

Recall : Geostrophic Balance.

Horizontal momentum equation (Boussinesq approx)

$$\frac{\partial \underline{u}}{\partial t} + \underline{u} \cdot \nabla \underline{u} + \underline{f} \times \underline{u} = - \frac{1}{\rho} \nabla_{\perp} \tilde{p}$$

$\underline{f} \hat{z}$
 $f = 2\Omega \sin \phi$

ρ
 reference density (ρ_0)

\tilde{p}
 pressure anomaly (\tilde{p})

$$\underline{u} = (u, v) \quad \nabla_{\perp} = (\partial_x, \partial_y)$$

$$\underbrace{\frac{\partial \underline{u}}{\partial t} + \underline{u} \cdot \nabla \underline{u}}_{U^2/L} + \underbrace{\underline{f} \times \underline{u}}_{fU} = - \underbrace{\frac{1}{\rho} \nabla_{\perp} \tilde{p}}_{\frac{P}{\rho L}}$$

$$T_{adv} = L/U$$

$$\text{Ratio of inertial to Coriolis} = \frac{U^2/L}{fU} = \frac{U}{fL} = Ro.$$

For "rapidly rotating" $Ro \rightarrow 0$

$$\Rightarrow \text{Geostrophic balance: } \underline{f} \times \underline{u} = - \frac{1}{\rho} \nabla_{\perp} \tilde{p}.$$

Pressure scale in geostrophic balance?

$$fU \sim \frac{P}{\rho L} \Rightarrow P \sim fU \rho L.$$

E.g. $f \sim 10^{-4} \text{ s}^{-1}$ (typical midlatitude flow)

$U \sim 10^{-1} \text{ m s}^{-1}$ (ocean), $\rho \sim 1000 \text{ kg m}^{-3}$ (seawater)

$L \sim 10^5 \text{ m} \sim 100 \text{ km}$ (ocean eddy)

Rossby number in ocean:

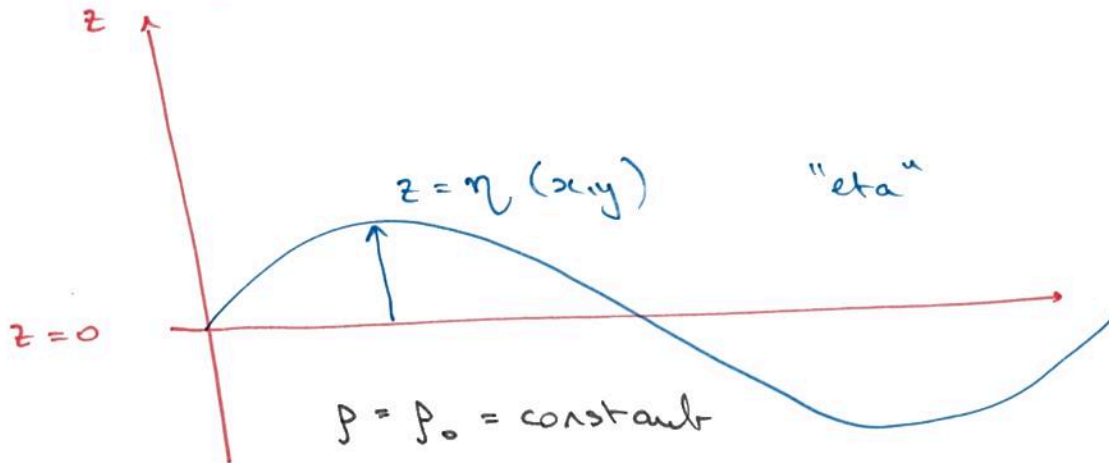
$$Ro \sim \frac{U}{fL} = \frac{10^{-1}}{10^{-4} 10^5} \sim 0.01 \ll 1.$$

