### Imperial College London

# **Computer Networks** and Distributed Systems

**Tutorial – Bridging and Routing Protocols** 

Course 527 - Spring Term 2015-2016

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### **Spanning Tree Protocol (Layer 2)**

Used by switches to turn a redundant topology into a **spanning tree**:

- Avoid and **eliminate loops** in the network by negotiating a loop-free path through a **root bridge**.
- Disables unwanted links by **blocking** ports.
- Ensures that there will be only one active path to every destination.

STP defined by IEEE 802.1d.

Switches run STP by default – no configuration needed.

#### Part 4 - Contents

Spanning Tree Bridging Protocol

Distance Vector Routing Protocol

Link-State Routing Protocol

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### **Spanning Tree Algorithm**

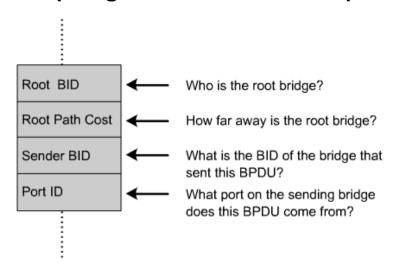
The switches use this algorithm to decide which ports should be shut down.

- 1. Choose one switch to be "root bridge"
- 2. Choose a "root port" on each other switch
- 3. Choose a "designated port" on each segment.
- 4. Close down all other ports.

See step-by-step example at:

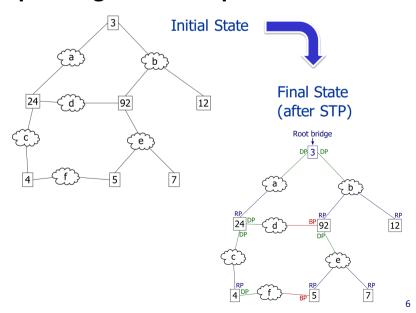
http://www.cisco.com/image/gif/paws/10556/spanning\_tree1.swf

### **BPDU (Bridge Protocol Data Units)**



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### **Spanning Tree Example**



### **Root and Designated Ports**

**Root Port**: This is the port that is the closest to the root bridge in terms of path cost.

**Designated port**: it can send the best BPDU on the segment to which it is connected.

- On a given segment, there can be only one path toward the root bridge otherwise redundant paths would create a bridging loop.
- All bridges connected to a given segment listen to each other's BPDUs and agree on the bridge sending the best BPDU as the designated bridge for the segment.

A Root Port can **never** be a Designated Port.

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### **Distance Vector Protocol (Layer 3)**

A **distance vector routing** algorithm operates by having each router maintain a table (i.e., vector):

- Best known distance to each router.
- Which link to use to get there.

Each table is indexed by, and containing one entry for each router in the network:

- Preferred outgoing line for that destination.
- Estimate of the distance to that destination.

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#### **Distance Vector Protocol**

A router is assumed to know the **distance** (cost) to each of its neighbors.

Once every  $T_{msec'}$  each router sends to each neighbor a list of its **estimated delays** to each destination:

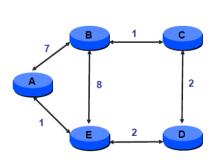
- It also receives a similar list from each neighbor.

#### If R has neighbor X:

- Table from X:  $X_i$ = estimated delay to get to router i.
- If delay to X estimated by R is m:
  - R can reach i in m+X<sub>i</sub> msec.

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### **Example: Initial State**



Info at	ſ	Distance to Node												
node	Α	В	С	D	Ε									
Α	0	7	00	œ	1									
В	7	0	1	00	8									
С	∞	1	0	2	00									
D	∞	00	2	0	2									
E	1	8	00	2	0									

### **Bellman-Ford Algorigthm**

 $c(x,v) = \cos t$  for direct link from x to v:

– Node x maintains costs of direct links c(x,v).

