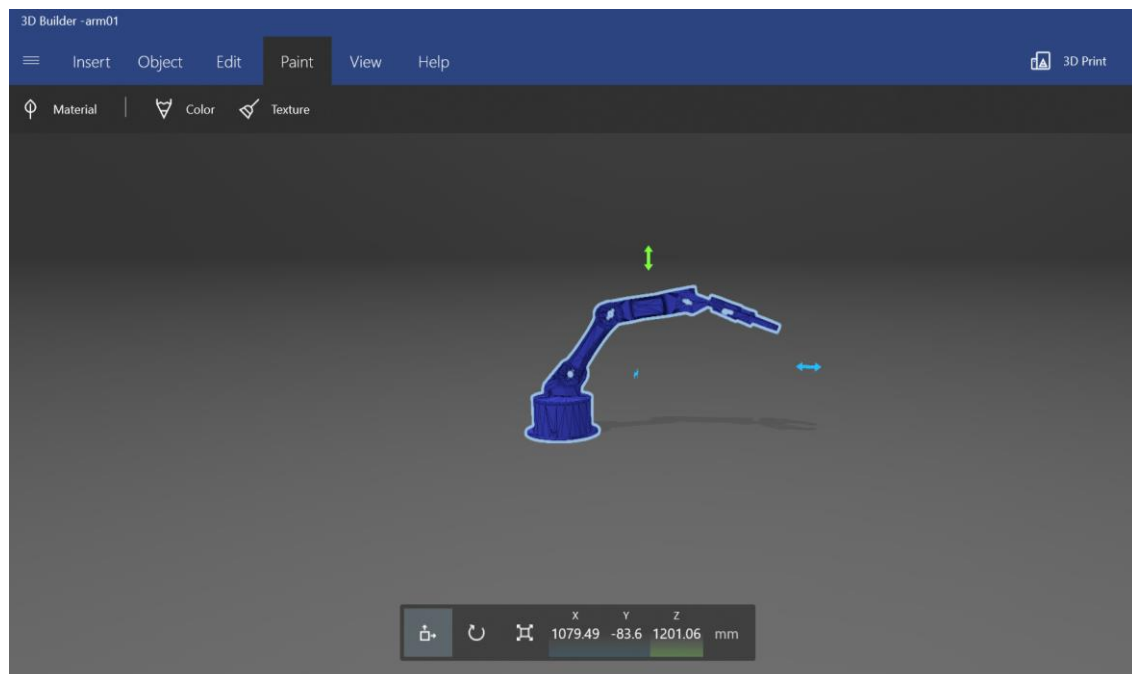
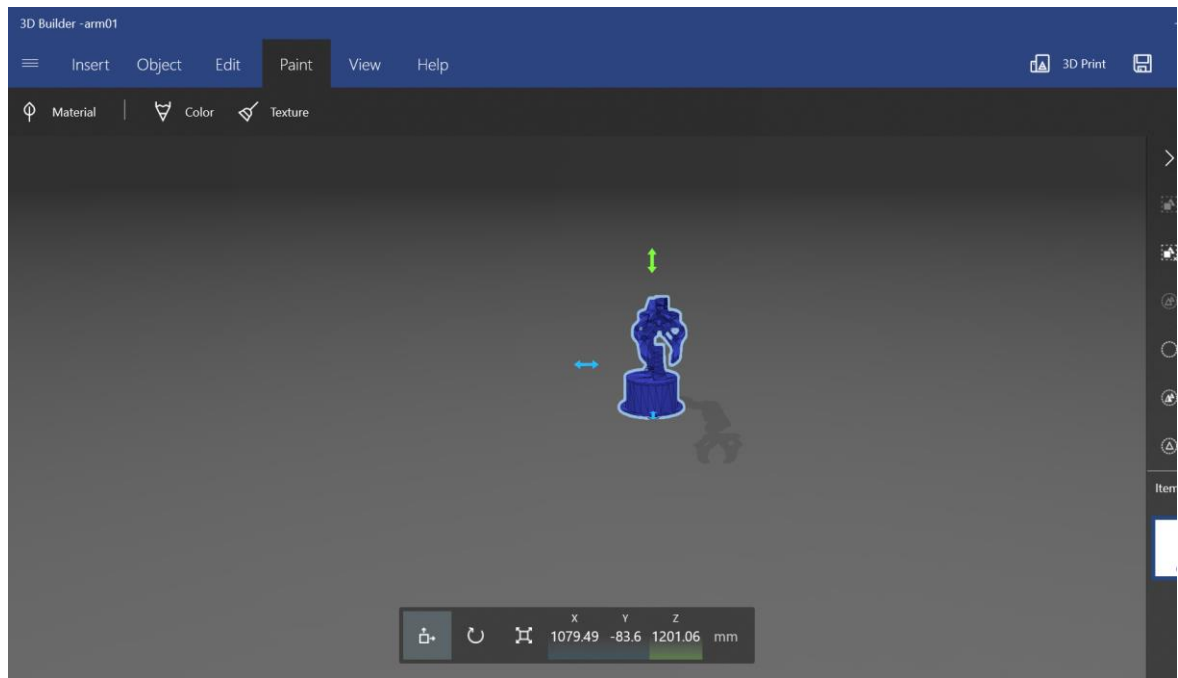


The task of installing the robotic arm and the assembly method for assembling the robotic arm

Follow the steps:

- 1- Download any 3D software
- 2- Download the robotic arm parts file via ([smart-methods \(Smart Methods\) \(github.com\)](https://github.com/smart-methods/Smart-Methods))
- 3 - Connect each part (base, shoulder, elbow, etc.).
- 4- Fix the base with screws on the movable base
- 5 - Attach the base servo motor to the waist.
- 6 - Attach the clutch to the arm with the arm
- 7 - Then connect the two groups together





End effector

A knife or sharp tool is generally used in its place and is tied and fixed by passing the mounting tape through the holes designated for it.

