view_frames Result Recorded at time: 1508314395.431 map Broadcaster: /pose_integrator Average rate: 100.209 Hz Most recent transform: 1508314395.476 (-0.045 sec old) Buffer length: 4.850 sec odom Broadcaster: /hsrb/robot_hardware Broadcaster: /hsrb/robot_hardware Average rate: 62.286 Hz Average rate: 30.228 Hz Most recent transform: 1508314395.454 (-0.024 sec old) Most recent transform: 1508314395.454 (-0.024 sec old) Buffer length: 4.833 sec Buffer length: 4.830 sec base_footprint base_footprint_wheel Broadcaster: /hsrb/robot state/robot state pub Average rate: 100.196 Hz Most recent transform: 1508314395.971 (-0.540 sec old) Buffer length: 4.841 sec Broadcaster: /hsrb/robot_state/robot_state_pub Broadcaster: /hsrb/robot_state/robot_state_pub Broadcaster: /hsrb/robot_state/robot_state_pub Broadcaster: /hsrb/robot_state/robot_state_pub Broadcaster: /hsrb/robot_state/robot_state_pub Average rate: 100.196 Hz Average rate: 100.196 Hz Average rate: 41.869 Hz Average rate: 41.869 Hz Average rate: 41.869 Hz Most recent transform: 1508314395.428 (0.003 sec old) Most recent transform: 1508314395.971 (-0.540 sec old) | Most recent transform: 1508314395.971 (-0.540 sec old) Most recent transform: 1508314395.428 (0.003 sec old) Most recent transform: 1508314395.428 (0.003 sec old) Buffer length: 4.841 sec Buffer length: 4.841 sec Buffer length: 4.801 sec Buffer length: 4.801 sec Buffer length: 4.801 sec arm_lift_link base_roll_link base_range_sensor_link torso_lift_link base_imu_frame Broadcaster: /hsrb/robot_state/robot_state_pub Broadcaster: /hsrb/robot_state/robot_state_pub Broadcaster: /hsrb/robot_state/robot_state_pub Broadcaster: /hsrb/robot_state/robot_state_pub Broadcaster: /hsrb/robot_state/robot_state_pub Broadcaster: /hsrb/robot_state/robot_state_pub Average rate: 41.869 Hz Most recent transform: 1508314395.428 (0.003 sec old) /Most recent transform: 1508314395.428 (0.003 sec old) Buffer length: 4.801 sec base_l_passive_wheel_x_frame head_pan_link base_r_drive_wheel_link arm_flex_link base_l_drive_wheel_link base_r_passive_wheel_x_frame Broadcaster: /hsrb/robot state/robot state pub Broadcaster: /hsrb/robot_state/robot_state_pub Broadcaster: /hsrb/robot state/robot state pub Broadcaster: /hsrb/robot_state/robot_state_pub Average rate: 41.869 Hz Average rate: 41.869 Hz Average rate: 41.869 Hz Average rate: 41.869 Hz Most recent transform: 1508314395.428 (0.003 sec old) Buffer length: 4.801 sec Buffer length: 4.801 sec Buffer length: 4.801 sec Buffer length: 4.801 sec head_tilt_link arm_roll_link base_l_passive_wheel_y_frame base_r_passive_wheel_y_frame Broadcaster: /hsrb/robot_state/robot_state_pub Broadcaster: /hsrb/robot_state/robot_state_pub Broadcaster: /hsrb/robot_state/robot_state_pub Broadcaster: /hsrb/robot state/robot state pub Broadcaster: /hsrb/robot_state/robot_state_pub Broadcaster: /hsrb/robot_state/robot_state_pub Broadcaster: /hsrb/robot_state/robot_state_pub Average rate: 41.869 Hz Average rate: 100.196 Hz 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Broadcaster: /hsrb/robot_state/robot_state_pub Broadcaster: /hsrb/robot_state/robot_state_pub Average rate: 100.196 Hz Average rate: 41.869 Hz Average rate: 100.196 Hz Average rate: 100.196 Hz Average rate: 100.196 Hz Nost recent transform: 1508314395.971 (-0.540 sec old) Most recent transform: 1508314395.428 (0.003 sec old) Most recent transform: 1508314395.971 (-0.540 sec old) Most recent transform: 1508314395.971 (-0.540 sec old) Most recent transform: 1508314395.971 (-0.540 sec old) Buffer length: 4.801 sec Buffer length: 4.841 sec Buffer length: 4.841 sec Buffer length: 4.841 sec Buffer length: 4.841 sec wrist_roll_link head_l_stereo_camera_gazebo_frame head_r_stereo_camera_gazebo_frame head_rgbd_sensor_gazebo_frame head_center_camera_gazebo_frame Broadcaster: /hsrb/robot_state/robot_state_pub Broadcaster: /hsrb/robot_state/robot_state_pub Average rate: 100.196 Hz Average rate: 100.196 Hz Buffer length: 4.841 sec Buffer length: 4.841 sec hand_palm_link wrist_ft_sensor_frame Broadcaster: /hsrb/robot_state/robot_state_pub Broadcaster: /hsrb/robot_state/robot_state_pub Broadcaster: /hsrb/robot_state/robot_state_pub Broadcaster: /hsrb/robot_state/robot_state_pub Average rate: 100.195 Hz Average rate: 41.869 Hz Average rate: 41.869 Hz Average rate: 41.869 Hz Most recent transform: 1508314395.971 (-0.540 sec old) | Most recent transform: 1508314395.428 (0.003 sec old) Most recent transform: 1508314395.428 (0.003 sec old) Most recent transform: 1508314395.428 (0.003 sec old) Buffer length: 4.841 sec Buffer length: 4.801 sec Buffer length: 4.801 sec Buffer length: 4.801 sec hand_camera_frame hand_l_proximal_link hand_motor_dummy_link hand_r_proximal_link Broadcaster: /hsrb/robot_state/robot_state_pub Broadcaster: /hsrb/robot_state/robot_state_pub Broadcaster: /hsrb/robot_state/robot_state_pub Average rate: 41.869 Hz Average rate: 41.869 Hz Average rate: 100.195 Hz Most recent transform: 1508314395.971 (-0.540 sec old) Most recent transform: 1508314395.428 (0.003 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Broadcaster: /hsrb/robot_state/robot_state_pub Average rate: 100.195 Hz Average rate: 100.196 Hz Average rate: 100.196 Hz Most recent transform: 1508314395.971 (-0.540 sec old) Most recent transform: 1508314395.971 (-0.540 sec old) Most recent transform: 1508314395.971 (-0.540 sec old) Buffer length: 4.841 sec Buffer length: 4.841 sec Buffer length: 4.841 sec hand_l_finger_vacuum_frame hand_r_finger_tip_frame hand_l_finger_tip_frame