# MEMS 1060: Homework #4

Due on February 28, 2021 at  $6:00 \mathrm{pm}$ 

 $Professor\ Sammak\ Th\ 6:00PM$ 

Made using  $\LaTeX/Inkscape.$  Source files available upon request.

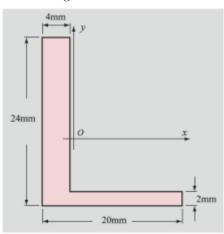
Shane Riley

# Problem 1

Given the cross-sectional area shown, find the principal moments and axes of inertia, given the following:

- $I_x = 7523[mm^4]$
- $I_u = 3210[mm^4]$
- $I_{xy} = I_{yx} = 2640 [mm^4]$
- $\bullet \ \ I = \begin{bmatrix} I_x & -I_{xy} \\ -I_{yx} & I_y \end{bmatrix}$

Figure 1: Problem 1.



### Solution

We must find eigenvalues and eigenvectors of the I matrix. In order to do this, we will solve the characteristic equation for  $\lambda$  (we will call the moment of inertia matrix [A] and the identity matrix [I] for clarity):

$$det[A - \lambda I] = 0$$

$$\begin{vmatrix} I_x - \lambda & -I_{xy} \\ -I_{yx} & I_y - \lambda \end{vmatrix} = 0$$

$$(I_x - \lambda)(I_y - \lambda) - (-I_{xy})(-I_{yx}) = 0$$

$$I_x I_y - \lambda I_y - \lambda I_x + \lambda^2 - I_{xy}^2 = 0$$

$$\lambda^2 - (I_x + I_y)\lambda + (I_x I_y - I_{xy}^2) = 0$$

We now employ the quadratic formula to find our eigenvalues:

$$\lambda_1, \lambda_2 = \frac{(I_x + I_y) \pm \sqrt{(I_x + I_y)^2 - 4(I_x I_y - I_{xy}^2)}}{2}$$
$$\lambda_1 \approx 8775[mm^4]$$
$$\lambda_2 \approx 1958[mm^4]$$

From here, we must find our corresponding normalized eigenvectors for these eigenvalues. We will solve the proper equation to find these eigenvectors.

$$[A - I\lambda][v] = 0$$

$$\begin{bmatrix} I_x - \lambda_1 & -I_{xy} \\ -I_{yx} & I_y - \lambda_1 \end{bmatrix} \begin{bmatrix} v_1^{(1)} \\ v_2^{(1)} \end{bmatrix} = 0$$

This linear system is to be solved for both  $\lambda_1$  and  $\lambda_2$ . For both, we will fix  $v_2$  to 1 to find  $v_1$  and then we will normalize. This could be done by hand for a 2x2, but I will reduce the matrix in MATLAB and solve the following equation:

$$(rref([A-I\lambda]) + \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}) * [v] = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

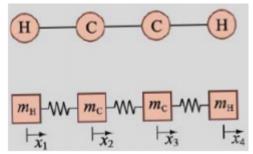
By making this tweak and then normalizing the output, we find our eigenvalues. See the source code.

Using the characteristic polynomial method, we find the principal axes and moments of inertia for the cross section:  $\lambda_1 = 8775[mm^4]$ ,  $\lambda_2 = 1958[mm^4]$ ,  $u_1 = [-0.9035; 0.4286]$ ,  $u_2 = [0.4286; 0.9035]$ 

## Problem 2

Given an acetylene molecule idealized as four masses attached by springs and the givens  $k_{CH} = 592[kg/s^2]$ ,  $k_{CC} = 1580[kg/s^2]$ ,  $m_H = 1[amu]$ ,  $m_C = 12[amu]$ , and  $1[amu] = 1.6605 * 10^-27[kg]$ , find the frequencies and corresponding eigenvalues.

Figure 2: Problem 2.