Pressure scale:

$$P \sim f U \rho L = 10^{-4} \times 10^{-1} \times 10^3 \times 10^5 \sim 10^3.$$

$$\sim 1000 \text{ Pa.}$$

Example: geostrophic balance in the ocean



Hydrostatic balance:

$$\frac{dp}{dz} = -\rho_0 g \Rightarrow \int_{\phi(z)}^{\phi_0} dp = - \int_z^{\eta(x,y)} \rho_0 g dz$$

$$\phi_0 - \phi(z) = -\rho_0 g (\eta - z)$$

$$\Rightarrow \phi(z) = \underbrace{\phi_0}_{\text{air pressure}} - \underbrace{\rho_0 g z}_{\text{water pressure}} + \underbrace{\rho_0 g \eta(x,y)}_{\text{modification due to } \eta(x,y)}$$

($z < 0$ in the ocean)

Geostrophic balance:

$$\begin{aligned}\underline{f} \times \underline{u} &= \underline{f} \hat{\underline{z}} \times \underline{u} = -\frac{1}{\rho_0} \nabla_{\underline{z}} (\rho_0 - \rho_0 g z + \rho_0 g \eta(x, y)) \\ &= -g \nabla_{\underline{z}} \eta(x, y)\end{aligned}$$

If on an f -plane ($f = f_0$)

$$\Rightarrow \hat{\underline{z}} \times \underline{u} = -\frac{g}{f} \nabla_{\underline{z}} \eta = -\nabla_{\underline{z}} \left(\frac{g\eta}{f} \right).$$

Useful identity: if $\underline{u} \perp \hat{\underline{z}}$ then

$$\hat{\underline{z}} \times (\hat{\underline{z}} \times \underline{u}) = -\underline{u}$$

"uncross"
equations.

Proof: $\underline{u} = u \hat{\underline{x}} + v \hat{\underline{y}}$

$$\hat{\underline{z}} \times \underline{u} = u \hat{\underline{z}} \times \hat{\underline{x}} + v \hat{\underline{z}} \times \hat{\underline{y}} = u \hat{\underline{y}} - v \hat{\underline{x}}$$

$$\hat{\underline{z}} \times (\hat{\underline{z}} \times \underline{u}) = u \hat{\underline{z}} \times \hat{\underline{y}} - v \hat{\underline{z}} \times \hat{\underline{x}} = -u \hat{\underline{x}} - v \hat{\underline{y}} = -\underline{u}$$

Exercise: For $\underline{v} = (u, v, w)$ prove that

$$\hat{\underline{z}} \times (\hat{\underline{z}} \times \underline{v}) = w \hat{\underline{z}} - \underline{v} = -u \hat{\underline{x}} - v \hat{\underline{y}} \quad \leftarrow \text{NB}$$

Applying $\hat{\underline{z}} \times$ to each side:

$$\hat{\underline{z}} \times (\hat{\underline{z}} \times \underline{u}) = -\hat{\underline{z}} \times \nabla_{\underline{z}} \left(\frac{g\eta}{f} \right)$$

$$\begin{aligned}\underline{u} &= \hat{\underline{z}} \times \nabla_{\underline{z}} \psi & \psi &= \frac{g\eta}{f} \\ &= \nabla_{\perp} \psi.\end{aligned}$$

= "geostrophic streamfunction"

$$\nabla_{\perp} = \hat{\underline{z}} \times \nabla_{\underline{z}} = \left(-\frac{\partial}{\partial y}, \frac{\partial}{\partial x} \right)$$

Implications:

* Flow is incompressible in 2D:

$$\nabla_{\perp} \cdot \underline{u} = \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = \frac{\partial}{\partial x} \left(-\frac{\partial \psi}{\partial y} \right) + \frac{\partial}{\partial y} \left(\frac{\partial \psi}{\partial x} \right) = 0$$

* ψ is a streamfunction

\Rightarrow flow is along lines of constant $\psi = \frac{\partial \eta}{\partial t}$

\Rightarrow flow is along lines of constant sea surface height η

* if we know $\eta(x, y)$ we know the flow!

