

# 5

## Linear Algebra

### Eigenvalues and Eigenvectors

#### Linear Algebra

*and its applications*

FOURTH EDITION



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# Outline

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- Geometrical Interpretation of Eigenvalues and Eigenvectors
- Characteristic Equation
- Diagonalization
- Reading: Section 5.1, 5.2, 5.3 from Linear Algebra and Its Applications

# Learning Objectives

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- Interpret the eigenvalues and eigenvectors geometrically.
- Verify if a vector or a value is an eigenvector or eigenvalue
- Calculate eigenvalues and eigenvectors from the Characteristic Equation
- Determine if a given matrix is diagonalizable or not.
- If possible, diagonalize a matrix.
- Determine eigenvalues and eigenvectors in  $\mathbb{R}$ .

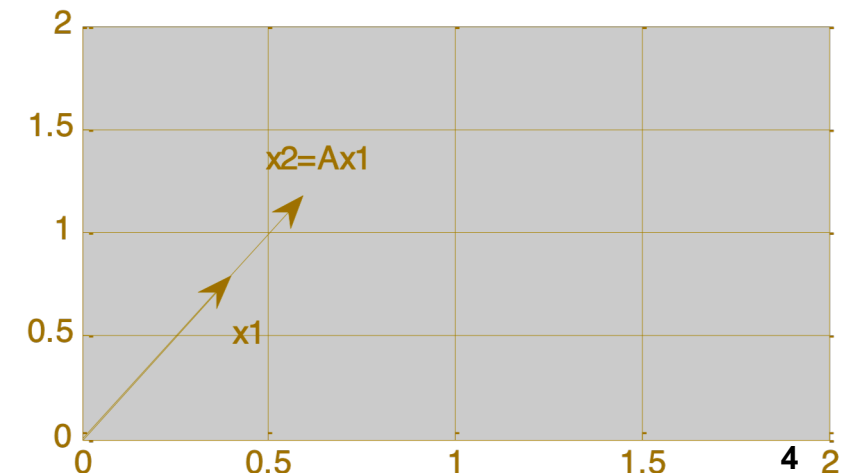
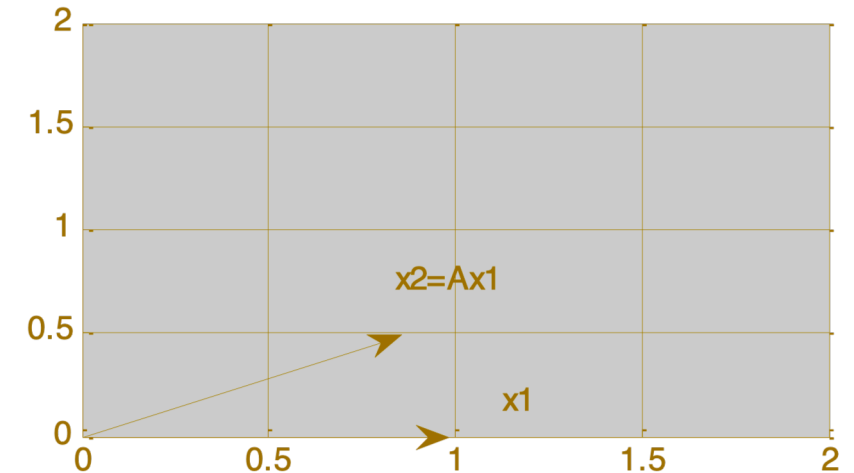
# Matrix Transformation

- Anytime a matrix is multiplied by a vector, that vector gets transformed to a new vector. This transformation is denoted by  $x \mapsto Ax$ .

