# **Short Notes**

SP015 Physics 1 2025/26, SR

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# 1 Tips for Solving Physics Problems

- 1. Understand the Problem: Carefully read the problem. Identify what is given and what is required.
- 2. **Draw a Diagram:** Visualize the problem with a sketch or free-body diagram. Label all known and unknown quantities.
- 3. List Known and Unknown Quantities: Write down all given values and the quantity you are solving for.
- 4. Choose the Right Equations: Identify the physical principles involved (e.g., Newton's laws, conservation laws, kinematic equations).
- 5. Check Units: Ensure all quantities are in the correct SI units before performing calculations.
- 6. Solve Symbolically First: If possible, manipulate equations symbolically before substituting numbers.
- 7. **Substitute and Calculate:** Plug in known values and compute the result. Use appropriate significant figures.
- 8. Check Your Answer: Consider whether your answer makes sense physically. Check units and magnitude.
- 9. **Practice Regularly:** Consistent practice improves speed, confidence, and familiarity with problem types.
- 10. Stay Calm and Organized: Keep your work neat to avoid confusion and reduce mistakes.

# 2 Dimensional Analysis and Vectors

# **Dimensions of Physical Quantities**

- **Dimension:** Represents the nature of a physical quantity with respect to basic physical quantities (e.g., mass [M], length [L], time [T]).
- Example: Velocity has dimension  $[LT^{-1}]$

## **Derived Quantities**

- Derived quantities are expressed in terms of base quantities.
- Example: Force  $F = ma \Rightarrow [F] = [M][LT^{-2}] = [MLT^{-2}]$

# **Dimensional Homogeneity**

## Concept

**Dimensional Homogeneity:** An equation is dimensionally correct if all terms have the same dimensions.

#### Try It Yourself

**Example:** Check if  $s = ut + \frac{1}{2}at^2$  is dimensionally correct.

$$[u] = [LT^{-1}], \quad [t] = [T], \quad [a] = [LT^{-2}] \Rightarrow [s] = [L]$$

All terms yield [L]; thus, the equation is dimensionally homogeneous.

#### Scalars and Vectors

- Scalar: Has only magnitude (e.g., mass, speed, energy).
- **Vector:** Has both magnitude and direction (e.g., velocity, force).

## Vector Components

### Concept

**Resolving Vectors:** Any vector  $\vec{A}$  can be resolved into x and y components.

$$A_x = A\cos\theta, \quad A_y = A\sin\theta$$

#### Resultant of Vectors

- Resultant vector is the vector sum of all vectors.
- Use vector addition (head-to-tail or parallelogram method).
- For 2D vectors:

$$R = \sqrt{(\sum A_x)^2 + (\sum A_y)^2}, \quad \tan \theta = \frac{\sum A_y}{\sum A_x}$$

#### Try It Yourself

**Example:** Find the resultant of three vectors:  $\vec{A} = 5 \text{ N}$  east,  $\vec{B} = 3 \text{ N}$  north, and  $\vec{C} = 4 \text{ N}$  west.

• Resolve into components:

$$A_x = +5, \ B_y = +3, \ C_x = -4$$

• 
$$\sum A_x = 5 - 4 = 1, \sum A_y = 3$$

• 
$$R = \sqrt{1^2 + 3^2} = \sqrt{10} \approx 3.16 \,\mathrm{N}$$

• 
$$\theta = \tan^{-1}(3/1) = 71.6^{\circ}$$
 north of east

# 3 Kinematics

# Describing Motion in One Dimension

# Concept

**Displacement vs Distance:** Displacement is the change in position (can be negative), while distance is the total length traveled (always positive).

$$\Delta x = x_f - x_i$$

#### Concept

Velocity: Velocity is the rate of change of position. It has both magnitude and direction.

Average Velocity:

$$v_{\rm avg} = \frac{\Delta x}{\Delta t}$$

Instantaneous Velocity:

$$v = \frac{\mathrm{d}x}{\mathrm{d}t}$$

Uniform Velocity: The object moves equal distances in equal time intervals. Acceleration is zero.

