QUESTION 1:

State: a snapshot that represents the problem at any moment

State space: all states contained together

Search tree: a "tree" that consist of all the elements that could be searched

Search node: element that holds data

Goal: what you want the end result to be

Action: the options the agent can do based on the current state

Transition model: the things you do within an action that changes a state

Branching factor: offspring per node

QUESTION 2:

A:

- **1.) What a representation of a 'state'** is: a map that holds a "list" of all the countries that either hold one of the four colors or no color at all
- 2.) What a reasonable initial state is: a list of countries that hold no color
- **3.) The actions you can take:** doing the bigger countries first and color it a color thats not its adjacent color
- **4.) The transition model:** coloring a non colored country, making it a colored country, leaving all the other countries in the state they were previously in before they country was colored
- **5.) The cost function:** no cost function because theres the same amount of steps for coloring the countries
- **6.) The goal test:** all the countries are not sharing the same color with their adjacent country

B:

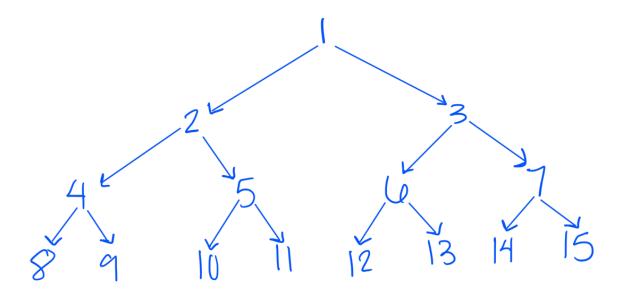
- 1.) What a representation of a 'state' is: a monkey in a room with bananas either hanging from a ceiling or retrieved by the monkey who has either moved, sacked, and/or climbed crates
- **2.) What a reasonable initial state is:** monkey in a room with unstacked or unmoved crates and suspended bananas
- **3.) The actions you can take:** left, right, up, down direction for the boxes; boxes stacked and unstacked; monkey climbing on/ off boxes; grab bananas
- **4.) The transition model:** stacking and moving the crates making it available for the monkey to climb
- **5.) The cost function:** number of actions
- 6.) The goal test: retrieving all the bananas from the ceiling

C:

- **1.) What a representation of a 'state' is:** three jugs either filled to capacity, empty, or empty with water from another jug or the faucet.
- **2.) What a reasonable initial state is:** three jugs of various sizzes that dont contain water
- **3.) The actions you can take:** filling or pour out contents of a jug with either the faucet or another jug
- **4.) The transition model:** filling a jug from water source making it filled to capacity or emptying a jug filled to capacity making it empty
- **5.) The cost function:** number of actions
- **6.) The goal test:** one gallon is filled to capacity

QUESTION 3:

a. Image



b. Suppose the goal state is 11

i. Breadth-first: 1, 2, 3, 4, 5, 11ii. Depth-limited: 1, 2, 4, 5, 11

iii. Iterative deepening: 1; 1, 2, 3; 2, 4, 5, 11

c. Since the successor is (n/2) it helps the search focus. The branching factor is 2 forward and 1 reversed

d. Yes, if you start at the goal state, you could use the single reverse successor until 1 is reached