



Financial Econometrics

Basic Probability and Statistics

Tim C.C. Hung 洪志清

February 14th, 2022



- **Outcomes**: the mutually exclusive potential results of a random process.
- **Sample Space**: the set of all possible outcomes.
- **Event**: a subset of the sample space.



- **Probability Distribution:**
the proportion of the time that the outcome occurs in the long run.
- **Probability Space:**
a triple (Ω, F, P) consists of the sample space Ω , event F , and a probability measure $P \rightarrow [0, 1]$
- **Venn Diagram:** unions, intersections, and complements.



- Operations: \cap :interaction; \cup :Union; A^C :Event A 's complement

- **Principles:**

- ▶ $Pr(A) + Pr(A^C) = Pr(\Omega) = 1$
- ▶ $Pr(A \cup B) = Pr(A) + Pr(B) - Pr(A \cap B)$
– *Principle of Inclusion and Exclusion* (排容原理)
- ▶ $Pr((A \cap B)^C) = Pr(A^C \cup B^C)$
- ▶ $Pr((A \cup B)^C) = Pr(A^C \cap B^C)$
– *De Morgan's Laws*
- ▶ $Pr(A \cup (B \cap C)) = Pr((A \cup B) \cap (A \cup C))$
- ▶ $Pr(A \cap (B \cup C)) = Pr((A \cap B) \cup (A \cap C))$
– *Distributive Property of Sets*



- **Random Experiment:** *NBA's Most Valuable Player.*
- **Sample Outcome:** *Nikola Jokic (2021).*
- **Sample Space:**
 $\Omega = \{LeBron James, Stephen Curry, Kevin Durant, Giannis Antetokounmpo, Nikola Jokic, \dots\}$
- **Events:**
Event A : An European player wins.
($A = \{Giannis Antetokounmpo, Nikola Jokic, \dots\}$)
Event B : A point guard wins.
($B = \{Stephen Curry, Derrick Rose, Steph Nash, \dots\}$)



- **Random Variable:** a real-valued *function* from some sample space Ω to some measurable space.
- The value depends on the particular outcome we happen to observe.
- Random variables can be discrete or continuous.
- Random variables can be scalar (univariate) or vectors (multivariate).
- Conventions: Let capital letters (X) denote the random variable and small letters (x) as a particular realization.



- Possible outcomes for one coin toss: $\Omega = \{heads, tails\}$.
- Random variable X takes the value $x = \begin{cases} 1, & \text{if head} \\ 0, & \text{if tail} \end{cases}$
- X has a probability mass function $f(x) = \begin{cases} \frac{1}{2}, & \text{if } x = 1 \\ \frac{1}{2}, & \text{if } x = 0 \end{cases}$



- Probability Function: $f(x) = P[X = x]$
- For continuous X , the measure of any given x is 0.
- Probability Density Function (PDF): describes positive probabilities to intervals in the range of x .
 - ▶ $f(x) \geq 0$
 - ▶ $P[X \in [a, b]] = P[a \leq X \leq b] = \int_a^b f(x)dx$
 - ▶ $\int_{-\infty}^{\infty} f(x)dx = 1$
- Cumulative Distribution Function (CDF): $F(x) = P[X \leq x]$



- The expected value of a random variable X is a *suitably weighted average* over the range of x , or the *center* of the distribution.
 - ▶ Usually denoted as $E[X]$, μ_X , or μ .
 - ▶ Also called the **expectation of X** , or the **mean of X**

- Definition:
$$E[X] = \begin{cases} \sum x * f(x) & \text{if } X \text{ is discrete} \\ \int_{-\infty}^{\infty} x * f(x) dx & \text{if } X \text{ is continuous} \end{cases}$$

- We can also take expectations of functions.



