

Work of Adhesion

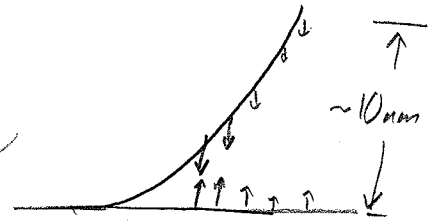
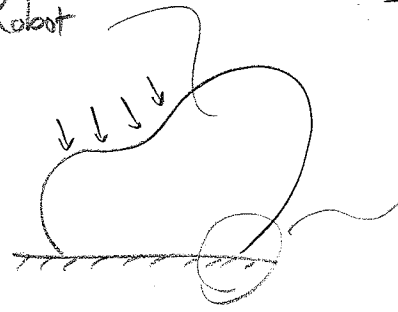
/ C. Majidi 6/3/12

"Soft Robot"

Potential Energy

- Elastic Strain
- Force
- Pressure
- Adhesion

Surface Traction
Mechanical Work

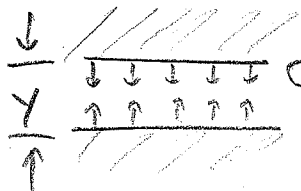


Surface/Interfacial Forces

- Electrostatic
- Permanent Polar (Capillary)
- Induced / Fluctuating Polarity (van der Waals)

①

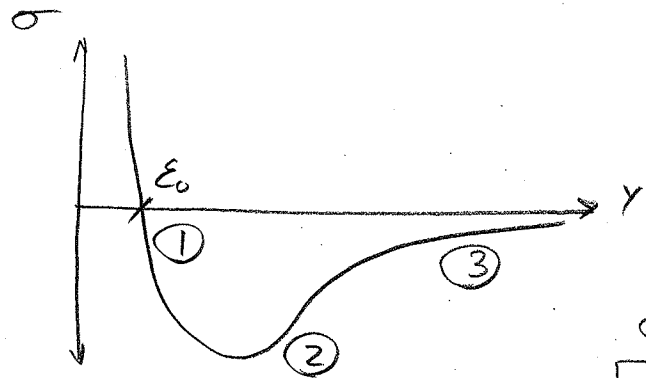
Lennard-Jones Potential



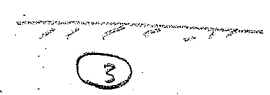
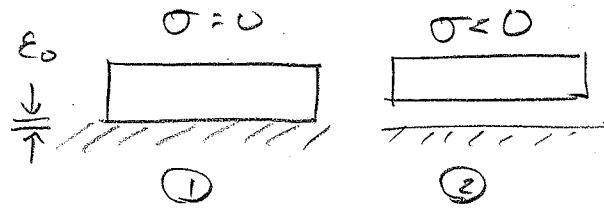
$$\sigma = \frac{\alpha}{y^{13}} - \frac{\beta}{y^7}$$

Nuclear Repulsion

v.d. Waals attraction



$$\sigma = 0$$



②

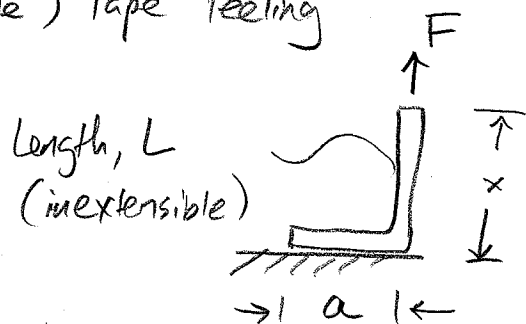
Work of Adhesion, $W_{ad} = \int_{\epsilon}^{\infty} -\sigma dy$

