

Fuzzy Logic Toolbox

Analysis and Design

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Matlab Fuzzy Toolbox

- Matlab Fuzzy Toolbox consist of two useful tools:

- FIS Editor:

This Editor in combination with 4 other editors provides a powerful environment to define and modify Fuzzy Inference System (FIS) variable

- Fuzzy Controller:

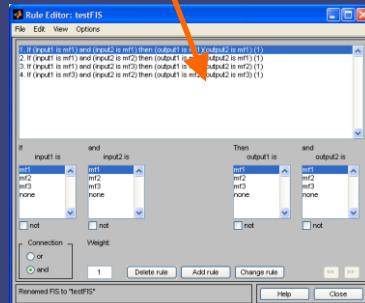
This is a block in fuzzy Toolbox Library in Simulink environment. This block admits FIS variable produced by FIS Editor and implements the desirable rules

Fuzzy Inference System

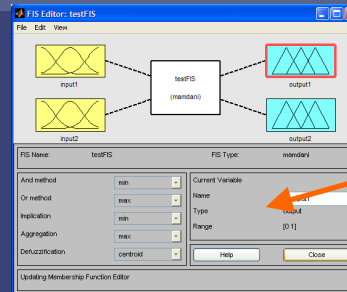
FIS Editor

IF-THEN rules
Define/Modify