#### Solution

In order to find the frequencies, we must represent the amplitudes of vibration as a matrix and find its eigenvalues. The coefficient matrix [a] is displayed such that it produces the amplitudes of vibration [A]:

$$a = \begin{bmatrix} \frac{k_{CH}}{m_H} & -\frac{k_{CH}}{m_H} & 0 & 0\\ -\frac{k_{CH}}{m_C} & \frac{(k_{CH}+k_{CC})}{m_C} & -\frac{k_{CC}}{m_C} & 0\\ 0 & -\frac{k_{CC}}{m_C} & \frac{(k_{CH}+k_{CC})}{m_C} & -\frac{k_{CH}}{m_C}\\ 0 & 0 & -\frac{k_{CH}}{m_H} & \frac{k_{CH}}{m_H} \end{bmatrix}$$
$$[a - \omega^2 I][A] = 0$$

Because of the setup of this type of problem, it so happens that the frequencies are simply the roots of the eigenvalues of the [a] matrix. Therefore if we find the eigenvalues and eigenvectors of [a], we have effectively

solved the problem. We will implement QR factorization in order to do find the eigenvalues, and then we will compute the corresponding eigenvectors using row-reduction in MATLAB. For the iteration, I ran 100 iterations and then compared the resulting eigenvalues to those from the stock function. In a more rigorous implementation it would be worth using a residual convergence criteria for the eigenvalues.

Using QR factorization, the following eigenvalues are found. The frequencies are simply the squares of these eigenvalues. Note: one of the eigenvalues coming from the factorization as 16 orders of magnitude less than the others. We will consider this to likely be an eigenvalue of zero clouded by machine error. We will check the eigenvector to be sure.

In order to find the corresponding eigenvectors, one must keep a running product of Q matrices for every iteration.

$$[A - I\lambda] * [v] = 0$$

Found eigenvalues:

$$\lambda_1 = 4.053 * 10^{29}$$
$$\lambda_2 = 3.862 * 10^{29}$$
$$\lambda_3 = 1.395 * 10^{29}$$
$$\lambda_4 = 0$$

Frequencies:

$$\omega_1 = 6.366 * 10^{14} [s^{-1}]$$

$$\omega_2 = 6.215 * 10^{14} [s^{-1}]$$

$$\omega_3 = 3.735 * 10^{14} [s^{-1}]$$

$$\omega_4 = 0 [s^{-1}]$$

Eigenvectors (normalized):

$$v_{1} = \begin{bmatrix} 0.701 \\ -0.096 \\ 0.096 \\ -0.701 \end{bmatrix}$$

$$v_{2} = \begin{bmatrix} 0.705 \\ -0.059 \\ -0.059 \\ 0.705 \end{bmatrix}$$

$$v_{3} = \begin{bmatrix} 0.604 \\ 0.368 \\ -0.368 \\ -0.604 \end{bmatrix}$$

$$v_{4} = \begin{bmatrix} 0.5 \\ 0.5 \\ 0.5 \\ 0.5 \\ 0.5 \end{bmatrix}$$

Using the QR factorization method, the frequencies and corresponding eigenvectors are found.

```
1 % MEMS 1060 Homework 4
  % Author: Shane Riley
  % Date: 2/28/2021
  format long
  % Problem 1
  % Given the area, find the principal moments and axes of inertia
   disp(" ");
   disp("Problem 1");
   I_x = 7523;
                     \% [mm^4]
   I_{-y} = 3210;
                     \% [mm^4]
11
   I_{-}xy = 2640;
                     \% [mm^4]
12
13
   A = [\dots]
14
       I_x
               -I_xy
15
       -I_{-}xy
                  I_{-}y
16
        ];
17
  % Solve using the characteristic equation. Done on paper. Roots/eigenvalues
   % checked using stock function
21
   coeff = [...
        1
       - (I_{-}x + I_{-}y)
24
       I_x * I_y - I_xy^2
26
   e = roots(coeff);
28
  % Find eigenvectors from eigenvalues
   char = @(lambda) A - lambda .* eye(2);
32
  \% Find v such that Av = 0
33
34
  % Find matrix
   r_{char} = @(x) rref(char(x)); % row reduce
   r_char_e1 = r_char(e(1));
   r_{char} = 2 = r_{char} (e(2));
39
  % Find v
   v_e1 = [-r_char_e1(1,:); 0,1] \setminus [0;1]; \% \text{ fix } v_2 \text{ to } 1
   v_e2 = [-r_char_e2(1,:); 0,1] \setminus [0;1]; \% \text{ fix } v_2 \text{ to } 1
42
43
  % Normalize v
44
   normalize = @(x) x/norm(x);
45
46
   v_e1_norm = normalize(v_e1);
47
   v_e2\_norm = normalize(v_e2);
48
49
```