$\sim 10-100 \text{ mJ/m}^2$

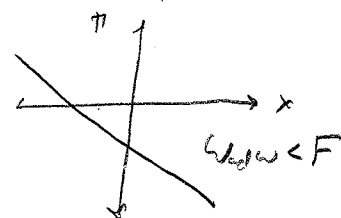
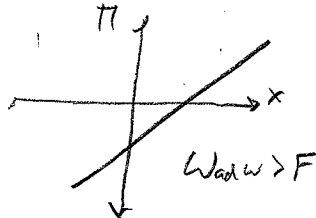
Potential Energy, $\Pi_{ad} = -[W_{ad}] \times [\text{Contact Area}]$

or $\Pi_{ad} = [W_{ad}] \times \underbrace{[\text{Non-Contact Area}]}_{\text{"Eulerian Coordinates"}}$

Example) Tape Peeling

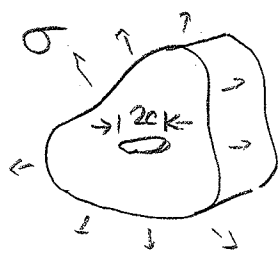


$\Pi = -Fx - W_{ad}wa$
 $= (W_{ad}w - F)x - W_{ad}wL$) $a = L - x$



(3)

Griffith Balance



"Poisson's Ratio", $\nu = 1/2$ (incompressible)

$\Pi = \underbrace{-\frac{\pi \sigma^2 c^2 (1-\nu^2)}{E}}_{\text{Mechanical (Ingles 1913)}} + \underbrace{2W_{ad}c}_{\text{Adhesion (Griffith 1920)}}$

At equilib., $\frac{d\Pi}{dc} = 0 \Rightarrow \boxed{\sigma = \sqrt{\frac{W_{ad} E}{\pi c (1-\nu^2)}}}$ Fracture Strength

(4)

Linear Elastic Fracture Mechanics (LEFM)

$$G_c = W_{ad}$$

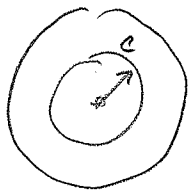
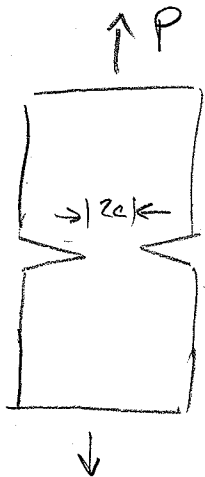
$$G_c = \frac{(1-\nu^2)K_I^2}{E}, \text{ "Strain Energy Release Rate"}$$

K_I = Mode I stress intensity factor

$$\text{Griffith Crack: } \begin{cases} \Pi_{ad} = 2W_{ad}c \\ K_I = \sigma\sqrt{2\pi c} \end{cases}$$

⑤

Circumferential Crack

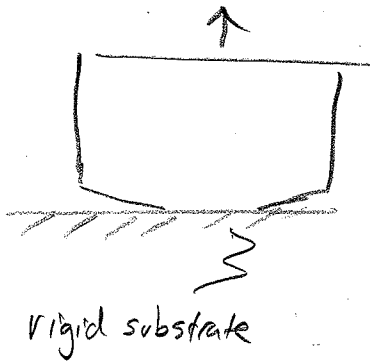


$$\left. \begin{aligned} K_I &= \frac{P}{2c\sqrt{\pi c}} \\ G_c &= \frac{(1-\nu^2)P^2}{4\pi E c^3} \end{aligned} \right\} \Rightarrow P = \sqrt{\frac{4\pi E W_{ad} c^3}{1-\nu^2}}$$

$$P_0 = \sqrt{\frac{4\pi E W_{ad} R^3}{1-\nu^2}}$$

⑥

Contact Mechanics



$$G = \frac{(1-\nu^2)K_I^2}{2E}$$

Flat Punch: $P_0 = \sqrt{\frac{8\pi E W a R^3}{1-\nu^2}}$

Hemisphere: $P_0 = \frac{3}{2}\pi W a R$
(JKR theory)

