

MATRICULATION DIVISION

PHYSICS

LABORATORY MANUAL SP015 & SP025

TWELFTH EDITION

MATRICULATION DIVISION MINISTRY OF EDUCATION MALAYSIA

PHYSICS LABORATORY MANUAL SEMESTER I & II SP015 & SP025

MINISTRY OF EDUCATION MALAYSIA MATRICULATION PROGRAMME

TWELFTH EDITION

First Printing, 2003
Second Printing, 2004
Third Printing, 2005 (Sixth Edition)
Fourth Printing, 2006 (Seventh Edition)
Fifth Printing, 2007 (Eighth Edition)
Sixth Printing, 2011 (Ninth Edition)
Seventh Printing, 2013 (Tenth Edition)
Eighth Printing, 2018 (Eleventh Edition)
Ninth Printing, 2020 (Twelfth Edition)
Copyright © 2020 Matriculation Division
Ministry of Education Malaysia

ALL RIGHTS RESERVED. No part of this publication may be reproduced or transmitted in any form or by any means, electronic or mechanical, including photocopying, recording or any information storage and retrieval system, without the prior written permission from the Director of Matriculation Division, Ministry of Education Malaysia.

Published in Malaysia by

Matriculation Division
Ministry of Education Malaysia,
Level 6 – 7, Block E15,
Government Complex Parcel E,
Federal Government Administrative Centre,
62604 Putrajaya,
MALAYSIA.

Tel: 603-88844083 Fax: 603-88844028

Website: http://www.moe.gov.my/v/BM

Malaysia National Library Physics Laboratory Manual Semester I & II SP015 & SP025 Twelfth Edition

eISBN 978-983-2604-51-8

NATIONAL EDUCATION PHILOSOPHY

Education in Malaysia is an on-going effort towards further developing the potential of individuals in a holistic and integrated manner, so as to produce individuals who are intellectually, spiritually and physically balanced and harmonious based on a firm belief in and devotion to God. Such an effort is designed to produce Malaysian citizens who are knowledgeable and competent, who possess high moral standards and who are responsible and capable of achieving a high level of personal well-being as well as being able to contribute to the betterment of the family, society and the nation at large.

NATIONAL SCIENCE EDUCATION PHILOSOPHY

In consonance with the National Education Philosophy, science education in Malaysia nurtures a science and technology culture by focusing on the development of individuals who are competitive, dynamic, robust and resilient and able to master scientific knowledge and technological competency.

FOREWORD

I am delighted to write the foreword for the Laboratory Manual, which aimed to equip students with knowledge, skills, and the ability to be competitive undergraduates.

This Laboratory Manual is written in such a way to emphasise students' practical skills and their ability to read and understand instructions, making assumptions, apply learnt skills and react effectively in a safe environment. Science process skills such as making accurate observations, taking measurement in correct manner, using appropriate measuring apparatus, inferring, hypothesizing, predicting, interpreting data, and controlling variables are further developed during practical session. The processes are incorporated to help students to enhance their Higher Order Thinking Skills such as analytical, critical and creative thinking skills. These skills are crucial to prepare students to face upcoming challenges in the 21st century era.

The manipulative skills such as handling the instruments, setting up the apparatus correctly and drawing the diagrams can be advanced through practical session. The laboratory experiments are designed to encourage students to have enquiry mind. It requires students to participate actively in the science process skills before, during and after the experiment by preparing the pre-report, making observations, analysing the results and in the science process skills before, during, after the experiment by preparing the pre-report, making observations, analysing the results and drawing conclusions.

It is my hope and expectation that this manual will provide an effective learning experience and referenced resource for all students to equip themselves with the skills needed to fulfil the prerequisite requirements in the first-year undergraduate studies.

Dr. HAJAH ROSNARIZAH BINTI ABDUL HALIM

Director

Matriculation Division

CONTENTS

		Page
1.0 Learnin	ng Outcomes	v
2.0 Guidan	ice for Students	vii
3.0 Signific	cant Figures	ix
4.0 Uncerta	ainty in Measurement	xi
	Semester I	
Experiment	Title	
1	Measurement and Uncertainty	1
2	Free Fall and Projectile Motion	4
3	Energy	10
4	Rotational Motion of A Rigid Body	17
5	Simple Harmonic Motion (SHM)	21
6	Standing Waves	24
	Semester II	
Experiment	Title	Page
1	Capacitor	27
2	Ohm's Law	31
3	Potentiometer	34
4	Magnetic Field	37
5	Geometrical Optics	45
6	Diffraction	48
References		51
Acknowledgen	nents	52

1.0 Learning Outcomes

1.1 Matriculation Science Programme Educational Objectives

Upon a year of graduation from the programme, graduates are:

- i. Knowledgeable and technically competent in science disciplines in-line with higher educational institution requirement.
- ii. Able to communicate competently and collaborate effectively in group work to compete in higher education environment.
- iii. Able to solve scientific and mathematical problems innovatively and creatively.
- iv. Able to engage in life-long learning with strong commitment to continue the acquisition of new knowledge and skills.

1.2 Matriculation Science Programme Learning Outcomes

At the end of the programme, students should be able to:

 Acquire knowledge of science and mathematics fundamental in higher level education.
 (PEO 1, MOF LOD 1)

2. Demonstrate manipulative skills in laboratory work. (PEO 1, MQF LOD 2)

3. Communicate competently and collaborate effectively in group work with skills needed for admission in higher education institutions.

(PEO 2, MQF LOD 5)

 Apply logical, analytical and critical thinking in scientific studies and problem solving. (PEO 3, MQF LOD 6)

5. Independently seek and share information related to science and mathematics.

(PEO 4, MQF LOD 7)

1.3 Physics 1 Course Learning Outcome

At the end of the course, student should be able to:

- Describe basic concepts of Physics of motion, force and energy, waves, matter and thermodynamics. (C2, PLO 1, MQF LOD 1)
- 2. Demonstrate manipulative skills during experiments in measurement and uncertainty, free fall and projectile motion, friction, energy, rotational motion of rigid body and standing waves in laboratory.

 (P3, PLO 2, MQF LOD 2)
- 3. Solve problems related to Physics of motion, force and energy, waves, matter and thermodynamics. (C4, PLO 4, CTPS 3, MQF LOD 6)

1.4 Physics 2 Course Learning Outcome

At the end of the course, student should be able to:

- Explain basic concepts of electric current, electronics, magnetism, optics, quantization of light, wave properties of particles and nuclear physics.
 (C2, PLO 1, MOF LOD 1)
- 2. Demonstrate manipulative skills during experiments in capacitor, electric current and direct current circuits, magnetic field, geometrical optics and physical optics.
 - (P3, PLO 2, MQF LOD 2)

 Solve machines of electric exament, electronics in
- Solve problems of electric current, electronics, magnetism, optics, quantization of light, wave properties of particles and nuclear physics.
 (C4, PLO 4, CTPS 3, MQF LOD 6)

1.5 Physics Practical Learning Outcomes

Physics experiment is to give the students a better understanding of the concepts of physics through experiments. The **aims** of the experiments in this course are to be able to:

1. introduce students to laboratory work and to equip them with the practical skills needed to carry out experiment in the laboratory.

- 2. determine the best range of readings using appropriate measuring devices.
- 3. recognise the importance of single and repeated readings in measurement.
- 4. analyse and interpret experimental data in order to deduce conclusions for the experiments.
- 5. make conclusions in line with the objective(s) of the experiment which rightfully represents the experimental results.
- 6. verifying the correct relationships between the physical quantities in the experiments.
- 7. identify the limitations and accuracy of observations and measurements.
- 8. familiarise student with standard experimental techniques.
- 9. choose suitable apparatus and to use it correctly and carefully.
- 10. gain scientific trainings in observing, measuring, recording and analysing data as well as to determine the uncertainties (errors) of various physical quantities observed in the experiments.
- 11. handle apparatus, measuring instruments and materials safely and efficiently.
- 12. present a good scientific report for the experiment.
- 13. follow instructions and procedures given in the laboratory manual.
- 14. gain confidence in performing experiments.

2.0 Guidance for Students

2.1 Ethics in the laboratory

- a. Follow the laboratory rules.
- b. Students must be punctual for the practical session. Students are not allowed to leave the laboratory before the practical session ends without permission.

- c. Co-operation between members of the group must be encouraged so that each member can gain experience in handling the apparatus and take part in the discussions about the results of the experiments.
- d. Record the data based on the observations and not based on any assumptions. If the results obtained are different from the theoretical value, state the possible reasons.
- e. Get help from the lecturer or the laboratory assistant should any problems arise during the practical session.

2.2 Preparation for experiment

2.2.1 Planning for the practical

a. Before entering the laboratory

- i) Read and understand the objectives and the theory of the experiment.
- ii) Think and plan the working procedures properly for the whole experiment. Make sure you have appropriate table for the data.
- iii) Prepare a jotter book for the data and observations of the experiments during pre-lab discussion.

b. Inside the laboratory

- i) Check the apparatus provided and note down the important information about the apparatus.
- ii) Arrange the apparatus accordingly.
- iii) Conduct the experiment carefully.
- iv) Record all measurements and observations made during the experiment.

2.3 Report writing

The report must be written properly and clearly in English and explain what has been carried out in the experiment. Each report must contain name, matriculation number, number of experiment, title, date and practicum group.

The report must also contain the followings:

i) Objective • state clearly

ii) Theory • write concisely in your own words

• draw and label diagram if necessary

iii) Apparatus • name, range, and sensitivity, e.g

Voltmeter: 0.0 - 10.0 VSensitivity: $\pm 0.1 \text{ V}$

iv) Procedure • write in passive sentences about all the

steps taken during the experiment

v) Observation • data tabulation with units and

uncertainties

• data processing (plotting graph, calculation to obtain the results of the

experiments and its uncertainties)

vi) Discussion • give comments about the experimental results by comparing it with the

standard value

• state the source of mistake(s) or error(s) if any as well as any precaution(s) taken

to overcome them

• answer all the questions given

vii) Conclusion • state <u>briefly</u> the results with reference to

the objectives of the experiment

Reminder: NO PLAGIARISM IS ALLOWED.