- For example matrix  $A = \begin{bmatrix} \sqrt{3}/2 & -1/2 \\ 1/2 & \sqrt{3}/2 \end{bmatrix}$  transforms vector  $x_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$  to a new vector

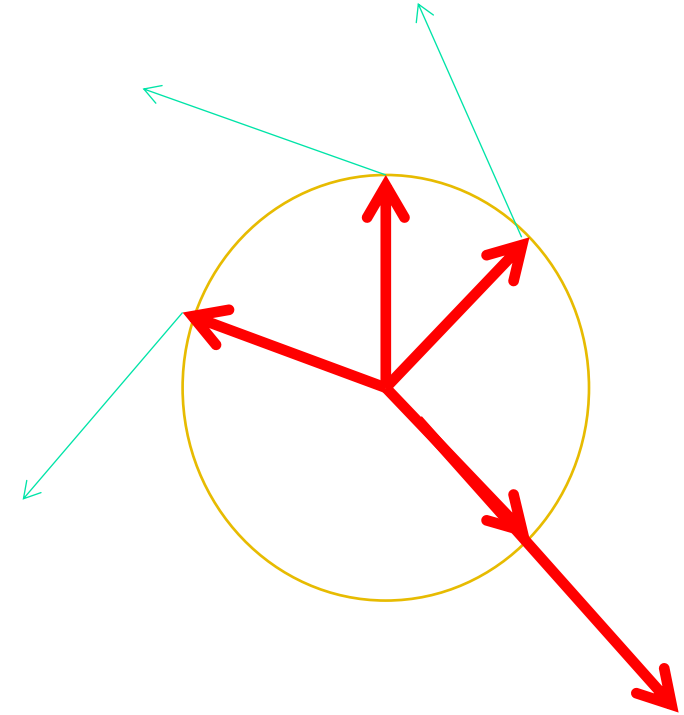
on the plane  $x_2 = \begin{bmatrix} \sqrt{3}/2 \\ 1/2 \end{bmatrix}$ .

- As can be seen in the figure the new vector is a rotated version of the old vector.
- If  $A$  transforms a vector  $x$  into a parallel (same direction) vector, then  $x$  is called an eigenvector of  $A$ .



# Geometrical Interpretation of Eigenvectors

- These 4 red vectors are unit vectors (inside a unit circle) each multiplied by a matrix  $A$ .
- Only 1 out of these 4 vectors is transformed to a new vector that is aligned (parallel) with the original.
- This vector is an eigenvector of matrix  $A$ .



# Example

- Let  $A = \begin{bmatrix} 3 & -2 \\ 1 & 0 \end{bmatrix}$ ,  $\vec{u} = \begin{bmatrix} -1 \\ +1 \end{bmatrix}$ , and  $\vec{v} = \begin{bmatrix} +2 \\ +1 \end{bmatrix}$ .
- Are either of the two vectors an eigenvector of matrix  $A$ ?

```
A = matrix(c(3,1,-2,0),nrow = 2)
u = c(-1,1)
v = c(2,1)
(Au = A%%u)
(AV = A%%v)
```

	[,1]
[1,]	-5
[2,]	-1
	[,1]
[1,]	4
[2,]	2

- $A \mathbf{v}$  is just  $2\mathbf{v}$ . So  $A$  only stretches  $\mathbf{v}$ , and hence  $\mathbf{v}$  is an eigenvector of  $A$ .
- The images of  $\mathbf{u}$  and  $\mathbf{v}$  under multiplication by  $A$  are shown in Fig. 1.

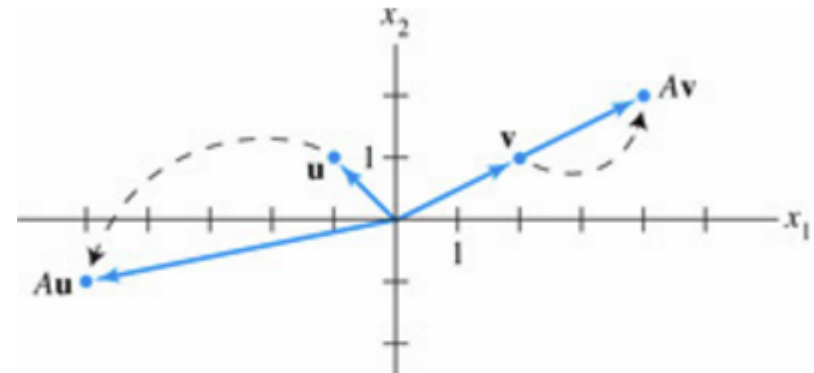


FIGURE 1 Effects of multiplication by  $A$ .

