

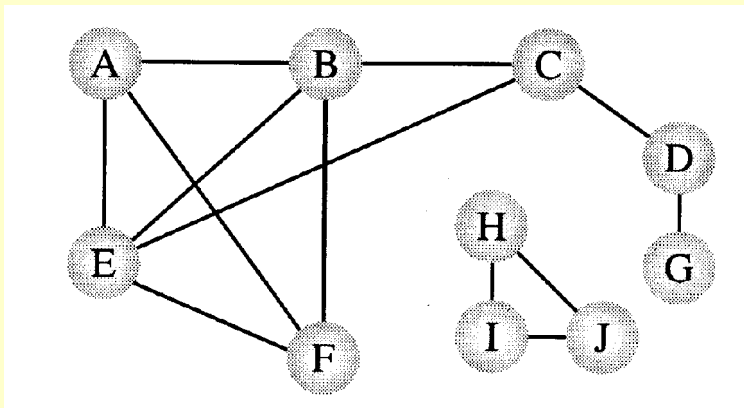
# CSE304 – Design & Analysis of Algorithms

Articulation Points, Bridges &  
Biconnected Components

# Connectivity/Biconnectivity for Undirected Graph

A node and **all the nodes reachable** from it compose a **connected component**. A graph is called **connected** if it has only one connected component.

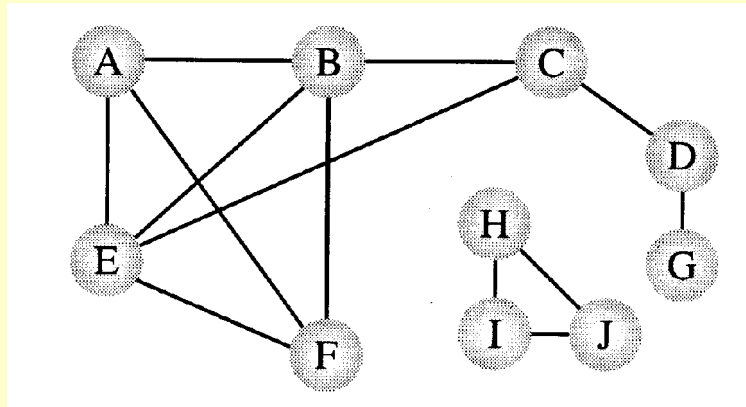
Since the function **visit()** of DFS visits every node that is reachable and has not already been visited, the **DFS can easily be modified** to print out the connected components of a graph.



Two connected components

# Connectivity/Biconnectivity

In actual uses of graphs, such as networks, we need to establish not only that every node is connected to every other node, but also there are **at least two independent paths between any two nodes**. A maximum set of nodes for which there are two different paths is called **biconnected**.



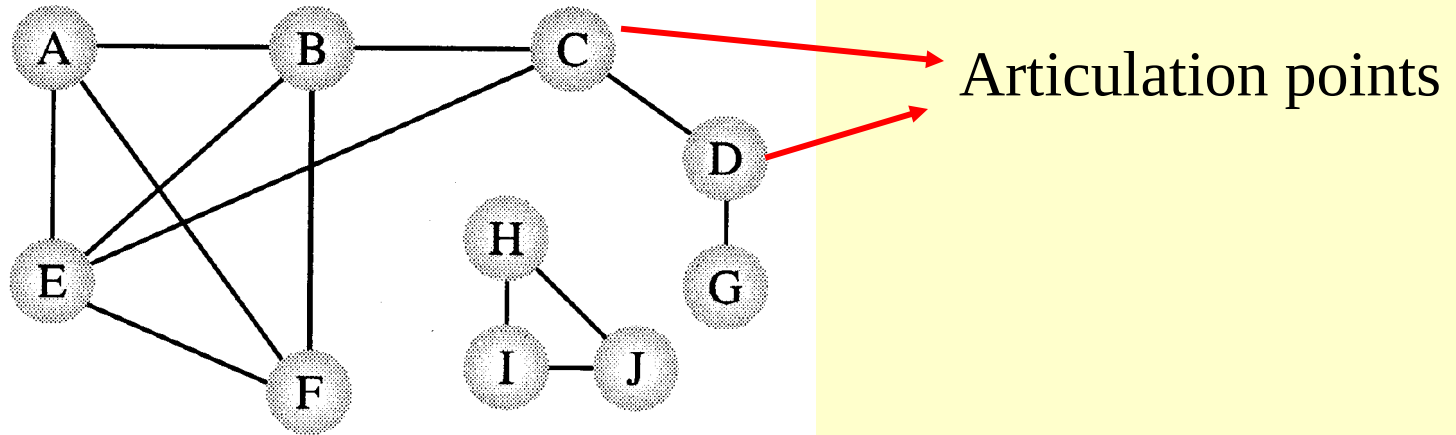
$\{H, I, J\}$  and  $\{A, B, C, E, F\}$  are biconnected.

