

Ocean: treat as incompressible. (density does not change with pressure).

$$\rho_0 = \text{constant.}$$

Hydrostatic balance:

$$\frac{dp}{dz} = -\rho_0 g$$

$$\int dp = -\int \rho_0 g dz$$

$$p(z) - p(0) = -\rho_0 g z \Rightarrow p(z) = p(0) - \rho_0 g z$$

$z < 0.$

z	p
0	1 atm.
-10m	1.99 atm
-100m	10.9 atm.
-1000m	100.2 atm.

Density does depend on temperature & salinity.
(T) (S).

$$\rho(T, S).$$

$$S = \frac{\text{mass of "salt"}}{\text{mass of seawater}}$$

$$\sigma = \rho - \rho_0 = \text{density anomaly}$$

$$\rho_0 = 1000 \text{ kg m}^{-3} = \text{reference density.}$$

Equation of state for seawater:

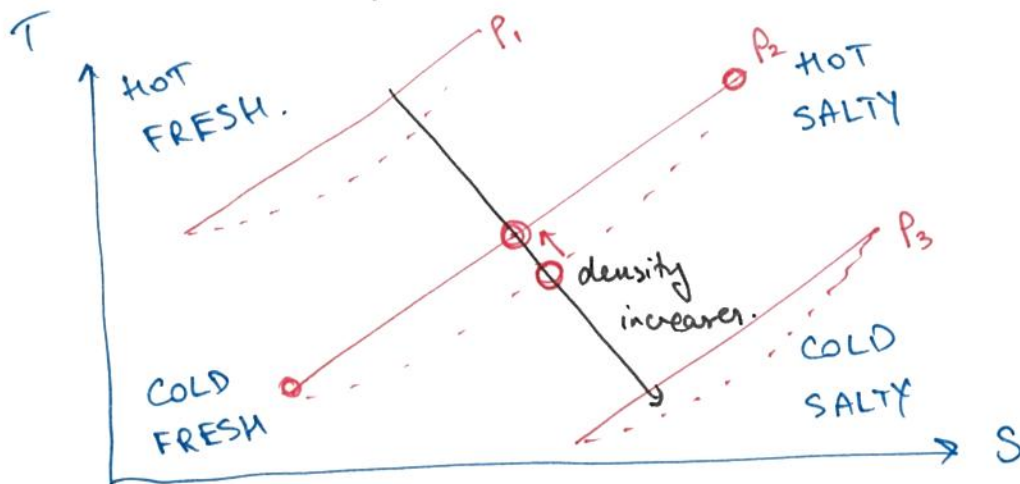
Linearize in T, S :

$$p(T, S) = \underbrace{p(T_0, S_0)}_{P_0} + \left. \frac{\partial p}{\partial T} \right|_{T_0, S_0} (T - T_0) + \left. \frac{\partial p}{\partial S} \right|_{T_0, S_0} (S - S_0) + \dots$$

$$= P_0 \left[1 + \underbrace{\frac{1}{P_0} \left. \frac{\partial p}{\partial T} \right|_{T_0, S_0}}_{\text{negative.}} (T - T_0) + \underbrace{\frac{1}{P_0} \left. \frac{\partial p}{\partial S} \right|_{T_0, S_0}}_{\text{positive}} (S - S_0) \right] + \dots$$

$T \uparrow \quad p \downarrow$ $S \uparrow \quad p \uparrow$

$$= P_0 (1 - \alpha_T (T - T_0) + \beta_S (S - S_0))$$



$$P_1 < P_2 < P_3$$

To close : need. $\frac{DT}{Dt} = Q_T$ $\frac{DS}{Dt} = Q_S$

Example: use EOS for dry air and hydrostatic balance to calculate $p(z)$

$$\phi = p R_d T \quad \Rightarrow \quad p = \frac{\phi}{R_d T}$$

Assume an isothermal atmosphere ($T_0 = \text{constant}$)

hydrostatic balance: $\frac{d\phi}{dz} = -p g = -\frac{\phi g}{R_d T_0}$

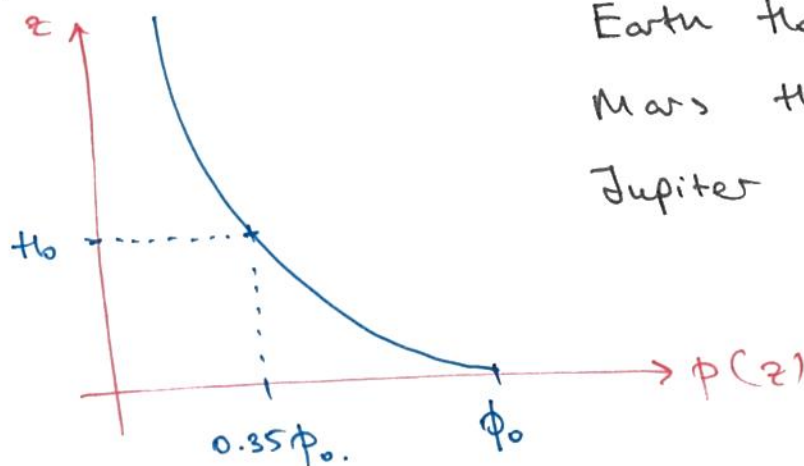
$$\int \frac{d\phi}{\phi} = -\int \frac{g}{R_d T_0} dz \quad \Rightarrow \quad \ln \phi = -\frac{g z}{R_d T_0} + C$$