## Concept

**Acceleration:** The rate at which velocity changes with time.

**Average Acceleration:** 

$$a_{\rm avg} = \frac{\Delta v}{\Delta t}$$

**Instantaneous Acceleration:** 

$$a = \frac{\mathrm{d}v}{\mathrm{d}t}$$

# Motion Graphs and Interpretation

- Displacement-Time Graph: Slope = velocity.
- Velocity-Time Graph: Slope = acceleration; Area = displacement.
- Acceleration-Time Graph: Area = change in velocity.

# Equations of Motion for Constant Acceleration

#### Concept

Use these equations when acceleration is constant:

- (1)  $v = v_0 + at$
- (2)  $x = x_0 + v_0 t + \frac{1}{2} a t^2$
- (3)  $v^2 = v_0^2 + 2a(x x_0)$
- (4)  $x = x_0 + \frac{1}{2}(v_0 + v)t$

# **Projectile Motion**

### Concept

Projectile motion is 2D motion under the influence of gravity. Horizontal and vertical motions are independent.

### Horizontal Launch

- Horizontal velocity is constant.
- Vertical motion is free fall.

Horizontal: 
$$x = v_0 t$$
 Vertical:  $y = \frac{1}{2}gt^2$ 

## Launch at an Angle

$$v_{0x} = v_0 \cos \theta$$
 and  $v_{0y} = v_0 \sin \theta$ 

Horizontal: 
$$x = v_{0x}t$$
 Vertical:  $y = v_{0y}t - \frac{1}{2}gt^2$ 

**Key Formulas:** 

$$h_{\text{max}} = \frac{v_{0y}^2}{2g}, \quad t = \frac{2v_{0y}}{g}, \quad R = \frac{v_0^2 \sin(2\theta)}{g}$$

#### Try It Yourself

**Example:** A ball is launched at 25 m/s at 40°. Find its range.

$$v_{0x} = 25\cos(40^\circ), \quad v_{0y} = 25\sin(40^\circ)$$
  
 $t = \frac{2v_{0y}}{g}, \quad R = v_{0x}t$ 

### Watch Out!

Don't mix horizontal and vertical equations. Treat them separately!

# 4 Momentum and Newton's Laws of Motion

#### Concept

Momentum: Momentum is the product of an object's mass and its velocity. It is a vector quantity.

$$\vec{p} = m\vec{v}$$

#### Concept

**Impulse:** Impulse is the product of force and the time interval over which it acts. It equals the change in momentum.

$$\vec{J} = \vec{F}\Delta t = \Delta \vec{p}$$

# Impulse-Momentum Theorem

$$\vec{F}\Delta t = m\vec{v}_f - m\vec{v}_i$$

#### Try It Yourself

**Example:** A 2 kg ball initially moving at 3 m/s comes to rest in 0.5 s. What is the impulse?

$$J = \Delta p = m(v_f - v_i) = 2(0 - 3) = -6 \,\mathrm{N} \cdot \mathrm{s}$$

## Impulse from Force-Time Graphs

• The area under a force-time graph equals the impulse.

# Conservation of Momentum

#### Concept

**Principle:** If no external forces act on a system, the total momentum of the system remains constant.

$$\vec{p}_{\text{total, before}} = \vec{p}_{\text{total, after}}$$

#### Collisions

- Elastic Collision: Both momentum and kinetic energy are conserved.
- Inelastic Collision: Momentum is conserved, but kinetic energy is not.
- Perfectly Inelastic: Objects stick together after the collision.

#### 2D Collisions

Apply conservation of momentum independently in the x and y directions:

$$m_1 v_{1x} + m_2 v_{2x} = m_1 v'_{1x} + m_2 v'_{2x}$$

$$m_1 v_{1y} + m_2 v_{2y} = m_1 v'_{1y} + m_2 v'_{2y}$$

#### Try It Yourself

**Try This:** Two carts collide on a frictionless surface. Use momentum conservation to find final velocities.

## Forces and Newton's Laws

## **Common Forces**

- Weight (W): W = mg
- Normal Force (N): Perpendicular support force from a surface.
- Tension (T): Force transmitted by a string or rope.
- Friction (f): Opposes motion; depends on normal force.
- External Force (F): Any additional applied force.

## Free Body Diagrams (FBD)

- Draw all forces acting on an object.
- Represent forces as arrows pointing in the direction of action.

### Static and Kinetic Friction

$$f_s \le \mu_s N$$
 (Static)

$$f_k = \mu_k N$$
 (Kinetic)

#### Watch Out!

Static friction adjusts up to its maximum value to prevent motion. Kinetic friction is constant once the object is moving.

