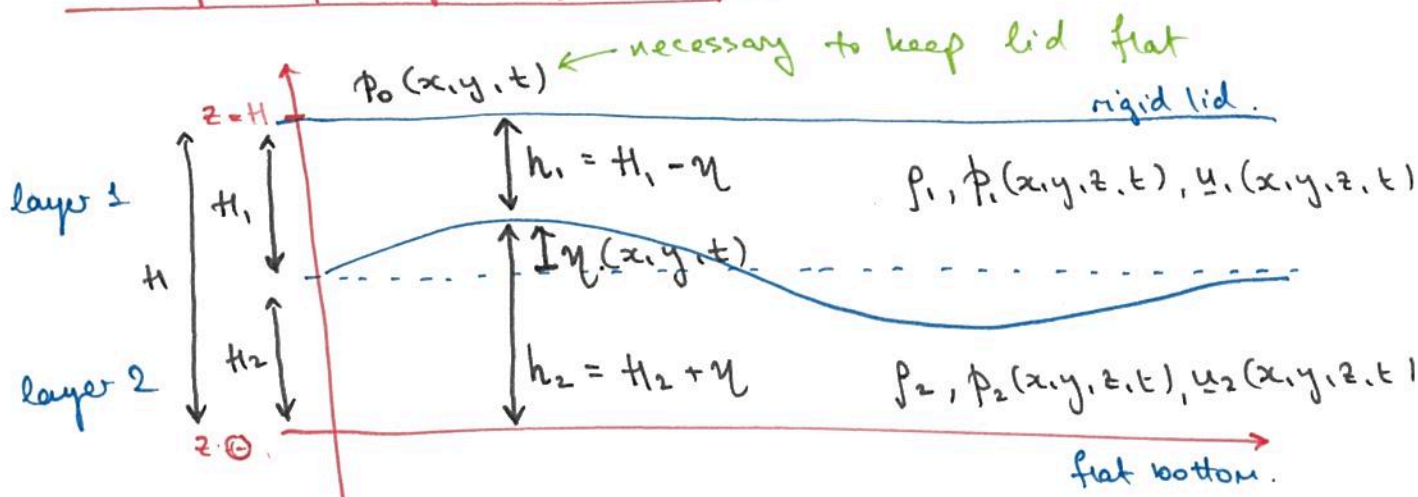


# BAROCLINIC INSTABILITY

## Two-layer quasigeostrophic model



Pressure in each layer:

$$\phi_1 = \phi_0 + \rho_1 g (H - z)$$

$$\phi_2 = \phi_0 + \rho_1 g h_1 + \rho_2 g (h_2 - z)$$

$$= \phi_0 + \rho_1 g (H_1 - \eta) + \rho_2 g (H_2 + \eta - z)$$

Pressure gradients:

$$\nabla_z \phi_1 = \nabla_z \phi_0$$

$$\nabla_z \phi_2 = \nabla_z \phi_0 - \rho_1 g \nabla \eta + \rho_2 g \nabla \eta.$$

$$= \nabla_z \phi_0 + \rho_0 g' \nabla \eta.$$

$$\rho_0 = \text{average density}, \quad g' = \frac{\rho_2 - \rho_1}{\rho_0} \quad \text{reduced gravity}$$

[Used Boussinesq approximation:  $\rho_0 \approx \rho_1 \approx \rho_2$ ]

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## Geostrophic balance (f-plane approximation).

$$\text{layer 1: } f_0 \hat{z} \times \underline{u}_1 = - \frac{1}{\rho_0} \nabla_z \phi_1$$

↑  
Boussinesq approximation.

$$\Rightarrow \underline{u}_1 = - \hat{z} \times (\hat{z} \times \underline{u}_1) = \hat{z} \times \nabla_z \left( \frac{\phi_1}{f_0 \rho_0} \right) = \hat{z} \times \nabla \psi_1$$

$$\psi_1 = \frac{\phi_1}{f_0 \rho_0} \quad \text{geostrophic streamfunction in layer 1.}$$

$$\text{layer 2: } f_0 \hat{z} \times \underline{u}_2 = - \frac{1}{\rho_0} \nabla_z \phi_2$$

$$\Rightarrow \underline{u}_2 = - \hat{z} \times (\hat{z} \times \underline{u}_2) = \hat{z} \times \nabla_z \left( \frac{\phi_2}{f_0 \rho_0} \right) = \hat{z} \times \nabla \psi_2$$