ASIDE: In general can write

$$\underline{u}_{2D} = \nabla \phi + \nabla_{\perp} \psi$$

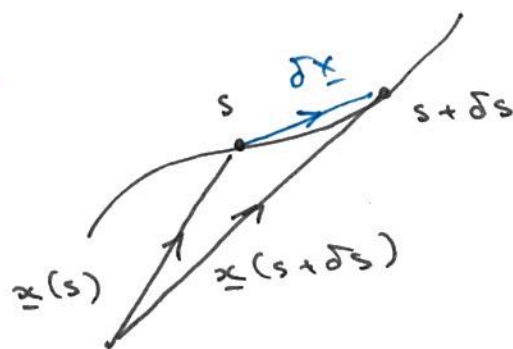
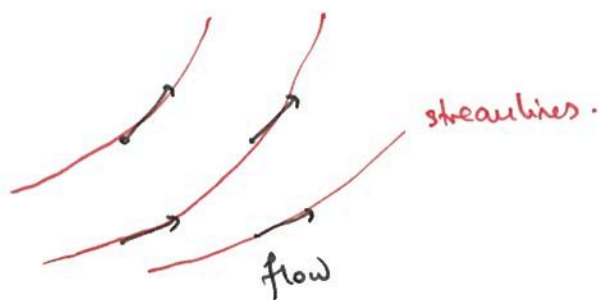
\uparrow
potential
function

\uparrow
streamfunction.

Helmholtz
decomposition.

$$\nabla \cdot \underline{u}_{2D} = \nabla^2 \phi \quad \left(\nabla \cdot \nabla_{\perp} \psi = 0 \right).$$

Streamline: A line tangent to \underline{v} everywhere at fixed t .



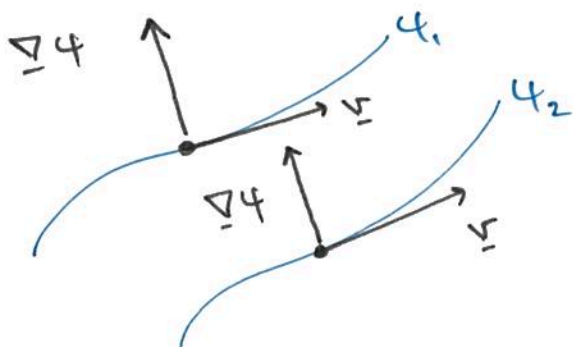
$$\delta \underline{x} \parallel \underline{v} \text{ as } \delta s \rightarrow 0$$

Def: $\frac{d\underline{x}}{ds}$ is tangent to \underline{v} : $\frac{d\underline{x}}{ds} \times \underline{v} = 0$.

$$\Rightarrow \frac{d\underline{v}}{ds} = \lambda \underline{v} \xrightarrow{\text{rescale } s} \frac{d\underline{x}}{ds} = \underline{v}$$

NB: a streamline is not the same thing as a particle trajectory except when flow is stationary.

Streamfunction: function whose level sets are streamlines
[only makes sense for incompressible flow] In 2D:



$$\underline{n} = \underline{\nabla} \psi$$

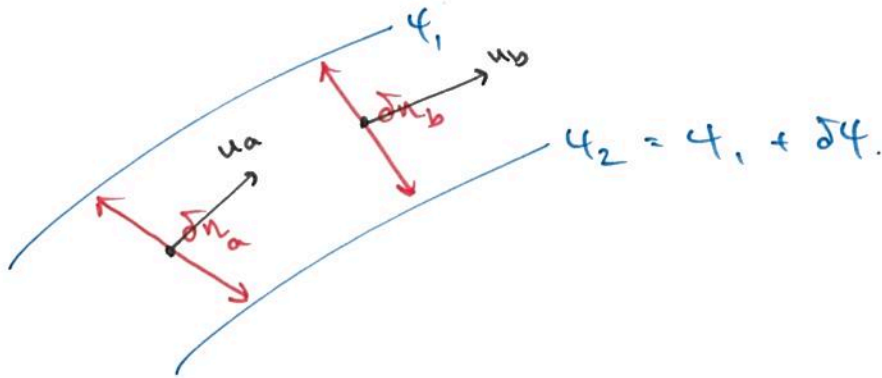
$$\underline{v} = \hat{\underline{z}} \times \underline{\nabla} \psi = \underline{\nabla}_{\perp} \psi \\ = (-\psi_y, \psi_x).$$

$$\text{By construction: } \underline{\nabla} \psi \cdot \underline{\nabla}_{\perp} \psi = \underline{n} \cdot \underline{v} = 0$$

$$\text{Note also: } \underline{\nabla} \cdot \underline{\nabla}_{\perp} \psi = 0$$

