

Last time: Truncation error for $D_t^+ u = D_x^+ D_x^- u$

$$v = \frac{h}{h^2} \begin{cases} \text{if } v = \frac{1}{6}, |\tau_j^n| \leq M \left(\frac{h^2}{6} + \frac{h^4}{360} \right), M = \sup_x |\partial_x^6 g(x)| \\ \text{otherwise } |\tau_j^n| \leq M \left(\frac{h}{2} + \frac{h^2}{12} \right), M = \sup_x |\partial_x^4 g(x)| \end{cases}$$

Today: • Consistency, stability, convergence
• Lax-Richtmyer equivalence theorem

recall that $h = \Delta x, k = \Delta t$

def: A scheme is consistent if $\tau_j^n \rightarrow 0$ as $k, h \rightarrow 0$

One can also specify the rate, e.g. $\tau_j^n = O(k + h^2)$

"first order in time, second order in space"

We'll be more precise about what $\tau_j^n \rightarrow 0$ means below.

We established uniform convergence above, with $|\tau_j^n| \leq M \left(\frac{k}{2} + \frac{h^2}{12} \right)$
↑
indep. of n, j

In words:

- A scheme is consistent if the exact solution of the PDE is an approximate solution of the scheme
- It is convergent if the exact solution of the scheme is an approximate solution of the PDE. (The solution of the scheme is close to the exact solution of the PDE)

Lax-Richtmyer equivalence theorem: A consistent finite difference scheme for a well-posed initial value problem is convergent iff it is stable.

main result here: consistency + stability \Rightarrow convergence

setting of Lax-Richtmyer paper:

$$u_t = Au \quad (0 \leq t \leq T)$$

$$u(0) = g$$

$$\text{our case: } A = \frac{\partial^2}{\partial x^2}$$

linear, constant coefficient

ODE in a Banach space \mathcal{B}

complete normed linear space

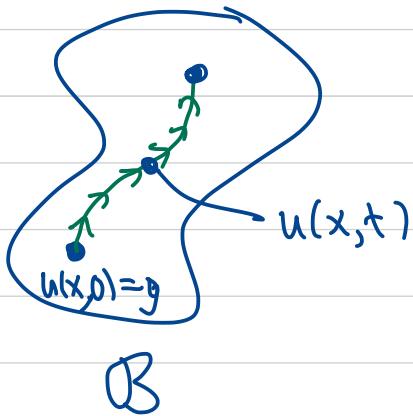
$\mathcal{B} = BC(\mathbb{R})$, bounded, continuous functions on \mathbb{R}

$$\text{max norm: } \|g\| = \|g\|_{\infty} = \sup_{-\infty < x < \infty} |g(x)|$$

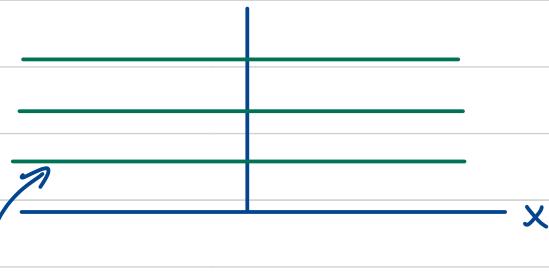
(other Banach spaces also work nicely for the heat equation)

e.g. $L^1(\mathbb{R}), L^2(\mathbb{R})$

abstract picture



each point in \mathcal{B} is a function of x with t frozen

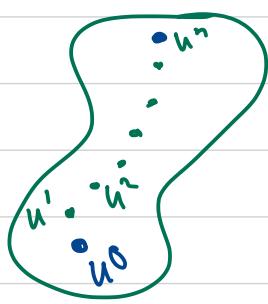


a time slice of the solution
 $u(x, t)$ is a function of x and can be thought of as a point on the solution curve in the space \mathcal{B} .

our case

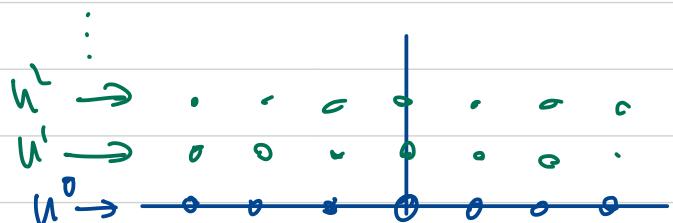
$$u(x, t) = \frac{1}{\sqrt{4\pi t}} \int_{-\infty}^{\infty} e^{-\frac{(x-\xi)^2}{4t}} g(\xi) d\xi$$