$$\begin{aligned} \psi_2 = \frac{\phi_2}{f_0 \rho_0} &= \frac{1}{f_0 \rho_0} \left( \phi_0 + \rho_1 g (H - \eta) + \rho_2 g (H_2 + \eta - z) \right) \\ &= \frac{\phi_0}{f_0 \rho_0} + \frac{\rho_1 g}{f_0 \rho_0} H + \frac{\rho_2 g}{f_0 \rho_0} H_2 + \frac{g'}{f_0} \eta - \frac{\rho_2 g}{f_0 \rho_0} z \\ &= \frac{\phi_0}{f_0 \rho_0} + \frac{g'}{f_0} \eta + \text{constants.} \\ &\quad \text{(ignore)} \end{aligned}$$

$$\begin{aligned} \text{Compare with } \psi_1 = \frac{\phi_1}{f_0 \rho_0} &= \frac{\phi_0}{f_0 \rho_0} + \frac{\rho_1 g}{f_0 \rho_0} (H - z) \\ &= \frac{\phi_0}{f_0 \rho_0} + \text{constants} \\ &\quad \text{(ignore)} \end{aligned}$$

$$\text{So find } \psi_2 = \psi_1 + \frac{g' \eta}{f_0} \quad \text{[ignoring constants]}$$

$$\text{or } \boxed{\psi_2 - \psi_1 = \frac{g' \eta}{f_0}}$$

PV in each layer

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For a single layer we found

$$q = \nabla^2 \psi + \beta y - \frac{f_0^2}{gH} \psi$$

$$L_d = \frac{\sqrt{gH}}{f_0}$$

To calculate PV in multiple layers use shallow water PV and expand:

$$\begin{aligned} Q_i &= \frac{\zeta_i + f}{h_i} = \frac{\zeta_i + f_0 + \beta y}{-h_i(1 + h_i'/h_i)} \quad i=1,2 \\ &\approx \frac{\zeta_i + \beta y + f_0}{h_i} \left(1 - \frac{h_i'}{h_i}\right) \\ &\approx \frac{\zeta_i + \beta y + f_0}{h_i} - \frac{f_0}{h_i} \frac{h_i'}{h_i} + \text{higher order terms} \end{aligned}$$

define quasigeostrophic PV:

$$q_i = \zeta_i + \beta y - \frac{f_0 h_i'}{h_i} \quad i=1,2$$

(ignoring factors of  $f_0, h_i$ ).

Then

$$\begin{aligned} q_1 &= \zeta_1 + \beta y - \frac{f_0 h_1'}{h_1} \\ &= \nabla^2 \psi_1 + \beta y + \frac{f_0^2}{g'H_1} (\psi_2 - \psi_1) \end{aligned}$$

$$\begin{aligned} \zeta_1 &= \nabla^2 \psi_1 \\ h_1' &= -\eta = -\frac{f_0}{g'} (\psi_2 - \psi_1) \end{aligned}$$

$$\begin{aligned} q_2 &= \zeta_2 + \beta y - \frac{f_0 h_2'}{h_2} \\ &= \nabla^2 \psi_2 + \beta y - \frac{f_0^2}{g'H_2} (\psi_2 - \psi_1) \end{aligned}$$

$$\begin{aligned} \zeta_2 &= \nabla^2 \psi_2 \\ h_2' &= \eta = \frac{f_0}{g'} (\psi_2 - \psi_1) \end{aligned}$$

↑ vortex stretching/squeezing

Simplification:  $H_1 = H_2 = \frac{H}{2}$ .

In that case :

$$\frac{f_0^2}{g'H_1} = \frac{f_0^2}{g'H_2} = \frac{K_d^2}{2}.$$

$$K_d^{-1} = L_d = \frac{\sqrt{g'H}}{2f_0} = \left\{ \begin{array}{l} \text{internal} \\ \text{baroclinic} \end{array} \right\} \text{ Rossby radius of deformation.}$$

Then,

$$q_1 = \nabla^2 \psi_1 + \beta y + \frac{K_d^2}{2} (\psi_2 - \psi_1)$$

$$q_2 = \nabla^2 \psi_2 + \beta y - \frac{K_d^2}{2} (\psi_2 - \psi_1)$$

Equations of motion

$$\frac{Dq_1}{Dt} = \frac{\partial q_1}{\partial t} + \underline{u}_1 \cdot \nabla q_1 = 0 \quad \underline{u}_1 = \left( -\frac{\partial \psi_1}{\partial y}, \frac{\partial \psi_1}{\partial x} \right)$$