3.0 Significant Figures

The significant figures of a number are those digits carry meaning contributing to its precision. Therefore, the most basic way to

indicate the precision of a quantity is to write it with the correct number of significant figures.

The significant figures are all the digits that are known accurately plus the one estimated digit. For example, we say the distance between two towns is 200 km, that does not mean we know the distance to be exactly 200 km. Rather, the distance is 200 km to the nearest kilometres. If instead we say that the distance is 200.0 km that would indicate that we know the distance to the nearest tenth of a kilometre.

More significant figures mean greater precision.

Rules for identifying significant figures:

- 1. Nonzero digits are always significant.
- 2. Final or ending zeros written to the right of the decimal point are significant.
- 3. Zeros written on either side of the decimal point for the purpose of spacing the decimal point are not significant.
- 4. Zeros written between significant figures are significant.

Example:

Value	Number of significant figures	Remarks
0.5	1	Implies value between 0.45 and 0.55
0.500	3	Implies value between 0.4995 and 0.5005
0.050	2	Implies value between 0.0495 and 0.0505
5.0	2	Implies value between 4.95 and 5.05
1.52	3	Implies value between 1.515 and 1.525
1.52 × 10 ⁴	3	Implies value between 15150 and 15250

Value	Number of significant figures	Remarks
150	2 or 3 (ambiguous)	The zero may or may not be significant. If the zero is significant, the value implied is between 149.5 and 150.5. If the zero is not significant, the value implied is between 145 and 155.

4.0 Uncertainty in Measurements

No matter how careful or how accurate are the instruments, the results of any measurements made at best are only close enough to their true values (actual values). Obviously, this is because the instruments have certain smallest scale by which measurement can be made. Chances are, the true values lie within the smallest scale. Hence, we have uncertainties in our measurements.

The uncertainty of a measurement depends on its type and how it is done. For a quantity x with uncertainty Δx , the measurement should be recorded as $x \pm \Delta x$ with appropriate unit.

The relative uncertainty of the measurement is defined as $\frac{\Delta x}{x}$.

and therefore its percentage of uncertainty, is given by $\frac{\Delta x}{x} \times 100\%$.

4.1 Single Reading

(a) If the reading is taken from a single point or at the end of the scale we use:

$$\Delta x = \frac{1}{2} \times \text{(smallest division of the scale)}$$

(b) If the readings are taken from two points on the scale:

$$\Delta x = 2 \times \left[\frac{1}{2} \times (\text{smallest division from the scale}) \right]$$

(c) If the apparatus has a vernier scale:

 $\Delta x = 1 \times \text{(smallest unit of the vernier scale)}$

4.2 Repeated Readings

For a set of n repeated measurements, the best value is the average value, that is

$$\bar{x} = \frac{\sum_{i=1}^{n} x_i}{n}$$

where: n is the number of measurements taken x_i is the ith measurement value

The uncertainty is given by

$$\Delta x = \frac{\sum_{i=1}^{n} |\overline{x} - x_i|}{n}$$

The result should be written in the form of

$$x = \overline{x} \pm \Delta x$$

4.3 Straight Line Graphs

Straight line graphs are very useful in data analysis for many physics experiments.

From straight line equation, that is, y = mx + c we can easily determine the gradient m of the graph and its intercept c on the vertical axis.

When plotting a straight line graph, the line does not necessary passes through all the points. Therefore, it is important to determine the uncertainties Δm and Δc for the gradient of the graph and the y-interception respectively.

Method to determine Δm and Δc :

Consider the data obtained is as follows:

x	x_1	x_2	x_3 x_n
у	<i>y</i> 1	<i>y</i> ₂	<i>y</i> ₃ <i>y</i> _n

(a) Find the centroid (\bar{x}, \bar{y}) , where

$$\bar{x} = \frac{\sum\limits_{i=1}^{n} x_i}{n}$$
 and $\bar{y} = \frac{\sum\limits_{i=1}^{n} y_i}{n}$

- (b) Draw the best straight line passing through the centroid and balance.
- (c) Determine the gradient of the line by drawing a triangle using dotted lines. The gradient is given by

$$m = \frac{y_2 - y_1}{x_2 - x_1}$$

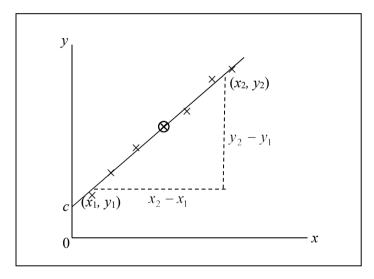


Figure A

(d) The uncertainty of the slope, Δm can be calculated using the following equation

$$\Delta m = \sqrt{\frac{\sum_{i=1}^{n} (y_i - \hat{y}_i)^2}{(n-2)\sum_{i=1}^{n} (x_i - \bar{x})^2}}$$

where n is the number of readings and \bar{x} is the average value of x given by

$$\bar{x} = \frac{1}{n} \sum_{i=1}^{n} x_i$$

and the estimated value of y, \hat{y}_l is given by,

$$\widehat{y}_i = \widehat{m}x_i + \widehat{c}$$

(e) The uncertainty of the y-intercept, Δc can be calculated using the following equation

$$\Delta c = \sqrt{\frac{1}{n-2} \sum_{i=1}^{n} (y_i - \hat{y}_i)^2 \left(\frac{1}{n} + \frac{\bar{x}^2}{\sum_{i=1}^{n} (x_i - \bar{x})^2} \right)}$$

4.4 Procedure to draw a straight line graph and to determine its gradient with its uncertainty

- (a) Choose appropriate scales to use at least 80% of the sectional paper. Draw, label, mark the two axes, and give the units. Avoid using scales of 3, 7, 9, and the likes or any multiple of them. Doing so will cause difficulty in plotting the points later on.
- (b) Plot all points clearly with ×. At this stage you can see the pattern of the distribution of the graph points. If there is a point which is clearly too far-off from the rest, it is necessary to repeat the measurement or omit it.
- (c) Calculate the centroid and plot it on the graph.

Example:

Suppose a set of data is obtained as below. Graph of T^2 against ℓ is to be plotted.

$\ell \ (\pm \ 0.1 \ cm)$	10.0	20.0	30.0	40.0	50.0	60.0
$T^2 (\pm 0.01 \text{ s}^2)$	0.33	0.80	1.31	1.61	2.01	2.26

From the data:

$$\bar{\ell} = \frac{10.0 + 20.0 + 30.0 + 40.0 + 50.0 + 60.0}{6} = 35.0 \text{ cm}$$

$$\overline{T^2} = \frac{0.33 + 0.80 + 1.31 + 1.61 + 2.01 + 2.26}{6} = 1.39 \text{ s}^2$$

Therefore, the centroid is (35.0 cm, 1.39 s²).

- (d) Draw a best straight line through the centroid and balance. Points above the line are roughly in equal number and positions to those below the line.
- (e) Determine the gradient of the line. Draw a fairly large right-angle triangle with part of the line as the hypotenuse.

From the graph in **Figure B**, the gradient of the line is as follows:

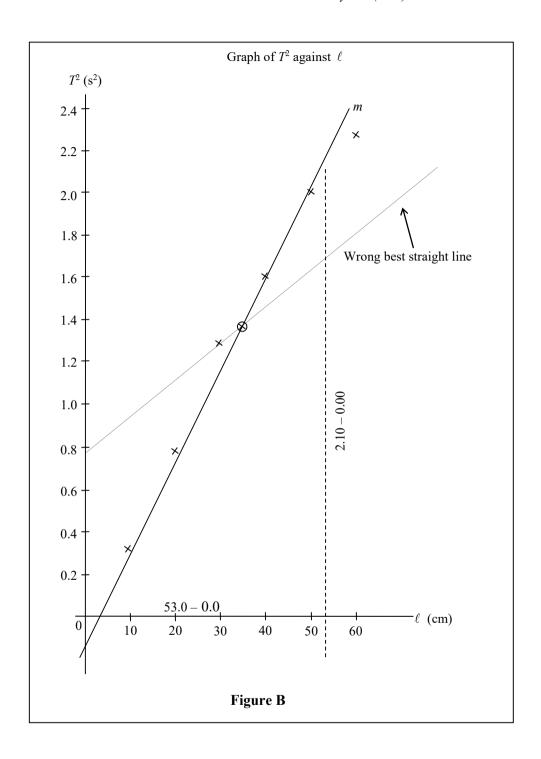
For the best line:

$$m = \frac{(2.10 - 0.00) \text{ s}^2}{(53.0 - 0.0) \text{ cm}}$$
$$= 0.040 \text{ s}^2 \text{ cm}^{-1}$$

The gradient of the graph and its uncertainty should be written as follows:

$$m = (0.040 \pm) \text{ s}^2 \text{ cm}^{-1}$$

Take extra precaution so that the number of significant figures for the gradient and its uncertainty are in consistency.