98

```
disp("Eigenvalues: ")
   fprintf('\%1.4f\n', e(1));
51
   fprintf('\%1.4f\n', e(2));
52
53
   disp("Eigenvectors: ")
54
   disp(v_e1_norm);
55
   disp(v_e2_norm);
56
57
  %% Problem 2
58
  % Write a user-defined function to find eigenvalues. Use it to solve the
  % for the vibration frequencies and corresponding eigenvectors of an
  % acetylene molecule
61
   disp(" ");
62
   disp("Problem 2");
63
64
   amu = 1.6605 * 10^-27; \% [kg/amu]
65
                        \% [kg/s^2]
   k_ch = 592;
66
   k_{cc} = 1580;
                        \% [kg/s^2]
67
   m_h = 1*amu;
                        % [amu]
   m_c = 12*amu;
                        % [amu]
69
70
71
  % Matrix for amplitude vibrations
   coeff = [...]
73
       (k_ch/m_h)
                     -(k_ch/m_h)
                                         0
74
       -(k_ch/m_c)
                      (k_ch+k_cc)/m_c
                                          -(k_cc/m_c)
75
                          (k_ch+k_cc)/m_c
           -(k_cc/m_c)
                                               -(k_ch/m_c)
                -(k_ch/m_h) (k_ch/m_h)
       0
       ];
  % Get eigenvalues
   e = AllEig(coeff);
82
  % Handle machine error
83
   eround = round(e,5, 'significant');
   eround (4) = 0;
85
   omega = eround.(0.5);
   disp("Eigenvalues: ")
   for i=1:length (eround)
90
       disp(eround(i));
91
   end
92
93
   disp("Omega: ")
94
   for i=1:length(eround)
95
       disp(omega(i));
96
   end
97
```

```
99
   % Supporting functions
100
101
   function e = AllEig(A)
102
   % ALLEIG returns a vector of eigenvalues for a given matrix A (uses QR
103
   % factorization)
   % A - nxn matrix
105
   % e - vector of eigenvalues
106
107
   NUM_ITER = 1000; % TODO: add a convergence criteria
108
109
   [n, \tilde{z}] = size(A);
110
   I = eye(n);
111
112
   pQ = I;
113
   Anew = A;
    for iteration = 1:NUM_ITER
        % Seed QR
117
        Q = I;
        R = Anew;
119
        for i=1:n-1
121
            \% c vector
122
             c = R(:, i);
             c(1:i-1)=0;
124
            % e vector
126
             e1(1:n,1) = 0;
127
             if c(i) > 0
                  e1(i)=1;
129
             else
                  e1(i) = -1;
131
             end
132
             v = c + norm(c)*e1;
133
134
             % householder
135
            H = I - (2/(v'*v))*(v*v');
136
137
            % Iterate values
138
            Q = Q*H;
139
            R = H*R;
140
        end
141
142
        % New A
143
        Anew = R*Q;
144
        pQ \,=\, pQ*Q;
145
   end
146
147
```

```
^{148} % Get eigenvalues using Q and R ^{149} e=diag(Anew); ^{150} disp(pQ); ^{151} end
```