# **NACHOS**

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## **Project Management**

- For steps 2, 3 and 4, the basic parts were done concurrently
- Shakeel: Additional parts of Step2, Thread Join, Process Exit
- Sannara: User Semaphores, Thread Join,
- Juan: Files systems, Process Join

#### **Outline**

- **★** Multithreading
  - Thread Creation
  - Stack Management
  - Thread Join
  - Thread Exit
  - User Semaphore
- **★** Multiprocessing
  - Process Creation (ForkExec)
  - Exit of process
  - Waiting on Processes (UserWaitPID)
- **★** Filesystem
  - Directory Tree
  - Open Files Table and concurrent access
  - Increasing the file size

#### **Thread Creation**

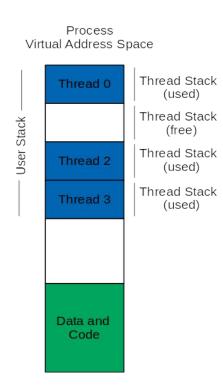
- Thread id is unique across its address space
- Thread id is not being used even after the termination of a thread.
- One to One mapping between NachOS user level threads and kernel level threads.
- Inside a process threads share the same address space but has its own registers and stack.

#### **Supporting Structure:**

- A counter, *tidcounter*,
- A counter, livethreads,
- A bit map, *stackFrames*
- An array of semaphores, called createdThreads used for ThreadJoin

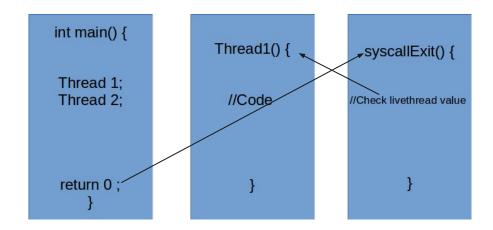
## **Stack Management**

- UserStackSize
- User Stack is divided into frames
- bitmap *stackFrames*, returns an integer value the frame number



#### **Thread Exit**

- What happens to child threads if the main thread returns i.e calls syscallExit()?
- Threads won't have a chance to complete in this case.
- Synchronised handler for syscallExit()
- Livethreads Counter



#### **Thread Join**

- UserThreadJoin System call
- createdThreads: Array of semaphores

```
thread1(void* a)
{
    ...
    UserThreadExit();
}
int main()
{
    ...
    tid1=ThreadCreate(thread1);
    UserThreadJoin(tid1);
    ...

    tid1 = 3
```

#### Case 1: Thread 1 finishes before main executes UserThreadJoin

Initial status of creathedThreads

2	3	4
0	0	0

Thread1 with tid = 3 finishes: creathedThreads[3]->V()

2	3	4	_
0	1	0	

Main thread reaches Join: creathedThreads[3]->P() Main thread continues

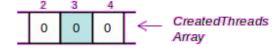
 2	3 4		
0	0	0	

#### Case 2: Main executes UserThreadJoin before thread 1 finishes

Initial status of creathedThreads



Main thread reaches Join: creathedThreads[3] →P() Main thread waits



Thread1 with tid = 3 finishes: creathedThreads[3]->V() Main thread will continue



### **User Semaphores**

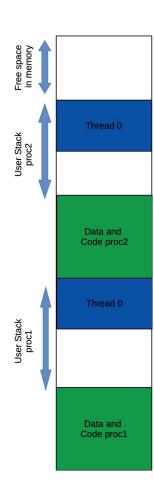
- A new sem\_t data type that is based on ints which are used to represent semaphoresID
- These IDs are used as the index in an array.
- Functionalies & Implementation method
  - SemInit(sem\_t \*arg1, int arg2):
     UserSemaphores[semID] with the value from arg2
  - SemP(sem\_t\* arg): Calls the kernels wait on UserSemaphores[semID] on the index obtained from arg.
  - SemV(sem\_t\* arg): Call the kernels post on UserSemaphores[semID] on the index obtained from arg.