4.5 Calculation of uncertainties

Rewrite the data in the form of

ℓ	$\ell - \overline{\ell}$	$\left(\boldsymbol{\ell}-\overline{\ell}\right)^2$	T^2	$\widehat{T^2}$	$T^2 - \widehat{T^2}$	$\left(T^2-\widehat{T}^2\right)^2$
10.0	-25.0	625.0	0.33	0.4	-0.070	0.0049
20.0	-15.0	225.0	0.80	0.8	0.000	0.0000
30.0	-5.0	25.0	1.31	1.2	0.110	0.0121
40.0	5.0	25.0	1.61	1.6	0.010	0.0001
50.0	15.0	225.0	2.01	2.0	0.010	0.0001
60.0	25.0	625.0	2.26	2.4	-0.140	0.0196
$\Sigma = 210.0$		$\Sigma = 1750.0$				$\Sigma = 0.0368$

Where, $\bar{\ell}$ is the average of ℓ ,

$$\overline{\ell} = \frac{210}{6} = 35.0 \text{ cm}$$

Where, $\widehat{T^2}$ is the expected value of T^2

$$\widehat{T^2} = 0.04 \ell$$

Calculate the uncertainty of slope, Δm

 $\Delta c = \pm 0.09$

$$\Delta m = \sqrt{\frac{\sum_{i=1}^{n} (y_i - \hat{y}_i)^2}{(n-2)\sum_{i=1}^{n} (x_i - \bar{x})^2}}$$
$$= \sqrt{\frac{0.0368}{(6-2)(1750)}}$$

$$=\pm 0.002$$

Then, calculate the uncertainty of y-intercept, Δc

$$\Delta c = \sqrt{\left(\frac{\sum_{i=1}^{n} (y_i - \hat{y}_i)^2}{n - 2}\right) \left(\frac{1}{n} + \frac{\bar{x}^2}{\sum_{i=1}^{n} (x_i - \bar{x})^2}\right)}$$
$$\Delta c = \sqrt{\left(\frac{0.0368}{6 - 2}\right) \left(\frac{1}{6} + \frac{35^2}{1750}\right)}$$

The data given in section **4.4** was obtained from an experiment to verify the relation between T^2 and ℓ . Theoretically, the quantities obey the following relation,

$$T^2 = \left(\frac{k}{p}\right)\ell$$

where k is a natural number equals 39.48 and p is a physical constant. Calculate p and its uncertainty.

Solution:

From the equation, we know that

$$\frac{k}{p} = \text{gradient } m$$

$$p = \frac{k}{m}$$

$$= \frac{39.48}{0.040}$$

$$= 987 \text{ cm s}^{-2}$$

Since k is a natural number which has no uncertainties, that is $\Delta k = 0$.

$$\Delta p = \left(\frac{\Delta k}{k} + \frac{\Delta m}{m}\right) p$$
$$= \left(0 + \frac{0.002}{0.040}\right) 987$$
$$= 49.35$$

so we write,

$$p = (987 \pm 49.35) \text{ cm s}^{-2}$$
 or $p = (1000 \pm 50) \text{ cm s}^{-2}$

PHYSICS 1 SP015

EXPERIMENT 1: MEASUREMENT AND UNCERTAINTY

Course Learning Objective: Demonstrate manipulative skills during experiments in **measurement and uncertainty**, free fall and projectile motion, energy, rotational motion of rigid body, simple harmonic motion and standing waves in laboratory. (P3, CLO2, PLO 2, MQF LOD 2)

Learning Outcomes: At the end of this lesson, students should be able to:

- i. measure length of various objects, and
- ii. determine the uncertainty of length of various objects.

Student Learning Time (SLT):

Face-to-face	Non face-to-face
2 hours	0

Theory:

Measuring some physical quantities is part and parcel of any physics experiment. It is important to realise that not all measured values are exactly the same as the actual values. This could be due to errors that we made during the measurement, or perhaps the apparatus that we used may not be accurate or sensitive enough. Therefore, as a rule, the uncertainty of a measurement must be taken and it has to be recorded together with the measured value.

The uncertainty of a measurement depends on the type of measurement and how it is done. For a quantity x with the uncertainty Δx , its measurement is recorded as below:

$$x \pm \Lambda x$$

The relative uncertainty of the measurement is defined as:

$$\frac{\Delta x}{x}$$

and therefore its percentage of uncertainty is $\frac{\Delta x}{x} \times 100\%$.

1.1 Single Reading

(a) If the reading is taken from a single point or at the end of the scale,

$$\Delta x = \frac{1}{2} \times \text{ (smallest division from the scale)}$$

(b) If the readings are taken from two points on the scale,

$$\Delta x = 2 \times \left[\frac{1}{2} \times (\text{smallest division from the scale}) \right]$$

(c) If the apparatus uses a vernier scale,

 $\Delta x = 1 \times \text{(smallest unit from the vernier scale)}$

1.2 Repeated Readings

For a set of n repeated measurements of x, the best value is the average value given by

$$\overline{x} = \frac{\sum_{i=1}^{n} x_i}{n}$$

where n = the number of measurements taken

 $x_i =$ the i^{th} measurement

The uncertainty is given by

$$\Delta x = \frac{\sum_{i=1}^{n} |\overline{x} - x_i|}{n}$$
 1.2

The result should be written as

$$x = \overline{x} \pm \Delta x$$
 1.3

Apparatus:

A metre rule

A vernier callipers

A micrometer screw gauge

A travelling microscope

A coin

A glass rod

A ball bearing

A capillary tube (1 cm long)

Procedure:

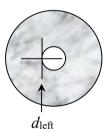
- 1. Choose the appropriate instrument for measurement of
 - (i) length of a laboratory manual.
 - (ii) diameter of a coin.

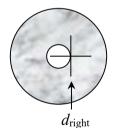
- (iii) external diameter of a glass rod.
- (iv) diameter of a ball bearing.
- 2. For task (i) to (iv), perform the measurement and record your results in a suitable table for at least 5 readings. Refer to **Table 1.1** as an example. Determine the percentage of uncertainty for each set of readings.

Table 1.1

	1 abic 1.1	
No.	Length of the laboratory manual, ℓ (±)	$ \overline{\ell} - \ell_i $ ()
1		
2		
3		
4		
5		
Average	$\overline{\ell} = \frac{\sum_{i=1}^{n} \ell_i}{n} = \dots$	$\Delta \ell = \frac{\sum_{i=1}^{n} \overline{\ell} - \ell_i }{n} = \dots$

3. Use travelling microscope to measure the internal diameter of the capillary tube. Adjust the microscope so that the cross-hairs coincide with the left and right edge of the internal diameter of the tube as shown in **Figure 1.1**. Record d_{left} and d_{right} .





The internal diameter, $d = |d_{right} - d_{left}|$

Figure 1.1

Determine the uncertainty and the percentage of uncertainty of the internal diameter of the capillary tube.

EXPERIMENT 2: FREE FALL AND PROJECTILE MOTION

Course Learning Objective: Demonstrate manipulative skills during experiments in measurement and uncertainty, **free fall and projectile motion**, energy, rotational motion of rigid body, simple harmonic motion and standing waves in laboratory.

(P3, CLO2, PLO 2, MQF LOD 2)

Learning Outcomes: At the end of this lesson, students should be able to:

- i. determine the acceleration due to gravity, g using free fall motion
- ii. determine the acceleration due to gravity, g using projectile motion

Student Learning Time (SLT):

Face-to-face	Non face-to-face
2 hours	0

Theory:

A. Free fall motion

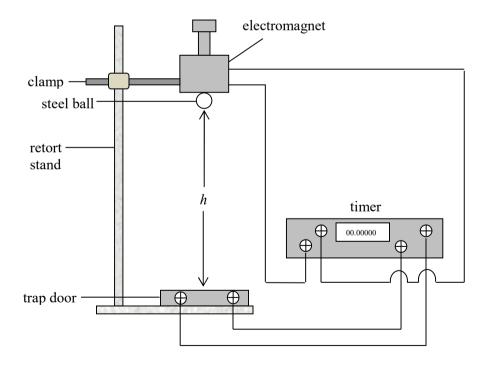


Figure 2.1

Note: Refer to **Figure 2.3** in page 22 for free fall apparatus with separate power supply for the electromagnet.

When a body of mass m falls freely from a certain height h above the ground, it experiences a linear motion. The body will obey the equation of motion,

$$s = ut + \frac{1}{2}at^2$$

By substituting the following into equation 2.1,

s = -h (downward displacement of the body from the falling point to the ground)

u = 0 (the initial velocity of the body)

a = -g (the downward acceleration due to gravity)

we obtain

$$h = \frac{1}{2}gt^2$$

B. Projectile motion

By referring to Figure 2.2, from the law of conservation of energy, the potential energy of a steel ball of mass m equals its kinetic energy,

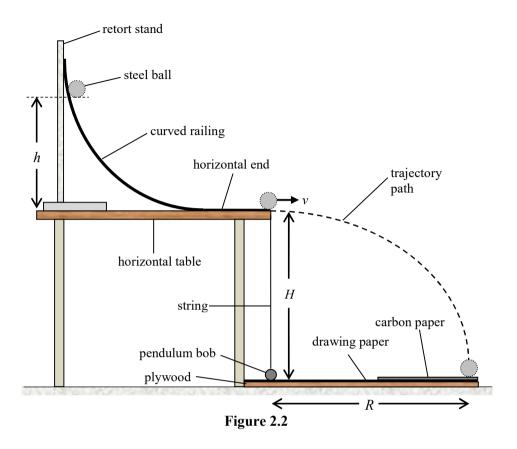
$$mgh = \frac{1}{2}mv^2 + \frac{1}{5}mv^2$$
 2.3

where *h* is the height of the release point above the track *v* is the velocity of the steel ball at the end of the track

Note: The rotational kinetic energy for solid sphere is $\frac{1}{5}mv^2$.

The range, R of the steel ball is given by

$$R = vt 2.4$$



Solving equations 2.3 and 2.4, we obtain

$$h = \frac{7}{10} \frac{R^2}{gt^2}$$
 2.5

where t is the time taken for the steel ball from the end of the curved track to reach the ground.