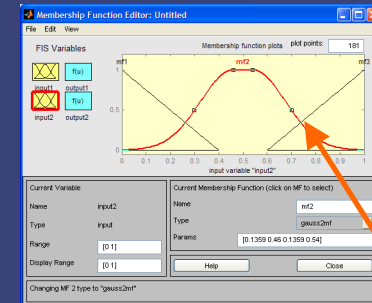
Rule Editor



Change and Modify
Inference Settings

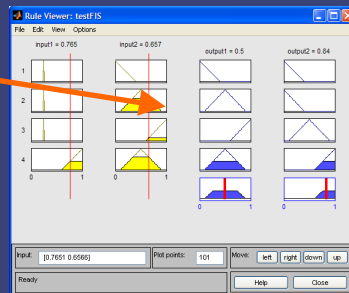


Membership Function Editor

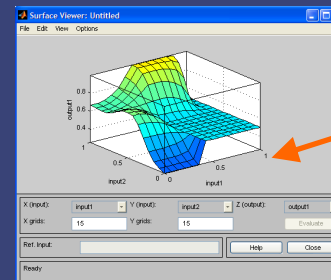


Modifying Input/Output
Membership functions

Easy test for
Input/Output
Relationship



Rule Viewer



Surface Viewer

Visualization of
Membership Func.
in 2 input system

FIS Diagram

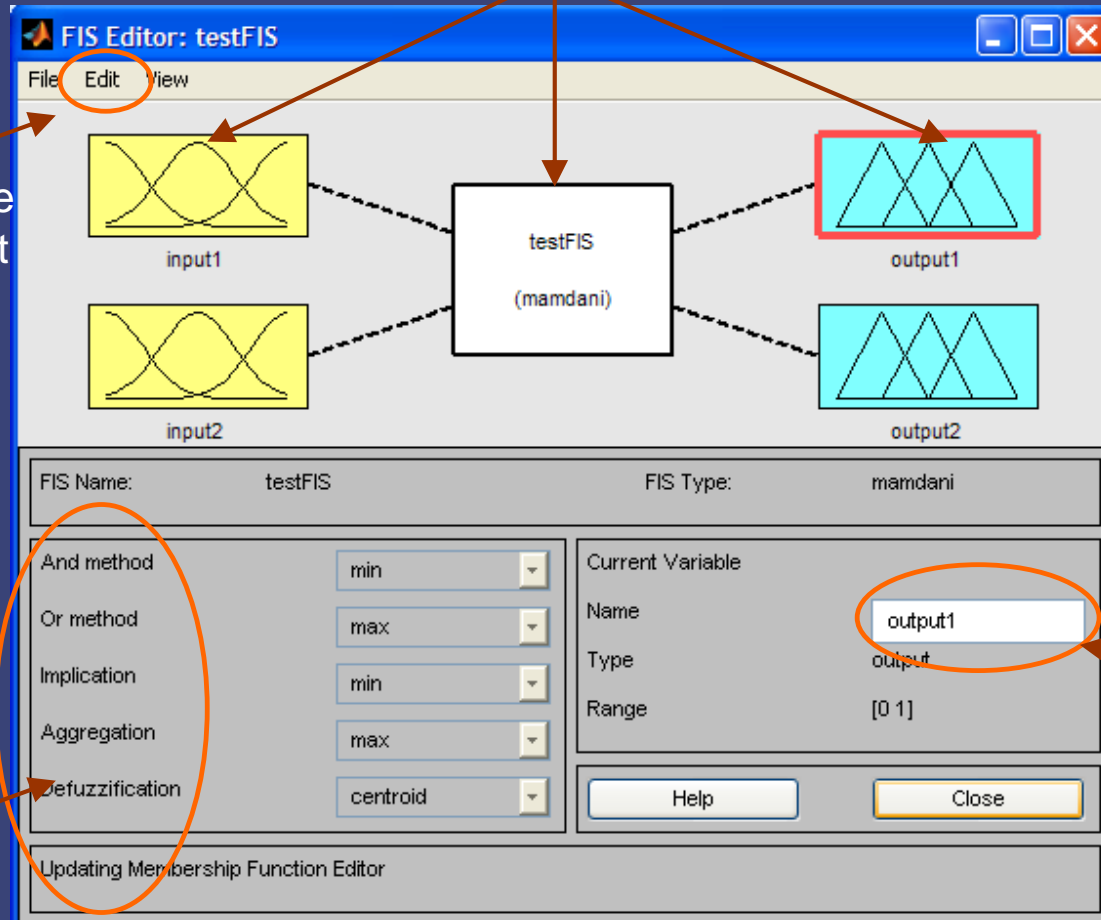
- To implement a Fuzzy inference system, five steps must be followed:
 1. Fuzzyfication using input membership functions
 2. Apply Fuzzy Operand
 3. Apply Implication method on each rule
 4. Aggregate all Outputs
 5. Defuzzification of output set