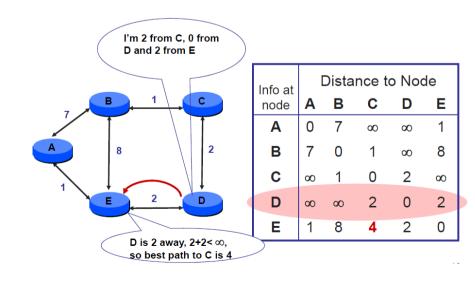
 $D_x(y)$  = estimate of least cost from x to y:

- Node x maintains distance vector  $D_x = [D_x(y): y \in N]$ . Node x maintains its neighbors' distance vectors:

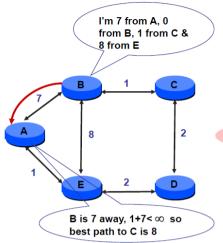
– For each neighbor v, x maintains  $D_v = [D_v(y): y \in N]$ . Each node v periodically sends  $D_v$  to its neighbors:

- And neighbors update their own distance vectors.
- $D_x(y)$  ←  $min_v\{c(x,v)+D_v(y)\}$  for each node  $y \in N$ .

D Sends Vector to E



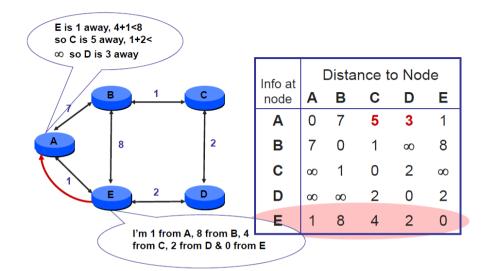
### **B Sends Vector to A**



	Info at	Distance to Node												
	node	Α	В	С	D	E								
	Α	0	7	8	00	1								
	В	7	0	1	∞	8								
	С	œ	1	0	2	00								
	D	œ	$\infty$	2	0	2								
,	Ε	1	8	4	2	0								

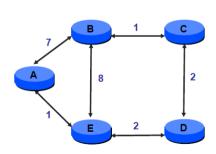
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### **E Sends Vector to A**



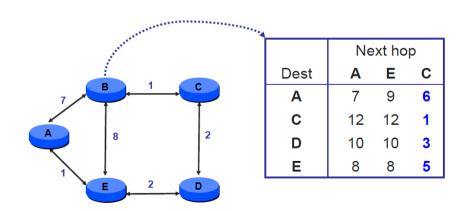
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# **Until Convergence**



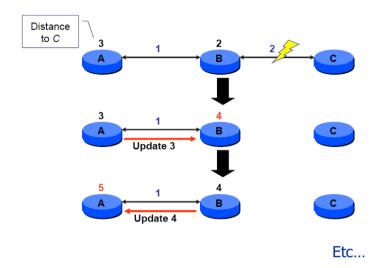
Info at	Distance to Node											
node	Α	В	С	D	E							
Α	0	6	5	3	1							
В	6	0	1	3	5							
С	5	1	0	2	4							
D	3	3	2	0	2							
E	1	5	4	2	0							

### **Node B's Distance Vector**



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### **Counting to Infinity Problem**



### **Link-State Routing (Layer 3)**

#### Same goal as Distance Vector, but different approach:

 Tell every node what you know about your direct neighbors.

#### Two phases:

- Reliable flooding:
  - Tell all routers what you know about your local topology.
- **Path calculation** (Dijkstra's algorithm):
  - Each router computes best path over complete network.

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## **Reliable-Flooding**

Each router transmits a Link State Packet on all links:

- Identifier of the sender.
- List of neighbors with their associated costs.

A neighboring router **forwards** out all links except incoming.

Keep a copy locally; don't forward previously-seen LSPs.

#### **Caveats**:

- Acknowledgments and retransmissions.
- Sequence numbers.
- Time-to-live for each packet.

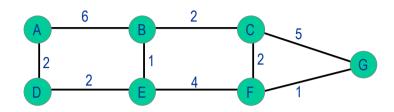
### **Running Dijkstra Algorithm**

Determine the **shortest distance** between a start node and any other node in a graph.

```
1: function Dijkstra(Graph, source):
      for each vertex v in Graph:
                                       // Initialization
3:
        dist[v] := infinity
                                       // Initial distance from source to v is set to \infty
        previous[v] := undefined
                                        // Previous node in optimal path from source
4:
                                      // Distance from source to source
5:
     dist[source] := 0
      Q := the set of all nodes in Graph // All nodes in the graph are unoptimized
      while Q is not empty:
                                       // main loop
7:
        u := node in Q with smallest dist[]
8:
9:
        remove u from Q
10:
        for each neighbor v of u:
                                       // where v has not yet been removed from Q.
11:
          alt := dist[u] + dist\_between(u, v)
12:
          if alt < dist[v] // Relax (u,v)
13:
            dist[v] := alt
14:
             previous[v] := u
      return previous[]
```

