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1) Genetic Algorithm

- It has a population where each individual represents a possible solution of a given problem.
- It is based on Darwin's evolution ideas where each individual is considered as a chromosome and each bit as a character & random mutations or crossovers are done to find the best fit solution.

Applications: complex optimization problems like travelling salesman, neural network etc.

2) PSO

- This algorithm is based on cooperative behaviour of animals like birds, ants or fish, by imitating their collective behaviour.
- It consists of particles representing a solution to a problem. These explore the solution space by adjusting based on experience & success of others.

Applications: Neural network training, distribution networks.

3) Ant Colony Optimization.

- It is based on ability of ants to find the shortest path between food source & nest & adapting to changes in environment.
- The three main ideas used are preference for paths with high pheromone level, higher rate of growth of amount of pheromone on shorter path, trail mediated solution among ants.
- All ants construct a solution & their pheromone trails are updated based on the quality of solutions found.

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LAB-1

Genetic Algorithm for Optimization Problems

Pseudo Code:

→ Set the parameters:

population-size = 100

mutation rate = 0.1

max value = 10 min value = -10

→ fitness function() $f(x) = x^2$

→ Initialize population()

`np.random.uniform(min, max, range)`

→ select parents (population)

fitness values = fitness(f, population)

selected indices =

`np.random.choice(n, size=2, p=prob)`

→ crossover(p1, p2)

if `np.rand()` < crossover_rate:

$(p1 + p2) / 2$

else p1

→ mutate(child, max, min)

if `np.rand()` < mutation_rate

`np.random.uniform(max, min)`

else child

→ genetic_algorithm()

initialize_population(size, max, min)

for i in range(size)

p1, p2 = select_parents(population)

child = crossover(p1, p2)

child = mutate(child, max, min)

new_population.append(child)

best_solution = population[np.argmax(fitness(population))]

return best_solution, fitness(best_solution)

Best x : -9.9130010

Maximum $f(x)$: 98.2735)

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Particle Swarm Optimization for function Optimization

Algorithm:

1) Initialize Parameters

 $P \rightarrow$ no of particles $C_1 \rightarrow$ cognitive coeff $D \rightarrow$ no of Dimensions $C_2 \rightarrow$ social coeff $T \rightarrow$ no of iterations $w \rightarrow$ inertia weight

2) Initialise Particles

 \rightarrow For each particle randomly initialize: $\hookrightarrow x_i$ - particle's position, v_i - velocity $\hookrightarrow p_{best}$ - best position & evaluate fitness.

3) Determine Global best

~~Set~~ $g_{best} \rightarrow$ particle with best fitnessSet g_{best} to the position of the particle with lowest fitness

4) In loop, from 1 to T:

 \rightarrow Update velocity: Generate r_1, r_2

$$C = C_1 * r_1 * (p_{best} - x_i)$$

$$S = C_2 * r_2 * (g_{best} - x_i)$$

$$v_i = w * v_i + C + S$$

 \rightarrow update position: $x_i = x_i + v_i$ \rightarrow calculate fitness of new position x_i \rightarrow update p_{best} if new fitness is greater &
 \hookrightarrow & also g_{best} 5) Print Solution: After all iterations print g_{best} & optimal fitness

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Ant Colony Optimization for Travelling Salesman Problem

Algorithm:

- 1) Represent the cities as nodes in a graph and construct a distance matrix
- 2) Initialize parameters:
 - $m \rightarrow$ no of ants
 - $\alpha \rightarrow$ importance of pheromone
 - $\beta \rightarrow$ heuristic information
 - $P \rightarrow$ pheromone evaporation rate
 - $Q \rightarrow$ " deposit constant
- 3) For each ant:
 - \rightarrow Randomly select start city
 - \rightarrow Build a complete tour by iteratively selecting next city
 - \hookrightarrow For each unvisited city j calculate probability of moving from i to j
 - \hookrightarrow Use the probability to select next city
 - \rightarrow Add selected city to tour & mark as visited.
- 4) Calculate total length of each tour & keep track of best tour found so far.
- 5) Update pheromones:
 - pheromones $\ast = (1 - P)$
 - pheromone-increase = $Q / \text{tour-length}$
- 6) Return the shortest tour & its length as the best solution

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Cuckoo Search

Algorithm:

- 1) Define the objective function $f(x)$ to optimize
& bounds of search space x_{min}, x_{max} .
$$f(x) = x^2$$
- 2) Initialize parameters:
 $n \rightarrow$ no of nests $P_a \rightarrow$ discovery probability
max no of iterations
- 3) Generate an initial population of nests with random positions within search space.
- 4) Evaluate fitness of each nest using the objective function.
- 5) Generate new solutions:
 \rightarrow For each nest, generate new solⁿ
$$x_{new} = x_{cur} + \text{step size} \times \text{Levy flight}$$

 \rightarrow levy flight is a random walk with step sizes from a Levy distribution.
- 6) Abandon worst nests:
 \rightarrow Using probability P_a , abandon a fraction of worst nests & replace with new ones.
- 7) Repeat steps 4-6 for specified no of iterations
- 8) Return the nest with best fitness & corresponding position

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Grey Wolf Optimizer

Algorithm:

- 1) Define the objective function $f(x)$ & specify bounds of search space x_{min} , x_{max}
- 2) Initialize parameters:
 $n \rightarrow$ no of wolves in a pack
max iterations
- 3) Generate initial population of wolves with random positions
- 4) Evaluate fitness:
 \rightarrow calculate fitness of each wolf using objective function
 \rightarrow identify three best wolves: α , β , δ

5) For each wolf:

$$\vec{D}_\alpha = |\vec{C}_1 \cdot \vec{X}_\alpha - \vec{X}|$$

$$\vec{X}_1 = \vec{X}_\alpha - \vec{A}_1 \cdot \vec{D}_\alpha$$

Similarly for β & δ

$$\vec{X}(t+1) = \frac{\vec{X}_1 + \vec{X}_2 + \vec{X}_3}{3}$$

\vec{A} & \vec{C} are coefficient vectors

- 6) Return the position of α wolf & its fitness

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Parallel Cellular Algorithms & Programs

Algorithm:

- 1) Objective function : $f(x) = \sum x_i^2$
- 2) Initialize parameters:
no of cells, grid size, dimensions, bounds
no of iterations
 $np.random.uniform(bounds[0], bounds[1])$
- 3) Initialize population with initial positions of all cells
- 4) Evaluate Fitness for each cell & put it into a 1D array
- 5) Identify the neighbours using Moore neighbourhood structure
- 6) Update each cell's state by copying the position of its best neighbour
- 7) Main Algorithm:
Print the best solution & its fitness.

5) for dx in $[-1, 0, 1]$:
for dy in $[-1, 0, 1]$:
if $dx == 0$ and $dy == 0$:
continue.
 $nx, ny = (x + dx) \% \text{grid_size}$
 $\text{neighbours.append}(nx * \text{grid_size} + ny)$

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Optimization via Gene Expression Algorithm

Algorithm :

- 1) Define the objective function $f(x) = \sum x_i^2$
- 2) Initialize parameters:
no of genes, bounds, mutation rate
crossover rate, no of generations
- 3) Generate a population P with G genes each
 $x_i^j \rightarrow j^{\text{th}}$ gene of i^{th} individual
- 4) Evaluate fitness using the objective function $f(x)$
- 5) Filter the population with lower fitness values
- 6) Choose two parents at a time & perform crossover
- 7) Introduce variability in offspring by randomly altering genes.
- 8) Combine the offsprings to the new population
- 9) Output the genetic sequence with two best fitness