

Theorem: We fix δ and we give a lower bound for the probability that a random matrix is δ -approximately scaled by the scaling factors (x,y) of $E[\tilde{A}]$. $P(\delta, M, N) = \text{Probability that } \tilde{A} \text{ is } \delta\text{-app. sc. by } x,y$

* Let's restrict ourselves to the case of doubly stochastic scaling of square matrices

Hoeffding (Boundedness):

$$P(\mathcal{A}) = P(\delta, M) \geq 1 - 4M \exp\left(-\frac{\delta^2 M^2}{M \cdot c_p^2}\right)$$

depends only on the bounds $[a,b]$

independent of M

Let $\mathcal{A} = \{\tilde{A} - \delta\text{-approx. scaled}\}$

For any $\tilde{A} \in \mathcal{A}$ \rightsquigarrow deterministic procedure

\tilde{x}, \tilde{y} : Exact scaling factors that don't deviate too much from x,y pointwise.

$$\text{Bound: } \left| \frac{\tilde{x}_i - x_i}{x_i} \right| \leq c_e \cdot \delta$$

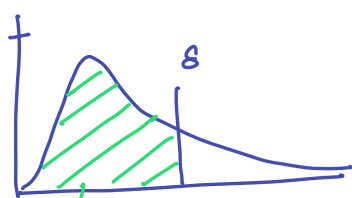
Independent of N \leftarrow depends only on ele. bounds $[a,b]$

Question 1: Is $c_e \cdot \delta$ the best bound you can get?

$$\text{Let } \mathcal{B} = \left\{ \left| \frac{\tilde{x}_i - x_i}{x_i} \right| \leq c_e \cdot \delta \text{ and } \left| \frac{\tilde{y}_j - y_j}{y_j} \right| \leq c_e \cdot \delta \quad \forall i,j \text{ for some } x,y \right\}$$

$$\mathcal{B} \supseteq \mathcal{A} \Rightarrow P(\mathcal{B}) > P(\mathcal{A})$$

To estimate the bound \rightsquigarrow Fix a $\delta \rightsquigarrow$ Estimator for $P(\mathcal{A})$ from this estimate $\rightarrow p$ (say)



Or compute from this cutoff: normalised

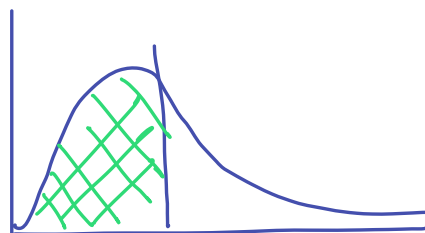
To study dependence on δ

$$\text{Area of } \mathcal{A} = P(\delta, M) = P(\mathcal{A})$$

$$\mathcal{A} \subseteq \mathcal{B}$$

$$\text{Area of } \mathcal{B} = P(\mathcal{B})$$

Loose upper Bound



$$E(\tilde{x}, \tilde{y})$$

normalise

Discrepancy relate to
checks how effective
going from approximate scaling
to actual scaling is.

→ This is different from what
we want though
Estimating exact upper bound
How much bigger is $IP(B)$
than $IP(A)$

↙
* This is what we want in
practice?

Question 2: Dependence on N : upper bound.

Empirically: change N

Fix $S \rightsquigarrow$ Change N and compute
the maximum.

But probability
also changes: Print that
out.

→ Weak upper bound. $B(N)$

For fixed probability: we can find S_N using quantiles

Find Bounds: $B(S_N, N)$

§ Question 3: Dependence on α

Keep N fixed \rightsquigarrow plot the quantiles and see how approximate
scaling changes

Bound for so% of them

look at approximately scaled and then estimate the bound from
that \rightarrow would give a very weak upper bound

- Dealing with A instead of $B \rightarrow$ even though S
is fixed prob is increasing
- $\|x\| = \|y\| \rightarrow$ used to guess
the bound

§ THEORETICAL DEPENDENCE OF S ON N FOR FIXED PROBABILITY

Empirically: For a fixed probability of p

We would need $4N \exp(-k S^2 N) = O(1)$

$$S^2 N = O(\log N) \rightsquigarrow S = O\left(\sqrt{\frac{\log N}{N}}\right)$$

↗ which also
matches rate
of convergence

Empirically: For both chi-squared
and uniform: seems to
resemble $O\left(\sqrt{\frac{\log N}{N}}\right)$

we get for
scaling factors
WHP \Rightarrow connection
*

which is better $O\left(\sqrt{\frac{\log N}{N}}\right)$

* In practice: \hookrightarrow How do you compare? Curve fitting?

§ ASYMPTOTICS FROM LINDA'S PAPER: Doubly Stochastic case

$$\varepsilon(\tilde{x}, \tilde{y}) = \max \left\{ \max_{i \in [N]} \frac{|\tilde{x}_i - \tilde{x}_i^*|}{x_i}, \max_{i \in [N]} \frac{|\tilde{y}_i - \tilde{y}_i^*|}{y_i} \right\}$$

Claim: Boundedness, + by: assumptions carry forward.

\exists scaling factors $\{\tilde{x}^{(n)}, \tilde{y}^{(n)}\}_{n \in \mathbb{N}}$ s.t.

$$\varepsilon(\tilde{x}^{(n)}, \tilde{y}^{(n)}) = O_{\text{whp}} \left(\sqrt{\frac{\log N}{N}} \right)$$

\hookrightarrow doubly stochastic
case.

Question: How does dependence on N feature in this proof?

\hookrightarrow Not through the approximate scaling bound's dependence on N

It is through choosing δ_n increasingly small enough to shrink the
bound but while also ensuring the probability tends to 1.

Hence, $\sqrt{\frac{\log N}{N}}$ matches * \sim can this be improved or is it
tight?

§ PRACTICE?

- To get scaling factors close to the ones we have.
- Deterministic if we know if they are approximately scaled at the
a suitable δ -level