let $C = \ln \phi_0$ (surface pressure)

$$\ln \phi - \ln \phi_0 = -\frac{z}{H_0}$$

$$H_0 = \frac{R_d T_0}{g} = \text{"scale height"}$$

$$\Rightarrow \phi = \phi_0 e^{-z/H_0}$$



Earth $H_0 \approx 7.5 \text{ km}$

Mars $H_0 \approx 11 \text{ km}$

Jupiter $H_0 \approx 27 \text{ km}$

Boussinesq approximation.

- exploit smallness of density variations (in the ocean)

$$\rho = \underbrace{\rho_0}_{\text{reference density}} + \underbrace{\tilde{\rho}(x, y, z, t)}_{\text{small perturbation}} \quad \frac{|\tilde{\rho}|}{\rho_0} \ll 1.$$

- define reference pressure $\phi_0(z)$ in hydrostatic balance with ρ_0

$$\phi = \phi_0(z) + \tilde{\phi}(x, y, z, t) \quad \frac{|\tilde{\phi}|}{\phi_0} \ll 1.$$

where. $\frac{d\phi_0}{dz} = -\rho_0 g$

- sub into momentum equation.

$$\frac{D\underline{v}}{Dt} + 2\underline{\Omega} \times \underline{v} = -\frac{1}{\rho} \underline{\nabla} \phi - g \hat{z}$$

$$\rho = \rho_0 + \tilde{\rho}$$

$$(\rho_0 + \tilde{\rho}) \left[\frac{D\underline{v}}{Dt} + 2\underline{\Omega} \times \underline{v} \right] = -\underline{\nabla}(\phi_0 + \tilde{\phi}) - (\rho_0 + \tilde{\rho})g \hat{z}$$

(Arrows point from $\tilde{\phi}$ and $\tilde{\rho}$ to "keep!")

Boussinesq approx: neglect $\tilde{\rho}$ EXCEPT where multiplied by g .

$$\rho_0 \left[\frac{D\underline{v}}{Dt} + 2\underline{\Omega} \times \underline{v} \right] \approx - \underbrace{\frac{d\phi_0}{dz} \hat{z}}_{\text{cancel (in hydrostatic balance)}} - \underline{\nabla} \tilde{\phi} - \underbrace{\rho_0 g \hat{z}}_{\text{cancel (in hydrostatic balance)}} - \tilde{\rho} g \hat{z}$$

$$\Rightarrow \left[\frac{D\underline{v}}{Dt} + 2\underline{\Omega} \times \underline{v} \right] = -\frac{1}{\rho_0} \underline{\nabla} \tilde{\phi} - \underbrace{\frac{\tilde{\rho} g}{\rho_0} \hat{z}}_{\text{reduced gravity}}$$

Boussinesq momentum equation.

Continuity equation

$$\frac{D\rho}{Dt} = -\rho \nabla \cdot \underline{v}$$

$$\rho = \rho_0 + \tilde{\rho}$$

$$\Rightarrow \frac{D\tilde{\rho}}{Dt} = -\underbrace{\rho_0 \nabla \cdot \underline{v}}_{\text{largest term}} - \tilde{\rho} \nabla \cdot \underline{v}$$

the $\rho_0 \nabla \cdot \underline{v}$ term has no term to balance it so.

$$\Rightarrow \rho_0 \nabla \cdot \underline{v} = 0. \quad !$$

$$\Rightarrow \boxed{\nabla \cdot \underline{v} = 0.} \quad \begin{array}{l} \text{In B-approx, continuity equation} \\ \rightarrow \text{incompressibility condition.} \end{array}$$

* Note: this doesn't mean $\rho = \rho_0 + \tilde{\rho}$ is constant.

$$\text{or } \frac{D\tilde{\rho}}{Dt} = 0.$$

(Need information about sources of heating/cooling.)

