



Figure 1:

0 is the origin that lies at the centroid of the base triangle. The three neighbors have their centers at  $C_1$ ,  $C_2$  and  $C_3$  that lie opposite to vertices 1, 2 and 3 respectively of base triangle.

The circumradius of all triangles is  $R$ . Length of each edge of the triangles is  $a$ .

$$a = \sqrt{3} R \quad \text{--- (1)}$$

Note that the centers of each neighboring triangles lie on the circumcircle of base triangle. This means,

$$|\vec{C}_1| = |\vec{C}_2| = |\vec{C}_3| = R \quad \text{--- (2)}$$

The three vertices of the triangle will henceforth be represented by  $V_1$ ,  $V_2$  and  $V_3$  respectively instead of just 1, 2 and 3.

With the coordinate system as shown in figure 1, the three vertices have co-ordinates as:

$$\begin{aligned} V_1 &\equiv \left( -\frac{\sqrt{3}}{2} R, -\frac{R}{2} \right) \\ V_2 &\equiv \left( \frac{\sqrt{3}}{2} R, -\frac{R}{2} \right) \\ V_3 &\equiv (0, R) \end{aligned} \quad \text{--- (3)}$$

The co-ordinates of centers of three neighboring triangles are

$$\begin{aligned} C_1 &\equiv \left( \frac{\sqrt{3}}{2} R, \frac{R}{2} \right) \\ C_2 &\equiv \left( -\frac{\sqrt{3}}{2} R, \frac{R}{2} \right) \\ C_3 &\equiv (0, -R) \end{aligned} \quad \text{--- (4)}$$

We model the scalar conservative equation

$$\frac{\partial U}{\partial t} + A \frac{\partial U}{\partial x} + B \frac{\partial U}{\partial y} = 0 \quad \text{--- (5)}$$

Written in finite volume discrete form, the equation becomes

$$\frac{dU}{dt} + Q(U) - D(U) = 0 \quad \text{--- (6)}$$

here  $Q(U)$  is the FV integral of convective fluxes and  $D(U)$  is the FV integral of Artificial dissipation fluxes.

$$Q(U) \equiv \frac{1}{h} \sum_{k=1}^3 (\vec{V} \cdot \vec{S}_k) U_{ek} \quad \text{--- (7)}$$

$$h \equiv \text{area of base triangle} \equiv \frac{3\sqrt{3}}{4} R^2$$

$\vec{V} = A\hat{i} + B\hat{j}$  where  $A, B$  are convective velocities along  $x, y$  axis.  
 $\vec{S}_k$  = area vector associated with  $k^{\text{th}}$  edge of base triangle.

Now,  $|\vec{S}_k| = a$  because each triangle is equilateral triangle.

$\therefore \vec{S}_1 = a \frac{\vec{C}_1}{|\vec{C}_1|}$ ; This is because <sup>line</sup> ~~edge~~ joining centers of two neighboring triangles is ~~a~~ perpendicular to the common edge for equilateral triangles.

$$\therefore \vec{S}_k = a \frac{\vec{C}_k}{|\vec{C}_k|}$$

but  $|\vec{C}_k| = R$  and  $a = \sqrt{3} R$ , thus

$$\vec{S}_k = \sqrt{3} \vec{C}_k \quad \text{--- (8)}$$

$U_{ek}$  is the value of scalar at the mid point of the  $k^{\text{th}}$  edge.

$$\therefore U_{e1} = \frac{U_0 + U_1}{2}$$

$$\text{or general form: } U_{ek} = \frac{1}{2} (U_0 + U_k) \quad \text{--- (9)}$$

Artificial dissipation term is composed of 2<sup>nd</sup> and 4<sup>th</sup> order term; for the time being we will concentrate only on 2<sup>nd</sup> order term.

$$\therefore D_2(u) \equiv \frac{\epsilon_2}{h} \sum_{k=1}^3 (|\vec{v} \cdot \vec{S}_k|) (U_k - U_0) \quad \text{--- (10)}$$

