BIRLA INSTITUTE OF TECHNOLOGY AND SCIENCE, PILANI



MICROPROCESSORS AND INTERFACING (CS F241) DESIGN ASSIGNMENT

"FIRE ALARM SYSTEM"

Submitted by:

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PROBLEM STATEMENT

This system checks for abnormal smoke content in a room every two seconds. Under abnormal conditions it throws open two doors and two windows and opens a valve that releases the gas to put-out the fire. An Alarm is also sounded; this alarm is sounded until the smoke level in the room drops to an acceptable level. The smoke detection system is made up of two smoke sensors placed on the ceiling of the room. When the smoke level comes back below the danger level, the doors, windows and valves are closed.

ASSUMPTIONS

In order to reduce the design effort as well as to get the simplest design possible using the minimum amount of hardware while meeting all the restrictions specified by our problem statement, we have made the following assumptions:

- The smoke sensors used come with a built in ADC. It gives high output (1) in case smoke is present near it but gives low output (0) when smoke is not present.
- Abnormal conditions are considered when both the smoke sensors give high output.
- Dangerous conditions are considered when only one of the sensors gives high output.
- Below the danger level, both the sensors give low output and the doors, windows and valve are closed.
- We have used LEDs to simulate the 2 doors, 2 windows, 1 valve and 1 alarm.

DESIGN PROCESS

(A) Components Used:

Chip Number	Quantity	Chip	Purpose					
8086	1	Microprocessor	Central Processing Unit					
8253A	1	Programmable Interval Timer	Used to generate timing signals					
8255A	1	Programmable Peripheral Interface	Used to interface ports as input and output for smoke sensors, opening and closing of doors, valves and windows and the sounding of alarm					
2732	2	EPROM	Read only Erasable Programmable memory to house code segment					
6116	2	RAM	Read Write Memory to house the segment					
-	33	2 input OR Gate	Used for Decoding Logic					
-	5	NOT Gate	Used for Decoding Logic					
-	6	LED (equivalent to mechanical switches relay and alarms in chart)	Simulate doors, windows and valves					
74LS373	3	8 bit buffer bidirectional buffers	Buffering address bus					
74LS245	2	8 bit buffer bidirectional buffers	Buffering data bus					
74LS244	2	Octal Buffers	Creation of Vector number (40h)					

(B) Memory Organization:

Total RAM used by system = 4KB

Total ROM used by system = 8KB

RAM chip used = 6116.

So, size of each RAM chip = 16/8 = 2KB.

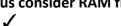
Hence, number of 6116 RAM chips required = 4KB/2KB = 2.

EPROM chip used = 2732

So, size of each ROM chip = 32/8 = 4KB.

Hence, number of 2732 EPROM chips required = 8KB/4KB = 2.

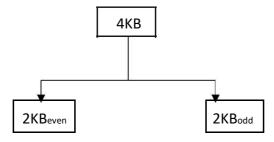
Let us consider RAM first.



RAM must house the data segment and stack segment.

Starting address of RAM = 00000H

System has 4KB RAM. So, Ending address of RAM = 00FFFH.



Even Bank of RAM = 00000H, 00002H, 00004H, 00006H, , 00FFEH.

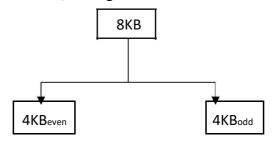
	A 19	A 18	A 17	A 16	A 15	A 14	A 13	A 12	A 11	A 10	A 9	A 8	A 7	A 6	A 5	A 4	Аз	A 2	A ₁	Αo
Start Address	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
End Address	0	0	0	0	0	0	0	0	1	1	1	1	1	1	1	1	1	1	1	1

Now, let us consider ROM.

ROM must house the code segment.

Starting address of ROM = FD000H

System has 8KB ROM. So, Ending address of ROM = FEFFFH.



Even Bank of ROM = FD000H, FD002H, FD004H, FD006H, , FEFFEH.

Odd Bank of ROM = FD001H, FD003H, FD005H, FD007H, , FEFFFH.