Next we set up a grid and define our finite difference scheme as an operator from one discrete time slice to the next



$\mathcal{B}_h = \ell^\infty(\mathbb{Z}) = \text{space of bounded sequences } \{f_j\}_{j=-\infty}^{\infty}$

$$u^{n+1} = \underbrace{\mathcal{B}(k, h)}_{\text{bounded operator on } \mathcal{B}_h} u^n$$



our case:

$$B(k, h) = \nu u_{j+1} + (1-2\nu)u_j + \nu u_{j-1}, \quad \nu = \frac{h}{h^2}$$

next define a refinement path $h = H(k)$ relating h to h

$$\text{our case: } \nu = \frac{k}{h^2} = \text{const}, \quad H(k) = \sqrt{k/\nu}$$

let $B = B(k)$ denote $B(k, H(k))$

def: A scheme is stable if $\forall T > 0 \exists K, \varepsilon > 0$ s.t.

$$\|B(k)^n\| \leq K \quad \text{for} \quad \begin{aligned} 0 < k < \varepsilon \\ 0 \leq nk \leq T \end{aligned}$$

operator norm: $\|A\| = \sup_{\substack{u \neq 0 \\ u \in \mathbb{B}}} \frac{\|Au\|}{\|u\|}$ $\left(\Rightarrow \|Au\| \leq \|A\| \cdot \|u\| \right)$
for all $u \in \mathbb{B}$
and $\|AB\| \leq \|A\| \cdot \|B\|$

$B(k)^n$ means $\underbrace{B(k) \cdot B(k) \cdots B(k)}_{n \text{ times}}$

proof of Lax-Richtmyer:

$$\left(\begin{array}{l} \text{error} \\ e_j^n = u_j^n - u(jh, nh) \end{array} \right)$$

scheme: $u_j^{n+1} = B(k)u_j^n$

exact: $u(jh, (n+1)h) = B(k)u(jh, nh) + k\tau_j^n$

subtract: $e_j^{n+1} = B(k)e_j^n - k\tau_j^n$

so

$$\begin{aligned}
 e_j^0 &= B(k) e_j^0 - k \tau_j^0 \\
 e_j^1 &= B(k)^2 e_j^0 - B(k) k \tau_j^0 - k \tau_j^1 \\
 &\vdots \\
 e_j^n &= B(k)^n e_j^0 - B(k)^{n-1} k \tau_j^0 - B(k)^{n-2} k \tau_j^1 \\
 &\quad - \dots - B(k) k \tau_j^{n-2} - k \tau_j^{n-1}
 \end{aligned}$$

picture:

$$\begin{aligned}
 t &= nk \\
 t &= (m+1)k \\
 t &= mk \\
 t &= k \\
 t &= 0
 \end{aligned}$$

τ^m enters here

$$e_j^{m+1} = B(k) e_j^m - k \tau_j^m$$

thus gets propagated by $B(k)$ $\underbrace{n-(m+1)}_l$ times

$$B(k)^l k \tau_j^m$$

take norms, use triangle inequality and $\|B(k)^l\| \leq K$

$$\begin{aligned}
 \|e^n\| &\leq K \underbrace{\|e^0\|}_0 + Kk(\|\tau^0\| + \|\tau^1\| + \dots + \|\tau^{n-1}\|) \\
 &\leq K nk \max_{1 \leq l \leq n} \|\tau^l\|, \quad nk \leq T
 \end{aligned}$$

In our case, $\|\tau^l\| = \begin{cases} O(h^{1+\nu}) & \nu \neq \frac{1}{6} \\ O(h^2 + h^4) & \nu = \frac{1}{6} \end{cases}$ and we will show

that the scheme is stable if $\nu \leq \frac{1}{2}$ $(K=1, \varepsilon=\infty)$
works

Conclusion :

$$\|e^n\| \leq \begin{cases} TM \left(\frac{h}{2} + \frac{h^2}{12} \right) & \nu \neq \frac{1}{6}, 0 < \nu \leq \frac{1}{2} \\ TM \left(\frac{h^2}{6} + \frac{h^4}{360} \right) = \frac{TMh^4}{135} & \nu = \frac{1}{6} \end{cases}$$

↑
true for all n satisfying $0 \leq nh \leq T$

$$\max_{0 \leq nh \leq T} \sup_{-\infty < j < \infty} |e_j^n| = \max_n \|e^n\| \leq \text{RHS}$$

∴ The maximum value of the error on the grid
goes to zero as $k, h \rightarrow 0$ with $\nu = \frac{k}{h^2} \leq \frac{1}{2}$ held fixed