## Solution in Python

```
A = np.array([[3,-2],[1,0]])
u = np.array([-1],[1])
v = np.array([2],[1])
Au = A@u
Av = A@v
print('Au=\n',Au, '\nAv=\n',Av)
```

```
Au=
 [[-5]
 [-1]]
Av=
 [[4]
 [2]]
```

# Eigenvectors and Eigenvalues

- **Definition:** An **eigenvector** of an  $n \times n$  matrix  $A$  is a nonzero vector  $\mathbf{x}$  such that  $A\mathbf{x} = \lambda\mathbf{x}$  for some scalar  $\lambda$ . A scalar  $\lambda$  is called an **eigenvalue** of  $A$  if there is a nontrivial solution  $\mathbf{x}$ . Such an  $\mathbf{x}$  is called an *eigenvector corresponding to  $\lambda$* .

- $\lambda$  is an eigenvalue of an  $n \times n$  matrix  $A$  if and only if the equation  $A\mathbf{x} = \lambda\mathbf{x}$

$$(A - \lambda I)\mathbf{x} = \mathbf{0} \quad \text{----(1)}$$

has a nontrivial solution.

$$\text{e.g. } \begin{bmatrix} 3 & -2 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\left( \begin{bmatrix} 3 & -2 \\ 1 & 0 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$



## Example

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- Show that 7 is an eigenvalue of matrix

$$A = \begin{bmatrix} 1 & 6 \\ 5 & 2 \end{bmatrix} \text{ and find the corresponding eigenvectors.}$$

# Solution

- **Solution:** The scalar 7 is an eigenvalue of  $A$  if and only if the equation

$$A\mathbf{x} = 7\mathbf{x} \quad \text{----(2)}$$

has a nontrivial solution.

- But (2) is equivalent to  $A\mathbf{x} - 7\mathbf{x} = \mathbf{0}$ , or

$$(A - 7I)\mathbf{x} = \mathbf{0} \quad \text{----(3)}$$

- To solve this homogeneous equation, form the matrix

$$A - 7I = \begin{bmatrix} 1 & 6 \\ 5 & 2 \end{bmatrix} - \begin{bmatrix} 7 & 0 \\ 0 & 7 \end{bmatrix} = \begin{bmatrix} -6 & 6 \\ 5 & -5 \end{bmatrix}$$

## Solution

- The columns of  $A - 7I$  are obviously linearly dependent, so (3) has nontrivial solutions.
- To find the corresponding eigenvectors, use row operations:

$$\begin{bmatrix} -6 & 6 & 0 \\ 5 & -5 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & -1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

- $x_1 - x_2 = 0 \Rightarrow x_1 = x_2$
- The general solution has the parametric of form  $\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = x_2 \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ .
- Each vector of this form with  $x_2 \neq 0$  is an eigenvector corresponding to  $\lambda = 7$ .

# Eigenspace

- Let  $A$  be an  $n \times n$  matrix and let  $\lambda$  be an eigenvalue of  $A$ . This implies that the equation  $(A - \lambda I)\mathbf{x} = 0$  has a nontrivial solution.
- The set of all solutions of above equation is a subspace of  $\mathbb{R}^n$  and is called the eigenspace of  $A$  corresponding to  $\lambda$ .
- Therefore, the collection of all eigenvectors corresponding to  $\lambda$ , together with the zero vector is called the eigenspace.

## Example

- **Example 2:** Let  $A = \begin{bmatrix} 4 & -1 & 6 \\ 2 & 1 & 6 \\ 2 & -1 & 8 \end{bmatrix}$ . An eigenvalue of  $A$  is 2. Find a basis for the corresponding eigenspace.

- **Solution:** Form

$$A - 2I = \begin{bmatrix} 4 & -1 & 6 \\ 2 & 1 & 6 \\ 2 & -1 & 8 \end{bmatrix} - \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix} = \begin{bmatrix} 2 & -1 & 6 \\ 2 & -1 & 6 \\ 2 & -1 & 6 \end{bmatrix}$$

and row reduce the augmented matrix for  $(A - 2I)\mathbf{x} = \mathbf{0}$ .

