Introduction to TensorFlow and Keras

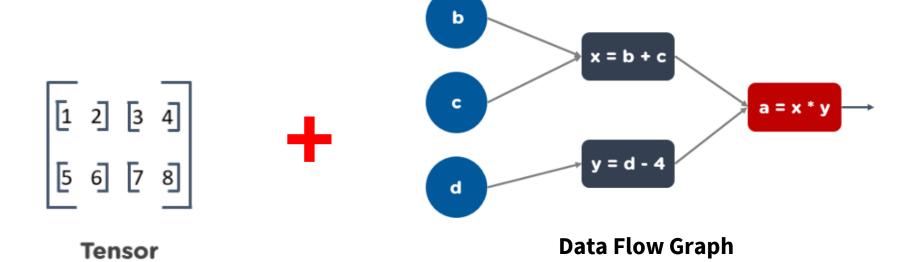


What are TensorFlow?

TensorFlow is general purpose **Python programming language** based open-source end-to-end platform Developed by Google Brain Team for creating **Machine Learning applications**.

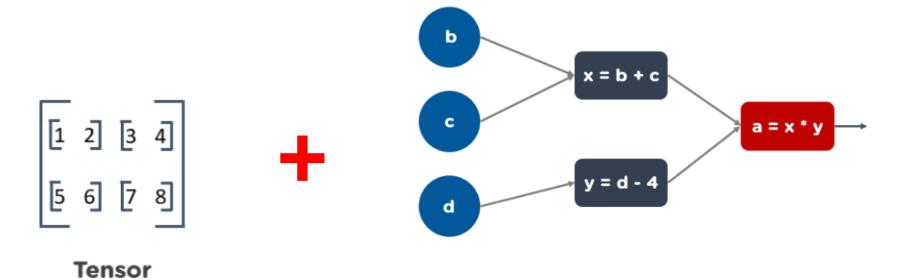
It is one of the most popular programming platform for high dimensional computation and implementing complex deep learning models.

TensorFlow





Tensor + Data Flow Graph



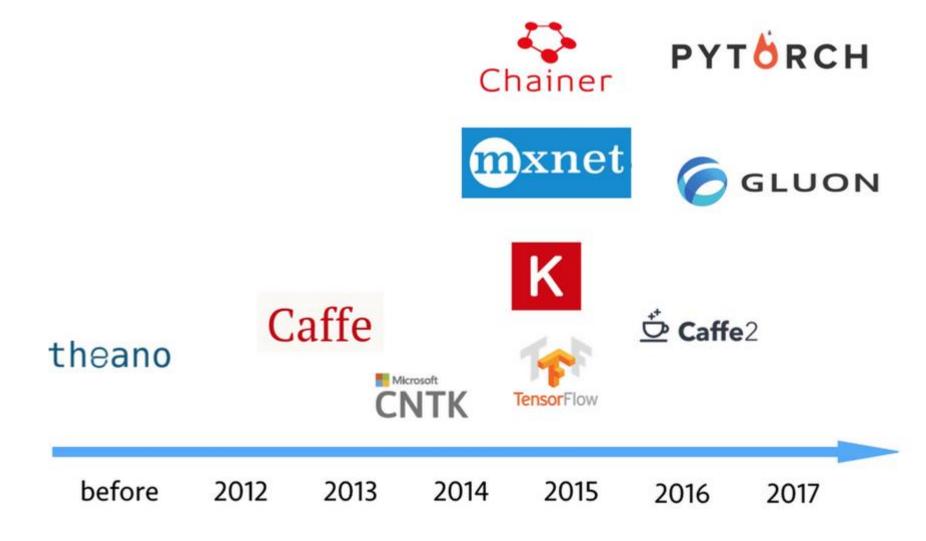
TensorFlow 2.0

- Eager execution, allowing to build the models and run instantly.
- Keras, high-level API for different Deep Learning Models, is incorporated with TensorFlow 2.0.
- Using Keras API, building complex deep learning models becomes a trivial task
- The size of the program becomes much smaller in 2.0 as compared to 1.0





Different Deep Learning Frameworks



However, because of open source availability, easy to use, and high portability other programming platforms, we will be using TensorFlow and Keras.

At the end of this module, you will learn

- How to write algebraic programs using TensorFlow?
- How to visualize the computational flow using Data Flow Graph
- How to implement neural networks?
- How to estimate parameters?
- How to simplify implementation of neural models using Keras?

Lesson 15

What are Tensor?

What are Tensors?

Wikipedia:

A **tensor** is an algebraic object that describes a multilinear relationship between sets of algebraic objects related to a vector space.

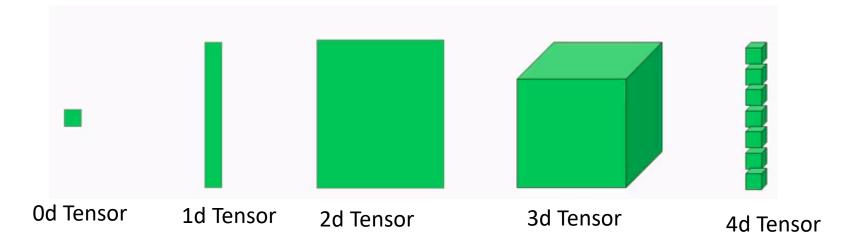
In short, tensors are generalization of scalars and vectors

What are Tensors?

Wikipedia:

A **tensor** is an algebraic object that describes a multilinear relationship between sets of algebraic objects related to a vector space.

In short, tensors are generalization of scalars data and vectors.





Rank = 0

Shape = (0)

(10)

Scalar

Rank = 0

Shape = (0)

1

2

3

Vector

Rank = 1

Shape = (3)

(10)

Scalar

Rank = 0

Shape = (0)

1

2

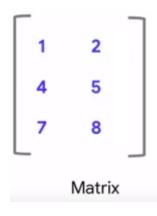
3

Vector

Rank = 1

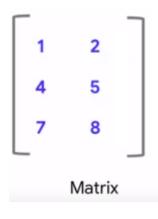
Shape = (3)

3 number of Rank 0 tensors

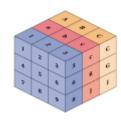


Rank = 2 Shape = (3x2) 3 number of Rank 1 tensors of shape 2

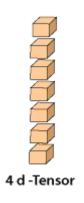
Rank = 3



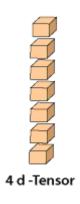
Rank = 2 Shape = (3x2) 3 number of Rank 1 tensors of shape 2



