

A woman with long dark hair and large gold earrings is holding a yellow cup. In the background, a robot is visible. The scene is slightly blurred, suggesting a focus on the interaction.

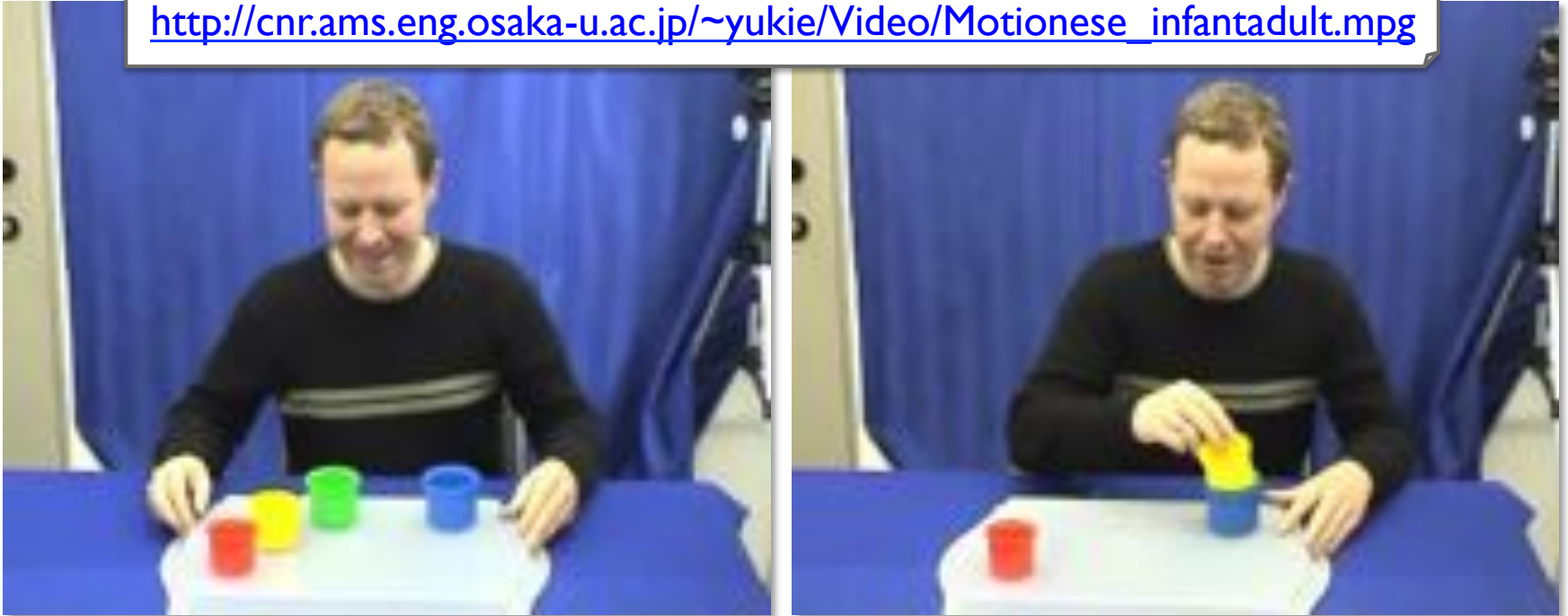
What Should Robots Learn from Caregiver-Infant Interaction?

Yukie Nagai, Osaka University

ShanghAI Lecture, Osaka, October 20, 2011

How Do Caregivers Teach Actions?

http://cnr.ams.eng.osaka-u.ac.jp/~yukie/Video/Motionese_infantadult.mpg



[Rohlfing et al., 2006; Nagai & Rohlfing, 2007-2009]

- Caregivers **exaggerate their actions** when interacting with *infants* vs. *adults* (i.e., **motionese**) [Brand et al., 2002].