# Newton's Laws of Motion

- 1. **First Law (Inertia):** An object remains at rest or in uniform motion unless acted upon by a net external force.
- 2. Second Law:  $\sum \vec{F} = m\vec{a}$
- 3. Third Law: For every action, there is an equal and opposite reaction.

# Applying Newton's Laws

- Identify all forces.
- Draw the FBD.
- Apply  $\sum \vec{F} = m\vec{a}$  in each direction.

### Try It Yourself

**Example:** A box on a rough surface is pulled with a rope at an angle. Find the acceleration.

# 5 Work, Energy, and Power

### Concept

Work and the Scalar Product: Work is the scalar product (dot product) of force and displacement vectors. It measures the energy transferred by a force acting over a distance.

$$W = \vec{F} \cdot \vec{d} = Fd \cos \theta$$

**Physical Meaning:** Only the component of force in the direction of displacement does work. If  $\theta = 90^{\circ}$ ,  $\cos \theta = 0$  and no work is done.

# Work by a Constant Force

- Force must be constant in magnitude and direction.
- Displacement must be in a straight line.

#### Try It Yourself

**Example:** A  $10\,\mathrm{N}$  force acts at an angle of  $30^\circ$  to the direction of motion over  $5\,\mathrm{m}$ . Find the work done.

$$W = Fd\cos\theta = 10 \times 5 \times \cos(30^\circ) = 43.3 \,\mathrm{J}$$

# Force-Displacement Graphs

- The area under the graph equals the work done.
- For variable force, break into segments or integrate if needed.

# Forms of Mechanical Energy

#### Concept

Kinetic Energy: Energy due to motion.

$$KE = \frac{1}{2}mv^2$$

#### Concept

Gravitational Potential Energy: Energy due to position in a gravitational field.

$$PE_g = mgh$$

#### Concept

Elastic Potential Energy: Stored energy in a stretched or compressed spring.

$$PE_s = \frac{1}{2}kx^2$$

# Conservation of Mechanical Energy

### Concept

In the absence of non-conservative forces (like friction), the total mechanical energy remains constant:

$$E_{\text{mechanical}} = KE + PE = \text{constant}$$

#### Try It Yourself

Example: A ball is dropped from a height of 10 m. Find its speed just before hitting the ground.

$$mgh = \frac{1}{2}mv^2 \Rightarrow v = \sqrt{2gh}$$
$$v = \sqrt{2 \times 9.8 \times 10} = 14.0 \,\text{m/s}$$

# Work-Energy Theorem

# Concept

Work done by the net force on an object equals its change in kinetic energy.

$$W_{\text{net}} = \Delta KE = \frac{1}{2}mv^2 - \frac{1}{2}mv_0^2$$

# Power

# Concept

Average Power: Rate at which work is done over time.

$$P_{\rm avg} = \frac{W}{t}$$

### Concept

Instantaneous Power: The dot product of force and velocity at a given instant.

$$P = \vec{F} \cdot \vec{v} = Fv \cos \theta$$

#### Try It Yourself

Example: A car engine does 10 000 J of work in 5 s. What is its average power?

$$P = \frac{10000}{5} = 2000 \,\mathrm{W}$$

# 6 Uniform Circular Motion and Centripetal Force

# **Angular Quantities**

#### Concept

**Angular Displacement** ( $\theta$ ): The angle through which an object moves on a circular path, measured in radians.

•  $\theta = \frac{s}{r}$  where s is arc length and r is radius.

## Concept

**Period** (T): Time taken for one complete revolution.

#### Concept

Frequency (f): Number of revolutions per second.

$$f = \frac{1}{T}$$

### Concept

Angular Velocity ( $\omega$ ): Rate of change of angular displacement.

$$\omega = \frac{\theta}{t} = 2\pi f = \frac{2\pi}{T}$$

### **Unit Conversions**

- $360^{\circ} = 2\pi \text{ radians}$
- 1 revolution =  $2\pi$  radians
- Use: degrees  $\times \frac{\pi}{180}$  = radians

#### **Uniform Circular Motion**

- Object moves in a circle at constant speed.
- Direction of velocity changes, so object is accelerating.