- Discrete example: X is the result of one toss of a fair die:
$$E[X] = 1 * \frac{1}{6} + 2 * \frac{1}{6} + 3 * \frac{1}{6} + 4 * \frac{1}{6} + 5 * \frac{1}{6} + 6 * \frac{1}{6} = \frac{7}{2}$$
- Continuous example: If the pdf of Y is given by $f(y) = 1$ for $y \in [1, 2]$ and $f(y) = 0$ otherwise, $E[Y] = \int_1^2 (1 * y) dy = \frac{3}{2}$
- Bernoulli random variable B : $E[B] = 1 * p + 0 * (1 - p) = p$
- **Linearity of Expectation:** $E[X] + E[Y] = E[X + Y]$



- The variance of X measures the dispersion of X . It is usually denoted by $Var[X]$, or σ_X^2 , or σ_X^2 .

- Definition: $Var[X] = E[(X - E(X))^2]$
$$= \begin{cases} \sum (x - \mu_X)^2 f(x) & \text{if } X \text{ is discrete} \\ \int_{-\infty}^{\infty} (x - \mu_X)^2 f(x) dx & \text{if } X \text{ is continuous} \end{cases}$$

- We can also show that:

$$\begin{aligned} Var[X] &= E[(X - E(X))^2] \\ &= E[X^2 - 2(XE(X)) + (E(X))^2] \\ &= E[X^2] - E[X] * 2E[X] + (E[X])^2 \\ &= E[X^2] - (E[X])^2 \end{aligned}$$



- Standard Deviation: Square Root of Variance.

- Discrete example: X is the result of one toss of a fair die:

$$Var[X] = \frac{1}{6} * [(1 - \frac{7}{2})^2 + (2 - \frac{7}{2})^2 + (3 - \frac{7}{2})^2] + (4 - \frac{7}{2})^2 + (5 - \frac{7}{2})^2 + (6 - \frac{7}{2})^2]$$

or alternatively, $Var[X] = E[X^2] - (E[X])^2 = \frac{91}{6} - (\frac{7}{2})^2$

$$Var[X] = \frac{35}{12}$$

- Bernoulli random variable B :

$$Var[B] = (1 - p)^2 * p + (0 - p)^2 * (1 - p) = p(1 - p)$$

$$\sigma_B = \sqrt{p(1 - p)}$$



- Variance Properties: for some constants a, b, c ,
 - ▶ $Var[X + c] = Var[X]$
 - ▶ $Var[cX] = c^2 Var[X]$
 - ▶ $Var[aX + b] = a^2 Var[X]$
 - ▶ $Var[aX + bY] = a^2 Var[X] + b^2 Var[Y] + 2ab Cov(X, Y)$
- $Cov(X, Y)$: covariance of X and Y , defined as: $E[(X - \mu_X)(Y - \mu_Y)]$
 - ▶ $Cov(X, Y) = E[XY] - E[X]E[Y]$
 - ▶ $Cov(X, X) = Var[X]$
 - ▶ $Cov(X, Y) = Cov(Y, X)$
 - ▶ $Cov(aX, bY) = ab Cov(X, Y)$
- For some $Y = a + bX$, $\mu_Y = a + b\mu_X$, $\sigma_Y^2 = b^2 \sigma_X^2$
- Can you proof them?



- Discrete Version: the joint probability distribution of two discrete random variables, say X and Y , is the probability that the random variables simultaneously take on certain values, say x and y .
- The joint probability distribution can be written as the function:
 $Pr(X = x, Y = y)$.
- The marginal probability distribution of a random variable Y is just another name for its probability distribution (without reference to X).

$$Pr(Y = y) = \sum_{i=1}^I Pr(X = x_i, Y = y)$$



- Continuous Version:

Suppose the joint probability function for X and Y is denoted as $f(x, y)$

- $Pr(a < X < b, c < Y < d) = \int_a^b \int_c^d f(x, y) dy dx.$

- $f(x, y) \geq 0.$

- $\int_x \int_y f(x, y) dy dx = 1.$

- The marginal probability function for X is:

$$f_X(x) = \int_{-\infty}^{\infty} f(x, y) dy$$



- **Bayes' theorem:** $Pr(A|B) = \frac{Pr(A \cap B)}{Pr(B)}$
- Alternatively, $Pr(A \cap B) = Pr(A|B) * Pr(B) = Pr(B|A) * Pr(A)$, or $Pr(Y = y \cap X = x) = Pr(Y = y|X = x) * Pr(X = x)$
- If X and Y are independent, $Pr(Y = y) = Pr(Y = y|X = x)$ for any given x , vice versa.
- Thus, if X and Y are independent, $Pr(Y = y \cap X = x) = Pr(Y = y) * Pr(X = x)$



- Conditional expectation of Y given $X = x$ is:

$$E[Y|X = x] = \sum_{i=1}^I y_i \Pr(Y = y_i|X = x)$$

- The mean of Y is the weighted average of the conditional expectation of Y given X , weighted by the probability distribution of X :

$$E(Y) = \sum_{j=1}^J E[Y|X = x_j] * \Pr(X = x_j)$$

- This is called, the **Law of Iterated Expectation**:

$$E[Y] = E_X[E(Y|X)]$$



- The variance of Y conditional on X is the variance of the conditional distribution of Y given X .
- $$Var(Y|X = x) = \sum_i^I [y_i - E(Y|X = x)]^2 * Pr(Y = y_i|X = x)$$



- Now, back to covariance!
- Covariance is a measure of the extent to which two random variables move together.
- In the discrete version:

$$\begin{aligned} Cov(X, Y) &\equiv \sigma_{XY} \\ &= E[(X - \mu_X)(Y - \mu_Y)] \\ &= \sum_i^I \sum_j^J (x_i - \mu_X)(y_j - \mu_Y) * Pr(X = x_i, Y = y_j) \end{aligned}$$



- Correlation, or $Corr(X, Y)$ is defined as:

$$Corr(X, Y) = \frac{Cov(X, Y)}{\sqrt{Var(X)Var(Y)}} = \frac{\sigma_{XY}}{\sigma_X \sigma_Y}$$

- Random variables X and Y are considered *uncorrelated* if $Corr(X, Y) = 0$

- Also, $-1 \leq Corr(X, Y) \leq 1$



- Independence implies non-correlation!
- Suppose $E[Y|X] = \mu_Y$ for any x

$$\begin{aligned} Cov(X, Y) &= E[XY] - \mu_X \mu_Y \\ &= E[X * E(Y|X)] - \mu_X \mu_Y \\ &= E[X] * E[Y|X] - \mu_X \mu_Y = 0 \end{aligned}$$

- However, the reverse is not necessarily true.
- *Correlation does not imply causality!*

Example



- Suppose the following is a survey of our students with/without intern experience.

	Junior ($X=0$)	Senior ($X=1$)	Total
No Intern ($Y=0$)	10 (25%)	2 (5%)	12 (30%)
Intern ($Y=1$)	10 (25%)	18 (45%)	28 (70%)
Total	20 (50%)	20 (50%)	40 (100%)

- Can you see the joint, marginal, and conditional probability of X and Y ?
- Can you calculate the expected value and variance of X and Y ?
- Can you calculate the covariance of X and Y ? Are they independent?



- The probability density function of a normal distributed random variable (the normal PDF) is:

$$f_Y(y) = \frac{1}{\sqrt{2\pi}\sigma_Y} \exp\left[-\frac{1}{2}\left(\frac{y - \mu_Y}{\sigma_Y}\right)^2\right]$$

- A **Standard Normal Distribution** has a mean of 0 and a standard deviation of 1, usually denoted by Z .
- Its cumulative distribution function is denoted by Φ .
For some constant c , $Pr(Z \leq c) = \Phi(c)$.