Shape = (3x3x3) 3 number of Rank 2 tensors of shape 3x3

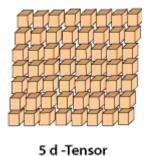


Rank = 4Shape = (7x3x3x3) 7 number of Rank 3 tensors of shape 3x3x3



Rank = 4

Shape = (7x3x3x3) 7 number of Rank 3 tensors of shape 3x3x3



Rank = 5

Shape = (7x8x3x3x3) 7 number of Rank 4 tensors of shape 8x3x3x3

```
import tensorflow as tf

t = tf.constant(4)
print(t)
tf.Tensor(4, shape=(), dtype=int32)
```

```
import tensorflow as tf

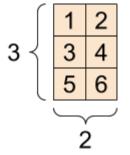
t = tf.constant(4)
print(t)
tf.Tensor(4, shape=(), dtype=int32)
```

import tensorflow as tf

t = tf.constant([2.0, 3.0, 4.0])
print(t)

tf.Tensor([2. 3. 4.], shape=(3,), dtype=float32)

tf.Tensor([[1 2] [3 4] [5 6]], shape=(3, 2), dtype=float16

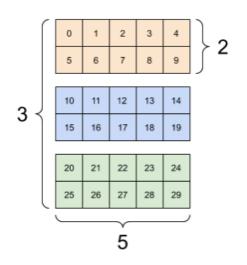


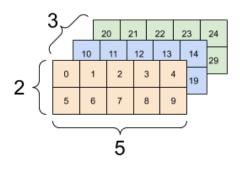
No. of rows = 3

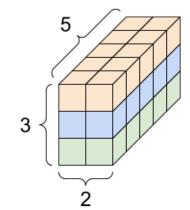
No. of Columns = 2

import tensorflow as tf t = tf.constant([[0, 1, 2, 3, 4],[5, 6, 7, 8, 9]], [[10, 11, 12, 13, 14], [15, 16, 17, 18, 19]], [[20, 21, 22, 23, 24], [25, 26, 27, 28, 29]] print(t)

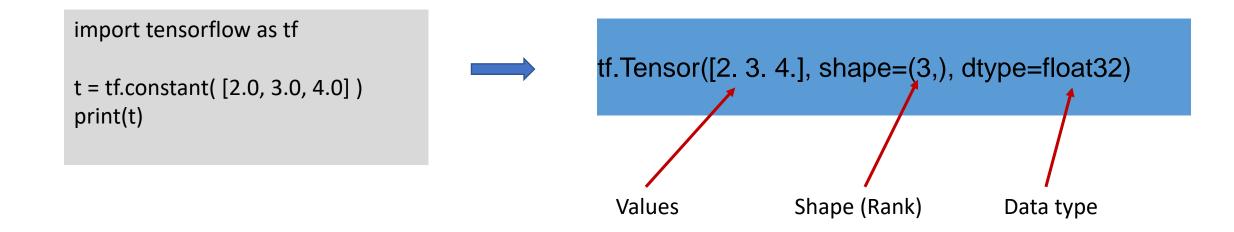
tf.Tensor([[[0 1 2 3 4] [5 6 7 8 9]] [[10 11 12 13 14] [15 16 17 18 19]] [[20 21 22 23 24] [25 26 27 28 29]]], shape=(3, 2, 5), dtype=int32)







Components of a Tensor?



Summary

- What are Tensors?
- Different types of Tensors
- Rank of a Tensor
- Shape of a Tensor
- Components of a Tensor

Lesson 17:

Arithmetic Operations on Tensors

Operations between two Tensors

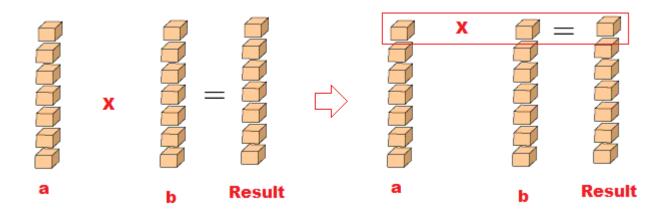
Given two tensors x and y,

- Arithmetic operations such as plus, minus, multiplication, division can be performed between x and y, and produce another tensor.
 - x + y, x-y, x*y, x/y
- To perform a binary operation between two tensors, the shape of the two should be compatible.
- Element wise operations between the two tensors are performed.

Operations between two Tensors

Given two tensors x and y,

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 - x + y, x-y, x*y, x/y
- To perform a binary operation between two tensors, the shape of the two should be compatible.
- Element wise operations between the two tensors are performed.



```
X (1d array): 3
Y (1d array 1
```

Result (1d array): 3

X (1d array): 3 [1, 2, 3]

Y (1d array 1 2

Result (1d array): 3

X (1d array): 3 [1, 2, 3]

Y (1d array 1 2

Result (1d array): 3

TensorFlow performs broadcast of the lower shape tensor.

It means, the low dimensional tensor is replicated till we find the matching shape

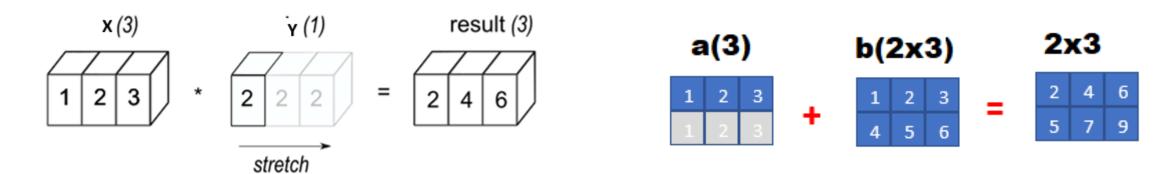
X (1d array): 3 [1, 2, 3]

Y (1d array 1 2

Result (1d array): 3

TensorFlow performs broadcast of the lower shape tensor.

It means, the low dimensional tensor is replicated till we find the matching shape



Two Sides Broadcast (Stretch)

X (1d array): 3

Y (2d array): 3 x 1

Result (2d array): 3 x 3

1	2	3
1	2	3
1	2	3

4	4	4
5	5	5
6	6	6

5	6	7
6	7	8
7	8	9

Lesson 18: Compatibility between two tensors

Compatibility of two Tensors for Arithmetic Operation

Two tensors x and y are said to be compatible if

Compatibility of two Tensors for Arithmetic Operation

Two tensors x and y are said to be compatible if

- Their dimensions and shapes are same
 - Dimension(x) = Dimension(y)
 - Shape(x) = Shape(y)

1	2	3	_	1	2	3	_	2	4	6
1	2	3	+	4	5	б	_	5	7	9

X (2d array): 2 x 4

Y (2d array): 2 x 4

Result (2d array): 2 x 4

Compatibility of two Tensors for Arithmetic Operation

Two tensors x and y are said to be compatible if

- Their dimensions and shapes are same
 - Dimension(x) = Dimension(y)
 - Shape(x) = Shape(y)

- X (2d array): 2 x 4
- Y (2d array): 2 x 4
- Result (2d array): 2 x 4
- Their dimensions or shapes are different, but the following condition is satisfied.
 - For all dimension position, one of component dimension has shape 1.

```
X (2d array): 2 x 1
```

Y (2d array): 2 x 4

Result (2d array): 2 x 4

Two tensors x and y are said to be compatible if

- Their dimensions and shapes are same
 - Dimension(x) = Dimension(y)
 - Shape(x) = Shape(y)

Result (2d array): 2 x 4

```
X (2d array): 2 x 4
```

Y (2d array): 2 x 4

Result (2d array): 2 x 4

Their dimensions or shapes are different, but the following condition is satisfied.