### Concept

Centripetal Acceleration ( $a_c$ ): Acceleration directed toward the center of the circle.

$$a_c = \frac{v^2}{r} = \omega^2 r$$

## Concept

Centripetal Force  $(F_c)$ : Net force causing centripetal acceleration.

$$F_c = ma_c = m\frac{v^2}{r} = m\omega^2 r$$

#### Try It Yourself

**Example:** A 1.0 kg object moves in a circle of radius 2.0 m at 3.0 m/s. Find the centripetal force.

$$F_c = \frac{(1)(3)^2}{2} = 4.5 \,\mathrm{N}$$

# Special Cases of Uniform Circular Motion

- 1. Horizontal Circle (e.g., mass on a string on a frictionless table)
  - Tension provides centripetal force.
  - $T = \frac{mv^2}{r}$
- 2. Vertical Circle (e.g., a pendulum or roller coaster loop)
  - Tension and weight both affect net force.
  - At top:  $T + mg = \frac{mv^2}{r}$
  - At bottom:  $T mg = \frac{mv^2}{r}$
- 3. Conical Pendulum (e.g., mass on a string moving in horizontal circle)
  - Tension has vertical (balances mg) and horizontal (provides  $F_c$ ) components.
  - Use trigonometry:  $T\cos\theta = mg$ ,  $T\sin\theta = \frac{mv^2}{r}$

#### Try It Yourself

**Example:** A  $0.5 \,\mathrm{kg}$  mass moves in a horizontal circle of radius  $1.0 \,\mathrm{m}$  at  $2.0 \,\mathrm{m/s}$ . Find the tension in the string if the angle is  $30^{\circ}$ .

$$F_c = \frac{mv^2}{r} = \frac{0.5 \times 4}{1} = 2.0 \,\mathrm{N}$$

$$T = \frac{F_c}{\sin \theta} = \frac{2.0}{\sin(30^\circ)} = 4.0 \,\text{N}$$

# 7 Simple Harmonic Motion (SHM)

### What is SHM?

#### Concept

**Simple Harmonic Motion (SHM):** A type of periodic motion where the restoring force is directly proportional to displacement and directed toward the equilibrium position.

$$F = -kx$$

- SHM is characterized by sinusoidal functions.
- Occurs in systems like springs and pendulums.

## Displacement in SHM

$$x(t) = A\sin(\omega t + \phi)$$

- $\bullet$  A: Amplitude
- $\omega$ : Angular frequency  $\left(\omega = \sqrt{\frac{k}{m}}\right)$
- $\phi$ : Phase constant

## Velocity in SHM

• As a function of time:

$$v(t) = \frac{dx}{dt} = A\omega\cos(\omega t + \phi)$$

• As a function of displacement:

$$v(x) = \omega \sqrt{A^2 - x^2}$$

### Acceleration in SHM

• As a function of time:

$$a(t) = -A\omega^2 \sin(\omega t + \phi)$$

• As a function of displacement:

$$a(x) = -\omega^2 x$$

# Energy in SHM

• Kinetic Energy:

$$KE = \frac{1}{2}mv^2 = \frac{1}{2}m\omega^2(A^2 - x^2)$$

• Potential Energy:

$$PE = \frac{1}{2}kx^2 = \frac{1}{2}m\omega^2x^2$$

• Total Mechanical Energy:

$$E = KE + PE = \frac{1}{2}kA^2 = \text{constant}$$

• Total energy depends on the square of the amplitude.

# Graphs in SHM

- Displacement-time: sine or cosine wave
- Velocity-time: cosine or sine wave (shifted)
- Acceleration-time: inverted sine wave
- Energy-displacement:
  - KE is maximum at x = 0, zero at  $x = \pm A$
  - PE is zero at x = 0, maximum at  $x = \pm A$
  - Total energy remains constant

## Period of SHM

• Mass-spring system:

$$T=2\pi\sqrt{\frac{m}{k}}$$

• Simple pendulum:

$$T = 2\pi \sqrt{\frac{L}{g}}$$

#### Try It Yourself

**Example:** A 0.2 kg mass is attached to a spring with  $k = 50 \,\mathrm{N/m}$ . Find the period of oscillation.

$$T = 2\pi \sqrt{\frac{0.2}{50}} = 2\pi \sqrt{0.004} \approx 0.4 \,\mathrm{s}$$

# 8 Waves and Sound

#### Wave Characteristics

### Concept

Wavelength ( $\lambda$ ): The distance between two consecutive points that are in phase (e.g., crest to crest or trough to trough).

