

Lecture 28

EE 421 / CS 425

Digital System Design

Fall 2023

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Topics

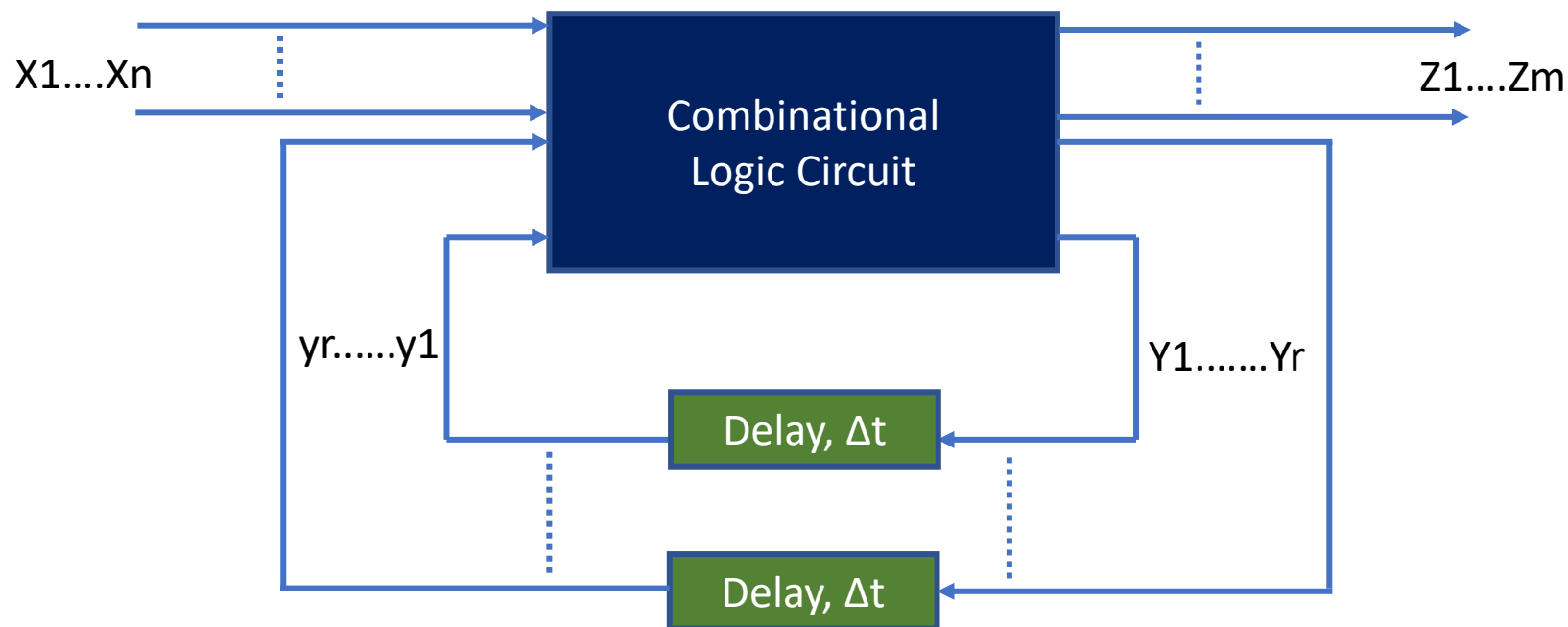
- Asynchronous Sequential Circuits
- Types of Asynchronous Circuits:
 - Pulse mode Asynchronous Circuits
- Analysis of Pulse Mode Circuits
- Design of Pulse Mode Circuits

Asynchronous Sequential Circuits

- A clock is **not** utilized to synchronize state changes
- Only external inputs and current states are available to cause state changes

Fundamental Mode Asynchronous Circuits

- These circuits have **level inputs** and **unlocked memory elements**
- Uses inherent delays present in logic circuit elements
- Assume that **each delay element has same delay Δt**