Result (3d array): $2 \times 4 \times 3$

For all dimension position, one of component dimension has shape 1.

```
X (2d array): 2 x 1 X (3d array): 2 x 1 x 3
Y (2d array): 2 x 4 Y (3d array): 2 x 4 x 1
```

Two tensors x and y are said to be compatible if

- Their dimensions and shapes are same
 - Dimension(x) = Dimension(y)
 - Shape(x) = Shape(y)

- X (2d array): 2 x 4
- Y (2d array): 2 x 4
- Result (2d array): 2 x 4
- Their dimensions or shapes are different, but the following condition is satisfied.
 - For all dimension position, one of component dimension has shape 1.

```
X (2d array): 2 x 1 X (3d array): 2 x 1 x 3 X (3d array): 2 x 1 x 3

Y (2d array): 2 x 4 Y (3d array): 2 x 4 x 1 Y (3d array): 1 x 4 x 1

Result (2d array): 2 x 4 Result (3d array): 2 x 4 x 3 Result (3d array): 2 x 4 x 3
```

Two tensors x and y are said to be compatible if

- Their dimensions and shapes are same
 - Dimension(x) = Dimension(y)
 - Shape(x) = Shape(y)

- X (2d array): 2 x 3
 - Y (2d array): 2 x 4
- Result (2d array): 2 x 4
- Their dimensions and/or shapes are different, but the following condition is satisfied.
 - For all dimension position, one of component dimension has shape 1.

```
a: (2d array): 256 x 3
b: (1d array): 3
Result: (2d array): 256 x 3
```

Two tensors x and y are said to be compatible if

- Their dimensions and shapes are same
 - Dimension(x) = Dimension(y)
 - Shape(x) = Shape(y)

- X (2d array): 2 x 3
- Y (2d array): 2 x 4
- Result (2d array): 2 x 4
- Their dimensions and/or shapes are different, but the following condition is satisfied.
 - For all dimension position, one of component dimension has shape 1.

```
a: (2d array): 256 x 3
b: (1d array): 3
We assume that, we have default 1.

Result: (2d array): 256 x 3
(3) ~ (1 x 3)
(2 x 3) ~ (1 x 2 x 3)
```

Two tensors x and y are said to be compatible if

- Their dimensions and shapes are same
 - Dimension(x) = Dimension(y)
 - Shape(x) = Shape(y)

```
X (2d array): 2 x 3
Y (2d array): 2 x 4
```

Result (2d array): 2 x 4

- Their dimensions and/or shapes are different, but the following condition is satisfied.
 - For all dimension position, one of component dimension has shape 1.

Two tensors x and y are said to be compatible if

- Their dimensions and shapes are same
 - Dimension(x) = Dimension(y)
 - Shape(x) = Shape(y)

- X (2d array): 2 x 3 Y (2d array): 2 x 4
- Result (2d array): 2 x 4
- Their dimensions and/or shapes are different, but the following condition is satisfied.
 - For all dimension position, one of component dimension has shape 1.

```
A (4d array): 8 x 1 x 6 x 1
B (3d array): 7 x 1 x 5
Result (4d array): 8 x 7 x 6 x 5
```

The resultant dimension is

- Higher dimension
- Higher shape of the component dimensions

They are not compatible

```
A (1d array): 3
B (1d array): 4 # trailing dimensions do not match

A (2d array): 2 x 1
B (3d array): 8 x 4 x 3 # second from last dimensions mismatched
```

Summary

- Operations are performed element wise.
- If the shapes between the two tensors are different, but compatible, the tensor with smaller shape is stretched.

Lesson 18: More on Tensor

Variable Tensor

A variable tensor is created using **tf.Variable()** function.

Syntax: tf.Variable(initial_value=None, trainable=None, validate_shape=True, caching_device=None, name=None, variable_def=None, dtype=None, import_scope=None, constraint=None, synchronization=tf.VariableSynchronization.AUTO, aggregation=tf.compat.v1.VariableAggregation.NONE, shape=None)

- *initial_value*: by default None. The initial value for the Variable is a Tensor, or a Python object convertible to a Tensor.
- trainable: by default None. If True, GradientTapes will keep an eye on this variable's usage.
- **validate_shape**: by default True. Allows the variable to be initialised with an unknown shape value if False. The shape of initial value must be known if True, which is the default.
- name:by default None. The variable's optional name. Defaults to 'Variable' and is automatically uniquified.
- variable_def: by default None.
- **dtype:** by default None. If set, initial_value will be converted to the given type. If None, either the datatype will be kept (if initial_value is a Tensor), or convert_to_tensor will decide.
- **shape:** by default None. if None the shape of initial_value will be used. if any shape is specified, the variable will be assigned with that particular shape.

Few examples of Variable Tensor

```
import tensorflow as tf x = \text{tf.Variable}([1, 2, 3, 4]) x = \text{tf.Variable}([1.2, 4.4, 5, 6]) x = \text{tf.Variable}(['a', 'b', 'c', 'd']) x = \text{tf.Variable}([True, False]) x = \text{tf.Variable}([3 + 4j])
```

Find the attributes of Tensor

```
x = tf.Variable([1,2,3,4])
print(x.name)

print(x.shape)

print(x.dtype)

print(x.numpy())

Variable:0
(4,)
<dtype: 'int32'>
[1 2 3 4]
```

```
x = tf.Variable([[1,2,3,4],[5,6,7,8]])
print(x.name)

print(x.shape)

print(x.dtype)

print(x.numpy())

Variable:0
(2, 4)
<dtype: 'int32'>
[[1 2 3 4]
```

[5 6 7 8]]

Find the attributes of Tensor

```
x = tf.Variable([1,2,3,4])
print(x.name)

print(x.shape)

print(x.dtype)

print(x.numpy())
```

```
Variable:0
(4,)
<dtype: 'int32'>
[1 2 3 4]
```

Constant tensor can be converted to Variable tensor

```
x_con = tf.constant([1,2,3,4])
x_var = tf.Variable(t_con)
print(x_var)
<tf.Variable 'Variable:0' shape=(4,) dtype=int32, numpy=array([1, 2, 3, 4])>
```

Variable tensor can be converted to Constant tensor

```
x_var = tf.Variable([1,2,3,4])
x_con = tf.constant(x_var)
print(x_con)

tf.Tensor([1 2 3 4], shape=(4,), dtype=int32)
```

Include data type as parameter

```
x = tf.constant([1,2,3,4], dtype=tf.float32)
print(x)

tf.Tensor([1. 2. 3. 4.], shape=(4,), dtype=float32)
```

Lesson 20

```
x = tf.constant([1,2,3,4,5,6])
print(x)

tf.Tensor([1 2 3 4 5 6], shape=(6,), dtype=int32)
```

