

Plan:

- implicit methods
- backward Euler
- Crank-Nicolson
- truncation error of C-N

Implicit methods: the timestep restriction  $\nu = \frac{k}{h^2} \leq \frac{1}{2}$  makes the schemes we have studied so far impractical.

Switching to an implicit method removes this stability constraint.

simplest example: backward Euler (backward time, centered space BTCS)

$$D_t^+ u_j^n = D_x^+ D_x^- u^{n+1}$$

$$\frac{u_j^{n+1} - u_j^n}{k} = \frac{u_{j+1}^{n+1} - 2u_j^{n+1} + u_{j-1}^{n+1}}{h^2}$$

$$- \nu u_{j+1}^{n+1} + (1 + 2\nu) u_j^{n+1} - \nu u_{j-1}^{n+1} = u_j^n \quad \left( \nu = \frac{k}{h^2} \right)$$

z-transform

$$B u^{n+1} = u^n$$

$$\rightarrow G(\xi) \hat{u}^{n+1}(\xi) = \hat{u}^n(\xi)$$

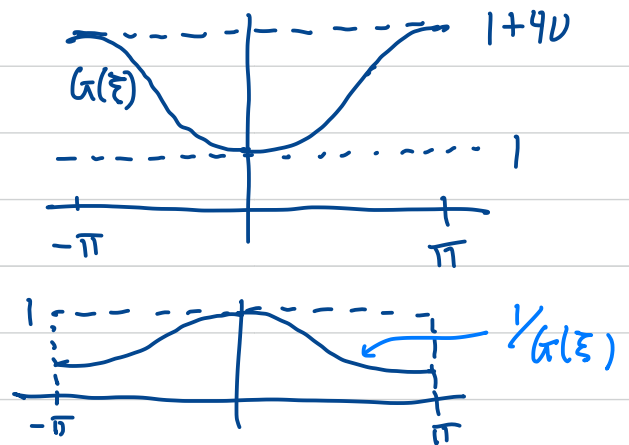
$$\hat{u}^{n+1}(\xi) = \frac{1}{G(\xi)} \hat{u}^n(\xi)$$

$$G(\xi) = -\nu e^{i\xi} + (1 + 2\nu) - \nu e^{-i\xi}$$

$$= 1 + 2\nu(1 - \cos \xi) = 1 + 4\nu \sin^2(\xi/2)$$

$$|\bar{g}(\xi)| \geq 1, \quad 0 < \frac{1}{\bar{g}(\xi)} \leq 1$$

$$\|B^{-1}\|_{\ell_h^2} = \left\| \frac{1}{\bar{g}(\xi)} \right\|_{\infty} = 1$$



So the scheme  $u^{n+1} = B^{-1}u^n$  is unconditionally stable. Even on the refinement path  $h=k, v = \frac{1}{k}$  we still have  $\|(B^{-1})^n\| \leq K = 1$  for  $0 < nk \leq T$

the amplification factor of

$$\left\{ \begin{array}{l} B = I \\ \alpha B_1 + \beta B_2 \\ B_1, B_2 \\ B^{-1} \end{array} \right\} \text{ is } \left\{ \begin{array}{l} \bar{g}(\xi) = 1 \\ \alpha \bar{g}_1(\xi) + \beta \bar{g}_2(\xi) \\ \bar{g}_1(\xi) \bar{g}_2(\xi) \\ \frac{1}{\bar{g}(\xi)} \end{array} \right\}$$

$B$  is invertible on  $\ell_h^2$  iff  $|\bar{g}(\xi)| \neq 0$  for  $\xi \in [-\pi, \pi]$

problem with BTCS: the truncation error is still

$O(k+h^2)$ . This was fine when  $k$  was  $\nu h^2$  but  
 now  $O(k)$  is too big. 
 $\uparrow$   
 fixed constant

solution: use a more accurate timestepper

implicit trapezoidal rule  $\rightarrow$  Crank-Nicolson scheme

$$D_t^+ u_j^n = \frac{1}{2} \left[ D_x^+ D_x^- u_j^n + D_x^+ D_x^- u_j^{n+1} \right]$$

$$\frac{u^{n+1} - u^n}{k} = \frac{1}{2} \frac{Bu^n}{h^2} + \frac{1}{2} \frac{Bu^{n+1}}{h^2}$$

$$Bu_j = u_{j+1} - 2u_j + u_{j-1}$$

$$\begin{aligned} G(\xi) &= e^{i\xi} - 2 + \bar{e}^{i\xi} \\ &= -2(1 - \cos \xi) = -4 \sin^2 \xi/2 \end{aligned}$$

$$(I - \frac{\nu}{2} B) u^{n+1} = (I + \frac{\nu}{2} B) u^n \quad \nu = \frac{k}{h^2}$$

$$(1 - \frac{\nu}{2} G(\xi)) \hat{u}^{n+1}(\xi) = (1 + \frac{\nu}{2} G(\xi)) \hat{u}^n(\xi)$$

$$u^{n+1} = (I - \frac{\nu}{2} B)^{-1} (I + \frac{\nu}{2} B) u^n = B_1 u^n$$

$$\hat{u}^{n+1}(\xi) = \frac{1 + \frac{\nu}{2} G(\xi)}{1 - \frac{\nu}{2} G(\xi)} = \frac{1 - 2\nu \sin^2(\xi/2)}{1 + 2\nu \sin^2(\xi/2)} = G_1(\xi)$$

$$|1 - a| \leq 1 + |a| = 1 + a \quad (a = 2\nu \sin^2(\xi/2) \geq 0)$$

$$\Rightarrow |G_1(\xi)| = \frac{|1 - a|}{|1 + a|} \leq 1 \quad \left( \text{and } G(0) = 1 \right)$$

$$\text{So } \|B_1\|_{\ell_h^2} = \|G_1\|_\infty = 1$$

C.-N. is  
unconditionally  
stable

truncation error (Lax-Richtmyer framework)

$$u^{n+1} = B_1 u^n \quad \left[ B_1 = (I - \frac{\nu}{2} B)^{-1} (I + \frac{\nu}{2} B) \right]$$

$$u_{\text{exact}}^{n+1} = B_1 u_{\text{exact}}^n + k \tau^n$$

easier to compute

$$D_t^+ u_{\text{exact}}^n = \frac{1}{2} \left[ D_x^+ D_x^- u_{\text{exact}}^n + D_x^+ D_x^- u_{\text{exact}}^{n+1} \right] + \tilde{\tau}^n$$

relationship between the two:  $\tau^n = (I - \frac{\nu}{2} B)^{-1} \tilde{\tau}^n$

$$\|\tau^n\|_{2,h} \leq \|\tilde{\tau}^n\|_{2,h} \quad \text{since} \quad \left| \frac{1}{1 - \frac{\nu}{2} G(\xi)} \right| \leq 1$$

$\uparrow$   
 $1 + 2\nu \sin^2(\frac{\xi}{2})$

stencil:  $t_n+k$   $\bullet$   $\bullet$   $\bullet$   
 $t_n$   $\bullet$   $\bullet$   $\bullet$   
 $x_j$   $*$   
 $\leftarrow$  do Taylor expansion at  $(x_j, t_n + \frac{1}{2}k)$

$$\begin{aligned} \textcircled{*} \quad (D_t^+ u_{\text{exact}}^n)_j &= \frac{u(jh, nk+k) - u(jh, nk)}{k} \\ &= \frac{\left[ u + \frac{k}{2} u_t + \frac{1}{2} \left( \frac{k}{2} \right)^2 u_{tt} + \frac{1}{6} \left( \frac{k}{2} \right)^3 u_{ttt} + \dots \right] - \left[ u - \frac{k}{2} u_t + \dots \right]}{k} \\ &= u_t + \frac{k^2}{24} u_{ttt} + O(k^4) \quad \leftarrow \begin{matrix} \uparrow \\ \text{at } (jh, nk + \frac{k}{2}) \end{matrix} \end{aligned}$$

( $u_{tt}$  term cancelled by symmetry of midpoint)

lecture 2

$$(D_x^+ D_x^- u_{\text{exact}}^n)_j = u_{xx}(jh, nk) + \frac{h^2}{12} u_{xxxx}(jh, nk) + O(h^4)$$

$$(D_x^+ D_x^- u_{\text{exact}}^{n+1})_j = u_{xx}(jh, nk+k) + \frac{h^2}{12} u_{xxxx}(jh, nk+k) + O(h^4)$$

now we expand  $u_{xx}$ ,  $u_{xxxx}$  at  $(jh, nk + \frac{k}{2})$   
in the time direction

e.g.  $u_{xx}(jh, nk+k) = u_{xx} + \frac{k}{2} u_{xxt} + \frac{(k/2)^2}{2} u_{xxtt} + \frac{(k/2)^3}{6} u_{xxttt} + \dots$

$$\frac{1}{2}(\cdot + \cdot) = u_{xx} + \frac{k^2}{8} u_{xxtt} + O(k^4) \quad \leftarrow \text{at } (jh, nk + \frac{k}{2})$$

$$+ \frac{h^2}{12} \left( u_{xxxx} + \frac{k^2}{8} u_{xxxxtt} + O(k^4) \right) + O(h^4)$$

so  $\tilde{\tau}_j^n = \text{⊗} - \text{⊗}$

$$= \underbrace{(u_t - u_{xx})}_0 + \frac{k^2}{24} u_{ttt} - \frac{k^2}{8} u_{xxtt} - \frac{h^2}{12} u_{xxxx} + O(k^4 + h^4)$$

$$= O(k^2 + h^2)$$

$$0 \leq (k^2 - h^2)^2$$

$$0 \leq k^4 - 2k^2h^2 + h^4$$

$$2k^2h^2 \leq k^4 + h^4$$