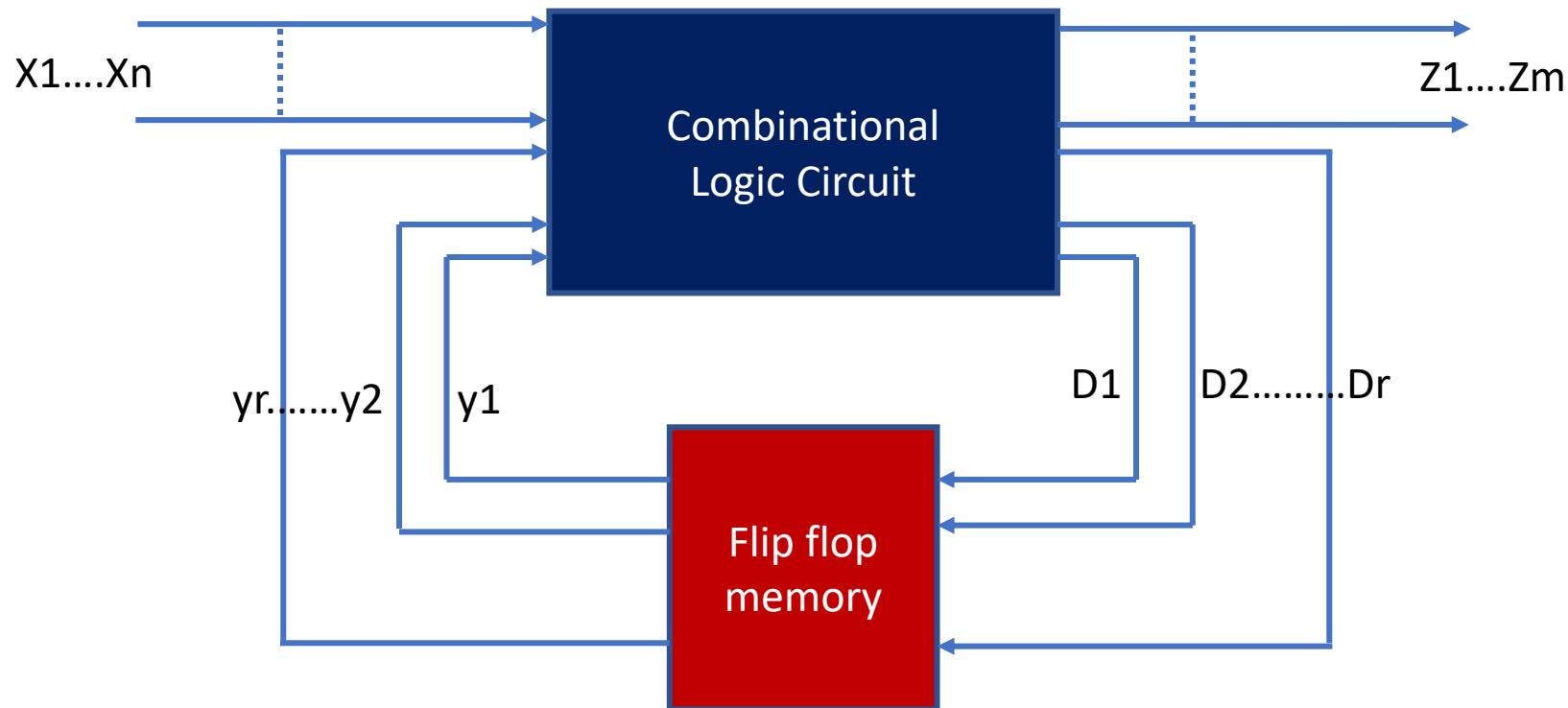


Other conditions for Fundamental Mode cct

- All delays in a circuit branch are lumped to a single Δt
- The delay is always Δt
- Inputs are restricted so that only one input variable is allowed to change value at a given instant to ensure correct behavior
- For predictable operations, input changes should be spaced in time by at least Δt ; the time needed for the circuit to settle down to a stable state following an input change

Pulse Mode Asynchronous Circuits

- Pulses will not occur simultaneously on two or more input lines
- Memory element transitions are limited only by input pulses
- Input variables are used either only in uncomplemented or in the complemented forms, but not both together



Pulse Mode Asynchronous Sequential

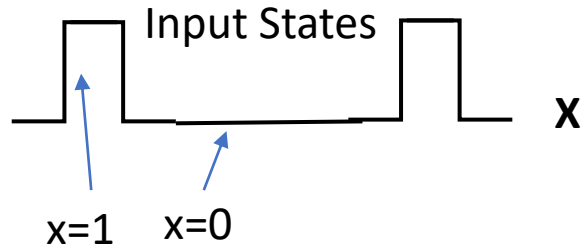
Pulse Mode Asynchronous Circuits :

- In the pulsed mode, the input variables are allowed to be applied in the form of pulses, rather than in the form of levels.
- But the width of input pulses is a critical parameter. There are two restrictions on the width of the input pulses.
 - The first requirement is that the pulses should be long enough so that the circuit can respond to them.
 - The second requirement is that the pulses should not be too long so that they are still present after the new secondary state is reached.
- The base of calculating the minimum pulse width is the propagation delay of the excitation logic.
- The maximum pulse width is calculated based on the total propagation delay through the excitation logic and the memory.

Conditions for Pulse mode circuits

- Input pulses should be spaced in time by at least the response time of the slowest memory element
- No memory element will be in process of changing state when a new input pulse arrives

Analysis of a Pulse Mode Asynchronous Sequential Circuit

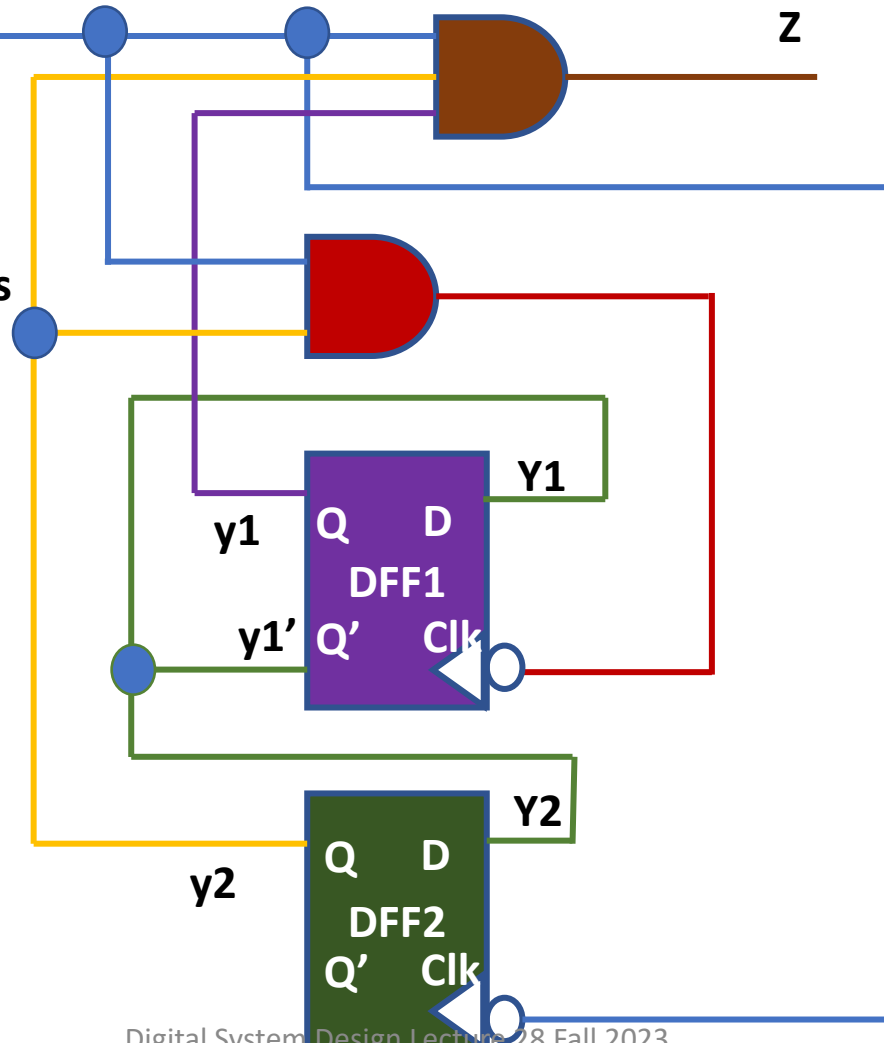


Input X is made up of asynchronous pulses

Initial state $y_1=y_2=0$

Present states = y_1, y_2 (small y)

Next states = Y_1, Y_2 (capital Y)



Logic Equations:

$$D1=y_1'$$

$$D2=y_1'$$

$$Z=X.y_1.y_2$$

$$C1=X.y_2$$

$$C2=X$$

Contd: Analysis Pulse Mode Ascynch Seq Cct

- Define:
- Inputs:
 - I_0 = no pulse on X
 - I_1 = pulse on X
- States:
 - A = 00 (y1y2)
 - B = 01
 - C = 10
 - D = 11
- Outputs:
 - Z = 0
 - Z = 1

Timing Diagram of Pulsed Sequential Circuit

Logic

Equations:

$D1=y1'$

$D2=y1'$

$Z=X.y1.y2$

$C1=X.y2$

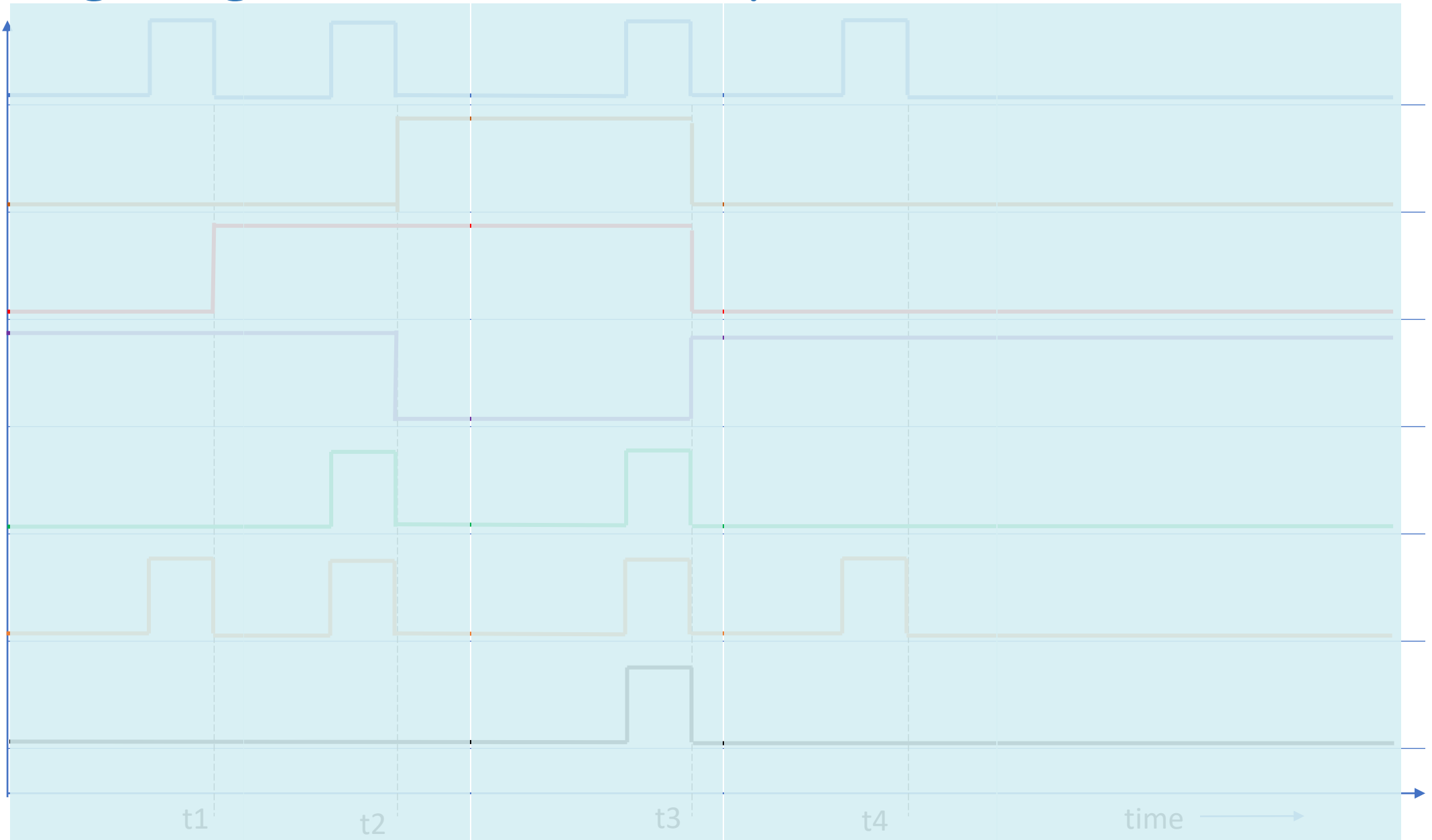
$C2=X$

$y1$
 $y2$
 $D1=D2$

$C1$

$C2$

z

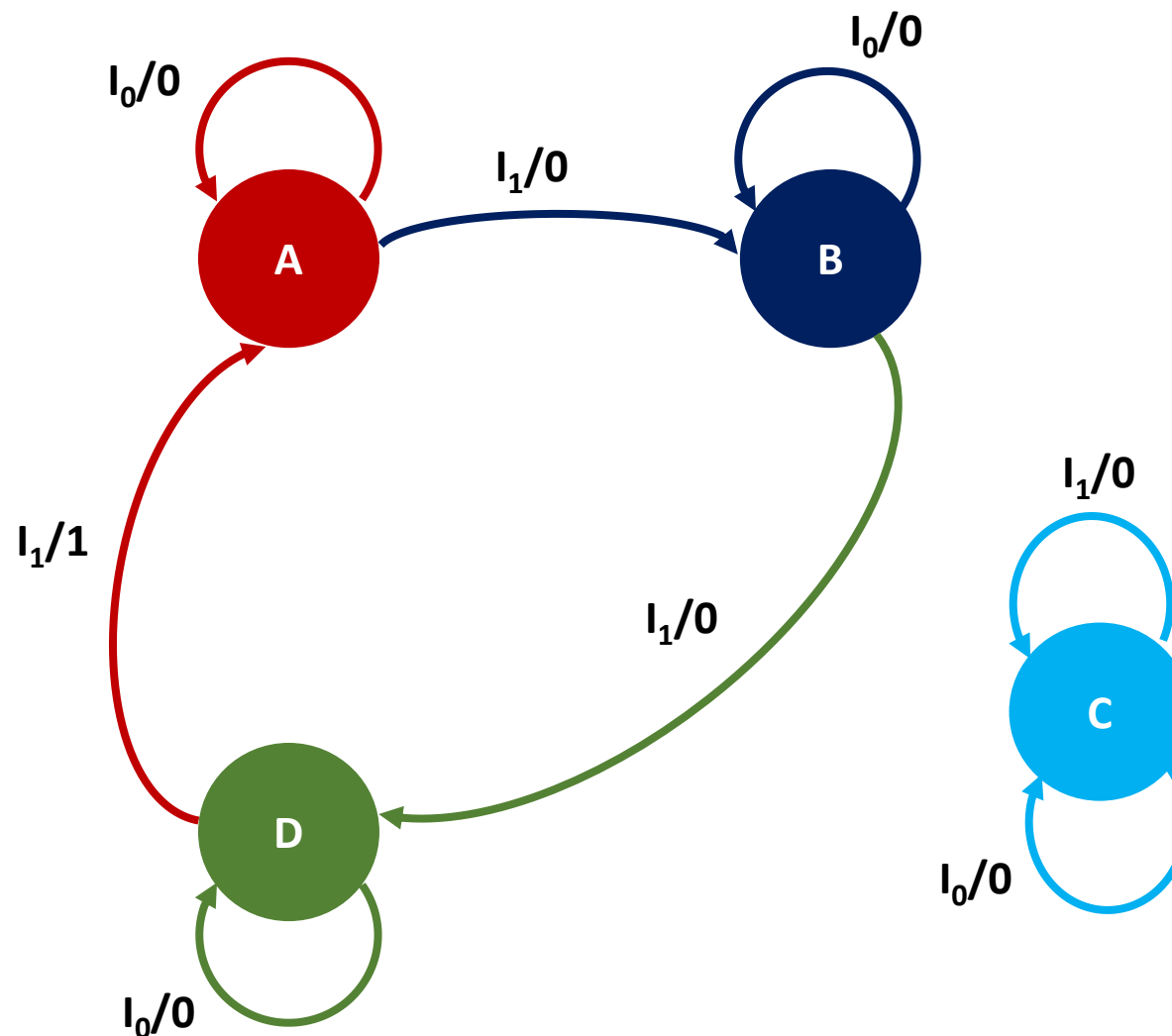


State Table and STG for Pulsed Sequential Circuit

Present state	I_0	I_1
A	A/0	B/0
B	B/0	D/0
C	C/0	C/0
D	D/0	A/1

Next State / Output

I_0 = no pulse on X
 I_1 = pulse on X



K-maps

Present state	I ₀	I ₁
A	A/0	B/0
B	B/0	D/0
C	C/0	C/0
D	D/0	A/1

For D1

y1y2	X=0	X=1
00	1	1
01	1	1
11	0	0
10	0	0

- Inputs:
 - I₀ = no pulse on X
 - I₁ = pulse on X
- States:
 - A = 00 (y1y2)
 - B = 01
 - C = 10
 - D = 11
- Outputs:
 - Z = 0
 - Z = 1