Chi-Squared Distribution



- The Chi-squared distribution is the distribution of the **sum** of m squared **independent** standard normal random variables.
- The distribution depends on m , which is called the *degrees of freedom* of the Chi-squared distribution.
- A Chi-squared distribution with m degrees of freedom is denoted as χ_m^2 .



- The Student t distribution with m degrees of freedom is defined to be the distribution of the **ratio** of a **standard normal random variable**, divided by the **square root** of an independently distributed **Chi-squared random variable** with m degrees of freedom divided by m .
- Say, there's a standard normally distributed Z and a random variable W with a Chi-squared distribution and degrees of freedom of m ,

$$\frac{Z}{\sqrt{\frac{W}{m}}} \sim t_m$$

- For some m that is large enough, $t_\infty \rightarrow Z$.



- $F_{m,n} = \frac{\chi_m^2/m}{\chi_n^2/n}$, where χ_m^2 and χ_n^2 are independent.
- When $n \rightarrow \infty$, $\chi_n^2/n \rightarrow 1$.
- $F_{m,\infty}$ is the distribution of a random variable with a Chi-squared distribution with m degrees of freedom, divided by m .
- Equivalently, the $F_{m,\infty}$ distribution is the distribution of the average of m squared standard normal random variables.



- Simple random sampling is the simplest sampling scheme in which n objects are selected at **random** from a **population** and each member of the population is **equally likely** to be included in the sample.
- Since the members of the population included in the sample are selected at **random**, the values of the observations Y_1, Y_2, \dots, Y_n are themselves random.
- Because Y_1, \dots, Y_n are randomly drawn from the same population, the marginal distribution of Y_i is the same for each $i = 1, 2, \dots, n$. Y_1, \dots, Y_n are said to be **identically distributed**.
- When Y_1, \dots, Y_n are drawn from the same distribution and are independently distributed, they are said to be independently and identically distributed, or **i.i.d.**



- Denote the sample average $\bar{Y} = \frac{1}{n}(Y_1 + Y_2 + \dots + Y_n) = \frac{1}{n} \sum_{i=1}^n Y_i$
- \bar{Y} also has a distribution (called sampling distribution).
 - ▶ $E[\bar{Y}] = \frac{1}{n} \sum_{i=1}^n E[Y_i] = \frac{1}{n} * n\mu_Y = \mu_Y$
 - ▶ $Var(\bar{Y}) = Var(\frac{1}{n} \sum_{i=1}^n Y_i)$
$$= \frac{1}{n^2} \sum_{i=1}^n Var(Y_i) + \frac{1}{n^2} \sum_{i=1}^n \sum_{j=1, j \neq i}^n Cov(Y_i, Y_j)$$
$$= \frac{\sigma_Y^2}{n}$$



- The **Law of Large Numbers**:

The property that \bar{Y} is near μ_Y with increasing probability as n increases is called **convergence in probability**, or **consistency**.

- More formally, consider a sequence $\{S_n\}$. $\{S_n\}$ is said to **converge in probability** to a limit, μ , if the **probability** that S_n is within $\pm\delta$ of μ tends to one as $n \rightarrow \infty$ as long as the constant δ is positive.

- $S_n \xrightarrow{p} \mu$ if and only if $Pr[|S_n - \mu| \geq \delta] \rightarrow 0$ as $n \rightarrow \infty$ for all $\delta > 0$.

- If $S_n \xrightarrow{p} \mu$, then S_n is said to be a **consistent estimator** of μ .



- The **Central Limit Theorem**:

The property that the distribution of \bar{Y} is well approximated by a normal distribution when n is large enough.

- Since the mean of \bar{Y} is μ_Y and its variance is $\frac{\sigma_Y^2}{n}$, when n is large the distribution of \bar{Y} is approximately $N(\mu_Y, \sigma_Y^2/n)$
- Accordingly, $\frac{\bar{Y} - \mu_Y}{\sigma_{\bar{Y}}}$ is well approximated by the standard normal distribution $N(0, 1)$.
- Let $\{F_n\}$ be a sequence of cumulative distribution functions corresponding to a sequence of random variables $\{S_n\}$. Then, the sequence of random variables S_n is said to **converge in distribution** to S (denoted as $S_n \xrightarrow{d} S$) if the distribution functions $\{F_n\}$ converge to F .



