

8 Bootstrap

8.1 Basic Idea

The main principle of the **bootstrap** is that our data can be used to approximate the population.

1. We can observe a sample $X = (X_1, \dots, X_n)$ with distribution function F and the statistical model $\mathcal{P} = \{P_\theta; \theta \in \Theta\}$.
2. We are interested in the parameter $\theta = \theta(F)$, the distribution properties of a given estimator $\hat{\theta} = \hat{\theta}(X)$, and the distribution properties of a given function $T(X, F)$.
3. Estimate F or P_θ by some estimator \hat{F}_n or P^* .
4. Draw independently B random samples $x_{(j)}^*$ of size n from P^* , $j = 1, \dots, B$, that is $X_{(j)}^* \sim P^*$. The samples $x_{(j)}^*$ are called the **bootstrap samples**.
5. For each j , estimate θ using the bootstrap sample $x_{(j)}^*$ as $\hat{\theta}_j^* = \hat{\theta}(x_{(j)}^*)$. The **bootstrap replications** of $\hat{\theta}$ are $\hat{\theta}_1^*, \dots, \hat{\theta}_B^*$. The **bootstrap replications** of the function $T(X, F)$ are $T_{(j)}^* = T(X_{(j)}^*, \hat{F}_n)$, $j = 1, \dots, B$.
6. Pretend that the bootstrap replications are an iid sample from the distribution of $T(X, F)$.

Example 1. Suppose that we have observed iid data x_1, \dots, x_n from a statistical model $X \sim P$ with distribution function F . Our focus is the median of this distribution, denoted by $m(F)$. We use the sample median $m_{(n)}$ to estimate the population median $m(F)$. The “bias” can be computed by $T(\mathbf{X}, \mathbf{F}) = m_{(n)} - m(F)$. In bootstrap, the first steps are the same as classical inference:

1. Our data is $\mathbf{x} = (x_1, \dots, x_n)$ from $\mathbf{X} = (X_1, \dots, X_n)$.
2. The parameter is $m(F)$. We are interested in $T = m_{(n)} - m(F)$.
3. If we choose the nonparametric approach, we estimate \mathbf{F} by some estimator $\hat{\mathbf{F}}_n$ using \mathbf{x} as

$$\hat{F}_n(x) = \frac{1}{n} \sum_{i=1}^n 1(x_i \leq x).$$

The estimated distribution P^* is $P(X = x_i) = n^{-1}$ for any i . The estimator of $m(F)$ is $m_{(n)} = m(\hat{F}_n)$.

4. Draw independently B bootstrap samples $\mathbf{x}_{(j)}^* = (x_{1j}^*, \dots, x_{nj}^*)$ of size n from P^* , $j = 1, \dots, B$.
5. For each j , estimate $m(\hat{F}_n)$ using the bootstrap sample $\mathbf{x}_{(j)}^*$ as $m_{(n),j}$, where $m_{(n),j}$ is the sample median of $x_{1j}^*, \dots, x_{nj}^*$. Compute the difference

$$T_j = m_{(n),j} - m_{(n)},$$

since $m_{(n)}$ is the median of the distribution P^* .

6. View $m_{(n),j} - m_{(n)}$, $j = 1, \dots, B$, as an iid sample from the distribution of $m_{(n)} - m(F)$. For example, the bias of the estimator $m_{(n)}$ can be approximated by

$$\frac{1}{B} \sum_{j=1}^B m_{(n),j} - m_{(n)}.$$

Parametric and nonparametric approaches can make some difference.

1. The [parametric bootstrap](#) assumes a parametric form of the statistical model P index by some parameter θ .
 - For example, we assume $X \sim N(\mu, \sigma^2)$. The bootstrap samples are drawn from $N(\hat{\mu}, \hat{\sigma}^2)$.
2. The [nonparametric bootstrap](#) estimates F by the empirical distribution function.
 - The estimated distribution is $P(X = x_i) = n^{-1}$ for any i .

Definition 1 (ecdf). Let x_1, \dots, x_n be a sequence of iid measurements, then the fraction

$$\hat{F}_n(x) = \frac{1}{n} \sum_{i=1}^n 1(x_i \leq x)$$

is called the [empirical cumulative distribution function](#) (ecdf) or the [empirical distribution function](#).

8.2 Why Does Bootstrap Work?

By Law of large numbers, $\hat{F}_n(x) \xrightarrow{P} F(x)$, where $F(x)$ is the true cdf, for every fixed x .

Theorem 1 (Glivenko-Cantelli Theorem for Unidimensional Case). *Let Z_1, \dots, Z_n be iid real valued random variables with distribution function $F(z) = P(Z \leq z)$. Denote the empirical distribution function by*

$$F_n(z) = \frac{1}{n} \sum_{i=1}^n 1(Z_i \leq z).$$

Then,

$$P \left\{ \sup_{z \in \mathbb{R}} |F_n(z) - F(z)| > \epsilon \right\} \leq 8(n+1) \exp \left\{ -\frac{1}{32} n \epsilon^2 \right\}.$$

In particular, by the Borel-Cantelli lemma,

$$\lim_{n \rightarrow \infty} \sup_{z \in \mathbb{R}} |F_n(z) - F(z)| = 0, \text{ with probability 1.}$$

In fact, we can improve the result to

$$P \left\{ \sup_{z \in \mathbb{R}} |F(z) - F_n(z)| > \epsilon \right\} \leq 2 \exp \left\{ -2n \epsilon^2 \right\}.$$

Recall that bootstrap aims to approximate the exact distribution of $T(X, F)$ using the distribution of $T(X^*, \hat{F}_n)$, if we take nonparametric bootstrap as an example.