[1, 2, 3, 4, 5, 6]

```
x = tf.constant([1,2,3,4,5,6])
print(x)

tf.Tensor([1 2 3 4 5 6], shape=(6,), dtype=int32)

x = tf.constant([1,2,3,4,5,6], shape=(2,3))
print(x)

tf.Tensor(
[[1 2 3]
  [4 5 6]], shape=(2, 3), dtype=int32)
```

```
[1, 2, 3, 4, 5, 6]
```

```
[ 1, 2, 3]
[ 4, 5, 6]
```

```
x = tf.constant([1,2,3,4,5,6])
print(x)

tf.Tensor([1 2 3 4 5 6], shape=(6,), dtype=int32)

x = tf.constant([1,2,3,4,5,6], shape=(2,3))
print(x)

tf.Tensor(
[[1 2 3]
  [4 5 6]], shape=(2, 3), dtype=int32)
```

```
[1, 2, 3, 4, 5, 6]
```

```
[ 1, 2, 3]
[ 4, 5, 6]
```

```
[ 1, 2]
[ 3, 4]
[ 5, 6]
```

```
x = tf.constant([1,2,3,4,5,6])
print(x)
tf.Tensor([1 2 3 4 5 6], shape=(6,), dtype=int32)
                                                                   [1, 2, 3]
x = tf.constant([1,2,3,4,5,6], shape=(2,3))
                                                                   [4, 5, 6]
print(x)
tf.Tensor(
[[1 2 3]
  [4 5 6]], shape=(2, 3), dtype=int32)
                                                                   [1, 2]
tf.reshape(x, (3,2))
                                                                   [3, 4]
<tf.Tensor: shape=(3, 2), dtype=int32, numpy=
                                                                   [5, 6]
array([[1, 2],
       [3, 4],
        [5, 6]])>
```

```
[1, 2, 3, 4, 5, 6]
```

Flatten the tensor

```
[ 1, 2, 3, 4]
[ 5, 6, 7, 8]
```

```
x = tf.constant([[1,2,3,4],[5,6,7,8]], shape=(8))
print(x)
```

```
tf.Tensor([1 2 3 4 5 6 7 8], shape=(8,), dtype=int32)
```

Flatten the tensor

```
[ 1, 2, 3, 4]
[ 5, 6, 7, 8]
```

```
x = tf.constant([[1,2,3,4],[5,6,7,8]], shape=(8))
print(x)
```

tf.Tensor([1 2 3 4 5 6 7 8], shape=(8,), dtype=int32)

```
x = tf.constant([[1,2,3,4],[5,6,7,8]])
tf.reshape(x, (8))
<tf.Tensor: shape=(8,), dtype=int32, numpy=array([1, 2, 3, 4, 5, 6, 7, 8])>
```

Reshape the tensor with (-1)

```
x = tf.constant([[1,2,3,4],[5,6,7,8]])
print(x)

tf.Tensor(
[[1 2 3 4]
  [5 6 7 8]], shape=(2, 4), dtype=int32)
```

```
[ 1, 2, 3, 4]
[ 5, 6, 7, 8]
```

```
tf.reshape(x, (-1))
<tf.Tensor: shape=(6,), dtype=int32, numpy=array([1, 2, 3, 4, 5, 6])>
```

[1, 2, 3, 4, 5, 6, 7, 8]

```
[ 1, 2, 3, 4]
[ 5, 6, 7, 8]
```

```
[ 1, 2]
[ 3, 4]
[ 5, 6]
[ 7, 8]
```

```
[ [ 1, 2]
[ 3, 4] ]
[ [ 5, 6]
[ 7, 8] ]
```

```
x = tf.constant([1,2,3,4,5,6,7,8])
tf.reshape(x, (2,-1,2))
<tf.Tensor: shape=(2, 2, 2), dtype=int32, numpy=
array([[[1, 2],
        [3, 4]],
       [[5, 6],
        [7, 8]]])>
x = tf.constant([[1,2,3,4],[5,6,7,8]])
tf.reshape(x, (-1,2,2))
<tf.Tensor: shape=(2, 2, 2), dtype=int32, numpy=
array([[[1, 2],
        [3, 4]],
       [[5, 6],
       [7, 8]]])>
```

```
[ [ 1, 2]
[ 3, 4] ]
[ [ 5, 6]
[ 7, 8] ]
```

```
[ [ 1, 2]
[ 3, 4] ]
[ [ 5, 6]
[ 7, 8] ]
```

Summary

We have learnt

- How to create a variable tensor?
- How to convert a constant tensor to a variable tensor, and vice versa?
- How to reshape a tensor?

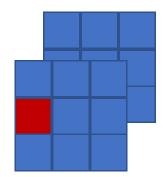
Lesson 22: Accessing the element of a Tensor

tf.slice(<input>,<begin>,<size>)

•input: Tensor

begin: starting location for each dimension of input

•size: number of elements for each dimension of input, using -1 includes all remaining elements



Shape: [2, 3, 3]

Begin: [0, 1, 0]

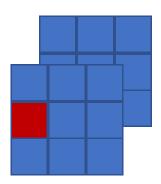
Size: [1, 1, 1]

tf.slice(<input>,<begin>,<size>)

•input: Tensor

begin: starting location for each dimension of input

•size: number of elements for each dimension of input, using -1 includes all remaining elements



Shape: [2, 3, 3]

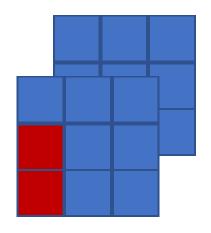
Begin: [0, 1, 0]

Size: [1, 1, 1]

```
tf.Tensor(
[[[ 1.  2.  3.]
  [ 4.  5.  6.]
  [ 7.  8.  9.]]

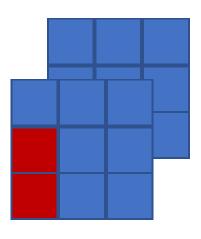
[[10. 11. 12.]
  [13. 14. 15.]
  [16. 17. 18.]]], shape=(2, 3, 3), dtype=float32)

tf.Tensor([[[4.]]], shape=(1, 1, 1), dtype=float32)
```

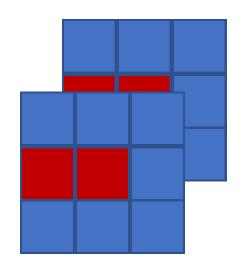


Shape: [2, 3, 3]

Begin: [0, 1, 0]

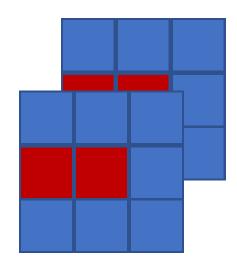


```
import tensorflow as tf
x = tf.constant([[[1., 2., 3.], [4., 5., 6], [7., 8., 9]]),
                [[10., 11.,12], [13., 14., 15], [16., 17., 18]]])
print(x)
res = tf.slice(x, [0, 1, 0], [1, 2, 1])
print("\n")
print(res)
tf.Tensor(
[[[ 1. 2. 3.]
 [ 4. 5. 6.]
  [7. 8. 9.]]
 [[10. 11. 12.]
 [13. 14. 15.]
  [16. 17. 18.]]], shape=(2, 3, 3), dtype=float32)
tf.Tensor(
[[[4.]
 [7.]]], shape=(1, 2, 1), dtype=float32)
```



Shape: [2, 3, 3]

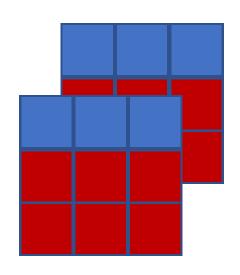
Begin: [0, 1, 0]