Velocity + streamfunction :

Distance between streamlines \rightarrow velocity



$$\underline{u} = \nabla_{\perp} \psi \sim \frac{\delta \psi}{\delta n}$$

$$u_a \sim \frac{\delta \psi_a}{\delta n_a}$$

$$u_b \sim \frac{\delta \psi_b}{\delta n_b}$$

$$\text{but } \delta \psi_a = \delta \psi_b = \delta \psi$$

$$\rightarrow u_a \sim \frac{\delta \psi}{\delta n_a}$$

$$u_b \sim \frac{\delta \psi}{\delta n_b}$$

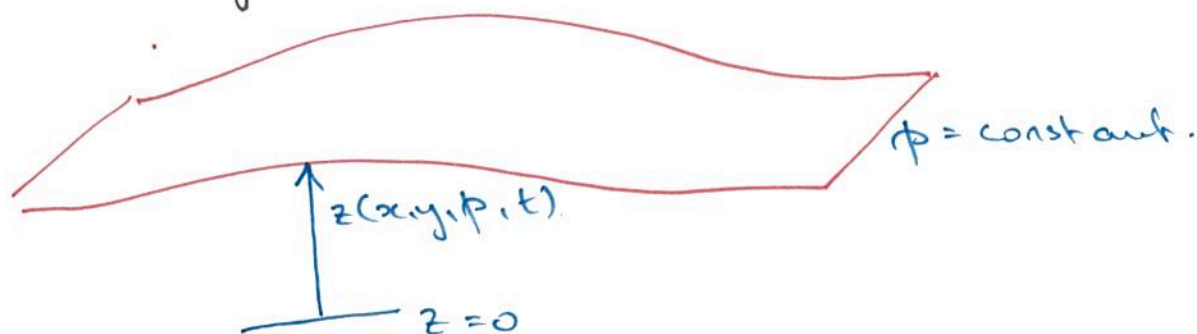
$$\Rightarrow u_a \uparrow \text{ if } \delta n_a \downarrow$$

Example: Geostrophic balance in the atmosphere

Moral: pressure is a more useful "vertical coordinate" for compressible flows (atmosphere)

$$z = z(x, y, p, t)$$

= height of a constant pressure surface



Transforming between "pressure coordinates" and "z-coordinate"

Consider a field $f = f(x, y, z(x, y, p))$

∇_z = horizontal gradient at fixed height z

∇_p = horizontal gradient at fixed pressure p .

$$\nabla_p f = \nabla f \Big|_{p = \text{constant}}$$

$$= \nabla f \Big|_{z = \text{constant}} + \frac{\partial f}{\partial z} \nabla z \Big|_{p = \text{constant}}$$

E.g. $\frac{\partial f}{\partial x} \Big|_p = \frac{\partial f}{\partial x} \Big|_z + \frac{\partial f}{\partial z} \frac{\partial z}{\partial x} \Big|_p$.

Now take $f = \phi$:

$$\left. \nabla \phi \right|_{\phi = \text{constant}} = 0 = \left. \nabla \phi \right|_z + \frac{\partial \phi}{\partial z} \left. \nabla z \right|_{\phi}.$$

$$\boxed{\nabla_z \phi = - \frac{\partial \phi}{\partial z} \nabla_{-\phi} z = \rho g \nabla_{-\phi} z}$$

Geostrophic balance in pressure coordinates:

$$\boxed{f \times \underline{u} = - \frac{1}{\rho} \nabla_z \phi = - g \nabla_{-\phi} z}$$

THERMAL WIND BALANCE

Geostrophic balance	+	Hydrostatic balance	=	Thermal wind balance
horizontal ϕ -grad.		vertical ρ -grad.		vertical shear
+		+		+
Coriolis force		gravity		horizontal density gradients