FIS Editor

Double click to load other Editors

Add or Remove
Input or Output

Set or
Modify
Inference
settings



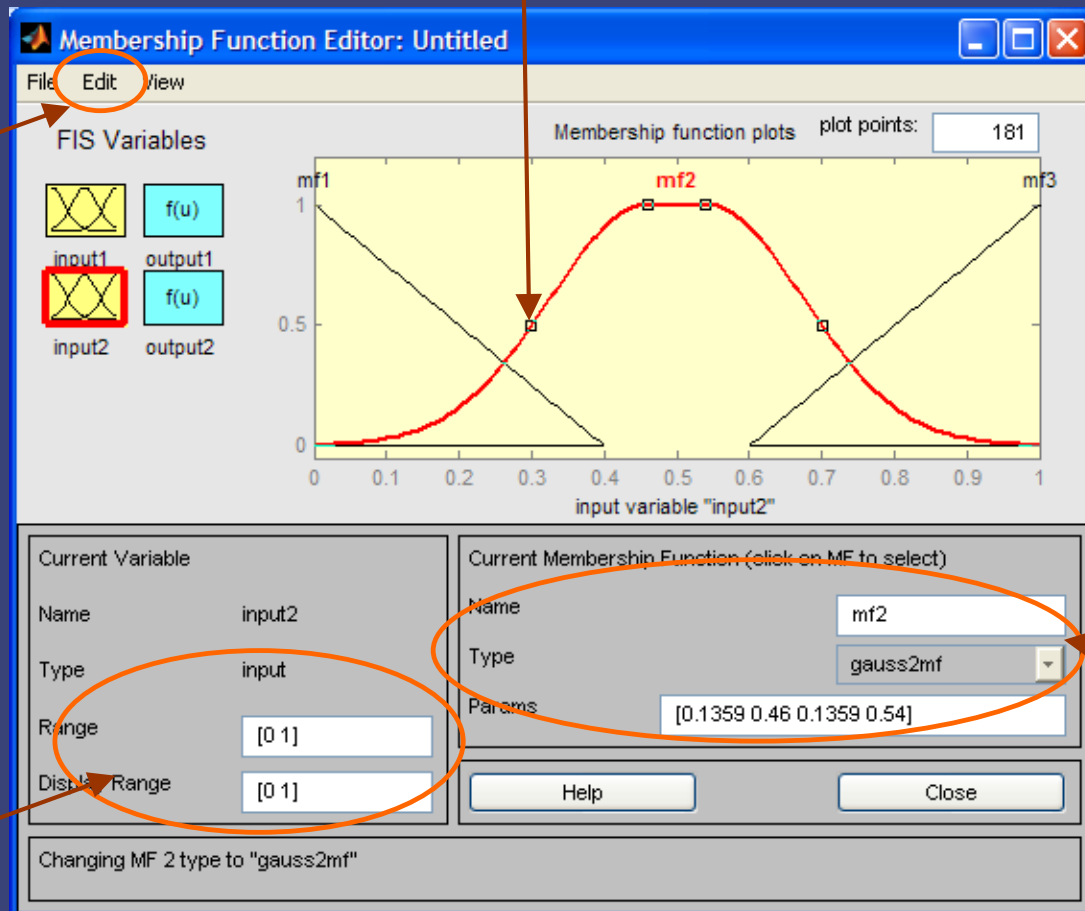
Change name of
Input or Output

