

Version 1.01

MATLAB Essentials Of a Specialist

Solving algebraic equation

Roots of polynomial

$x + 4 = 0$

```
>> equation = [1 4];
```

```
>> roots(equation)
```

```
ans = -4
```

$x^2 - 4 = 0$

```
>> equation = [1 0 -4]; %  $Ax^2 + Bx + C = 0$  [A B C]
```

```
>> roots(equation)
```

```
ans =
```

```
2.0000
```

```
-2.0000
```

$x^2 - 3x + 9 = 0$

```
>> roots([1 -3 9]);
```

```
>> ans
```

```
ans =
```

```
1.5000 + 2.5981i
```

```
1.5000 - 2.5981i
```

Solving System of Linear Equation

$Ax = B$

$x + 2y = 4$ $3x + 4y = 5$

```
>> A = [1 2; 3 4];
```

```
>> B = [4; 5];
```

```
>> x = A\B
```

```
x =
```

```
-3.0000
```

```
3.5000
```

alternate

```
>> x = inv(A)*B % or (A^-1)*B
```

linsolve

```
>> linsolve(A,B)
```

Solving symbolically

```
#  $x + 3 = 2$ 
```

```
>> syms x
```

```
>> solve('x+3=2',x)
```

```
ans =
```

```
-1
```

```
#  $x^2 + 2x - 3 = 12$ 
```

```
>> syms x
```

```
>> solve('x^2+2*x-3=12',x)
```

```
ans =
```

```
-5
```

```
3
```

```
#  $\sin x = 3$ 
```

```
>> syms x y
```

```
>> solve('sin(x)=3',x)
```

```
ans =
```

```
asin(3)
```

```
pi - asin(3)
```

```
>> double(ans)
```

```
ans =
```

```
1.5708 - 1.7627i
```

```
1.5708 + 1.7627i
```

```
#  $x+2*y=-3*z$  % Solve for y
```

```
>> syms x y z
```

```
>> solve('x+2*y=-3*z',y)
```

```
ans =
```

```
- x/2 - (3*z)/2
```

```
>> pretty(ans)
```

```
  x    3 z
```

```
- - - ---
```

```
  2    2
```

```
# x+2*y=-3*z % Solve for z
```

```
>> syms x y z
```

```
>> solve('x+2*y = -3*z',z)
```

```
ans =
```

```
- x/3 - (2*y)/3
```

```
>> solve('sin(x) + exp(z) = 3*y',y)
```

```
ans =
```

```
exp(z)/3 + sin(x)/3
```

```
>> solve('sin(x) + exp(z) = 3*y',x)
```

```
ans =
```

```
-asin(exp(z) - 3*y)
```

```
pi + asin(exp(z) - 3*y)
```

```
# Linear equations symbolically
```

```
>> syms x
```

```
>> solve('x+3=2',x)
```

```
ans =
```

```
-1
```

```
# Linear equations Solve using symbolic toolbox
```

```
>> syms x y z
```

```
>> [x y] = solve ('3*x - y = 2','x+y=1')
```

```
x = 3/4
```

```
y = 1/4
```

```
>> solution = solve ('3*x - y = 2','x+y=1')
```

```
solution =
```

```
    x: [1x1 sym]
```

```
    y: [1x1 sym]
```

```
>> solution.x
```

```
ans =
```

```
3/4
```

```
>> solution.y
```

```
ans =
```

```
1/4
```

```
# Solve with constant in coefficients in linear equation
```

```
>> [x y] = solve('2*x-3*c*y=5','c*x+2*y=7')
```

```
x =
```

```
(21*c + 10)/(3*c^2 + 4)
```

```
y =
```

```
-(5*c - 14)/(3*c^2 + 4)
```

Creating Mathematical Functions

```
# f(x) = x^2
```

```
>> f = inline('x^2','x')
```

```
f =
```

```
Inline function:
```

```
f(x) = x^2
```

```
>> f(2)
```

```
ans =
```

```
4
```

```
# area of a triangle
```

```
>> areaofTriangle = inline('.5*b*h','b','h');
```

```
>> areaofTriangle
```

```
areaofTriangle =
```

```
Inline function:
```

```
areaofTriangle(b,h) = .5*b*h
```

```
>> areaofTriangle(5,10)
```

```
ans =
```

```
25
```

Algorithms

Bisec Rule

```
%% function
% f = 2 - 2 + log(x)

%% Initial guesses
x1 = 1;
xu = 4;

f1 = 2-x1 + log(x1);
fu = 2-xu + log(xu);

%% check signs

flag = f1*fu;

if flag>0 %opposite sign
    error('Initial guesses should have different signs.');
```

end

%% iterative solution using bisecRule

```
err = abs(x1-xu);
xNew = (x1 + xu) / 2;
fNew = 2 - xNew + log(xNew);
%%check signs of fNew*f1
if f1*fNew > 0
    x1 = xNew;
    f1 = fNew;
else
    xu = xNew;
    fu = fNew;
end
```

Newton Raphson

```
% f = 2 - x + log(x)
% f1 = - 1 + 1/x
% algorithm
% Newguess = Currentguess - (f(Currentguess)/f1(Currentguess))
%% implementing
NewGuess = 8.0;
f=1;
while(f~=0)
    Guess = NewGuess;
    f = 2 - Guess + log(Guess);
    f1 = - 1 + (1/Guess);
    NewGuess = Guess - (f/f1);
end
```

Gauss-Siedal Method

```
x = [1,2,2,1;2,2,4,2;1,3,2,5;2,6,5,8]; a = [1;0;2;4];
A = [x,a]; solution = x\a;
%% use A(1,1) as pivot element
for i = 2:1:length(a)
    alpha = A(i,1) / A(1,1);
    A(i,:) = A(i,:) - alpha * A(1,:);
end
%% use A(2,2) as pivot element
for i = 3:1:length(a)
    alpha = A(i,2) / A(2,2);
    A(i,:) = A(i,:) - alpha * A(2,:);
end
%%
for j = 1:1:(length(a)-1)
    for i = j+1:1:length(a)
        alpha = A(i,j) / A(j,j);
        A(i,:) = A(i,:) - alpha * A(j,:);
    end
end
```

Maclaurin

```
n = 5;
aAll = [0.1,0.05,0.02,0.01];

vec = [1:n];
err=[];

for i=1:length(aAll)
    terms = aAll(i).^vec ./ cumprod(vec);

    expVal = 1 + cumsum(terms);

    trueVal = exp(aAll(i));

    err = [err;abs(trueVal - expVal)];
end

plot(err);
xlabel('step size');
ylabel('error');
hold on;
```