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Consider the following network:



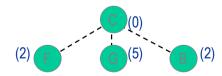
Link state database:

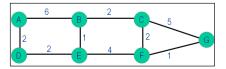
	Α			В			С		D				E			F			G		
	В	6		Α	6		В	6		Α	2		В	1		С	2		С	5	
	D	2	П	С	2		F	2		Е	2		D	2		Е	4		F	1	
,				Е	1		G	5				-	F	4		G	1				

# Dijkstra's LSR Algorithm

Examine C's LSP

- Cost to F, G, and B

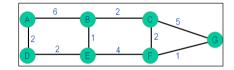




# Dijkstra's LSR Algorithm

Running Dijkstra on C

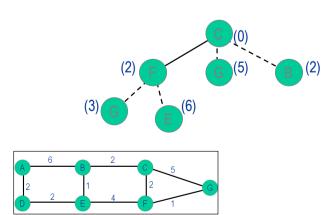




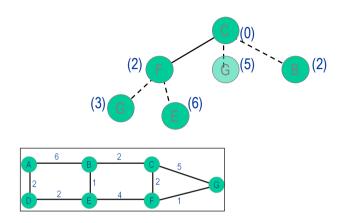
# Dijkstra's LSR Algorithm

Pick node in Q with lowest dist: F

- Its predecessor is determined: C (cannot be changed)

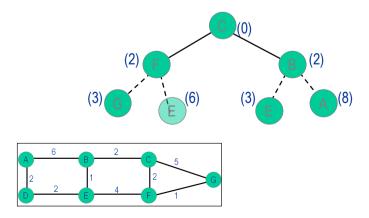


Update G cost and predecessor



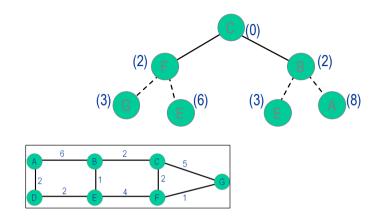
# Dijkstra's LSR Algorithm

Update E cost and predecessor



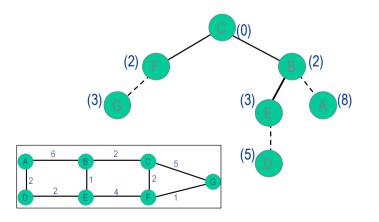
# Dijkstra's LSR Algorithm

Pick node in Q with lowest dist: B

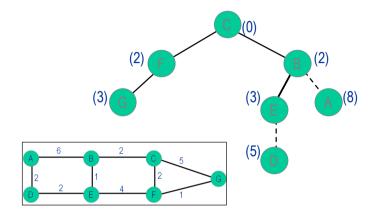


# Dijkstra's LSR Algorithm

Pick node in Q with lowest dist: E

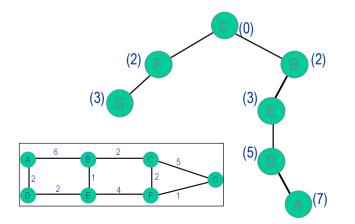


Pick node in Q with lowest dist: G



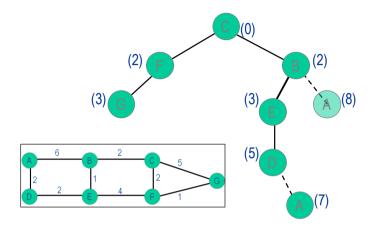
# Dijkstra's LSR Algorithm

Pick node in Q with lowest dist: A



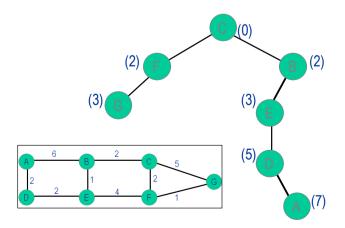
# Dijkstra's LSR Algorithm

Pick node in Q with lowest dist: D
- Update A cost and predecessor



# Dijkstra's LSR Algorithm

Q is empty: DONE



We can now create a routing (forwarding) table for C:

