

mdp

November 22, 2020

Citation – Used multiple resources to understand and compile code for MDP algorithm.

```
[1]: import gym
import time
import random
import numpy as np
import pandas as pd
import matplotlib.pyplot as plt
import seaborn as sns
from gym.envs.toy_text.frozen_lake import generate_random_map
from hiive.mdptoolbox.mdp import PolicyIteration, ValueIteration, QLearning, u
    ↪ PolicyIterationModified
from hiive.mdptoolbox.example import forest
from timeit import default_timer as timer
from datetime import timedelta

import warnings
warnings.filterwarnings('ignore')
```

1 Functions

```
[2]: def frozen_lake_environment(size=4,p=0.80):
    __size = size
    environment = 'FrozenLake-v0'
    desc_map = generate_random_map(size=__size,p=p)
    env = gym.make(environment,desc=desc_map,is_slippery=True)
    env.reset()

    #     env = gym.make(environment)
    states = env.observation_space.n
    actions = env.action_space.n
    env = env.unwrapped
    desc = env.unwrapped.desc
    return env, desc, states, actions, __size

[3]: def frozen_lake_get_PR(env,states,actions):
    prob_transitions = np.zeros((actions, states, states))
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rewards = np.zeros((states,actions))
for state in env.P:
    for action in env.P[state]:
        for opt in env.P[state][action]:
            prob_transitions[action][state][opt[1]] += opt[0]
            rewards[state][action] += opt[2]
return prob_transitions, rewards

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[4]: def forest_get_PR(input_state):
    prob_transitions, rewards = forest(S=input_state)
    return prob_transitions, rewards

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[5]: def
    ↪gamma_analysis(gamma_prob_transitions,gamma_rewards,gamma_size,gamma_gammas=np.
    ↪arange(0.1, 0.99, 0.01)):
    VI_ary, PI_ary = [],[]
    #     gammas = np.arange(0.1, 0.99, 0.04)
    gammas = gamma_gammas
    for gamma in gammas:
        vi = ValueIteration(gamma_prob_transitions,gamma_rewards, gamma)
        vi.run()
        vi_time = vi.time
        vi_max_value = np.amax(vi.V)
        vi_mean_value = np.mean(vi.V)
        vi_value = vi.V
        vi_iters = vi.iter
        vi_policy = vi.policy
        VI_ary.
    ↪append(['VI',gamma_size,gamma,vi_time,vi_max_value,vi_mean_value,vi_iters,vi_policy,vi_valu

        pi = PolicyIteration(gamma_prob_transitions,gamma_rewards, gamma)
        pi.run()
        pi_time = pi.time
        pi_max_value = np.amax(pi.V)
        pi_mean_value = np.mean(pi.V)
        pi_value = pi.V
        pi_iters = pi.iter
        pi_policy = pi.policy
        PI_ary.
    ↪append(['PI',gamma_size,gamma,pi_time,pi_max_value,pi_mean_value,pi_iters,pi_policy,pi_valu

    df_vi = pd.
    ↪DataFrame(VI_ary,columns=['iter_type','size','gamma','time','max_value','mean_value','itera
    df_pi = pd.
    ↪DataFrame(PI_ary,columns=['iter_type','size','gamma','time','max_value','mean_value','itera
    return df_vi, df_pi

```

```
[6]: def plot_gamma_analysis(gamma_df_vi, gamma_df_pi):
    fig, axs = plt.subplots(nrows=1, ncols=4, figsize=(20,4))
    sns.lineplot(gamma_df_vi['gamma'], gamma_df_vi['iterations'], linestyle='-.',
    ↪', label = "Value Iteration", ax=axs[0], alpha=0.5, color='red')
    sns.lineplot(gamma_df_pi['gamma'], gamma_df_pi['iterations'],
    ↪linestyle='--', label = "Policy Iteration", ax=axs[0], alpha=0.5,
    ↪color='blue')
    axs[0].set_title('Iterations vs Gamma')

    sns.lineplot(gamma_df_vi['gamma'], gamma_df_vi['time'], linestyle='-.',
    ↪label = "Value Iteration", ax=axs[1], alpha=0.5, color='red')
    sns.lineplot(gamma_df_pi['gamma'], gamma_df_pi['time'], linestyle='--',
    ↪label = "Policy Iteration", ax=axs[1], alpha=0.5, color='blue')
    axs[1].set_title('Time vs Gamma')

    sns.lineplot(gamma_df_vi['gamma'], gamma_df_vi['max_value'], linestyle='-.',
    ↪', label = "Value Iteration", ax=axs[2], alpha=0.5, color='red')
    sns.lineplot(gamma_df_pi['gamma'], gamma_df_pi['max_value'],
    ↪linestyle='--', label = "Policy Iteration", ax=axs[2], alpha=0.5,
    ↪color='blue')
    axs[2].set_title('Max Value vs Gamma')

    sns.lineplot(gamma_df_vi['gamma'], gamma_df_vi['mean_value'], linestyle='-.',
    ↪', label = "Value Iteration", ax=axs[3], alpha=0.5, color='red')
    sns.lineplot(gamma_df_pi['gamma'], gamma_df_pi['mean_value'],
    ↪linestyle='--', label = "Policy Iteration", ax=axs[3], alpha=0.5,
    ↪color='blue')
    axs[3].set_title('Mean Value vs Gamma')

    for ax in axs.flat:
        ax.legend(loc='best')
        ax.minorticks_on()
        ax.grid(b=True, which='major', color='k', linestyle='-', alpha=0.1)
        ax.grid(b=True, which='minor', color='r', linestyle='-', alpha=0.05)
    fig.tight_layout()
```

```
[7]: def
    ↪epsilon_analysis(epsilon_prob_transitions, epsilon_rewards, epsilon_size, epsilon_
    ↪arange(0.001, 0.05, 0.001), epsilon_gamma=0.99):
        VI_ary, PI_ary = [], []
        gamma = epsilon_gamma
    #     epsilons = np.arange(0.001, 0.05, 0.005)
        epsilons = epsilon_epsilons

    for epsilon in epsilons:
```

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        vi = ValueIteration(epsilon_prob_transitions, epsilon_rewards, gamma,
↪epsilon=epsilon)
        vi.run()
        vi_time = vi.time
        vi_max_value = np.amax(vi.V)
        vi_mean_value = np.mean(vi.V)
        vi_value = vi.V
        vi_iters = vi.iter
        vi_policy = vi.policy
        VI_ary.
↪append(['VI', epsilon_size, epsilon, vi_time, vi_max_value, vi_mean_value, vi_iters, vi_policy, vi_

        pi = PolicyIterationModified(epsilon_prob_transitions, epsilon_rewards,
↪gamma, epsilon=epsilon)
        pi.run()
        pi_time = pi.time
        pi_max_value = np.amax(pi.V)
        pi_mean_value = np.mean(pi.V)
        pi_value = pi.V
        pi_iters = pi.iter
        pi_policy = pi.policy
        PI_ary.
↪append(['PI', epsilon_size, epsilon, pi_time, pi_max_value, pi_mean_value, pi_iters, pi_policy, pi_

        df_vi = pd.
↪DataFrame(VI_ary, columns=['iter_type', 'size', 'epsilon', 'time', 'max_value', 'mean_value', 'ite
        df_pi = pd.
↪DataFrame(PI_ary, columns=['iter_type', 'size', 'epsilon', 'time', 'max_value', 'mean_value', 'ite
        return df_vi, df_pi

```

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[8]: def plot_epsilon_analysis(epsilon_df_vi, epsilon_df_pi):
    fig, axs = plt.subplots(nrows=1, ncols=4, figsize=(20,4))
    sns.lineplot(epsilon_df_vi['epsilon'], epsilon_df_vi['iterations'],
↪linestyle='-.', label = "Value Iteration", ax=axs[0], alpha=0.5, color='red')
    sns.lineplot(epsilon_df_pi['epsilon'], epsilon_df_pi['iterations'],
↪linestyle='--', label = "Policy Iteration", ax=axs[0], alpha=0.5,
↪color='blue')
    axs[0].set_title('Iterations vs Epsilon')

    sns.lineplot(epsilon_df_vi['epsilon'], epsilon_df_vi['time'], linestyle='-.
↪', label = "Value Iteration", ax=axs[1], alpha=0.5, color='red')
    sns.lineplot(epsilon_df_pi['epsilon'], epsilon_df_pi['time'],
↪linestyle='--', label = "Policy Iteration", ax=axs[1], alpha=0.5,
↪color='blue')
    axs[1].set_title('Time vs Epsilon')

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sns.lineplot(epsilon_df_vi['epsilon'], epsilon_df_vi['max_value'],
↳linestyle='-.', label = "Value Iteration", ax=axes[2], alpha=0.5, color='red')
sns.lineplot(epsilon_df_pi['epsilon'], epsilon_df_pi['max_value'],
↳linestyle='--', label = "Policy Iteration", ax=axes[2], alpha=0.5,
↳color='blue')
axes[2].set_title('Max Value vs Epsilon')

sns.lineplot(epsilon_df_vi['epsilon'], epsilon_df_vi['mean_value'],
↳linestyle='-.', label = "Value Iteration", ax=axes[3], alpha=0.5, color='red')
sns.lineplot(epsilon_df_pi['epsilon'], epsilon_df_pi['mean_value'],
↳linestyle='--', label = "Policy Iteration", ax=axes[3], alpha=0.5,
↳color='blue')
axes[3].set_title('Mean Value vs Epsilon')

for ax in axes.flat:
    ax.legend(loc='best')
    ax.minorticks_on()
    ax.grid(b=True, which='major', color='k', linestyle='-', alpha=0.1)
    ax.grid(b=True, which='minor', color='r', linestyle='-', alpha=0.05)
fig.tight_layout()

