

Dimension Reduction:

Set up: Data has p dimensions. $x_i \in \mathbb{R}^p$

Assume: $\sum x_i = 0$
 $\frac{1}{n} \sum x_i = 0$

(You can always centered data)

We want to find a function f :

$f: \mathbb{R}^p \rightarrow \mathbb{R}^q, q < p$
that "encodes" x_i to
 $z_i = f(x_i) \in \mathbb{R}^q$
($f(\cdot)$ is "encoder")

Generally we also want a decoder function $g(\cdot)$

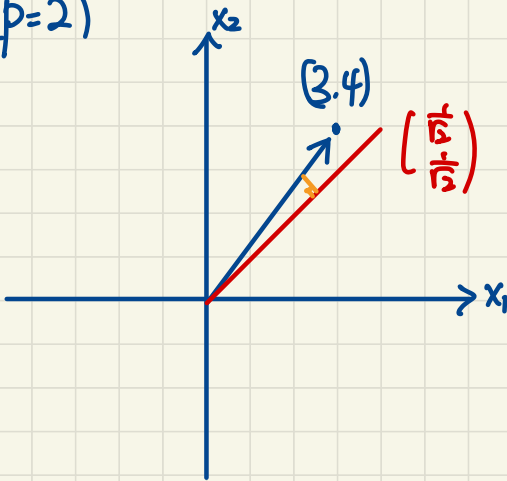
$$g: \mathbb{R}^q \rightarrow \mathbb{R}^p$$

We would lose information. But we want the reconstruction minimized.

$$\frac{1}{n} \sum_{i=1}^n \|x_i - g(f(x_i))\|^2$$

$\|\cdot\|$: norm / length 長度

$(p=2)$



$$a_1 = \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix}$$

$$A = (a_i)$$

$$f(x) = A^T x, x \in \mathbb{R}^2$$

$$g(z) = Az, z \in \mathbb{R}^1$$

quiz:

$x = \begin{pmatrix} 3 \\ 4 \end{pmatrix}$. What is

$$z = f(x) = ?$$

$$f(x) = A^T x$$

$$\left(\frac{1}{12}, \frac{1}{12}\right) \begin{pmatrix} 3 \\ 4 \end{pmatrix} = \frac{3}{12} + \frac{4}{12} = \frac{7}{12} = z$$

$$\hat{x} = g(z) = ?$$

$$g(z) = \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} \cdot \frac{1}{\sqrt{2}} = \begin{pmatrix} \frac{1}{2} \\ \frac{1}{2} \end{pmatrix} = \hat{x}$$

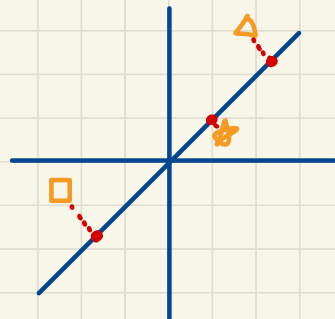
$$\|x - \hat{x}\| = ? \Rightarrow \sqrt{\left(3 - \frac{7}{2}\right)^2 + \left(4 - \frac{7}{2}\right)^2}$$

$$= \sqrt{\frac{1}{4} + \frac{1}{4}}$$

$$= \sqrt{2} \#$$

$g(f(x)) = \text{projection of } x \text{ on } a$

$a_i^T x$ = inner product of a_i & x



What if $p > 3$ ($q > 3$) dimensions > 3

We can't eyeball anymore

你老婆的正面照



你老婆的侧面照

For $q=1$

PCA find a line to projection onto so that reconstruction error is minimized.

q Find Need Vector

$q=1$ a line $a_1 \in \mathbb{R}^p$

$q=2$ a plane $a_1, a_2 \in \mathbb{R}^p$

$q=3$ 3D space $a_1, a_2, a_3 \in \mathbb{R}^p$

The vectors a_1, a_2, a_3 these are the
"principal Components" (PC)

Rmk: if $x \in \mathbb{R}^p$, we at most have p PCs

We require:

$$\|a_j\| = \sqrt{a_j^T a_j} = 1$$

$$a_j^T a_{j'} = 0 \quad j \neq j' \Leftrightarrow \text{orthogonal}$$

Quiz: Suppose $p=3, q=2$

which of the following can be the first PC?