Boussinesq: Geostrophy

$$\underline{f} \times \underline{u} = - \frac{1}{\rho_0} \nabla_z \phi.$$

$$\frac{\partial}{\partial z} : \underline{f} \times \frac{\partial \underline{u}}{\partial z} = - \frac{1}{\rho_0} \nabla_z \left[\frac{\partial \phi}{\partial z} \right] = - \rho g \quad (\text{HS balance})$$

$$\boxed{\underline{f} \times \frac{\partial \underline{u}}{\partial z} = \frac{g}{\rho_0} \nabla_z \rho} \quad \text{Thermal wind balance}$$

$$\hat{z} \times \frac{\partial \underline{u}}{\partial z} = \frac{g}{f\rho_0} \nabla_z p$$

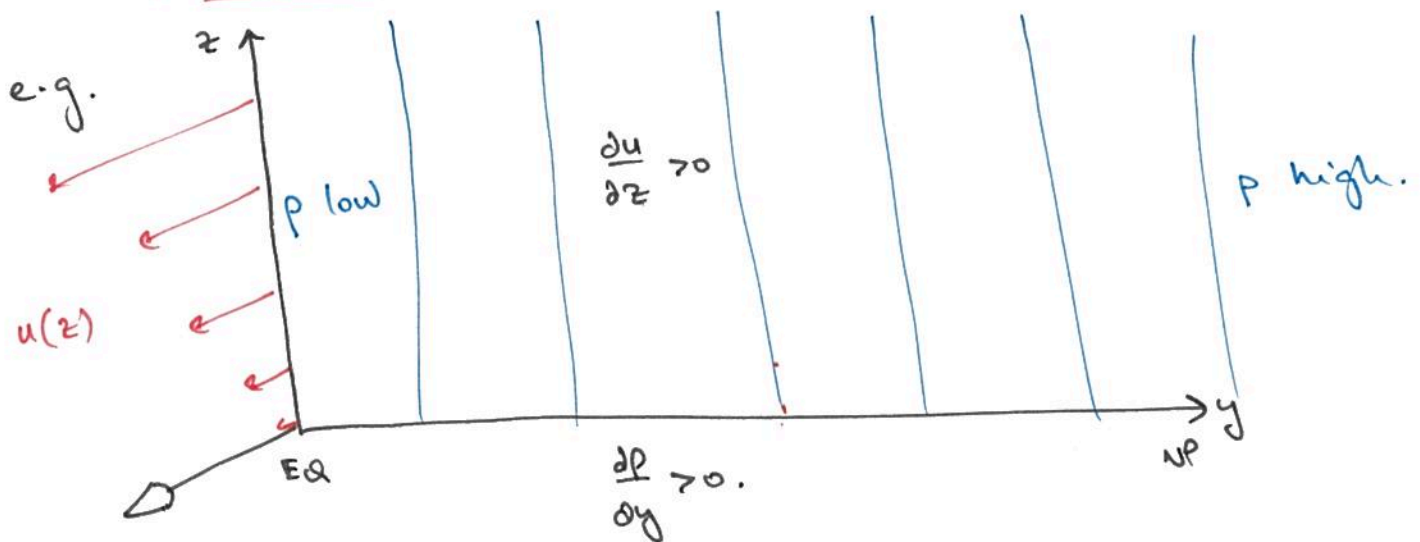
$$\underline{f} = f \hat{z}$$

$$\hat{z} \times (\hat{z} \times \frac{\partial \underline{u}}{\partial z}) = - \frac{\partial \underline{u}}{\partial z}$$

$$\Rightarrow \boxed{\frac{\partial \underline{u}}{\partial z} = - \frac{g}{f\rho_0} \hat{z} \times \nabla_z p.}$$

$$\frac{\partial u}{\partial z} = \frac{g}{f\rho_0} \frac{\partial p}{\partial y}$$

$$\frac{\partial v}{\partial z} = - \frac{g}{f\rho_0} \frac{\partial p}{\partial x}$$



Taylor - Proudman Theorem and Thermal Wind

3D Navier Stokes equation (no approximation):

$$\frac{D\underline{v}}{Dt} + 2\underline{\Omega} \times \underline{v} = -\frac{1}{\rho} \nabla \phi - \nabla \Phi$$

$\frac{D\underline{v}}{Dt}$ \uparrow full 3D velocity (u, v, w)
 $\underline{\Omega}$ \uparrow $\underline{\Omega} = \Omega \hat{e}$
 $\nabla \Phi$ \uparrow Gravitational potential.

Assume:

- * $R_0 \rightarrow 0$ (neglect inertial term)
- * $\nabla \cdot \underline{v} = 0$ (3D incompressible)

$$2\underline{\Omega} \times \underline{v} = -\frac{1}{\rho} \nabla \phi - \nabla \Phi$$

horizontal components \rightarrow Geostrophic balance
 vertical component \rightarrow hydrostatic balance

Curl both sides:

$$\begin{aligned} \nabla \times (2\underline{\Omega} \times \underline{v}) &= -\nabla \times \left(\frac{1}{\rho} \nabla \phi \right) - \cancel{\nabla \times \nabla \Phi} \\ &\stackrel{\text{product rule}}{=} -\nabla \left(\frac{1}{\rho} \right) \times \nabla \phi - \frac{1}{\rho} \cancel{\nabla \times \nabla \phi} \\ &= \frac{1}{\rho^2} \nabla \rho \times \nabla \phi. \end{aligned}$$

Vector identity:

$$\nabla \times (\underline{A} \times \underline{B}) = \underline{A} (\nabla \cdot \underline{B}) - \underline{B} (\nabla \cdot \underline{A}) + \underline{B} \cdot \nabla \underline{A} - \underline{A} \cdot \nabla \underline{B}$$

$$\nabla \times (2\underline{\Omega} \times \underline{v}) = 2\underline{\Omega} (\cancel{\nabla \cdot \underline{v}}) - \underline{v} (\cancel{\nabla \cdot 2\underline{\Omega}}) + \underline{v} \cdot \cancel{\nabla 2\underline{\Omega}} - 2\underline{\Omega} \cdot \cancel{\nabla \underline{v}}$$

incompressible. $\underline{\Omega} = \text{const}$ $\underline{\Omega} = \text{const}$.

$$= -2\underline{\Omega} \cdot \nabla \underline{v}$$

So:

$$-2\underline{\Omega} \cdot \nabla \underline{v} = \frac{1}{\rho^2} \nabla \rho \times \nabla p. \quad (*)$$

Taylor - Proudman theorem.

J. Proudman (1916) & G. I. Taylor (1921) + experimental verification.

Definition: A fluid is called a barotropic fluid if its density is a function of pressure only:

$$\rho = \rho(p).$$

Theorem: For a rapidly rotating, incompressible barotropic fluid, the velocity $\underline{v} = (u, v, w)$ has no variation along the axis of rotation.

Proof: From (*) a rapidly rotating incompressible fluid satisfies

$$-2\underline{\Omega} \cdot \nabla \underline{v} = \frac{1}{\rho^2} \nabla \rho \times \nabla p.$$

For a barotropic fluid $\rho = \rho(p)$

$$\nabla \rho = \frac{d\rho}{dp} \nabla p. \Rightarrow \nabla \rho \times \nabla p = \frac{d\rho}{dp} \nabla p \times \nabla p = \underline{0}$$

From (*) then

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$$-2\underline{\underline{\Omega}} \cdot \underline{\underline{\nabla}} \underline{\underline{v}} = 0.$$

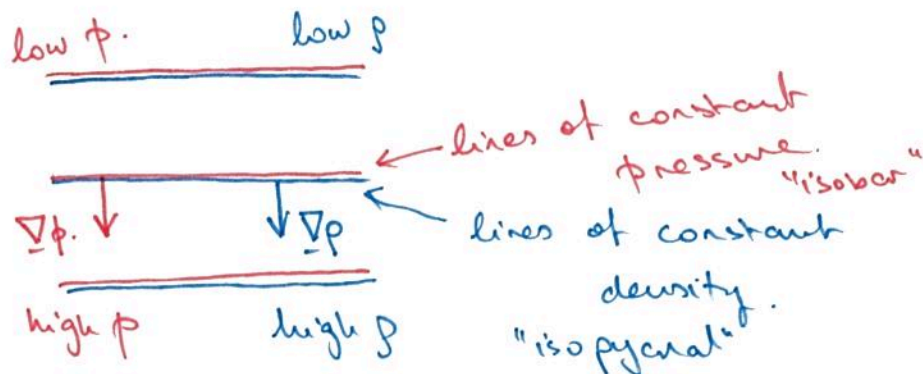
$$\underline{\underline{\Omega}} = \Omega \hat{\underline{\underline{z}}}$$