Shape: [2, 3, 3]

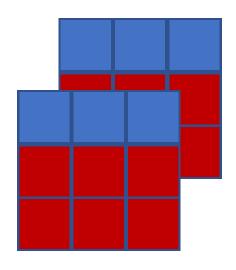
Begin: [0, 1, 0]

```
import tensorflow as tf
x = tf.constant([[[1., 2., 3.], [4., 5.,6], [7., 8.,9]]),
                [[10., 11.,12], [13., 14., 15], [16., 17., 18]]])
print(x)
res = tf.slice(x, [0, 1, 0], [2, 1, 2])
print("\n")
print(res)
tf.Tensor(
[[[ 1. 2. 3.]
 [ 4. 5. 6.]
  [7. 8. 9.]]
 [[10. 11. 12.]
  [13. 14. 15.]
  [16. 17. 18.]]], shape=(2, 3, 3), dtype=float32)
tf.Tensor(
[[[ 4. 5.]]
 [[13. 14.]]], shape=(2, 1, 2), dtype=float32)
```



Shape: [2, 3, 3]

Begin: [0, 1, 0]



Shape: [2, 3, 3]

Begin: [0, 1, 0]

```
import tensorflow as tf
x = tf.constant([[[1., 2., 3.], [4., 5.,6], [7., 8.,9]],
                [[10., 11.,12], [13., 14., 15], [16., 17., 18]]])
print(x)
res = tf.slice(x, [0, 1, 0], [-1, -1, -1])
print("\n")
print(res)
tf.Tensor(
[[[ 1. 2. 3.]
  [4. 5. 6.]
  [7. 8. 9.]]
 [[10. 11. 12.]
  [13. 14. 15.]
  [16. 17. 18.]]], shape=(2, 3, 3), dtype=float32)
tf.Tensor(
[[[ 4. 5. 6.]
  [7. 8. 9.]]
 [[13. 14. 15.]
 [16. 17. 18.]]], shape=(2, 2, 3), dtype=float32)
```

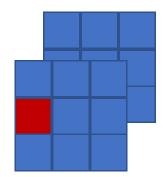
Lesson 5: Accessing the element of a Tensor

tf.slice(<input>,<begin>,<size>)

•input: Tensor

•begin: starting location for each dimension of input

•size: number of elements for each dimension of input, using -1 includes all remaining elements



Shape: [2, 3, 3]

Begin: [0, 1, 0]

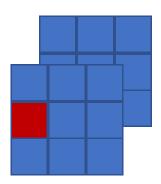
Size: [1, 1, 1]

tf.slice(<input>,<begin>,<size>)

•input: Tensor

begin: starting location for each dimension of input

•size: number of elements for each dimension of input, using -1 includes all remaining elements



Shape: [2, 3, 3]

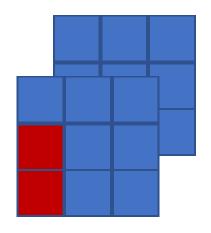
Begin: [0, 1, 0]

Size: [1, 1, 1]

```
tf.Tensor(
[[[ 1.  2.  3.]
  [ 4.  5.  6.]
  [ 7.  8.  9.]]

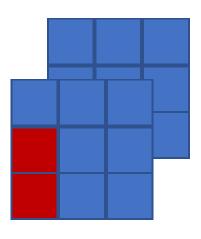
[[10. 11. 12.]
  [13. 14. 15.]
  [16. 17. 18.]]], shape=(2, 3, 3), dtype=float32)

tf.Tensor([[[4.]]], shape=(1, 1, 1), dtype=float32)
```

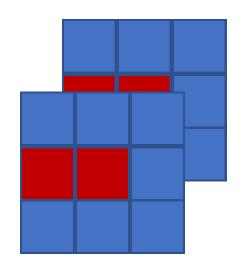


Shape: [2, 3, 3]

Begin: [0, 1, 0]

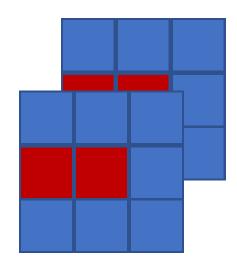


```
import tensorflow as tf
x = tf.constant([[[1., 2., 3.], [4., 5., 6], [7., 8., 9]]),
                [[10., 11.,12], [13., 14., 15], [16., 17., 18]]])
print(x)
res = tf.slice(x, [0, 1, 0], [1, 2, 1])
print("\n")
print(res)
tf.Tensor(
[[[ 1. 2. 3.]
 [ 4. 5. 6.]
  [7. 8. 9.]]
 [[10. 11. 12.]
 [13. 14. 15.]
  [16. 17. 18.]]], shape=(2, 3, 3), dtype=float32)
tf.Tensor(
[[[4.]
 [7.]]], shape=(1, 2, 1), dtype=float32)
```



Shape: [2, 3, 3]

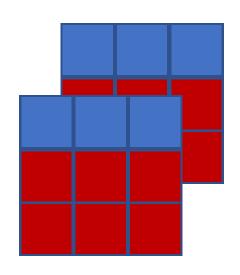
Begin: [0, 1, 0]



Shape: [2, 3, 3]

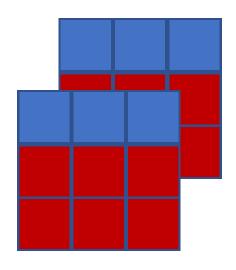
Begin: [0, 1, 0]

```
import tensorflow as tf
x = tf.constant([[[1., 2., 3.], [4., 5.,6], [7., 8.,9]]),
                [[10., 11.,12], [13., 14., 15], [16., 17., 18]]])
print(x)
res = tf.slice(x, [0, 1, 0], [2, 1, 2])
print("\n")
print(res)
tf.Tensor(
[[[ 1. 2. 3.]
 [ 4. 5. 6.]
  [7. 8. 9.]]
 [[10. 11. 12.]
  [13. 14. 15.]
  [16. 17. 18.]]], shape=(2, 3, 3), dtype=float32)
tf.Tensor(
[[[ 4. 5.]]
 [[13. 14.]]], shape=(2, 1, 2), dtype=float32)
```



Shape: [2, 3, 3]

Begin: [0, 1, 0]



Shape: [2, 3, 3]

Begin: [0, 1, 0]

```
import tensorflow as tf
x = tf.constant([[[1., 2., 3.], [4., 5.,6], [7., 8.,9]],
                [[10., 11.,12], [13., 14., 15], [16., 17., 18]]])
print(x)
res = tf.slice(x, [0, 1, 0], [-1, -1, -1])
print("\n")
print(res)
tf.Tensor(
[[[ 1. 2. 3.]
  [4. 5. 6.]
  [7. 8. 9.]]
 [[10. 11. 12.]
  [13. 14. 15.]
  [16. 17. 18.]]], shape=(2, 3, 3), dtype=float32)
tf.Tensor(
[[[ 4. 5. 6.]
  [7. 8. 9.]]
 [[13. 14. 15.]
 [16. 17. 18.]]], shape=(2, 2, 3), dtype=float32)
```

tf.gather(<params>,<indices>,<axis>)

