

## 1. Network structure

The network has  $n$  layers. Layer 1 is the input layer, and layer  $n$  is the output layer. Each layer  $i$  has  $m_i$  nodes.

Each node (except in the first layer) has an input  $z_{ij}$ . Here  $i$  indicates the layer number and  $j$  indicates the node number within the layer. Each node has an output  $y_{ij}$ .

## 2. Forward pass calculations

The outputs in the first layer are set to an input pattern,  $y_{1i} = I_i$ .

The inputs of the remaining nodes are calculated as  $z_{ij} = \sum_k W_{jk}^{i-1} y_{(i-1)k}$ . Here  $W^p$  is the matrix of weights that connects layer  $p$  to layer  $p + 1$ .

The outputs of the remaining nodes are calculated as  $y_{ij} = f(z_{ij})$ .  $f$  is called the activation function.

## 3. Backward pass calculations

The error of the network's response to an input pattern is  $E = 0.5 \sum_i (y_{ni} - O_i)^2$ . Here  $O_i$  is the targetted output pattern.

As a first step towards calculating the gradient of the error with respect to the weights, we calculate the delta terms, defined as  $\delta_{ij} = \partial E / \partial z_{ij}$ .

The deltas at the output layer  $n$  are given by

$$\delta_{ni} = \frac{\partial E}{\partial z_{ni}} = \frac{\partial E}{\partial y_{ni}} \frac{\partial y_{ni}}{\partial z_{ni}} = (y_{ni} - O_i) f'(z_{ni})$$

The deltas at earlier layers  $1 < k < n$  are given by

$$\begin{aligned} \delta_{ki} &= \frac{\partial E}{\partial z_{ki}} = \sum_j \frac{\partial E}{\partial z_{(k+1)j}} \frac{\partial z_{(k+1)j}}{\partial y_{ki}} \frac{\partial y_{ki}}{\partial z_{ki}} = \sum_j \delta_{(k+1)j} W_{ji}^k f'(z_{ki}) \\ &= f'(z_{ki}) \sum_j \delta_{(k+1)j} W_{ji}^k \end{aligned}$$

That is,  $\delta_{ki}$  is calculated as a weighted sum of the  $\delta_{(k+1)j}$ 's, using the same weights as in the forward pass.

Finally, we can use the deltas to find the error gradient with respect to the weights.

$$\frac{\partial E}{\partial W_{ij}^k} = \frac{\partial E}{\partial z_{(k+1)i}} \frac{\partial z_{(k+1)i}}{\partial W_{ij}^k} = \delta_{(k+1)i} y_{kj}$$