1. $a_1 = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$ $a_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$

2. $a_1 = \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix}$ $a_2 = \begin{pmatrix} \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \end{pmatrix}$

3. $a_1 = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$ $a_2 = \begin{bmatrix} 3 \\ 2 \\ 1 \end{bmatrix}$

4. $a_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$ $a_2 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$

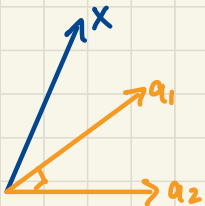
Ans: 4. Since $p=3$, a has to be 3×1
and has to be unit vector

How to define projection.

for $q > 1$

Suppose $q=2$

$p=3, q=2$



$$z = \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} = \begin{pmatrix} a_1^T x \\ a_2^T x \end{pmatrix} = \begin{pmatrix} a_1^T \\ a_2^T \end{pmatrix} x = (a_1, a_2)^T x$$

$$\begin{aligned} \hat{x} &= z_1 a_1 + z_2 a_2 \\ &= \underbrace{a_1^T x a_1}_{\text{projection on } a_1} + \underbrace{a_2^T x a_2}_{\text{projection on } a_2} = (a_1, a_2) (a_1, a_2)^T x \end{aligned}$$

$$a_1, a_2, \dots, a_q$$

$$A = (a_1, a_2, \dots, a_q)$$

$$f(x) = A^T x$$

$$g(z) = Az$$

Optimal a_1, a_2, \dots, a_q

$$\min \frac{1}{n} \sum_{i=1}^n \|x_i - AA^T x_i\|^2$$

$$\text{s.t. } \|a_j\| = 1 \quad j = 1, 2, \dots, q$$

$$a_j^T a_{j'} = 0 \quad j \neq j'$$

① Find $a_1 \in \mathbb{R}^p$

$$\min_{a_1 \in \mathbb{R}^p} \frac{1}{n} \sum \|x_i - a_1 a_1^T x_i\|^2$$

$$\text{s.t. } \|a_1\| = 1$$

② Given a_1 , solve

$$\tilde{x} = x_i - a_1 a_1^T x_i$$

$$\min_{a_2 \in \mathbb{R}^p} \frac{1}{n} \sum \|\tilde{x}_i - a_2 a_2^T \tilde{x}_i\|^2$$

$$\text{s.t. } \|a_2\| = 1$$

$$a_1^T a_2 = 0$$

Claim:

minimize reconstruction error:
= max variation of $a_1^T x$

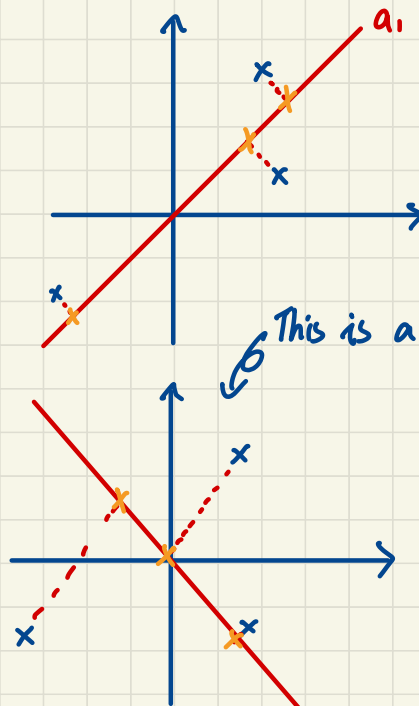
Originally, a_1 solves

$$\min_{a_1} \frac{1}{n} \sum \|x_i - a_1 a_1^T x_i\|^2$$

$$\text{s.t. } \|a_1\| = 1$$

max $\text{Var}(a_1^T x_i)$ when n large.

