

# Transformers, I

LING 575K Deep Learning for NLP

Shane Steinert-Threlkeld

April 28 2021

# Announcements

- HW3 grades posted
- HW4: use floating-point numbers for bag-of-words counts, e.g.
  - NOT [1, 0, 0, 3], but [1.0, 0.0, 0.0, 3.0]
- Patas
  - condor\_q + held jobs
  - Output log file! [empty = patas is too busy, otherwise there should be info]

# Today's Plan

- Attention
- Limitations of Recurrent Models
- Transformers: building blocks
  - Self-attention
  - Encoder architecture

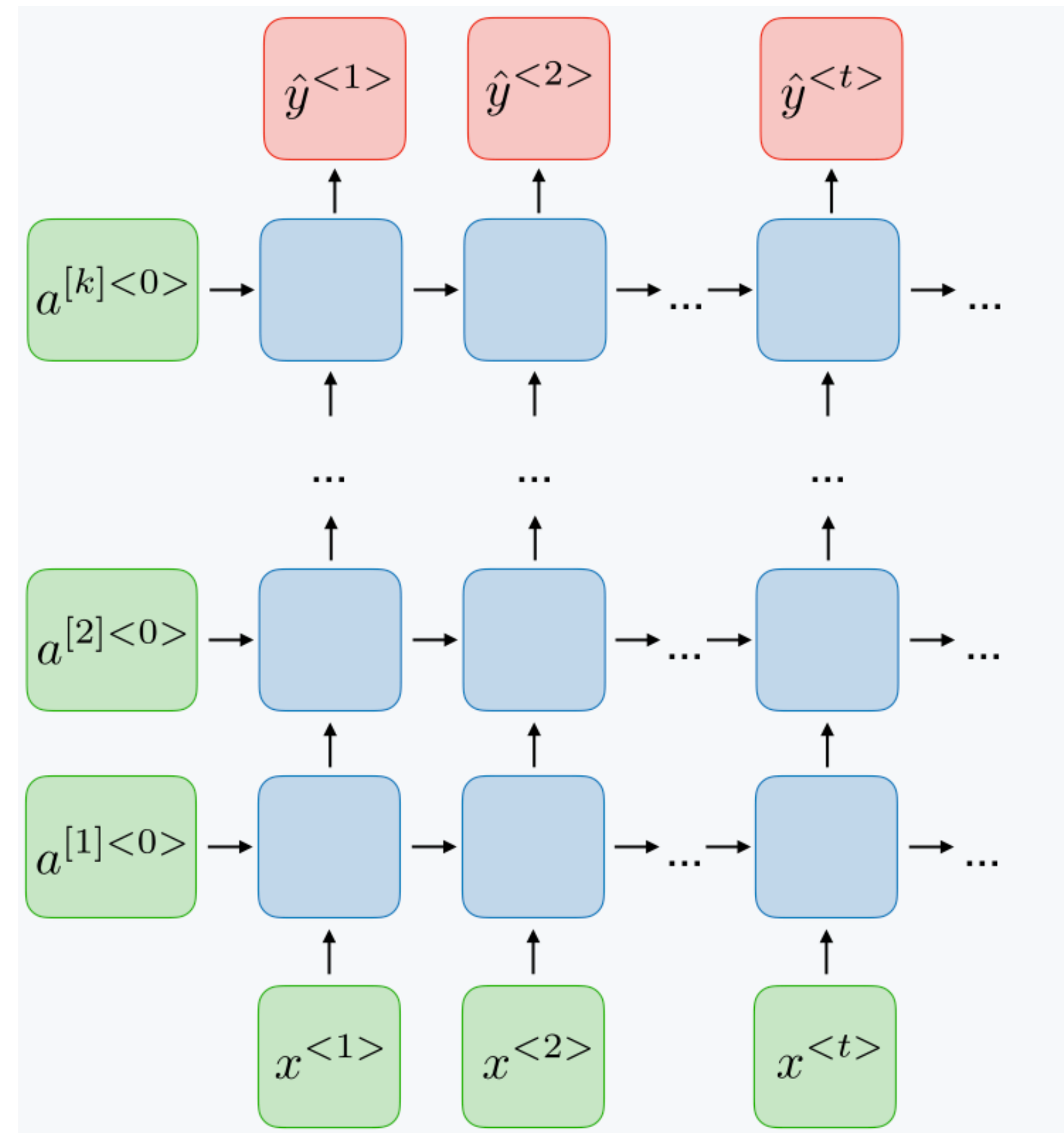
# Limitations of Recurrent Models

# RNNs Unrolling

- Recall: RNNs are “unrolled” across time, same operation at each step
- This has at least two issues:
  - Creates “long path lengths” between sequence positions
  - Not parallelizable

# Long Path Lengths

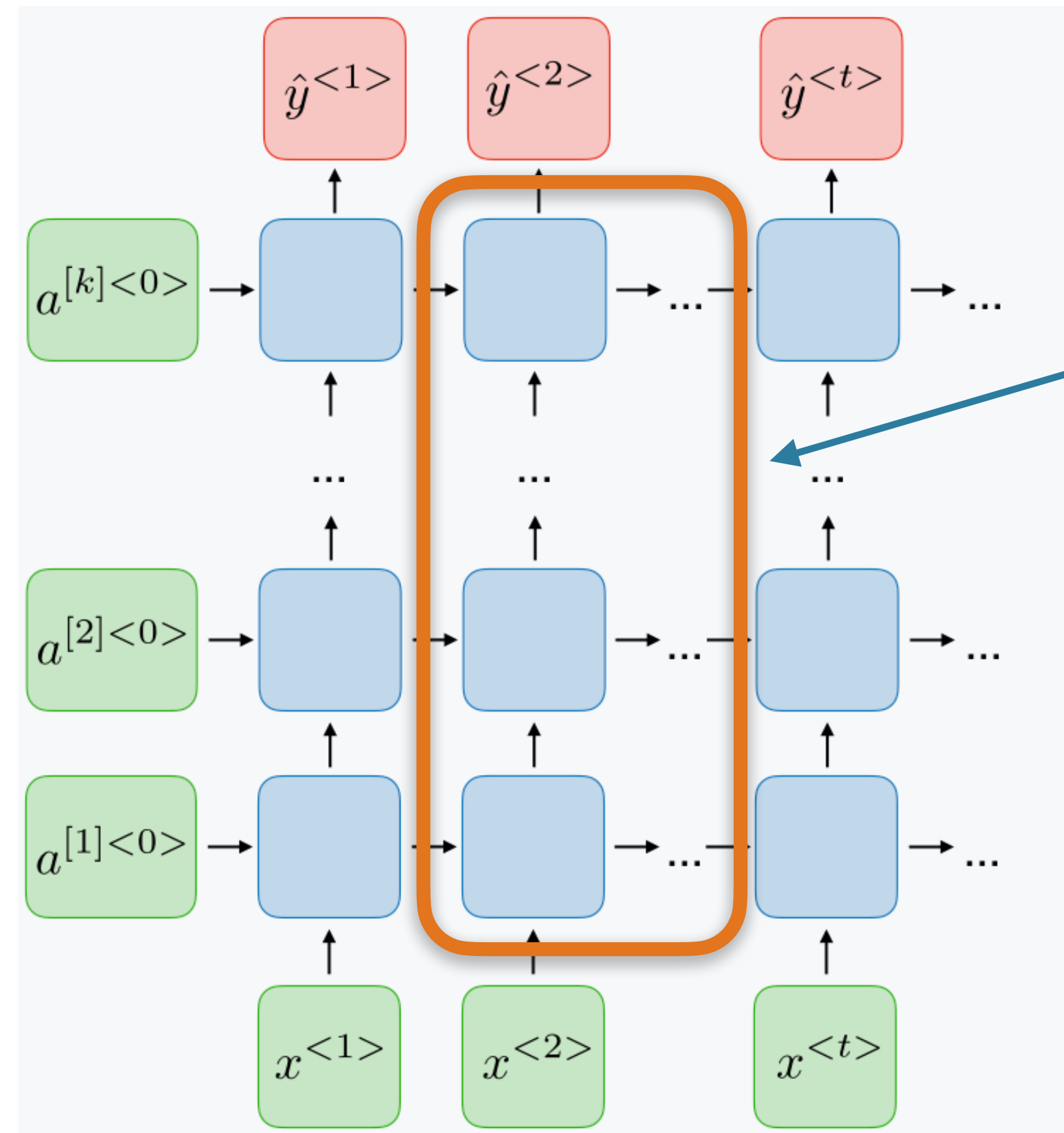
- Gating mechanisms help RNNs learn long distance dependencies, by alleviating the vanishing gradient problem
- But: still takes a linear number of computations for one token to influence another
- Long-distance dependencies are still hard!



Students who ... enjoy

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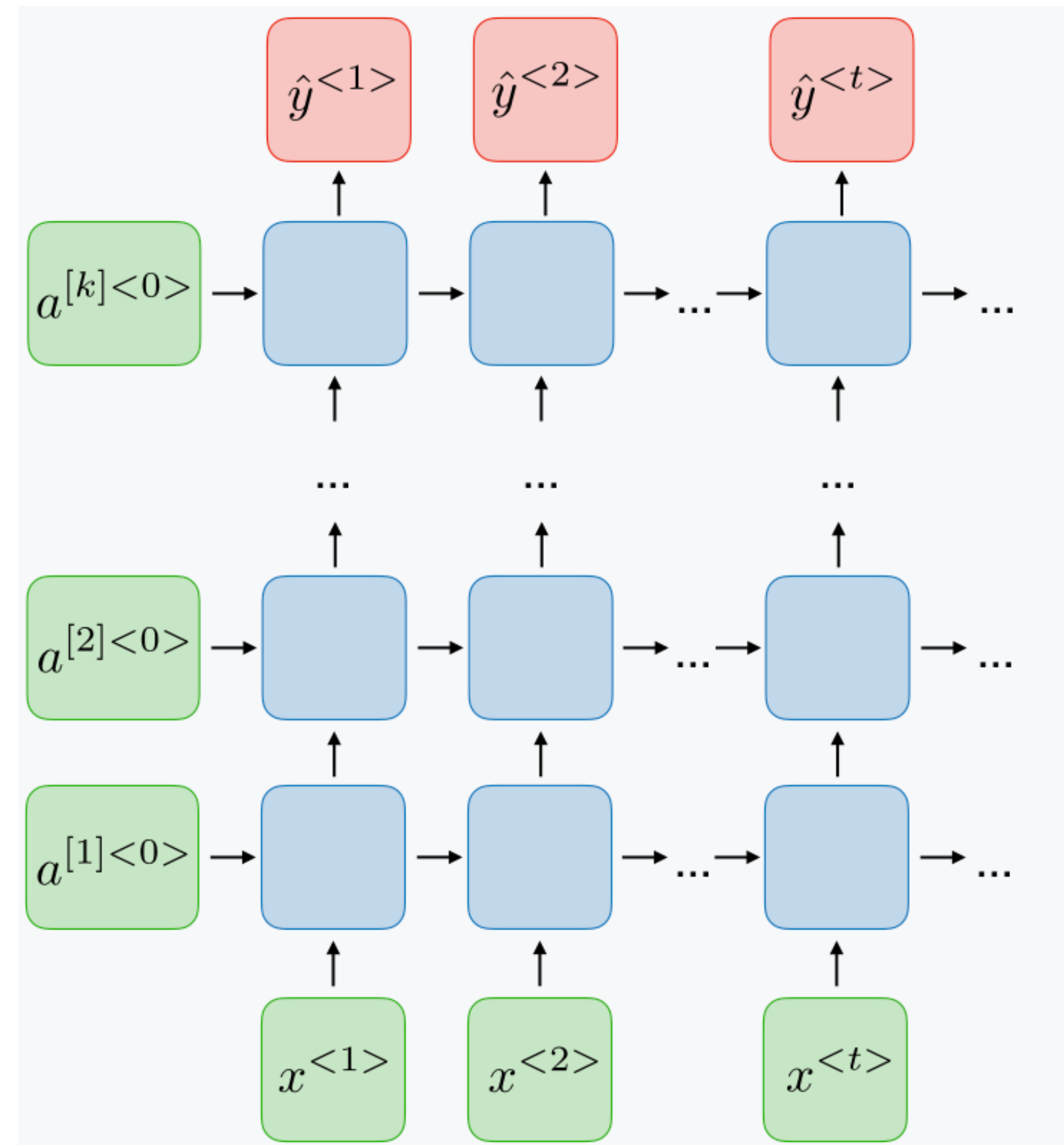
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# Lack of Parallelizability

- Modern hardware (e.g. GPUs) are very good at doing *independent* computations in parallel
- RNNs are inherently serial:
  - Cannot compute future time steps without the past
- Bottleneck that makes scaling up difficult