```

```

[9]: def optimal_policy(optimal_df_vi,optimal_df_pi,optimal_size,epsilon,env_type):
    optimal_vi = optimal_df_vi[optimal_df_vi['epsilon'] == epsilon]
    optimal_pi = optimal_df_pi[optimal_df_pi['epsilon'] == epsilon]

    print(optimal_vi.shape)
    print(optimal_pi.shape)
    print(np.array(list(optimal_vi['policy'])).shape)
    print(np.array(list(optimal_pi['policy'])).shape)

    if env_type == 'frozen-lake':
        vi_policy_arr = np.array(list(optimal_vi['policy'])).
↳reshape(optimal_size,optimal_size).astype(str)
        vi_value_arr = np.round(np.array(list(optimal_vi['value'])).
↳reshape(optimal_size,optimal_size),2)

        vi_policy_arr[vi_policy_arr=='0'] = '←'
        vi_policy_arr[vi_policy_arr=='1'] = '↓'
        vi_policy_arr[vi_policy_arr=='2'] = '→'
        vi_policy_arr[vi_policy_arr=='3'] = '↑'

        vi_policy_viz = (np.asarray([a+" "+str(v) for a, v in zip(vi_policy_arr.
↳flatten(), vi_value_arr.flatten())])).reshape(optimal_size,optimal_size)

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elif env_type == 'forest':

    vi_policy_arr = np.array(list(optimal_vi['policy'])).
    ↪reshape(optimal_size).astype(str)
    vi_value_arr = np.round(np.array(list(optimal_vi['value']))).
    ↪reshape(optimal_size),2)

    vi_policy_arr[vi_policy_arr=='0'] = 'W'
    vi_policy_arr[vi_policy_arr=='1'] = 'C'

    vi_policy_viz = (np.asarray([a+" "+str(v) for a, v in zip(vi_policy_arr.
    ↪flatten(), vi_value_arr.flatten())])).reshape(optimal_size)

    if env_type == 'frozen-lake':
        pi_policy_arr = np.array(list(optimal_pi['policy'])).
        ↪reshape(optimal_size,optimal_size).astype(str)
        pi_value_arr = np.round(np.array(list(optimal_pi['value']))).
        ↪reshape(optimal_size,optimal_size),2)

        pi_policy_arr[pi_policy_arr=='0'] = '←'
        pi_policy_arr[pi_policy_arr=='1'] = '↓'
        pi_policy_arr[pi_policy_arr=='2'] = '→'
        pi_policy_arr[pi_policy_arr=='3'] = '↑'

        pi_policy_viz = (np.asarray([a+" "+str(v) for a, v in zip(pi_policy_arr.
        ↪flatten(), pi_value_arr.flatten())])).reshape(optimal_size,optimal_size)
    elif env_type == 'forest':

        pi_policy_arr = np.array(list(optimal_pi['policy'])).
        ↪reshape(optimal_size).astype(str)
        pi_value_arr = np.round(np.array(list(optimal_pi['value']))).
        ↪reshape(optimal_size),2)

        pi_policy_arr[pi_policy_arr=='0'] = 'W'
        pi_policy_arr[pi_policy_arr=='1'] = 'C'

        pi_policy_viz = (np.asarray([a+" "+str(v) for a, v in zip(pi_policy_arr.
        ↪flatten(), pi_value_arr.flatten())])).reshape(optimal_size)

    return vi_value_arr, vi_policy_viz, pi_value_arr, pi_policy_viz

```

```

[10]: def plot_optimnal_policy(plot_vi_value_arr, plot_vi_policy_viz,
    ↪plot_pi_value_arr, plot_pi_policy_viz,plot_size,env_type):

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if env_type == 'frozen-lake':
    plt.figure(figsize=(plot_size,plot_size))
    plt.title("Value Iteration: Optimal Policy")
    sns.heatmap(plot_vi_value_arr, annot=plot_vi_policy_viz, fmt="")

    plt.figure(figsize=(plot_size,plot_size))
    plt.title("Policy Iteration: Optimal Policy")
    sns.heatmap(plot_pi_value_arr, annot=plot_pi_policy_viz, fmt="")
elif env_type == 'forest':
    print("Value Iteration: Optimal Policy")
    line=""
    for val in plot_vi_policy_viz:
        line += (" {} |".format(val))
    print(line)

    print("Value Iteration: Optimal Policy")
    line=""
    for val in plot_pi_policy_viz:
        line += (" {} |".format(val))
    print(line)

```

```

[11]: def size_analysis(size_env_type,size_sizes,size_gamma=0.99):

    # fl_size = 8
    # fl_p = 0.85
    # env, desc, states, actions, size = frozen_lake_environment(fl_size,fl_p)

    # fl_prob_transitions, fl_rewards = frozen_lake_get_PR(env,states,actions)

    # fm_size = 1000
    # fm_prob_transitions, fm_rewards = forest_get_PR(fm_size)

    sizes = size_sizes
    gamma = size_gamma
    VI_ary, PI_ary = [],[]

    for size in sizes:
        if size_env_type == 'frozen-lake':
            fl_p = 0.85
            env, desc, states, actions, _ = frozen_lake_environment(size,fl_p)
            size_prob_transitions, size_rewards =  
            →frozen_lake_get_PR(env,states,actions)
        elif size_env_type == 'forest':
            size_prob_transitions, size_rewards = forest_get_PR(size)

        vi = ValueIteration(size_prob_transitions, size_rewards, gamma)

```

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vi.run()
vi_time = vi.time
vi_max_value = np.amax(vi.V)
vi_mean_value = np.mean(vi.V)
vi_value = vi.V
vi_iters = vi.iter
vi_policy = vi.policy
VI_ary.
↪append(['VI',size,vi_time,vi_max_value,vi_mean_value,vi_iters,vi_policy,vi_value])

pi = PolicyIterationModified(size_prob_transitions, size_rewards, gamma)
pi.run()
pi_time = pi.time
pi_max_value = np.amax(pi.V)
pi_mean_value = np.mean(pi.V)
pi_value = pi.V
pi_iters = pi.iter
pi_policy = pi.policy
PI_ary.
↪append(['PI',size,pi_time,pi_max_value,pi_mean_value,pi_iters,pi_policy,pi_value])

df_vi = pd.
↪DataFrame(VI_ary,columns=['iter_type','size','time','max_value','mean_value','iterations',''])
df_pi = pd.
↪DataFrame(PI_ary,columns=['iter_type','size','time','max_value','mean_value','iterations',''])
return df_vi, df_pi

```

```

[12]: def plot_size_analysis(size_df_vi, size_df_pi):
    fig, axs = plt.subplots(nrows=1, ncols=4, figsize=(20,4))
    sns.lineplot(size_df_vi['size'], size_df_vi['iterations'], linestyle='-.',
↪label = "Value Iteration", ax=axs[0], alpha=0.5, color='red')
    sns.lineplot(size_df_pi['size'], size_df_pi['iterations'], linestyle='--',
↪label = "Policy Iteration", ax=axs[0], alpha=0.5, color='blue')
    axs[0].set_title('Iterations vs size')

    sns.lineplot(size_df_vi['size'], size_df_vi['time'], linestyle='-.', label=
↪= "Value Iteration", ax=axs[1], alpha=0.5, color='red')
    sns.lineplot(size_df_pi['size'], size_df_pi['time'], linestyle='--', label=
↪= "Policy Iteration", ax=axs[1], alpha=0.5, color='blue')
    axs[1].set_title('Time vs size')

    sns.lineplot(size_df_vi['size'], size_df_vi['max_value'], linestyle='-.',
↪label = "Value Iteration", ax=axs[2], alpha=0.5, color='red')
    sns.lineplot(size_df_pi['size'], size_df_pi['max_value'], linestyle='--',
↪label = "Policy Iteration", ax=axs[2], alpha=0.5, color='blue')

```



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    axs[2].set_title('Max Value vs size')

    sns.lineplot(size_df_vi['size'], size_df_vi['mean_value'], linestyle='-.',
    ↪label = "Value Iteration", ax=axs[3], alpha=0.5, color='red')
    sns.lineplot(size_df_pi['size'], size_df_pi['mean_value'], linestyle='--',
    ↪label = "Policy Iteration", ax=axs[3], alpha=0.5, color='blue')
    axs[3].set_title('Mean Value vs size')

    for ax in axs.flat:
        ax.legend(loc='best')
        ax.minorticks_on()
        ax.grid(b=True, which='major', color='k', linestyle='-', alpha=0.1)
        ax.grid(b=True, which='minor', color='r', linestyle='-', alpha=0.05)
    fig.tight_layout()

```

```

[13]: def
    ↪ql_gamma_analysis(ql_gamma_prob_transitions,ql_gamma_rewards,ql_gamma_size,ql_gamma_gammas=
    ↪arange(0.1, 0.99, 0.01),ql_gamma_n_iter=100000):

        gammas = ql_gamma_gammas
        Q_ary = []

        for gamma in gammas:
            ql = QLearning(ql_gamma_prob_transitions,ql_gamma_rewards,
            ↪gamma,n_iter=ql_gamma_n_iter)
            ql.run()
            ql_time = ql.time
            ql_max_value = np.amax(ql.V)
            ql_mean_value = np.mean(ql.V)
            ql_value = ql.V
            ql_q_matrix = ql.Q
            ql_policy = ql.policy
            #         ql_mean_discrepancy = ql.mean_discrepancy
            #         Q_ary.
            ↪append(['QL', gamma_size, gamma, ql_time, ql_max_value, ql_mean_value, ql_q_matrix, ql_policy, ql_v
            Q_ary.
            ↪append(['QL', ql_gamma_size, gamma, ql_time, ql_max_value, ql_mean_value, ql_q_matrix, ql_policy, q

            #         df_ql = pd.
            ↪DataFrame(VI_ary, columns=['iter_type', 'size', 'gamma', 'time', 'max_value', 'mean_value', 'q_mat
            df_gamma_ql = pd.
            ↪DataFrame(Q_ary, columns=['iter_type', 'size', 'gamma', 'time', 'max_value', 'mean_value', 'q_matr
            return df_gamma_ql

```

```
[14]: def plot_ql_gamma_analysis(plot_gamma_df_ql):

    fig, axs = plt.subplots(nrows=1, ncols=3, figsize=(20,4))

    #     sns.lineplot(plot_gamma_df_ql['gamma'], plot_gamma_df_ql['iterations'],
    ↪linestyle='-.', label = "Value Iteration", ax=axs[0], alpha=0.5, color='red')
    #     axs[0].set_title('Iterations vs Gamma')

    sns.lineplot(plot_gamma_df_ql['gamma'], plot_gamma_df_ql['time'],
    ↪linestyle='-.', label = "Q Learning", ax=axs[0], alpha=0.5, color='red')
    axs[0].set_title('Time vs Gamma')

    sns.lineplot(plot_gamma_df_ql['gamma'], plot_gamma_df_ql['max_value'],
    ↪linestyle='-.', label = "Q Learning", ax=axs[1], alpha=0.5, color='red')
    axs[1].set_title('Max Value vs Gamma')

    sns.lineplot(plot_gamma_df_ql['gamma'], plot_gamma_df_ql['mean_value'],
    ↪linestyle='-.', label = "Q Learning", ax=axs[2], alpha=0.5, color='red')
    axs[2].set_title('Mean Value vs Gamma')

    for ax in axs.flat:
        ax.legend(loc='best')
        ax.minorticks_on()
        ax.grid(b=True, which='major', color='k', linestyle='-', alpha=0.1)
        ax.grid(b=True, which='minor', color='r', linestyle='-', alpha=0.05)
    fig.tight_layout()

[15]: def
    ↪ql_n_iter_analysis(ql_n_iter_prob_transitions,ql_n_iter_rewards,ql_n_iter_size,ql_n_iter_gamma,
    ↪99,ql_n_iter_epsilon=0.9,ql_n_iter_n_iters=[10000,50000,100000]):

    n_iters = ql_n_iter_n_iters
    Q_ary = []
    run_stats = []

    for n_iter in n_iters:
    #     ql = QLearning(ql_n_iter_prob_transitions,ql_n_iter_rewards,
    ↪ql_n_iter_gamma,epsilon=ql_n_iter_epsilon,n_iter=n_iter)
    ql = QLearning(ql_n_iter_prob_transitions,ql_n_iter_rewards,
    ↪ql_n_iter_gamma,epsilon=ql_n_iter_epsilon)
        ql.max_iter = n_iter
        ql_run_stat = ql.run()
        run_stats.extend(ql_run_stat)
    #     print(run_stats)
```

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        ql_time = ql.time
        ql_max_value = np.amax(ql.V)
        ql_mean_value = np.mean(ql.V)
        ql_value = ql.V
        ql_q_matrix = ql.Q
        ql_policy = ql.policy
#         ql_mean_discrepancy = ql.mean_discrepancy
#         Q_ary.
    →append(['QL',gamma_size,gamma,ql_time,ql_max_value,ql_mean_value,ql_q_matrix,ql_policy,ql_v
        Q_ary.
    →append(['QL',ql_n_iter_size,n_iter,ql_time,ql_max_value,ql_mean_value,ql_q_matrix,ql_policy

#         df_ql = pd.
    →DataFrame(VI_ary,columns=['iter_type','size','gamma','time','max_value','mean_value','q_mat
        df_n_iter_ql = pd.
    →DataFrame(Q_ary,columns=['iter_type','size','iterations','time','max_value','mean_value','q
        df_n_iter_run_stat = pd.DataFrame.from_dict(ql_run_stat,orient='columns')
    return df_n_iter_ql, df_n_iter_run_stat

```

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[16]: def plot_ql_n_iter_analysis(plot_n_iter_df_ql,plot_df_n_iter_run_stat):

    fig, axs = plt.subplots(nrows=1, ncols=3, figsize=(20,5))

#     sns.lineplot(plot_n_iter_df_ql['gamma'], plot_n_iter_df_ql['iterations'],□
    →linestyle='-.', label = "Value Iteration", ax=axs[0], alpha=0.5, color='red')
#     axs[0].set_title('Iterations vs Gamma')

    sns.lineplot(plot_n_iter_df_ql['iterations'], plot_n_iter_df_ql['time'],□
    →linestyle='-.', label = "Q Learning", ax=axs[0], alpha=0.5, color='red')
    axs[0].set_title('Time vs Iterations')

    sns.lineplot(plot_n_iter_df_ql['iterations'],□
    →plot_n_iter_df_ql['max_value'], linestyle='-.', label = "Q Learning",□
    →ax=axs[1], alpha=0.5, color='red')
    axs[1].set_title('Max Value vs Iterations')

    sns.lineplot(plot_n_iter_df_ql['iterations'],□
    →plot_n_iter_df_ql['mean_value'], linestyle='-.', label = "Q Learning",□
    →ax=axs[2], alpha=0.5, color='red')
    axs[2].set_title('Mean Value vs Iterations')

#     sns.lineplot(plot_df_n_iter_run_stat['Iteration'],□
    →plot_df_n_iter_run_stat['Mean V'], linestyle='-.', label = "Q Learning",□
    →ax=axs[3], alpha=0.5, color='red')
#     axs[3].set_title('Mean Value vs Iterations')

```

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for ax in axs.flat:
    ax.legend(loc='best')
    ax.minorticks_on()
    ax.grid(b=True, which='major', color='k', linestyle='-', alpha=0.1)
    ax.grid(b=True, which='minor', color='r', linestyle='-', alpha=0.05)
fig.tight_layout()

```

2 Set Environments

2.1 Frozen Lake

```

[21]: fl_size = 8
      fl_p = 0.95
      fl_env, fl_desc, fl_states, fl_actions, fl_size = frozen\_lake\_environment(fl_size, fl_p)

```

```

[22]: fl_prob_transitions, fl_rewards = frozen\_lake\_get\_PR(fl_env, fl_states, fl_actions)

```