$$\Rightarrow \frac{\partial \underline{\underline{v}}}{\partial z} = 0 \quad \Rightarrow \quad \frac{\partial u}{\partial z} = \frac{\partial v}{\partial z} = \frac{\partial w}{\partial z} = 0.$$

Therefore u, v, w have no variation in z -direction.

Barotropic
fluid.

$$p = p(\phi)$$



Surfaces of constant p = surfaces of constant ϕ

$$\Rightarrow \underline{\underline{\nabla}} p \parallel \underline{\underline{\nabla}} \phi.$$

Corollary :

If there exists a solid boundary within the fluid then

* $w = 0$ everywhere (flow is effectively 2D)

* flow is confined into cylinders aligned along axis of rotation ("Taylor columns")

Proof: since $\frac{\partial w}{\partial z} = 0$, then if $w = 0$ on a boundary

then $w = 0$ everywhere.

Additionally, since $\frac{\partial u}{\partial z} = \frac{\partial v}{\partial z} = 0$, u and v are

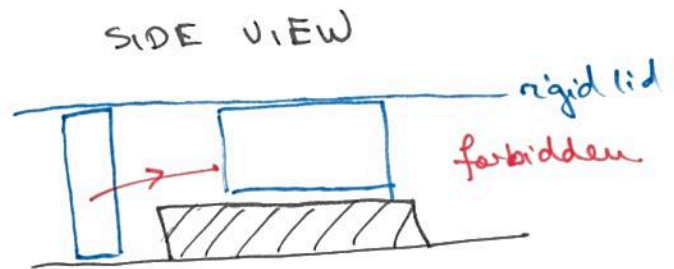
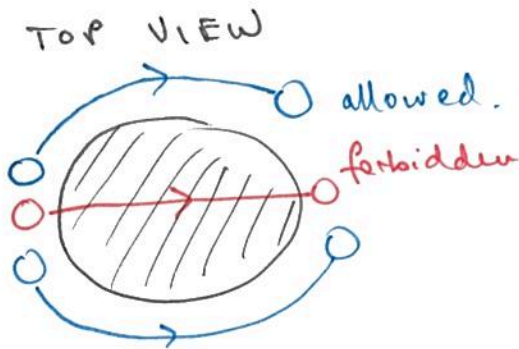
constant in the z -direction. \Rightarrow effectively 2D "barotropic flow"

Physically: rotation makes the fluid "rigid" \rightarrow it resists deformation in the z -direction and instead forms columns that cannot be tilted, squashed, stretched!



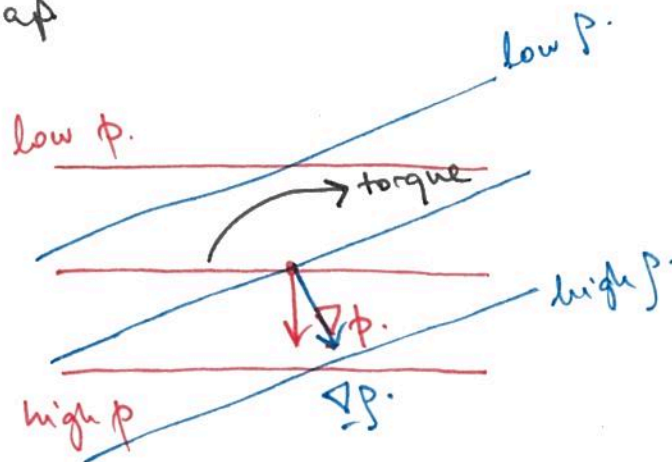
u, v are constant in z
 $w = 0$

Example: flow around a mountain / sea mount



BAROCLINIC FLUID.