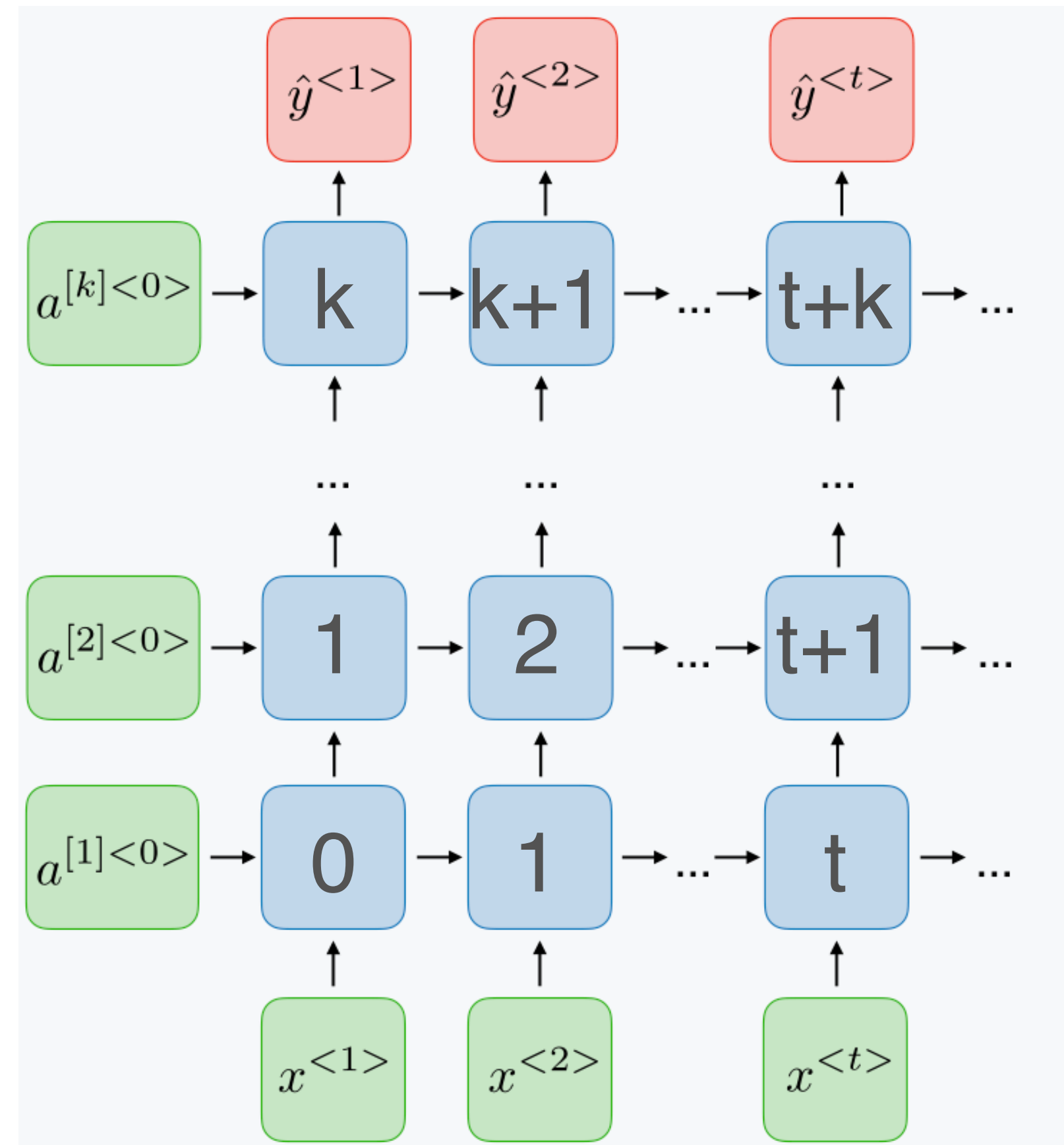


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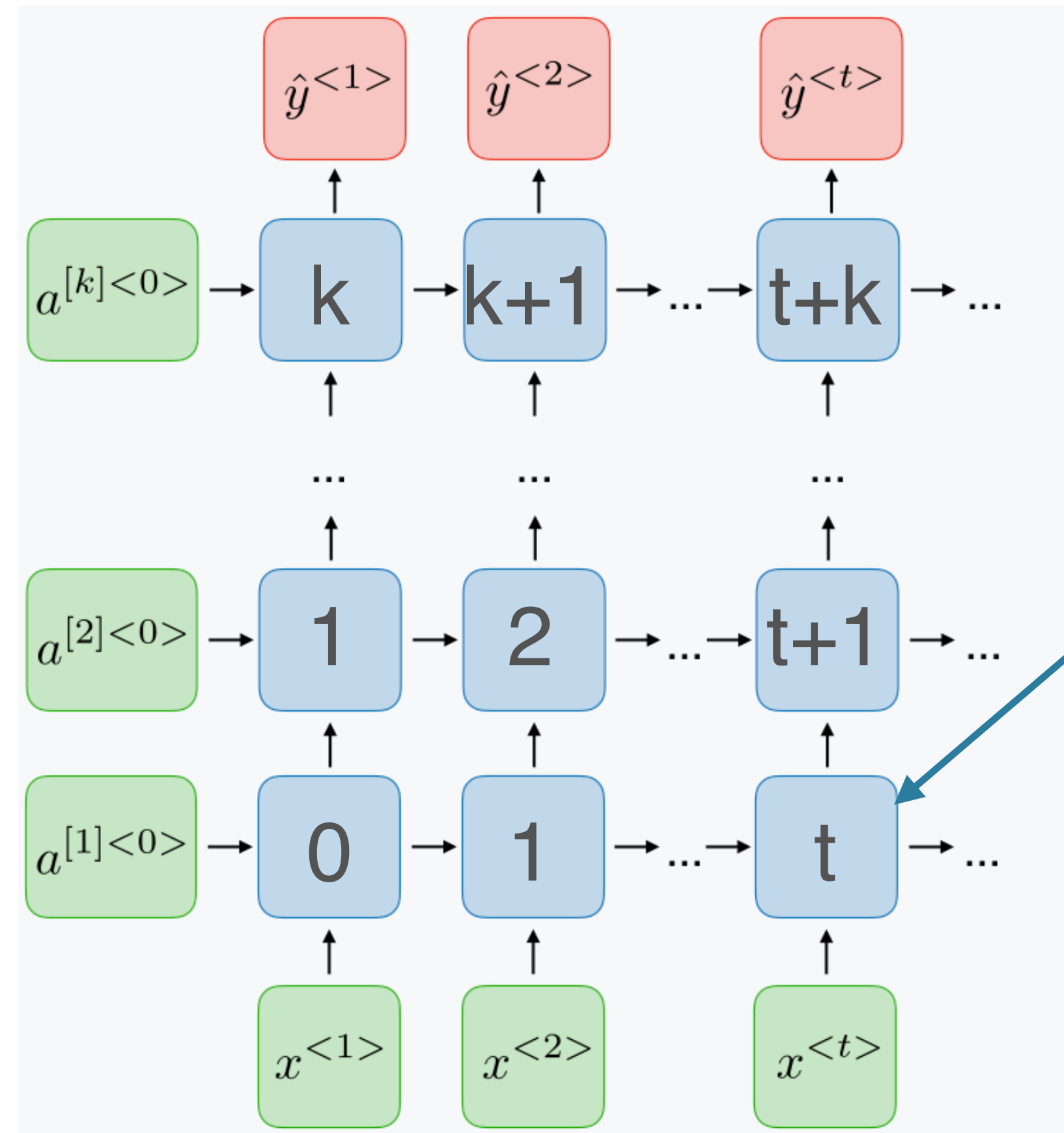
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Number of computation steps required: linear in sequence length

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# Transformer Architecture

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# Attention Is All You Need

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**Illia Polosukhin\*<sup>‡</sup>**  
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[Paper link](#)

(but see [Annotated](#) and [Illustrated](#) Transformer)

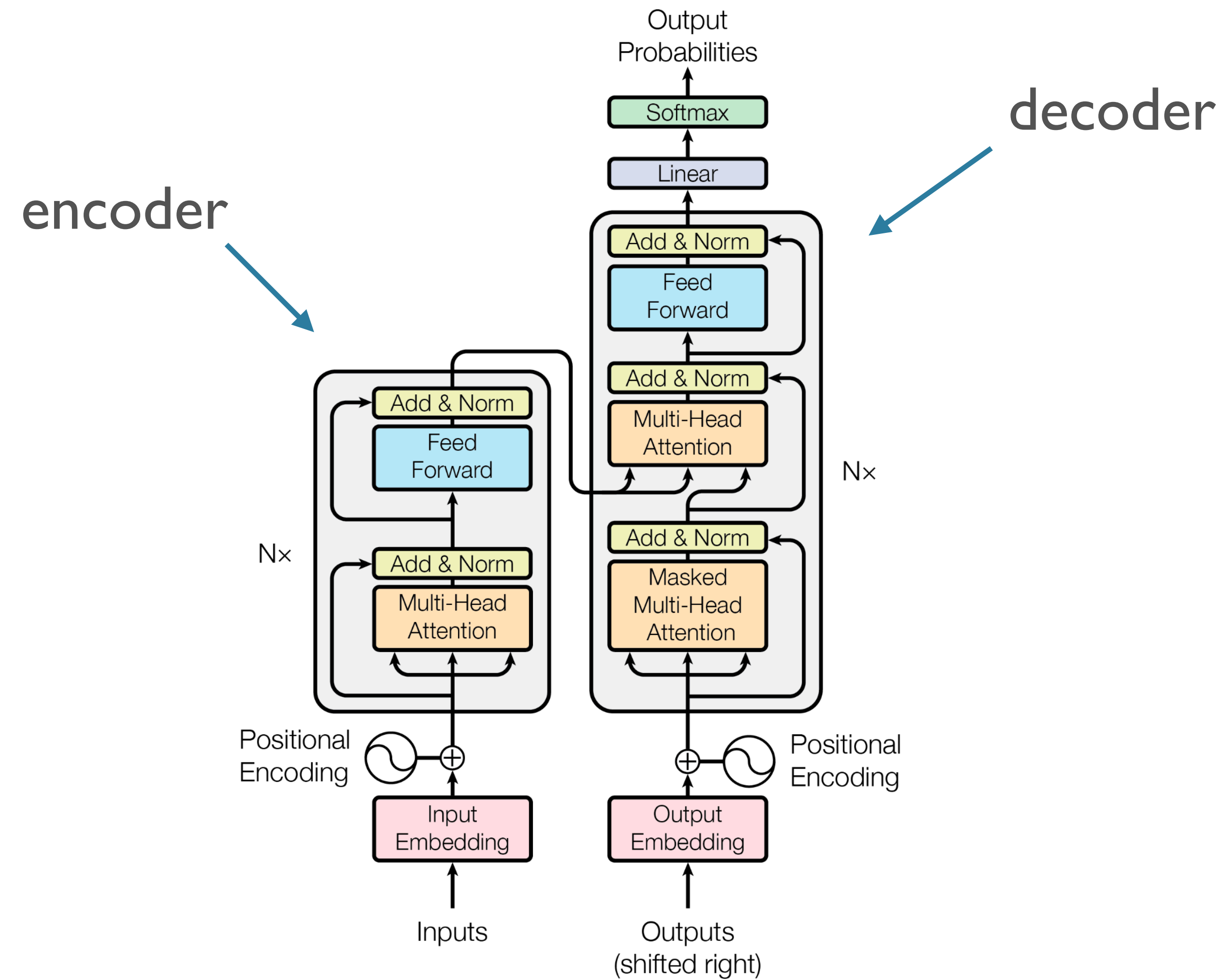
## Abstract

The dominant sequence transduction models are based on complex recurrent or convolutional neural networks that include an encoder and a decoder. The best performing models also connect the encoder and decoder through an attention mechanism. We propose a new simple network architecture, the Transformer, based solely on attention mechanisms, dispensing with recurrence and convolutions entirely. Experiments on two machine translation tasks show these models to be superior in quality while being more parallelizable and requiring significantly less time to train. Our model achieves 28.4 BLEU on the WMT 2014 English-to-German translation task, improving over the existing best results, including ensembles, by over 2 BLEU. On the WMT 2014 English-to-French translation task, our model establishes a new single-model state-of-the-art BLEU score of 41.0 after training for 3.5 days on eight GPUs, a small fraction of the training costs of the best models from the literature.