	A 19	A 18	A 17	A 16	A 15	A 14	A 13	A 12	A 11	A 10	A 9	A 8	A 7	A 6	A 5	A 4	Аз	A ₂	A 1	Αo
Start Address	1	1	1	1	1	1	0	1	0	0	0	0	0	0	0	0	0	0	0	0
End Address	1	1	1	1	1	1	1	0	1	1	1	1	1	1	1	1	1	1	1	1

(C) IO BASED MEMORY MAPPING:

1.) 8253 Programmable Interval Timer

According to our problem statement, we need to check values from sensors every 2 seconds. For this we need a timer and hence we are using 8253. It is organized in the following way:

	Address	A7	A6	A5	A4	А3	A2	A1	A0
Port A	30н	0	1	0	1	0	0	0	0
Port B	32н	0	1	0	1	0	0	1	0
Port C	34н	0	1	0	1	0	1	0	0
Control	36н	0	1	0	1	0	1	1	0
Reg.									

2.) 8255 Programmable Peripheral Interface

One 8255(Programmable Peripheral Interface) are used to communicate with other input and output devices. It is organized in the following manner.

	Address	A7	A6	A5	A4	А3	A2	A1	Α0
Port A	00н	0	0	0	0	0	0	0	0
Port B	02н	0	0	0	0	0	0	1	0
Port C	04н	0	0	0	0	0	1	0	0
Control Reg.	06н	0	0	0	0	0	1	1	0

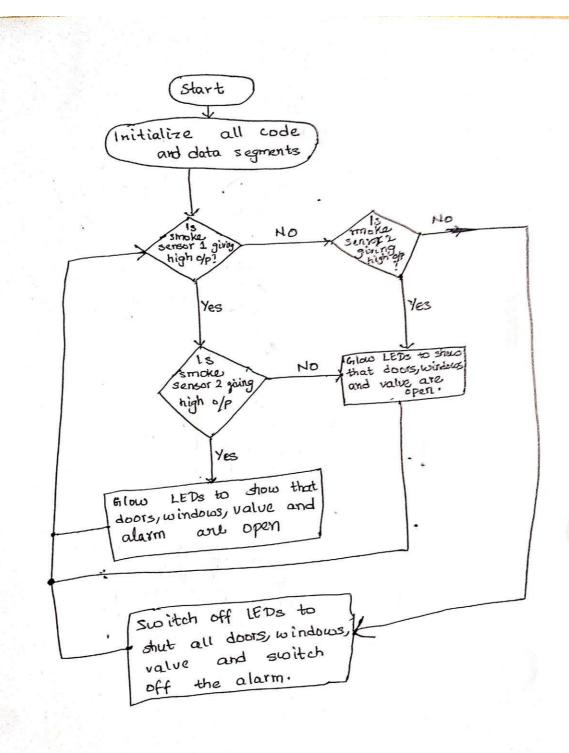
(D)SENSOR:

MQ-2 Smoke Sensor circuit with built in Analog to digital convertor (with logic 1 as output in case of presence of smoke else logic 0 is the output)

The 8253 is used in Mode 2 as a rate counter where an interrupt is given to the 8086 microprocessor every 2 seconds. On the interrupt the 8086 checks for the values at the smoke detectors, that is if it is logic 1 or logic 0. On the basis of the following truth table the actions are taken:

SENSOR 1	SENSOR 2	ACTION TAKEN
0	0	Close door, valves and
		windows
0	1	Open door, valves and
		windows
1	0	Open door, valves and
		windows
1	1	Open door, valves and
		Windows and alarm is
		sounded

FLOWCHART



CODE

```
.model tiny
#make_bin#
#LOAD_SEGMENT=FFFFh#
#LOAD_OFFSET=0000h#
.code
.startup
    jmp st1
    db
         1024 dup(0)
st1:
      cli
; initialize port a & b as input & port c as output
    mov al,92h
                  ;10010010b
    out 06h, al
; initialize counter mode 2 in 8253
    ;30h = address of count0 i.e. starting address for 8253
    ;count reqd = 5*10^6
    ;count0 stores 2500
    mov al,34h
    out 36h,al
    mov al,0C4h
    out 30h,al
    mov al,09h
    out 30h,al
    ;count1 stores 2000
    mov al,74h
```

```
out 36h,al
    mov al,0D0h
    out 32h,al
    mov al,07h
    out 32h,al
    ;take input from smoke sensors
next: in
          al,00h
    mov bl,al
    ;check if both are on or not
    cmp bl,81h
    jz glow
    cmp bl,80h
         offAlarm
    jΖ
             cmp bl,01h
         offAlarm
    jΖ
        ; close valves, doors and windows
off: mov
               al,0FFh
        out
               04h,al
    jmp over
   ;open valves, doors and windows and
sound alarm glow: mov al,0C0h
    out 04h,al
    jmp over
offAlarm: mov al,0E0h
     out 04h,al
     jmp over
```