- $S_n \xrightarrow{d} S$ if and only if $\lim_{n \rightarrow \infty} F_n(t) = F(t)$,
where the limit holds at all t at which the limiting distribution F is continuous.
- The distribution F is called the **asymptotic distribution** of S_n .
- If Y_1, \dots, Y_n are i.i.d. and $0 < \sigma_Y^2 < \infty$, then

$$\sqrt{n}(\bar{Y} - \mu_Y) \xrightarrow{d} N(0, \sigma_Y^2)$$

- In other words, the asymptotic distribution of

$$\sqrt{n} \frac{\bar{Y} - \mu_Y}{\sigma_Y} = \frac{\bar{Y} - \mu_Y}{\sigma_Y / \sqrt{n}} = \frac{\bar{Y} - \mu_Y}{\sigma_{\bar{Y}}} \sim N(0, 1)$$



- An **estimator** is a rule for calculating an estimate of a given quantity based on observed data.
- Example: Estimating Population Mean (μ_Y):
One natural way is to simply compute the sample average (\bar{Y})!
- \bar{Y} is not the only possible estimator. For example, the first observation Y_1 can be another estimator of μ_Y .
- What makes one estimator **better** than another? What are desirable **characteristics** of the sampling distribution of an estimator?



- In general, we want an estimator that gets as close as possible to the unknown true value, at least in some average sense.
- In other words, we want the sampling distribution of an estimator to be as **tightly** centered around the unknown value as possible.
- This leads to three specific desirable characteristics of an estimator: **unbiasedness**, **consistency**, and **efficiency**!



- Let $\hat{\mu}_Y$ denote some estimator of μ_Y .
- **Unbiasedness:** $E[\hat{\mu}_Y] = \mu_Y$
- **Consistency:** $\hat{\mu}_Y \xrightarrow{p} \mu_Y$
- **Efficiency:** Let $\tilde{\mu}_Y$ be another estimator of μ_Y . Suppose that both $\tilde{\mu}_Y$ and $\hat{\mu}_Y$ are unbiased estimators. If $Var(\hat{\mu}_Y) < Var(\tilde{\mu}_Y)$, then $\hat{\mu}_Y$ is said to be more **efficient** than $\tilde{\mu}_Y$.



- Let's compare \bar{Y} and Y_1 under these criterion.
- We can see that $E[\bar{Y}] = \mu_Y$ and $\bar{Y} \xrightarrow{p} \mu_Y$
- We can also see that $E[Y_1] = \mu_Y$
- However, $Var(\bar{Y}) = \frac{\sigma_Y^2}{n} < \sigma_Y^2 = Var(Y_1)$ for $n > 1$.
- Therefore, for $n \geq 2$, \bar{Y} is more efficient than Y_1 .



- Another example,
 $\tilde{Y} = \frac{1}{n}(\frac{1}{2}Y_1 + \frac{3}{2}Y_2 + \dots + \frac{1}{2}Y_{n-1} + \frac{3}{2}Y_n)$ for some even number n .
- $E[\tilde{Y}] = \frac{1}{2n} * \sum_{odd\ i} Y_i + \frac{3}{2n} * \sum_{even\ i} Y_i = \frac{1}{2n} * \frac{n}{2} * \mu_Y + \frac{3}{2n} * \frac{n}{2} * \mu_Y = \mu_Y$
- $Var(\tilde{Y}) = (\frac{1}{2n})^2 * \frac{n}{2} * \sigma_Y^2 + (\frac{3}{2n})^2 * \frac{n}{2} * \sigma_Y^2 = \frac{5}{4n} \sigma_Y^2 > \frac{1}{n} \sigma_Y^2 = Var(\bar{Y})$
- In fact, \bar{Y} is the most efficient estimator of μ_Y among all unbiased estimators that are weighted averages of Y_1, \dots, Y_n .
- \bar{Y} is also called the **Best Linear Unbiased Estimator (BLUE)** for μ_Y .
- \bar{Y} is also the least square estimator (the solution of minimizing $\sum_{i=1}^n (Y_i - M)^2$) for μ_Y . We will discuss about it shortly.



