In The Name of God

Introduction to Control Theory and Applications

Amirkabir University of Technology

Department of Electrical Engineering

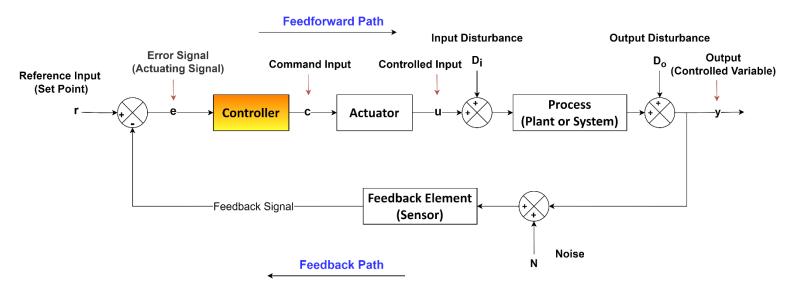
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Fall 2024

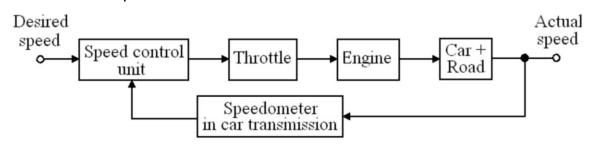
Control System



Closed-loop (feedback) Control System



☐ Car Cruise Control Example:



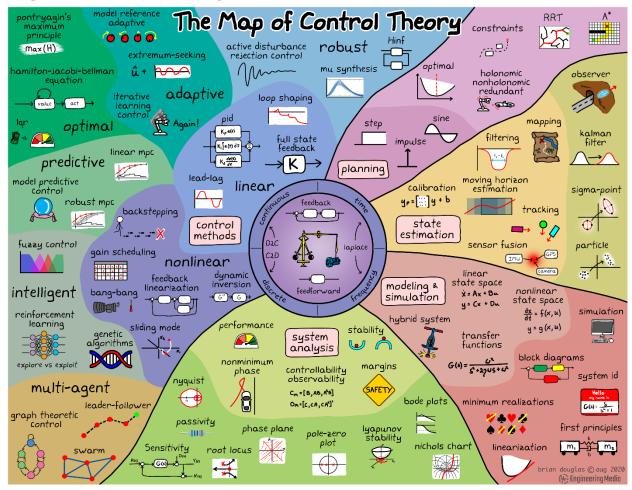
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Control Theory Branches

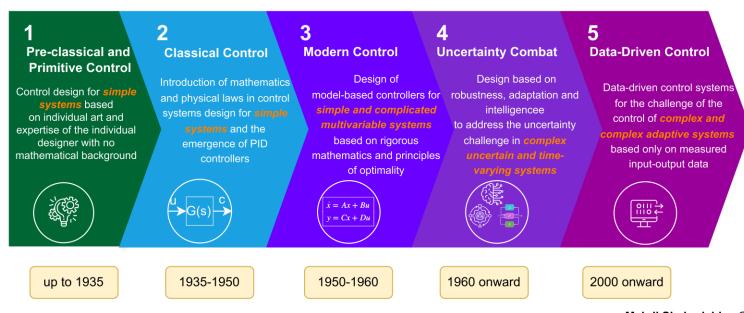


The Map of Control Theory



Paradigm Shift in Control Systems Design

Paradigm Shift in Control Systems Design

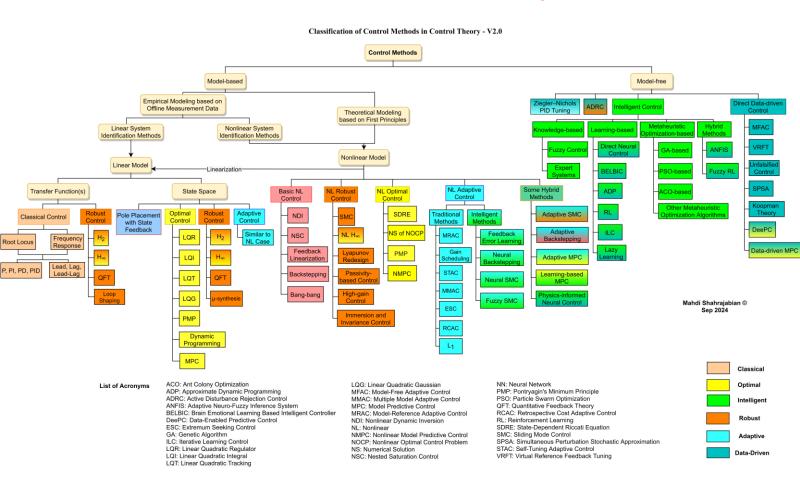


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This diagram is inspired by the concepts in: Khaki-Sedigh, Ali. An Introduction to Data-Driven Control Systems. John Wiley & Sons, 2023.