How Do People Teach Actions?

http://cnr.ams.eng.osaka-u.ac.jp/~yukie/Video/SocialRobot_02_subject.mpg



[Muhl & Nagai, 2007; Nagai et al., 2008]

- People tend to **exaggerate actions** directed to robots.



Take Home Message

1. **Teachers guide** infants'/robots' learning.

e.g.) Exaggeration of motion, social signals, etc.

Both a teacher and a learner mutually shape interaction.

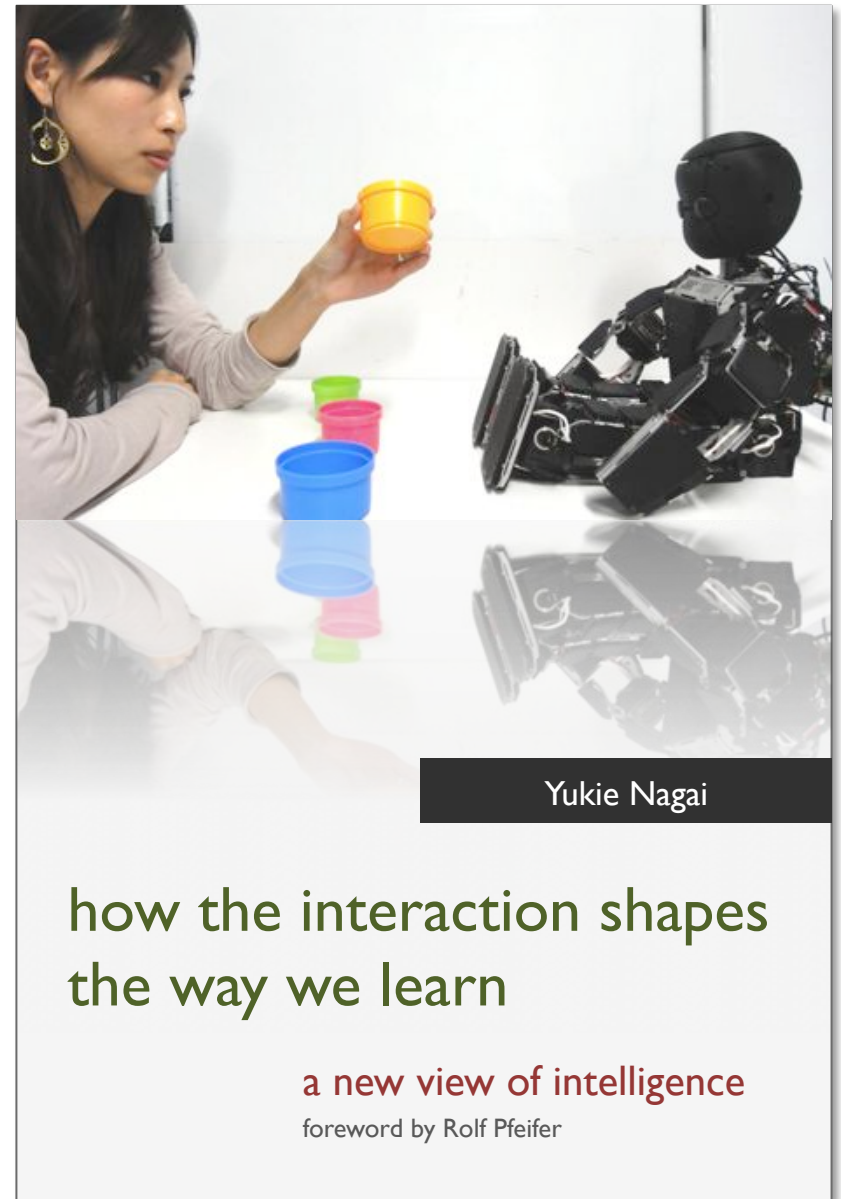
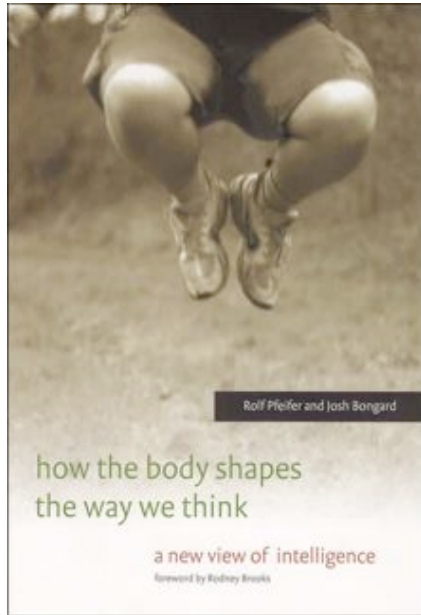
2. **Infants/robots elicit** teachers' scaffolding.