- **Hypothesis Testing:**

A method of statistical inference used to determine a possible conclusion from two different, and likely conflicting, hypotheses.

- **Null Hypothesis:** usually denoted as H_0

- **Alternative Hypothesis:** usually denoted as H_1 or H_A .
Could be more than one.

- E.g. Hypothesis testing for population mean.

$$H_0: E[Y] = \mu_{Y,0}$$

$$H_1: E[Y] \neq \mu_{Y,0} \text{ (Two-sided test)}$$



- **p -Value**: the probability of drawing a statistic at least as adverse to the null as the value actually computed with your data, *assuming that the null hypothesis is true*.
- If the p -value is small (e.g., less than or equal to a pre-specified level, say, 5%), then we say the null hypothesis is *unlikely* to be true, and we are in favor of the alternative hypothesis. That is, **we reject the null hypothesis**.
- Please be aware that even if the null hypothesis is not rejected, this does not mean that the null hypothesis is true. It is **accepted tentatively** with the recognition that it might be rejected later based on additional data.



- Calculating the p -value based on \bar{Y} (Two-sided Test):

$$p - value = Pr(\quad |\bar{Y} - \mu_{Y,0}| > |\bar{Y}^{act} - \mu_{Y,0}| \quad | \quad H_0 \text{ is true} \quad)$$

where \bar{Y}^{act} is the actual \bar{Y} we observe (from the data).

- To compute the p -value, we need to know the sampling distribution of \bar{Y} under the null hypothesis.
- If n is large, \bar{Y} is well approximated by a normal distribution.



$$\begin{aligned} p\text{-value} &= Pr(|\bar{Y} - \mu_{Y,0}| > |\bar{Y}^{act} - \mu_{Y,0}| \mid H_0 \text{ is true}) \\ &= Pr(\left| \frac{\bar{Y} - \mu_{Y,0}}{\sigma_Y} \right| > \left| \frac{\bar{Y}^{act} - \mu_{Y,0}}{\sigma_Y} \right| \mid H_0 \text{ is true}) \\ &= Pr(\left| \frac{\bar{Y} - \mu_{Y,0}}{\sigma_Y/\sqrt{n}} \right| > \left| \frac{\bar{Y}^{act} - \mu_{Y,0}}{\sigma_Y/\sqrt{n}} \right| \mid H_0 \text{ is true}) \\ &= Pr(\left| \frac{\bar{Y} - \mu_{Y,0}}{\sigma_{\bar{Y}}} \right| > \left| \frac{\bar{Y}^{act} - \mu_{Y,0}}{\sigma_{\bar{Y}}} \right| \mid H_0 \text{ is true}) \\ &= Pr(|t| > |t^{act}| \mid H_0 \text{ is true}) \end{aligned}$$

$t = \frac{\bar{Y} - \mu_{Y,0}}{\sigma_Y/\sqrt{n}}$ is the t -statistic or t -ratio.

- Question: Do we know σ_Y or $\sigma_{\bar{Y}}$?



