CSCI 567 Homework 5

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Problem 1. HMM

• Question 1.1 Following the procedure described in slide 35 lecture 18:

something₁ =
$$p(x_1) = 0.7 \times 0.4 + 0.3 \times 0.2 = 0.34$$
 (1)

$$\alpha_1(1) = \frac{0.4 \times 0.7}{somethinq_1} = 0.82$$
 (2)

$$\alpha_1(2) = \frac{0.3 \times 0.2}{somethinq_1} = 0.18$$
 (3)

$$something_2 = \sum_{i} P(x_2|z_2 = s_j) \sum_{i} a_{ij} \alpha_1(i)$$
(4)

$$something_2 = 0.4 \times (0.8 \times 0.82 + 0.4 \times 0.18) + 0.2 \times (0.2 \times 0.82 + 0.6 \times 0.18) = 0.35$$
 (5)

$$\alpha_2(1) = \frac{0.4 \times (0.8 \times 0.82 + 0.4 \times 0.18)}{something_2} = 0.83$$
 (6)

$$\alpha_2(2) = \frac{0.2 \times (0.2 \times 0.82 + 0.6 \times 0.18)}{something_2} = 0.15$$
 (7)

$$something_3 = \sum_{i} P(x_3|z_3 = s_j) \sum_{i} a_{ij} \alpha_2(i)$$
(8)

$$something_3 = 0.1 \times (0.8 \times 0.83 + 0.4 \times 0.15) + 0.3 \times (0.2 \times 0.83 + 0.6 \times 0.15) = 0.15$$
 (9)

$$\alpha_3(1) = \frac{0.1 \times (0.8 \times 0.83 + 0.4 \times 0.15)}{something_3} = 0.48 \tag{10}$$

$$\alpha_3(2) = \frac{0.3 \times (0.2 \times 0.83 + 0.6 \times 0.15)}{something_3} = 0.51$$
 (11)

similarly:

$$something_4 = \sum_{j} P(x_4|z_4 = s_j) \sum_{i} a_{ij} \alpha_3(i)$$
(12)

$$something_4 = 0.4 \times (0.8 \times 0.48 + 0.4 \times 0.51) + 0.2 \times (0.2 \times 0.48 + 0.6 \times 0.51) = 0.32$$
 (13)

$$\alpha_4(1) = 0.74, \alpha_4(2) = 0.25$$
 (14)

$$something_5 = \sum_{i} P(x_5|z_5 = s_j) \sum_{i} a_{ij} \alpha_4(i)$$
(15)

$$something_5 = 0.1 \times (0.8 \times 0.74 + 0.4 \times 0.25) + 0.3 \times (0.2 \times 0.74 + 0.6 \times 0.25) = 0.16$$
 (16)

$$\alpha_5(1) = 0.44, \alpha_5(2) = 0.56 \tag{17}$$

$$something_6 = \sum_{i} P(x_6|z_6 = s_j) \sum_{i} a_{ij} \alpha_5(i)$$
(18)

$$something_6 = 0.4 \times (0.8 \times 0.44 + 0.4 \times 0.56) + 0.2 \times (0.2 \times 0.44 + 0.6 \times 0.56) = 0.31$$
 (19)

$$\alpha_6(1) = 0.73, \alpha_6(2) = 0.27 \tag{20}$$

Thus

$$P(X_{1:6}) = something_1 \times ... \times something_6 = 0.34 \times 0.35 \times ... \times 0.31 = 0.000283 \ \ (21)$$

• Question 1.2 using Viterbi Algorithm:

$$\delta_0(1) = \delta_0(2) = 1$$

$$\delta_1(1) = \delta_0(1) \times \pi_1 \times b_{1A} = 0.28 \tag{22}$$

$$\delta_1(2) = \delta_0(2) \times \pi_2 \times b_{2A} = 0.06 \tag{23}$$

$$\Psi_1(1) = \Psi_1(2) = *S* \tag{24}$$

$$\delta_2(1) = Max\delta_1(i)a_{i1}P(x_2|z_2 = s_1) = max(0.28 \times 0.8 \times 0.4, 0.06 \times 0.4 \times 0.4) = 0.09 (25)$$

$$\psi_2(1) = 1 \tag{26}$$

$$\delta_2(2) = Max \delta_1(i) a_{i2} P(x_2 | z_2 = s_2) = max(0.28 \times 0.2 \times 0.2, 0.06 \times 0.6 \times 0.2) = 0.0112$$
(27)

$$\psi_2(2) = 1 \tag{28}$$

similarly we get:

$$\delta_3(1) = Max\delta_2(i)a_{i1}P(x_3|z_3 = s_1) = 0.09 \times 0.8 \times 0.1 = 0.0072$$
(29)

$$\psi_3(1) = 1 \tag{30}$$

$$\delta_3(2) = Max\delta_2(i)a_{i2}P(x_3|z_3 = s_2) = 0.09 \times 0.2 \times 0.3 = 0.0054$$
(31)

$$\psi_3(2) = 1 \tag{32}$$

$$\delta_4(1) = 0.0072 \times 0.8 \times 0.4 = 0.0023 \tag{33}$$

$$\psi_4(1) = 1 \tag{34}$$

$$\delta_4(2) = 0.0054 \times 0.6 \times 0.2 = 0.00065 \tag{35}$$

$$\psi_4(2) = 2 \tag{36}$$

$$\delta_5(1) = 0.0023 \times 0.8 \times 0.1 = 0.000184 \tag{37}$$

$$\psi_5(1) = 1 \tag{38}$$

$$\delta_5(2) = 0.0023 \times 0.2 \times 0.3 = 0.000138 \tag{39}$$

$$\psi_5(2) = 1 \tag{40}$$

$$\delta_6(1) = 0.000184 \times 0.8 \times 0.4 = 0.000059 \tag{41}$$

$$\psi_6(1) = 1 \tag{42}$$

$$\delta_6(2) = 0.000138 \times 0.6 \times 0.2 = 0.0000165 \tag{43}$$

$$\psi_6(2) = 2 \tag{44}$$

By backtracking we get the following the likely state path as:

$$z^* = \{1111111\}$$