Intuition:



This is a shitty projection.

$$\frac{1}{n} \sum \|x_i - a, a,^T x_i\|^2$$

$$\Rightarrow \|x\|^2 = \underbrace{\|x_i - a, a,^T x_i\|^2}_{\text{Want small}} + \underbrace{\|a, a,^T x\|^2}_{\text{large}}$$

$$\min \frac{1}{n} \sum \|x_i - a, a,^T x_i\|^2$$



$$\max \frac{1}{n} \sum \|a, a,^T x\|^2$$

$$\|x_i - a, a,^T x_i\|^2 = \|x\|^2 - \|a, a,^T x\|^2$$

$$\frac{1}{n} \sum \|a, a,^T x\|^2$$

$$= \frac{1}{n} \sum (a,^T x)^2 \|a\|^2 = 1$$

$$= \frac{1}{n} \sum_i (a,^T x)^2$$

$$\xrightarrow{P} E[(a,^T x)^2] \text{ when } n \rightarrow \infty$$

n large:

$$\max E[(a,^T x)^2]$$

$$E[(a,^T x)(a,^T x)]$$

$$= E[(a,^T x)(x^T a)]$$

$$= E[a^T x x^T a]$$

$$\begin{aligned} & a,^T (E x x^T) a, \\ &= a,^T \text{Cov}(x) a, \\ &= \text{Var}(a,^T x) \end{aligned}$$

Recall: $E x_i = 0$

$$x_i = \begin{pmatrix} x_{i1} \\ x_{i2} \\ x_{i3} \\ \vdots \\ x_{ip} \end{pmatrix}$$

$$x_i^T = (x_{i1}, x_{i2}, \dots, x_{ip})$$

$$x_i x_i^T = \begin{pmatrix} x_{i1}^2 & x_{i1} x_{i2} & \dots \\ x_{i2} x_{i1} & x_{i2}^2 & \dots \\ \vdots & \vdots & \ddots \end{pmatrix}$$

diagonal $E[x_{ij}^2]$

$$= \text{Var}(x_{ij})$$

off diagonal:

$$x_{ij} \dots x_{ij'}$$

$$= \text{Cov}(x_{ij}, x_{ij'})$$

$$\begin{aligned} E[x_i x_i^T] &= \text{Cov} \\ &= \Sigma \quad (x_i) \end{aligned}$$

Summary

We can find $a_1, a_2, \dots, a_q \in \mathbb{R}$ by

$$\max_{a_1} \text{Var}(a_1^T x) \\ \text{s.t. } \|a_1\| = 1$$

$$\max_{a_2} \text{Var}(a_2^T x) \\ \text{s.t. } \|a_2\| = 1 \\ a_1^T a_2 = 0$$

Quiz:

$$p=3 \quad q=2$$

Which A corresponds then plane $x=y$

$$\hat{x} = A A^T x$$

Hint:

$$\text{Let } A = (a_1, a_2)$$

What a_1, a_2 span the plane $x=y$

A simpler problem:

Which A project the plane $z=0$ $A = (a_1, a_2) = \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{pmatrix}$ inner product

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} \rightarrow \begin{pmatrix} x \\ y \\ 0 \end{pmatrix}$$

$$z=0 \\ a_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \quad a_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$$

$$A A^T x = \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} \\ = \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x \\ y \\ 0 \end{pmatrix}$$

$$X=y$$

$$a_1 = \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \\ 0 \end{pmatrix} \quad A = (a_1, a_2) \quad a_2 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

Original problem:

$$\min_{a_1, a_2, \dots, a_q \in \mathbb{R}^p} \frac{1}{n} \sum \|X_i \cdot A A^T X_i\|^2$$

$$\text{s.t. } \|a_j\| = 1 \\ a_j^T a_{j'} = 0 \quad j \neq j'$$

$$A = (a_1, a_2, \dots, a_q)$$

Last class, we can
solve a_1, a_2, \dots, a_q by
(when n large)

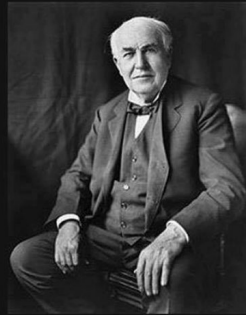
$$\max_{a_1} \text{Var}(a_1^T X) \\ \text{s.t. } \|a_1\| = 1$$

$$\max_{a_2} \text{Var}(a_2^T X) \\ \|a_2\| = 1 \quad a_1^T a_2 = 0$$

If there is a problem you can't solve, then there is an easier problem you can't solve: find it.