```

[ ]:

```

```

[ ]:

```

2.2 Forest Management

```

[23]: fm_size = 1000
      fm_prob_transitions, fm_rewards = forest\_get\_PR(fm_size)

```

```

[24]: fm_states = fm_size
      fm_actions = 2

```

3 Value Iteration and Policy Iteration

3.1 Gamma Analysis

```

[25]: fl_gammas = np.arange(0.1, 0.99, 0.04)
      fl_df_gamma_vi, fl_df_gamma_pi = gamma\_analysis(fl_prob_transitions, fl\_rewards, fl_size, fl_gammas)

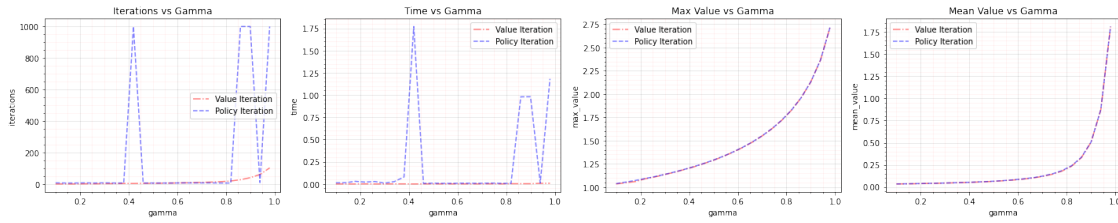
```

```

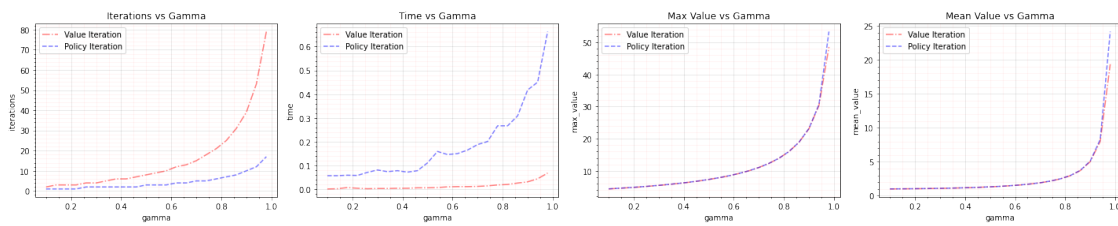
[26]: fm_gammas = np.arange(0.1, 0.99, 0.04)
      fm_df_gamma_vi, fm_df_gamma_pi = gamma\_analysis(fm_prob_transitions, fm\_rewards, fm_size, fm_gammas)

```

```
[27]: plot_gamma_analysis(fl_df_gamma_vi, fl_df_gamma_pi)
```



```
[28]: plot_gamma_analysis(fm_df_gamma_vi, fm_df_gamma_pi)
```

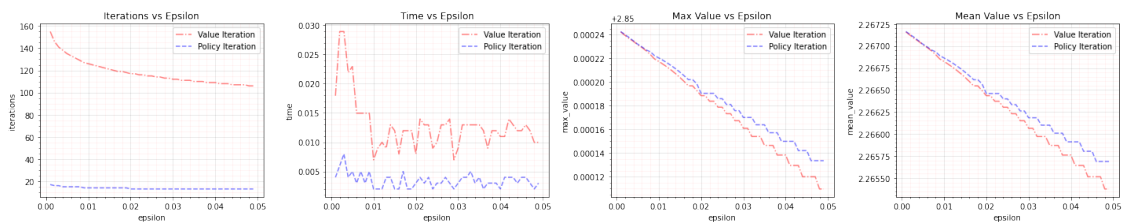


3.2 Epsilon Analysis

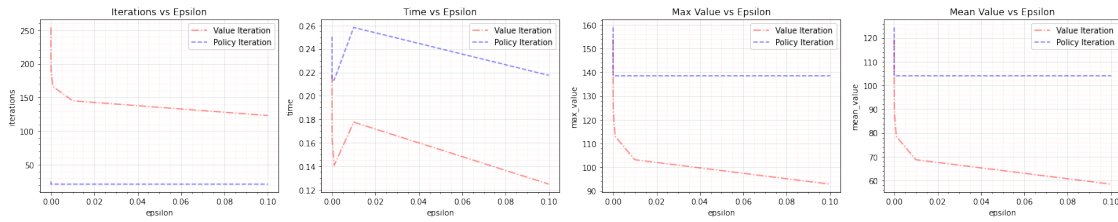
```
[29]: fl_epsilons = np.arange(0.001,0.05, 0.001)
fl_gamma = 0.99
fl_df_epsilon_vi, fl_df_epsilon_pi = epsilon_analysis(fl_prob_transitions,
↪fl_rewards,fl_size,fl_epsilons,fl_gamma)
```

```
[30]: # fm_epsilons = np.arange(0.001,0.05, 0.001)
# fm_epsilons = np.array([0.1,0.01,0.001, 0.0001, 0.00001, 0.000001, 0.
↪00000001,0.00000001,0.0000000001])
fm_epsilons = np.array([0.1,0.01,0.001, 0.0001, 0.00001, 0.000001, 0.0000001])
fm_gamma = 0.9999
fm_df_epsilon_vi, fm_df_epsilon_pi = epsilon_analysis(fm_prob_transitions,
↪fm_rewards,fm_size,fm_epsilons,fm_gamma)
```