Fourier decomposition of the scalar quantity:

$$U_0 \equiv \hat{U} e^{i(\vec{k} \cdot \vec{r}_0 - \omega t)} \quad \text{--- (11)}$$

here,  $\vec{k} \equiv k_x \hat{i} + k_y \hat{j}$  is the wave number vector

$\vec{r}_0$  = position vector of base triangle's center

$\omega$  = pulsation

$\hat{U}$  = Fourier coefficient

Similarly :

$$\begin{aligned} U_1 &= \hat{U} e^{i(\vec{k} \cdot (\vec{C}_0 + \vec{C}_1) - \omega t)} \\ &= U_0 e^{i\vec{k} \cdot \vec{C}_1} \end{aligned}$$

$$\therefore \text{Generally } U_k = U_0 e^{i\vec{k} \cdot \vec{C}_k} \quad \text{--- (12)}$$

Note that in our placement of co-ordinates axis,  $\vec{C}_0$  is origin.

Using (9) and (12) we can write edge mid point quantities as

$$\begin{aligned} U_{ek} &= \frac{1}{2} (U_0 + U_0 e^{i\vec{k} \cdot \vec{C}_k}) \\ &= \frac{U_0}{2} (1 + e^{i\vec{k} \cdot \vec{C}_k}) \quad \text{--- (13)} \end{aligned}$$

Similarly,

$$U_k - U_0 \equiv U_0 e^{i\vec{k} \cdot \vec{C}_k} - U_0 = U_0 (e^{i\vec{k} \cdot \vec{C}_k} - 1) \quad \text{--- (14)}$$

Expanding  $Q(U)$ ; From (7)

$$\begin{aligned} Q(U) &= \frac{1}{h} \left[ (\vec{V} \cdot \vec{S}_1) U_{e1} + (\vec{V} \cdot \vec{S}_2) U_{e2} + (\vec{V} \cdot \vec{S}_3) U_{e3} \right] \\ &= \frac{U_0}{2h} \left[ (\vec{V} \cdot \vec{S}_1) (1 + e^{i\vec{k} \cdot \vec{C}_1}) + (\vec{V} \cdot \vec{S}_2) (1 + e^{i\vec{k} \cdot \vec{C}_2}) + (\vec{V} \cdot \vec{S}_3) (1 + e^{i\vec{k} \cdot \vec{C}_3}) \right] \\ &= \frac{U_0}{2h} \left[ \vec{V} \cdot (\vec{S}_1 + \vec{S}_2 + \vec{S}_3) + \sum_{k=1}^3 (\vec{V} \cdot \vec{S}_k) e^{i\vec{k} \cdot \vec{C}_k} \right] \\ &= \frac{U_0}{2h} \left[ \sum_{k=1}^3 (\vec{V} \cdot \vec{S}_k) e^{i\vec{k} \cdot \vec{C}_k} \right] \quad \text{--- (15)} \end{aligned}$$

Note that  $\vec{k}$  should not be confused with the summation index  $k$  in the above expression.

In a similar manner, we can expand  $D_2(u)$  using (10)

$$\begin{aligned}
 D_2(u) &= \frac{\epsilon_L}{h} \left[ \sum_{k=1}^3 |\vec{V} \cdot \vec{S}_k| (u_k - u_0) \right] \\
 &= \frac{\epsilon_L}{h} \left[ \sum_{k=1}^3 |\vec{V} \cdot \vec{S}_k| u_0 (e^{i\vec{k} \cdot \vec{C}_k} - 1) \right] \\
 &= \frac{u_0 \epsilon_L}{h} \left[ \sum_{k=1}^3 |\vec{V} \cdot \vec{S}_k| e^{i\vec{k} \cdot \vec{C}_k} - \sum_{k=1}^3 |\vec{V} \cdot \vec{S}_k| \right] \quad (16)
 \end{aligned}$$