# Connectivity/Biconnectivity

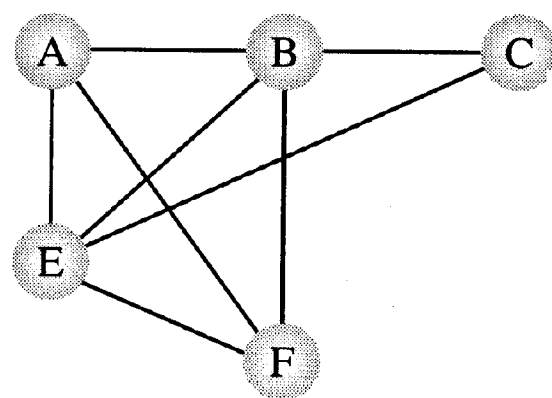
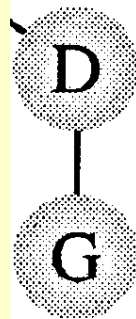
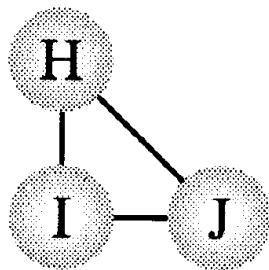
Another way to define this concept is that there are **no single points of failure**, no nodes that when deleted along with any adjoining arcs, would split the graph into two or more separate connected components. Such a node is called an **articulation point**.

If a graph contains no articulation points, then it is **biconnected**. If a graph does contain articulation points, then it is useful to **split the graph** into the pieces where each piece is a maximal biconnected subgraph called a **biconnected component**.

# Connectivity/Biconnectivity



Three biconnected components

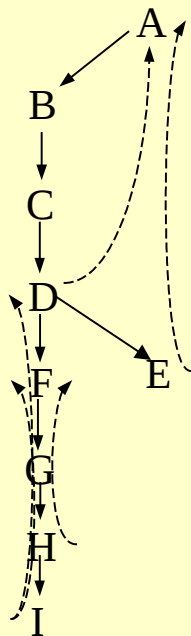
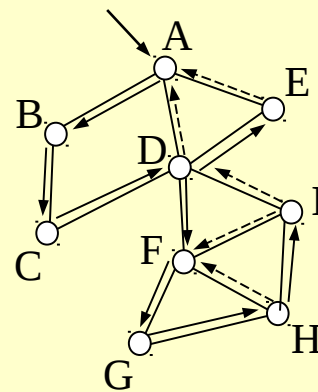
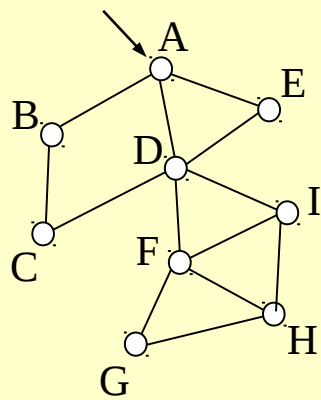


# Finding Articulations

- Problem:
  - Given any graph  $G = (V, E)$ , find all the articulation points.
  - Possible strategy:
    - For all vertices  $v$  in  $V$ :  
Remove  $v$  and its incident edges  
Test connectivity using a DFS.
    - Execution time:  $\Theta(n(n+m))$ .
    - Can we do better?

# Finding Articulation Points

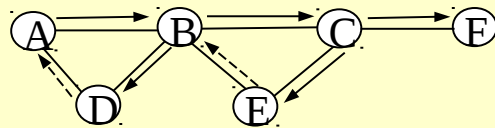
- A DFS tree can be used to discover articulation points in  $\Theta(n + m)$  time.



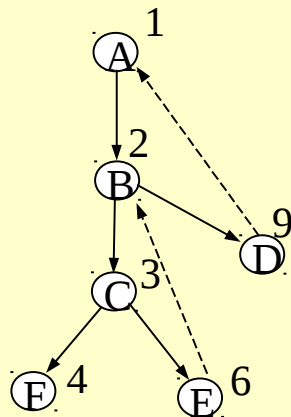
Can you characterize  $D$  ?



## Depth First Search number

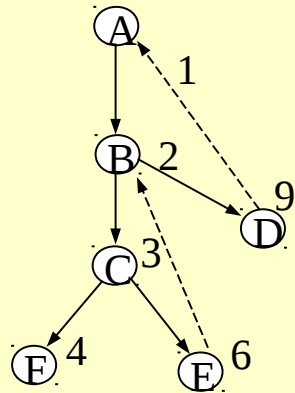


$G = (V, E)$

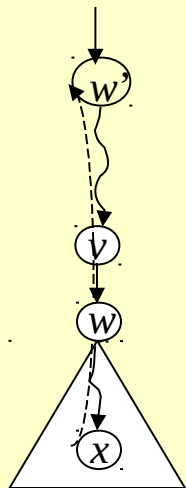


A	B	C	D	E	F
1	2	3	9	6	4

Any relation between Discovery time and articulation point ?