Apparatus:

A retort stand with a clamp

A timer

A metre rule

A free fall adaptor

A horizontal table

A steel ball (diameter of 1.0 cm)

A curved railing (**Important:** *The lower end of the track must be horizontal.*)

A piece of carbon paper

A piece of drawing paper

Cellophane tape

Plasticine

A pair of scissors or a cutter

A piece of string

A pendulum bob

A plywood

Procedure:

A. Free fall motion

- 1. Set up the apparatus as in **Figure 2.1**.
- 2. Switch on the circuit and attach the steel ball onto the upper contact.
- 3. Adjust the height h of the electromagnet above the point of impact.
- 4. Switch off the circuit and let the ball fall. Record the value of *h* and *t*.
- 5. Repeat step (3) and (4) for at least eight different values of h.
- 6. Tabulate your data.
- 7. Plot a graph of h against t^2 .
- 8. Determine the value of g from the gradient of the graph.

Note: The value range of h-axis should be extended slightly more than the height of the table.

9. Determine the value of Δg .

B. Projectile Motion

- 1. Set up the apparatus as in **Figure 2.2**.
- 2. Release the steel ball on the curvature railing from eight different heights *h* and record the values of *R*.

- 3. Tabulate your data.
- 4. Plot a graph of h against R^2 .
- 5. Measure the height H from the edge of the railing to the landing surface. By referring to the graph of h against t^2 from experiment A obtain the value of t^2 for H using extrapolation.
- 6. Calculate the value of g from the h against R^2 graph.
- 7. Determine the value of Δg .
- 8. Compare the value of *g* obtained from both experiments with the standard value. Write your comments.

Updated: 12/03/2020

Set-up for free fall apparatus with separate power supply to electromagnet.

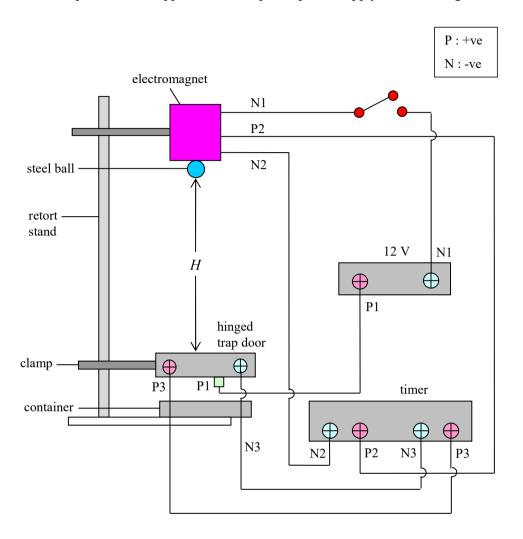


Figure 2.3

EXPERIMENT 3(a): ENERGY

Course Learning Objective: Demonstrate manipulative skills during experiments in measurement and uncertainty, free fall and projectile motion, **energy**, rotational motion of rigid body, simple harmonic motion and standing waves in laboratory.

(P3, CLO2, PLO 2, MQF LOD 2)

Learning Outcomes: At the end of this lesson, students should be able to verify the law of conservation of mechanical energy.

Student Learning Time (SLT):

Face-to-face	Non face-to-face
2 hours	0

Theory:

From Hooke's law, the stretching force F of an elastic chord is proportional to the extension x as

$$F = kx 3.1$$

where k is the elastic force constant.

The potential energy stored in the elastic chord is given by

$$U = \frac{1}{2}kx^2$$
3.2

If a body of mass m is attached to an elastic chord and extends the latter by x; upon release the body will reach a maximum kinetic energy K.

$$K = \frac{1}{2}mv^2$$

where v is the maximum speed of the mass.

From the law of conservation of mechanical energy, this maximum kinetic energy equals to the elastic potential energy U stored in the elastic chord, that is

$$K = U$$

$$\frac{1}{2}mv^2 = \frac{1}{2}kx^2$$
 3.4

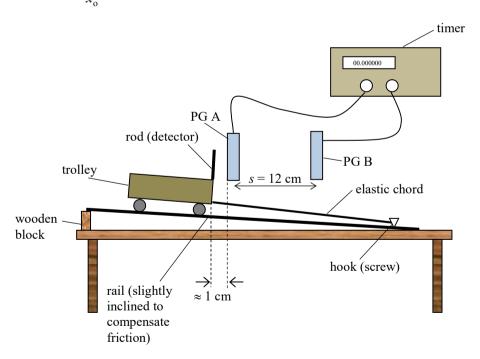
Let x_0 be the elongation of the elastic chord when the mass m hangs freely to it, then the elastic force constant k is given by

$$k = \frac{mg}{x_0}$$
 3.5

Substitute into equation 3.5 into equation 3.4, we obtain

$$v^2 = \frac{g}{x_0} x^2 \tag{3.6}$$

Evidently, if we plot a graph of v^2 against x^2 , we will get a straight line with a gradient of $\frac{g}{x_0}$.



PG: Photogate

Figure 3.1

Apparatus:

A trolley with a hook and a detector rod

A pair of photogates

A timer

A metre rule

An elastic chord

Two retort stands

A small wooden block

A rail

Procedure:

1. Set up the apparatus as in **Figure 3.1**. Use a wooden block to raise one end of the rail so that the effect of friction is just compensated.

Note: The friction effect is just compensated if the trolley moves freely without acceleration till the end of the rail when pushed slightly.

2. Arrange the photogates (PG) A and B at a fixed distance s about 12 cm apart from each other. Ensure that PG A is placed approximately 1 cm from the trolley with the elastic chord unstretched.

Note: Ask your laboratory assistant to fix the screw to the rail if it does not have one.

- 3. Pull the trolley to stretch the elastic chord by an elongation *x* within the range of 2 cm to 5 cm. Release the trolley until it passes the two photogates and then record the time *t* read by the timer.
- 4. Repeat step (3) two times to obtain the average value of *t*. Calculate the speed of the trolley, *v* where $v = \frac{s}{t}$.
- 5. Repeat step (4) for at least six different ascending values of x and tabulate the results.
- 6. Plot a graph of v^2 against x^2 .
- 7. Determine the gradient of the graph.

- 8. Hang the trolley freely onto the elastic chord and determine the elongation x_0 of the elastic chord. Calculate the value of $\frac{g}{x_0}$.
- 9. Compare whether the gradient of the graph equals to the value of $\frac{g}{x_0}$ calculated in step (8). Does your experimental result verify the law of conservation of mechanical energy? Write your comments.

EXPERIMENT 3(b): ENERGY

Course Learning Objective: Demonstrate manipulative skills during experiments in measurement and uncertainty, free fall and projectile motion, **energy**, rotational motion of rigid body, simple harmonic motion and standing waves in laboratory.

(P3, CLO2, PLO 2, MQF LOD 2)

Learning Outcomes: At the end of this lesson, students should be able to verify the law of conservation of energy.

Student Learning Time (SLT):

Face-to-face	Non face-to-face
2 hour	0

Theory:

Consider a steel ball of mass m, initially at rest at height h vertically above a velocity detector. By taking the position of the velocity detector as the reference point, the potential energy is mgh and the kinetic energy of the ball is zero. Thus the total initial energy E_1 of the steel ball is given by

$$E_1 = mgh 3.1$$

When the steel ball is released, it falls freely with acceleration g. At the instance it reaches the velocity detector, the gravitational potential energy is zero and its kinetic energy is $\frac{1}{2}mv^2$. Hence the total final energy E_2 of the steel ball is given by

$$E_2 = \frac{1}{2} m v^2$$
 3.2

According to the law of conservation of energy, in the absence of external force the total energy of a system remains constant. In this case, the law is verified if we demonstrate experimentally that E_1 equals E_2 , that is,

$$\frac{1}{2}mv^2 = mgh$$

And we obtain

$$v^2 = 2gh 3.3$$

Consequently, if a graph of v^2 against h is plotted, we should obtain a straight line curve passing through the origin with gradient equals 2g.

Apparatus:

A steel ball

A metre ruler

A free fall adaptor

Velocity detector (Two photogates PG A and PG B)

A timer

A retort stand

Procedure:

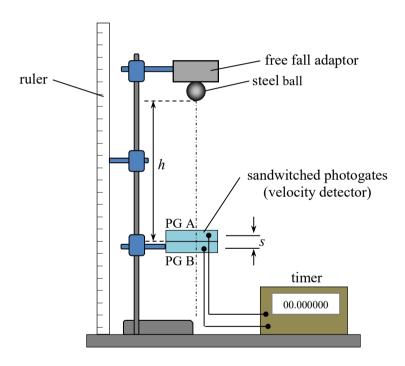


Figure 3.1

- 1. Construct a velocity detector by sandwitching photogates (PG) A and B using binding tape. Measure the distance *s* between the photogates.
- 2. Set up the apparatus as shown in **Figure 3.1**.
- 3. Switch ON the timer and reset to zero. Set the falling distance *h* at 15 cm. Release the steel ball and record the time *t*. Repeat the process to obtain the average time.

- 4. Repeat step (3) for h = 20, 25, 30, 35, 40,and 45 cm.
- 5. Tabulate your data. For each value of h calculate the velocity v using $v = \frac{s}{t}$.
- 6. Plot a graph of v^2 against h.
- 7. Use the graph to determine the value of acceleration due to gravity g and compare the value of g with the standard value.
- 8. Determine the uncertainty for the value of g obtained in (7).
- 9. Do the results of your experiment verify the law of conservation of energy? Write your comments.

EXPERIMENT 4: ROTATIONAL MOTION OF A RIGID BODY

Course Learning Objective: Demonstrate manipulative skills during experiments in measurement and uncertainty, free fall and projectile motion, energy, **rotational motion of rigid body**, simple harmonic motion and standing waves in laboratory.