Definition 2. The bootstrap is [consistent](#) if

$$\sup_t \left| P(T(X, F) \leq t) - P(T(X^*, \hat{F}_n) \leq t \mid \hat{F}_n) \right| \xrightarrow{P} 0,$$

where the second probability $P(T(X^*, \hat{F}_n) \leq t \mid \hat{F}_n)$ is still a random variable.

By the [Glivenko-Cantelli theorem](#), we know that

$$P \left(\sup_x |\hat{F}_n(x) - F(x)| > \epsilon \right) \rightarrow 0.$$

Hence for sufficiently large n , sampling from F is similar to sampling from \hat{F}_n . More assumptions are needed in order for bootstrap to work.

Proposition 1. Suppose that

$$\begin{aligned} P(T(X, F) \leq x) &\rightarrow F_A(x), \\ P\left(T\left(X^*, \hat{F}_n\right) \leq x \mid \hat{F}_n\right) &\xrightarrow{P} F_A(x), \end{aligned}$$

where $F_A(x)$ is a continuous function. Then bootstrap is consistent.

Example 2. Suppose that X_1, \dots, X_n is an iid $(\mu, 1)$, where $E[X] = \mu$ and $\text{Var}[X] = 1$, but not necessarily normal. We are interested in $T(\bar{X}, \mu) = \sqrt{n}(\bar{X} - \mu)$.

1. By CLT, $T(\bar{X}, \mu) = \sqrt{n}(\bar{X} - \mu) \xrightarrow{d} N(0, 1)$. Hence,

$$P(\sqrt{n}(\bar{X} - \mu) \leq x) \rightarrow \Phi(x),$$

where $\Phi(x)$ is a continuous function in x .

2. In the bootstrap world, we simulate (X_1^*, \dots, X_n^*) from \hat{F}_n . The conditional mean and variance is

$$\begin{aligned} E[X_i^* \mid \hat{F}_n] &= \bar{X}, \\ \text{Var}[X_i^* \mid \hat{F}_n] &= \frac{1}{n} \sum_{i=1}^n (X_i - \bar{X})^2. \end{aligned}$$

By Strong Law of Large Numbers, $\bar{X} \rightarrow \mu$ and $\frac{1}{n} \sum_{i=1}^n (X_i - \bar{X})^2 \rightarrow 1$ for almost every sequence X_1, X_2, \dots (almost surely convergence). To obtain the asymptotic distribution of \bar{X}^* , we need CLT for a triangular array, since we don't have identical distribution anymore when we change n . The Lindeberg-Feller CLT says that the sequence $\frac{1}{\sqrt{n}} \sum_{i=1}^n (Y_{n,i} - E[Y_{n,i}]) \xrightarrow{d} N(0, \sigma^2)$ under some assumptions. Using this CLT, conditional on \hat{F}_n , we have

$$\sqrt{n}(\bar{X}^* - \bar{X}) = \frac{1}{\sqrt{n}} \sum_{i=1}^n (X_i^* - \bar{X}) \xrightarrow{d} N(0, 1).$$

Equivalently,

$$P(\sqrt{n}(\bar{X}^* - \bar{X}) \leq x \mid \hat{F}_n) \rightarrow \Phi(x),$$

conditionally on X_1, X_2, \dots . The convergence holds for almost every sequence X_1, X_2, \dots , since $\bar{X} \rightarrow \mu$ and $\frac{1}{n} \sum_{i=1}^n (X_i - \bar{X})^2 \rightarrow 1$ for almost every sequence X_1, X_2, \dots (almost surely convergence). This suggests that

$$P(\sqrt{n}(\bar{X}^* - \bar{X}) \leq x \mid \hat{F}_n) \xrightarrow{P} \Phi(x).$$

The extra convergence in probability is needed because the LHS probability depends on \hat{F}_n .

Example 3 (Bootstrap can fail). Suppose that X_1, \dots, X_n is an iid uniform $[0, \theta]$, we can show that $\sqrt{n}(X_{[n]} - \theta)$ does not converge to a normal distribution. In fact,

$$T = \frac{n(\theta - X_{[n]})}{\theta} \xrightarrow{d} \text{Exp}(1).$$

If nonparametric bootstrap works, the distribution of $T^* = n(x_{[n]} - X_{[n]}^*)/x_{[n]}$ should converge to distribution of T . But

$$P(T^* = 0) \rightarrow 1 - e^{-1},$$

because

$$\begin{aligned}
 \mathbb{P}\left(\max_i X_i^* = x_{[n]} \mid x_1, \dots, x_n\right) &= 1 - \underbrace{\left[P\left(X_i^* < x_{[n]} \mid x_1, \dots, x_n\right)\right]^n}_{\text{all bootstrap sample } < x_{[n]}} \\
 &= 1 - \left(1 - \frac{1}{n}\right)^n \rightarrow 1 - e^{-1} > 0.
 \end{aligned}$$