Assume that  $(a,b) \Leftrightarrow a \rightarrow b$   
 Tree edge :  $(a,b) \quad a < b$   
 Back edge :  $(a,b) \quad a > b$



If there is a back edge from  $x$   
 to a proper ancestor of  $v$ ,  
 then  $v$  is reachable from  $x$ .

# Finding Articulation Points

- A DFS tree can be used to discover articulation points in  $\Theta(n + m)$  time.
  - We start with a program that computes a DFS tree labeling the vertices with their **discovery times**.
  - We also compute a function called **low(v)** that can be used to characterize each vertex as an articulation or non-articulation point.
  - The root of the DFS tree will be treated as a special case:
    - The root has a  $d[]$  value of 1.

# Finding Articulation Points

- The root of the DFS tree is an articulation point if and only if it has two or more children.
  - Suppose the root has two or more children.
    - Recall that back edges never link vertices between two different subtrees.
    - So, the subtrees are only linked through the root vertex and its removal will cause two or more connected components (i.e. the root is an articulation point).
  - Suppose the root is an articulation point.
    - This means that its removal would produce two or more connected components each previously connected to this root vertex.
    - So, the root has two or more children.

# Definition of $\text{low}(v)$

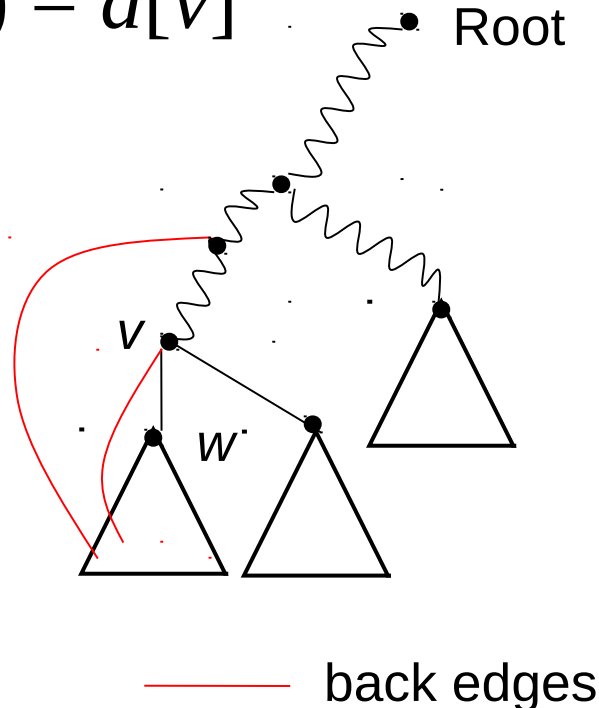
- Definition. The value of  $\text{low}(v)$  is the discovery time of the vertex closest to the root and reachable from  $v$  by following zero or more tree edges downward, and then at most one back edge.
- We can efficiently compute Low by performing a postorder traversal of the depth-first spanning tree.

$$\text{low}[v] = \min\{\begin{array}{l} d[v], \\ \text{lowest } d[w] \text{ among all back edges } (v,w) \\ \text{lowest } \text{low}[w] \text{ among all tree edges } (v,w) \end{array}\}$$

- In English:  $\text{low}(v) < d[v]$  indicates if there is another way to reach  $v$  which is not via its parent

# Low( $v$ )

- Observe that if there is a back edge from somewhere below  $v$  to above  $v$  in the tree, then  $\text{low}(v) < d[v]$
- Otherwise  $\text{low}(v) = d[v]$



# Finding Articulation Points

- Let  $v$  be a non-root vertex of the DFS tree  $T$ .
- Then  $v$  is an articulation point of  $G$  if and only if there is a child  $w$  of  $v$  with  $low(w) \geq d[v]$ .

# Articulation Points: Pseudocode

**Data:** color[V], time, prev[V], d[V], f[V], low[V]

```
DFS(G) // where prog starts
{
    for each vertex u ∈ V
    {
        color[u] = WHITE;
        prev[u]=NIL;
        low[u]=inf;
        f[u]=inf; d[u]=inf;
    }
    time = 0;
    for each vertex u ∈ V
        if (color[u] == WHITE)
            DFS_Visit(u);
}
```



# Articulation Points: Pseudocode

```
DFS_Visit(v)
{ color[v]=GREY;time=time+1;d[v] = time;
  low[v]= d[v];
  for each w ∈ Adj[v]{
    if(color[w] == WHITE){
      prev[w]=u;
      DFS_Visit(w);
      if low[w] >= d[v]
        record that vertex v is an articulation
      if (low[w] < low[v]) low[v] := low[w];
    }
    else if w is not the parent of v then
      //--- (v,w) is a BACK edge
      if (d[w] < low[v]) low[v] := d[w];
  }
  color[v] = BLACK;  time = time+1;  f[v] = time;
}
```

# Special Case

- When “v” is a root of the DFS tree, you have to check it manually.

# Source

- Mark Allen Weiss – Data Structure and Algorithm Analysis in C
  - Articulation Point
- Exercise:
  - Cormen – Exercise 22-2
  - What is bridge? How can it be detected?