(P3, CLO2, PLO 2, MQF LOD 2)

Learning Outcomes: At the end of this lesson, students should be able to determine the moment of inertia of a fly-wheel.

Student Learning Time (SLT):

Face-to-face	Non face-to-face
2 hour	0

Theory:

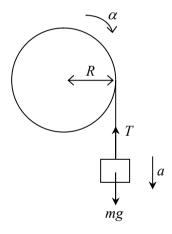


Figure 4.1

By referring to **Figure 4.1**, apply Newton's second law for linear motion,

$$mg - T = ma$$

$$T = m(g - a)$$
4.1

and applying Newton's second law for rotational motion,

$$TR - \tau = I\alpha$$
 4.2

where a is the downward linear acceleration

 τ is the frictional torque (unknown)

 α is the angular acceleration

T is the tension in the string

R is the radius of the axle

I is the moment of inertia of the fly-wheel

Therefore,

$$\alpha = \left(\frac{R}{I}\right)T - \left(\frac{\tau}{I}\right) \tag{4.3}$$

The graph α against T is a straight line graph with gradient $\frac{R}{I}$.

Moment of inertia of the fly-wheel,

$$I = \frac{R}{\text{gradient}}$$
 4.4

From kinematics, $s = ut + \frac{1}{2}(-a)t^2$ (negative sign means the acceleration is downward)

By substituting, s = -h and u = 0 into the equation above, we obtain

$$h = \frac{1}{2}at^2$$

Hence the linear acceleration,

$$a = \frac{2h}{t^2} \tag{4.5}$$

where h s the falling distance of mass

t is the time taken for the mass to fall to the floor

Angular acceleration,

$$\alpha = \frac{a}{R}$$
 4.6

Apparatus:

A fly-wheel

A stop watch

A set of slotted mass with hook (Use suitable masses for the fly-wheel to rotate at a suitable rate)

A metre rule

A G-clamp

A piece of inelastic string to hang the mass to the fly-wheel

A piece of softboard or plywood

A vernier callipers

Procedure:

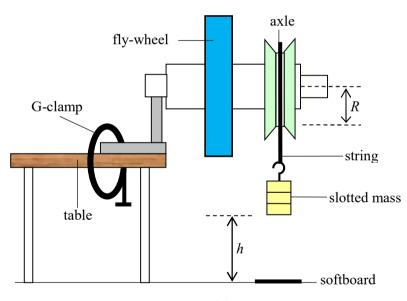


Figure 4.2

- 1. Set up the apparatus as in **Figure 4.2**.
- 2. Measure the diameter d of the axle and calculate its radius R.
- 3. Record the falling slotted mass m.

- 4. Choose a fixed point at a height *h* above the floor. Record *h*.
- 5. Release the slotted mass from the fixed height *h* after the string has been wound around the axle.
- 6. Record the time *t* for the slotted mass to reach the floor.
- 7. Calculate a, T and α using equations 4.5, 4.1 and 4.6 respectively.
- 8. Repeat steps (3) to (7) for at least six different values of *m*. Tabulate your results.
- 9. Plot a graph of α against T.
- 10. Determine the gradient of the graph and calculate the moment of inertia of the fly-wheel and its uncertainty.
- 11. Compare the moment of inertia to the theoretical value given by your lecturer.

EXPERIMENT 5: SIMPLE HARMONIC MOTION (SHM)

Course Learning Objective: Demonstrate manipulative skills during experiments in measurement and uncertainty, free fall and projectile motion, energy, rotational motion of rigid body, **simple harmonic motion** and standing waves in laboratory.

(P3, CLO2, PLO 2, MQF LOD 2)

Learning Outcomes: At the end of this lesson, students should be able to:

- i. determine the acceleration due to gravity g using a simple pendulum.
- ii. investigate the effect of large amplitude oscillation to the accuracy of g obtained from the experiment.

Student Learning Time (SLT):

Face-to-face	Non face-to-face
2 hour	0

Theory:

An oscillation of a simple pendulum is an example of a simple harmonic motion (SHM) if

- (i) the mass of the spherical bob is a point mass
- (ii) the mass of the string is negligible
- (iii) amplitude of the oscillation is small (< 10°)

According to the theory of SHM, the period of oscillation of a simple pendulum *T* is given by

$$T = 2\pi \sqrt{\frac{\ell}{g}}$$
 5.1

where ℓ is the length of pendulum

g is the acceleration due to gravity

Rearrange equation 7.1, we obtain

$$T^2 = \frac{4\pi^2 \ell}{g}$$
 5.2

Evidently, a graph of T^2 against ℓ is a straight line of gradient equals $\frac{4\pi^2}{g}$

Hence from the gradient of the graph, the value of g can be calculated.

Apparatus:

A piece of string (≈105 cm)

A small pendulum bob

A pair of small flat pieces of wood or cork

A retort stand with a clamp

A stopwatch

A metre rule

A protractor with a hole at the centre of the semicircle

An optical pin

A pair of scissors or a cutter

A stabilizing weight or a G-clamp

Procedure:

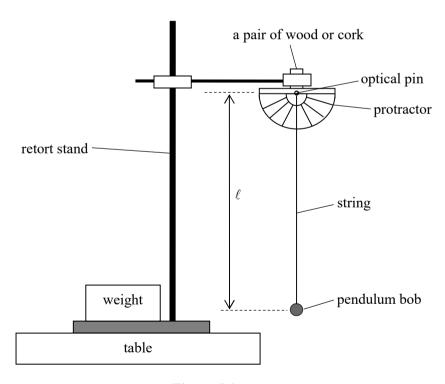


Figure 5.1

- 1. Set up a simple pendulum as in **Figure 5.1**.
- 2. Measure the length ℓ of the pendulum.
- 3. Release the pendulum at less than 10° from the vertical in one plane and measure the time t for 20 oscillations. Repeat the operation and calculate the average value. Then calculate the period of oscillation T of the pendulum.

Note: *Start the stopwatch after several complete oscillations.*

- 4. Repeat step (3) for at least six different values of length ℓ of the pendulum. Record the values for ℓ and T.
- 5. Plot a graph of T^2 against ℓ and determine the value of g and its uncertainty.
- 6. Fix the length of pendulum at 100.0 cm. Release the pendulum through a large arc of about 70° from the vertical. Record the time t for 5 complete oscillations. Repeat the operation and calculate the average value. Then calculate the period T of the oscillation of the simple pendulum.
- 7. Calculate the acceleration due to gravity, g using equation 5.1 and the value of ℓ and T from step (6).
- 8. Compare the values of *g* obtained from step (5) and step (7). Does your result differ from the standard value? Write your comments.

EXPERIMENT 6: STANDING WAVES

Course Learning Objective: Demonstrate manipulative skills during experiments in measurement and uncertainty, free fall and projectile motion, energy, rotational motion of rigid body, simple harmonic motion and **standing waves** in laboratory.

(P3, CLO2, PLO 2, MQF LOD 2)

Learning Outcomes: At the end of this lesson, students should be able to:

- i. To investigate standing waves formed in a stretched string.
- ii. To determine the mass per unit length of the string.

Student Learning Time (SLT):

Face-to-face	Non face-to-face
2 hours	0

Theory:

When a stretched string is vibrated at a frequency f, the standing waves formed have both ends as nodes. The frequency and the tension in the string obey the following relation

$$f = \frac{1}{2\ell} \sqrt{\frac{T}{\mu}}$$

or

$$T = 4\mu f^2 \ell^2 \tag{6.1}$$

where f is the frequency

 ℓ is the length between two nodes

T is the tension in the string

 μ is the mass per unit length

Evidently, a graph of T against ℓ^2 is a straight line of gradient equals $4\mu f^2$. Hence, the value of μ can be calculated.

Apparatus:

A G-clamp
A solenoid (about 100 turns) or ticker timer
An AC supply (2 – 6 V)
A metal rod (soft iron)
Two bar magnets
A magnet holder

A piece of string approximately 2 m long A pulley with clamp A wooden wedge Set of slotted mass 2 g, 5 g, 10 g and 20 g A metre rule Connecting wires

Procedure:

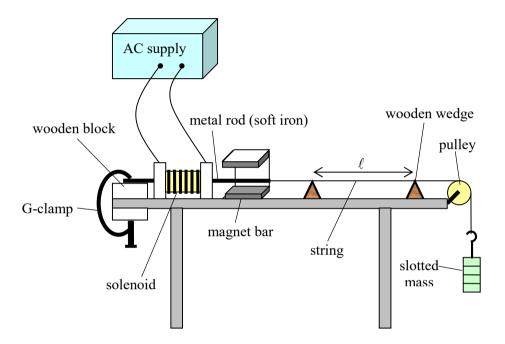


Figure 6.1

- 1. Set up the apparatus as in **Figure 6.1**.
- 2. Connect the terminals of the solenoid to the AC power supply (2 V, 50 Hz).

Caution: Do not exceed 4 V to avoid damage to the solenoid.

- 3. Place the metal rod between the two bar magnets.
- 4. Tie one end of the string to the rod and the other to the hook of the slotted mass. Make sure that the length of the string from the end of the rod to the pulley is not less than 1.5 m.

- 5. Clamp the metal rod properly. Switch on the power supply. Adjust the position of the metal rod to get maximum vibration.
- 6. Place the wooden wedges below the string as close as possible to the pulley.
- 7. Adjust the position of the wooden wedges until a clear single loop standing wave (fundamental mode) is observed. Record the distance ℓ between the wedges and total mass m (mass of the hook and the slotted mass).
- 8. Add a small mass, preferably 10 g to the hook and repeat step (7) for at least six different readings.
- 9. Construct a table for the values of m and ℓ . Calculate weight W where W = mg. Note that W = T. (Explain why?)
- 10. Plot a graph of T against ℓ^2 .
- 11. Determine the gradient of the straight line graph.
- 12. Deduce the mass per unit length, μ and its uncertainty of the string if the frequency of the vibration is 50 Hz.
- 13. Weigh the mass and measure the total length of the string. Calculate the mass per unit length of the string and compare it with the result obtained in step (12).