George Pólya

quoteslancy



發明燈泡不是給你裝奶茶用的

~湯瑪斯·愛迪生 1847-1931

$$\max_{a_i} \text{Var}(a_i^T x)$$

$$\|a_i\|=1$$

$$\text{Var}(a_i^T x) = a_i^T \underbrace{\Sigma}_{k \times p} \underbrace{a_i}_{p \times 1} \in \mathbb{R}$$

$$\Sigma = \begin{pmatrix} \lambda_1 & & 0 \\ & \lambda_2 & \\ 0 & & \ddots \\ & & & \lambda_p \end{pmatrix}$$

Without loss of generality.

$$\lambda_1 > \lambda_2 > \lambda_3 > \dots > \lambda_p$$

Objective

$$\begin{aligned} \text{Var}(a_i^T x) &= a_i^T \Sigma a_i \\ &= (a_{i1} \ a_{i2} \ \dots \ a_{ip}) \begin{pmatrix} \lambda_1 & & 0 \\ & \lambda_2 & \\ 0 & & \ddots \\ & & & \lambda_p \end{pmatrix} \begin{pmatrix} a_{i1} \\ a_{i2} \\ \vdots \\ a_{ip} \end{pmatrix} \\ &= \lambda_1 a_{i1}^2 + \lambda_2 a_{i2}^2 + \dots + \lambda_p a_{ip}^2 \end{aligned}$$

$$\|a_i\|=1$$

$$a_{i1}^2 + a_{i2}^2 + \dots + a_{ip}^2 = 1$$

$$\max_x \lambda_1 a_{i1}^2 + \lambda_2 a_{i2}^2 + \dots + \lambda_p a_{ip}^2$$

$$\text{s.t. } a_{i1}^2 + a_{i2}^2 + \dots + a_{ip}^2 = 1$$

Solution:

$$a_{11}^* = 1 \quad a_{12}^* = a_{13}^* = \dots = a_{1p}^* = 0$$

$$a_1 = \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix} \quad A = (a_i)$$

$$AA^T \begin{pmatrix} x_{11} \\ x_{12} \\ \vdots \\ x_{1p} \end{pmatrix} = \begin{pmatrix} x_{11} \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$

$$\max_{a_2} \text{Var}(a_2^T x)$$

$$\hookrightarrow a_{21}^2 \lambda_1 + a_{22}^2 \lambda_2 + \dots + a_{2p}^2 \lambda_p$$

$$\text{s.t. } \|a_2\| = 1 \rightarrow a_{21}^2 + a_{22}^2 + \dots + a_{2p}^2 = 1$$

$$a_1^T a_2 = 0$$

$$(1 \ 0 \ 0 \dots 0) \begin{pmatrix} a_{21} \\ a_{22} \\ \vdots \\ 0 \end{pmatrix} = 0 \quad \Leftrightarrow a_{21} = 0$$

$$\max_{a_2} a_{22}^2 \lambda_2 + a_{23}^2 \lambda_3 + \dots + a_{2p}^2 \lambda_p$$

$$\text{s.t. } a_{22}^2 + \dots + a_{2p}^2 = 1$$

$$\Rightarrow a_{22} = 1$$

$$a_{23} = a_{24} = \dots = a_{2p} = 0$$

$$a_{21} = 0 \quad (\text{by orthogonality})$$

$$a_1^* = \begin{pmatrix} 0 \\ 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$

$$a_3^* = \begin{pmatrix} 0 \\ 0 \\ 1 \\ \vdots \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 5 \\ 3 \\ 2 \\ 1 \\ 0 \end{pmatrix} \mapsto \begin{pmatrix} 5 \\ 3 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

That's the end of the lecture today
中秋節快樂



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