```
[31]: plot_epsilon_analysis(fl_df_epsilon_vi, fl_df_epsilon_pi)
```



```
[32]: plot_epsilon_analysis(fm_df_epsilon_vi, fm_df_epsilon_pi)
```



3.3 Optimal Policy

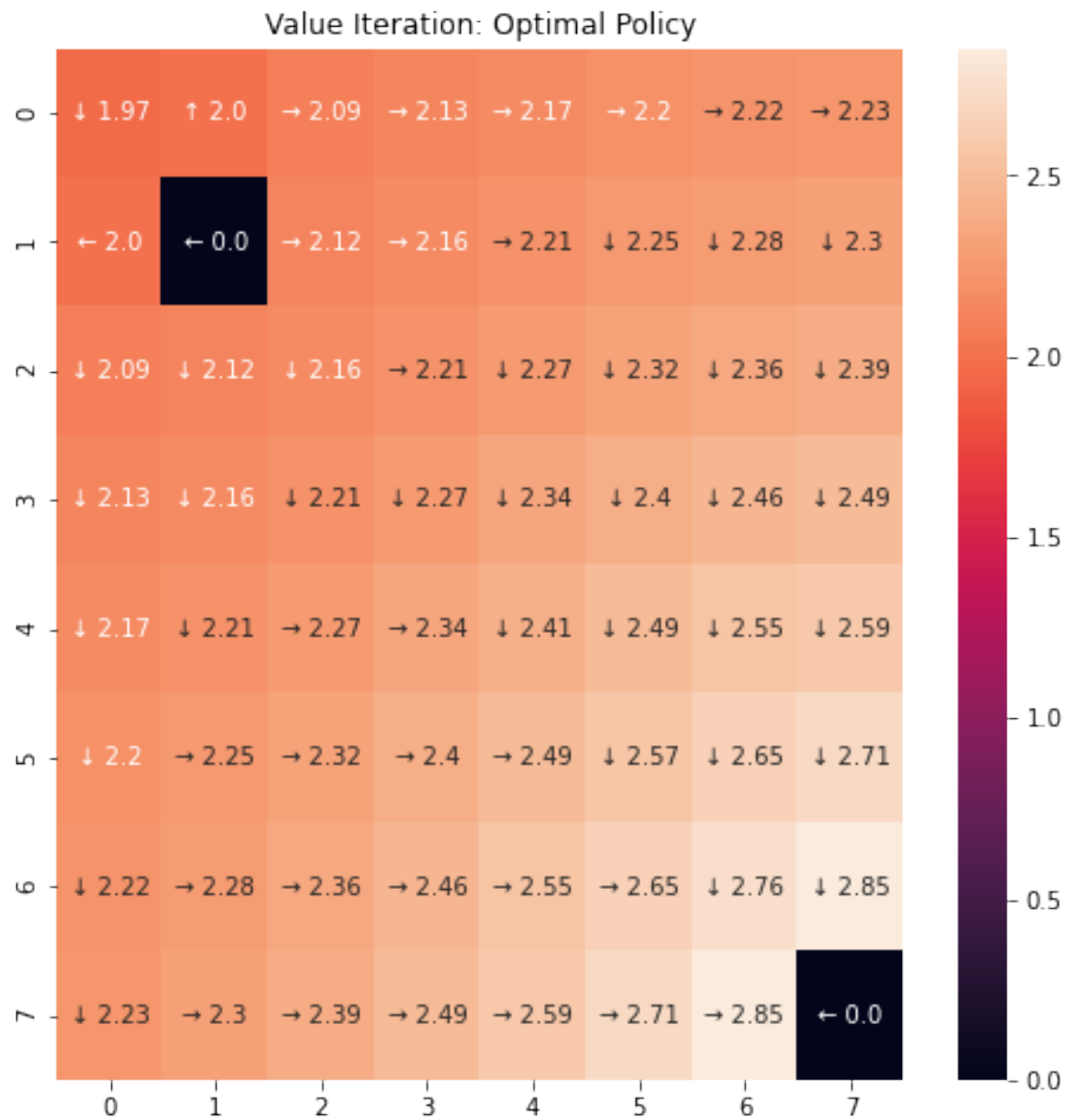
```
[33]: fl_vi_value_arr, fl_vi_policy_viz, fl_pi_value_arr, fl_pi_policy_viz =  
    ↪ optimal_policy(fl_df_epsilon_vi, fl_df_epsilon_pi, fl_size, 0.011, 'frozen-lake')
```

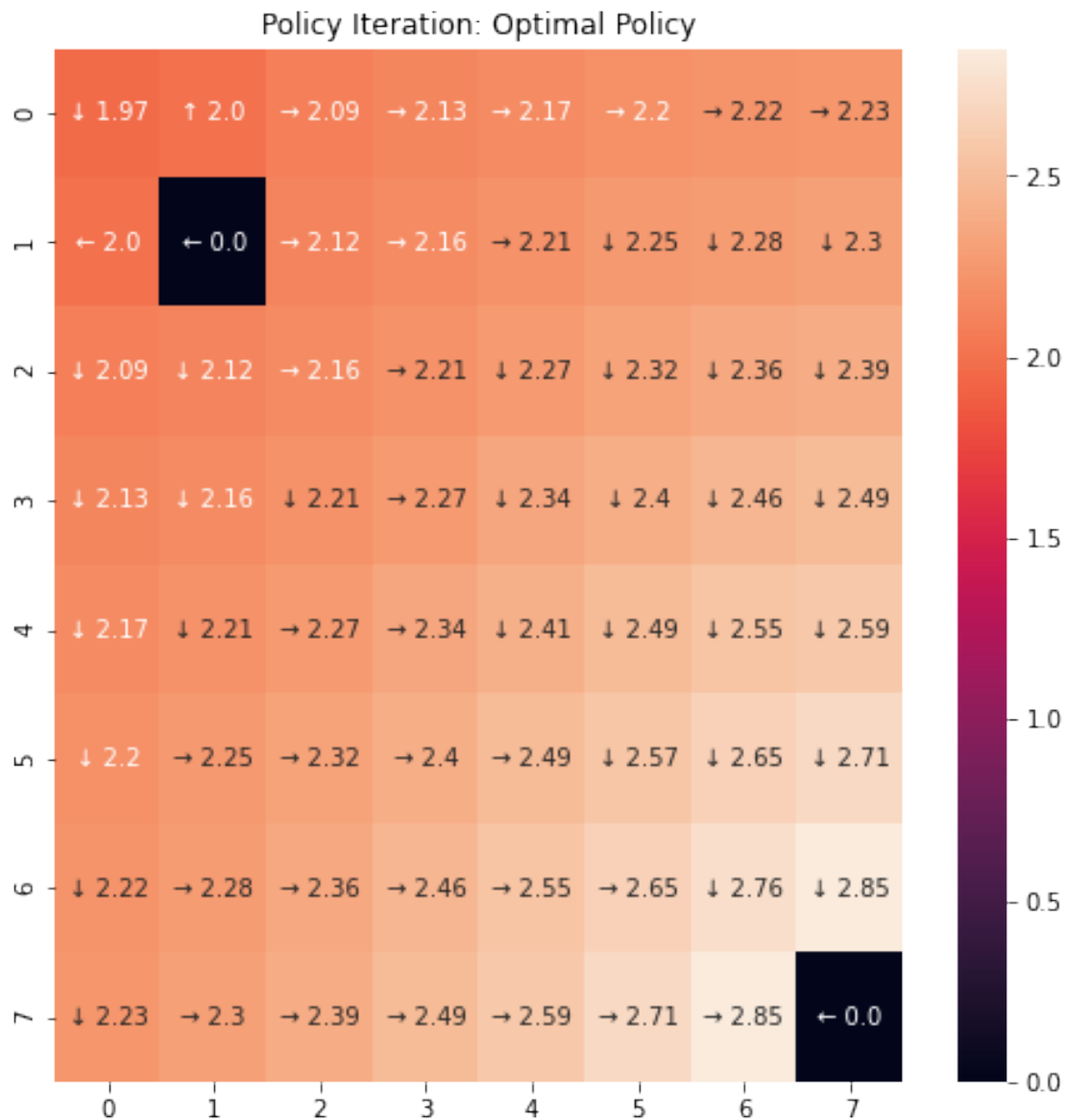
```
(1, 9)  
(1, 9)  
(1, 64)  
(1, 64)
```

```
[34]: fm_vi_value_arr, fm_vi_policy_viz, fm_pi_value_arr, fm_pi_policy_viz =  
    ↪ optimal_policy(fm_df_epsilon_vi, fm_df_epsilon_pi, fm_size, 0.0001, 'forest')
```

```
(1, 9)  
(1, 9)  
(1, 1000)  
(1, 1000)
```

```
[35]: plot_optimal_policy(fl_vi_value_arr, fl_vi_policy_viz, fl_pi_value_arr,  
    ↪ fl_pi_policy_viz, fl_size, 'frozen-lake')
```





```
[36]: plot_optimnal_policy(fm_vi_value_arr, fm_vi_policy_viz, fm_pi_value_arr,
    ↪fm_pi_policy_viz, fm_size, 'forest')
```

Value Iteration: Optimal Policy

```
W 87.98 | C 88.5 | C 88.5 | C 88.5 | C 88.5 | C 88.5 | C 88.5 | C 88.5 | C 88.5
| C 88.5 | C 88.5 | C 88.5 | C 88.5 | C 88.5 | C 88.5 | C 88.5 | C 88.5 | C 88.5
| C 88.5 | C 88.5 | C 88.5 | C 88.5 | C 88.5 | C 88.5 | C 88.5 | C 88.5 | C 88.5
| C 88.5 | C 88.5 | C 88.5 | C 88.5 | C 88.5 | C 88.5 | C 88.5 | C 88.5 | C 88.5
| C 88.5 | C 88.5 | C 88.5 | C 88.5 | C 88.5 | C 88.5 | C 88.5 | C 88.5 | C 88.5
| C 88.5 | C 88.5 | C 88.5 | C 88.5 | C 88.5 | C 88.5 | C 88.5 | C 88.5 | C 88.5
| C 88.5 | C 88.5 | C 88.5 | C 88.5 | C 88.5 | C 88.5 | C 88.5 | C 88.5 | C 88.5
```


[illegible]

[illegible]

[illegible]

[illegible]

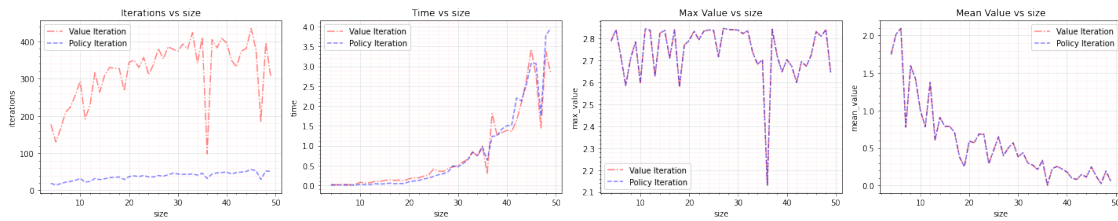
103.82		C	103.82		C	103.82		C	103.82		C	103.82		C	103.82		C	103.82		C
103.82		C	103.82		C	103.82		C	103.82		C	103.82		C	103.82		C	103.82		C
103.82		C	103.82		C	103.82		C	103.82		C	103.82		C	103.82		C	103.82		C
103.82		C	103.82		C	103.82		C	103.82		C	103.82		C	103.82		C	103.82		C
103.82		C	103.82		C	103.82		C	103.82		C	103.82		C	103.82		C	103.82		C
103.82		C	103.82		C	103.82		C	103.82		C	103.82		C	103.82		C	103.82		W
103.95		W	104.55		W	105.21		W	105.95		W	106.78		W	107.69		W	108.7		W
109.83		W	111.09		W	112.48		W	114.03		W	115.75		W	117.66		W	119.79		W
122.15		W	124.77		W	127.68		W	130.92		W	134.52		W	138.52					

3.4 Size Analysis

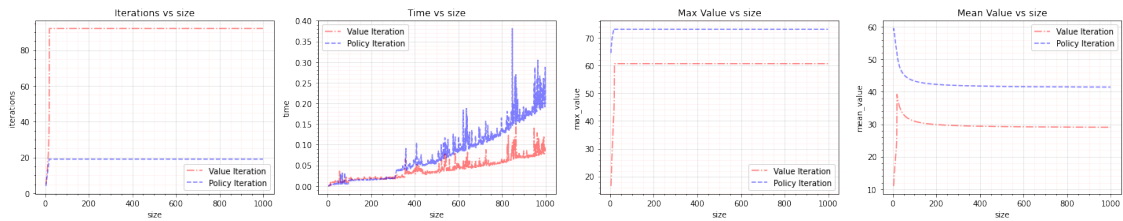
```
[37]: fl_gridsizes = range(4, 50, 1)
      fl_df_size_vi, fl_df_size_pi =
      ↪size_analysis('frozen-lake',fl_gridsizes,size_gamma=0.99)
```