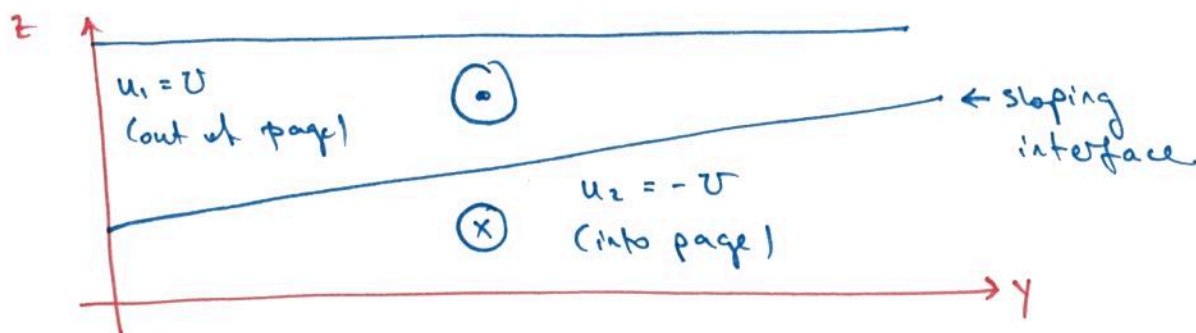
$$\frac{Dq_2}{Dt} = \frac{\partial q_2}{\partial t} + \underline{u}_2 \cdot \nabla q_2 = 0 \quad \underline{u}_2 = \left( -\frac{\partial \psi_2}{\partial y}, \frac{\partial \psi_2}{\partial x} \right)$$

## BASE STATE

Thermal wind balance

$$\bar{\psi}_1 = -Uy \Rightarrow \bar{u}_1 = -\bar{\psi}_{1,y} = U$$

$$\bar{\psi}_2 = Uy \Rightarrow \bar{u}_2 = -\bar{\psi}_{2,y} = -U$$



Add small perturbations:

$$\eta_1 = \bar{\eta}_1 + \tilde{\eta}_1 = -Uy + \tilde{\eta}_1$$

$$\eta_2 = \bar{\eta}_2 + \tilde{\eta}_2 = Uy + \tilde{\eta}_2$$

base state has zero relative vorticity

$$q_1 = \underbrace{\nabla^2 \bar{\eta}_1 + \beta y + \frac{k d^2}{2} (\bar{\eta}_2 - \bar{\eta}_1)}_{\bar{q}_1} + \underbrace{\nabla^2 \tilde{\eta}_1 + \frac{k d^2}{2} (\tilde{\eta}_2 - \tilde{\eta}_1)}_{\tilde{q}_1}$$

$$= (\beta + k d^2 U) y + \nabla^2 \tilde{\eta}_1 + \frac{k d^2}{2} (\tilde{\eta}_2 - \tilde{\eta}_1)$$

$$q_2 = (\beta - k d^2 U) y + \nabla^2 \tilde{\eta}_2 - \frac{k d^2}{2} (\tilde{\eta}_2 - \tilde{\eta}_1)$$

Linearized equations of motion:

$$\left( \frac{\partial}{\partial t} + U \frac{\partial}{\partial x} \right) \tilde{q}_1 + \frac{\partial \tilde{q}_1}{\partial x} (\beta + k d^2 U) = 0$$

$$\left( \frac{\partial}{\partial t} - U \frac{\partial}{\partial x} \right) \tilde{q}_2 + \frac{\partial \tilde{q}_2}{\partial x} (\beta - k d^2 U) = 0$$

Plane wave solutions:

$$\tilde{\eta}_1 = \hat{\eta}_1 e^{i(kx + ly - \omega t)}$$

$$\tilde{\eta}_2 = \hat{\eta}_2 e^{i(kx + ly - \omega t)}$$

$$\omega = \omega_r + i\omega_i$$

$$\omega_i \neq 0 \Rightarrow \text{instability.}$$

Can show that equations of motion become

$$\textcircled{1} (c - U) \left( K^2 \hat{\eta}_1 + \frac{k d^2}{2} (\hat{\eta}_1 - \hat{\eta}_2) \right) + (\beta + k d^2 U) \hat{\eta}_1 = 0$$

$$\textcircled{2} (c + U) \left( K^2 \hat{\eta}_2 - \frac{k d^2}{2} (\hat{\eta}_1 - \hat{\eta}_2) \right) + (\beta - k d^2 U) \hat{\eta}_2 = 0$$

where

$$c = \frac{\omega}{k} = \text{phase speed.}$$

$$K = \sqrt{k^2 + l^2} = \text{wavenumber magnitude.}$$



$$\textcircled{1} + \textcircled{2} \Rightarrow$$

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$$(cK^2 + \beta)(\hat{\psi}_1 + \hat{\psi}_2) - U K^2(\hat{\psi}_1 - \hat{\psi}_2) = 0$$

$$\textcircled{1} - \textcircled{2} \rightarrow$$

$$[c(K^2 + Kd^2) + \beta](\hat{\psi}_1 - \hat{\psi}_2) - U(K^2 - Kd^2)(\hat{\psi}_1 + \hat{\psi}_2) = 0$$

Introduce

$$\hat{\psi}_S = \frac{1}{2}(\hat{\psi}_1 + \hat{\psi}_2)$$

barotropic mode  
(symmetric)

$$\hat{\psi}_A = \frac{1}{2}(\hat{\psi}_1 - \hat{\psi}_2)$$

baroclinic mode  
(antisymmetric)

$$(cK^2 + \beta)\hat{\psi}_S - U K^2 \hat{\psi}_A = 0$$

$$(c(K^2 + Kd^2) + \beta)\hat{\psi}_A - U(K^2 - Kd^2)\hat{\psi}_S = 0$$

$$\begin{vmatrix} cK^2 + \beta & -U K^2 \\ -U(K^2 - Kd^2) & c(K^2 + Kd^2) + \beta \end{vmatrix} \begin{vmatrix} \hat{\psi}_S \\ \hat{\psi}_A \end{vmatrix} = 0.$$

For non-trivial solutions, determinant = 0.

Case 1 :  $U = 0$

$$\begin{vmatrix} cK^2 + \beta & 0 \\ 0 & c(K^2 + Kd^2) + \beta \end{vmatrix}$$

$$= (cK^2 + \beta)(c(K^2 + Kd^2) + \beta) = 0$$

$$c = -\frac{\beta}{K^2}$$

phase speed of barotropic Rossby wave

$$c = -\frac{\beta}{K^2 + Kd^2}$$

phase speed of baroclinic Rossby wave

NO INSTABILITY!

Case 2:  $U \neq 0$  (nonzero shear, tilting interface)

$$\text{determinant} = (cK^2 + \beta)[c(K^2 + K_d^2) + \beta] - U^2 K^2 (K^2 - K_d^2) = 0$$

Quadratic in  $c$ :

$$c^2 K^2 (K^2 + K_d^2) + \beta (2K^2 + K_d^2) c + \beta^2 - U^2 K^2 (K^2 - K_d^2) = 0$$

$$c = -\beta \frac{2K^2 + K_d^2}{2K^2 (K^2 + K_d^2)} \pm \frac{\sqrt{D}}{2K^2 (K^2 + K_d^2)}$$

Discriminant

$$D = \beta^2 K_d^4 + 4U^2 K^4 (K^4 - K_d^4). < 0 \Rightarrow \text{instability}$$

For  $D < 0$  get complex  $c = c_r + ic_i$

$$\Rightarrow \psi \sim e^{\omega t} = e^{c_i k t}$$

When is  $D < 0$ ?

$$\beta^2 K_d^4 < 4U^2 K^4 (K_d^4 - K^4).$$

$$\Rightarrow 1 < \frac{4U^2 K_d^4}{\beta^2} \left\{ \frac{K^4}{K_d^4} \right\} \left( 1 - \left\{ \frac{K^4}{K_d^4} \right\} \right).$$

$$\text{let } \hat{U} = \frac{U K_d^2}{\beta} \quad \text{non-dimensional shear velocity}$$

$$\hat{K} = \frac{K}{K_d} \quad \text{non-dimensional wavenumber}$$

$$1 < 4 \hat{U}^2 \hat{K}^4 (1 - \hat{K}^4).$$

condition for  
instability

Rewrite as

$$(\hat{K}^4)^2 - \hat{K}^4 + \frac{1}{4\hat{U}^2} < 0.$$

quadratic inequality in  $\hat{K}^4$ .

Roots:  $\hat{K}_c^4 = \frac{1}{2} \pm \frac{1}{2} \sqrt{1 - \frac{1}{\hat{U}^2}}$

For real roots:  $\hat{U} > 1.$

$$\Rightarrow \boxed{\hat{U} > \frac{\beta}{K_d^2}}$$

threshold  
shear velocity  
for instability.

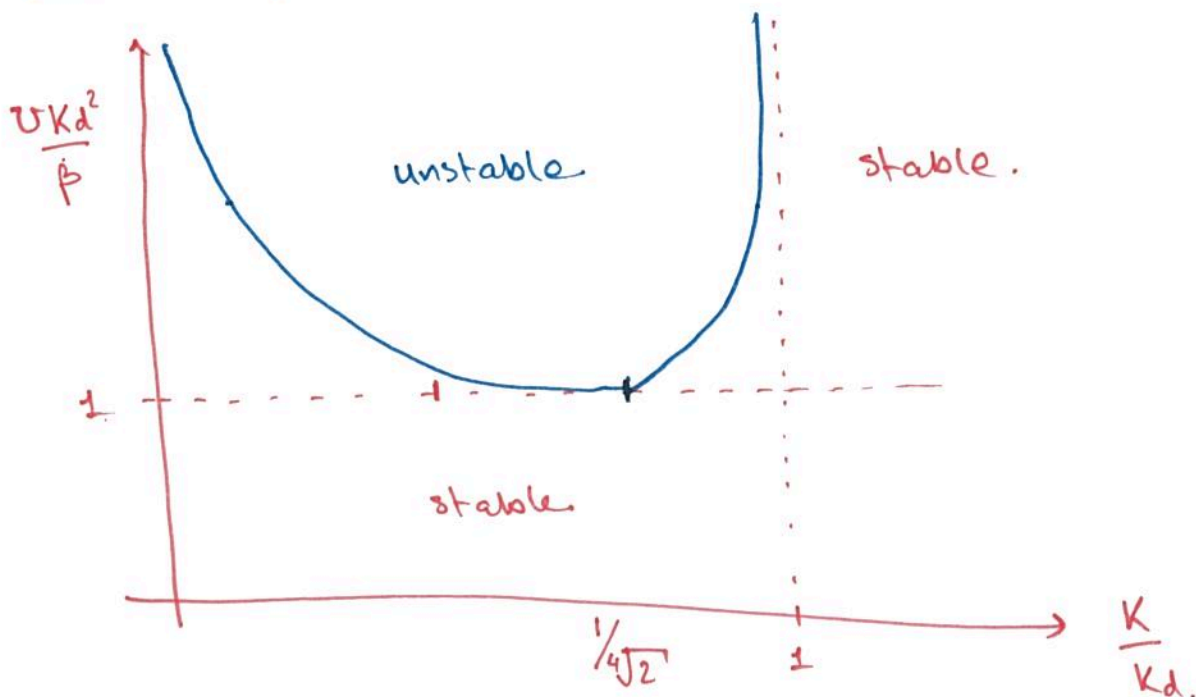
Value of  $\hat{K}_c$  for  $\hat{U} = \beta/K_d^2$  ( $\hat{U}=1$ )

$$\Rightarrow \hat{K}_c^4 = \frac{1}{2} \Rightarrow \hat{K}_c = \frac{1}{\sqrt[4]{2}}$$

When  $\hat{U} \rightarrow \infty$

$$\hat{K}_c \rightarrow 0, 1.$$

Regime diagram:





Why  $\pi/2$ ?

$$\hat{\psi}_A = \frac{c k^2 + \beta}{k^2 U} \hat{\psi}_S \quad -9-$$

For simplicity set  $\beta = 0$ .

$$\Rightarrow \hat{\psi}_A = \frac{c}{U} \hat{\psi}_S$$

For an unstable wave with  $\beta = 0$

$$\Rightarrow c = i c_i$$

$$\hat{\psi}_A = \frac{i c_i}{U} \hat{\psi}_S = e^{i\pi/2} \frac{c_i}{U} \hat{\psi}_S.$$