But if fluid is adiabatic (no heating/cooling)

$$\Rightarrow \boxed{\frac{D\tilde{\rho}}{Dt} = 0.}$$

Boussinesq approximations.

$$\frac{D\underline{v}}{Dt} + 2\Omega \times \underline{v} = -\frac{1}{\rho_0} \nabla \tilde{p} - \frac{\tilde{\rho}}{\rho_0} g \hat{z} \quad (\text{momentum})$$

$$\nabla \cdot \underline{v} = 0 \quad (\text{incompressible})$$

$$\frac{D\tilde{\rho}}{Dt} = 0 \quad (\text{adiabatic}).$$

Thin layer approximation: $L \gg H$

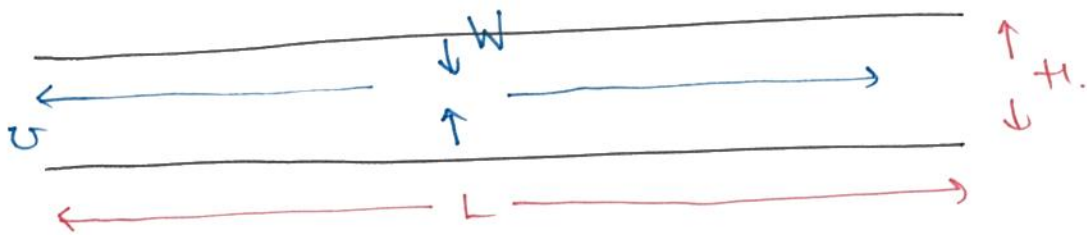
* $\nabla \cdot \underline{v} = 0$ (incompressibility)

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$

$$\frac{U}{L} \quad \frac{V}{L} \quad \frac{W}{H}$$

$$\Rightarrow \frac{U}{L} \sim \frac{W}{H} \Rightarrow W \sim U \frac{H}{L} \sim \alpha U$$

$\alpha \ll 1$.



\Rightarrow neglect terms involving w (compared with u, v)

EXCEPT in terms like $\frac{\partial w}{\partial z}$, $w \frac{\partial}{\partial z}$

x-momentum:

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + \underbrace{w \frac{\partial u}{\partial z}}_{\text{keep.}} + \cancel{w f_x} - v f_y = - \frac{1}{\rho_0} \frac{\partial p}{\partial x}$$

$w \ll v$

y-momentum:

$$\frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + \underbrace{w \frac{\partial v}{\partial z}}_{\text{keep.}} + u f_x = - \frac{1}{\rho_0} \frac{\partial p}{\partial y}$$

z-momentum:

$$\underbrace{\frac{\partial w}{\partial t} + u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z}}_{\text{neglect } w \ll u.} - \underbrace{u f_x}_{\text{NOT important in atm/ocn flows.}} = - \frac{1}{\rho_0} \frac{\partial p}{\partial z} - \frac{\rho_0}{\rho_0}$$

Simplified equations for rotating, stratified thin layer flow

$$\frac{Du}{Dt} - v f = - \frac{1}{\rho_0} \frac{\partial p}{\partial x}$$

$$\frac{Dv}{Dt} + u f = - \frac{1}{\rho_0} \frac{\partial p}{\partial y}$$

$$0 = - \frac{\partial p}{\partial z} - \rho g$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$

$$\frac{D\rho}{Dt} = 0.$$

- Note:
- * Boussinesq approx
 - * Tangent plane approx
 - * Thin layer approx

Compact notation:

$$\underline{u} = (u, v) \quad \underline{\nabla}_z = (\partial_x, \partial_y)$$

$$\underline{f} = f \underline{\hat{z}} \quad f = 2\Omega \sin \phi = \text{"Coriolis parameter"}$$

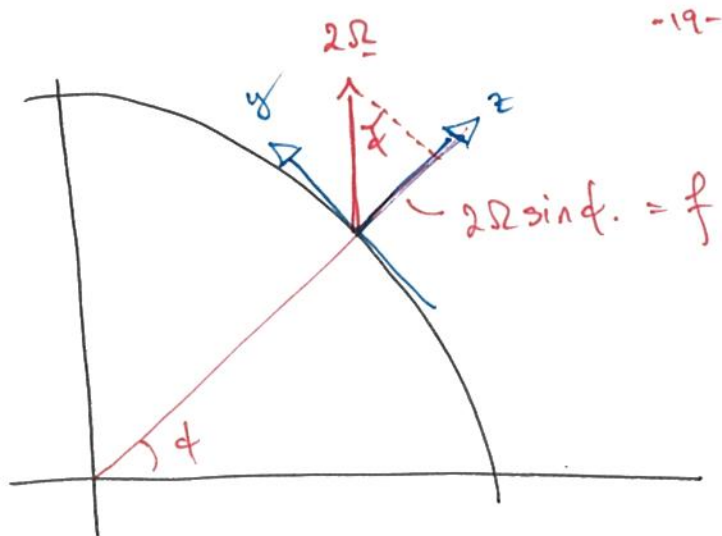
$$\frac{D\underline{u}}{Dt} + \underline{f} \times \underline{u} = - \frac{1}{\rho_0} \underline{\nabla}_z p \quad \text{momentum.}$$

$$\frac{\partial p}{\partial z} = - \rho g \quad \text{hydrostatic balance}$$

$$\frac{D\rho}{Dt} = 0 \quad \text{adiabatic}$$

$$\underline{\nabla}_z \cdot \underline{u} + \frac{\partial w}{\partial z} = 0.$$