## Solution

$$\begin{bmatrix} 2 & -1 & 6 & 0 \\ 2 & -1 & 6 & 0 \\ 2 & -1 & 6 & 0 \end{bmatrix} \sim \begin{bmatrix} 2 & -1 & 6 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

- At this point, it is clear that 2 is indeed an eigenvalue of  $A$  because the equation  $(A - 2I)\mathbf{x} = 0$  has free variables.

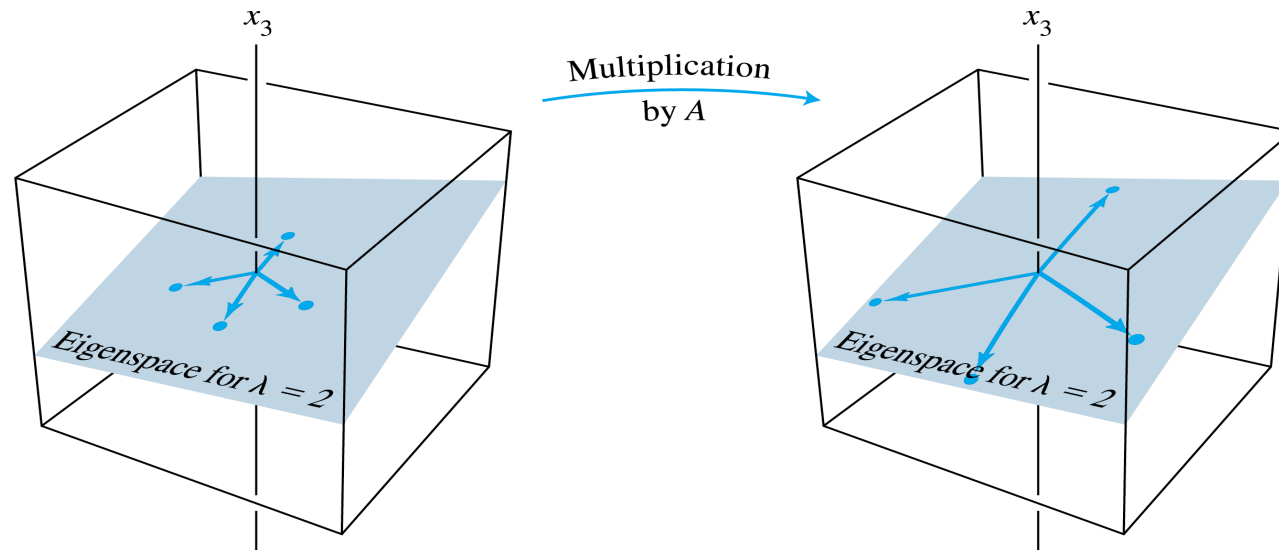
- $2x_1 - x_2 + 6x_3 = 0 \Rightarrow x_1 = \frac{1}{2}x_2 - 3x_3$

- The general solution is

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = x_2 \begin{bmatrix} 1/2 \\ 1 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -3 \\ 0 \\ 1 \end{bmatrix}, \quad x_2 \text{ and } x_3 \text{ free.}$$

# Solution

- The eigenspace, shown in the following figure, is a two-dimensional subspace of  $\mathbb{R}^3$ .



$A$  acts as a dilation on the eigenspace.

- Any multiple of  $\begin{bmatrix} 1/2 \\ 1 \\ 0 \end{bmatrix}$  and  $\begin{bmatrix} -3 \\ 0 \\ 1 \end{bmatrix}$  would be a basis. E.g.  $\left\{ \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix}, \begin{bmatrix} -3 \\ 0 \\ 1 \end{bmatrix} \right\}$

# Eigenvalue of a Triangular Matrix

- **Theorem 1:** The eigenvalues of a triangular matrix are the entries on its main diagonal.
- Example: What are the eigenvalues of  $A = \begin{bmatrix} 3 & 6 & -8 \\ 0 & 0 & 6 \\ 0 & 0 & 2 \end{bmatrix}$  and  $B = \begin{bmatrix} 4 & 0 & 0 \\ -2 & 1 & 0 \\ 5 & 3 & 4 \end{bmatrix}$ .
- The eigenvalues of  $A$  are 3, 0, and 2. The eigenvalues of  $B$  are 4 and 1.