when $p \neq p(\phi)$ then surfaces of constant $p \neq \phi$.
do not overlap

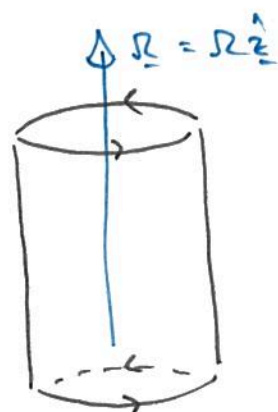


Thus $\nabla p \times \nabla \phi \neq 0$ (pointed into page)

$$\underbrace{-2 \underline{\underline{\Omega}} \cdot \underline{\underline{\nabla}} \underline{\underline{v}}}_{\text{vorticity production by tilting}} = \underbrace{\frac{1}{\rho^2} \underline{\underline{\nabla}} \rho \times \underline{\underline{\nabla}} \phi}_{\text{"baroclinic torque"}}$$

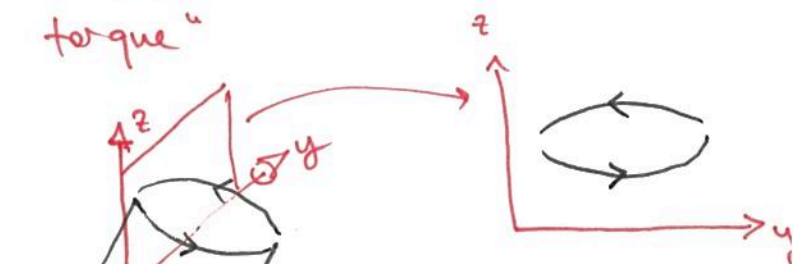
vorticity production
by tilting

"baroclinic
torque"



taylor
column.

tilting



tilting a
rotating column
"creates"
vorticity in
the direction
of tilt.

Baroclinic torque will balance vorticity
production by tilting Taylor columns.
(\Rightarrow Thermal wind balance).

A tilting Taylor column will no longer have $\frac{\partial \underline{\underline{v}}}{\partial z} = 0$.
In fact:

$$-2 \underline{\underline{\Omega}} \cdot \underline{\underline{\nabla}} \underline{\underline{v}} = -2 \Omega \frac{\partial \underline{\underline{v}}}{\partial z} = \frac{1}{\rho^2} \underline{\underline{\nabla}} \rho \times \underline{\underline{\nabla}} \phi.$$

In atmosphere + ocean: f-plane, thin layer, Boussinesq.

$$\begin{aligned} -f_0 \frac{\partial \underline{\underline{u}}}{\partial z} &= \frac{1}{\rho_0^2} \left(\underline{\underline{\nabla}}_z \rho + \hat{z} \frac{\partial \rho}{\partial z} \right) \times \left(\underline{\underline{\nabla}}_z \phi + \hat{z} \frac{\partial \phi}{\partial z} \right) \\ &= \frac{1}{\rho_0^2} \left(\underline{\underline{\nabla}}_z \tilde{\rho} \times \hat{z} \frac{\partial \phi_0}{\partial z} + \frac{\partial \tilde{\rho}}{\partial z} \hat{z} \times \underline{\underline{\nabla}}_z \phi_0 \right. \\ &\quad \left. + \cancel{\underline{\underline{\nabla}}_z \rho_0 \times \hat{z} \frac{\partial \tilde{\phi}}{\partial z}} + \cancel{\frac{\partial \rho_0}{\partial z} \hat{z} \times \underline{\underline{\nabla}}_z \tilde{\phi}} \right) + h.o.t \\ &= \frac{1}{\rho_0^2} \underline{\underline{\nabla}}_z \tilde{\rho} \times \hat{z} (-\rho_0 g) = \frac{g}{\rho_0} \hat{z} \times \underline{\underline{\nabla}}_z \tilde{\rho} \end{aligned}$$

$$\text{so } \frac{\partial u}{\partial t} = - \frac{g}{f\rho_0} \hat{z} \times \nabla_z \tilde{\rho}.$$