

**Embodied Artificial  
Evolution:  
the Next BIG Thing?**

**Gusz Eiben**

**VU University Amsterdam**

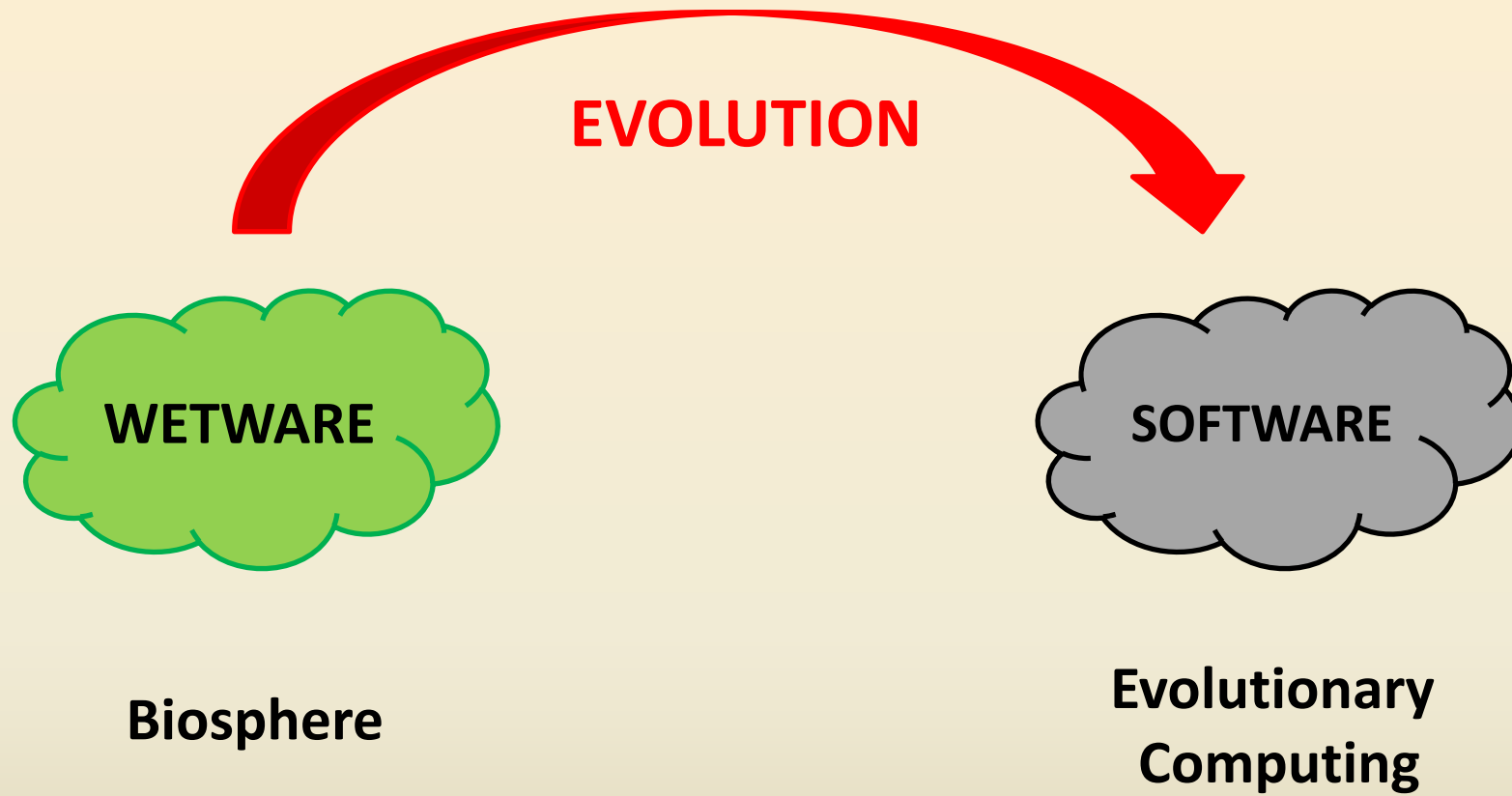
# Past, Present

- 19th century:

**evolution is a theory**, a passive, explanatory concept that helps us understand things

- 20<sup>th</sup> century:

**evolution is a tool**, an active, creative concept that helps us produce things (solutions for problems) **in digital spaces**