```
[38]: fm_sizes = range(4, 1000, 1)
      fm_df_size_vi, fm_df_size_pi = size_analysis('forest',fm_sizes,size_gamma=0.99)
```

```
[39]: plot_size_analysis(fl_df_size_vi, fl_df_size_pi)
```



```
[40]: plot_size_analysis(fm_df_size_vi, fm_df_size_pi)
```



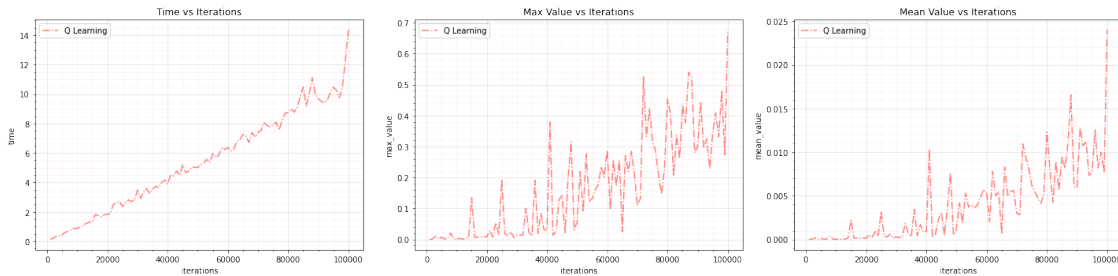
4 Q Learning

4.1 N-Iter Analysis

```
[45]: fl_ql_gamma = 0.99
      fl_ql_epsilon = 0.9
      # fl_ql_n_iters = [10000, 50000, 100000, 500000, 1000000]
      fl_ql_n_iters = np.arange(1000,100100,1000)
      # fl_ql_n_iters = np.arange(100,201,100)
      fl_df_n_iter_ql, fl_df_n_iter_run_stat = □
      ↪ ql_n_iter_analysis(fl_prob_transitions, □
      ↪ fl_rewards, fl_size, fl_ql_gamma, fl_ql_epsilon, fl_ql_n_iters)
```

```
[46]: fm_ql_gamma = 0.99
      fm_ql_epsilon = 0.9
      # fm_ql_n_iters = [10000, 50000, 100000, 500000, 1000000]
      fm_ql_n_iters = np.arange(1000,100100,1000)
      fm_df_n_iter_ql, fm_df_n_iter_run_stat = □
      ↪ ql_n_iter_analysis(fm_prob_transitions, □
      ↪ fm_rewards, fm_size, fm_ql_gamma, fm_ql_epsilon, fm_ql_n_iters)
```

```
[47]: plot_ql_n_iter_analysis(fl_df_n_iter_ql, fl_df_n_iter_run_stat)
```



```
[48]: plot_ql_n_iter_analysis(fm_df_n_iter_ql, fm_df_n_iter_run_stat)
```



```
[ ]:
```

```
[69]: fl_df_n_iter_ql[fl_df_n_iter_ql['iterations'] == 10000]
```

```
[69]: iter_type  size  iterations      time  max_value  mean_value  \
9         QL      8        10000  0.889622      0.001    0.000016
```

```

                                q_matrix  \
9  [[0.0, 0.0, 0.0, 0.0], [0.0, 0.0, 0.0, 0.0], [...
```

```

                                policy  \
9  (0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, ...
```

```

                                value
9  (0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, ...
```

```
[70]: def optimal_policy_ql(optimal_df_ql,optimal_size,iterations,env_type):
        optimal_ql = optimal_df_ql[optimal_df_ql['iterations'] == iterations]

        print(optimal_ql.shape)
        print(np.array(list(optimal_ql['policy']))).shape)

        if env_type == 'frozen-lake':
            ql_policy_arr = np.array(list(optimal_ql['policy'])).
            ↪reshape(optimal_size,optimal_size).astype(str)
            ql_value_arr = np.round(np.array(list(optimal_ql['value']))).
            ↪reshape(optimal_size,optimal_size),2)

            ql_policy_arr[ql_policy_arr=='0'] = '←'
            ql_policy_arr[ql_policy_arr=='1'] = '↓'
            ql_policy_arr[ql_policy_arr=='2'] = '→'
            ql_policy_arr[ql_policy_arr=='3'] = '↑'

            ql_policy_viz = (np.asarray([a+" "+str(v) for a, v in zip(ql_policy_arr.
            ↪flatten(), ql_value_arr.flatten())])).reshape(optimal_size,optimal_size)

            elif env_type == 'forest':

                ql_policy_arr = np.array(list(optimal_ql['policy'])).
                ↪reshape(optimal_size).astype(str)
                ql_value_arr = np.round(np.array(list(optimal_ql['value'])).
                ↪reshape(optimal_size),2)

                ql_policy_arr[ql_policy_arr=='0'] = 'W'
                ql_policy_arr[ql_policy_arr=='1'] = 'C'

                ql_policy_viz = (np.asarray([a+" "+str(v) for a, v in zip(ql_policy_arr.
                ↪flatten(), ql_value_arr.flatten())])).reshape(optimal_size)
```



```
return ql_value_arr, ql_policy_viz
```

```
[84]: def plot_optimnal_policy_ql(plot_ql_value_arr,
    ↪ plot_ql_policy_viz, plot_size, env_type):

    if env_type == 'frozen-lake':
        plt.figure(figsize=(plot_size, plot_size))
        plt.title("Q Learning: Optimal Policy")
        sns.heatmap(plot_ql_value_arr, annot=plot_ql_policy_viz, fmt="")