Membership Function Editor

Change parameter by dragging and scrolling

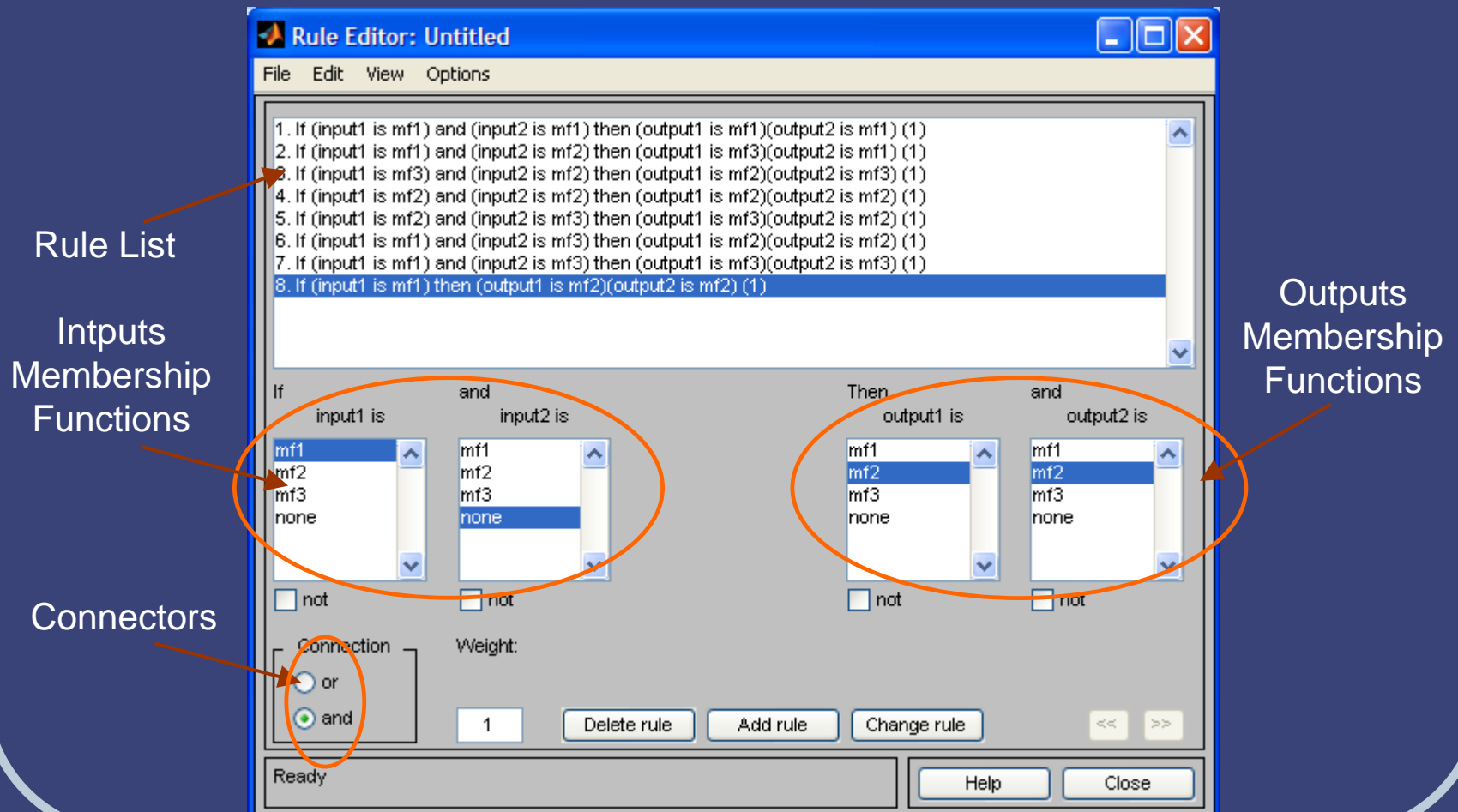
Add or Remove Membership Functions to or from any Input or Output