# Learnt through Evolutionary Computing

Engineering / mastering evolutionary processes

by

- designing evolvable objects (pieces of code, blueprints)
- designing mutation and crossover operators
- designing selection operators
- specifying fitness functions, reward mechanisms
- putting this all together and tuning it (DIVERSITY of alg's !)

for problem solving and simulation

# Learnt through Evol Comp (cont'd)



- Evolution can solve problems we don't fully understand and cannot clearly specify
- Evolution can cope with changing situations
- Evolution can come up with original, unexpected solutions (that can be reverse-engineered)



- Designing good EAs can be difficult (representation, parameters)
- No good theory
- Could take too long (can change with new hardware)

# Evolutionary computing and embodiment

- Evolution in **digital** space, result in **digital** space  
e.g., time tables, consumer models, robot controllers  
evolutionary optimization
- Evolution in **digital** space, result in **physical** space  
e.g., jet nozzle, satellite boom, Peter Bentley's coffee table  
evolutionary design / art
- Evolution in **physical** space, result in **physical** space  
embodied artificial evolution

# Past, Present, Future

- 19th century:

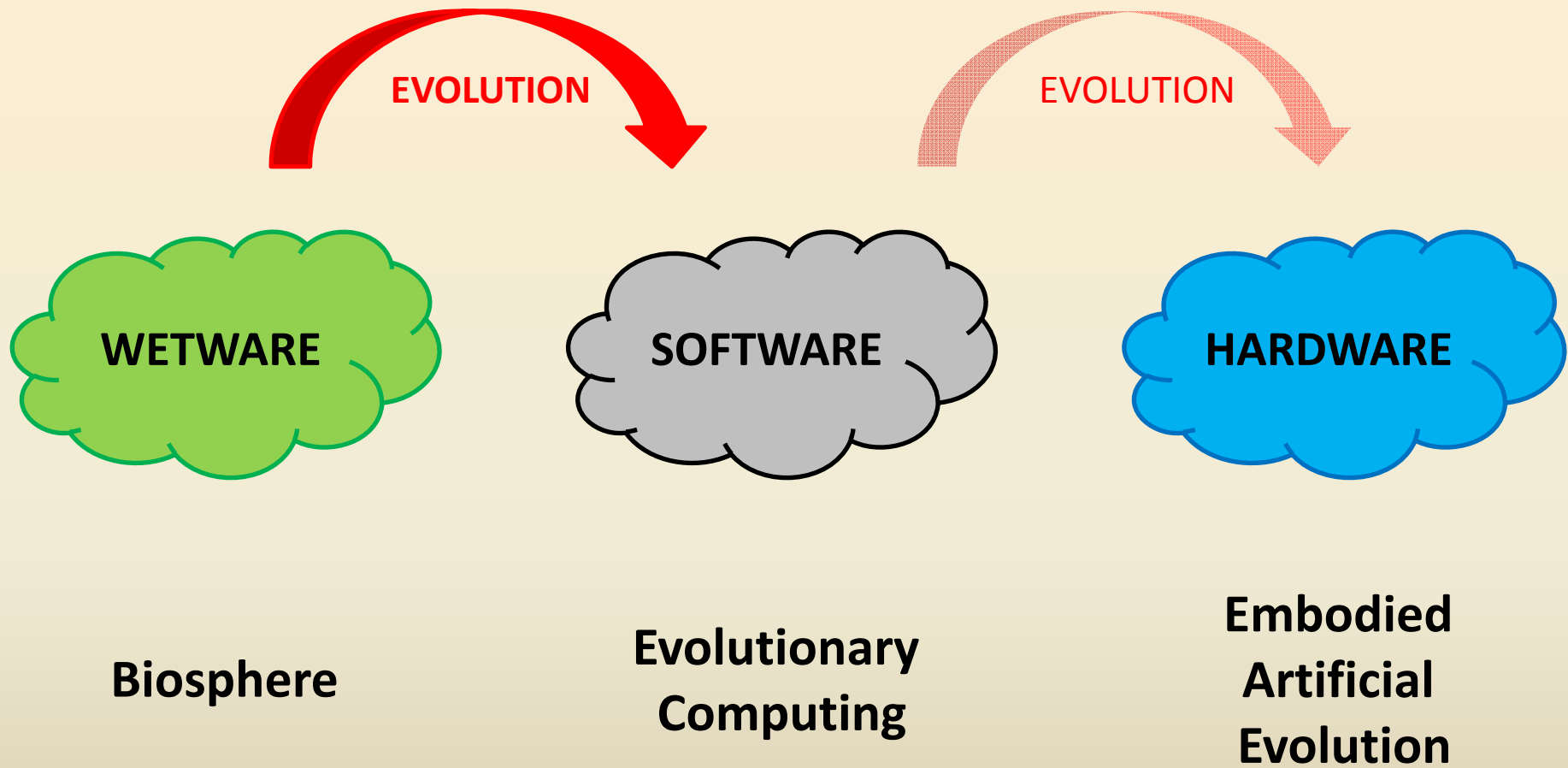
**evolution is a theory**, an explanatory concept that helps us understand things