# Key Idea

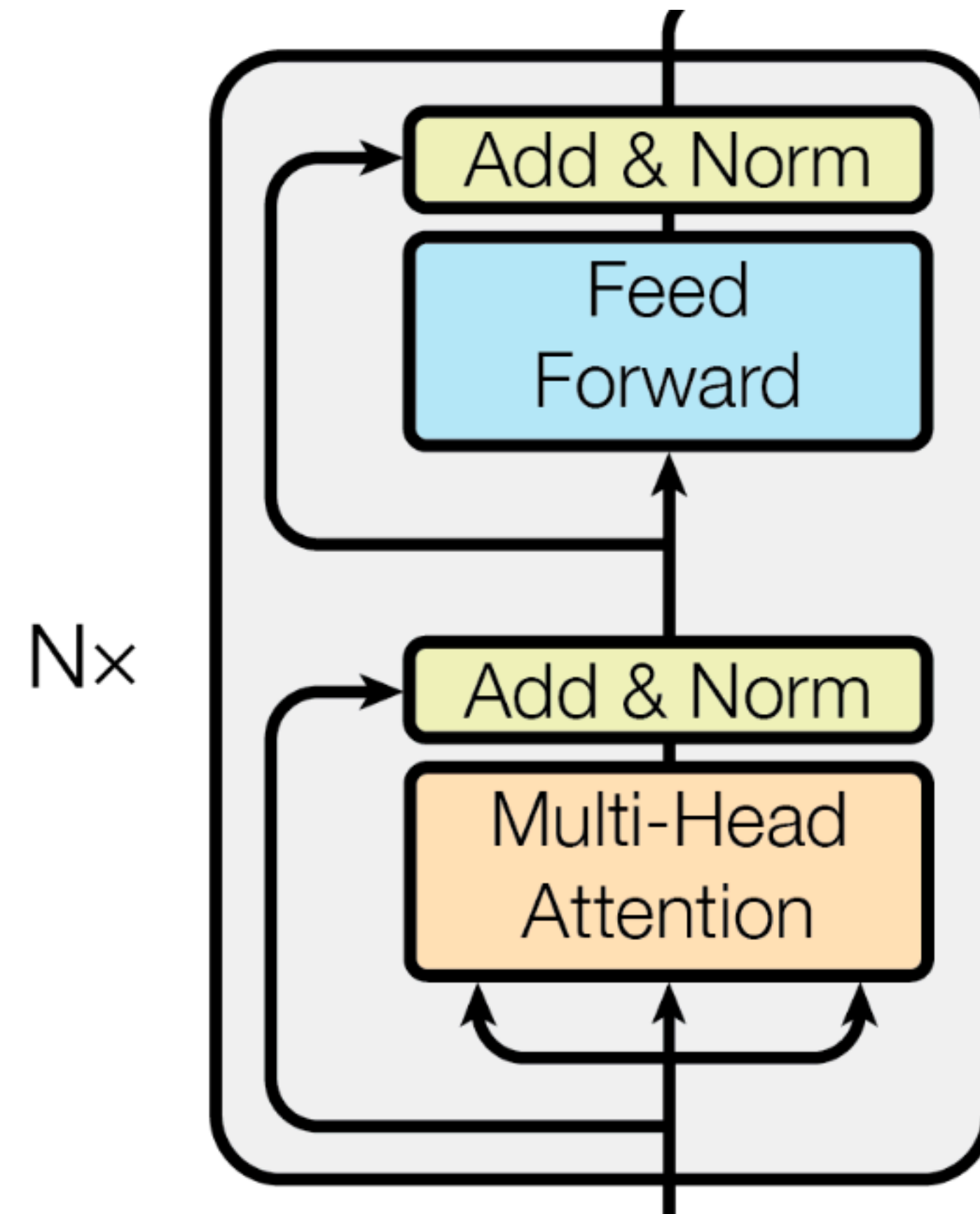
- Recurrence: not parallelizable, long “path lengths”
- *Attention*:
  - Parallelizable, short path lengths
- Transformer: “replace” recurrence with attention mechanism
  - Subtle issues in making this work, which we we will see

# Full Model

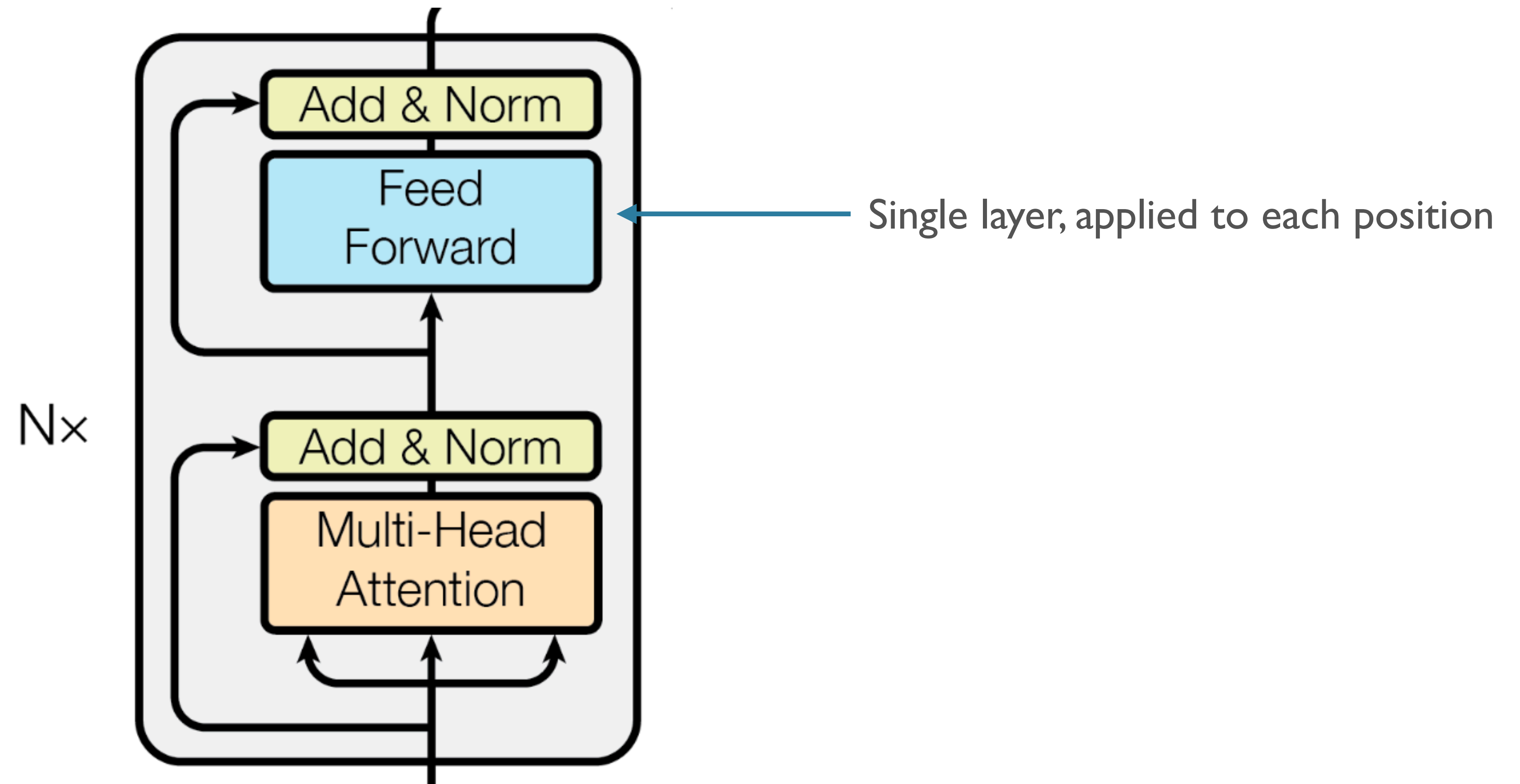




# Transformer Block

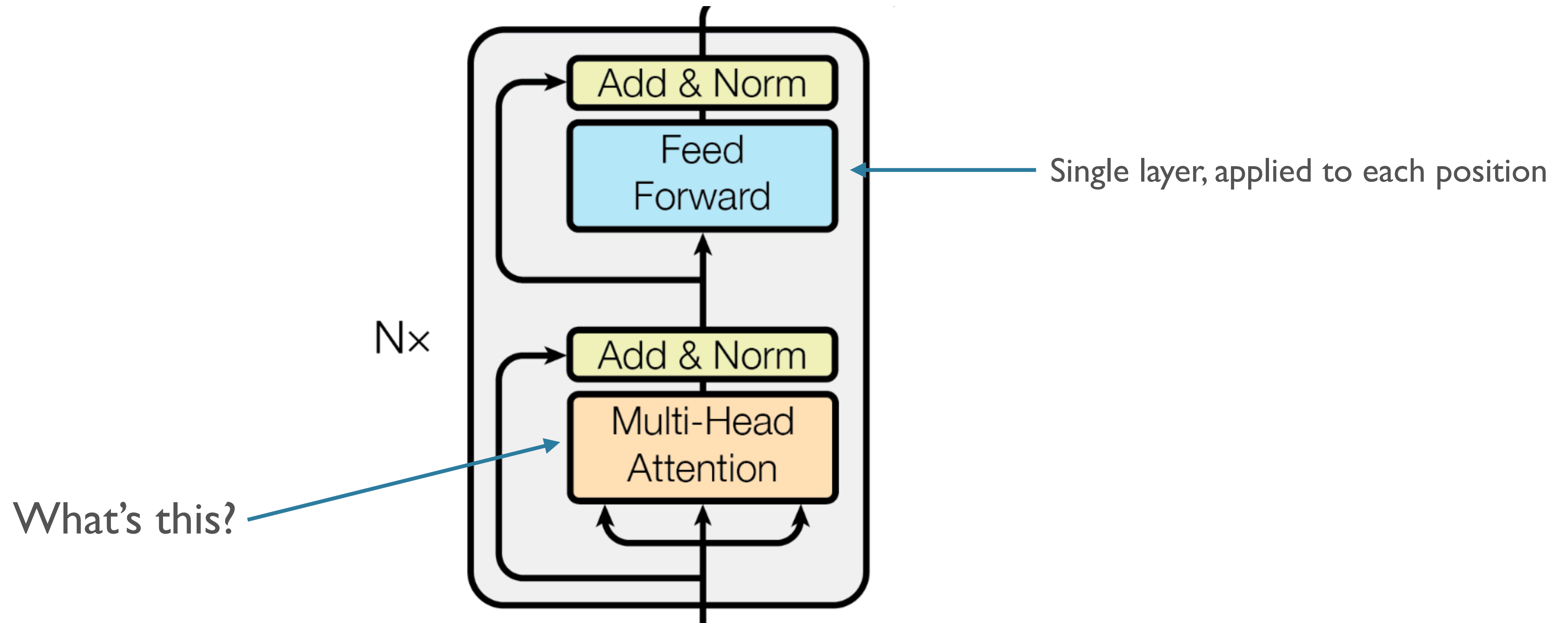


# Transformer Block





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# Scaled Dot-Product Attention

- Recall:

- Putting it together:  
(keys/values in matrices)

$$\text{Attention}(q, K, V) = \sum_j \frac{e^{q \cdot k_j}}{\sum_i e^{q \cdot k_i}} v_j$$

- Stacking *multiple* queries:  
(and scaling)

$$\text{Attention}(Q, K, V) = \text{softmax} \left( \frac{QK^T}{\sqrt{d_k}} \right) V$$

# Scaled Dot-Product Attention

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$$\alpha_j = q \cdot k_j$$

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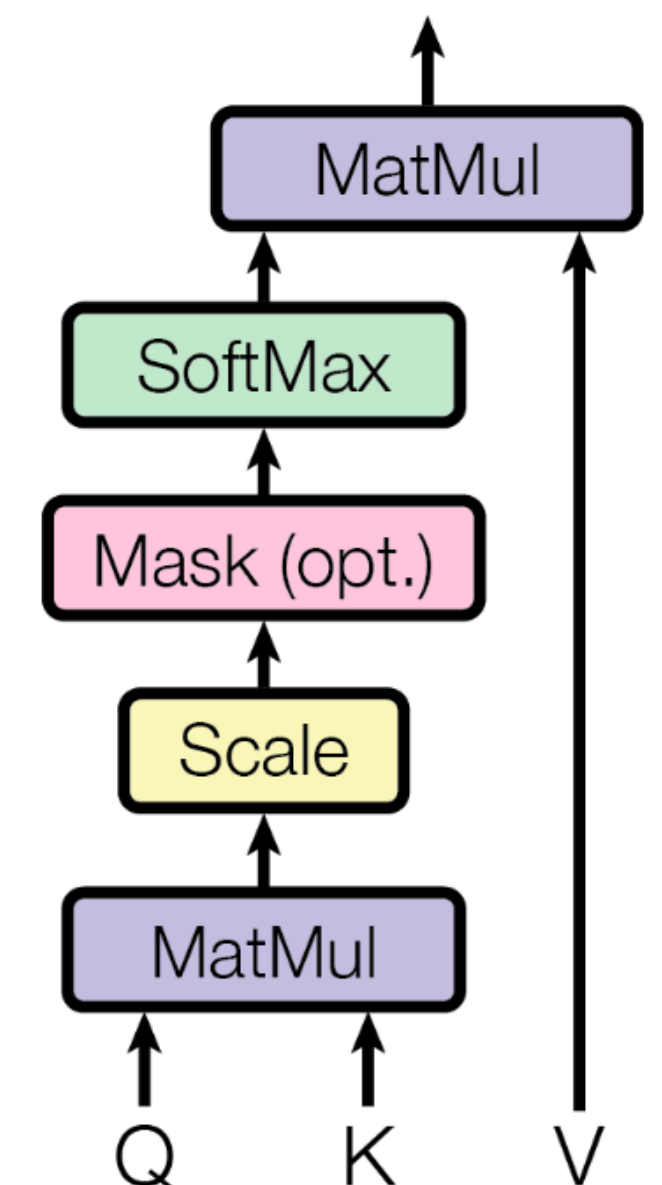
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- Transformer: *self*-attention
  - Every (token) position attends to every other position [including self!]
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    - Used for generation [NMT, LM, etc]
- So vector at each position is a query
  - And a key, and a value
  - Linearly transformed, to be different “views”



# Self-Attention, Details

- Every token attends to every other token
- $X$ : [seq\_len, embedding\_dim]
  - $XW_q$ : queries
  - $XW_k$ : keys
  - $XW_v$ : values
- Each  $W$  is [embedding\_dim, embedding\_dim] learned matrix

# Self-Attention: Details

$$\text{Attention}(Q, K, V) = \text{softmax} \left( \frac{QK^T}{\sqrt{d_k}} \right) V$$

- $Q = XW_q$ ,  $K = XW_k$ ,  $V = XW_v$ 
  - $K^T$ : [embedding\_dim, seq\_len]
  - $QK^T$ : [seq\_len, seq\_len]
    - Dot-product of rows of Q with columns of K
    - $(QK^T)_{ij} = q_i \cdot k_j$
- Scaled by sq-rt of hidden dimension [see paper for motivation]
- Softmax: along *rows*, gets the weights

# Self-Attention: Details

$$\text{Attention}(Q, K, V) = \text{softmax} \left( \frac{QK^T}{\sqrt{d_k}} \right) V$$

- Softmax output: each row has weights
  - How much  $q_i$  should pay attention to each  $v_j$
- Matrix multiplication with  $V$ : output is [seq\_len, embedding\_dim]
  - Each row: weighted average of the  $v_j$  (rows of  $V$ )
  - Each row: the weight sum attention value for each query (each input token)
- [NB: a more explicit notation, if you like: <https://namedtensor.github.io/>]

# Multi-headed Attention

- So far: a *single* attention mechanism.
- Could be a bottleneck: need to pay attention to different vectors *for different reasons*
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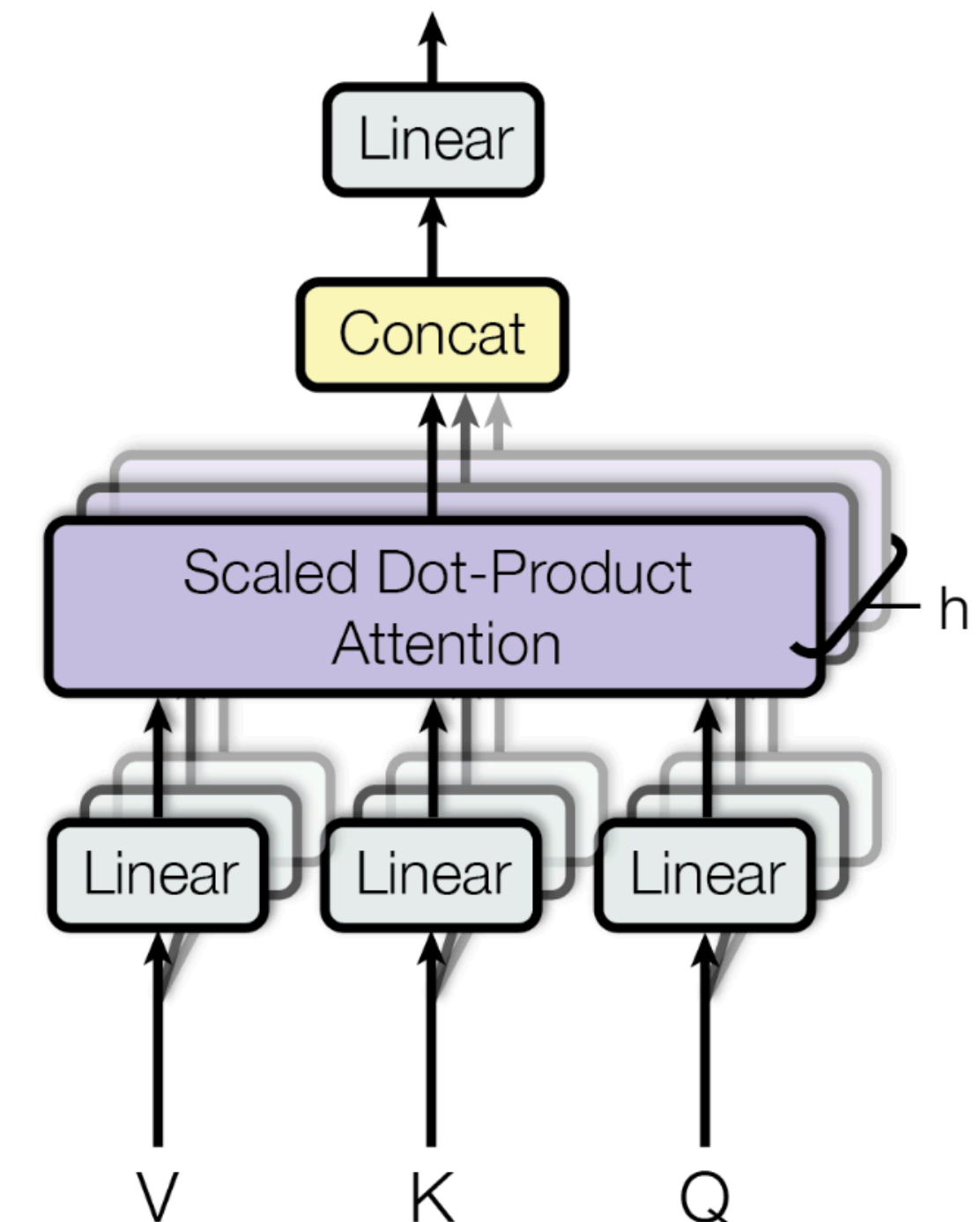
where  $\text{head}_i = \text{Attention}(QW_i^Q, KW_i^K, VW_i^V)$

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# Problem With Self-Attention

- Attention is order-independent
  - If we shuffle  $Q$ ,  $K$ ,  $V$ , we get the same output!

# Representing Order

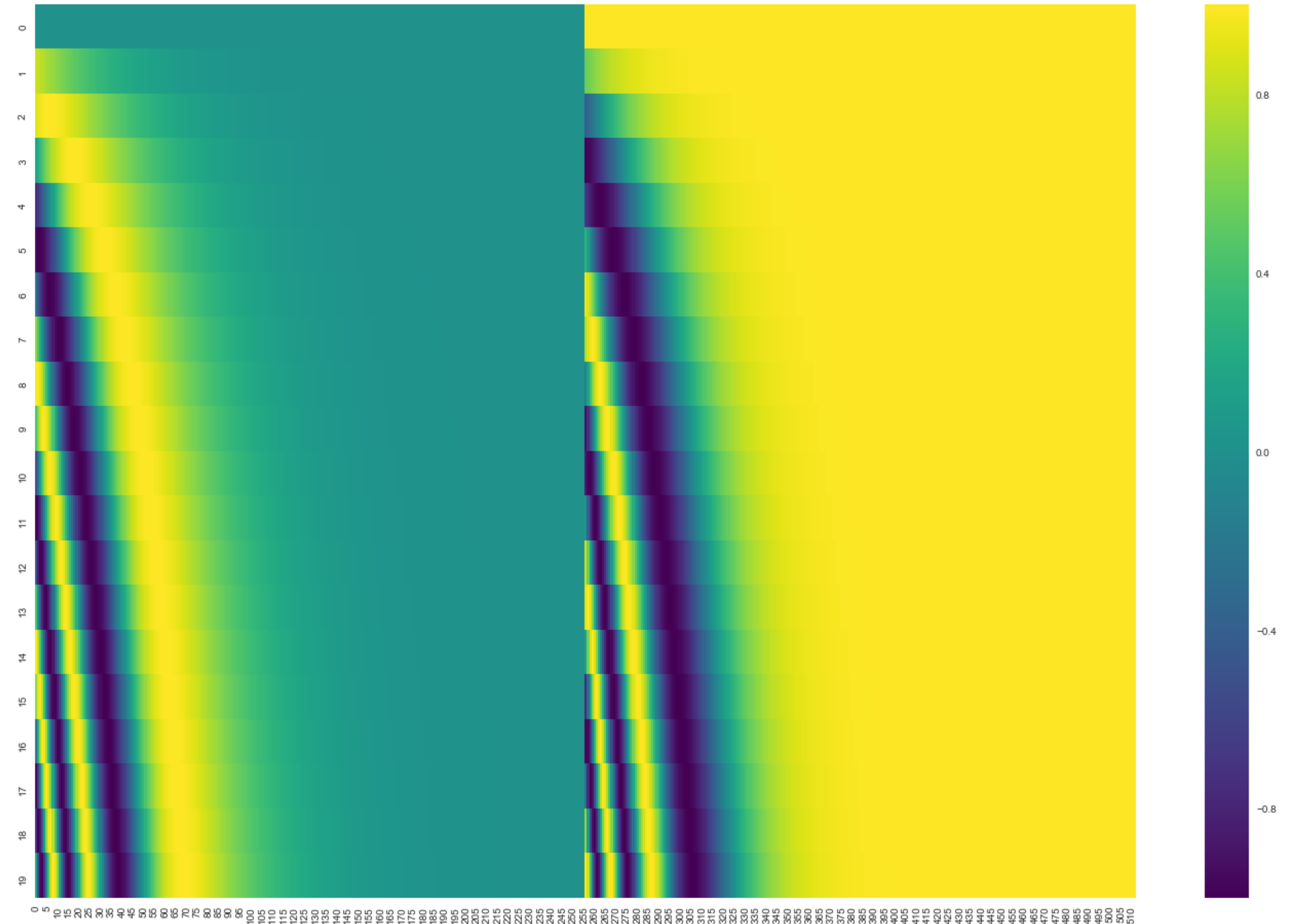


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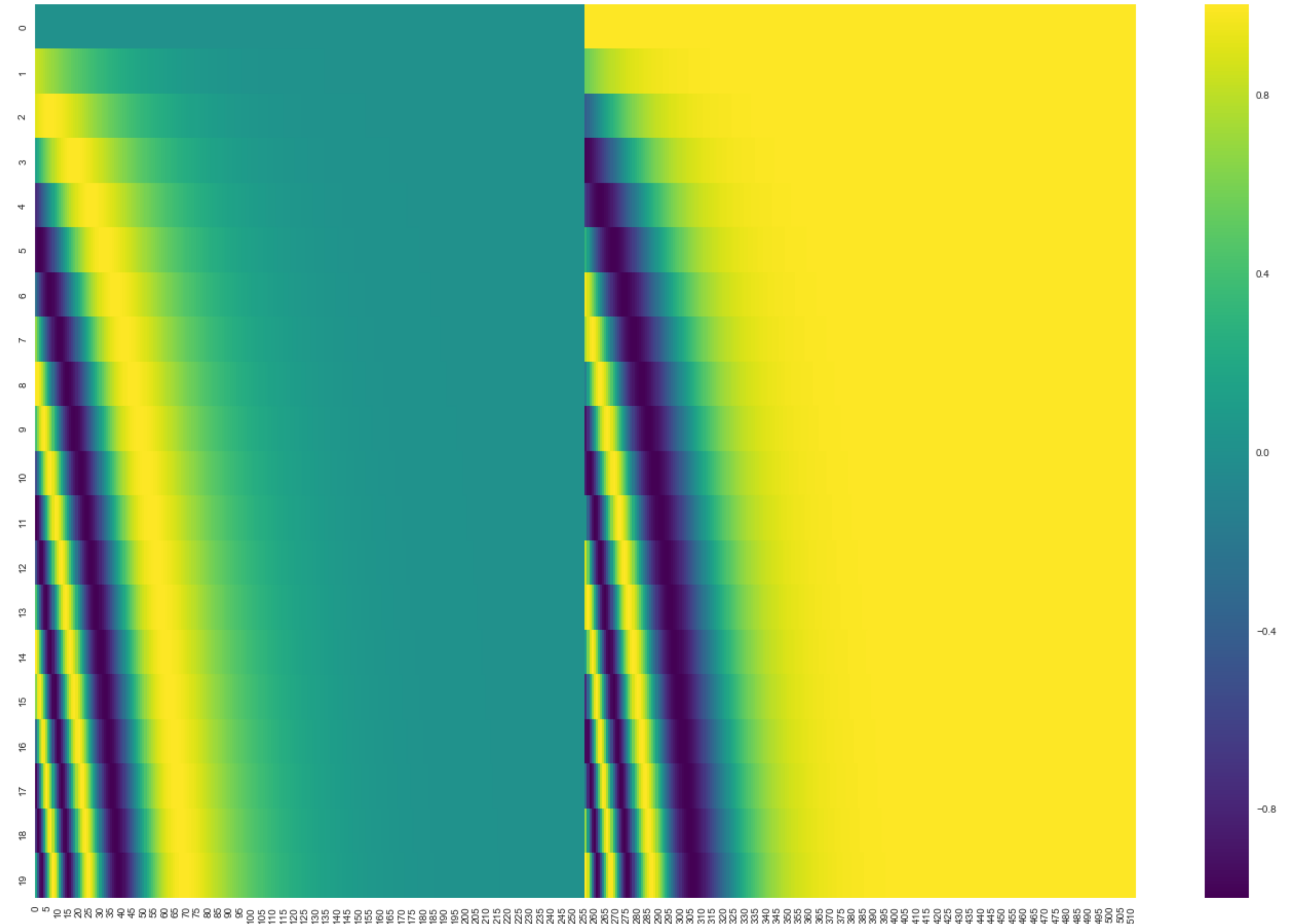
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[source](#)

