We must select exactly one incoming arc:

$$\sum_{i \in V, i \neq k} x_{ik} = 1.$$

- ▶ We must select exactly one outgoing arc:

$$\sum_{j \in V, j \neq k} x_{kj} = 1.$$

- ▶ Now each node is on a cycle.
- ▶ However, these are not enough to prevent **subtours**.

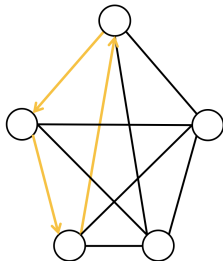


Eliminating subtours: alternative 1

- ▶ There are at least two ways to eliminate subtours.
- ▶ For each **subset of nodes** with at least two nodes, we limit the maximum number of arcs selected:

$$\sum_{i \in S, j \in S, i \neq j} x_{ij} \leq |S| - 1 \quad \forall S \subsetneq V, |S| \geq 2.$$

- ▶ When we have n nodes, we have $2^n - n - 2$ constraints.
 - ▶ 2^n ways to choose a subset.
 - ▶ n ways to choose a subset of one node.
 - ▶ 2 ways to choose a subset of zero node or n nodes.



Eliminating subtours: alternative 2

- ▶ Let u_i s represent the order of passing nodes. More precisely, $u_i = k$ if node i is the k th node to be passed in a tour.
- ▶ We add the following constraints:

$$u_1 = 1$$

$$2 \leq u_i \leq n$$

$$\forall i \in V \setminus \{1\}$$

$$u_i - u_j + 1 \leq (n - 1)(1 - x_{ij}) \quad \forall (i, j) \in E, i \neq 1, j \neq 1.$$

- ▶ If $x_{ij} = 0$, there is no constraint for u_i and u_j ; otherwise, u_j must be larger than u_i by at least 1.
- ▶ If a tour does not contain node 1, the last constraint pushes those u_i s to infinity and violates constraint 2.
- ▶ Note that only node 1 is not restricted by these constraints!
- ▶ When we have n nodes, we have n additional variables and $2n - 1 + (n - 1)(n - 2)$ constraints.

Complete formulation

- ▶ The complete formulation is

$$\begin{aligned} \min \quad & \sum_{(i,j) \in E} d_{ij} x_{ij} \\ \text{s.t.} \quad & \sum_{i \in V, i \neq k} x_{ik} = 1 \quad \forall k \in V \\ & \sum_{j \in V, j \neq k} x_{kj} = 1 \quad \forall k \in V \\ & x_{ij} \in \{0, 1\} \quad \forall (i, j) \in E. \end{aligned}$$

with either alternative 1 or alternative 2.

- ▶ Which alternative is better?