- 20<sup>th</sup> century:

**evolution is a tool**, an active, creative concept that helps us produce things (solutions for problems) **in digital spaces**

- 21<sup>st</sup> century:

**evolution is a tool**, an active, creative concept that helps us produce things (solutions for problems) **in physical spaces**





# Embodied Artificial Evolution

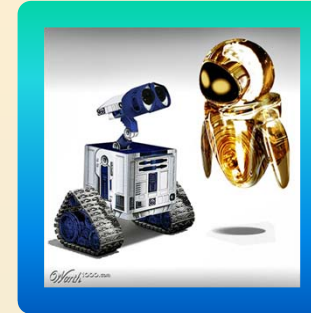
Old: Evolution of code (blueprint)

New: Evolution of things

1. Takes place in **physical objects**
2. Reproduction = **real birth** = new object made, survivor selection = **real death** = object gone
3. Reproduction and selection are **autonomous and asynchronous** (→ population size is inherently variable)
4. Fitness can be **task-based** and/or **open-ended**

# Application examples

- Artificial pets, robot companions, servants, explorers, ...



- Functional organisms, medical nano-robots, personal virus scanners



- Personal replicators (networked, evolutionary)



Note the difference: artifacts with or without inner controller,  
**Body vs. Body + mind**

# Motivation, benefits, impact

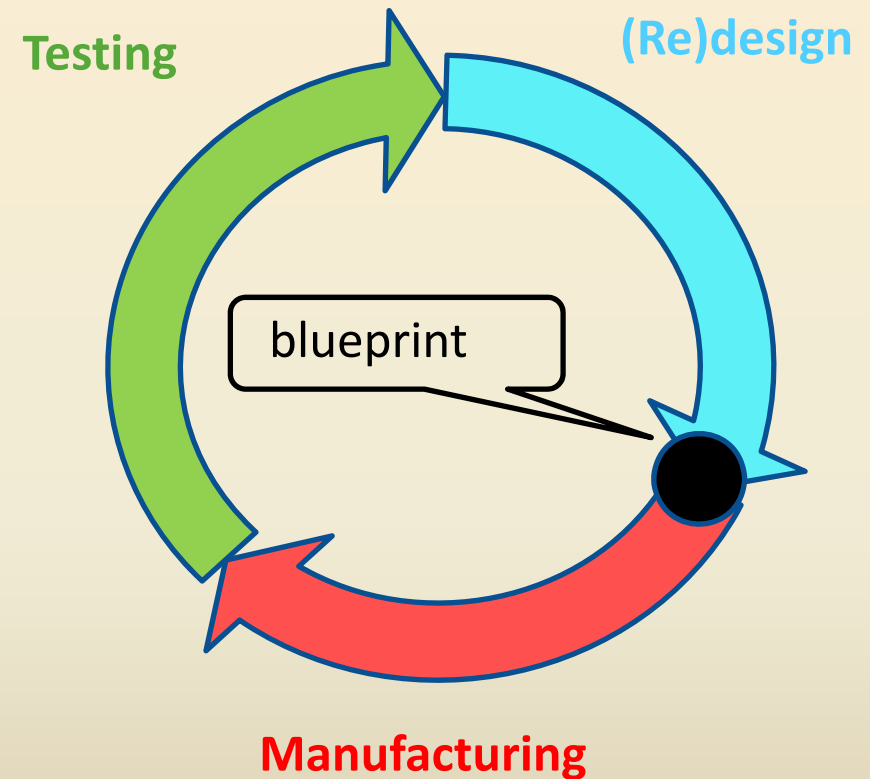
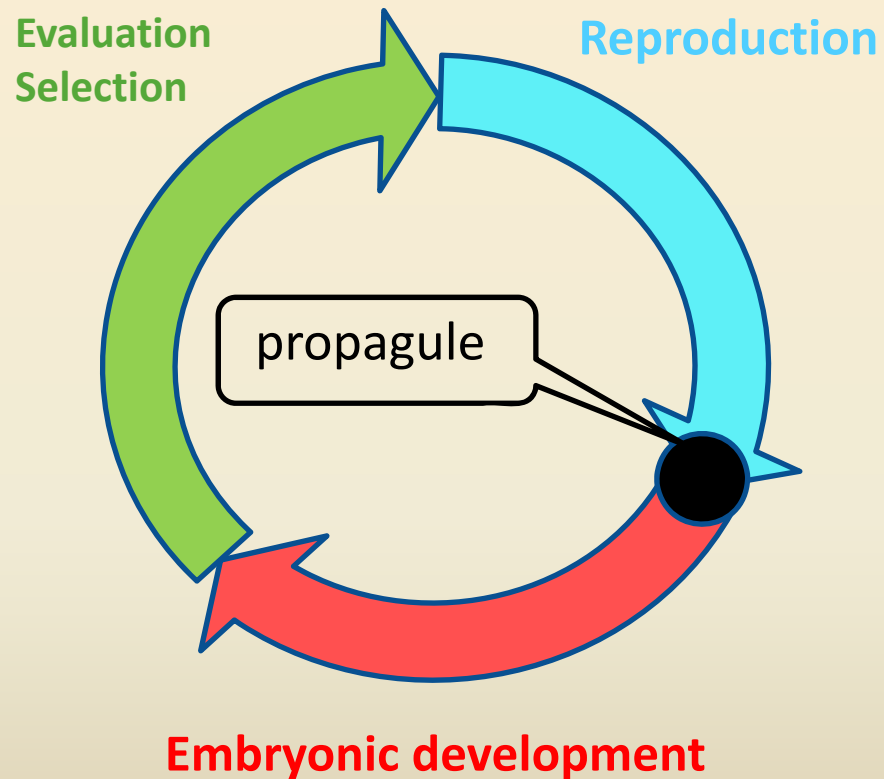
1. EAE / EoT is a **game changer in design & manufacturing**:
  - Old: design ends with manufacturing
  - New: design & manufacturing are one, intertwined continuous process, evolution → unexpected solutions
2. **New experimentalism for biology**: study evolution in a different medium by controllable and repeatable experiments → generalization, preconditions for evolution? Taxonomy? ...
3. **Redefines evolutionary computing** switch from digital to physical changes everything: MATTER MATTERS
4. EAE / EoT is a **game changer in computing & programming**:
  - Old: van Neumann architecture + computing and software (engineering) as we know it
  - New: HW = morphology, SW = control mechanisms, ???