- params: A tensor you want to extract values from.
- •indices: A tensor specifying the indices pointing into params
- Axis: axis to apply the operation



```
x = tf.constant([3, 5, 1, 6, 8, 7])
tf.gather(x, [2])
```

<tf.Tensor: shape=(1,), dtype=int32, numpy=array([1])>

tf.gather(<params>,<indices>,<axis>)

- params: A tensor you want to extract values from.
- •indices: A tensor specifying the indices pointing into params
- Axis: axis to apply the operation



```
x = tf.constant([3, 5, 1, 6, 8, 7])
tf.gather(x, [2])

<tf.Tensor: shape=(1,), dtype=int32, numpy=array([1])>

x = tf.constant([3, 5, 1, 6, 8, 7])
tf.gather(x, [0,3])

<tf.Tensor: shape=(2,), dtype=int32, numpy=array([3, 6])>
```

tf.gather(<params>,<indices>,<axis>)

- params: A tensor you want to extract values from.
- indices: A tensor specifying the indices pointing into params
- Axis: axis to apply the operation



```
x = tf.constant([3, 5, 1, 6, 8, 7])
tf.gather(x, [2])

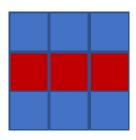
<tf.Tensor: shape=(1,), dtype=int32, numpy=array([1])>

x = tf.constant([3, 5, 1, 6, 8, 7])
tf.gather(x, [0,3])

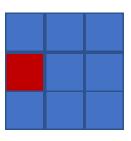
<tf.Tensor: shape=(2,), dtype=int32, numpy=array([3, 6])>

tf.gather(x, [[2, 0], [2, 5]])

<tf.Tensor: shape=(2, 2), dtype=int32, numpy= array([[1, 3], [1, 7]])>
```



tf.Tensor([[20. 21. 22.]], shape=(1, 3), dtype=float32)



tf.Tensor([[20.]], shape=(1, 1), dtype=float32)

Maximum element of a Tensor

Maximum element

```
x = tf.constant([[9,2,10,4],[5,6,7,8]])
print(tf.reduce_max(x))

tf.Tensor(10, shape=(), dtype=int32)
```

Index of the Maximum element

```
x = tf.constant([[9,2,10,4],[5,6,7,8]])
print(tf.math.argmax(x))
```

tf.Tensor([0 1 0 1], shape=(4,), dtype=int64)

```
tf.Tensor([2 2 0 2 2], shape=(5,), dtype=int64)
```

```
[ 9, 2, 10, 4]
[ 5, 6, 7 , 8]
```

```
[ 2, 20, 30, 3, 6 ]
[ 3, 11, 16, 1, 8 ]
[ 14, 45, 23, 5, 27]
```

Minimum element of a Tensor

Minimum element

```
x = tf.constant([[9,2,10,4],[5,6,7,8]])
print(tf.reduce_min(x))

tf.Tensor(2, shape=(), dtype=int32)
```

Index of the Minimum element

```
x = tf.constant([[9,2,10,4],[5,6,7,8]])
print(tf.math.argmin(x))
```

```
tf.Tensor([1 0 1 0], shape=(4,), dtype=int64)
```

```
tf.Tensor(
[[ 2 20 30 3 6]
  [ 3 11 16 1 8]
  [14 45 23 5 27]], shape=(3, 5), dtype=int32)
tf.Tensor([0 1 1 1 0], shape=(5,), dtype=int64)
```

```
[ 9, <mark>2</mark>, 10, 4]
[ 5, 6, 7 , 8]
```

```
[ 9, <mark>2</mark>, 10, 4]
[ 5, 6, 7 , 8]
```

```
[ 2, 20, 30, 3, 6 ]
[ 3, 11, 16, 1, 8 ]
[ 14, 45, 23, 5, 27]
```

Minimum/Maximum of Two Tensors

Minimum

```
x = tf.constant([0., 0., 0., 0.])
y = tf.constant([-5., -2., 0., 3.])
tf.math.minimum(x, y)

<tf.Tensor: shape=(4,), dtype=float32, numpy=array([-5., -2., 0., 0.], dtype=float32)>
```

Maximum

```
x = tf.constant([0., 0., 0., 0.])
y = tf.constant([-5., -2., 0., 3.])
tf.math.maximum(x, y)
```

<tf.Tensor: shape=(4,), dtype=float32, numpy=array([0., 0., 0., 3.], dtype=float32)>

Concatenation of Two Tensors

Along 0-Axis

Along 1-Axis

Modifying the value of a Tensor

Not a simple operation.

Possible for Variable type. But, for such operation, we would prefer to use numpy library.

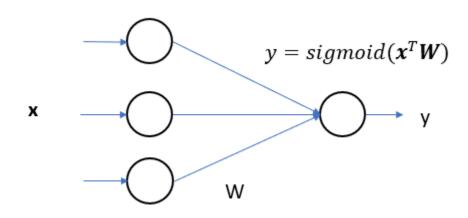
Matrix Multiplication

```
import tensorflow as tf
A1 = tf.constant([[1, 2, 3, 4]])
B1 = tf.constant([[3], [4], [5], [5]])
C1 = tf.multiply(A1, B1)
tf.print(C1)
[[3 6 9 12]
 [4 8 12 16]
 [5 10 15 20]
 [5 10 15 20]]
import tensorflow as tf
A1 = tf.constant([[1, 2, 3, 4]])
B1 = tf.constant([[3], [4], [5], [5]])
C1 = tf.matmul(A1, B1)
tf.print(C1)
[[46]]
```