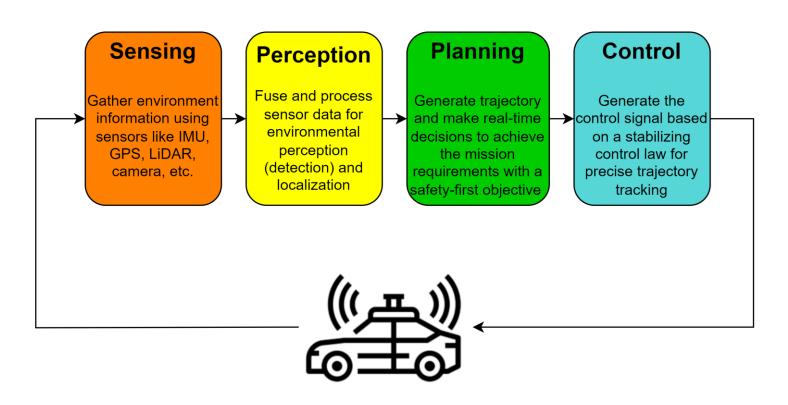


Classification of Control Methods in Control Theory



Autonomous Systems

The continuing goal of control systems is to provide extensive flexibility and a high level of autonomy.



Automation vs Autonomy

Automation

The use or introduction of automatic equipment in a manufacturing or other process or facility.

How automated a drone is always comes down to how much automatic equipment is involved and how much manual intervention it requires. An automated drone follows orders about destination and route but cannot make decisions.

Autonomy

Freedom from external control or influence; independence.

How autonomous a drone is must always be a measurement of how independent the platform and its workflow are. A truly autonomous drone would *decide* on destination and route as well as control in the air.

instances

repetitive

functions such as

scanning

Full and Partial Conditional Operational High **Trusted** No Autonomy **Assistance** Automation Operation Automation Autonomy Several assistance Autonomous Minor Human operator systems are most of the time No Human teleoperation Autonomous can initiate fully combined to give but the human operator assistance from under certain well autonomous assistance recommendations operator can take robotic onboard defined variables missions for the for the human back control at Systems systems robot to complete operator any point Safety features Human operator Autonomous such as collision can hand over when operating The autonomous Manual The robot can within certain avoidance or control to the system has more teleoperation of operate safely in areas however control over its autonomous independent the robot is complex operation for system to requires human own systems required in all environments and

Human System

assistance in

more complex

scenarios

complete an

autonomous

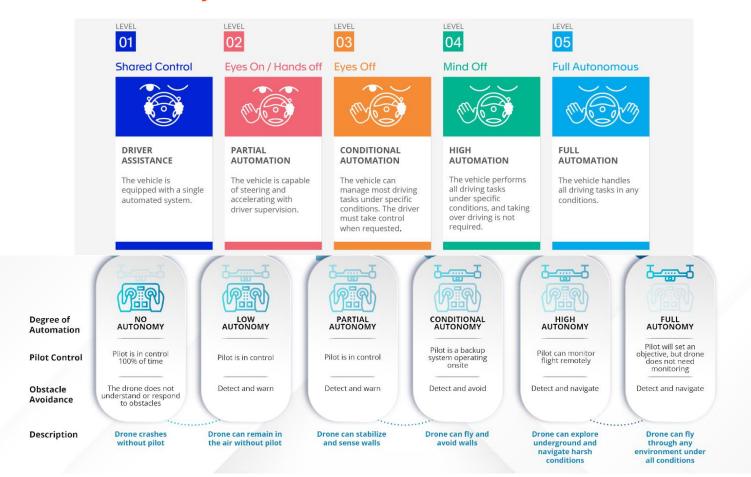
operation.

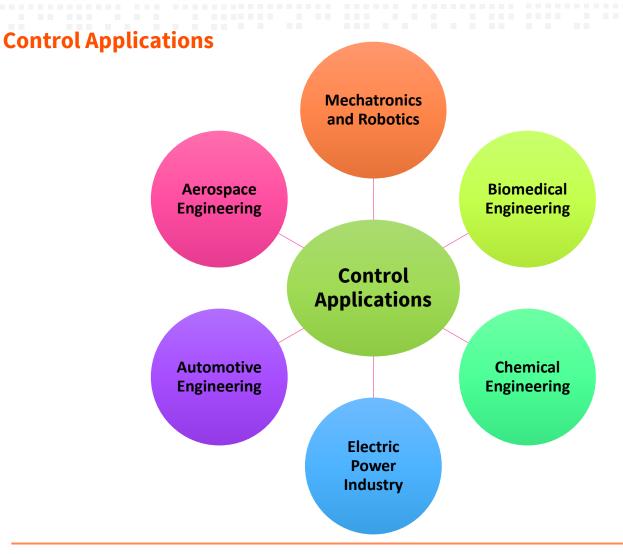
including action

unless revoked

missions

Levels of Autonomy





Control Applications









Learning Minimum Time Flight in Cluttered Environments

Robert Penicka, Yunlong Song, Elia Kaufmann, Davide Scaramuzza

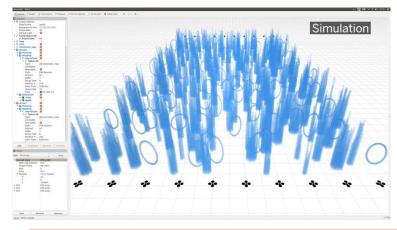




Control Applications









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Any Question?