Derivatives

Derivative

```
>> syms x    % taking the variable function must be defined in syms
```

```
>> f = inline('x^3+x^2+3','x')
```

```
f =
```

```
    Inline function:
```

```
    f(x) = x^3+x^2+3
```

```
>> diff(f(x),x)
```

```
ans =
```

```
3*x^2 + 2*x
```

Derivative at a point

```
>> syms x
```

```
>> f = inline('x^2-3','x')
```

```
f =
```

```
    Inline function:
```

```
    f(x) = x^2-3
```

```
>> f1 = inline(diff(f(x),x),'x')
```

```
f1 =
```

```
    Inline function:
```

```
    f1(x) = x.*2.0
```

```
>> f1(3)
```

```
ans =
```

```
    6
```

Partial derivative

```
>> syms x
```

```
>> syms y
```

```
>> f = inline('sin(x)+y^3','x','y')
```

```
f =
```

```
    Inline function:
```

```
    f(x,y) = sin(x)+y^3
```

```
>> diff( f(x,y),x ) % taking der with respect to x
```

```
ans =
```

```
cos(x)
```

```
>> diff ( f(x,y),y ) % taking der with respect to y
ans =
3*y^2
```

counting how many times a function can be differentiated

```
syms x
f = inline('x^4 - 3*x^3 + 2*x^2 - x + 16','x');
der = f(x);
count = 0;
while(der~=0)
f = inline( diff(f(x),x), 'x' );
der = f(x);
count = count + 1;
end
>> count
5
```

Derivative of two polynomials product $d/dx(P(x)*P(y))$

```
>> p1 = [3 6 9];
>> p2 = [1 2 0];
>> polyder(p1,p2);
>> ans
ans =
12    36    42    18
```

Numerical Differentiation

```
% tan inverse(a)
a = 1;
trueVal = 1/(1+a^2);
h = 0.001;
approxVal = (atan(a+h) - atan(a)) / h;
err = abs(approxVal - trueVal);
```

Limits

```
# limit(function,x,approachesvalue)
```

```
>> syms x
```

```
>> f = inline('sin(x)/x','x')
```

```
f =
```

```
    Inline function:
```

```
    f(x) = sin(x)/x
```

```
>> limit(f(x),x,0)
```

```
ans =
```

```
1
```

```
%approaches infinity = limit((f(x),x,Inf)
```

Integration

Indefinite Integral

#

>> syms x

>> f = inline ('x^2+2*x','x')

f =

Inline function:

f(x) = x^2+2*x

>> int(f(x),x);

>> ans

ans =

 $(x^2(x + 3))/3$

Definite Integral

int(f(x),lowerlimit,upperlimit)

>> syms x

>> f = inline('x^2+2*x','x')

f =

Inline function:

f(x) = x^2+2*x

>> int(f(x),1,4)

ans =

36

Numerical Integration

```
x=0:0.1:1; % x:lowerlimit:interval:upperlimit;
```

```
y=x.^2;
```

```
plot(x,y);
```

%% Trapezoid Method

```
avg_y = y(1:length(x)-1) + diff(y)/2;
```

```
A = sum(diff(x).*avg_y);
```

%% Simpson Method

```
A = quad('x.^2',0,1); %quad('func',lowerlimit,upperlimit);
```

%% Lobatto Method

```
A = quadl('x.^2',0,1);
```

Reading from a file

Reading numbers

```
>> nums = textread(numbers.txt')
```

```
nums = 123456789
```

Reading strings

```
>> textread('motto.txt','%s')
```

```
ans =
```

```
    'Visca'
```

```
    'El'
```

```
    'Barca'
```

Reading characters

```
>> cha = textread('motto.txt','%c');
```

```
>> cha
```

```
cha =
```

```
V
```

```
i
```

```
s
```

```
c
```

```
a
```

```
E
```

```
l
```

```
B
```

```
a
```

```
r
```

```
c
```

```
a
```

Reading images

```
>> ima = imread('img.jpg');
```

```
excel = xlsread('diode.xls', 'c4
```

Reading excel file

```
>> excel = xlsread('diode.xls','c4:c19');
```

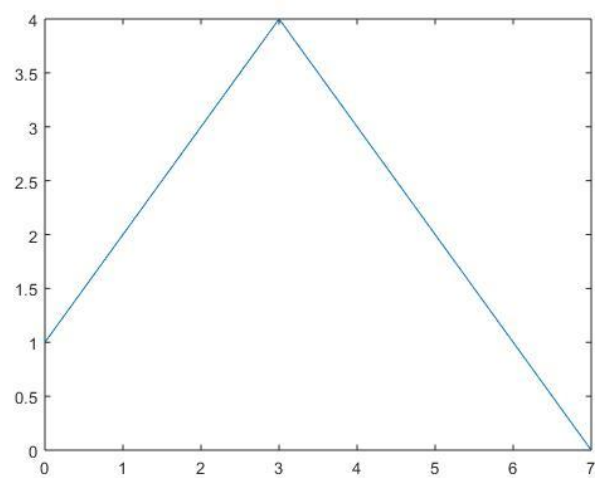
Reading audio file

```
>> audiofile = wavread('audio.wav');
```

Plotting

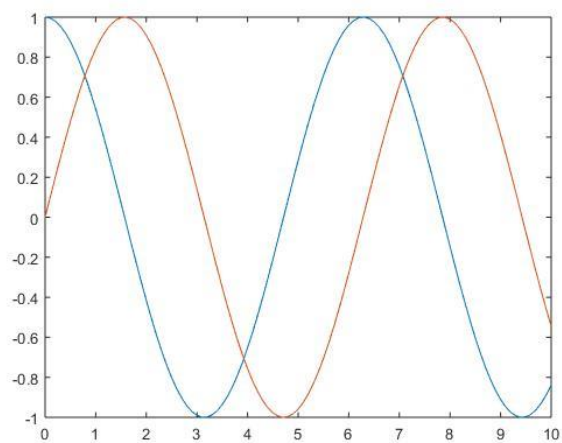
Basic Plot

```
>> x = [0 1 2 3 4 5 6 7];  
>> y = [1 2 3 4 3 2 1 0];  
>> plot(x,y)  
>> title('My Favourite Plot')  
>> xlabel('x-axis')  
>> ylabel('y-axis')  
>> plot(x,y)
```



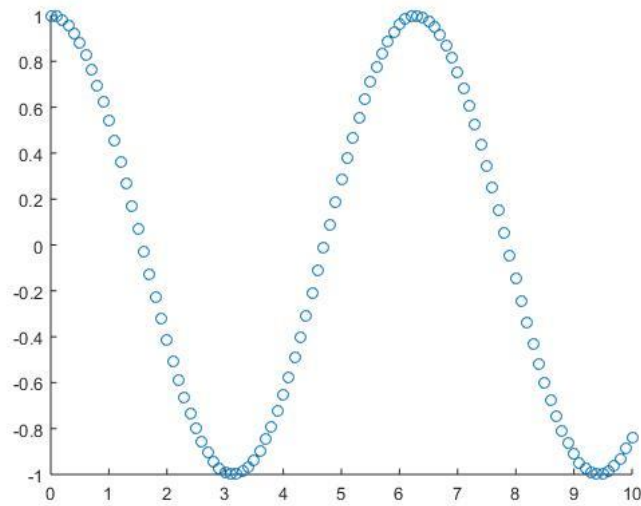
2 plots together

```
>> x = [0:0.1:10];  
>> y = cos(x);  
>> z = sin(x);  
>> plot(x,y,x,z)
```

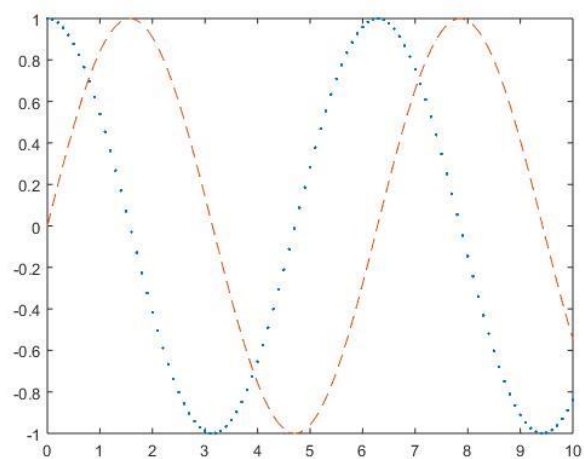


scatterplot

```
>> x = [0:0.1:10];  
>> y = cos(x);  
>> scatter(x,y)
```

**# Changing plot appearance**

```
>> plot(x,y,'.',x,z,'--')  
>> % legend('sinx','cosx') can be used to mention legends
```



Plot styles modification

```
plot(x,y,'ColorMarkerLine');
```

Specifier	LineStyle
'_'	Solid line (default)
'--'	Dashed line
'.'	Dotted line
'-.'	Dash-dot line

Marker Specifiers

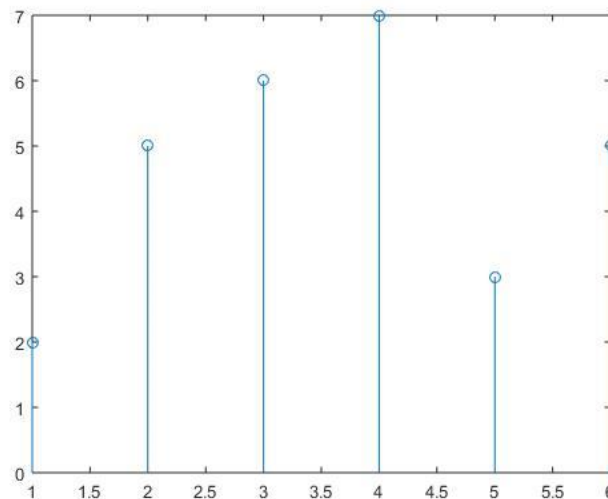
Specifier	Marker Type
'+'	Plus sign
'o'	Circle
'*'	Asterisk
'.'	Point
'x'	Cross
'square' or 's'	Square
'diamond' or 'd'	Diamond
'^'	Upward-pointing triangle
'v'	Downward-pointing triangle
'>'	Right-pointing triangle
'<'	Left-pointing triangle
'pentagram' or 'p'	Five-pointed star (pentagram)
'hexagram' or 'h'	Six-pointed star (hexagram)

Color Specifiers

Specifier	Color
'r'	Red
'g'	Green
'b'	Blue
'c'	Cyan
'm'	Magenta
'y'	Yellow
'k'	Black
'w'	White

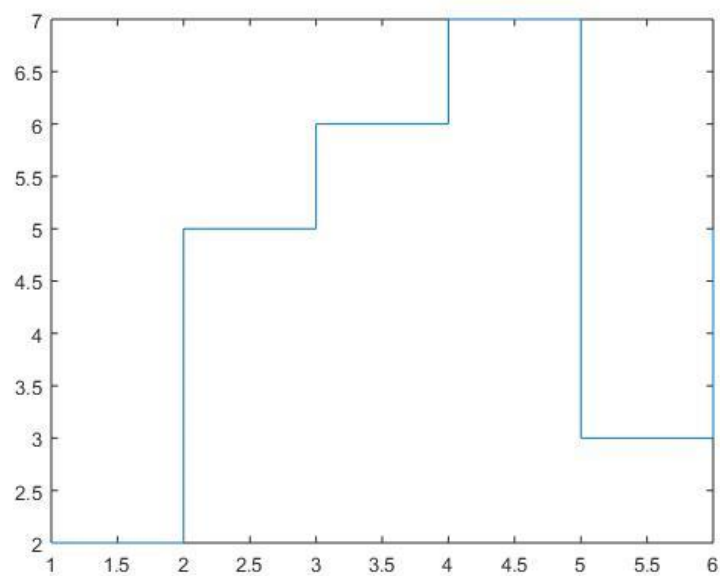
Stem plot

```
>> x = [1:6];
>> y = [2,5,6,7,3,5];
>> stem(x,y)
```



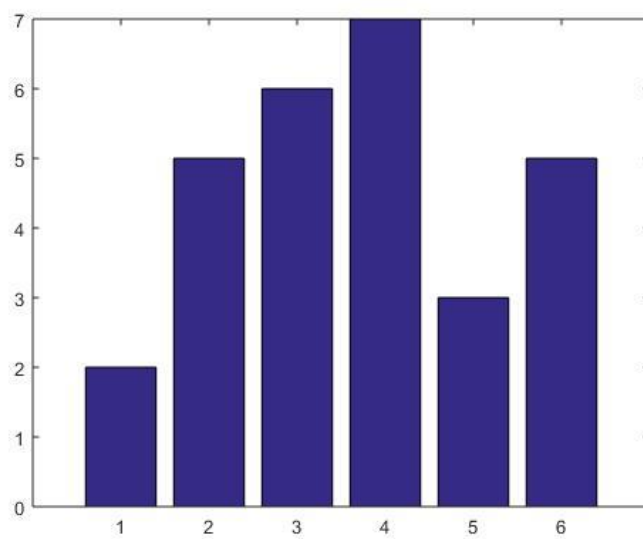
Stair Plot

```
>> x = [1:6];  
>> y = [2,5,6,7,3,5];  
>> stairs(x,y)
```