# Finding Eigenvalues: Example

- Find the eigenvalues of  $A = \begin{bmatrix} 2 & 3 \\ 3 & -6 \end{bmatrix}$
- Let's go to the definition of eigenvalues and eigenvectors:  $Ax = \lambda x$  where  $\lambda$  is a scalar and  $x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$ .

$$\begin{bmatrix} 2 & 3 \\ 3 & -6 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \lambda \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$\begin{bmatrix} 2x_1 + 3x_2 \\ 3x_1 - 6x_2 \end{bmatrix} = \begin{bmatrix} \lambda x_1 \\ \lambda x_2 \end{bmatrix}$$

$$\begin{bmatrix} 2x_1 + 3x_2 - \lambda x_1 \\ 3x_1 - 6x_2 - \lambda x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} (2 - \lambda)x_1 + 3x_2 \\ 3x_1 + (-6 - \lambda)x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

## Example – cont.

- Let's think about this system of equations geometrically. Each equation represents a line in 2D that passes through the origin.
- The only way for the two lines to have a nontrivial solution(s) is for the two lines to overlap.
- This requires the ratio of the coefficients of the two lines to be the same which means that the determinant of  $\begin{bmatrix} 2 - \lambda & 3 \\ 3 & -6 - \lambda \end{bmatrix}$  has to be zero. (This matrix has to be **non-invertible**).
- Recall  $\det \begin{bmatrix} a & c \\ b & d \end{bmatrix} = ad - bc$
- Therefore  $(2 - \lambda)(-6 - \lambda) - (3)(3) = 0 \Rightarrow \lambda^2 + 4\lambda - 21 = 0$
- The above equation is called **Characteristic Equation**.
- Solving for lambda results in values of 3 and -7.

# Characteristic Equation

- Given a square matrix  $A$ , one can obtain the eigenvalues of  $A$  from the Characteristic Equation:

$$\det(A - \lambda I) = 0$$

- Note that the characteristic equation transforms the matrix equation  $(A - \lambda I)x = 0$  which involves two unknowns ( $\lambda$  and  $x$ ) into the scalar equation which involves only one unknown ( $\lambda$ ).

# Finding Eigenvectors

## Example

- Find Eigenvectors of  $A = \begin{bmatrix} 2 & 3 \\ 3 & -6 \end{bmatrix}$ .
- Recall that eigenvalues of A were  $\lambda = -7$  and  $\lambda = 3$ .
- Eigenvectors can be found by plugging in the eigenvalues in either of two equations:
- $$\begin{bmatrix} (2 - \lambda)x_1 + 3x_2 \\ 3x_1 + (-6 - \lambda)x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

- $\lambda = -7 \xrightarrow{\text{top eq.}} 9x_1 + 3x_2 = 0$

- $x_1 = -\frac{x_2}{3}$

- $x_2 = 1 \Rightarrow x_1 = -\frac{1}{3}$

- $X = \begin{bmatrix} -1/3 \\ 1 \end{bmatrix}$  or any of its multiples

- Normalizing the above vector will result in:

$$\begin{bmatrix} 1 \\ 3\sqrt{(1+\frac{1}{9})} \\ 1 \\ \sqrt{(1+\frac{1}{9})} \end{bmatrix} = \begin{bmatrix} -0.3162 \\ 0.9487 \end{bmatrix} \text{ normal eigenvector corresponding to } \lambda = -7$$

- $\lambda = 3 \xrightarrow{\text{top eq.}} -x_1 + 3x_2 = 0$

- $x_1 = 3x_2$

- $x_2 = 1 \Rightarrow x_1 = 3$

- $X = \begin{bmatrix} 3 \\ 1 \end{bmatrix}$  or any of its multiples

- $\begin{bmatrix} 0.9487 \\ 0.3162 \end{bmatrix}$  normal eigenvector corresponding to  $\lambda = 3$