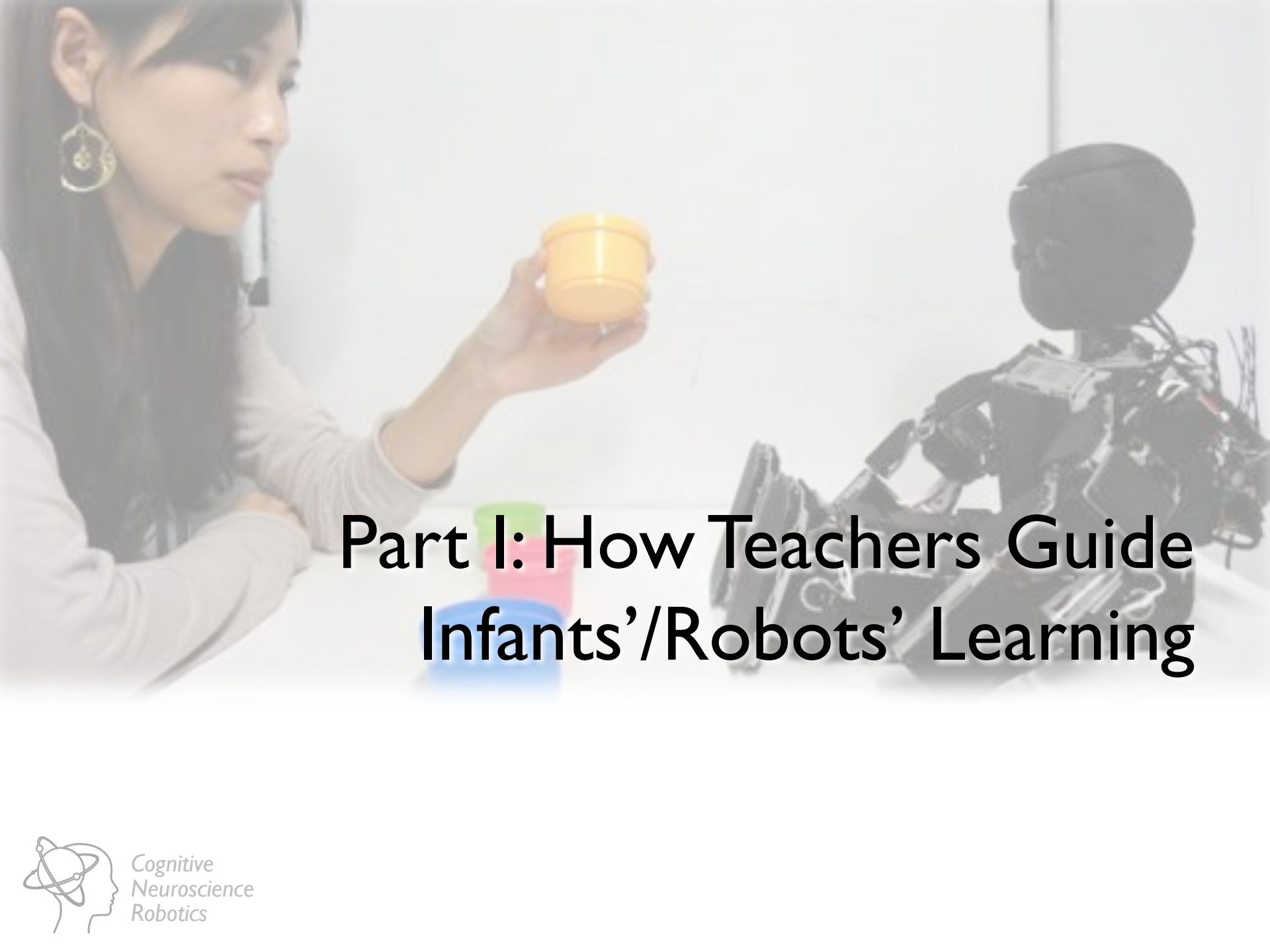
e.g.) Immature perception and actions, etc.