#### Concept

**Wavenumber** (k): The number of wave cycles per unit distance.

$$k = \frac{2\pi}{\lambda}$$

# Progressive Waves

A progressive (traveling) wave moves energy through a medium without transporting matter.

#### Concept

Wave Equation:

$$y(x,t) = A\sin(kx - \omega t + \phi)$$

# Wave vs Particle Velocity

• Particle Vibrational Velocity: Speed of oscillation of particles in the medium.

$$v_p(t) = \frac{\partial y}{\partial t} = A\omega\cos(kx - \omega t + \phi)$$

• Wave Propagation Velocity: Speed at which the wave form travels.

$$v = f\lambda = \frac{\omega}{k}$$

## Displacement-Time and Displacement-Distance Graphs

- **Displacement-Time:** Fixed location, plots y vs t (shows oscillation).
- Displacement-Distance: Fixed time, plots y vs x (shows wave shape).

# Wave Interference and Superposition

#### Concept

**Principle of Superposition:** When two or more waves overlap, the resultant displacement is the vector sum of the individual displacements.

- Constructive Interference: Waves in phase increase amplitude.
- Destructive Interference: Waves out of phase cancel each other.

# **Standing Waves**

#### Concept

## Standing Wave Equation:

$$y(x,t) = 2A\sin(kx)\cos(\omega t)$$

- Formed by the superposition of two identical waves traveling in opposite directions.
- Nodes: points of no motion.
- Antinodes: points of maximum motion.

# Progressive vs Standing Waves

- Progressive: Energy travels, all particles oscillate with same amplitude.
- Standing: Energy trapped, particles oscillate with varying amplitude.

# Resonance in Strings and Air Columns

1. Stretched String (both ends fixed)

$$f_n = \frac{n}{2L}v, \quad n = 1, 2, 3, \dots$$

2. Open-Ended Air Column (both ends open)

$$f_n = \frac{n}{2L}v, \quad n = 1, 2, 3, \dots$$

3. Closed-Ended Air Column (one end closed)

$$f_n = \frac{n}{4L}v, \quad n = 1, 3, 5, \dots$$

# Doppler Effect

### Concept

**Doppler Effect:** Apparent change in frequency due to relative motion between source and observer.

1. Moving Source, Stationary Observer

$$f' = \frac{f}{1 \pm \frac{v_s}{v}}$$

- $\bullet$  Use when source moves toward observer
- Use + when source moves away

# 2. Moving Observer, Stationary Source

$$f' = f\left(1 \pm \frac{v_o}{v}\right)$$

- ullet Use + when observer moves toward source
- $\bullet$  Use when observer moves away

#### Try It Yourself

**Example:** A  $500\,\mathrm{Hz}$  sound source moves toward a stationary observer at  $30\,\mathrm{m/s}$ . Speed of sound is  $340\,\mathrm{m/s}$ . Find the observed frequency.

$$f' = \frac{500}{1 - \frac{30}{340}} = \frac{500}{0.9118} \approx 548.2 \,\mathrm{Hz}$$

# 9 Young's Modulus, Heat Transfer and Heat Expansion

#### Stress and Strain

### Concept

Stress ( $\sigma$ ): Force applied per unit cross-sectional area.

$$\sigma = \frac{F}{A}$$

### Concept

Strain ( $\varepsilon$ ): Relative change in length.

$$\varepsilon = \frac{\Delta L}{L_0}$$

- Tensile stress/strain: Pulling force.
- Compressive stress/strain: Pushing force.

# Stress-Strain Graph

- Proportional limit: Hooke's law obeyed.
- Elastic region: Material returns to original shape.
- Yield point: Permanent deformation begins.
- Plastic region: Irreversible deformation.
- Ultimate tensile strength: Maximum stress before breaking.

#### Elastic and Plastic Deformation

- Elastic: Material returns to original shape (reversible).
- Plastic: Permanent deformation occurs (irreversible).

# Force-Elongation Graphs

- Brittle material: Sharp break with little elongation.
- Ductile material: Significant elongation before fracture.

