# RL Assignment2

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### 1 Question 2

In order to solve the grid problem, we solve the linear system of equations:

$$Ax = b \tag{1}$$

where the grid size is 5x5, thereby giving a total of 25 states and an action space of 4 possible states. We model this problem as a linear system shown above where A (25x25 matrix) depicts the transition from each state to every other possible state and b is the 25x1 vector depicting the reward. The solution x is the required value function i.e.:

```
Value [ 3.30899634 8.78929186 4.42761918 5.32236759 1.49217876 1.52158807 2.99231786 2.25013995 1.9075717 0.54740271 0.05082249 0.73817059 0.67311326 0.35818621 -0.40314114 -0.9735923 -0.43549543 -0.35488227 -0.58560509 -1.18307508 -1.85770055 -1.34523126 -1.22926726 -1.42291815 -1.97517905]
```

Figure 1: Value Function

## 2 Question 4

To obtain the state-action value function, we solve the linear inequality:

$$Ax >= b \tag{2}$$

Here, we have the action space of 4 possible actions and a total of 25 states. Therefore, A as a  $100 \times 25$  matrix since for every state we have a transition to every other state for each possible action. b is the  $100 \times 1$  vector and x is  $25 \times 1$  for the 25 states in the grid.

By solving the above non-linear system, we obtain the state-action value function and the policy as follows:

```
Value [[21.98 24.42 21.98 19.42 17.48]
  [19.78 21.98 19.78 17.8 16.02]
  [17.8 19.78 17.8 16.02 14.42]
  [16.02 17.8 16.02 14.42 12.98]
  [14.42 16.02 14.42 12.98 11.68]]
Policy
  ['right '] ['up ', 'down ', 'left ', 'right '] ['left '] ['up ', 'down ', 'left ', 'right '] ['left ']
  ['up ', 'right '] ['up '] ['up ', 'left '] ['left '] ['left ']
  ['up ', 'right '] ['up '] ['up ', 'left '] ['up ', 'left ']
  ['up ', 'right '] ['up '] ['up ', 'left '] ['up ', 'left ']
  ['up ', 'right '] ['up '] ['up ', 'left '] ['up ', 'left ']
  ['up ', 'right '] ['up ', 'left '] ['up ', 'left ']
  ['up ', 'right '] ['up ', 'left '] ['up ', 'left ']
```

Figure 2: Value Function and Policy

### 3 Question 6

#### 3.1 Policy Iteration

The policy and the state value function obtained after policy iteration method is shown below:

```
Value [[ 0. -1. -2. -3.]
  [-1. -2. -3. -2.]
  [-2. -3. -2. -1.]
  [-3. -2. -1. 0.]]
Policy
['---- ', '---- '] ['left '] ['left '] ['down ', 'left ']
  ['up '] ['up ', 'left '] ['up ', 'down ', 'left ', 'right '] ['down ']
  ['up '] ['up ', 'down ', 'left ', 'right '] ['down ', 'right '] ['down ']
```

The per iteration difference in value function is as follows:

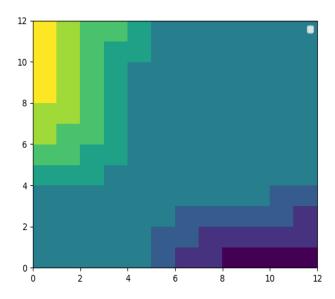
Iteration: 0 Difference between previous and current value function is : 5.766122522572036 Difference between previous and current value function is : 2.446230466082198 Iteration: 20 Difference between previous and current value function is: 1.0196738914812349 Iteration: 30 Difference between previous and current value function is: 0.424935441320615 Iteration: 40 Difference between previous and current value function is: 0.17708605754237206 Iteration: 50 Difference between previous and current value function is: 0.0737982024700002 Iteration: 60 Difference between previous and current value function is: 0.030754395706637752 Iteration: 70 Difference between previous and current value function is: 0.012816475518696007 Iteration: 80 Difference between previous and current value function is: 0.005341091604862473 Iteration: 90 Difference between previous and current value function is: 0.0022258271776756725 Iteration: 100 Difference between previous and current value function is: 0.0009275831592852963 Iteration: 110 Difference between previous and current value function is: 0.000386557647431135

#### 3.2 Value Iteration

The policy and the state value function obtained after value iteration method and the per iteration difference in value function is shown below:

## 4 Question 7

The optimal policy plot for original question as highlighted in the textbook is as follows:



For the modified problem as highlighted in Exercise 4.7, the optimal policy

plot and the 3D vlaue plot are as follows:

