

2 Statistical Inference Principles

2.1 Statistical Model and Background

Definition 1. A **statistical model** is a class of possible probability measures \mathcal{P} on the sample space \mathcal{X} , parameterized by parameter(s) θ :

$$\mathcal{P} = \{P_\theta : \theta \in \Theta\},$$

where P_θ is the distribution with parameter θ such that $X \sim P_\theta$, and Θ is the **parameter space**. A **sample** $\mathbf{X} = (X_1, \dots, X_n)$ is a collection of independent random variables where X_i is distributed according to a distribution $P_{i,\theta}$. The **sample size** n is the number of the random variables. A **statistic** T is a function of the sample

$$T : \mathbf{x} \in \mathcal{X} \rightarrow T(\mathbf{x}) = t \in \mathcal{T},$$

where \mathcal{T} is some set. With random variable \mathbf{X} , the function $T(\mathbf{X})$ is also a random variable, the distribution of which is given by

$$P_\theta^T(B) = P_\theta(\{\mathbf{x} : T(\mathbf{x}) \in B\}).$$

An **estimator** of θ is a statistic $\delta(X)$ that we want to use to estimate unknown parameter θ .

Example 1. If we assume $X \sim \text{Bernoulli}(\theta)$, then $P_\theta = \text{Bernoulli}(\theta)$, and our statistical model is

$$\mathcal{P} = \{\text{Bernoulli}(\theta) : \theta \in (0, 1)\}.$$

If we observe a sample X_1, \dots, X_n from it, one statistic of interest is $T(x) = \sum_{i=1}^n x_i$ or $T(x) = \bar{X} \equiv n^{-1} \sum_{i=1}^n x_i$.

2.2 Sufficient Statistic

Any statistic $T : x \in \mathcal{X} \rightarrow T(x) = t \in \mathcal{T}$ generates a partition of the sample space

$$\mathcal{X} = \bigcup_t \mathcal{X}_t \quad \text{with} \quad \mathcal{X}_t = \{\mathbf{x} : T(\mathbf{x}) = t\}.$$

Example 2. Suppose that we toss a coin 2 times independently. For $i = 1, 2$, let $X_i = 1$ if we get a head, and 0 otherwise.

- The sample space is $\mathcal{X} = \{(0, 0), (0, 1), (1, 0), (1, 1)\}$.
- Define the statistic $T(X_1, X_2) = X_1 + X_2$.
- The partition is

$$\mathcal{X} = \{(0, 0)\} \cup \{(0, 1), (1, 0)\} \cup \{(1, 1)\}.$$

Taking any partition incurs loss of information.

- For example, we only know we get 1 head, but don't know whether it is the first toss or the second.

But the lost information may be irrelevant for inference.

Definition 2 (Sufficient Statistic). A statistic T is said to be **sufficient** for the statistical model $\{P_\theta : \theta \in \Theta\}$ if the conditional distribution of X given $T = t$ is independent of θ for all t . Such T is called a **sufficient statistic**.

Note: the distribution of X depends on θ , the distribution of T depends on θ , but the distribution of $\mathbf{X} \mid T$ does not depend on θ . If T is sufficient for θ , then T captures all information about θ included in X .

Example 3 (Sufficient Statistic). Let X_1, \dots, X_n be i.i.d. Bernoulli random variables with parameter $\theta \in (0, 1)$. Define $T = \sum_{i=1}^n X_i$. Then,

$$\begin{aligned} P(X_1 = x_1, \dots, X_n = x_n \mid T = t) &= \frac{P(X_1 = x_1, \dots, X_n = x_n, T = t)}{P(T = t)} = \frac{P(X_1 = x_1, \dots, X_n = x_n)}{P(T = t)} \\ &= \frac{\prod_{i=1}^n \theta^{x_i} (1 - \theta)^{1-x_i}}{\binom{n}{t} \theta^t (1 - \theta)^{n-t}} = \frac{1}{\binom{n}{t}}, \end{aligned}$$

that does not depend on θ .

Theorem 1 (Factorization theorem). Let $\mathcal{P} = \{P_\theta : \theta \in \Theta\}$ be a family of distributions dominated by μ . A necessary and sufficient condition for a statistic T to be sufficient is that there exist functions $g(T(x), \theta) \geq 0$ and $h(x) \geq 0$ such that the densities satisfy

$$p(x \mid \theta) = g(T(x), \theta) h(x), \text{ almost everywhere under } \mu.$$

Example 4. Let X_1, \dots, X_n be i.i.d. random variables with parameter θ .

1. Bernoulli random variables with parameter $\theta \in (0, 1)$. Then,

$$p(x \mid \theta) = \theta^{\sum_{i=1}^n x_i} (1 - \theta)^{n - \sum_{i=1}^n x_i}.$$

Hence, $T(x) = \sum_{i=1}^n x_i$.

2. $N(\mu, \sigma^2)$ with $\theta = (\mu, \sigma^2)$. Then,

$$p(x \mid \theta) = \prod_{i=1}^n \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left\{-\frac{(x_i - \mu)^2}{2\sigma^2}\right\} = \frac{1}{(2\pi\sigma^2)^{n/2}} \exp\left\{-\frac{n\mu^2}{2\sigma^2}\right\} \exp\left\{\frac{n\mu}{\sigma^2} \bar{x} - \frac{1}{2\sigma^2} \sum_{i=1}^n x_i^2\right\}.$$

Hence $T(x) = (\bar{x}, \sum_{i=1}^n x_i^2)$.

Theorem 2 (Sufficiency in Exponential Family). Consider exponential family

$$p(x \mid \theta) = \exp\left\{\sum_{i=1}^s \eta_i(\theta) T_i(x) - A(\eta)\right\} h(x).$$

Then, the statistic $T(x) = (T_1(x), \dots, T_s(x))$ is sufficient.

Proof. The factorization theorem directly implies that $T(x) = (T_1(x), \dots, T_s(x))$ is sufficient. \square

Example 5. Let X_1, \dots, X_n be i.i.d. Bernoulli with parameter θ . Then,

$$p(x \mid \theta) = \exp\{n\bar{X} \log \theta + n(1 - \bar{X}) \log(1 - \theta)\},$$

belongs to exponential family. Hence, $T(x) = (n\bar{X}, n(1 - \bar{X}))$ is sufficient.

2.3 Minimal Sufficiency

Sufficient statistic is not unique. For the normal example, we can rewrite the density as

$$\begin{aligned} p(x \mid \theta) &= \frac{1}{(2\pi\sigma^2)^{n/2}} \exp\left\{-\frac{n\mu^2}{2\sigma^2}\right\} \exp\left\{\frac{n\mu}{\sigma^2} \bar{x} - \frac{1}{2\sigma^2} \left[\sum_{i=1}^n x_i^2 - n(\bar{x})^2\right] - \frac{n}{2\sigma^2} (\bar{x})^2\right\} \\ &= \frac{1}{(2\pi\sigma^2)^{n/2}} \exp\left\{-\frac{n\mu^2}{2\sigma^2}\right\} \exp\left\{\frac{n\mu}{\sigma^2} \bar{x} - \frac{n-1}{2\sigma^2} S^2 - \frac{n}{2\sigma^2} (\bar{x})^2\right\} \end{aligned}$$

Hence, $T(x) = (\bar{X}, S^2)$ is also sufficient. If T is sufficient for a family of distributions \mathcal{P} and $T = f(\tilde{T})$, then \tilde{T} is also sufficient for \mathcal{P} .

Example 6. Any sufficient statistic is a function of x . Hence, the original data x is sufficient.

Definition 3 (Minimal Sufficiency). A sufficient statistic T is called a **minimal sufficient statistic** if T is a measurable function of any other sufficient statistic (almost everywhere under \mathcal{P}). The set where this definition fails is a null set for every $P_\theta = \mathcal{P}$.

Theorem 3. Let $\mathcal{P} = \{P_\theta : \theta \in \Theta\}$ be a family of statistical models with density $p(x | \theta)$ with respect to a measure μ . Consider two independent samples x and y from P_θ . If $p(x | \theta) / p(y | \theta)$ does not depend on θ if and only if $T(x) = T(y)$ [we do not know T is sufficient yet]. Then T is sufficient and minimal sufficient.

Example 7. Let X_1, \dots, X_n be i.i.d. random variables with parameter θ .