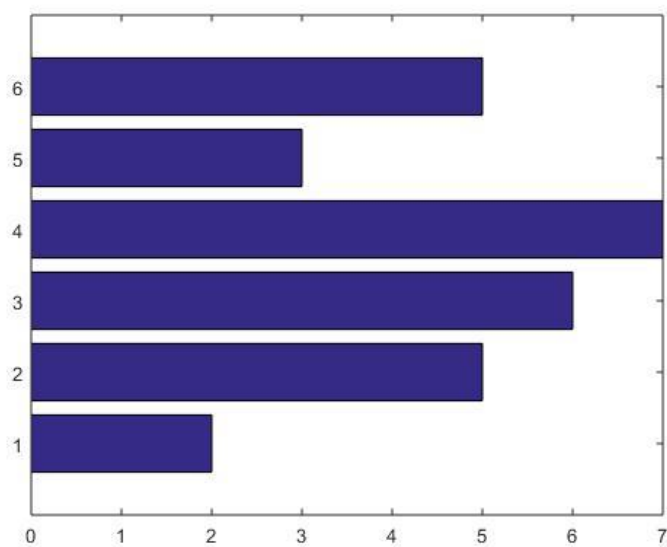
Bar plot

```
>> x = [1:6];  
>> y = [2,5,6,7,3,5];  
>> bar(x,y)
```



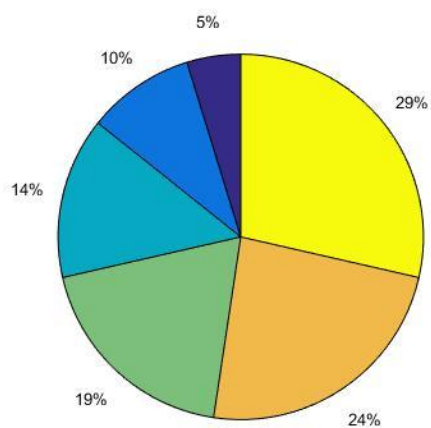
Horizontal Bar plot

```
>> x = [1:6];  
>> y = [2,5,6,7,3,5];  
>> barh(x,y)
```



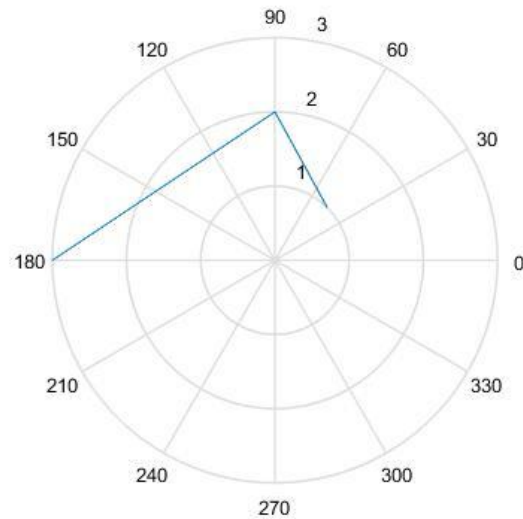
Pie plot

```
>> x = [1:6];  
>> pie(x)
```



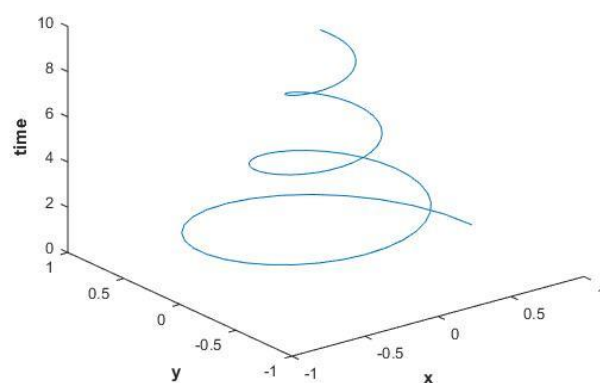
Polar Plot

```
>> theta = [pi/4 pi/2 pi];  
>> r = [1 2 3];  
>> polar(theta,r)
```



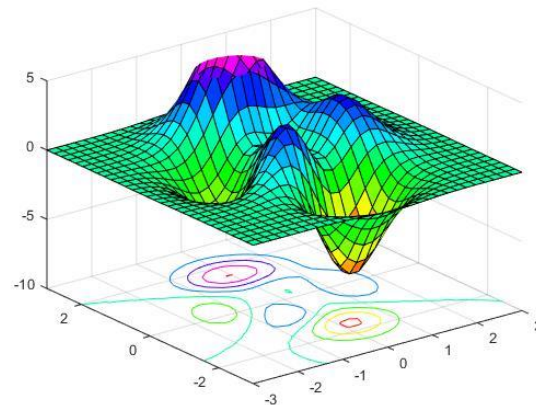
3D Plot

```
>> t = [0:0.1:10];  
>> x = exp(-0.2*t).*cos(2*t);  
>> y = exp(-0.2*t).*sin(2*t);  
>> plot3(x,y,t);  
xlabel('\bf x');  
ylabel('\bf y');  
zlabel('\bf time');
```



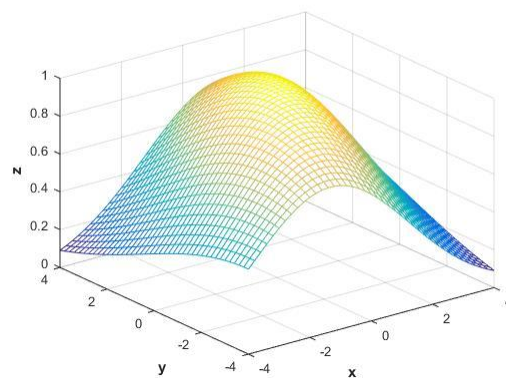
Surf

```
[x,y,z]=peaks(30);
surfc(x,y,z);
colormap hsv
axis([-3 3 -3 3 -10 5])
```