# Young's Modulus

# Concept

Young's Modulus (E): Ratio of stress to strain within elastic limit.

$$E = \frac{\sigma}{\varepsilon} = \frac{FL_0}{A\Delta L}$$

# Strain Energy

• From Force-Elongation Graph:

$$U = \frac{1}{2} F \Delta L$$

• Strain Energy per Unit Volume:

$$u = \frac{1}{2}\sigma\varepsilon$$

### **Heat Conduction**

#### Concept

Heat conduction: Transfer of heat through a material without movement of the material.

#### Concept

Rate of heat transfer:

$$Q = \frac{kA(\Delta T)}{L}$$

Where k is thermal conductivity, A is cross-sectional area,  $\Delta T$  is temperature difference, and L is thickness.

• For two rods in series:

$$Q = \frac{\Delta T}{\left(\frac{L_1}{k_1 A} + \frac{L_2}{k_2 A}\right)}$$

### Temperature-Distance Graph Analysis

- Insulated rod: Linear temperature gradient.
- Non-insulated: May show heat loss; gradient not linear.

#### Thermal Expansion

• Linear expansion:

$$\Delta L = \alpha L_0 \Delta T$$

• Area expansion:

$$\Delta A = 2\alpha A_0 \Delta T$$

• Volume expansion:

$$\Delta V = 3\alpha V_0 \Delta T$$

• Expansion of liquid in container: Effective expansion is liquid minus container expansion.

#### Try It Yourself

**Example:** An aluminum rod ( $\alpha = 23 \times 10^{-6}/^{\circ}C$ ) of length 1.0 m is heated from 20 °C to 100 °C. Find the change in length.

$$\Delta L = 23 \times 10^{-6} \times 1.0 \times (100 - 20) = 1.84 \times 10^{-3} \,\mathrm{m} = 1.84 \,\mathrm{mm}$$

# 10 Kinetic Theory and Thermodynamics

# Kinetic Theory of Gases

- Gas consists of large number of small particles in random motion.
- Collisions between particles and container walls are elastic.
- Volume of gas particles is negligible compared to container volume.
- No intermolecular forces except during collisions.
- Time of collision is negligible.

# Root Mean Square (RMS) Speed

#### Concept

RMS speed: The square root of the average of the squares of molecular speeds.

$$v_{\rm rms} = \sqrt{\frac{3kT}{m}} = \sqrt{\frac{3RT}{M}}$$

Where k is Boltzmann constant, R is gas constant, T is temperature, m is mass of one molecule, and M is molar mass.

# Ideal Gas Equation and RMS Speed

• Using ideal gas law PV = nRT:

$$v_{\rm rms} = \sqrt{\frac{3P}{\rho}}$$

Where  $\rho$  is the density of the gas.

## Translational Kinetic Energy

#### Concept

Average translational kinetic energy per molecule:

$$K_{\text{avg}} = \frac{3}{2}kT$$

# Degrees of Freedom

- Degree of freedom: Independent mode of motion.
- Monoatomic: 3 translational (3 DoF)
- Diatomic: 3 translational + 2 rotational = 5 DoF (at room temperature)
- Polyatomic: 3 translational + 3 rotational = 6 DoF

## **Equipartition of Energy**

• Each degree of freedom contributes  $\frac{1}{2}kT$  to average energy per molecule.

# Internal Energy of an Ideal Gas

#### Concept

Total internal energy for n moles:

$$U = \frac{f}{2}nRT$$

Where f is the number of degrees of freedom.

# First Law of Thermodynamics

#### Concept

Statement:

$$\Delta U = Q - W$$

Where  $\Delta U$  is change in internal energy, Q is heat added to system, and W is work done by system.

## Thermodynamic Processes

• Isothermal:  $T = \text{const}, \Delta U = 0$ 

• Isochoric: V = const, W = 0

• Isobaric: P = const

• Adiabatic: Q = 0

# Pressure-Volume Graphs

• Area under P-V curve = Work done by gas

#### Work Done in Processes

• Isothermal:

$$W = nRT \ln \left(\frac{V_f}{V_i}\right)$$

• Isochoric:

$$W = 0$$

• Isobaric:

$$W = P(V_f - V_i)$$

#### Try It Yourself

**Example:** One mole of ideal gas expands isothermally from 1.0 L to 2.0 L at 300 K. Find the work done.

$$W = (8.314)(300) \ln \left(\frac{2.0}{1.0}\right) = 1729.3 \,\mathrm{J}$$