- In practice, $\sigma_{\bar{Y}}$ is **unknown** and needs to be estimated.
- Estimator of the variance of Y :

$$S_Y^2 = \frac{1}{n-1} \sum_{i=1}^n (Y_i - \bar{Y})^2$$

- Why $n-1$?
- If we use n instead of $n-1$, say we have $S_Y^{*2} = \frac{1}{n} \sum_{i=1}^n (Y_i - \bar{Y})^2$.
See next page.



$$\begin{aligned} E[S_Y^{*2}] &= E\left[\frac{1}{n} \sum_{i=1}^n (Y_i - \bar{Y})^2\right] \\ &= E\left[\frac{1}{n} \sum_{i=1}^n (Y_i^2 - 2Y_i\bar{Y} + \bar{Y}^2)\right] \\ &= E\left[\frac{1}{n} \sum_{i=1}^n Y_i^2 - 2\frac{1}{n} \sum_{i=1}^n Y_i\bar{Y} + \frac{1}{n} \sum_{i=1}^n \bar{Y}^2\right] \\ &= E\left[\frac{1}{n} \sum_{i=1}^n Y_i^2 - 2\bar{Y}^2 + \bar{Y}^2\right] \\ &= E\left[\frac{1}{n} \sum_{i=1}^n Y_i^2 - \bar{Y}^2\right] \\ &= \frac{1}{n} \sum_{i=1}^n E[Y_i^2] - E[\bar{Y}^2] \\ &= \frac{1}{n} * n * (\mu_Y^2 + \sigma_Y^2) - (\mu_Y^2 + \frac{\sigma_Y^2}{n}) \\ &= \frac{n-1}{n} \sigma_Y^2 \end{aligned}$$



- Try again. We can show that $E[S_Y^2] \equiv E[\frac{1}{n-1} \sum_{i=1}^n (Y_i - \bar{Y})^2] = \sigma_Y^2$
- Furthermore, with some moderate assumption:
If Y_1, \dots, Y_n are i.i.d. and $E[Y^4] < \infty$, then
 $S_Y^2 \xrightarrow{p} \sigma_Y^2$
- **Standard Deviation** of \bar{Y} : $\sigma_Y = \frac{\sigma_Y}{\sqrt{n}} \rightarrow$ Not Observable!
- **Standard Error** of \bar{Y} : $\hat{\sigma}_Y = \frac{S_Y}{\sqrt{n}}$

Type I Type II Error



- **Type I error:**
the null hypothesis (無罪) is **rejected** when in fact it is **true** (誤判).
- **Type II error:**
the null hypothesis (無罪) is **not rejected** when in fact it is **false** (縱放).
- The pre-specified probability of type I error is the **significance level**.
- With a pre-specified significance level (e.g. 5%):
 - ▶ Reject if $|t| > 1.96$, or equivalently, reject if < 0.05
- The probability that the test incorrectly rejects the null when it is true is the **size** of the test.
- The probability that the test correctly rejects the null when the alternative is true is the **power** of the test.



- Because of the random sampling error, it is impossible to learn the **exact** value of the population mean of Y using only information in a sample.
- It is possible to use data from a random sample to construct a set of values that contains the true population mean μ_Y with a certain pre-specified probability.
- $\{\mu_Y \mid |\frac{\bar{Y} - \mu_Y}{S_Y/\sqrt{n}}| \leq 1.96\}$
 $\rightarrow \{\mu_Y \in (\bar{Y} - 1.96 * \frac{S_Y}{\sqrt{n}}, \bar{Y} + 1.96 * \frac{S_Y}{\sqrt{n}})\}$
- The probability that this interval contains the **true value** of the population mean is 95%.
- So, where is the **randomness** here? The confidence interval!
It will differ from one sample to the next; the population parameter, μ_Y , is not random!



- For two random variables X and Y .
- The population covariance and correlation can be estimated by the sample covariance and sample correlation.
- The sample covariance is:

$$S_{XY} = \frac{1}{n-1} \sum_{i=1}^n (X_i - \bar{X})(Y_i - \bar{Y})$$

- The sample correlation is:

$$r_{XY} = \frac{S_{XY}}{S_X S_Y}, |r_{XY}| \leq 1$$