For C1

y1y2	X=0	X=1
00	0	0
01	0	1
11	0	1
10	0	0

For D2

y1y2	X=0	X=1
00	1	1
01	1	1
11	0	0
10	0	0

For C2

y1y2	X=0	X=1
00	0	1
01	0	1
11	0	1
10	0	1

For Y1

y1y2	X=0	X=1
00	0	0
01	0	1
11	1	0
10	1	1

For Y2

y1y2	X=0	X=1
00	0	1
01	1	1
11	1	0
10	0	0

For Z

y1y2	X=0	X=1
00	0	0
01	0	0
11	0	1
10	0	0

Design of Pulse Mode Asynchronous Circuits

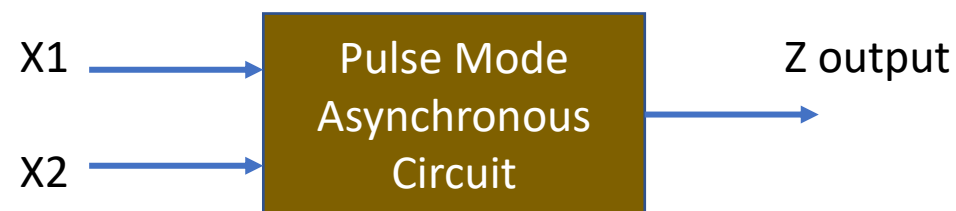
- To remember:
 - No clock is present
 - Inputs occur as pulses on any one input line at one time
 - Only un-complemented or complemented forms are used as inputs throughout
 - Triggering of Latches or flip flops is accomplished by utilizing information in input pulses

Design Steps in Pulse Mode Asynchronous

1. Derive a state diagram or a state table
2. Minimize the state table through State Reduction
3. Choose a state assignment and generate the transition/output table
4. Select the type of flipflop and determine the excitation equations
5. Determine the output equations
6. Choose appropriate circuit elements and draw the circuit diagram

Example – Design of Pulse Mode circuit

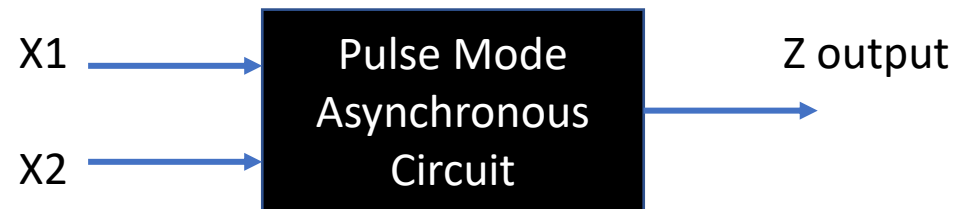
- Problem Statement: Design a pulse mode circuit that has two input lines, X1 and X2. There is one output line Z.
- The circuit should produce an output pulse to coincide with the last input pulse in the sequence X1 – X2 – X2 (Sequence Detector)
- No other input sequence should produce an output pulse



