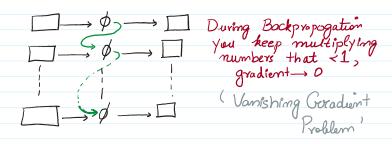
Problem with RNN

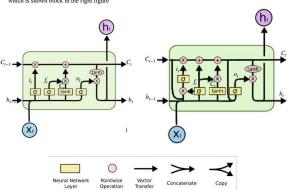
formula $ht = \phi(W_n h_{t-1} + W_x x_t + b)$

Some Activation function

At time t, take imput x & previous hidden state ht-1 to produce ht



Recurrent Neural Network
A standard LSTM as discussed in the lectures is shown below in left figure. We proposed a new LSTM which is shown block in the right figure



Write the equations gate (\tilde{C}_l) , input gate (i_l) , output gate (o_l) , forget gate (f_l) , cell update (C_l) and state update (h_l)

At t, given 0 $x_t \in \mathbb{R}^D$ 0 $h_{t-1} \in \mathbb{R}^h$

Compute

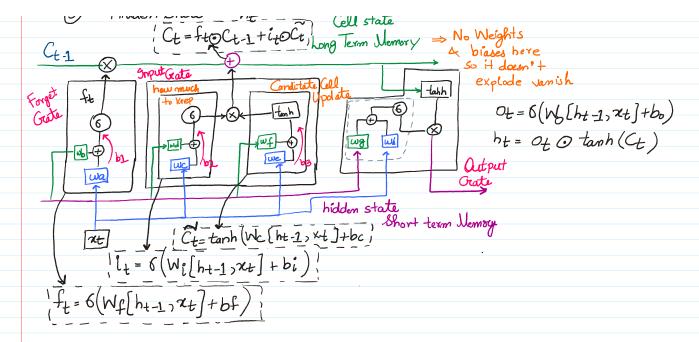
D Forget Grate: - ft & (0,1)

2 Input Grate :- it (0,1)

3 Canditate Grate :- C+ (-1, +1)

4) Output Geate: - Of (0,1)

(3) Hidden State _ ht - Cell state Ct = ftoCt-1 + itoCt) hong Term Memory > No Weights A biases here



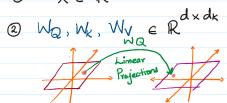
$$6 = \frac{e^{x}}{e^{x} + 1}$$

$$\tanh = \frac{e^{x} - e^{-x}}{e^{x} + e^{-x}}$$

We cannot parallelize an LSTM Very long Range dependencies fade

Attention Model dimension

O X \in R

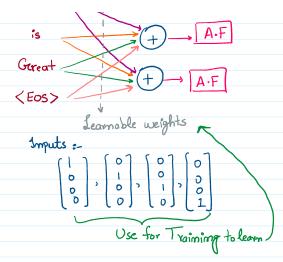


3
$$Q = W_Q \times K = \times W_K \quad V = \times W_V$$

$$Q, K, V \in \mathbb{R} \quad \text{North Multiplication Rules}$$
because $n \times d \quad d \times dk$

$$\frac{\text{Nord Embedding}}{\text{North Encoding}} \quad \text{size of} \quad n \times dk$$

$$\text{Shaheer} \quad E = \mathbb{R}$$



Positional Embedding

One Way is Sin v Soidal

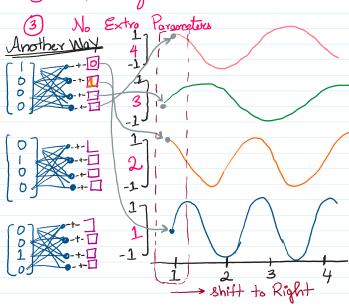
For Positions
$$t = 0, 1, 2 - - m - 1$$

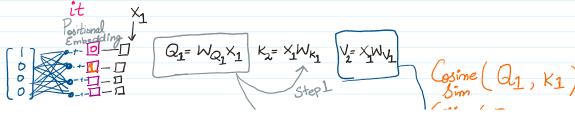
& dimension $d = 0, 1, 2 - - d$ dimension $d = 0, 1, 2 - - d$

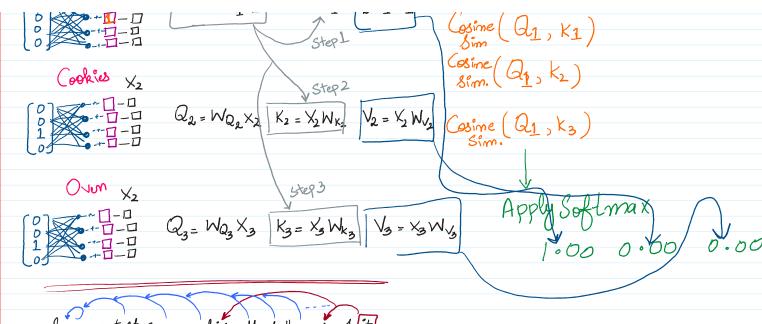
$$PE_{t,i} = \begin{cases} sin(\frac{t}{10000^{2i}}dmodd); & i even \\ cos(\frac{t}{10000^{2(i-1)}}/dmodel; & i odd) \end{cases}$$

$$PE \in IR$$

- 1 Unique Patterns
- 2 Smooth functions







Someone took some cookies alt of the over 4 it Smelt so Yum
Self attention

(it 't cookies' should have a higher cosine similarity S = GK

$$\hat{S} = \frac{S}{Jdk}$$

Diffusion Models

1) Forward Process

$$q(xt)xt-1) = \mathcal{N}(x_t; \sqrt{\alpha_t} K_{t-1}, \beta_t I)$$

where $\alpha_{t} = 1 - bt$ Bose Case 2

Where does of (xt | x0) $q(x_{t-1}|x_0) = \mathcal{N}(x_{t-1}; \sqrt{z_{t-1}}x_0, (-\overline{x_{t-1}})I)$

$$q(x_{t-1}|x_0) = \mathcal{N}(x_{t-1}; \sqrt{x_{t-1}}x_0, (1-x_{t-1})I)$$
where
$$\overline{x_{t-1}} = \overline{1} x_0$$

$$s=1$$

$$= x_1 x_2 - - x_{t-1}$$