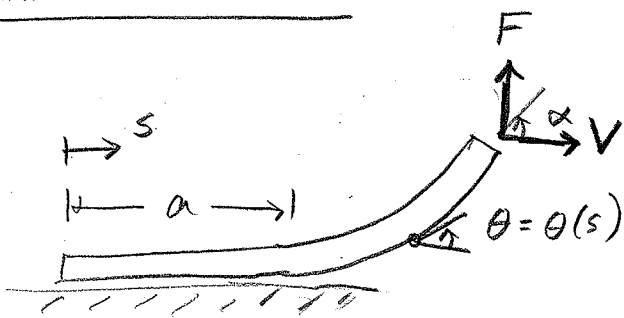
"Effects of contact shape on the scaling of biological attachments"

Spoleak, Gorb, Gaw, Arzt

Proc. Roy. Soc. A 461, 305-319 (2005)

(7)

Kendall Peel Model



$$\theta(a) = 0$$

$$\theta(L) = \alpha \text{ (if constrained)}$$

$$W a \times [\text{width}]$$

$$\Pi = \int_a^L \left\{ \underbrace{\frac{1}{2} D \left(\frac{d\theta}{ds} \right)^2}_{\text{Elastic Strain}} - \underbrace{F \sin \theta - V \cos \theta}_{\text{Mechanical Load}} \right\} ds - \underbrace{W a}_{\text{Adhesion}}$$

(8)

Minimize Π w.r.t. θ and a :

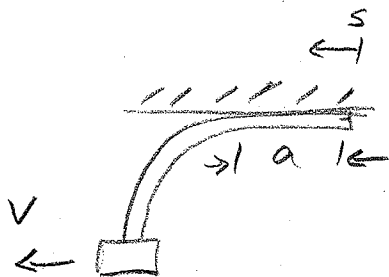
$$\left. \begin{aligned} \theta'' &= \frac{V}{D} \sin \theta - \frac{F}{D} \cos \theta \\ \theta'(a) &= \sqrt{\frac{2\omega}{D}} \\ \theta(a) &= 0 \\ \theta(L) &= \alpha \quad \text{or} \quad \theta'(L) = \frac{M}{D} \end{aligned} \right\} \begin{array}{l} \text{Microfiber Adhesion} \\ \begin{array}{c} \text{Diagram 1: Fiber on substrate with upward force } \uparrow \\ \text{Diagram 2: Fiber on substrate with downward force } \downarrow \end{array} \\ V = F = 0 \\ \alpha = \frac{\pi}{2} \\ \boxed{a = L - \frac{\pi}{2} \sqrt{\frac{D}{2\omega}}} \end{array}$$

$$\text{Stable Side Contact} \Leftrightarrow L > \frac{\pi}{2} \sqrt{\frac{D}{2\omega}} = L_{cr}$$

(9)