Block diagram of the desired system

Example – Pulse mode – Step 1

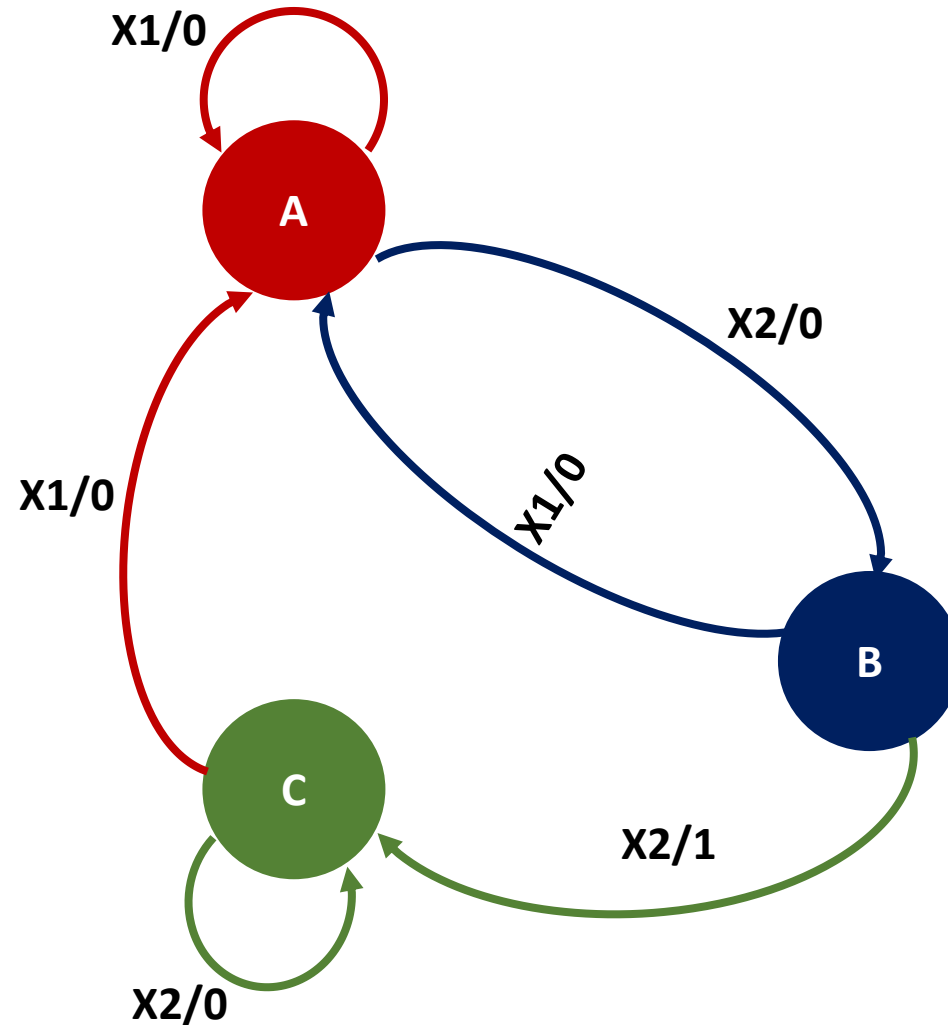
- Define the following three states of the circuit:
- A: indicates that the last input was X1
- B: indicates that the sequence X1 – X2 has occurred
- C: indicates that the sequence X1 – X2 – X2 has occurred



Block diagram of the desired system

Example – Pulse Mode – STG and State Table

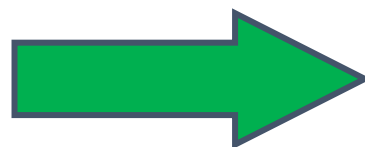
Present State	Next State/Output	
	When X1 appears	When X2 appears
A	A/0	B/0
B	A/0	C/1
C	A/0	C/0



Example Pulse Mode – State Assignments

Assign States: A=00, B=01, C=10 and generate the transition/output table

Present State	Next State/Output	
	When X1 appears	When X2 appears
A	A/0	B/0
B	A/0	C/1
C	A/0	C/0



Present State	Next State/Output Y1Y2/Z	
	When X1 appears	When X2 appears
00	00/0	01/0
01	00/0	10/1
10	00/0	10/0

Example – Pulse mode implement using T FF

State Table for Y1

Present State	Next State/Output Y1Y2/Z	
y1y2	When X1 appears	When X2 appears
00	00/0	01/0
01	00/0	10/1
10	00/0	10/0

Present State	Next State	
y1y2	X1	X2
00	0	0
01	0	1
11	d	d
10	0	1

State Table for T1

Present State	Next State Y1, Y2	
y1y2	When X1	When X2
00	0	0
01	0	1
11	d	d
10	1	0

$$T1 = X1.y1 + X2.y2$$

Example – Pulse Mode Implement using TFF (contd)

Present State	Next State/Output Y1Y2/Z	
y1y2	When X1 appears	When X2 appears
00	00/0	01/0
01	00/0	10/1
10	00/0	10/0