# Finding Eigenvalues and Eigenvectors in R and Python

```
> A=matrix(c(2,3,3,-6),nrow=2)
```

```
> A
      [,1] [,2]
[1,]     2     3
[2,]     3    -6
```

```
> eig = eigen(A)
```

```
> eig$values
[1]  3 -7
```

```
> eig$vectors
      [,1] [,2]
[1,] -0.9487 -0.3162
[2,] -0.3162  0.9487
```

```
from numpy import linalg as LA
import numpy as np
```

```
A = np.array([[2,3],[3,-6]])
print(A)
```

```
[[ 2  3]
 [ 3 -6]]
```

```
l, ev = LA.eig(A)
print('Eigen values are:', l)
print('Eigen vectors are:', ev[:,0], 'and', ev[:,1])
```

```
Eigen values are: [ 3. -7.]
```

```
Eigen vectors are: [0.9486833  0.31622777] and [-0.31622777  0.9486833 ]
```

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# Diagonalization

## Why Diagonalization? Example

- Given  $D = \begin{bmatrix} 5 & 0 \\ 0 & 3 \end{bmatrix}$  calculate  $D^3$ .
- $D^2 = \begin{bmatrix} 5 & 0 \\ 0 & 3 \end{bmatrix} \begin{bmatrix} 5 & 0 \\ 0 & 3 \end{bmatrix} = \begin{bmatrix} 25 & 0 \\ 0 & 9 \end{bmatrix}$
- $D^3 = \begin{bmatrix} 25 & 0 \\ 0 & 9 \end{bmatrix} \begin{bmatrix} 5 & 0 \\ 0 & 3 \end{bmatrix} = \begin{bmatrix} 125 & 0 \\ 0 & 27 \end{bmatrix}$
- In general  $D^k = \begin{bmatrix} 5^k & 0 \\ 0 & 3^k \end{bmatrix}$

## Why Diagonalization?

- If  $A$  is *similar* to  $D$ , then by definition  $A = PDP^{-1}$
- $A^k = \underbrace{(PDP^{-1})(PDP^{-1}) \dots (PDP^{-1})}_{k \text{ times}} =$   
$$\left( PD \underbrace{P^{-1}P}_I DP^{-1} \right) \dots (PDP^{-1}) =$$
- $(PD^2P^{-1}) \dots (PDP^{-1}) = PD^kP^{-1}$



## Example

- Let  $A = \begin{bmatrix} 7 & 2 \\ -4 & 1 \end{bmatrix}$ . Find a formula for  $A^k$ , given that  $A = PDP^{-1}$ ,  
where  $P = \begin{bmatrix} 1 & 1 \\ -1 & -2 \end{bmatrix}$  and  $D = \begin{bmatrix} 5 & 0 \\ 0 & 3 \end{bmatrix}$

# Solution

$$P^{-1} = \begin{bmatrix} 2 & 1 \\ -1 & -1 \end{bmatrix}$$

$$\begin{aligned} A^k &= PD^k P^{-1} = \begin{bmatrix} 1 & 1 \\ -1 & -2 \end{bmatrix} \begin{bmatrix} 5^k & 0 \\ 0 & 3^k \end{bmatrix} \begin{bmatrix} 2 & 1 \\ -1 & -1 \end{bmatrix} \\ &= \begin{bmatrix} 2 \cdot 5^k - 3^k & 5^k - 3^k \\ 2 \cdot 3^k - 2 \cdot 5^k & 2 \cdot 3^k - 5^k \end{bmatrix} \end{aligned}$$

# The Diagonalization Theorem

- An  $n \times n$  matrix  $A$  is diagonalizable if and only if  $A$  has  $n$  linearly independent eigenvectors.
- In fact,  $A = PDP^{-1}$ , with  $D$  a diagonal matrix, if and only if the columns of  $P$  are  $n$  linearly independent eigenvectors of  $A$ . In this case, the diagonal entries of  $D$  are eigenvalues of  $A$  that correspond, respectively, to the eigenvectors in  $P$ .
- In other words,  $A$  is diagonalizable if and only if there are enough eigenvectors to form a basis of  $\mathbb{R}^n$ .

