Team APCA-1 Matt Tarnowsky Ryan Burr David Culham Bobak Shahidehpour

Intermediate Project Assignment 2

0. Create a list of requirements based on the project description.

System start-up:

1. The system must be activated immediately after cruise control is activated.

Pedestrian Sensor:

- 2. A stereo camera should be placed on the front bumper centered in between the two headlights respectively to capture any wandering pedestrians that might be walking towards the vehicle.
- 3. The camera's sensors must have a range that covers a range of about 35 meters in front of the vehicle.
- 4. The camera sensor must detect pedestrians as well as their location relative to the vehicle and their velocity.
- 5. Pedestrian information must be sent to the Safety Controller every 100 milliseconds.
- 6. If lenses are covered the camera must stop all readings and warn the driver.

Brake-by Wire Actuator:

- 7. Responds to braking requests sent by the Safety Controller.
- 8. Applies brake torque via electro mechanical actuators at all four wheels of the vehicle at the velocity sent over by the Safety Controller.

Safety Controller:

- 9. Safety Controller reads in the vehicle speed and pedestrian information that was sent over by the Pedestrian Sensor.
- 10. PCA Algorithm uses the pedestrian information as well as the vehicle

speed to calculate if a collision will occur.

- 11. If a collision is imminent, then the PCA Algorithm will calculate how fast the vehicle needs to decelerate in order to avoid the pedestrian.
- 12. Once the Safety Controller determines that the collision has been avoided it will reactivate the cruise control.
- 13. If a collision is not imminent, then the vehicle will maintain the cruise control speed.

Alerts:

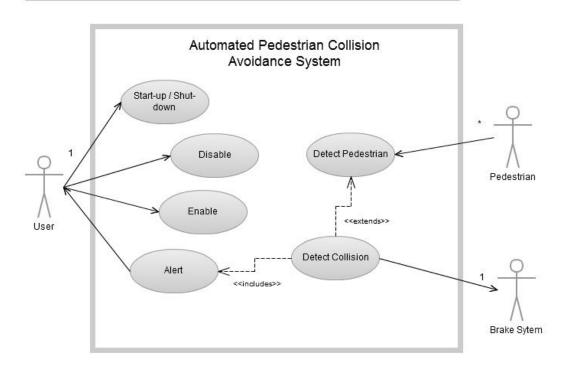
- 14. An auditory alert must be issued when the PCA Algorithm detects that a collision is imminent so that the driver knows the reason why the vehicle is braking. This alert should be a high-pitch sound that would last until the braking is complete.
- 15. There must also be a visual. Visual alerts will be in the form of an LED display near the windshield of the vehicle.
- 16. The vehicle's braking action and both alerts must be activated immediately after the PCA Algorithm detects a collision.

System Shutdown:

17. The system must be deactivated immediately after cruise control is turned off.

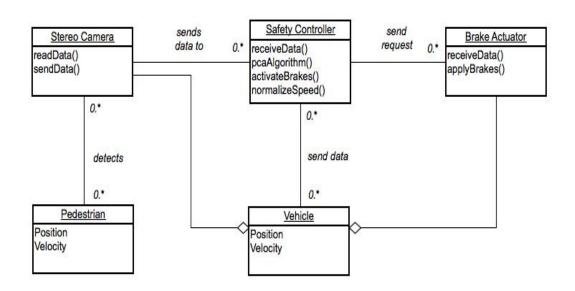
1. Create a first draft of a use case diagram.

Team Pedestrian Safety System Use Case Diagram



2. Create a first draft of a conceptual domain model.

APCA-1 Pedestrian Safety System



- 3. During this process, create a list of questions to pose to the customer.
 - 1. When does the system turn on? When the car is started or does the driver have to turn the system on manually?
 - 2. Does the car have to traveling at a constant speed for the system to work accurately?
 - 3. Will the camera be able to detect pedestrians when it is dark outside?
 - 4. Up to what distance do the cameras detect pedestrians?
 - 5. What happens when the camera lenses are covered in dirt/mud? Should an alert be sent to the driver? Can the system detect if the sensor is working correctly?
 - 6. Will the sensors be able to distinguish between objects? If so, will the system behave differently depending on the object detected?
 - 7. How stable are the sensors? Will the system be able to detect if the sensors are malfunctioning and how will it be handled if they are?
 - 8. Where is the camera placed on the vehicle?
 - 9. Will the system alert the driver if there is about to be a collision or will the system just brake to avoid the collision and carry on without notifying the driver?
 - 10. What does the user interface look like?
 - a. When system is first powered on what default information do you want to display?
 - 11. What kinds of security precautions are being taken?
 - 12. How is the system intended to behave in different weather conditions?
 - 13. Are there any legal constraints to be aware of?
 - 14. What interactions will a user have with a system?