Shear-Activated Adhesion

$$F = 0, \alpha = \frac{\pi}{2}, V \geq 0$$



$$a = \frac{C}{K} \left\{ K(C^2) - F\left(\frac{\pi}{4}, C^2\right) \right\}$$

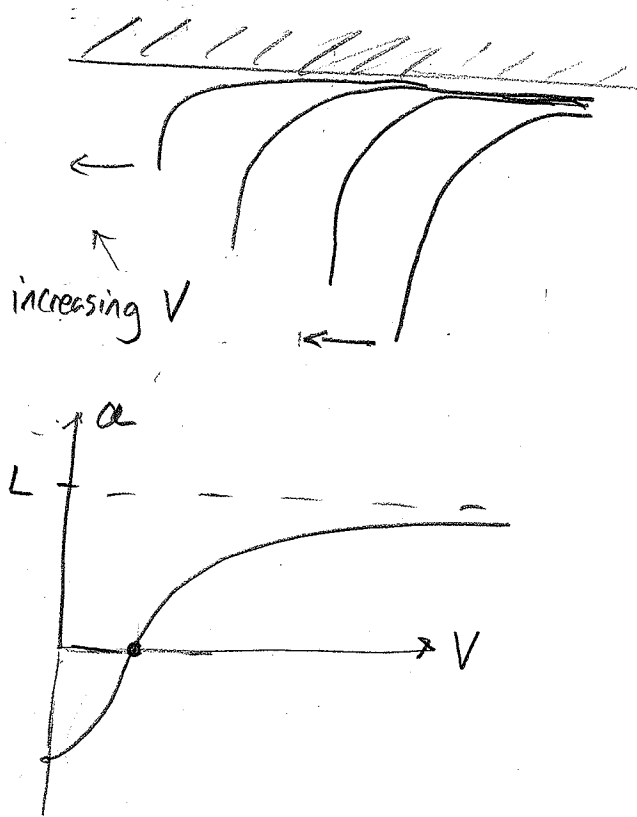
$$C = \sqrt{\frac{1}{1 + \omega/2V}}$$

$$K = \sqrt{\frac{V}{D}}$$

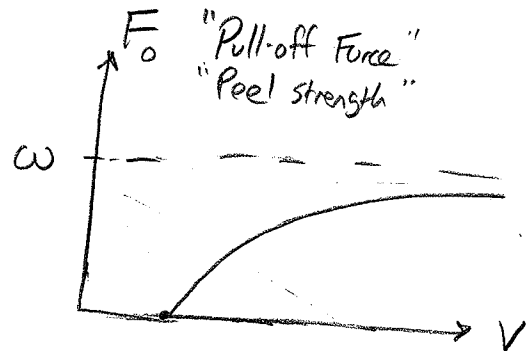
$F(\phi, m)$ = "Elliptic Integral of the First Kind"

$K(m) = F\left(\frac{\pi}{2}, m\right)$ = "Complete Elliptic Integral of the First Kind"

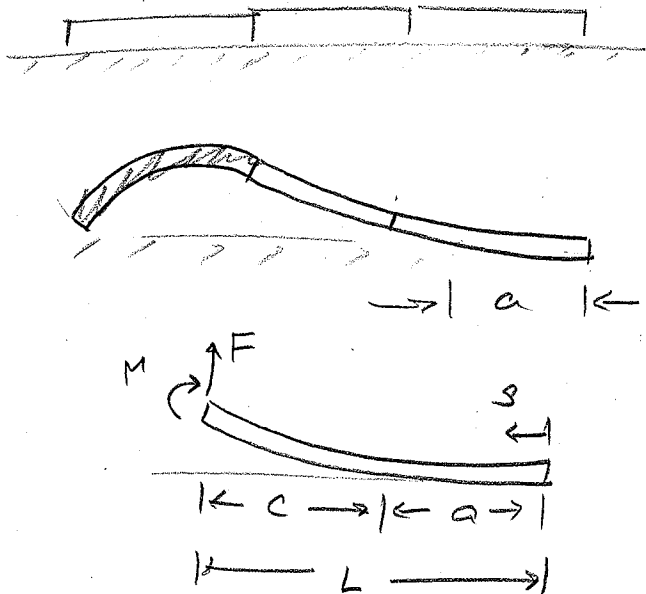
(10)



$$V=0 \Rightarrow a \leq 0 \text{ (no contact)}$$



Soft Robot Undulation



$$\Theta'' = -\frac{F}{D} \cos \Theta \approx -\frac{F}{D}$$

$$\Theta' = -\frac{F}{D} s + C_1$$

$$\Theta = -\frac{F}{2D} s^2 + C_1 s + C_2$$

$$\Theta(a) = 0, \quad \Theta'(a) = \sqrt{\frac{2\omega}{D}}, \quad \Theta'(L) = \frac{M}{D}$$

$$C_1 = \frac{M}{D} + \frac{FL}{D} \approx \sqrt{\frac{2\omega}{D}} + \frac{F_0}{D}$$

$$\therefore \boxed{M + F(L-a) = \sqrt{2\omega D}}$$

"Moment Discontinuity"

$$M_{ad} = \sqrt{2\omega D}$$