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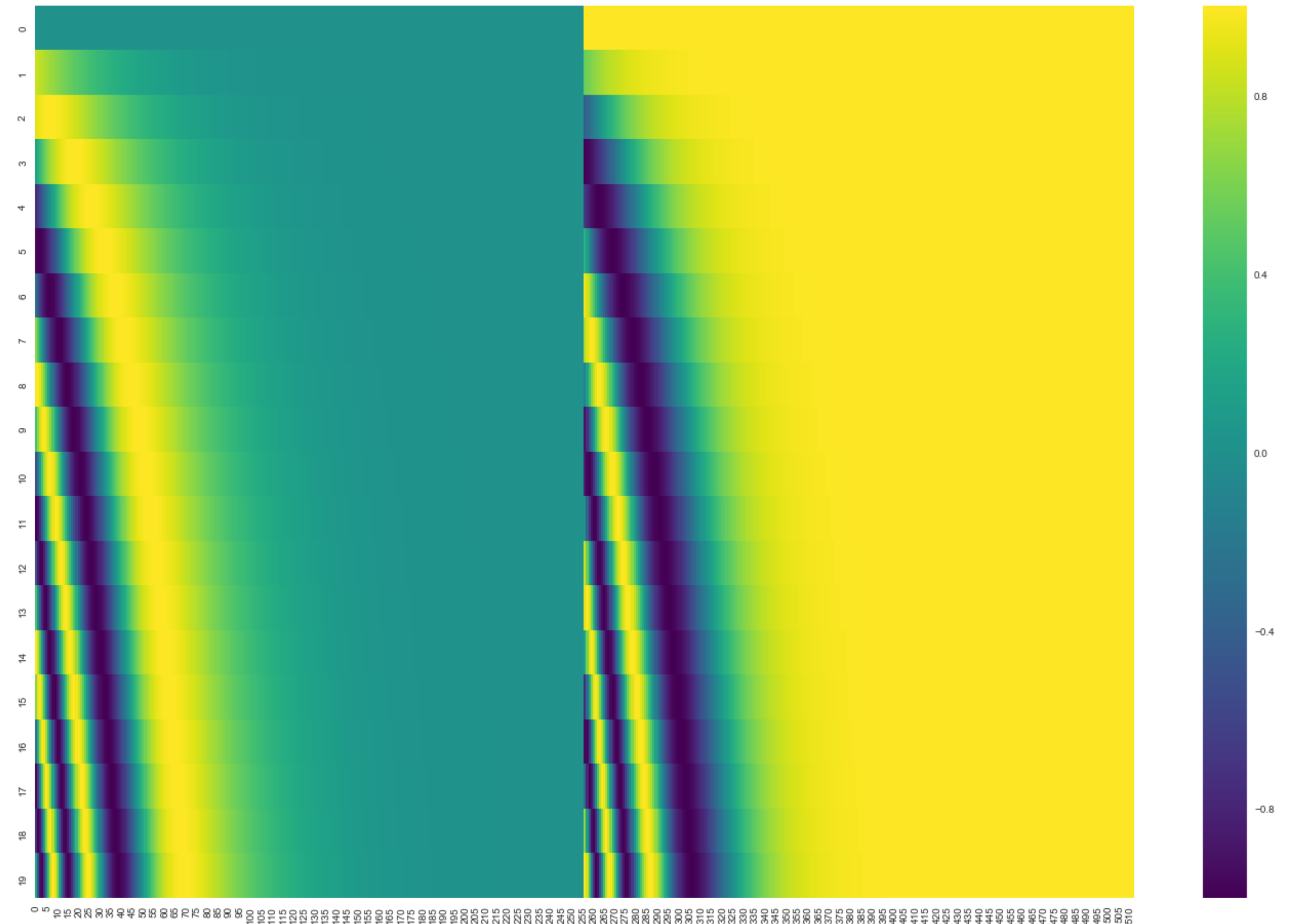
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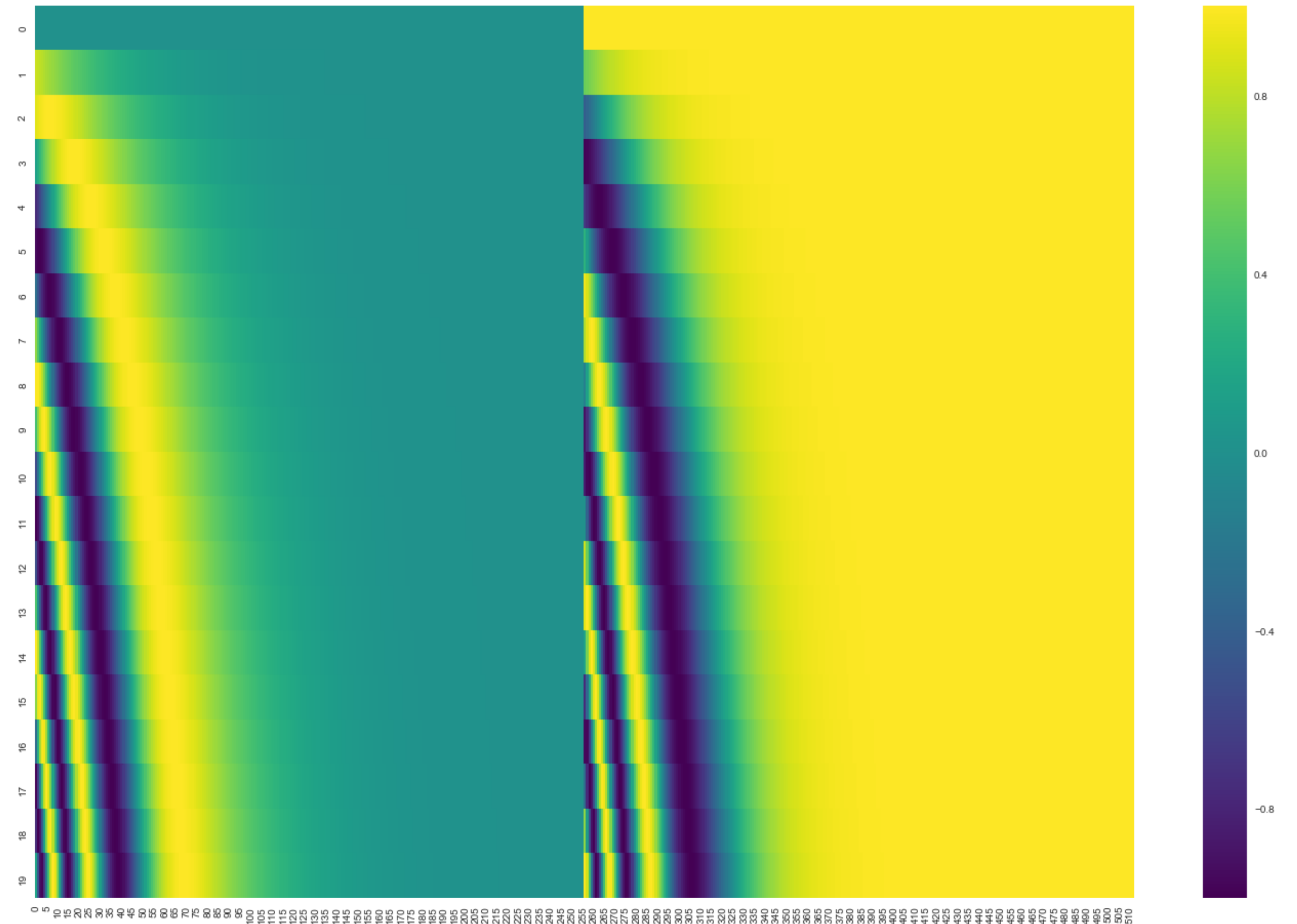
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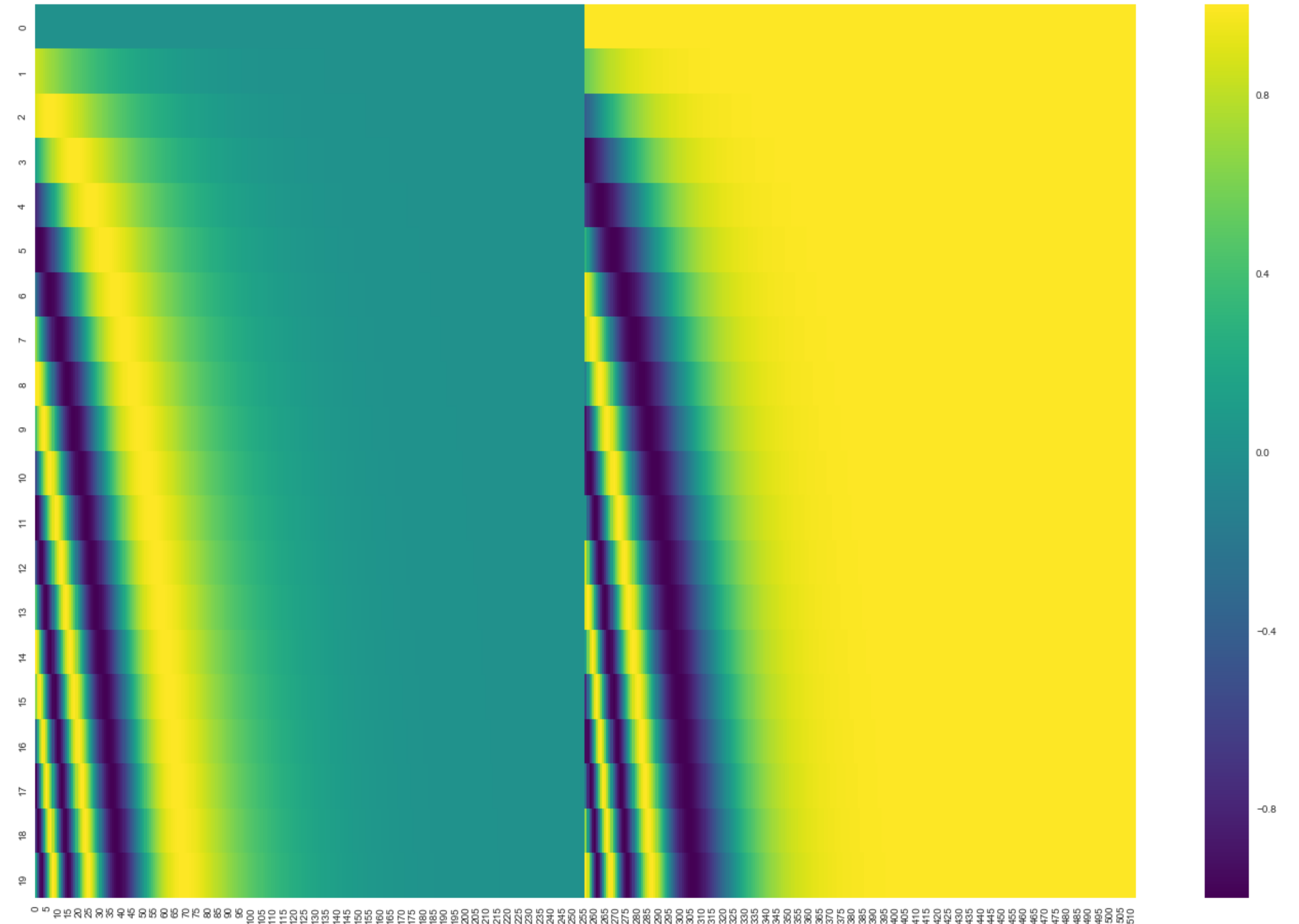
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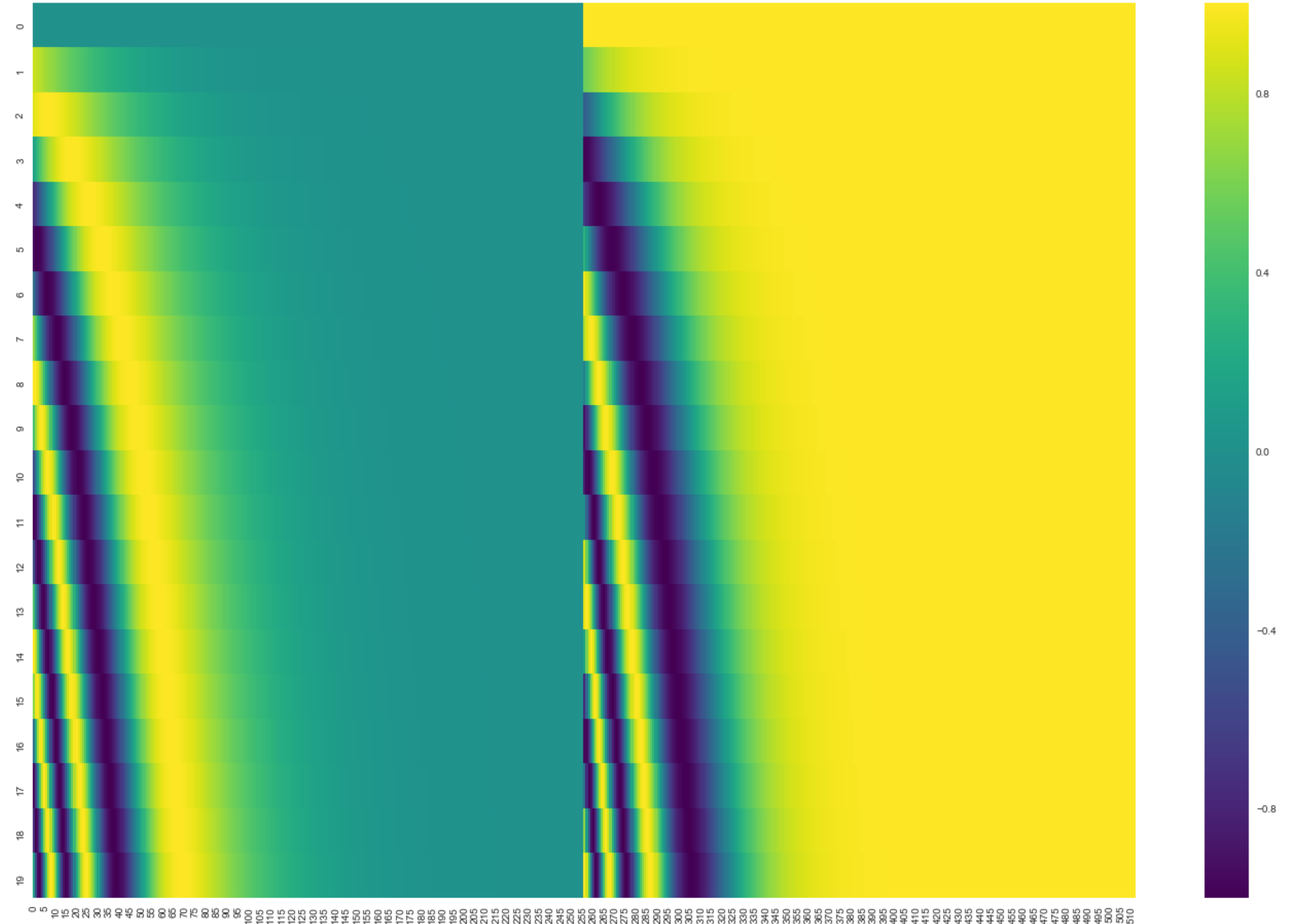
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- Can be fixed/pre-defined [see right] or entirely learned