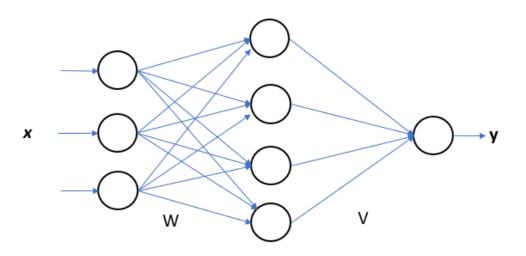
Lesson 28-29

Tensorflow and Keras

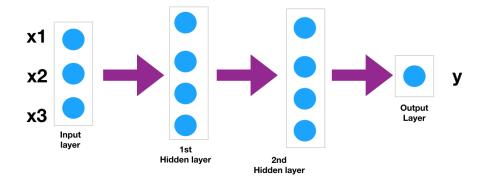
```
import numpy as np
D = np.array([[4,500,6],
             [4,550,5.5],
              [2,200,3.5],
             [2,250,4]])
label = np.array([[1,1,0,0]]).T
np.random.seed(1)
w = np.random.random((3,1))
for iteration in range(10):
   iLayer = D
   p = np.dot(iLayer,w)
                               # Perceptron
   oLayer = 1/(1+np.exp(-p)) # Sigmoid(x)
   MSE = 2*np.square(np.subtract(oLayer,label)).mean() # Mean Square Error
   print(MSE)
   der = oLayer * (1-oLayer) # dirivatives of sigmoid
   grad = np.dot(iLayer.T, der *MSE)
   w += 0.01*grad
   print(w)
print(oLayer)
```



```
import numpy as np
D = np.array([[4,500,6],
              [4,550,5.5],
              [2,200,3.5],
              [2,250,4]])
label = np.array([[1,1,0,0]]).T
np.random.seed(1)
W = np.random.random((3,4))
v = np.random.random((4,1))
for iteration in range(10):
    iLayer = D
    hP = np.dot(iLayer,w)
                               # Perceptron
    hLayer = 1/(1+np.exp(-hP)) # Sigmoid(x)
    oP = np.dot(hLayer,v)
                               # Perceptron
    oLayer = 1/(1+np.exp(-oP)) # Sigmoid(x)
    MSE = 2*np.square(np.subtract(oLayer,label)).mean() # Mean Square Error
    print(MSE)
    oDer = oP * (1-oP) # dirivatives of sigmoid
    vGrad = np.dot(oLayer.T, oDer *MSE)
    v += 0.00000001*vGrad
    print(v)
    hDer = hP * (1-hP) # dirivatives of sigmoid
    wGrad = np.dot(iLayer.T, hDer *v*oDer*MSE)
    W += 0.00000001*WGrad
    print(w)
print(oLayer)
```

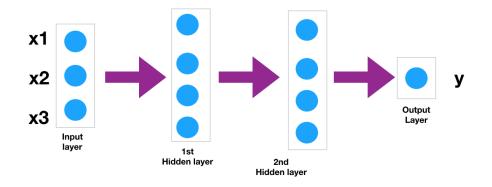


Sequential Vs Functional Keras API

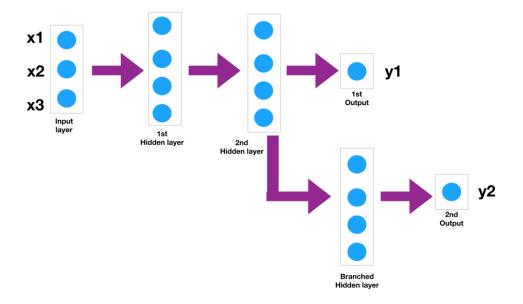


Sequential

Sequential Vs Functional Keras API

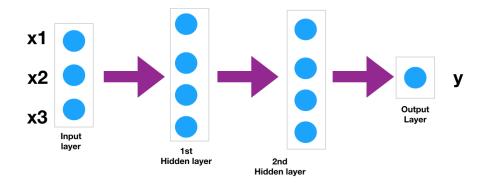


Sequential



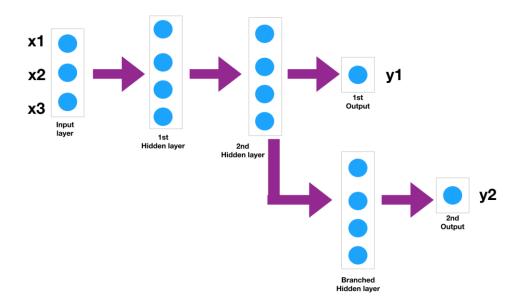
Functional

Functional Keras API



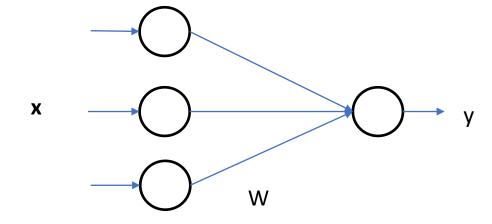
```
from tensorflow.keras.models import Model
from tensorflow.keras.layers import Input,Dense
D = np.array([[4,500,6],
              [4,550,5.5],
              [2,200,3.5],
              [2,250,4]])
label = np.array([[1,1,0,0]]).T
## Creating the layers
input layer = Input(shape=(3,))
layer 1 = Dense(4, activation="relu")(input layer)
layer 2 = Dense(4, activation="relu")(layer 1)
o layer = Dense(4, activation="relu")(layer 2)
##Defining the model by specifying the input and output layers
model = Model(inputs=input layer, outputs=o layer)
model.summary()
## defining the optimiser and loss function
model.compile(optimizer='adam', loss='mse')
## training the model
model.fit(D, label,epochs=2, batch_size=128,validation_data=(D,label))
```

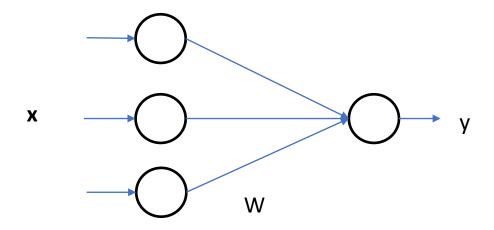
Functional Keras API



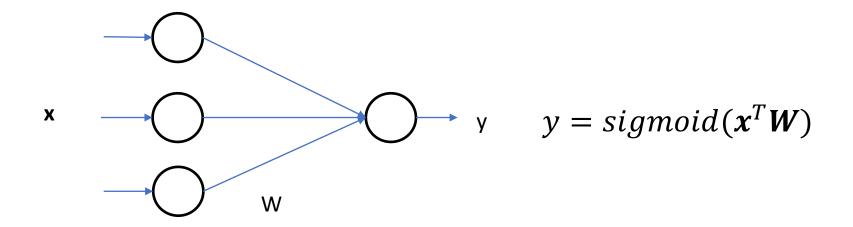
```
from tensorflow.keras.models import Model
from tensorflow.keras.layers import Input,Dense
D = np.array([[4,500,6],
              [4,550,5.5],
              [2,200,3.5],
              [2,250,4]])
label = np.array([[1,1,0,0]]).T
## Creating the layers
input layer = Input(shape=(3,))
layer 1 = Dense(4, activation="relu")(input layer)
layer_2 = Dense(4, activation="relu")(layer_1)
layer 3 = Dense(4, activation="relu")(layer 2)
o1 layer= Dense(1, activation="linear")(layer 2)
o2_layer= Dense(1, activation="linear")(layer_3)
##Defining the model by specifying the input and output layers
model = Model(inputs=input layer, outputs=[01 layer, 02 layer])
model.summary()
## defining the optimiser and loss function
model.compile(optimizer='adam', loss='mse')
## training the model
model.fit(D, label,epochs=2, batch_size=128,validation_data=(D,label))
```

Lesson 25-27: Implementing Neural Network in Python



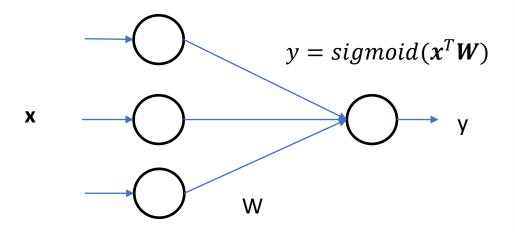


 $perceptron = x^T W$ y = sigmoid(perceptron)