# Physical medium ?

Huge diversity of approaches, under different umbrellas

- Hardware, mechatronics, plastics,
- Wetware bottom-up, chemistry
- Wetware top-down, biology
- Hybrids
- Functional fluids, programmable matter, microfluidics,
- .... ???

# A new game for “passive” stuff



# A new game for “active” stuff

WETWARE

HARDWARE



Cells

- very small
- self-replicating
- self-repairing
- self- ...

Robots

- very small to big
- programmable
- controllable
- sensors/actuators/controllers

**Sweet spot**

# Grand challenges

- **Body type**

Combine wetware with hardware (+software): self-\* and programmable

- **Reproduction - how to start**

Implement “birth” for human engineered physical devices (robots), artifacts (and “death” too, under selection)

- **Kill switch - how to stop**

Guarantee that human supervisors can shut down the system, if needed.

# Grand challenges cont'd

- **On-line in vivo design - UI & control**

- On-the-fly monitoring and steering by user preferences - selection
- Combination of autonomous and directed evolution. Freeze switch?

- **Evolvability & evolution speed**

Essential assessment criterion for the feasibility of potential applications.

- **Co-evolution of morphology & control (“body & mind”)**

- We cannot program these new guys the way we used to
- New HW, new SW, thus new computer, computing, etc. →
- New principles & methodology for development, testing, validation...
- Lifetime adaptation, learning, development , Lamarckism, ...



# ~~Conclusions~~ Closing remarks

- Evolution in the real world is different
- Computation in this new paradigm is different
  - new architecture for information processing / computing
  - redefines “program”, “programming”, software engineering, testing, validation, ect.
- Big Q's are implied:
  - Scientific (fundamental issues regarding evolution, notion of Life)
  - Technological (feasibility)
  - Applicability (remember IBM in the 1940ies)
  - Desirability (ethics, think of GMOs)
- Different communities → unifying vision / umbrella needed
- **Next BIG thing ?**