

# Shaipranesh S

|  [shaipranesh2\(github\)](#) | [shaipranesh1@gmail.com](mailto:shaipranesh1@gmail.com) | +91-9360374936 | [f20200731@pilani.bits-pilani.ac.in](mailto:f20200731@pilani.bits-pilani.ac.in)

## EDUCATION

### Birla Institute of Tech. and Science (BITS) Pilani

BS IN COMPUTER SCIENCE AND MSc  
IN CHEMISTRY

Aug 2020-Present | Pilani, India  
GPA: 8.52 / 10.0

### The Indian Public School, CBSE

Grad. May 2020 | Erode, India  
12th: 95.4%

## COURSEWORK

### Math

Linear algebra  
Probability and statistics  
Calculus  
Differential equations

### Coursera

Deeplearning specialization- Andrew Ng

## SKILLS

### Proficient:

C++ • C • Python • Pytorch •  
Tensorflow • ROS • OpenCV • Git

### Familiar:

JAX • R • Gazebo

## PROJECTS

### Zero-DCE implemenatation | SPRING 2022

Robotics researcher, [Team Robocon](#), BITS Pilani

Implemented a [deep learning model](#) for uniform enlightening of darkened images. Was used in the team's drone project for traversal in dark areas and better object detection.

- Read and implemented a Pytorch version of the CNN model from the [Zero-DCE paper](#).
- Tested the model against 2 data-sets and was able to achieve good results in less training time than the paper.

### PRM + A\* robot | SPRING 2022

Robotics researcher, [Team Robocon](#), BITS Pilani

A [gazebo simulation](#) of a turtlebot3 using Probabilistic Road Maps to sample out nodes from the map to move and uses A\* algorithm to find the shortest path from the start to goal. Then programmed and tune PID to help the robot steer.

- Used ROS to program the path-planning algorithm and created a custom Gazebo environment to test the system out.

### Image processing robot | FALL 2021

Robotics researcher, [CRISS Robotics](#), BITS Pilani

Programmed a custom line follower robot which only has a RGB-camera for sensor and to follow a coloured line. Also, programmed the bot to scan for AR tags and follow them.

- Used ROS and OpenCV to program the robot and implemented a PID controller for smooth travel of the robot.

## EXPERIENCE

### Ferminet improvement and implementation(Google Summer Of Code) | MAY 2022 - PRESENT

Guide: [Dr. Peter Eastman](#), Stanford University and Tony Davis, Deepchem

- Was selected for Google Summer Of Code for this project under the organisation Open Chemistry, which aims to develop libraries for computational chemistry.
- Working towards implementing and improving the Deep-learning model [Ferminet](#), a neural network which aims to find the electronic configuration(positions) of a molecule system as accurately as possible. Has material science and drug discovery applications.
- More on the project can be found [here](#)

### Classification of plastics using Multi-spectral images using Neural Networks | JUN 2022 - PRESENT

Guides: [Dr. Madan Kumar Lakshmanan](#), CSIR-CEERI, Chennai

- Investigating Radial Basis Neural network, SVM and Discriminant analysis techniques to sort plastics into their specific type from hyper-spectral images obtained by fusing camera images with Near Infrared spectra.

## POSITIONS OF RESPONSIBILITY

### Mentor, Peer Mentorship Program | AUG 2021 - PRESENT

Selected based on academic record, ethics and peer review to guide 7 freshmen mentees in academic and co-curricular pursuits.