1. Bernoulli random variables with parameter $\theta \in (0, 1)$. Then,

$$p(x | \theta) = \theta^{\sum_{i=1}^n x_i} (1 - \theta)^{n - \sum_{i=1}^n x_i}.$$

Consider the ratio

$$\begin{aligned} \frac{p(x | \theta)}{p(y | \theta)} &= \frac{\theta^{\sum_{i=1}^n x_i} (1 - \theta)^{n - \sum_{i=1}^n x_i}}{\theta^{\sum_{i=1}^n y_i} (1 - \theta)^{n - \sum_{i=1}^n y_i}} = \theta^{\sum_{i=1}^n x_i - \sum_{i=1}^n y_i} (1 - \theta)^{\sum_{i=1}^n y_i - \sum_{i=1}^n x_i} \\ &= \left(\frac{\theta}{1 - \theta} \right)^{\sum_{i=1}^n x_i - \sum_{i=1}^n y_i} \end{aligned}$$

The minimal sufficient statistic is $T = \sum_{i=1}^n x_i$.

2. Cauchy distribution with density

$$p(x | \theta) = \frac{1}{\pi [1 + (x - \theta)^2]}.$$

The ratio is

$$\frac{p(x | \theta)}{p(y | \theta)} = \frac{\prod_{i=1}^n [1 + (y_i - \theta)^2]}{\prod_{i=1}^n [1 + (x_i - \theta)^2]} = \frac{\prod_{i=1}^n [1 + y_i^2 - 2y_i\theta + \theta^2]}{\prod_{i=1}^n [1 + x_i^2 - 2x_i\theta + \theta^2]}.$$

The minimal sufficient statistic is the order statistic.

2.4 Completeness

Definition 4 (Completeness). A statistical model $\{P_\theta : \theta \in \Theta\}$ is called **complete**, if for any (Borel) measurable function $h : \mathcal{X} \rightarrow \mathbb{R}$, the statement

$$E[h(X)] = 0 \text{ for all } \theta \in \Theta$$

implies the result $P\{h(X) = 0 | \theta\} = 1$ for all $\theta \in \Theta$. A statistic $T \sim P_\theta^T$ is called **complete** if the statistical model $\{P_\theta^T : \theta \in \Theta\}$ is complete. If completeness holds for all bounded (Borel) measurable function $h(\cdot)$, then we say it is **boundedly complete**.

Remark 1. By the definition, a complete statistic is also boundedly complete.

Example 8. Completeness means that as long as the expectation is zero for all θ , we must have $h = 0$ as the only unbiased estimator of 0. In order to show it is not complete, we just need to find a nonzero h such that its expectation is 0 for all θ .

1. Consider the statistical model $\{\text{Uniform}(0, \theta), \theta \in \mathbb{R}_+\}$. Let h be an arbitrary function. The statement $E[h(X)] = 0$ is equivalent to

$$\int_0^\theta h(x) \frac{1}{\theta} dx = 0 \text{ for any } \theta.$$

The statistical model is complete. See P6 of the book Theoretical Statistics for a more detailed discussion.

2. Let X_1, \dots, X_n be i.i.d. random variable from Bernoulli(θ) where $\theta \in (0, 1)$. Then, $T = \sum_{i=1}^n X_i$ follows Binomial. Then,

$$\begin{aligned} 0 = E[h(T)] &= \sum_{t=0}^n h(t) \binom{n}{t} \theta^t (1-\theta)^{n-t} \\ &= (1-\theta)^n \sum_{t=0}^n h(t) \binom{n}{t} \left(\frac{\theta}{1-\theta}\right)^t. \end{aligned}$$

The statistic T is a complete statistic.

3. Let X_1, \dots, X_n be i.i.d. random variable from $N(\mu, \mu^2)$. The statistic $T = (\sum_{i=1}^n X_i, \sum_{i=1}^n X_i^2)$ is not complete. This is because we let

$$h(T) = \left(\sum_{i=1}^n X_i\right)^2 - \frac{n+1}{2} \sum_{i=1}^n X_i^2$$

Note that $E[\sum_{i=1}^n X_i] = n\mu$, $\text{Var}[\sum_{i=1}^n X_i] = n\mu^2$, $E[\sum_{i=1}^n X_i^2] = 2n\mu^2$. Then,

$$E[h(T)] = (n + n^2) \mu^2 - \frac{n+1}{2} \cdot 2n\mu^2 = 0,$$

but $h(T) \neq 0$.