NULL NULL 0 1	NULL
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## Fork Exec (Multiprocessing)

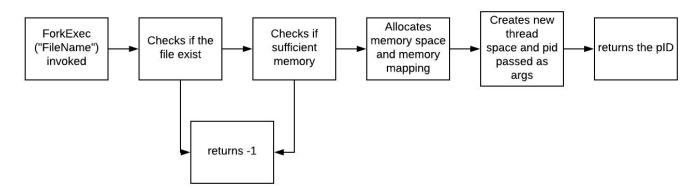
- Process are created through the system call ForkExec()
- Supporting Structure:
  - A counter, procounter,
  - A counter, livepro,
  - A bit map, frameProvider
  - o A identifier, pro



#### Fork Exec

#### 1. Implementations:

- a. Retrieves the file name passed obtained from the argument and attempts to open it with the function fileSystem->Open(Filename)
- b. Checks if the the file else was executable
- c. Checks if there is valid free memory through a function called CheckPhysicalSpace
- d. An object called *space*, data typed addrSpace, will be declared for the new process
- e. The construction of addrSpace for the new process maps frames in the physical memory to the page table and declares them as used through function *GetEmptyFrame*
- f. The new thread is then created with fork, given, a pointer to *space* and to the value of *procounter as an argument*.



## Managing processes exits

- Extended system call Exit
- A counter, *livepro*, is incremented and decremented every time a process starts and finishes
- livepro is checked If its value is at 0.
- If false, the ending process only releases its resources and memories
- No Halt is called

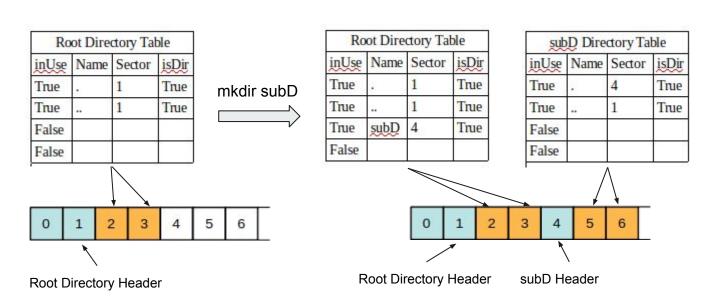
### **UserWaitpID**

- Mechanism user is similar to userThreadJoin which was spoken earlier
- An array of semaphores is used with process ID as indexes.
- UserWaitPid(pid) will invoke a semaphore wait at the index of pid in the semaphore array, which causes the the calling process to wait until the desired process has finishes its work and call a semaphore post.

### File System

- Directory tree
- Multiple open files
- Concurrent access to files
  - A file can be opened multiple times inside a process
  - o A file can not be open in mutiple processes at the same time
- Maximun supported file size: 119,75KB

## File System: Directory Tree



Executing *cd subD* from root directory:

- The global variable currentSector is set to 4;
- The global variable directoryFile point to subD file

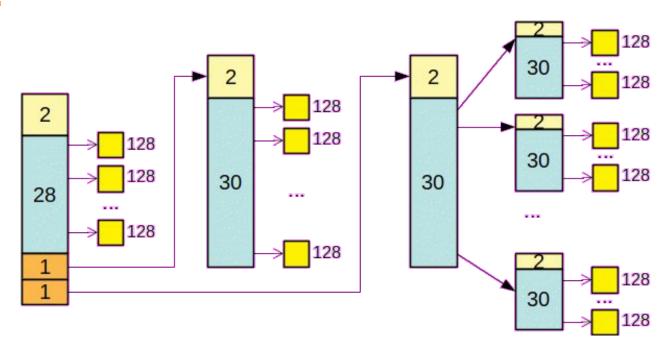
## **Open Files Table and Concurrent Access to Files**

- Two different processes cannot open the same file
- A file can be opened by different threads running in the same process.
- Two open files tables are implemented: one sistem-wide table, and one for each process
- Each open() creates a new entry in the per-process open files table.
  - It may create an entry in the system-wide open files table
- close() frees the corresponding entry in the per-process open files table.
  - It may free the corresponding entry in the system-wide open files table.

		Per Process en Files Tab	le
	inUse	OpenFile*	name
0			
1			
2			

Ope	ystem-v en Files	wide Table
<u>inUse</u>	name	pid
		i.

## Increasing the Maximum File Size



Max Size =  $(28+30+30^2)$  x 128 = 119,75KB

#### Conclusion

- 1. Working on this project made us really understand how an OS fundamentally works.
- 2. Our project has some limitations, but we had a tight time schedule. We also have some ideas how to fix them.
- 3. Git was a good tool to learn and explore.

Any Questions?