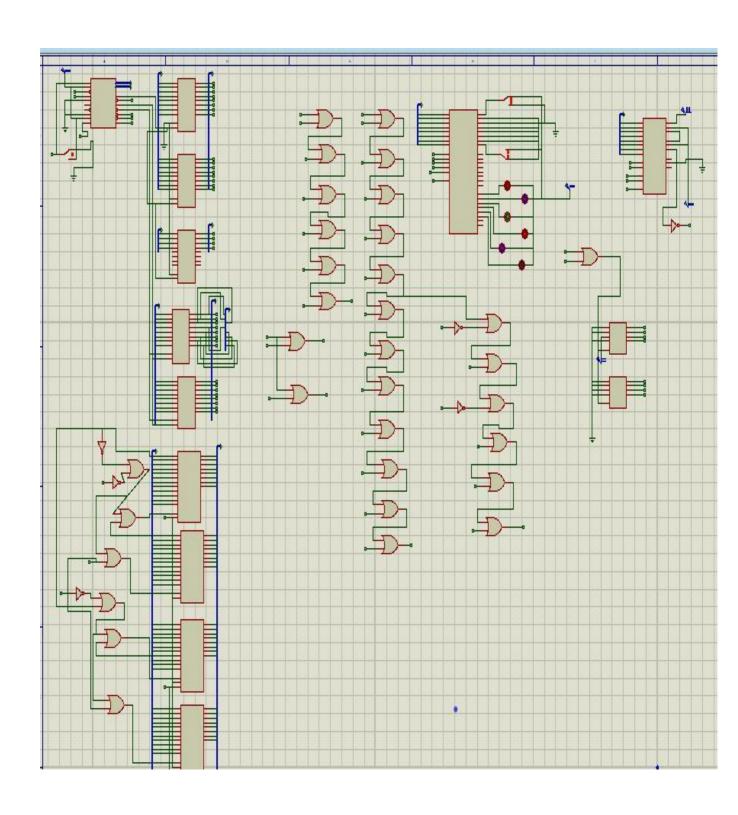
over:

```
;interupt generation using out of 8253 after every 2 seconds
lea si,read
mov ds:[256],si;vector number = 40h = 64d, so location in IVT = 64*4 = 256
mov cx,cs
mov ds:[258],cx

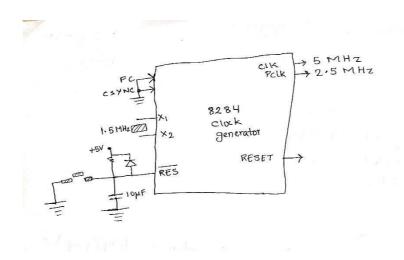
;set the interrupt flags
sti

;infinite loop, will stop only power is switched
off jmp next
.exit
read proc near:
    iret
read endp
end
```

CIRCUIT DIAGRAM



In the above circuit, 8284 was used to generate the required clock at frequencies 5MHz and 2.5 MHz.



REFERENCES TO MANUALS USED

8085/86 x86 processors (Intel processors book by Barey Brey) 2716_EPROM 6116 8255 SN74LS245 SN74LS373

All the above manuals were available on Internet.

For the smoke sensors, the below sites were referred

- http://www.learningaboutelectronics.com/Articles/MQ -2- smoke-sensor circuit- with- arduino.php http://store.fut electronics.com/products/smoke -sensor -module mq2- digital
- -analog
- http://www.nrdc entre.com/MQ2 Smoke- Sensor -Module
- http://www.hw -group.com/products/sensors/index _en. html