**# mesh**

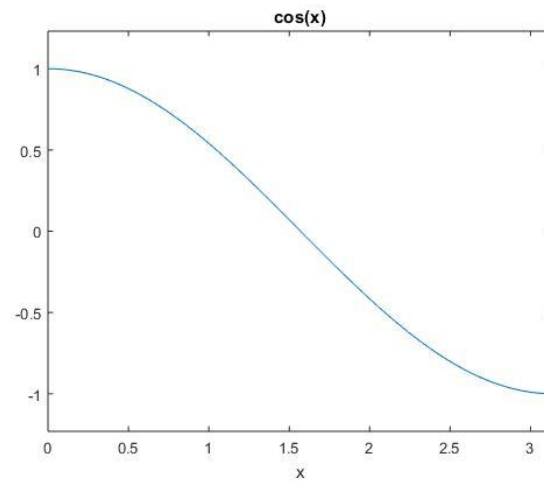
```
>> [x,y] = meshgrid(-4:0.2:4);
z = exp(-.05*(x.^2 + 0.5*(x-y).^2));
mesh (x,y,z);
xlabel('\bf x');
ylabel('\bf y');
zlabel('\bf time');

>> [x,y] = meshgrid(-4:0.2:4);
z = exp(-.05*(x.^2 + 0.5*(x-y).^2));
mesh (x,y,z);
xlabel('\bf x');
ylabel('\bf y');
zlabel('\bf z');
```



```
# ezplot
```

```
>> ezplot('cos(x)',[0 pi]);
```



```
# Multiple plots in same axis (again)
```

```
>> x = -pi:pi/20:pi;
```

```
>> y1 = sin(x);
```

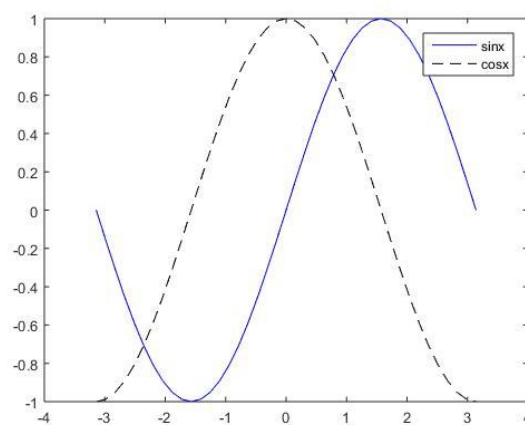
```
>> y2 = cos(x);
```

```
>> plot (x,y1,'b-');
```

```
>> hold on
```

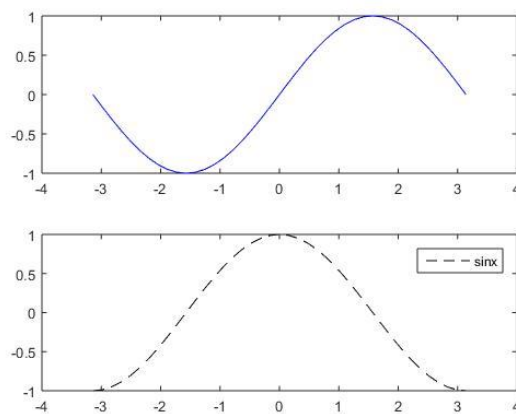
```
>> plot (x,y2,'k--');
```

```
>> legend('sinx','cosx');
```



Many figures in same window : Subplots

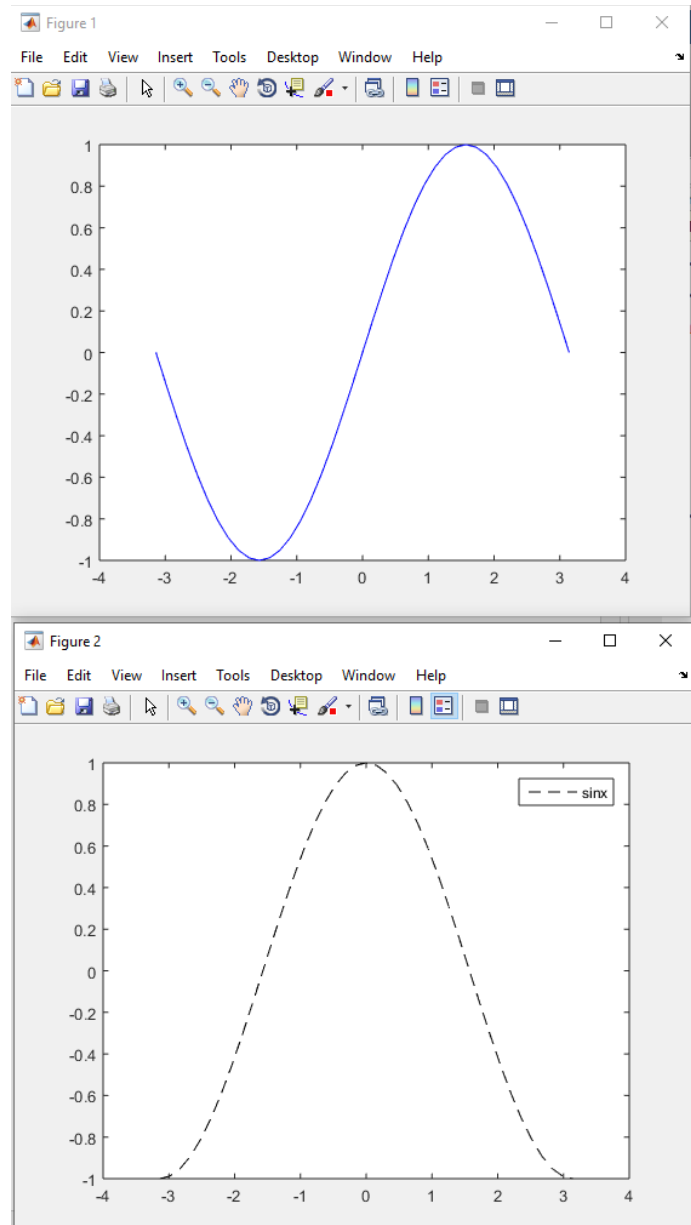
```
x = -pi:pi/20:pi;  
y1 = sin(x);  
y2 = cos(x);  
subplot(2,1,1)  
plot (x,y1,'b-');  
subplot(2,1,2);  
plot (x,y2,'k--');  
legend('sinx','cosx');
```

**# Enhanced Control of Plotted Lines**

```
# LineWidth  
# MarkerEdgeColor  
# MarkerFaceColor  
# MarkerSize  
>> plot (x,y,'PropertyName',value,'PropertyName',value,.....)
```