## Example

- Diagonalize the following matrix, if possible.

$$A = \begin{bmatrix} 1 & 3 & 3 \\ -3 & -5 & -3 \\ 3 & 3 & 1 \end{bmatrix}$$

## Solution

- *Step 1. Find the eigenvalues of  $A$ .*
- The characteristic equation is a cubic polynomial that can be factored:

$$0 = \det(A - \lambda I) = -\lambda^3 - 3\lambda^2 + 4$$

$$= -(\lambda - 1)(\lambda + 2)^2$$

$$\lambda = 1 \quad \lambda = -2$$

## Solution – cont.

- *Step 2. Find three linearly independent eigenvectors of  $A$ .*

$$\lambda = 1 : \mathbf{v}_1 = \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \quad \lambda = -2 : \mathbf{v}_2 = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} \quad \mathbf{v}_3 = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$$

- Note that  $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$  is a linearly independent set.

## Solution – cont.

- *Step 3. Construct  $P$  from the vectors in step 2.*
- The order of the vectors is unimportant.
- Using the order chosen in step 2, form

$$P = [\mathbf{v}_1 \quad \mathbf{v}_2 \quad \mathbf{v}_3] = \begin{bmatrix} 1 & -1 & -1 \\ -1 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix}$$

- *Step 4. Construct  $D$  from the corresponding eigenvalues.*
- In this step, it is essential that the order of the eigenvalues matches the order chosen for the columns of  $P$ .

$$D = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & -2 \end{bmatrix}$$

## Example

---

- Diagonalize the following matrix and verify your answer.

- $A = \begin{bmatrix} 2 & 4 & 3 \\ -4 & -6 & -3 \\ 3 & 3 & 1 \end{bmatrix}$



# Solution

```
> A = matrix(c(2,-4,3,4,-6,3,3,-3,1), nrow = 3)
```

```
> A
```

	[,1]	[,2]	[,3]
[1,]	2	4	3
[2,]	-4	-6	-3
[3,]	3	3	1

```
> eig = eigen(A)
```

```
> eigVal = eig$values
```

```
> eigVal
```

```
[1] -2+0i -2-0i 1+0i
```

```
> eigVec = eig$vectors
```

```
> round(eigVec, digits = 3)
```

	[,1]	[,2]	[,3]
[1,]	0.707+0i	0.707+0i	0.577+0i
[2,]	-0.707+0i	-0.707+0i	-0.577+0i
[3,]	0.000+0i	0.000+0i	0.577+0i

```
> eigValMat = diag(eigVal)
```

```
> eigValMat
```

	[,1]	[,2]	[,3]
[1,]	-2+0i	0+0i	0+0i
[2,]	0+0i	-2-0i	0+0i
[3,]	0+0i	0+0i	1+0i

```
> eigVec%*%eigValMat%*%ginv(eigVec)
```

	[,1]	[,2]	[,3]
[1,]	2-0i	4-0i	3-0i
[2,]	-4+0i	-6+0i	-3+0i
[3,]	3-0i	3-0i	1-0i

# Solution in Python

```
from numpy import linalg as LA
A = np.array([[2,4,3],[-4,-6,-3],[3,3,1]])
l, ev = LA.eig(A)
print('Eigen values are:', l)
print('Eigen vectors are:\n\n' , ev[:,0], '\n\n', ev[:,1], '\n\n', ev[:,2])
```