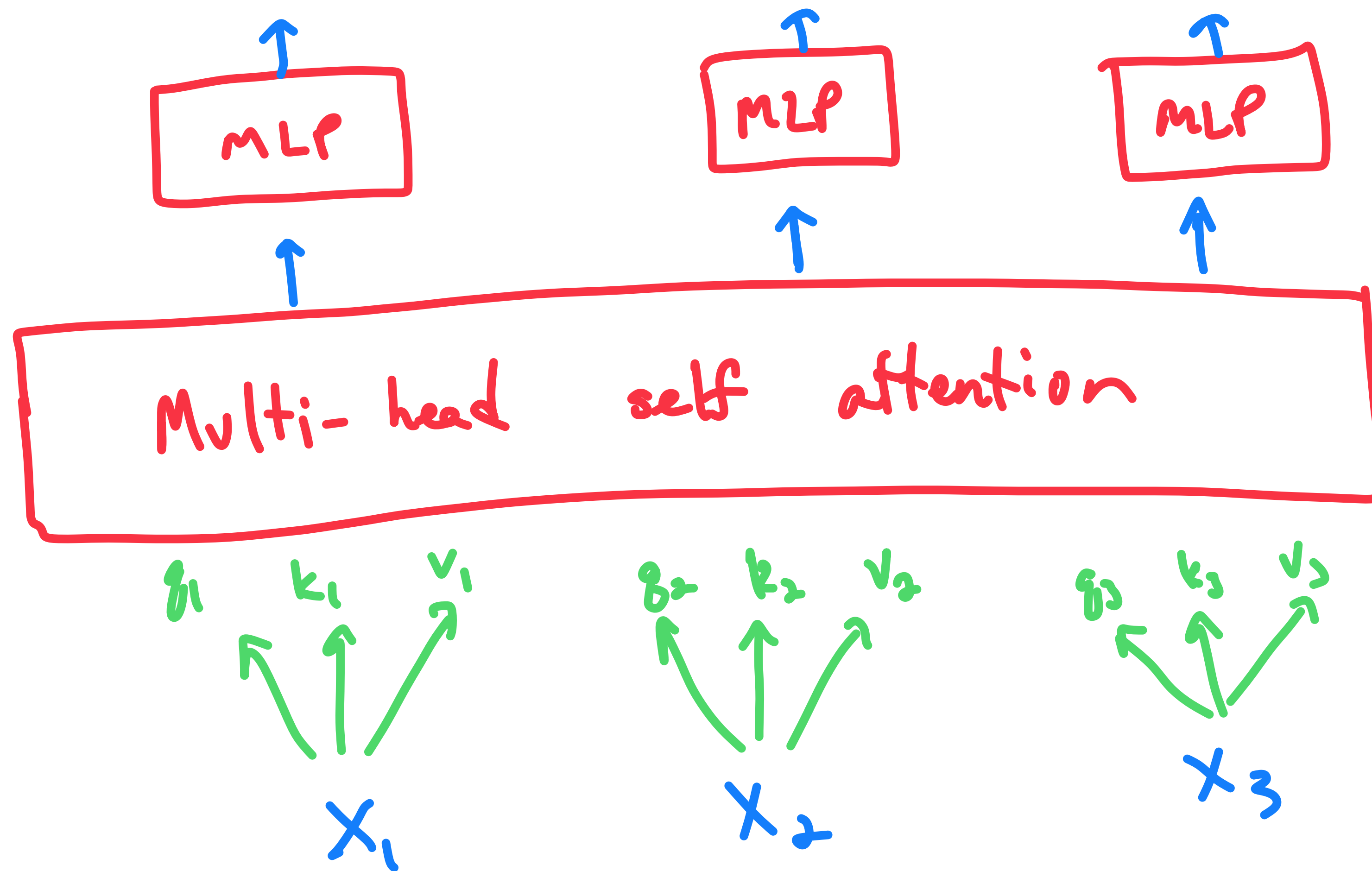
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# Fixed vs Learned Positional Encoding

- Fixed:
  - No need to be learned
  - Guaranteed to be unique to position
  - Generalizes to longer sequence lengths
- Learned:
  - Might learn more useful encodings of position than e.g. sinusoidal
  - Can't extrapolate to longer sequence lengths
  - [This has become the norm]



# Basic Transformer Encoder Block

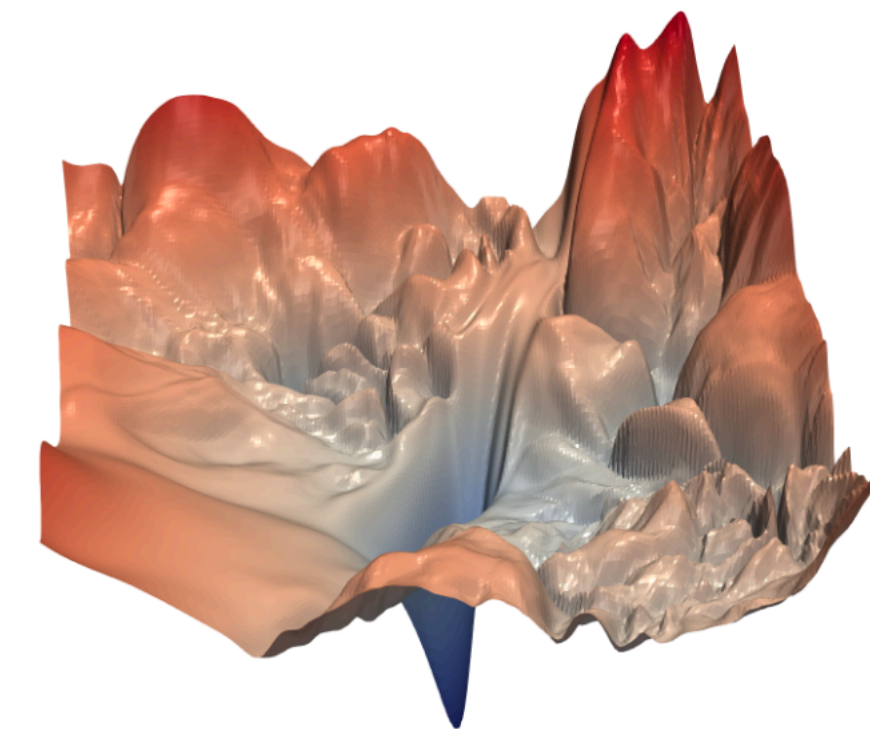
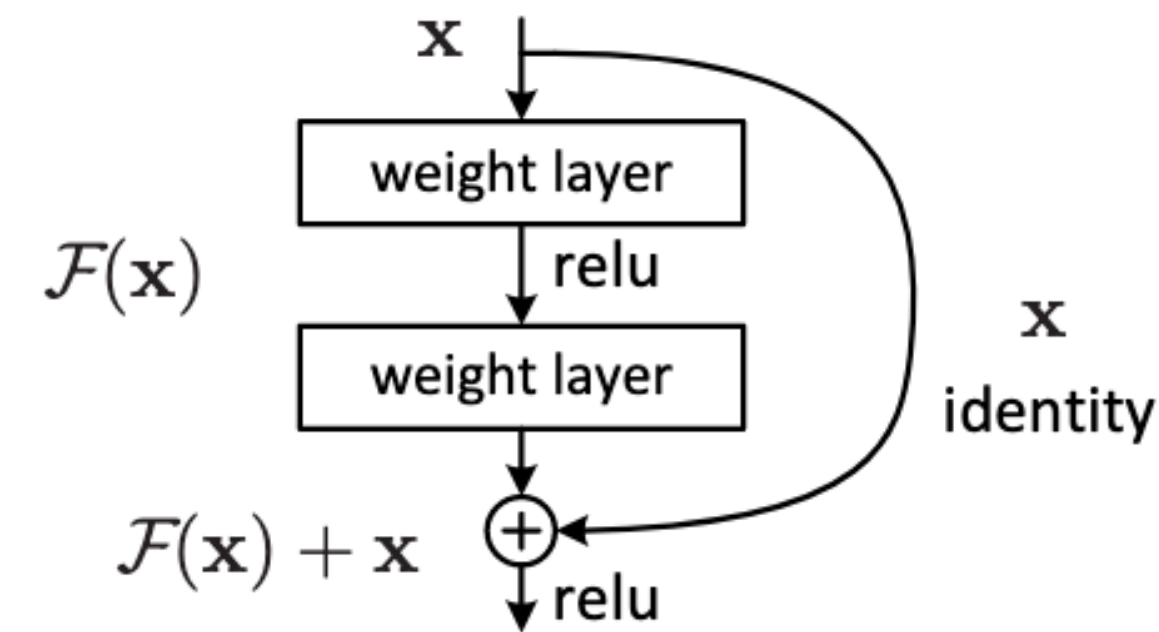


} same MLP applied at each position

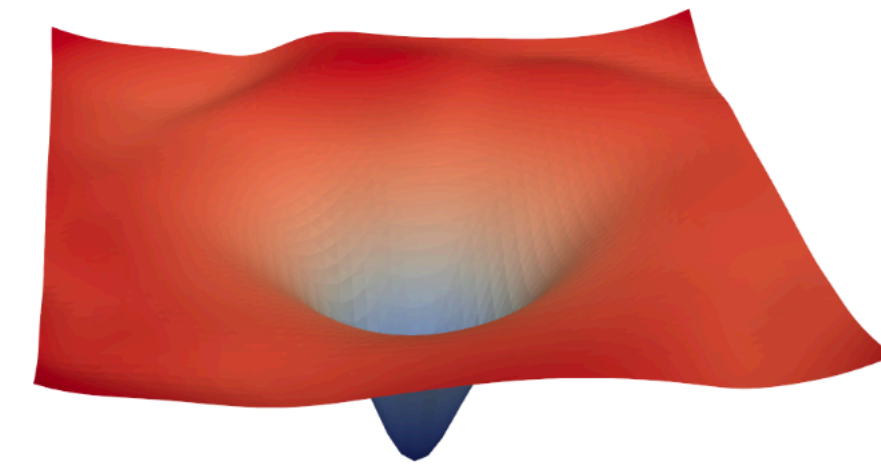
} shared  $w_q, w_k, w_v$

# Final Ingredients: Residual Connections

- Core idea: add a “skip” connection around neural building blocks
- Replace  $f(x)$  with  $x + f(x)$
- Makes training work much better, by smoothing out loss surface
- In Transformer: residual connection around both self-attention and feed-forward blocks
- Used widely now: FFNNs, CNNs, RNNs, Transformers, ...