    elif env_type == 'forest':
        print("Q Learning: Optimal Policy")
        line=""
        for val in plot_ql_policy_viz:
            line += (" {} |".format(val))
        print(line)
```

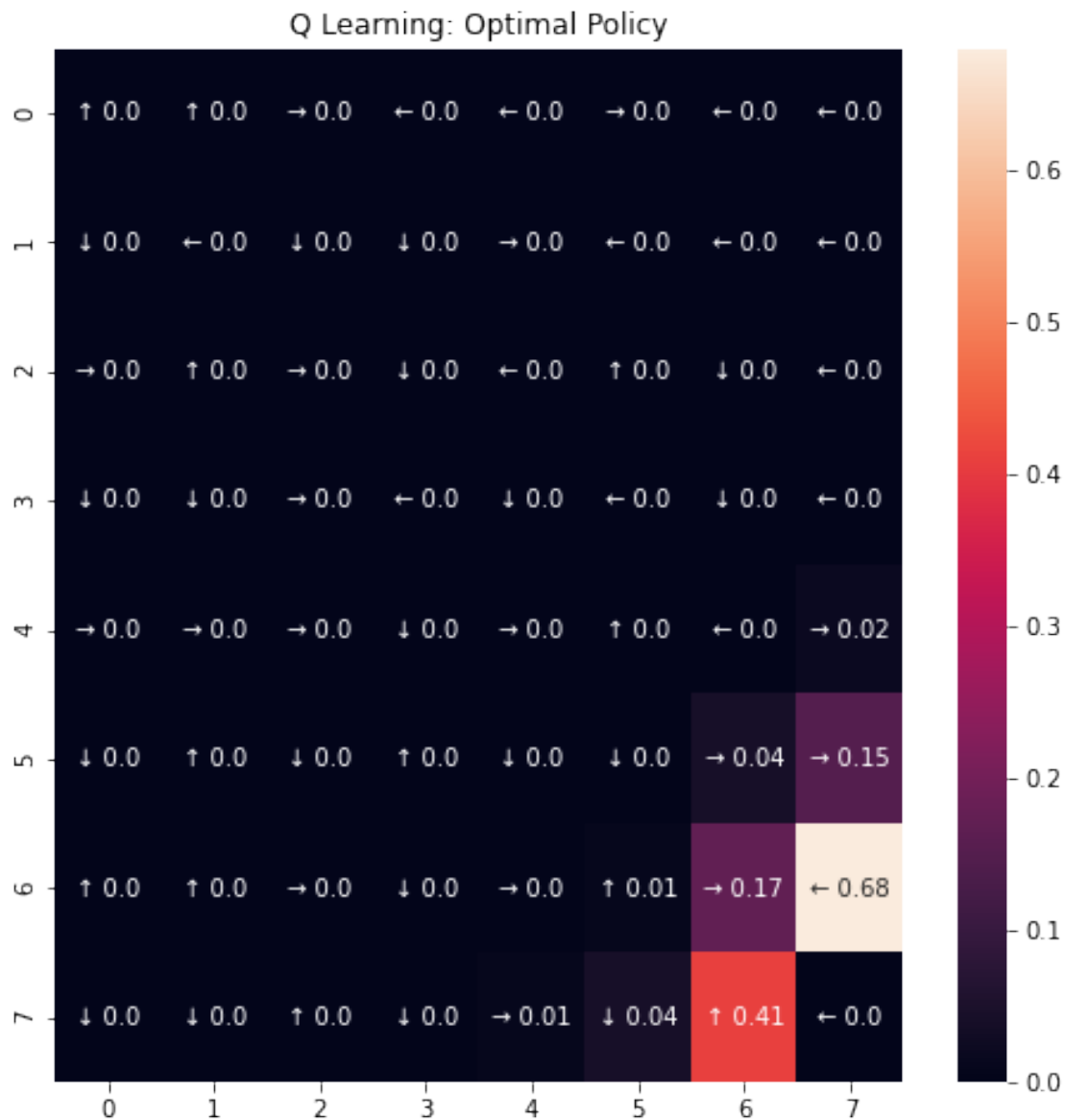
```
[85]: fl_ql_value_arr, fl_ql_policy_viz =
    ↪ optimal_policy_ql(fl_df_n_iter_ql, fl_size, 100000, 'frozen-lake')
```

```
(1, 9)
(1, 64)
```

```
[86]: fm_ql_value_arr, fm_ql_policy_viz =
    ↪ optimal_policy_ql(fm_df_n_iter_ql, fm_size, 100000, 'forest')
```

```
(1, 9)
(1, 1000)
```

```
[87]: plot_optimnal_policy_ql(fl_ql_value_arr, fl_ql_policy_viz, fl_size, 'frozen-lake')
```



```
[88]: plot_optimnal_policy_ql(fm_ql_value_arr, fm_ql_policy_viz, fm_size, 'forest')
```

Q Learning: Optimal Policy