Change Input or Output range

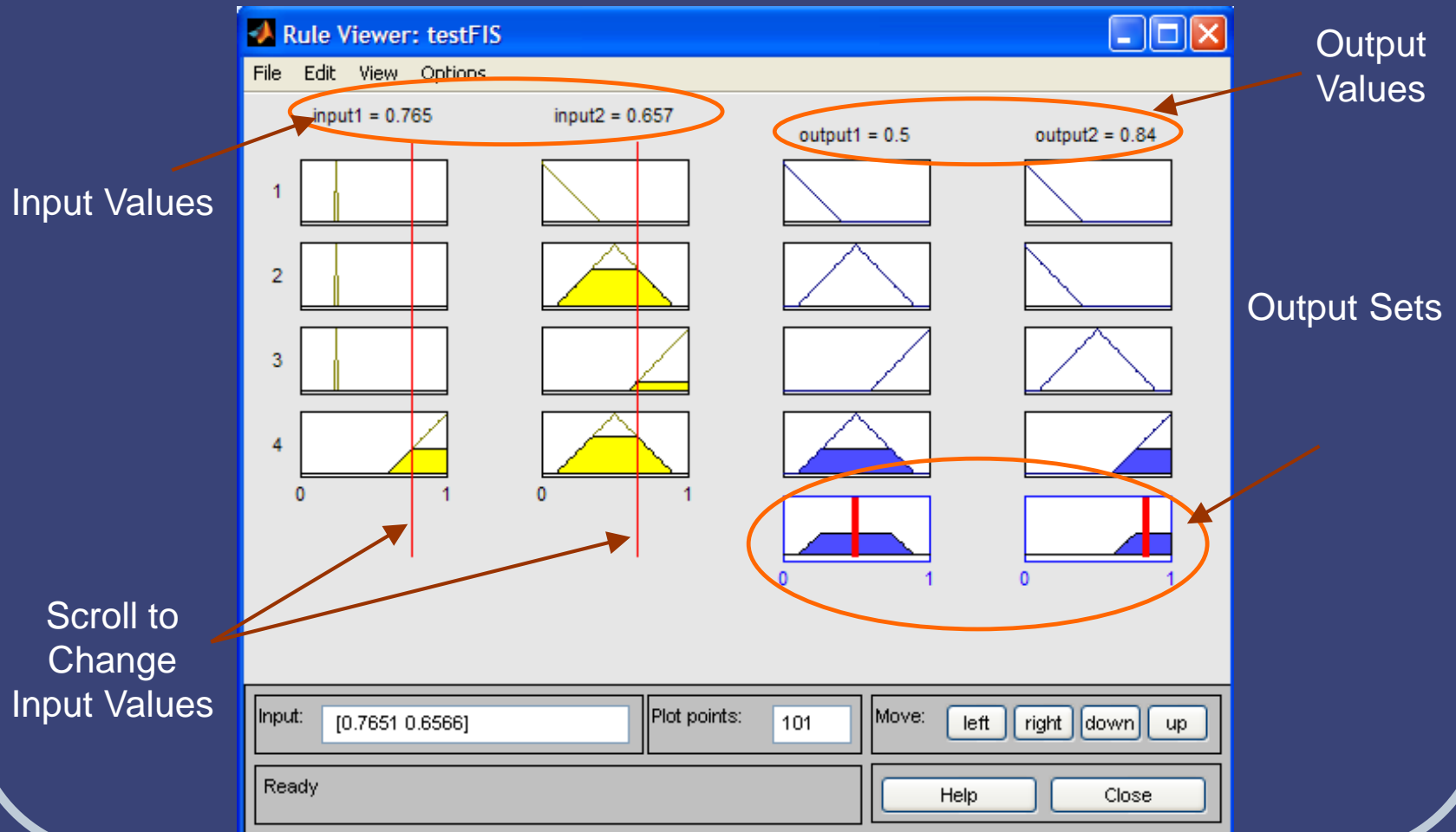


Set Membership Function parameters manually

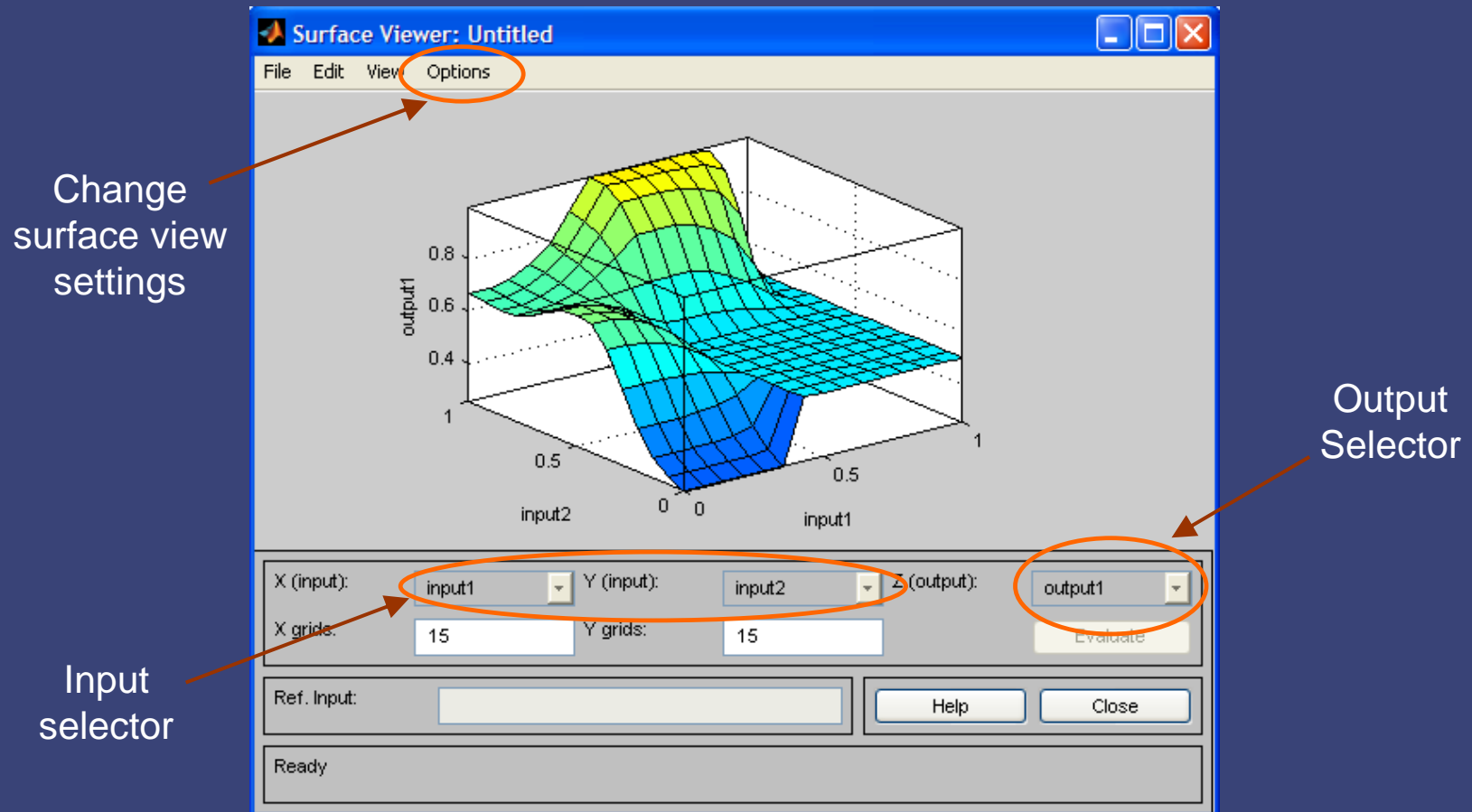
Rule Editor



Rule Viewer



Surface Viewer



FIS Editor Benefits

- Easily Define and modify a Fuzzy system
 - Simply Add or Remove Inputs and/or Outputs
 - Set or modify Inference methods
 - Simply Add or Remove Membership functions and easy management of function's parameters
 - Easy Rule definition and modification
 - Great Visualization area for FIS Diagram
 - 2-D visualization of Inference for any Input pairs to any Output
- Offers two Inference Engines
 - Mandani
 - Sugeno in which rule syntaxes became:

$$R^k : \text{If } \mathbf{x} \text{ is } A^k \text{ then } y = c^k, \quad k = 1, 2, \dots, K$$

ANFIS Editor

The screenshot shows the ANFIS Editor window titled "Anfis Editor: Untitled2". It features a menu bar (File, Edit, View), a central plot area, and several control panels. Annotations with arrows point to specific components:

- Input Data and Trained results:** Points to the central plot area showing training data (blue 'o') and FIS output (red '*').
- Data to be loaded:** Points to the "Load data" panel, specifically the "Training" radio button and the "worksp." option under "From:".
- Training Parameters:** Points to the "Train FIS" panel, specifically the "hybrid" option in the "Optim. Method:" dropdown and the "Error Tolerance:" input field.

Plot Data:

Index	Output
1	1.0
2	0.25
3	0.0
4	0.25
5	1.0

ANFIS Info.:

- # of inputs: 1
- # of outputs: 1
- # of input mfs: 5

Load data:

- Type: ☒ Training, ☐ Testing, ☐ Checking, ☐ Demo
- From: ☐ disk, ☒ worksp.
- Buttons: Load Data..., Clear Data

Generate FIS:

- ☐ Load from disk
- ☐ Load from worksp.
- ☒ Grid partition
- ☐ Sub. clustering
- Button: Generate FIS ...

Train FIS:

- Optim. Method: hybrid (dropdown)
- Error Tolerance: 0 (input field)
- Epochs: 3 (input field)
- Button: Train Now

Test FIS:

- Plot against: ☒ Training data, ☐ Testing data, ☐ Checking data
- Button: Test Now

Status Bar:

- Average testing error: 6.3702e-007
- Buttons: Help, Close