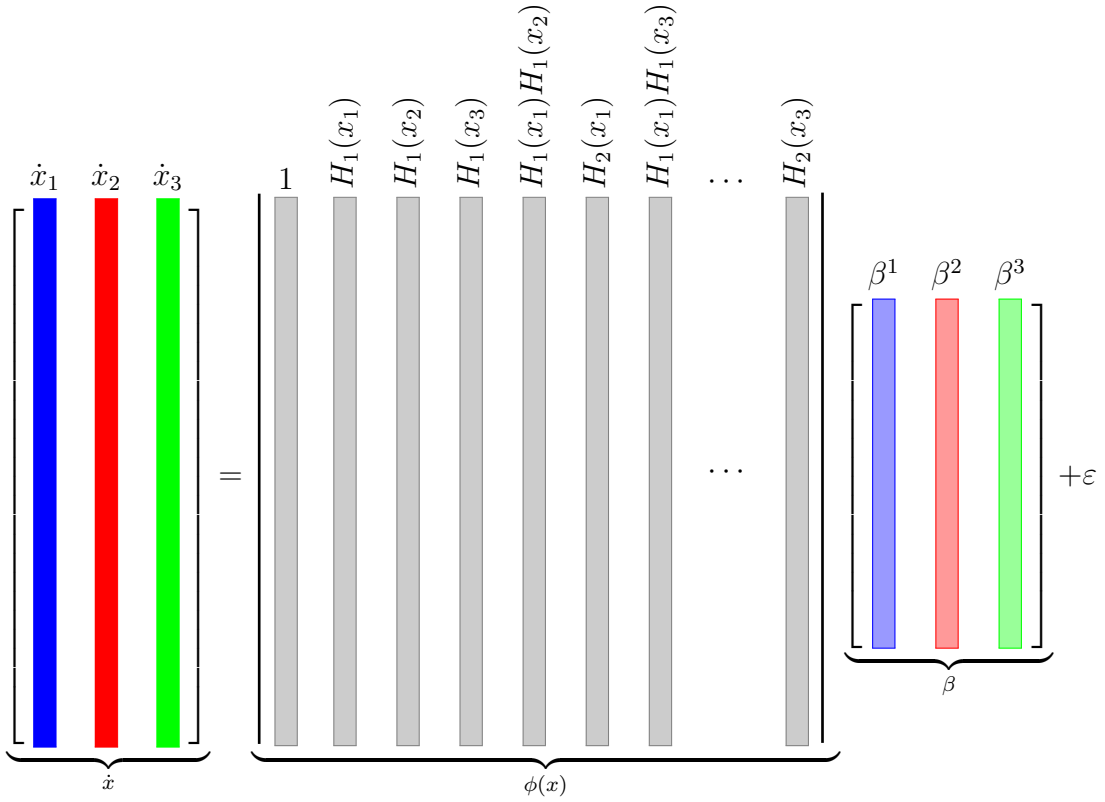
$\dot{x}_1$ $\dot{x}_2$ $\dot{x}_3$
$\dot{x}$
=
1 $H_1(x_1)$ $H_1(x_2)$ $H_1(x_3)$ $H_1(x_1)H_1(x_2)$ $H_2(x_1)$ $H_1(x_1)H_1(x_3)$ $\cdots$ $H_2(x_3)$
$\phi(x)$
β^1 β^2 β^3
β
$+\varepsilon$