Creating Multiple Figures in different windows

```
figure(1)
x = -pi:pi/20:pi;
y1 = sin(x);
y2 = cos(x);
plot (x,y1,'b-');
figure(2)
plot (x,y2,'k--');
legend('sinx','cosx');
```



Polynomials

Evaluate a polynomial

```
# polyval(P,k) evaluates value of x for which P(value) = k
P(x) = x^3 + x - 1
P = [1 0 1 -1]
```

Multiplication of Polynomials

```
P(x) = 3x + 2
Q(x) = 2x + 4
>> P = [3 2]
>> Q = [ 2 4]
>> prod = conv(P,Q)
```

Polynomial solution

```
>> y1 = sym('x-0.5*y+1.5*z-5');
>> y2 = sym('6*x+4*y-2*z-10');
>> y3 = sym('-x-y+z+1');
>> [x,y,z] = solve(y1,y2,y3)
x = 5.0
y = -6.0
z = -2.0
```

Transfer Function

```
#
>> num = [1 2];
>> den = [1 4 5];
>> H = tf(num,den)
```

H =

$$\frac{s + 2}{s^2 + 4s + 5}$$

Continuous-time transfer function.

```
>> pzmap(H)
>> grid on
>> [z,p] = tf2zp(num,den)
```

z =

$$-2$$

p =

$$\begin{aligned} &-2.0000 + 1.0000i \\ &-2.0000 - 1.0000i \end{aligned}$$

Signal Analysis

Amplitude Modulation

Mathematical Expression for AM

$$S_{AM}(t) = A_c * [1 + K_a * m(t)] * \cos(2 * (\text{pie}) * f_c * t)$$

K_a = Amplitude sensitivity of AM

$m(t)$ = message signal > $m(t) = A_m \sin(2 * \text{pie} * f_m * t)$

$c(t)$ = carrier signal > $c(t) = A_c \cos(2 * \text{pie} * f_c * t)$

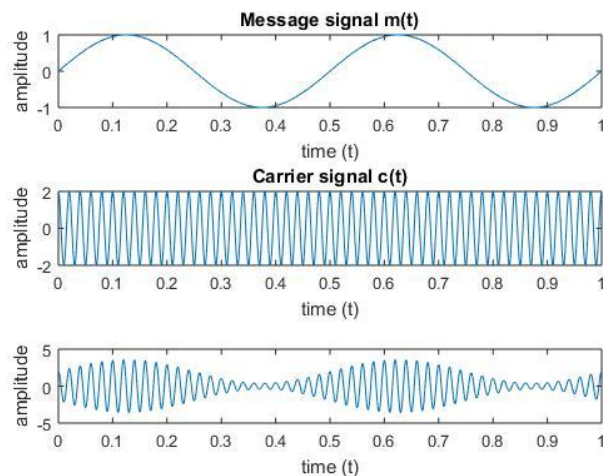
f_c = carrier frequency

f_m = message frequency

So, $S_{AM}(t) = A_c * [1 + K_a * m(t)] * c(t)$

Code

```
>> ka = 0.8;
>> Am = 1;
>> fm = 2;
>> t = [0:0.001:1];
>> mt = Am * sin(2*pi*fm*t);
>> Ac = 2;
>> fc = 50;
>> ct = Ac*cos(2*pi*fc*t);
>> St = (1+ka.*mt).*ct;
>> subplot(3,1,1)
>> plot(t,mt)
>> title('Message signal m(t)')
>> xlabel(' time (t) ')
>> ylabel(' amplitude ')
>> subplot(3,1,2)
>> plot(t,ct)
>> title('Carrier signal c(t)')
>> xlabel(' time (t) ')
>> ylabel(' amplitude ')
>> subplot(3,1,3)
>> plot(t,St)
>> xlabel(' time (t) ')
>> ylabel(' amplitude ')
```



Frequency Modulation

Mathematical Expression for FM

$$S_{FM}(t) = A_c * \cos [2\pi f_c t + \beta \sin(2\pi f_m t)]$$

K_f = Frequency sensitivity of FM

$$m(t) = \text{message signal} > m(t) = A_m \cos(2\pi f_m t)$$

$$c(t) = \text{carrier signal} > c(t) = A_c \sin(2\pi f_c t)$$

f_c = carrier frequency

f_m = message frequency

$$\beta = \text{modulation index} > \beta = K_f A_m / f_m$$

$$\text{So } S_{FM}(t) = A_c * \cos [2\pi f_c t + \beta \sin(2\pi f_m t)]$$

Code

```
>> Kf = 14;

>> Am = 1;

>> fm = 2;

>> beta = (Kf*Am)/fm;

>> t = linspace(0,1,500);

>> Ac = 1;

>> fc = 20;

linspace(startpoint,endpoint,no.ofpointsininterval)

>> Sfm = Ac*cos(2*pi*fc*t + beta*(sin(2*pi*fm*t)));

>> mt = Am*cos(2*pi*fm*t);

>> ct = Ac*cos(2*pi*fc*t);

>> subplot(3,1,1)

>> plot(t,mt)

>> title('Message signal m(t)')

>> subplot(3,1,2)

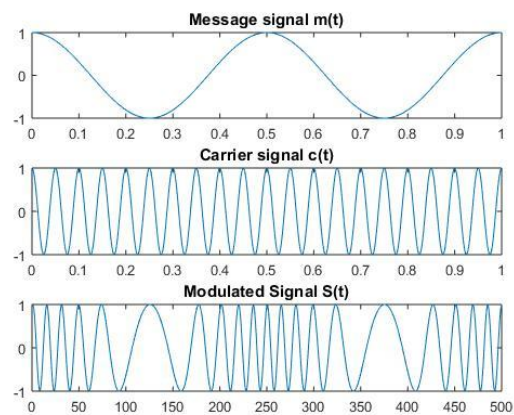
>> plot(t,ct) % plot(ct) same

>> title('Carrier signal c(t)')

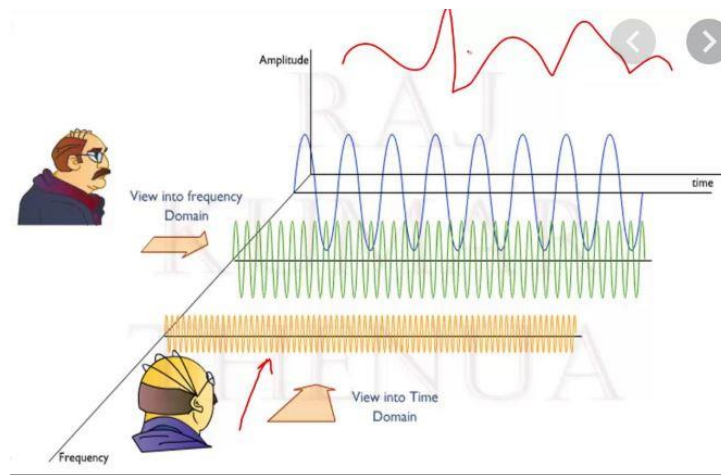
>> subplot(3,1,3)

>> plot(Sfm);

>> title('Modulated Signal S(t)')
```