PHYSICS 2 SP025

EXPERIMENT 1: CAPACITOR

Course Learning Objective: Demonstrate manipulative skills during experiments in **capacitor**, electric current and direct current circuits, magnetic field, geometrical optics and physical optics. (P3, CLO 2, PLO 2, MQF LOD 2)

Learning Outcomes: At the end of this lesson, students should be able to:

- i. determine the time constant of an RC circuit, and
- ii. determine the capacitance of a capacitor using an RC circuit.

Student Learning Time (SLT):

Face-to-face	Non face-to-face
2 hours	0

Theory:

The total charge, Q on each plate of a capacitor during the charging and discharging processes varies with time, t as shown in **Figure 1.1**.

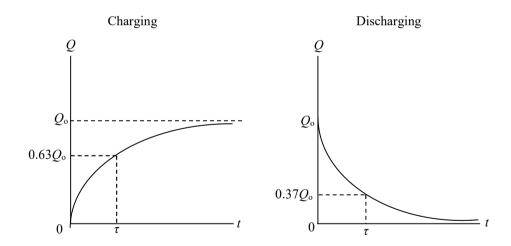


Figure 1.1

During the charging process

$$Q = Q_{o}(1 - e^{-t/\tau})$$
 1.1

During the discharging process

$$Q = Q_{o}e^{-t/\tau}$$
 1.2

where Q_0 is the initial amount of charge stored in a capacitor Q is the amount of charge at time t R is the resistance of a resistor C is the capacitance of a capacitor $\tau = RC$ is the time constant

During discharging, the magnitude of the current *I* varies with time as shown in **Figure 1.2**.

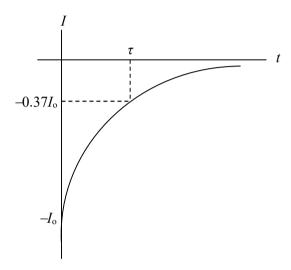


Figure 1.2

From equation 1.2, the magnitude of the discharge current is

$$I = -I_0 e^{\frac{t}{\tau}}$$
 1.3

Evidently at time $t = \tau$, the magnitude of the discharge current is $0.37I_o$. Negative sign shows the current flows in opposite direction to that of the current flows during the charging process.

Apparatus:

A DC power supply (4 - 6 V)

A switch

A DC microammeter

A stopwatch

A 100 kΩ resistor

Connecting wires

Two capacitors labelled C_1 and C_2 (470 – 1000 μ F)

Procedure:

Note: Before starting or repeating this experiment, make sure that the capacitors are fully discharged. This can be attained by short circuiting the capacitors.

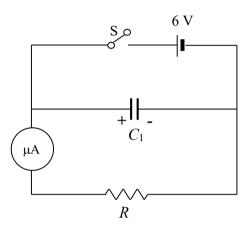


Figure 1.3

- 1. Set up the circuit as shown in **Figure 1.3** with switch S opened.
- 2. Read the microammeter for I_0 with switch S closed and record I_0 .
- 3. Open switch S and short circuit the capacitor using a connecting wire so that the capacitor is fully discharged.
- 4. Close switch S again to charge the capacitor so that the microammeter reading is back to I_0 .
- 5. Simultaneously open switch S and start the stopwatch to measure the time t of discharging process. Get at least six to eight pairs of current I and time t readings throughout the discharging process until the current is about $0.05I_0$.
- 6. Tabulate the values for both *I* and *t*.
- 7. Connect capacitor C_2 to the circuit as shown in **Figure 1.4**.

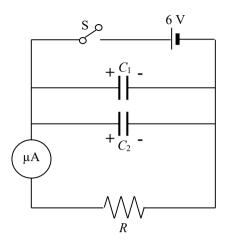


Figure 1.4

- 8. Repeat steps (3) to (6) to obtain the readings of the microammeter *I'* and the stopwatch *t'*. Record the readings and tabulate *I'* and *t'*.
- 9. Plot graphs of *I* against *t* and *I'* against *t'* using the same axes.
- 10. From the graphs, determine the time constants τ and τ' of the RC circuits.
- 11. Calculate the capacitance of the two circuits using equation $C = \frac{\tau}{R}$.

Note: The result obtained for circuit in **Figure 1.3** is for C_1 and the result for circuit in **Figure 1.4** is the effective capacitance C when capacitors C_1 and C_2 are in parallel combination.

- 12. Determine the value of C_2 .
- 13. Compare value from step (12) with the actual value of C_2 .

EXPERIMENT 2: OHM'S LAW

Course Learning Objective: Demonstrate manipulative skills during experiments in capacitor, **electric current and direct current circuits**, magnetic field, geometrical optics and physical optics. (P3, CLO 2, PLO 2, MQF LOD 2)

Learning Outcomes: At the end of this lesson, students should be able to:

- i. verify Ohm's law, and
- ii. determine the effective resistance of the resistors in series and parallel combination.

Student Learning Time (SLT):

3 - 1 - 1 - 1 - 1 - 1 - 1 - 1 - 1 - 1 -		
Face-to-face	Non face-to-face	
2 hours	0	

Theory:

At constant temperature the potential difference V across a conductor is directly proportional to the current I that flows through it. The constant of proportionality is known as resistance of the conductor denoted by R.

Mathematically, $V \propto I$

$$V = IR$$
 2.1

For resistors in series, the equivalent resistance is

$$R = R_1 + R_2 + R_3 + \dots + R_n$$
 2.2

For resistors in parallel, the equivalent resistance is

$$\frac{1}{R} = \frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_3} + \dots + \frac{1}{R_n}$$
 2.3

Apparatus:

A DC power supply (4 - 6 V)

Three resistors of the same resistance $(27 - 100 \Omega)$

A DC milliammeter

A DC ammeter (1 A)

A DC voltmeter

A variable resistor (resistance box or rheostat)

A switch

Connecting wires of about 50 cm long with crocodile clips Two connecting blocks for connecting the resistors A screw driver to loosen or tighten the connecting blocks

Procedure:

- 1. Determine the resistance of each resistor from their colour bands.
- 2. Set up the circuit as in **Figure 2.1**. Connect the three resistors in series.

Note: Ask your lecturer to check the circuit before switching ON the power.

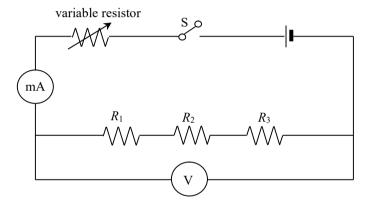


Figure 2.1

- 3. Change the resistance value in the variable resistor to get a minimum reading of the milliammeter. Record the reading of the voltmeter *V* and the milliammeter *I*.
- 4. Change the resistance value in the variable resistor to obtain at least five different values of *V* and *I*. Tabulate your data.
- 5. Plot a graph of *V* against *I*.
- 6. From the graph, deduce the effective resistance of the three resistors connected in series.
- 7. Compare the value obtained in step (6) with the calculated value.
- 8. Set up the circuit as in **Figure 2.2**.

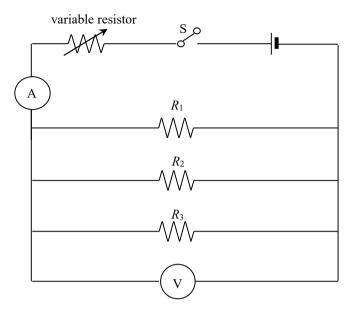


Figure 2.2

- 9. Repeat steps (3) to (5).
- 10. From the graph, deduce the effective resistance of the three resistors connected in parallel.
- 11. Compare the value obtained in step (10) with the calculated value.
- 12. Verify Ohm's law from the two plotted graphs.

EXPERIMENT 3: POTENTIOMETER

Course Learning Objective: Demonstrate manipulative skills during experiments in capacitor, **electric current and direct current circuits**, magnetic field, geometrical optics and physical optics. (P3, CLO 2, PLO 2, MQF LOD 2)

Learning Outcomes: At the end of this lesson, students should be able to determine the internal resistance *r* of a dry cell by using a potentiometer.

Student Learning Time (SLT):

Face-to-face	Non face-to-face
2 hours	0

Theory:

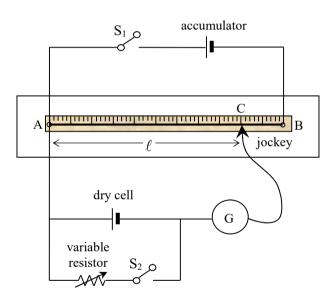


Figure 3.1

Let ε be the electromotive force (emf) and r the internal resistance of the dry cell. The emf of the dry cell is balanced by the potential difference across wire AB provided by the accumulator when the jockey is tapped at balance point, C with S_1 close and S_2 open. The balance condition is indicated when there is no deflection in the galvanometer. If ℓ_o is the length of the wire from A to C hence,

$$\varepsilon = k\ell_0$$
 3.1

where k is a constant.

With both S_1 and S_2 closed, the new length of wire at the balance point is equal to ℓ . Hence,

$$V = k\ell$$
 3.2

$$\varepsilon = V + Ir \tag{3.3}$$

Rearrange equation 3.1, 3.2 and 3.3, we obtain

$$\frac{\ell_{o}}{\ell} = r \left(\frac{1}{R}\right) + 1 \tag{3.4}$$

The graph $\frac{\ell_{o}}{\ell}$ against $\frac{1}{R}$ is a straight line graph and its gradient is r.