Using (8), (9), (13) in (15) and applying assumption  $A=B$  with

$$Q_x = k_x R; \quad Q_y = k_y R \quad \text{and} \quad \sigma = \frac{A \Delta t}{R} = \frac{B \Delta t}{R} \quad (17)$$

we get

$$\begin{aligned}
 Q(u) &= \frac{2u_0 \sigma}{3 \Delta t} \left[ \left( -\sqrt{3} \sin\left(\frac{Q_y}{2}\right) \sin\left(\frac{\sqrt{3}Q_x}{2}\right) + \cos\left(\frac{Q_y}{2}\right) \cos\left(\frac{\sqrt{3}Q_x}{2}\right) - \cos Q_y \right) \right. \\
 &\quad \left. + i \left( \sin\left(\frac{Q_y}{2}\right) \cos\left(\frac{\sqrt{3}Q_x}{2}\right) + \sin Q_y + \sqrt{3} \sin\left(\frac{\sqrt{3}Q_x}{2}\right) \cos\left(\frac{Q_y}{2}\right) \right) \right] \quad (18)
 \end{aligned}$$

And using (8), 9, 13 in 16 we get

$$\begin{aligned}
 D_2(u) &= \epsilon_L \frac{4u_0 \sigma}{3 \Delta t} \left[ \left( -\sin\left(\frac{Q_y}{2}\right) \sin\left(\frac{\sqrt{3}Q_x}{2}\right) + \sqrt{3} \cos\left(\frac{Q_y}{2}\right) \cos\left(\frac{\sqrt{3}Q_x}{2}\right) + \cos Q_y - \sqrt{3} - 1 \right) \right. \\
 &\quad \left. + i \left( \sqrt{3} \sin\left(\frac{Q_y}{2}\right) \cos\left(\frac{\sqrt{3}Q_x}{2}\right) - \sin Q_y + \sin\left(\frac{\sqrt{3}Q_x}{2}\right) \cos\left(\frac{Q_y}{2}\right) \right) \right] \quad (19)
 \end{aligned}$$

From Recalling (6)

Replacing (18) in (19) in (6) we get

$$\frac{du}{dt} + Q(u) - D(u) = 0$$

From (18) we write  $Q(u) = \frac{2u_0 \sigma}{3 \Delta t} \tilde{Q}(u)$  where  $\tilde{Q}(u)$  is part of eq (18) in square bracket



similarly from 19,

$$D_2(u) = \frac{4U_0\sigma\epsilon_2}{3\Delta t} \tilde{D}_2(u) \text{ where } \tilde{D}_2(u) \text{ is again part of eq 19 in square brackets.}$$

Replacing in (6), we get

$$\frac{du}{dt} + \frac{2U_0\sigma}{3\Delta t} \tilde{Q}(u) - \frac{\epsilon_2 4U_0\sigma}{3\Delta t} \tilde{D}_2(u) = 0$$

$$\text{or } \frac{du}{dt} + \frac{\sigma}{\Delta t} \left( \frac{2}{3} \tilde{Q}(u) - \frac{4\epsilon_2}{3} \tilde{D}_2(u) \right) u_0 = 0 \quad - (20)$$

Comparing eq (20) with model eq

$$\frac{dU_0}{dt} + \alpha U_0 = 0$$

$$\text{we get } \alpha = \frac{\sigma}{3\Delta t} \left( 2\tilde{Q}(u) - 4\epsilon_2 \tilde{D}_2(u) \right) \quad - (21)$$

For RK3 step defined in Jamson (1981) we have

$$G = \frac{|U_0^{n+1}|}{|U_0^n|} = 1 - (\alpha\Delta t) + \frac{(\alpha\Delta t)^2}{2} - \frac{(\alpha\Delta t)^3}{4} \quad - (22)$$

where  $\alpha$  is given by eq (21).

Thus  $G$  is a function of  $G = G(\sigma, \epsilon_2, \Delta x, \Delta y)$