Time domain to frequency domain

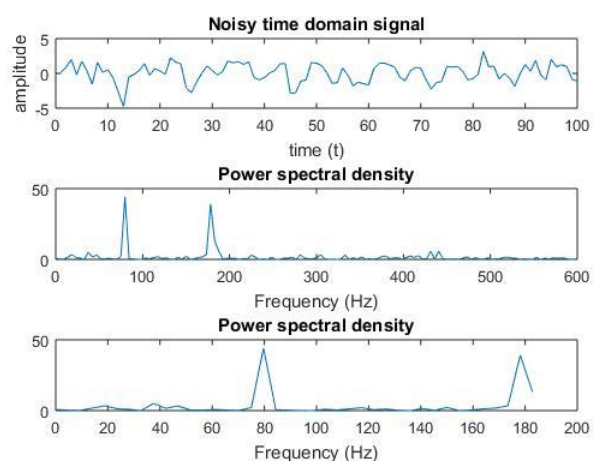


% Consider a signal sampled at 1.2kHz which is composed of 80Hz and 150Hz of sine waves and it is contaminated by a random noise.

% Write a matlab program to plot noisy signal in time domain as well as in frequency domain to get information about major frequency

% components present in the signal

```
fs = 1200;
t = 0:1/fs:1;
x = sin(2*pi*80*t) + sin(2*pi*180*t);
y = x + randn (size(t));
subplot(3,1,1)
plot(y(1:100))
title('Noisy time domain signal')
xlabel('time (t)');
ylabel('amplitude');
Y = fft(y,256);
Pyy = Y.*conj(Y)/300;
f = fs/256*(0:127);
subplot(3,1,2)
plot(f,Pyy(1:128))
title('Power spectral density')
xlabel('Frequency (Hz)')
subplot(3,1,3)
plot(f(1:40),Pyy(1:40))
title('Power spectral density')
xlabel('Frequency (Hz)')
```



String

Declaring string

```
>> str = 'this is a test';
```

```
>> whos
```

Name	Size	Bytes	Class	Attributes
str	1x14	28	char	

Converting string

```
>> x = double(str) %ascii value
```

```
x = 116    104    105    115    32    105    115    32    97    32    116    101
115    116
```

```
>> z = char(x)
```

```
z = this is a test
```

2D string

```
>> name = char('Shahriar Ahmad','Student');
```

```
>> name
```

```
name =
```

```
Shahriar Ahmad
```

```
Student
```

Joining Strings

```
>> str1 = 'I'; str2 = ' am Shahriar'; str3 = strcat(str1,str2)
```

```
str3 =
```

```
I am Shahriar
```

```
>> str4 = strvcat(str1,str2)
```

```
str4 =
```

```
I
```

```
am Shahriar
```

Comparing Strings

```
>> str1 = 'hello'; str2 = 'Hello'; str3 = 'hello';
```

```
>> strcmp(str1,str2)
```

```
ans = 0 % False
```

```
>> strcmp(str1,str3)
```

```
ans = 1 % True
```

```
>> strcmpi(str1,str2)
```

```
ans = 1
```

```
>> strcmp(str1,str2,n) %determines for first n characters
```

Comparing individual characters

```
>> a = 'fate';
```

```
>> b = 'cake';
```

```
>> c = a==b
```

```
c =
```

```
    0    1    0    1
```

Finding letters in strings

```
>> d = isletter(str)
```

```
d =
```

```
    1    1    1    1    0    0    0    1
```

Replace string

```
strrep(string,search,replace)
```

```
>> str = 'what is the test of this ice-cream?';
```

```
>> replacedstr = strrep(str,'test','taste')
```

```
replacedstr =
```

```
what is the taste of this ice-cream?
```

Sparse Array

eye to sparse array

```
>> a = eye(5)
```

```
a =
```

```

    1    0    0    0    0
    0    1    0    0    0
    0    0    1    0    0
    0    0    0    1    0
    0    0    0    0    1

```

```
>> as = sparse(a)
```

```
as =
```

```

(1,1)    1
(2,2)    1
(3,3)    1
(4,4)    1
(5,5)    1

```

```
>> whos
```

Name	Size	Bytes	Class	Attributes
a	5x5	200	double	
as	5x5	128	double	sparse

```
# Alternate way: >> a = speye(10)
```

```
# sparse to eye: >> a = full(b)
```

Functions

```
find() > find indices of non-zero elements
```

```
nnz() > number of non-zero elements
```

```
spy() > visualize sparsity pattern as a plot
```

```
issparse() > returns 1 for sparse matrix
```


Cell Arrays

Declaring cell arrays using assignment statements

```
>> a{1,1}=[1 3 -7; 2 0 6; 0 5 1];
>> a{1,2}='This is a test string';
>> a{2,1}=[3+4*i -5; -1*i 3-4*i];
>> a{2,2}= [ ];
>> a
a =
    [3x3 double]    'This is a test string'
    [2x2 double]           []
```

```
>> a(1,1)
ans =
    [3x3 double]
>> a{1,1}
ans =
     1     3    -7
     2     0     6
     0     5     1
```

```
>> c=a{1,1}(2,3)
c =
     6
```

Alternate way to declare

```
a(1,1)={ [1 3 -7; 2 0 6; 0 5 1] };
a(1,2)={'This is a test string'};
a(2,1)={ [3+4*i -5; -1*i 3-4*i] };
a(2,2)= { [ ] };
```

Empty cell arrays

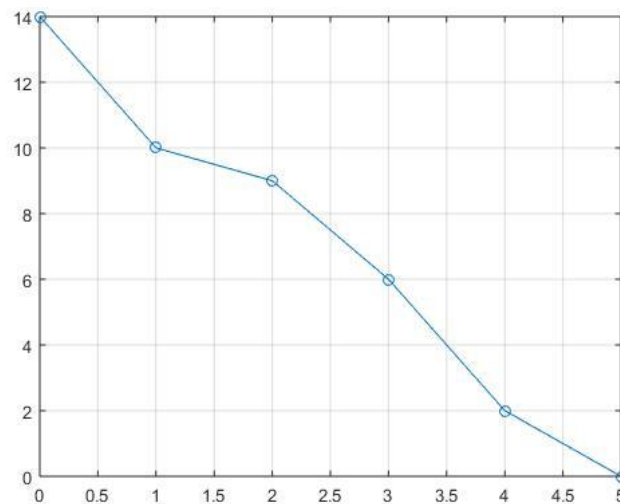
```
>> a = cell(2,2);
>> a
a =
     []     []
     []     []
```

Plot cell array

```
>> cellplot(a)
```

Interpolation

```
# interp1(x,y,new_x)
x = [0:5];
y= [14,10,9,6,2,0];
plot(x,y,'-o')
grid on
new_x = 3.5;
new_y = interp1(x,y,new_x)
new_y =
    4.0000
```



Methods

`Vq = interp1(X,V,Xq,METHOD)` specifies alternate methods.