State Table for Y2

Present State	Next State	
y1y2	When X1	When X2
00	0	1
01	0	0
11	d	d
10	0	0

State Table for T2

Present State	Next State	
y1y2	When X1	When X2
00	0	1
01	1	1
11	d	d
10	0	0

State Table for Z output

Present State	Next State	
y1y2	When X1	When X2
00	0	0
01	0	1
11	d	d
10	0	0

$$T2 = X1.y2 + X2.y1'$$

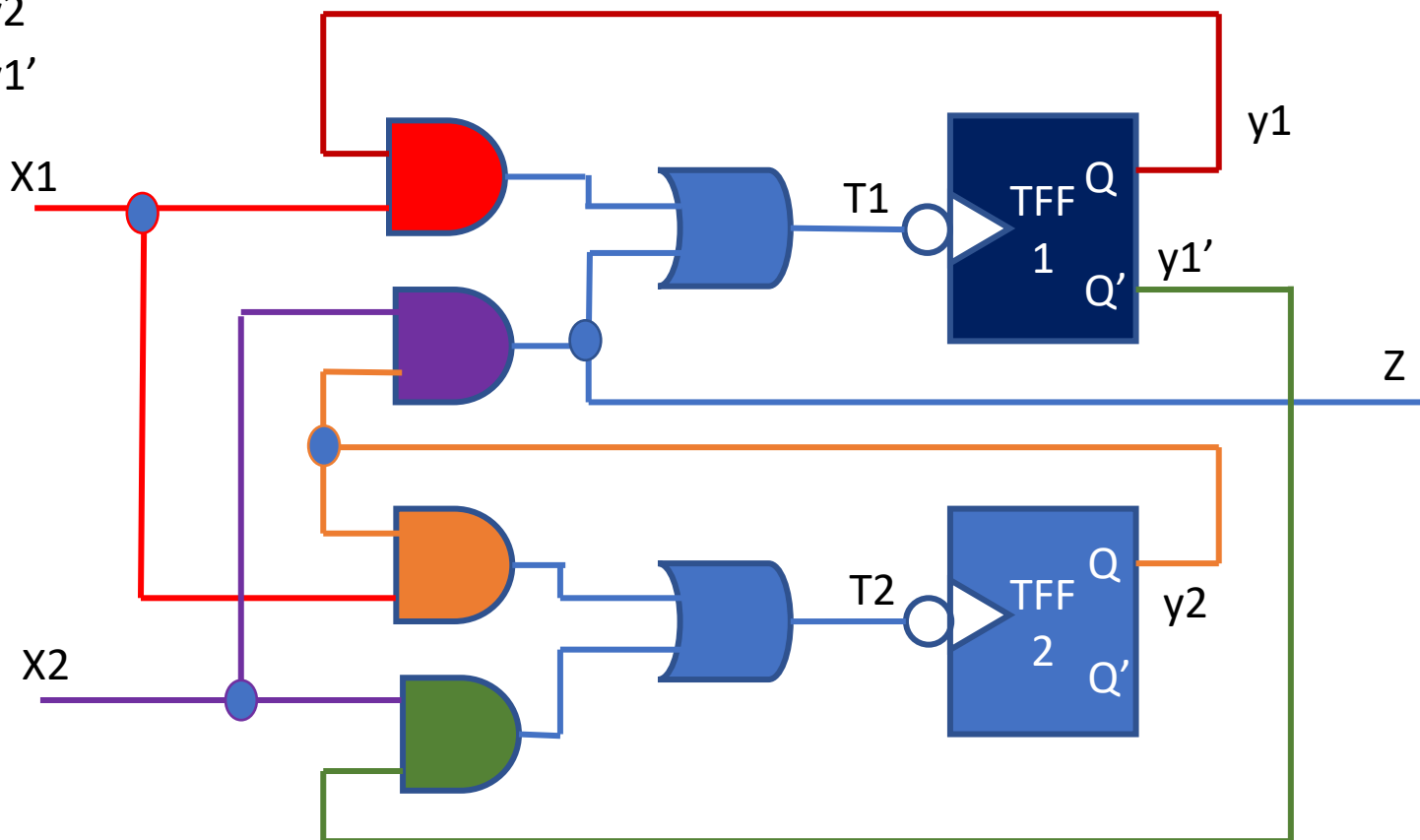
$$Z = X2.y2$$

Example – Pulse mode Circuit diagram

$$T1 = X1.y1 + X2.y2$$

$$T2 = X1.y2 + X2.y1'$$

$$Z = X2.y2$$



T1, T2 are in toggle mode
Toggle Input is enabled to '1'