Apparatus:

A potentiometer

A variable resistor $(0 - 1 \Omega)$ (A breadboard, six 1 Ω resistor and jumpers)

Two switches

A iockev

A 2 V accumulator (higher than 1.8 V) or regulated power supply

A 1.5 V dry cell

A galvanometer

Connecting wires

Procedure:

1. Set up the apparatus as shown in **Figure 3.1**.

Important: Make sure the polarity of the batteries is connected in right configuration. Ask your lecturer to check the circuit before switch ON the power.

- 2. With S_1 closed and S_2 opened, determine the value of ℓ_0 .
- 3. With both S_1 and S_2 closed, determine ℓ for at least six different values of R.

Note: Use 1 Ω resistor in parallel combination to obtain resistance 1Ω , $\frac{1}{2}\Omega$, $\frac{1}{3}\Omega$, $\frac{1}{4}\Omega$, $\frac{1}{5}\Omega$ and $\frac{1}{6}\Omega$ as shown in **Figure 3.2**.

- 4. Plot a graph of $\frac{\ell_o}{\ell}$ against $\frac{1}{R}$.
- 5. From the graph, determine the internal resistance of the dry cell r.

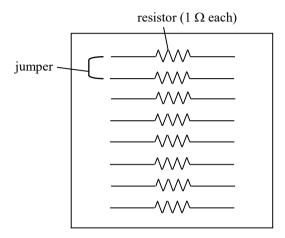


Figure 3.2

EXPERIMENT 4(a): MAGNETIC FIELD

Course Learning Objective: Demonstrate manipulative skills during experiments in capacitor, electric current and direct current circuits, **magnetic field**, geometrical optics and physical optics. (P3, CLO 2, PLO 2, MQF LOD 2)

Learning Outcomes: At the end of this lesson, students should be able to determine the value of the horizontal component of the earth magnetic field, $\vec{B}_{\rm E}$.

Student Learning Time (SLT):

Face-to-face	Non face-to-face
2 hours	0

Theory:

The magnetic field strength \vec{B} is a vector quantity so the addition of two magnetic fields obeys the parallelogram law. For example, if $\vec{B}_{\rm E}$ is the horizontal component of earth magnetic field and $\vec{B}_{\rm s}$ is the magnetic field of a solenoid which is perpendicular to $\vec{B}_{\rm E}$ then the resultant of the two fields \vec{B} is as shown in **Figure 4.1**. A compass needle is situated at the place where the two fields meet will be aligned to the direction of the resultant field \vec{B} .

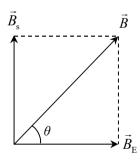


Figure 4.1

The magnetic field strength at the end of an N-turn solenoid of length ℓ and carries current I as shown in **Figure 4.2** is given by

$$B_{\rm s} = \frac{1}{2} \left(\frac{\mu_{\rm o} NI}{\ell} \right) \tag{4.1}$$

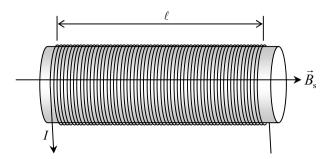


Figure 4.2

From Figure 4.1,

$$\tan \theta = \frac{B_{\rm s}}{B_{\rm E}}$$

$$\tan \theta = \frac{\frac{1}{2} \mu_o \left(\frac{N}{\ell}\right) I}{B_{\rm E}}$$
4.2

The gradient of graph $\tan \theta$ against I is

$$m = \frac{\frac{1}{2}\mu_{\rm o}\left(\frac{N}{\ell}\right)}{B_{\rm E}}$$
 4.3

Therefore,

$$B_{\rm E} = \frac{\frac{1}{2}\,\mu_{\rm o}N}{\ell m} \tag{4.4}$$

where $\mu_o = 4\pi \times 10^{-7}$ H m⁻¹ (permeability of free space).

Apparatus:

A 50 turn or 100 turn solenoid

A 2 V DC power supply

A DC ammeter (0 - 1 A)

A switch

Connecting wires

A rheostat

A compass

Procedure:

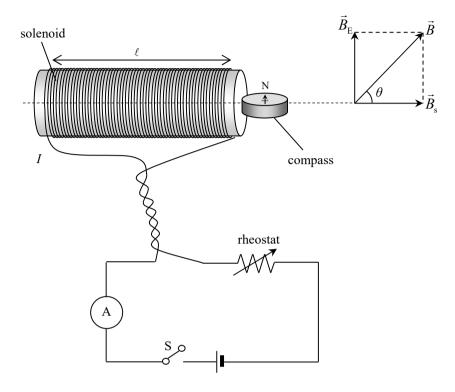


Figure 4.3

 Place a compass at one end of the solenoid. Let the compass stay still in N-S direction where the magnet pointer is perpendicular to the axis of the solenoid. The north direction of the compass must be pointed to the north.

Note: Choose a position to place your compass away from any iron structure to avoid any influence on the alignment of the compass needle.

- 2. Connect the solenoid in series with the rheostat, the ammeter, the power supply and the switch. The ammeter must be at least 50 cm away from the magnet. A complete set up is as in **Figure 4.3**.
- 3. Set the rheostat to its maximum value and switch on the circuit. Record the readings of the ammeter I and the angle of deflection θ . Reduce the resistance of rheostat to increase the current I and hence the corresponding value of θ . Obtain at least six sets of readings. The deflection angle should not be more than 80° .

4. Repeat step (3) by changing the polarity of the power supply. Record the angle θ_2 , pointed by the compass needle in **Table 4.1**.

Table 4.1

No.	Current, I (\pm)	θ_1 (±)	θ_2 $(\pm \dots)$	Average θ_{A} ()	$\tan heta_{ m A}$
1	(=:::::)	(=:::::)	(=:::::)	11 ()	
2					
3					
4					
5					
6					
7					
8					
9					

- 5. Remove the solenoid from the clamp and measure the length of the solenoid ℓ . Tabulate your data.
- 6. Plot a graph of $\tan \theta$ against *I*.
- 7. Use the graph to determine $B_{\rm E}$.
- 8. Compare your result with the standard value.

EXPERIMENT 4(b): MAGNETIC FIELD

Course Learning Objective: Demonstrate manipulative skills during experiments in capacitor, electric current and direct current circuits, **magnetic field**, geometrical optics and physical optics. (P3, CLO 2, PLO 2, MQF LOD 2)

Learning Outcomes: At the end of this lesson, students should be able to determine the value of the horizontal component of the earth magnetic field $\vec{B}_{\rm F}$.

Student Learning Time (SLT):

Face-to-face	Non face-to-face
2 hours	0

Theory:

The magnetic field strength \vec{B} is a vector quantity so the addition of two magnetic fields obeys the parallelogram law. For example, if $\vec{B}_{\rm E}$ is the horizontal component of earth magnetic field and $\vec{B}_{\rm c}$ is the magnetic field of a coil which is perpendicular to $\vec{B}_{\rm E}$ then the resultant of the two fields \vec{B} is as shown in **Figure 4.1**. A compass needle is situated at the place where the two fields meet will be aligned to the direction of the resultant field \vec{B} .

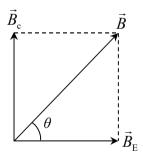


Figure 4.1

From Biot-Savart's Law, the magnetic field strength of the coil at the centre as shown in **Figure 4.2** is given by

$$B_{\rm c} = \frac{\mu_{\rm o} NI}{D}$$
 4.1

where $\mu_o = 4\pi \times 10^{-7} \text{ H m}^{-1} \text{ (permeability of free space)}$

I is the current in ampere

N is the number of turns in the coil

D is the diameter of the coil

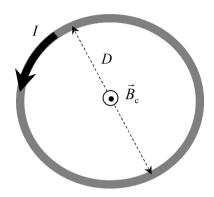


Figure 4.2

From Figure 4.1,

$$\tan \theta = \frac{B_{c}}{B_{E}}$$

$$\tan \theta = \frac{\mu_{o} N}{D(B_{E})} I$$
4.2

The gradient of graph $\tan \theta$ against I

$$m = \frac{\mu_{\rm o} N}{D(B_{\rm F})} \tag{4.3}$$

Therefore,

$$B_{\rm E} = \frac{\mu_{\rm o} N}{Dm}$$
 4.4

Apparatus:

Earth magnetic field measurement kit (EM-01) Connecting wires A DC ammeter (0 – 1 A) A rheostat A 2 V DC power supply

Procedure:

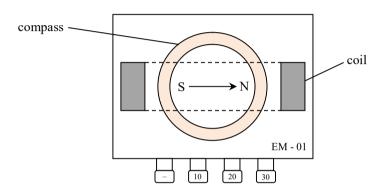


Figure 4.3

1. Position and adjust the EM-01 until the compass needle is pointed to the north as in **Figure 4.3**.

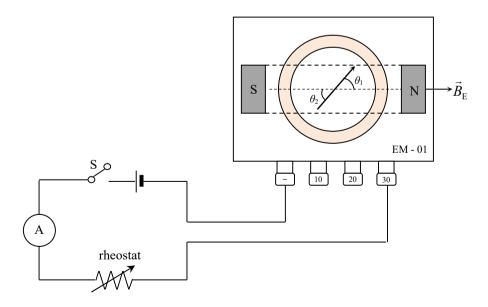


Figure 4.4

- 2. Set up apparatus as shown in **Figure 4.4**.
- 3. Set the rheostat to its maximum value and switch on the circuit. Record the readings of the ammeter I and the angle of deflection θ_1 , pointed by the compass needle in **Table 4.1**. Reduce the resistance of rheostat to increase the current I and hence the corresponding value of θ_1 .
- 4. Adjust the rheostat to obtain at least seven values of current and resultant angle of the compass needle. The deflection angle should not be more than 80°.
- 5. Repeat step (4) by changing the polarity of the power supply. Record the angle θ_2 , pointed by the compass needle in **Table 4.1**.

Table 4.1

Diameter of coil $D = (\dots \pm \dots)$ cm Number of turns N = 30

No.	current, I $(\pm \dots)$	θ_1 (\pm)	θ_2 (\pm)	average θ_{A} ()	$ an heta_{ m A}$
1	(=)	(=)	(=******)	Th (Time)	
2					
3					
4					
5					
6					
7					
8					
9					

- 6. Measure the diameter of the coil. Tabulate your data.
- 7. Plot a graph of $\tan \theta$ against *I*.
- 8. Use the graph to determine $B_{\rm E}$.
- 9. Compare your result with the standard value.

EXPERIMENT 5: GEOMETRICAL OPTICS

Course Learning Objective: Demonstrate manipulative skills during experiments in capacitor, electric current and direct current circuits, magnetic field, **geometrical optics** and physical optics. (P3, CLO 2, PLO 2, MQF LOD 2)

Learning Outcomes: At the end of this lesson, students should be able to determine the focal length of a convex lens.

Student Learning Time (SLT):

Face-to-face	Non face-to-face
2 hours	0

Theory:

From the lens equation,

$$\frac{1}{f} = \frac{1}{u} + \frac{1}{v}$$
 5.1

where f is the focal length u is the object distance v is the image distance

Multiply equation 6.1 with v,

$$\frac{v}{f} = \frac{v}{u} + 1$$

$$M = -\frac{v}{f} + 1$$
5.2

where $M = \frac{\text{height of image}}{\text{height of object}} = \frac{h_i}{h_0} = -\frac{v}{u}$ is the linear magnification.

Negative sign indicates that the image is inverted.

Hence the graph M against v is a straight line graph.

The equation also shows that M is proportional to v.

When v = 2f, M = -1.

Apparatus:

A convex lens

A piece of card with narrow triangle shaped slit

A screen

A light source

A metre rule

A lens holder

Plasticine

Procedure:

1. Use the convex lens to focus a distant object such as a tree outside the laboratory on a screen. The distance between the screen and the lens is the estimated focal length *f* of the lens.

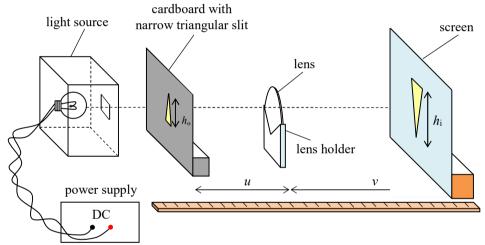


Figure 5.1

- 2. Set up the apparatus as in **Figure 5.1**.
- 3. Measure and record the height h_0 of the triangular slit on the cardboard. This is the height of the object for this experiment.
- 4. Place the object in front of the lens at a suitable distance (f < u < 2f) and adjust the position of the screen so that a sharp real, inverted image is projected on the screen.
- 5. Measure and record the object distance u, the image distance v and the height of the sharp image h_i .
- 6. Calculate the magnification of the image $M = \frac{h_i}{h_0}$

Updated: 13/09/2017

- 7. Change the location of the object. Repeat steps (5) and (6) until six sets of u, v and M are obtained. Tabulate your data.
- 8. Plot a graph of *M* against *v*.
- 9. Determine the focal length of the lens f from the gradient of the graph.
- 10. Read the image distance v from the graph when M = -1 and determine the focal length.

Updated: 13/09/2017

EXPERIMENT 6: DIFFRACTION

Course Learning Objective: Demonstrate manipulative skills during experiments in capacitor, electric current and direct current circuits, magnetic field, geometrical optics and **physical optics**. (P3, CLO 2, PLO 2, MQF LOD 2)

Learning Outcomes: At the end of this lesson, students should be able to:

- i. determine the wavelength of laser beam using a diffraction grating
- ii. the number of diffraction grating lines per unit length

Student Learning Time (SLT):

Face-to-face	Non face-to-face	
2 hour	0	

Theory:

When a laser beam is incident on a diffraction grating, a diffraction pattern in the form of a series of bright dots can be seen on the screen as shown in Figure 6.1

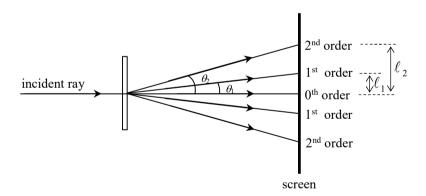


Figure 6.1

The relationship between the angle θ_n of the n^{th} order and the wavelength of laser λ is

$$\sin \theta_n = \frac{n\lambda}{d}$$
 6.1

Updated: 13/09/2017

where d is the distance between two consecutive lines of the diffraction grating, known as grating spacing.

Usually, the grating spacing is specified in number of lines per meter, such as N lines per meter. Hence, $N = \frac{1}{d}$. Then

$$\sin \theta_n = Nn\lambda \tag{6.2}$$

By measuring the angle θ_n for each order of diffraction n, λ can be determined.

Apparatus:

A laser pen

Two retort stands with clamps

A metre rule

A screen

Two diffraction gratings (A and B)

Note: *In the experiment, make sure that*

- *i)* the incident ray is normal to the diffraction grating.
- ii) the screen is parallel to the diffraction grating.

Procedure:

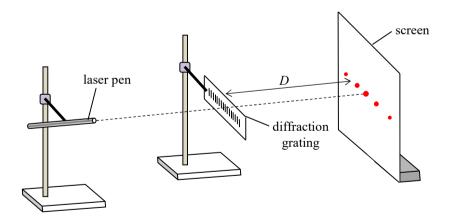


Figure 6.2

1. Set up the apparatus as shown in **Figure 6.2**. Ensure that the laser ray is pointed perpendicularly to the diffraction grating A.

- 2. The distance *D* from the diffraction grating to screen must be adjusted so that the spacing between the spots on the screen is as far as possible from one another. Measure and record the value of *D*.
 - **Caution:** A laser pen is NOT a toy. It is dangerous to look directly at the laser beam because it may cause permanent damage to your eyesight.
- 3. Measure the distance $\ell_1, \ell_2, \ell_3, ...$ that correspond to the diffraction order of 1, 2, 3, ... where ℓ_n is the distance between spots of order n to the centre spot.
- 4. Determine values of $\sin \theta_n$ for order of n = 1, 2, 3, ... using equation

$$\sin \theta_n = \frac{\ell_n}{\sqrt{(\ell_n)^2 + D^2}}$$

- 5. Tabulate your data. Plot a graph of sin θ_n against n.
- 6. From the graph, determine the wavelength of the laser beam λ . Note that the value of d for grating A can be calculated using the value of N printed on the grating.
- 7. Repeat steps (1) to (5) using grating B.
- 8. Using the value of λ in step (6), calculate the number of lines per mm of grating B.
- 9. Compare the value of λ and N for grating B with their actual values.

REFERENCES

- Cutnell, J. D. Johnson, K. W. (2015). Physics (10th ed.). USA: John Wiley & Sons, Inc.
 - Serway, R. A. & Jewett, J. A. (2014). *Physics for Scientists and Engineers* (9th ed.). International Student Edition. USA: Brooks/Cole Cengage Learning.
- Giordano, N. J. (2013). *College Physics Reasoning & Relationships* (2nd ed.). USA: Brook/Cole Cengage Learning.
- Giancoli, D. C. (2009). *Physics Principles with Application* (6th ed.). Prentice Hall.
- Haliday, D. & Resnick, R. Walker, J. (2009). *Fundamental of Physics*, Extended (8th ed.). Tear Walker Johs Wiley & Sons Inc.
- Hewitt, P.G. (2009). Conceptual Physics (11th ed.). Addison-Wesley.

ACKNOWLEDGEMENTS

The Matriculation Division, Ministry of Education Malaysia wish to thank everyone who has contributed in shaping and writing this PHYSICS LABORATORY MANUAL (12th Edition) for the One Year Matriculation Programme. Special thanks go to those for their many valuable suggestions and conscientiousness in completing this manual.

Dr. Hajah Rosnarizah binti Abdul Halim Director of Matriculation Division

Dr. Shah Jahan bin Assanarkutty
Deputy Director of Matriculation Division (Academic)

Mohd Junaidi bin Abd Aziz Senior Principal Assistant Director

Reviewers for the 12th Edition

- Prof. Dr. Mohd. Mustamam bin Abd. Karim, Universiti Pendidikan Sultan Idris
- Prof. Madya Dr. Abu Hassan bin Hussin, Universiti Teknologi MARA
- Prof. Madya Dr. Azhan bin Hashim @ Ismail, Universiti Teknologi MARA
- Prof Madya Dr. Rosnah binti Zakaria, Universiti Teknologi MARA
- Mohamed Hazri bin Ariffin, Kolej Matrikulasi Kelantan
- Marhalim bin Hashim, Kolej Matrikulasi Pulau Pinang
- Dr. Ariffin bin Abas, Kolej Matrikulasi Johor
- Nor Ezah binti Jamaluddin, Kolej Matrikulasi Pahang
- Salmah binti Othman, Kolej Matrikulasi Melaka
- Muhamad Fariq bin Che Mee, Kolej Matrikulasi Melaka
- Che Mohammad Zamri bin Bakar, Kolej Matrikulasi Perak
- Sarimah binti Kamrin, Kolej Matrikulasi Johor
- Shazrina binti Abd.Rahim, Kolej Matrikulasi Johor
- Lilis Suraini binti Mohd Ayob, Kolej Matrikulasi Selangor
- Bibi Aishah binti Roslan, Bahagian Matrikulasi KPM
- Azmajura binti Abdul Rahim @ Arifin, Bahagian Matrikulasi KPM
- Sulha binti Alias, Bahagian Matrikulasi KPM
- Aifaa binti Awang Kechik, Bahagian Matrikulasi KPM

eISBN 978-983-2604-51-8