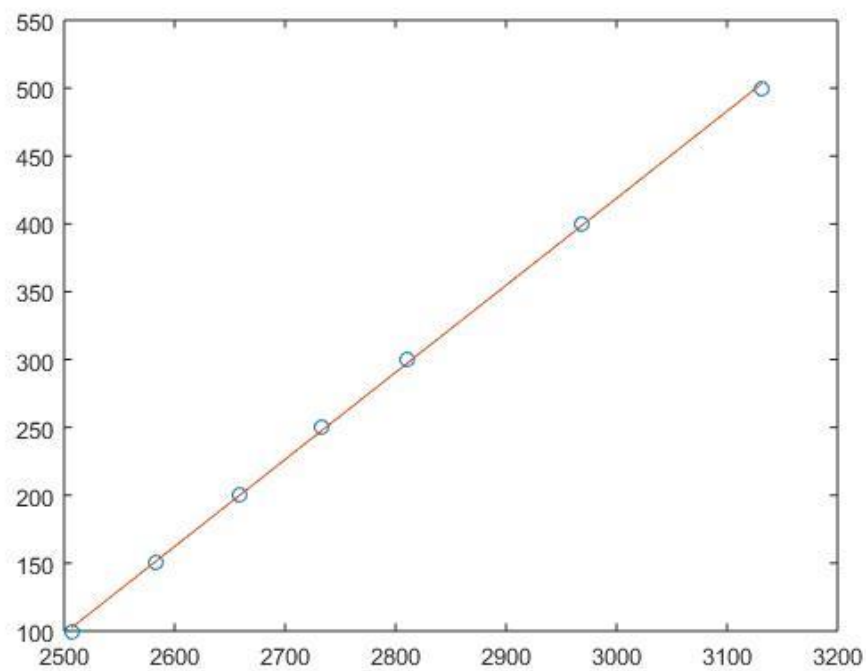
The default is linear interpolation. Use an empty matrix `[]` to specify the default. Available methods are:

- 'nearest' - nearest neighbor interpolation
- 'next' - next neighbor interpolation
- 'previous' - previous neighbor interpolation
- 'linear' - linear interpolation
- 'spline' - piecewise cubic spline interpolation (SPLINE)
- 'pchip' - shape-preserving piecewise cubic interpolation
- 'cubic' - same as 'pchip'
- 'v5cubic' - the cubic interpolation from MATLAB 5, which does not extrapolate and uses 'spline' if X is not equally spaced.

Curve Fitting

Linear Regression

```
T = [100,150,200,250,300,400,500];  
u = [2506.7,2582.8,2658.1,2733.7,2810.4,2967.9,3131.6];  
  
n = 1;  
  
p = polyfit(u,T,n);  
% y = ax+b  
a = p(1);  
b = p(2);  
x= u;  
ymodel = a*x+b;  
  
plot(u,T, 'o', u, ymodel);
```



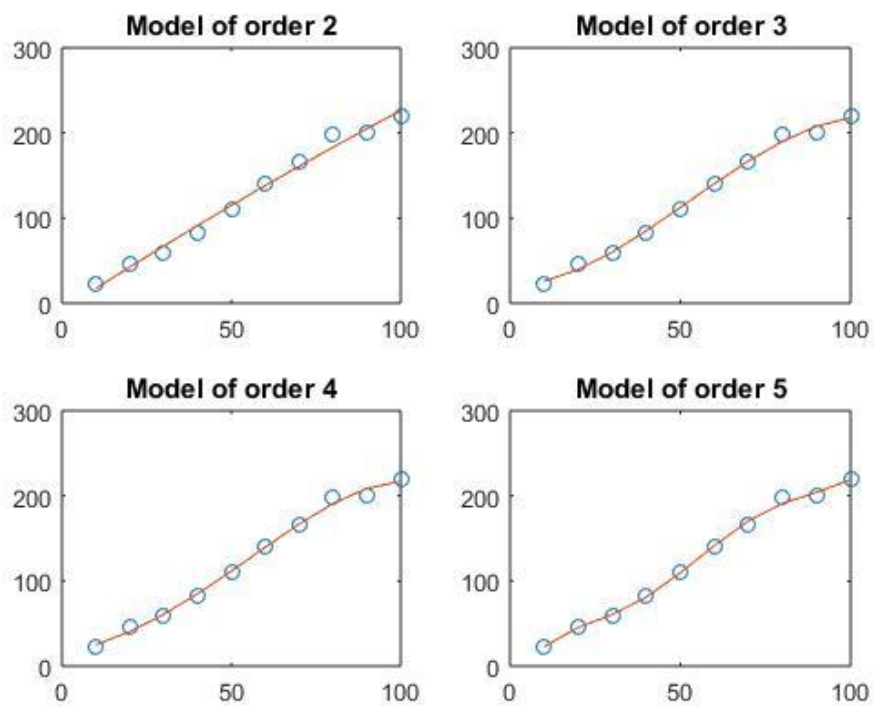
Polynomial Regression

```

x = [10:10:100];
y = [23,45,60,82,111,140,167,198,200,220];

for n=2:5
    p=polyfit(x,y,n);
    ymodel = polyval(p,x);
    subplot(2,2,n-1)
    plot(x,y,'o',x,ymodel);
    title(sprintf('Model of order %d',n));
end

```



Optimization

Minimum value of a polynomial

```
>> % minimum of a polynomial
>> x = -20:0.1:20;
>> y = 2.*x.^2 + 20.*x - 22;
>> plot(x,y)
>> grid on
>> i=1;
>> while (y(i) > y(i+1))
i = i + 1;
end
>> x(i)
ans =
    -5
>> y(i)
ans =
   -72
```