```
W 17.55 | C 18.06 | C 11.17 | C 1.11 | W 0.0 | W 0.0 | C 0.06 | W 0.0 | W 0.01
| W 0.0 | W 0.0 | W 0.0 | W 0.01 | W 0.01 | C 0.08 | W 0.0 | W 0.01 | W 0.0 | W
0.01 | C 0.03 | W 0.0 | W 0.0 | W 0.0 | W 0.01 | W 0.0 | W 0.01 | W 0.01 | W
0.01 | W 0.03 | W 0.0 | W 0.0 | W 0.02 | W 0.0 | W 0.01 | W 0.01 | W 0.01 | W
0.0 | W 0.02 | W 0.01 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.02 | W 0.01 | W 0.0
| C 0.01 | W 0.0 | W 0.0 | C 0.07 | W 0.0 | W 0.0 | W 0.0 | C 0.04 | W 0.0 | W
0.0 | W 0.0 | W 0.0 | C 0.01 | C 0.05 | C 0.01 | W 0.0 | W 0.0 | W 0.0 | W 0.0 |
W 0.0 | W 0.0 | C 0.03 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.0 |
```

W 0.0 | W 0.0 | W 0.0 | C 0.09 | C 0.0 | W 0.0 | W 0.0 | C 0.04 | W 0.0 | W 0.0
| W 0.0 | C 0.02 | W 0.0 | W 0.0 | W 0.0 | C 0.04 | W 0.0 | W 0.0 | W 0.0 | W
0.0 | C 0.03 | W 0.0 | W 0.0 | C 0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | C 0.05 |
W 0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.01 | W 0.01 | C 0.05 | C 0.03 | W 0.0 | W
0.0 | W 0.02 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | C 0.02 | W 0.01 | C 0.02
| W 0.0 | W 0.02 | W 0.0 | W 0.0 | W 0.0 | C 0.05 | W 0.0 | W 0.0 | C 0.03 | W
0.0 | W 0.01 | C 0.04 | W 0.0 | W 0.0 | W 0.0 | C 0.07 | W 0.0 | C 0.02 | W 0.0
| W 0.0 | W 0.0 | W 0.0 | W 0.0 | C 0.03 | W 0.01 | W 0.01 | W 0.0 | W 0.0 | W
0.0 | W 0.01 | W 0.0 | C 0.09 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.02 | W 0.0 |
W 0.0 | C 0.03 | W 0.01 | W 0.0 | W 0.01 | C 0.03 | C 0.03 | W 0.0 | C 0.1 | W
0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | C 0.03 | W 0.0 | W 0.02 | W 0.0 |
W 0.0 | W 0.01 | W 0.0 | W 0.01 | C 0.03 | W 0.0 | W 0.0 | C 0.02 | W 0.0 | W
0.0 | C 0.06 | W 0.0 | W 0.01 | W 0.0 | W 0.02 | W 0.0 | W 0.0 | C 0.05 | C 0.02
| C 0.03 | W 0.0 | W 0.0 | W 0.0 | C 0.04 | W 0.0 | W 0.0 | W 0.0 | W 0.01 | C
0.02 | W 0.0 | W 0.02 | W 0.0 | W 0.02 | W 0.0 | W 0.01 | W 0.0 | C 0.09 | W 0.0
| W 0.0 | W 0.0 | W 0.02 | C 0.03 | W 0.01 | C 0.04 | W 0.0 | W 0.0 | W 0.0 | W
0.0 | W 0.0 | C 0.04 | W 0.0 | C 0.03 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.01 |
W 0.01 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | C 0.07 | W 0.0 | W 0.01 | W 0.0 | W 0.0
| W 0.01 | W 0.02 | W 0.0 | C 0.02 | W 0.0 | C 0.01 | W 0.0 | W 0.0 | W 0.0 | W
0.0 | C 0.01 | W 0.01 | W 0.01 | W 0.0 | C 0.07 | W 0.01 | W 0.0 | W 0.04 | W
0.01 | W 0.01 | W 0.01 | W 0.0 | C 0.02 | W 0.0 | C 0.01 | W 0.0 | W 0.0 | W
0.02 | C 0.02 | W 0.0 | W 0.0 | C 0.04 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | C 0.02
| W 0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.01 | W 0.0 | W 0.01 | W 0.0 | W 0.0 | W
0.0 | W 0.01 | W 0.0 | W 0.03 | W 0.0 | W 0.01 | W 0.02 | W 0.0 | W 0.0 | C 0.04
| W 0.0 | W 0.0 | W 0.0 | W 0.02 | W 0.0 | W 0.03 | W 0.03 | W 0.02 | W 0.0 | C
0.01 | W 0.0 | W 0.01 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.01 | W 0.0 | W 0.02
| W 0.0 | W 0.0 | W 0.0 | C 0.04 | C 0.03 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | W
0.0 | W 0.0 | W 0.0 | C 0.04 | W 0.01 | W 0.01 | W 0.0 | W 0.01 | C 0.03 | W 0.0
| W 0.0 | W 0.0 | W 0.0 | W 0.02 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | W
0.02 | W 0.0 | C 0.04 | W 0.01 | W 0.0 | W 0.01 | C 0.01 | C 0.05 | W 0.0 | W
0.02 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.01 | C 0.04 | W 0.0 | W 0.0 | W 0.0 |
W 0.0 | C 0.08 | W 0.01 | W 0.0 | W 0.0 | W 0.0 | C 0.04 | W 0.01 | W 0.0 | C
0.03 | W 0.0 | W 0.01 | W 0.0 | W 0.0 | W 0.0 | W 0.01 | W 0.0 | W 0.0 | C 0.06
| C 0.02 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | C 0.01 | W 0.0 | W 0.0 | W 0.02 | W
0.0 | C 0.03 | W 0.0 | W 0.0 | C 0.03 | W 0.01 | C 0.01 | W 0.01 | W 0.0 | W
0.02 | C 0.01 | W 0.01 | W 0.0 | W 0.02 | W 0.02 | W 0.0 | W 0.01 | W 0.02 | W
0.0 | C 0.04 | C 0.03 | W 0.0 | W 0.0 | C 0.04 | W 0.0 | W 0.0 | W 0.0 | W 0.0 |
C 0.04 | W 0.0 | W 0.0 | W 0.0 | C 0.01 | W 0.0 | W 0.0 | W 0.01 | W 0.0 | C
0.05 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | C 0.02 | W 0.01 | W 0.01 | W 0.02
| W 0.0 | W 0.0 | W 0.01 | W 0.0 | W 0.0 | C 0.03 | W 0.0 | W 0.0 | W 0.0 | C
0.03 | W 0.0 | W 0.0 | W 0.01 | W 0.0 | W 0.0 | C 0.07 | C 0.01 | W 0.0 | W 0.0
| W 0.0 | W 0.0 | C 0.05 | W 0.0 | C 0.02 | W 0.0 | W 0.0 | W 0.0 | W 0.01 | W
0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.01 | W 0.0 | C 0.09 | W 0.0 | C 0.01 |
W 0.0 | W 0.01 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.0 |
W 0.01 | C 0.02 | W 0.02 | W 0.0 | W 0.0 | W 0.02 | C 0.02 | C 0.03 | W 0.0 | C
0.04 | W 0.01 | W 0.0 | W 0.0 | W 0.01 | W 0.0 | W 0.01 | W 0.0 | C 0.05 | W
0.01 | W 0.02 | C 0.04 | W 0.01 | W 0.0 | W 0.02 | W 0.0 | W 0.0 | W 0.0 | W 0.0
| C 0.09 | W 0.0 | C 0.03 | W 0.01 | W 0.0 | W 0.01 | W 0.01 | C 0.04 | W 0.0 |

W 0.0 | C 0.07 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.0 |
W 0.01 | W 0.0 | W 0.02 | W 0.0 | W 0.01 | W 0.0 | W 0.03 | W 0.0 | W 0.0 | W
0.0 | W 0.03 | W 0.02 | C 0.03 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | C 0.05
| W 0.0 | W 0.0 | C 0.05 | C 0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | C 0.02 | W
0.0 | W 0.0 | W 0.03 | C 0.05 | W 0.0 | W 0.0 | W 0.0 | W 0.01 | W 0.0 | W 0.0 |
W 0.0 | C 0.05 | C 0.03 | W 0.0 | W 0.0 | W 0.01 | W 0.0 | W 0.0 | C 0.03 | W
0.0 | W 0.0 | W 0.0 | W 0.02 | W 0.0 | W 0.01 | W 0.02 | W 0.0 | W 0.0 | W 0.0 |
C 0.06 | W 0.0 | W 0.02 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | C 0.02 | W 0.0 | W 0.0
| W 0.0 | W 0.0 | W 0.0 | W 0.0 | C 0.04 | W 0.0 | W 0.0 | C 0.03 | W 0.0 | W
0.0 | W 0.02 | W 0.0 | W 0.0 | W 0.0 | C 0.02 | W 0.0 | W 0.01 | W 0.0 | W 0.0 |
W 0.01 | W 0.02 | W 0.0 | W 0.01 | W 0.0 | C 0.05 | W 0.0 | W 0.0 | W 0.01 | W
0.0 | C 0.02 | W 0.0 | C 0.02 | W 0.0 | W 0.01 | W 0.0 | W 0.01 | W 0.0 | C 0.04
| W 0.0 | W 0.0 | C 0.04 | C 0.02 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | W
0.01 | W 0.0 | W 0.02 | W 0.01 | C 0.07 | W 0.0 | C 0.02 | W 0.01 | W 0.0 | W
0.01 | W 0.0 | W 0.0 | W 0.0 | W 0.01 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.0 |
C 0.03 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.01 | C 0.02 | W
0.01 | C 0.02 | W 0.01 | W 0.0 | W 0.02 | W 0.03 | W 0.0 | W 0.0 | C 0.06 | W
0.0 | W 0.01 | W 0.03 | W 0.0 | C 0.04 | C 0.02 | W 0.0 | W 0.0 | W 0.0 | W 0.0
| W 0.0 | C 0.03 | W 0.0 | W 0.0 | W 0.01 | W 0.0 | W 0.0 | W 0.0 | W 0.02 | C
0.08 | W 0.0 | C 0.03 | W 0.02 | C 0.05 | W 0.0 | W 0.0 | W 0.0 | W 0.01 | W 0.0
| W 0.02 | W 0.0 | C 0.08 | W 0.0 | W 0.0 | W 0.0 | C 0.08 | W 0.0 | W 0.0 | W
0.0 | C 0.03 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | C 0.04 | W 0.0 |
W 0.0 | C 0.02 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.01 | W 0.01 | W 0.0 | W
0.01 | W 0.0 | C 0.07 | W 0.0 | W 0.0 | W 0.0 | C 0.01 | W 0.0 | W 0.0 | W 0.0 |
W 0.0 | W 0.0 | W 0.0 | W 0.01 | W 0.03 | W 0.0 | W 0.01 | W 0.0 | W 0.0 | W
0.03 | W 0.0 | W 0.0 | W 0.0 | C 0.05 | W 0.02 | W 0.01 | W 0.01 | W 0.0 | W 0.0
| W 0.0 | W 0.0 | C 0.09 | W 0.01 | W 0.01 | W 0.01 | W 0.0 | W 0.0 | W 0.0 | W
0.0 | W 0.0 | W 0.03 | W 0.01 | W 0.01 | W 0.0 | W 0.0 | C 0.02 | W 0.01 | W 0.0
| C 0.08 | W 0.0 | W 0.0 | W 0.0 | W 0.01 | W 0.0 | C 0.02 | C 0.05 | W 0.02 | W
0.0 | W 0.01 | W 0.01 | C 0.03 | W 0.0 | W 0.0 | C 0.02 | C 0.03 | W 0.0 | W 0.0
| W 0.01 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | C 0.05 | W 0.0 | W 0.0 | W 0.0 | W
0.02 | C 0.08 | C 0.01 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.01 | W 0.02 | W
0.01 | W 0.02 | C 0.04 | W 0.0 | W 0.0 | C 0.04 | W 0.0 | W 0.01 | W 0.01 | W
0.0 | W 0.04 | W 0.0 | W 0.0 | W 0.02 | W 0.02 | W 0.0 | W 0.0 | W 0.03 | W 0.0
| W 0.02 | W 0.0 | W 0.01 | W 0.0 | W 0.01 | W 0.0 | W 0.01 | C 0.07 | W 0.0 | C
0.01 | C 0.02 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.03 | C 0.07 | W 0.0 | W 0.01
| W 0.01 | W 0.0 | W 0.0 | C 0.02 | C 0.06 | W 0.0 | W 0.02 | W 0.0 | C 0.02 | W
0.0 | W 0.0 | W 0.01 | W 0.0 | W 0.02 | W 0.01 | W 0.0 | W 0.02 | W 0.0 | W 0.0
| W 0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.02 | W 0.01 | C 0.05 | W 0.01 | W 0.0 | W
0.0 | W 0.01 | W 0.02 | W 0.0 | C 0.04 | W 0.0 | C 0.12 | W 0.0 | W 0.0 | W 0.0
| W 0.0 | W 0.02 | W 0.0 | W 0.0 | W 0.0 | W 0.01 | W 0.0 | W 0.01 | W 0.0 | W
0.01 | W 0.0 | W 0.02 | W 0.0 | W 0.0 | W 0.0 | C 0.01 | W 0.0 | W 0.01 | W 0.0
| W 0.0 | W 0.0 | C 0.04 | W 0.0 | C 0.05 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | W
0.02 | W 0.03 | W 0.0 | W 0.02 | W 0.02 | C 0.04 | W 0.0 | W 0.0 | W 0.01 | C
0.05 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | C 0.07 | C 0.01 | W 0.0 |
W 0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.02 | W 0.0 | C 0.11 | W 0.0 | W 0.0 | W 0.0
| W 0.02 | W 0.0 | W 0.0 | W 0.02 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.0 | W
0.0 | W 0.0 | W 0.0 | W 0.0 | W 0.02 | W 0.0 | W 0.0 | W 0.0 | C 0.08 | W 0.0 |

W 0.01 | W 0.0 | W 0.0 | W 0.0 | W 0.03 | W 0.0 | W 0.0 | C 0.05 | W 0.0 | W 0.0
| W 0.0 | W 0.0 | W 0.03 | W 0.0 | W 0.0 | W 0.16 |

[]: