```
function [Ix, Iy, It] = ImageDerivatives(I1, I2)
%IMAGEDERIVATIVES Calculates the derivative of the given images
   Parameters
%
   -----
  I1 - one frame of an image
%
   I2 - another frame (size identical to I1)
%
%
   Returns
%
   _____
%
  Ix - the derivative of the frame on the x axis
%
  Iy - the derivative of the frame on the y axis
%
  It - the derivative of the frame over time
   % kernels and constants
   Ky = 0.25 * [-1, -1; 1, 1];
   Kx = -Ky';
   Kt = 0.25 * ones(2, 2);
   CONV_PARAM = 'same';
   % actual work
   Ix = conv2(I1, Kx, CONV_PARAM) ...
       + conv2(I2, Kx, CONV_PARAM);
   Iy = conv2(I1, Ky, CONV_PARAM) ...
       + conv2(I2, Ky, CONV_PARAM);
   It = conv2(I2, Kt, CONV_PARAM) ...
       - conv2(I1, Kt, CONV_PARAM);
end
```

Published with MATLAB® R2014b