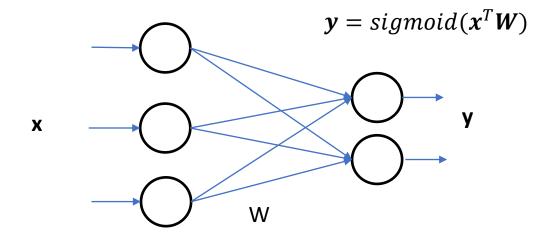
 $perceptron = x^T W$ y = sigmoid(perceptron)

Feed forward pass



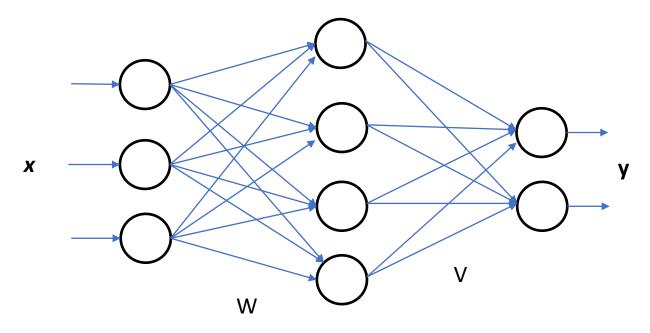
```
import numpy as np
                           # dataset
D = np.array([[1,2,3],
              [1,0,2],
              [0,1,4],
              [2,1,4]])
# Initialize weight matrix
np.random.seed(1)
w = np.random.random((3,1))
print("Weight Matrix : ")
print(w)
#Forward Pass
for iteration in range(1):
   iLayer = D
   oPer = np.dot(iLayer,w)
                                            # Perceptron
   oLayer = 1/(1+np.exp(-oPer))
                                      # Sigmoid
print("Input :")
print(D)
print("Predicted Output: ")
print(oLayer)
```

Feed forward pass



```
import numpy as np
D = np.array([[1,2,3],
                          # dataset
              [1,0,2],
              [0,1,4],
              [2,1,4]])
# Initialize weight matrix
np.random.seed(1)
W = np.random.random((3,2)
print("Weight Matrix : +)
print(w)
#Forward Pass
for iteration in range(1):
   iLayer = D
   oPer = np.dot(iLayer,w)
                                           # Perceptron
   oLayer = 1/(1+np.exp(-oPer))
                                     # Sigmoid
print("Input :")
print(D)
print("Predicted Output: ")
print(oLayer)
```

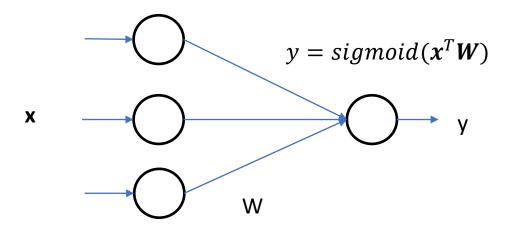
Feed forward pass



 $y = sigmoid(sigmoid(\mathbf{x}^T \mathbf{W})^T V)$

```
import numpy as np
D = np.array([[1,2,3],
             [1,0,2],
              [0,1,4],
             [2,1,4]])
# Initialize Weight Matrices
np.random.seed(1)
W = np.random.random((3,4))
print("W weight matrix:")
print(W)
print("V weight matrix:")
V = np.random.random((4,2))
print(V)
for iteration in range(1):
   iLayer = D
   hP = np.dot(iLayer,W)
                                # Hidden Layer
   hLayer = 1/(1+np.exp(-hP))
   oP = np.dot(hLayer,V)
                                # Output Layer
   oLayer = 1/(1+np.exp(-oP))
print("Input :")
print(training)
print("Predicted Output: ")
print(oLayer)
```

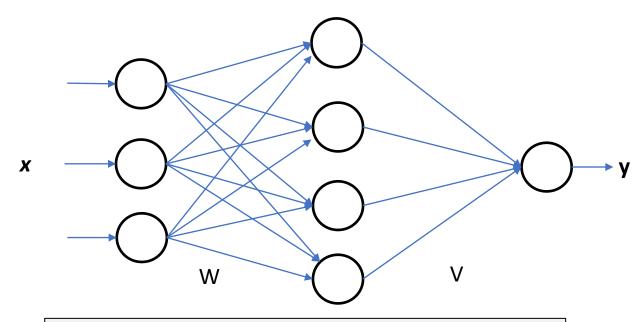
Backpropagation



$$\frac{\delta E}{\delta W_{11}} = \frac{\delta z_1}{\delta W_{11}} \times \frac{\delta y_1}{\delta z_1} \times \frac{\delta E}{\delta y_1}$$

$$\frac{\delta E}{\delta W_{11}} = x \times z(1-z) \times 2(y-y)$$

```
import numpy as np
D = np.array([[4,500,6],
              [4,550,5.5],
              [2,200,3.5],
              [2,250,4]])
label = np.array([[1,1,0,0]]).T
np.random.seed(1)
w = np.random.random((3,1))
for iteration in range(10):
    iLayer = D
   p = np.dot(iLayer,w)
                              # Perceptron
   oLayer = 1/(1+np.exp(-p)) # Sigmoid(x)
   MSE = 2*np.square(np.subtract(oLayer,label)).mean() # Mean Square Error
    print(MSE)
    der = oLayer * (1-oLayer) # dirivatives of sigmoid
    grad = np.dot(iLayer.T, der *MSE)
   W += 0.01*grad
    print(w)
print(oLayer)
```



$$\frac{\delta E}{\delta V_{11}} = \frac{\delta z_1}{\delta V_{11}} \times \frac{\delta y_1}{\delta z_1} \times \frac{\delta E}{\delta y_1} = \frac{\delta E}{\delta V_{11}}$$
$$= x \times z(1-z) \times 2(y-y)$$

$$\frac{\delta E}{\delta W_{11}} = \frac{\delta a_1}{\delta W_{11}} \times \frac{\delta h_1}{\delta a_1} \times \frac{\delta z_1}{\delta h_1} \times \frac{\delta y_1}{\delta z_1} \times \frac{\delta E}{\delta y_1}$$
$$= x \times a(1-a) \times V_{11} \times z(1-z) \times 2(y-y)$$

```
import numpy as np
D = np.array([[4,500,6],
             [4,550,5.5],
             [2,200,3.5],
             [2,250,4]])
label = np.array([[1,1,0,0]]).T
np.random.seed(1)
w = np.random.random((3,4))
v = np.random.random((4,1))
for iteration in range(10):
   iLayer = D
   hP = np.dot(iLayer,w) # Perceptron
   hLayer = 1/(1+np.exp(-hP)) # Sigmoid(x)
   oP = np.dot(hLayer,v) # Perceptron
   oLayer = 1/(1+np.exp(-oP)) # Sigmoid(x)
   MSE = 2*np.square(np.subtract(oLayer,label)).mean() # Mean Square Error
   print(MSE)
   oDer = oP * (1-oP) # dirivatives of sigmoid
   vGrad = np.dot(oLayer.T, oDer *MSE)
   v += 0.00000001*vGrad
   print(v)
   hDer = hP * (1-hP) # dirivatives of sigmoid
   wGrad = np.dot(iLayer.T, hDer *v*oDer*MSE)
   W += 0.00000001*WGrad
   print(w)
print(oLayer)
```