Primitive equations



$$\underline{f} = f(\phi) \underline{\hat{z}}$$

Two simplifications

1. f -plane approximation.

treat $f = 2\Omega \sin \phi$ as a constant ($\phi = \phi_0$)

$$f = f_0 = 2\Omega \sin \phi_0.$$

2. β -plane approximation.

allow linear changes of f with latitude $\phi = \phi_0 + \Delta\phi$

$$f = 2\Omega \sin(\phi_0 + \Delta\phi)$$

$$\approx 2\Omega \sin \phi_0 + \Delta\phi \left. \frac{\partial f}{\partial \phi} \right|_{\phi_0} \quad (\text{Taylor approx})$$

$$= 2\Omega \sin \phi_0 + 2\Omega \cos \phi_0 \cdot a \Delta\phi.$$

$$= \underbrace{f_0}_{f_0} + \underbrace{\frac{a}{\beta}}_{\beta} \underbrace{\Delta\phi}_{y}$$

$$f = f_0 + \beta y$$

$$y = a \Delta\phi = \text{distance north.}$$

$$\beta = \frac{1}{a} \left. \frac{\partial f}{\partial \phi} \right|_{\phi_0} = \frac{2\Omega \cos \phi_0}{a}$$

Geostrophic balance

Rapidly rotating flows: $Ro \ll 1$

$$Ro = \frac{\text{period of rotation}}{\text{time to move } L} \sim \frac{2\pi/\Omega}{L/U} \sim \frac{U}{L\Omega}$$

Compare sizes of terms (forces) in the horizontal momentum equation.

$$Ro \sim \frac{\text{inertial terms } (Du/Dt)}{\text{Coriolis term } (-v f)} \sim \frac{v/T}{v\Omega} \sim \frac{1}{\Omega T}$$

So if we choose relevant timescale $T \sim L/U$ (advective timescale)

$$\Rightarrow R \sim \frac{U}{L\Omega} \text{ as before}$$

Rapidly rotating flows are equivalent to neglecting inertial terms:

$$\cancel{\frac{Du}{Dt}} + \underbrace{f \times u}_{\text{Coriolis}} = - \underbrace{\frac{1}{\rho_0} \nabla_{\perp} \phi}_{\text{horizontal pressure gradient}}$$

$Ro \ll 1.$

\Rightarrow "geostrophic balance"

$$\begin{aligned} -fv &= -\frac{1}{\rho_0} \frac{\partial p}{\partial x} & \Rightarrow v &= \frac{1}{\rho_0 f} \frac{\partial p}{\partial x} \\ +fu &= -\frac{1}{\rho_0} \frac{\partial p}{\partial y} & u &= -\frac{1}{\rho_0 f} \frac{\partial p}{\partial y} \end{aligned}$$

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In f -plane approximation $f = f_0$

$$\Rightarrow v = \frac{\partial}{\partial x} \left(\frac{\phi}{\rho_0 f_0} \right) = \frac{\partial \psi}{\partial x}$$

$$u = -\frac{\partial}{\partial y} \left(\frac{\phi}{\rho_0 f_0} \right) = -\frac{\partial \psi}{\partial y}$$

$$\psi = \frac{\phi}{\rho_0 f_0}$$

"geostrophic
streamfunction"

* Flow is incompressible in 2D.

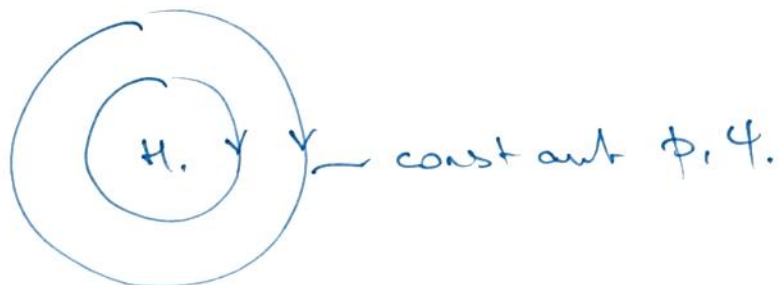
$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = -\frac{\partial^2 \psi}{\partial x \partial y} + \frac{\partial^2 \psi}{\partial y \partial x} = 0.$$

* ψ is a streamfunction

\Rightarrow flow is along contours of ψ .

\Rightarrow flow is along contours of ϕ .

NH



"anticyclone" \rightarrow clockwise in NH
 \rightarrow anticlockwise in SH.