(a) without skip connections



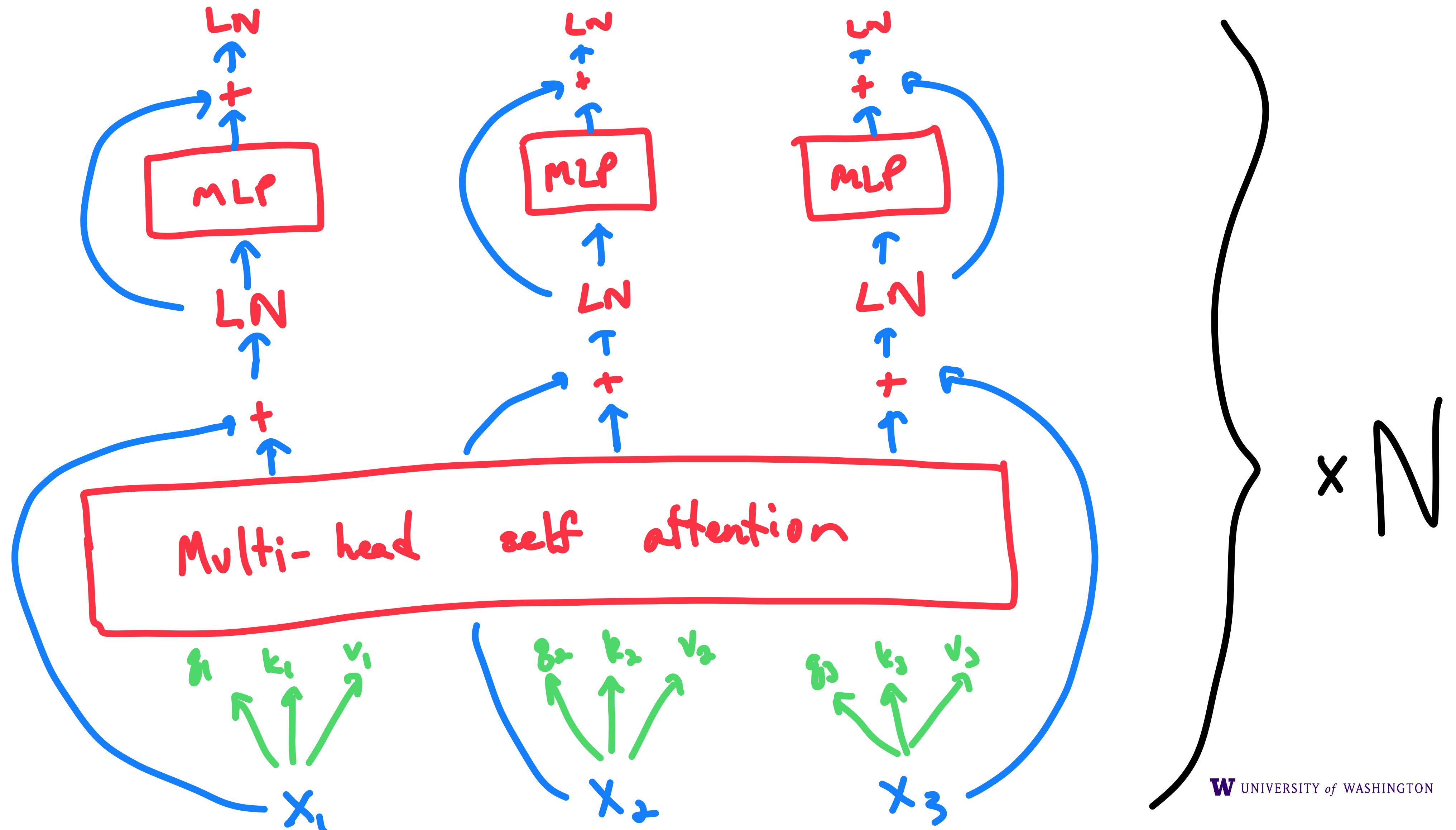
(b) with skip connections

[source](#)

# Final Ingredients: Layer Normalization

- Normalizing inputs: subtract mean, divide by standard deviation
  - Makes new mean 0, new standard deviation 1
  - Widely used in many kinds of statistical modeling [e.g. predictors in linear regression], including in NNs
- Layer norm: to each row  $x$  of a matrix [a batch]:
$$LN(x) = \frac{x - \mu}{\sigma + \epsilon} \gamma + \beta$$
  - Where  $\mu$  is mean,  $\sigma$  is std dev
  - $\gamma, \beta$  are learned scaling parameters [but often omitted entirely]

# Full Transformer Encoder Block



# Initial WMT Results

Model	BLEU		Training Cost (FLOPs)	
	EN-DE	EN-FR	EN-DE	EN-FR
ByteNet [15]	23.75			
Deep-Att + PosUnk [32]		39.2		$1.0 \cdot 10^{20}$
GNMT + RL [31]	24.6	39.92	$2.3 \cdot 10^{19}$	$1.4 \cdot 10^{20}$
ConvS2S [8]	25.16	40.46	$9.6 \cdot 10^{18}$	$1.5 \cdot 10^{20}$
MoE [26]	26.03	40.56	$2.0 \cdot 10^{19}$	$1.2 \cdot 10^{20}$
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Transformer (base model)	27.3	38.1	<b><math>3.3 \cdot 10^{18}</math></b>	
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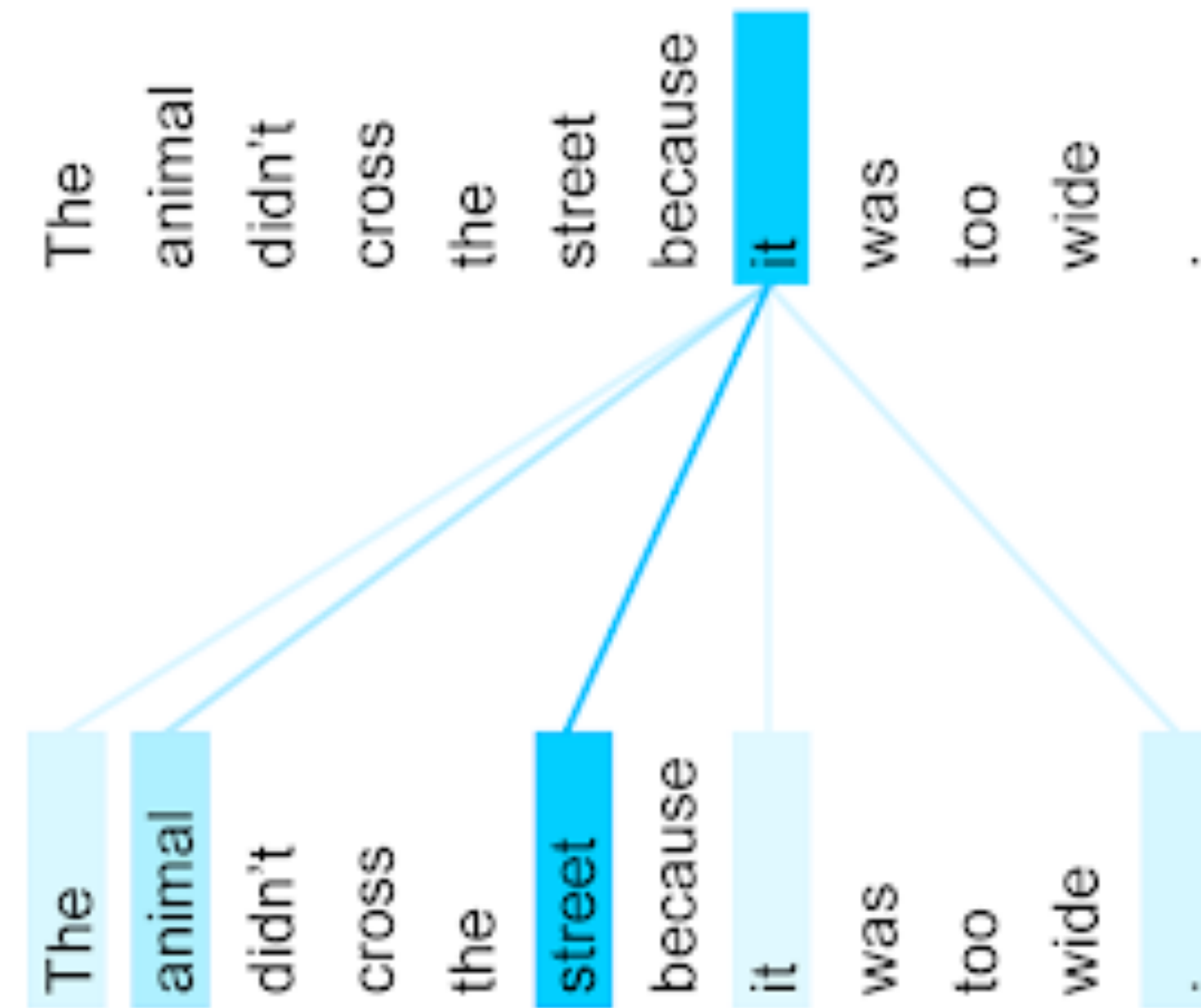
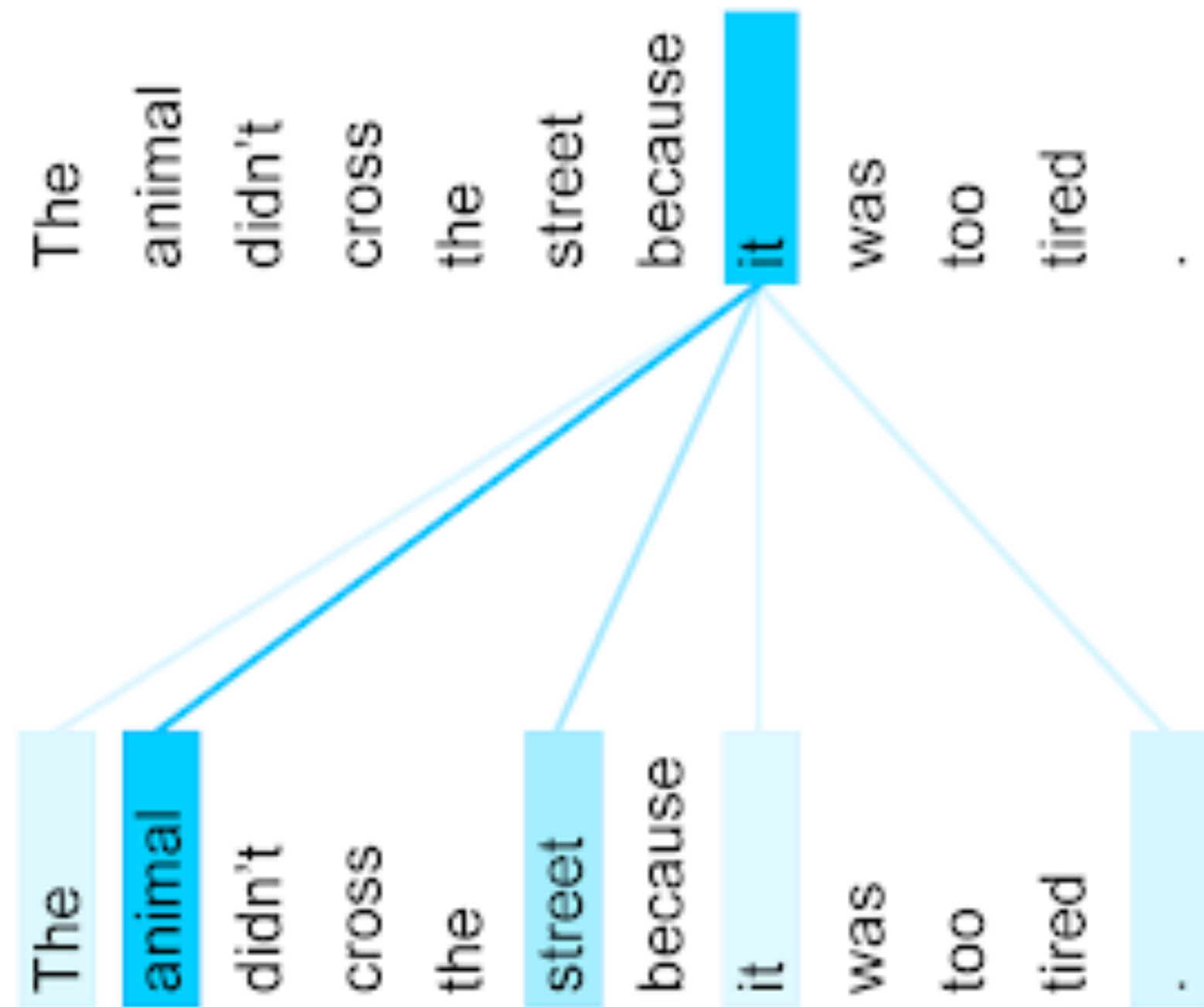