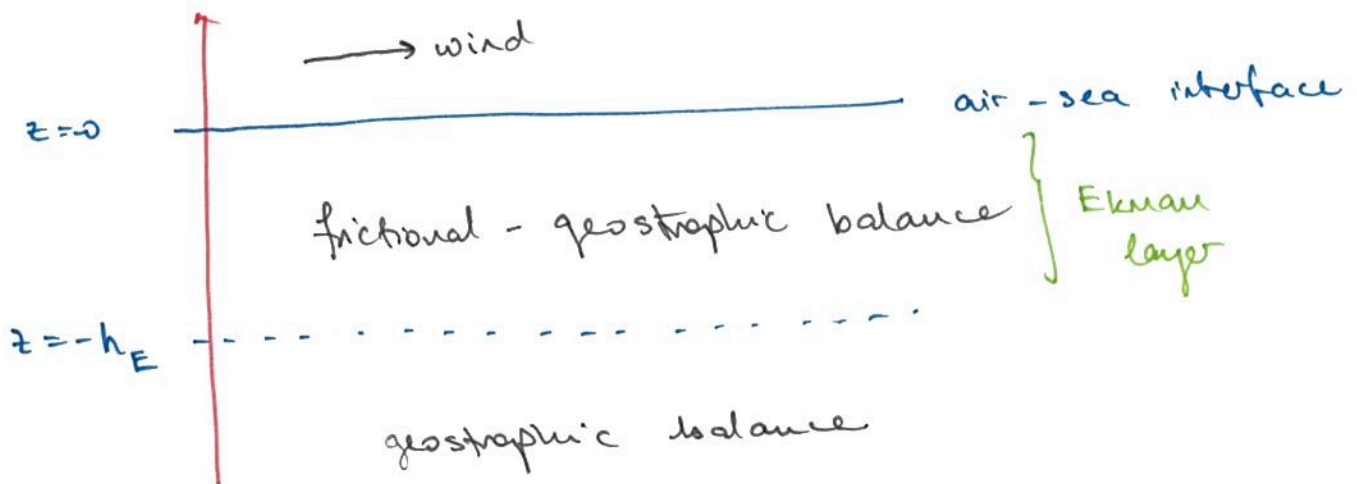
$\Rightarrow \pi/2$  phase shift between  $\hat{\psi}_A$  and  $\hat{\psi}_S$ .

$\Rightarrow \pi/2$  phase shift between  $\hat{\psi}_1$  and  $\hat{\psi}_2$ .

## The Ekman Layer

\* frictional boundary layer that connects geostrophic flow in the atmosphere/ocean. to friction-dominated flow near boundaries.

- Atmospheric Ekman layer near ground.
  - Weak bottom Ekman layer at ocean floor
  - Surface Ekman layer at air-sea interface.
- ↑ This is the Ekman layer we will focus on.



In the Ekman layer

$$\underline{f} \times \underline{u} = - \frac{1}{\rho_0} \underline{\nabla}_z p + A \frac{\partial^2 \underline{u}}{\partial z^2}$$

model for friction.

$A$  = "eddy viscosity" = models the effect of turbulent motions to remove/diffuse momentum

Also have hydrostatic balance ( $\rho = \rho_0 = \text{constant}$ )

$$\frac{\partial p}{\partial z} = 0 \quad (\text{p is the pressure perturbation})$$

$$\underline{\nabla} \cdot \underline{v} = 0 \quad (3D \text{ incompressibility})$$

If friction is not present / important (far from surface) then have geostrophic balance.

$$f_0 U \sim \frac{P}{\rho_0 L}$$

$\Rightarrow$  gives us a scaling for pressure  $P \sim f_0 U \rho_0 L$ .

This gives us (with friction)

$$f_0 \underline{\hat{U}} \times \underline{\hat{U}} = f_0 \underline{\hat{U}} (-\underline{\hat{\nabla}}_z \underline{\hat{p}}) + \frac{A \underline{\hat{U}}}{H^2} \frac{\partial^2 \underline{\hat{U}}}{\partial \hat{z}^2}$$

*from geostrophic scaling for pressure*

gives non-dimensional frictional - geostrophic balance:

$$\underline{\hat{U}} \times \underline{\hat{U}} = -\underline{\hat{\nabla}}_z \underline{\hat{p}} + Ek \frac{\partial^2 \underline{\hat{U}}}{\partial \hat{z}^2}$$

where  $Ek = \frac{A}{f_0 H^2} = \text{Ekman number (dimensionless)}$

This determines the importance of friction:

$Ek \ll 1$  : friction negligible

$Ek \gg 1$  : friction dominates.

Define thickness of the Ekman layer ( $h_E$ ) as the depth where  $Ek \sim O(1)$ :

$$Ek = 1 = \frac{A}{f_0 h_E^2} \Rightarrow \boxed{h_E = \sqrt{A/f_0}}$$

$h_E = \text{Ekman layer thickness} = \begin{cases} 1 \text{ km} & \text{in atm.} \\ 50 \text{ m} & \text{in ocn.} \end{cases}$