Proposition 1. *If T is a complete statistic and $S = \psi(T)$ for a continuous function ψ , then S is also complete. The proposition holds if we change both complete statistic to boundedly complete statistic.*

Proof. Since T is complete, then

$$E[h(T)] = 0 \text{ for all } \theta \in \Theta$$

implies the result $P\{h(T) = 0 \mid \theta\} = 1$ for all $\theta \in \Theta$. Assume that

$$E[h(S)] = E[h(\psi(T))] = 0 \text{ for all } \theta \in \Theta.$$

Since T is complete, we must have $P\{h(\psi(T)) = 0 \mid \theta\} = 1$ for all $\theta \in \Theta$, as long as $h(\psi(\cdot))$ is measurable. That is $P\{h(S) = 0 \mid \theta\} = 1$. \square

Theorem 4 (Bahadur's theorem: Completeness and Minimal Sufficiency). *If a minimal sufficient statistic exists, then*

1. *any sufficient and complete statistic is minimal sufficient.*
2. *any sufficient and boundedly complete statistic is minimal sufficient*

Proof. We show the first part of the theorem. Suppose that S is a minimal sufficient statistic, and that T is sufficient and complete. Then, $T - E[T | S] = T - E[T | S(T)]$ is a function of T , since S is minimal sufficient and is a function of any other sufficient statistic (including T). Note that

$$E(T - E[T | S]) = E[T] - E(E[T | S]) = 0.$$

Since T is complete, then we must have $T = E[T | S]$ with probability 1, that is, T is also a function of S . Since S is a function of any sufficient statistic, then T is a function of any sufficient statistic, which means that T is minimal sufficient. \square

Theorem 5. *For the exponential family in canonical form*

$$p(x | \eta) = \exp \left\{ \sum_{i=1}^s \eta_i T_i(x) - A(\eta) \right\} h(x),$$

consider the statistic $T = (T_1(x), \dots, T_d(x))$. If the exponential family is of full rank, T is also complete.

Proof. If you are interested in the proof, see Brown (1986), Fundamentals of Statistical Exponential Families with Applications in Statistical Decision Theory, Page 44. \square

2.5 Ancillary Statistic

Definition 5 (Ancillary Statistic). A statistic is called [ancillary](#) if its distribution does not depend on θ .

Example 9. Suppose that X_1, X_2 are iid $N(\theta, 1)$. Then, $X_1 - X_2 \sim N(0, 2)$ is an ancillary statistic.

Theorem 6 (Basu Theorem). *If a statistic T is complete and sufficient for $\mathcal{P} = \{P_\theta : \theta \in \Theta\}$, and if V is an ancillary statistic, then T and V are independent under P_θ for any $\theta \in \Theta$.*

Example 10. Suppose that X_1, \dots, X_n are iid $N(\mu, \sigma^2)$. A well-known result is that \bar{X} and $S^2 = \frac{1}{n-1} \sum_{i=1}^n (X_i - \bar{X})^2$ are independent. To show this result, we note that

$$p(x_1, \dots, x_n | \theta) = \frac{1}{(2\pi\sigma^2)^{n/2}} \exp \left\{ -\frac{1}{2\sigma^2} \sum_{i=1}^n x_i^2 + \frac{n\mu}{\sigma^2} \bar{x} - \frac{n\mu^2}{2\sigma^2} \right\}.$$

Hence, we have a full rank two-parameter exponential family. Thus, $T = (\bar{X}, \sum_{i=1}^n x_i^2)$ is sufficient and complete for the normal family with unknown μ . Define $Y_i = X_i - \mu \sim N(0, \sigma^2)$. Then,

$$X_i - \bar{X} = Y_i - \bar{Y}, \quad \forall i,$$

that only depends on σ^2 , not μ . Further

$$S^2 = \frac{1}{n-1} \sum_{i=1}^n (Y_i - \bar{Y})^2$$

only depends on σ^2 , not μ . That is, S^2 is an ancillary statistic [no μ is involved]. By the Basu theorem, \bar{X} and S^2 are independent.