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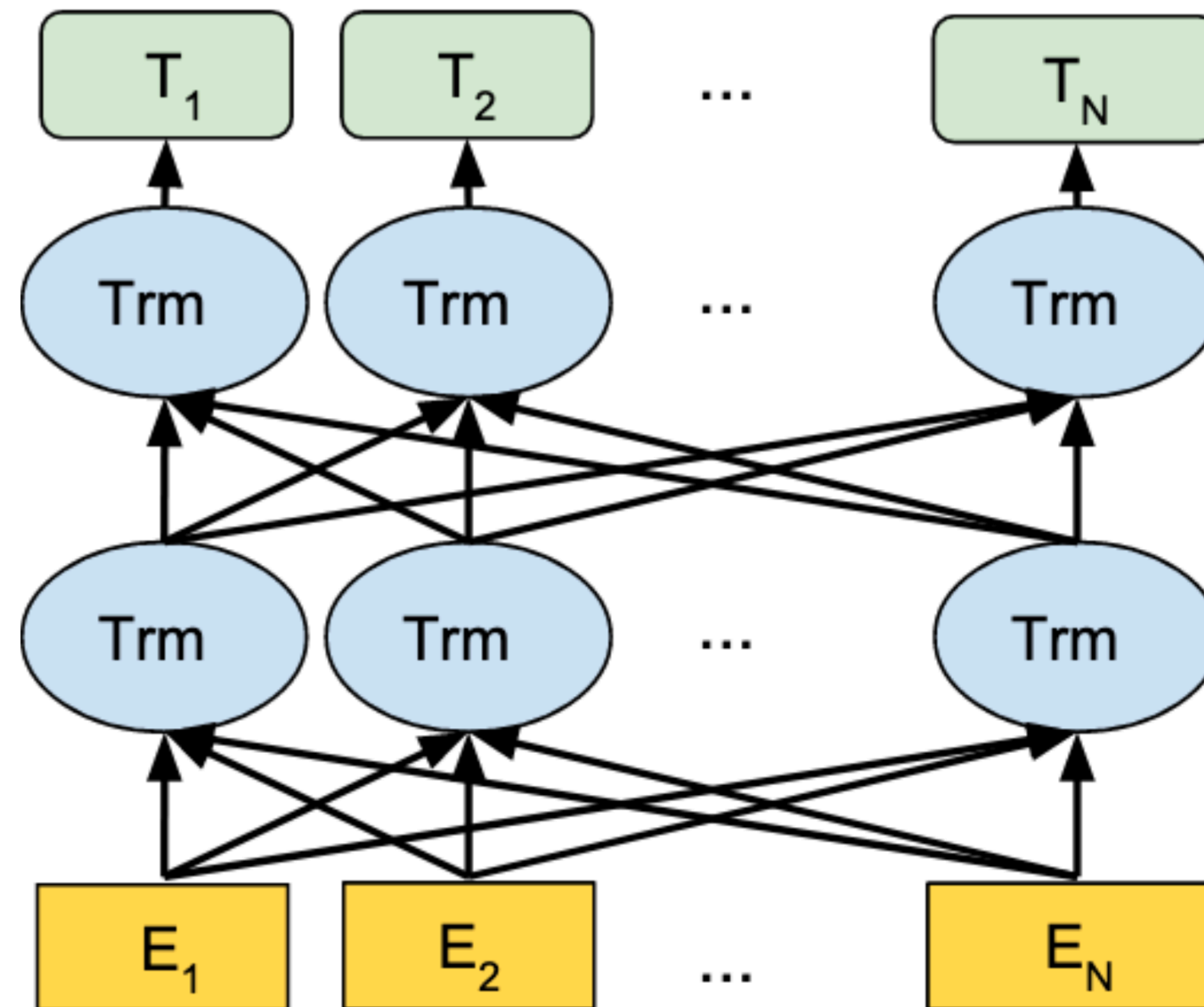
More on why  
important later

# Attention Visualization: Coreference?



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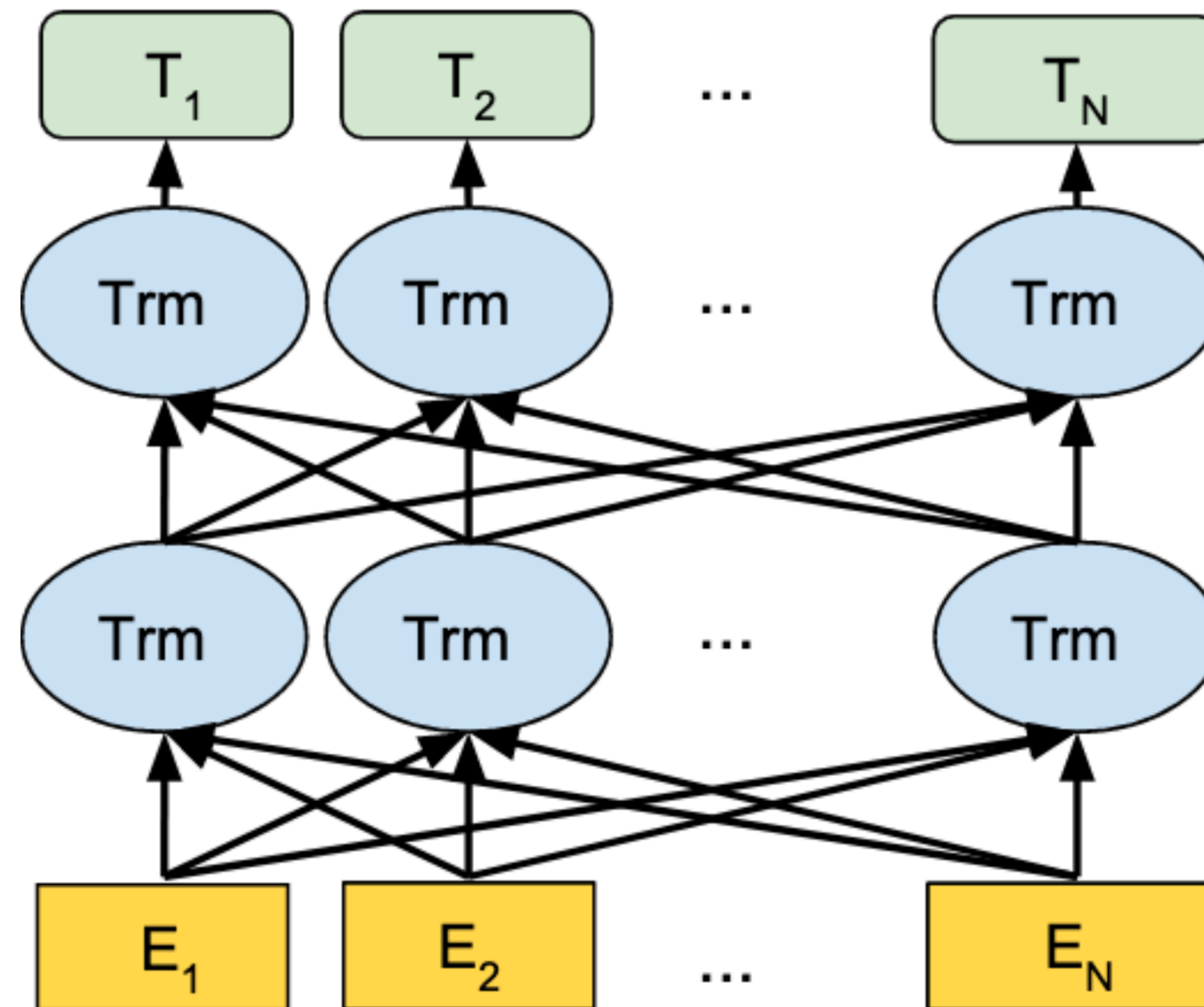
# Transformer: Path Lengths + Parallelism



[source](#) (BERT paper)



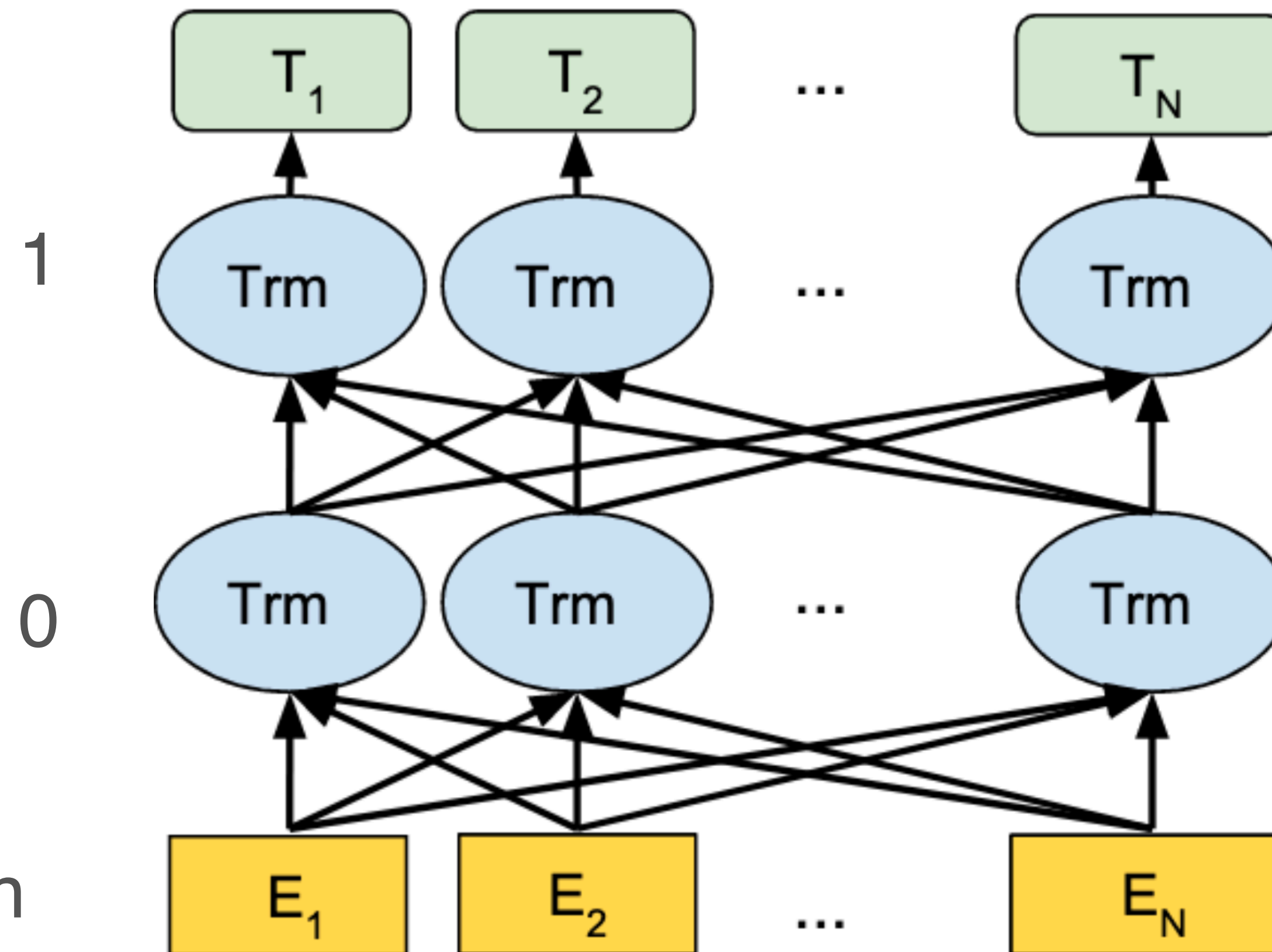
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Path lengths between tokens: 1  
[constant, not linear]

# Transformer: Path Lengths + Parallelism

Computation order:



Path lengths between tokens: 1  
[constant, not linear]

Also not linear in sequence length! Can be parallelized.

# Transformer: Summary

- *Entirely* feed-forward
  - Therefore massively parallelizable
  - RNNs are inherently sequential, a parallelization bottleneck
- (Self-)attention everywhere
- Long-term dependencies:
  - LSTM: has to maintain representation of early item
  - Transformer: very short “path-lengths”

# Next Time

- A deeper look at the *decoder* block of a Transformer
  - Attention masks
- Subword tokenization