Eigen values are: [ 1.+0.00000000e+00j -2.+4.43741475e-08j -2.-4.43741475e-08j]  
Eigen vectors are:

```
[ 0.57735027+0.j -0.57735027+0.j  0.57735027+0.j]
```

```
[ 7.07106781e-01+3.13772606e-08j -7.07106781e-01+0.00000000e+00j
 2.21670630e-15-3.13772606e-08j]
```

```
[ 7.07106781e-01-3.13772606e-08j -7.07106781e-01-0.00000000e+00j
 2.21670630e-15+3.13772606e-08j]
```

```
: eigValMatrix = np.diag(l)
```

```
: ev@eigValMatrix@LA.inv(ev)
```

```
: array([[ 2.+2.64785493e-09j,  4.+6.26348292e-09j,  3.-1.49027072e-24j],
        [-4.-4.89168448e-09j, -6.-4.78202217e-09j, -3.+1.00783883e-24j],
        [ 3.+1.86264515e-09j,  3.+1.86264515e-09j,  1.-3.42072075e-25j]])
```

# Theorem

---

- An  $n \times n$  matrix with  $n$  distinct eigenvalues is diagonalizable
- It is not *necessary* for an  $n \times n$  matrix to have  $n$  distinct eigenvalues in order to be diagonalizable, but this provides a sufficient condition for a matrix to be diagonalizable.

## Example

- Diagonalize the following matrices, if possible and verify that  $\mathbf{A} = \mathbf{PDP}^{-1}$  in R.

- $A = \begin{bmatrix} 5 & -8 & 1 \\ 0 & 0 & 7 \\ 0 & 0 & -2 \end{bmatrix}$

- $B = \begin{bmatrix} 5 & 0 & 0 & 0 \\ 0 & 5 & 0 & 0 \\ 1 & 4 & -3 & 0 \\ -1 & -2 & 0 & -3 \end{bmatrix}$

# Solution

```
> A = matrix(c(5,0,0,-8,0,0,1,7,-2), nrow = 3)
> A
      [,1] [,2] [,3]
[1,]    5   -8    1
[2,]    0    0    7
[3,]    0    0   -2
> eig=eigen(A)
> eig$values
[1]  5 -2  0
> eig$vectors
      [,1]      [,2]      [,3]
[1,]    1 -0.7512222 0.8479983
[2,]    0 -0.6346533 0.5299989
[3,]    0  0.1813295 0.0000000
```

```
> eig=eigen(A)
> lambda = diag(eig$values)
> lambda
      [,1] [,2] [,3]
[1,]    5    0    0
[2,]    0   -2    0
[3,]    0    0    0
```

```
> P%*%lambda%*%ginv(P)
      [,1]      [,2] [,3]
[1,]  5.000000e+00 -8.000000e+00  1
[2,]  4.227640e-16 -2.818427e-16  7
[3,] -1.207897e-16  8.052648e-17 -2
```

```
> P = eig$vectors
> P
      [,1]      [,2]      [,3]
[1,]    1 -0.7512222 0.8479983
[2,]    0 -0.6346533 0.5299989
[3,]    0  0.1813295 0.0000000
```

# Solution

```
> B = matrix(c(5,0,1,-1,0,5,4,-2,0,0,-3,0,0,0,0,-3), nrow =4)
```

```
> B
```

	[,1]	[,2]	[,3]	[,4]
[1,]	5	0	0	0
[2,]	0	5	0	0
[3,]	1	4	-3	0
[4,]	-1	-2	0	-3

```
> eig = eigen(B)
```

```
> lambda = diag(eig$values)
```

```
> lambda
```

	[,1]	[,2]	[,3]	[,4]
[1,]	5	0	0	0
[2,]	0	5	0	0
[3,]	0	0	-3	0
[4,]	0	0	0	-3

```
> P = eig$vectors
```

```
> P
```

	[,1]	[,2]	[,3]	[,4]
[1,]	0.9847319	0.0000000	0	0
[2,]	0.0000000	0.8728716	0	0
[3,]	0.1230915	0.4364358	1	0
[4,]	-0.1230915	-0.2182179	0	1

```
> det(P)
```

```
[1] 0.8595445
```

```
> round(P%%lambda%%ginv(P), digits=3)
```

	[,1]	[,2]	[,3]	[,4]
[1,]	5	0	0	0
[2,]	0	5	0	0
[3,]	1	4	-3	0
[4,]	-1	-2	0	-3