To Be UNpublished...

Inspired by ...



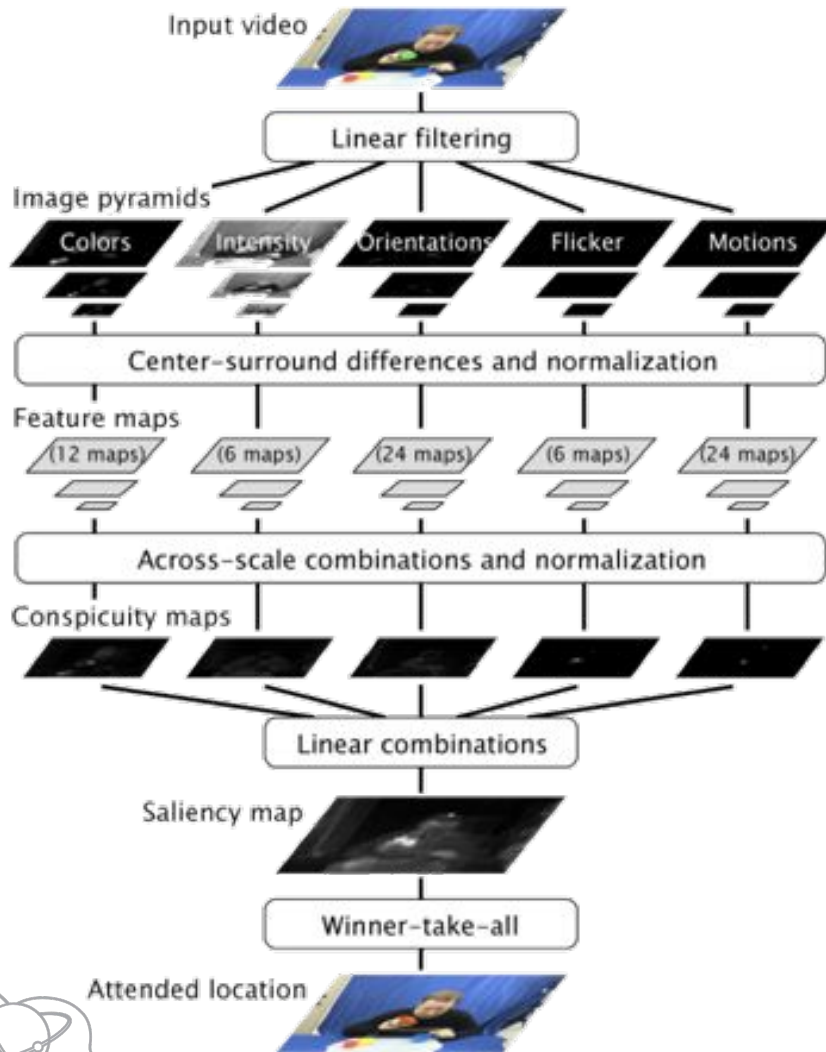
A woman with long dark hair and large gold earrings is holding a yellow plastic cup towards a humanoid robot. The robot has a black head and torso with visible mechanical joints and wires. In the background, there are colorful blocks (green, pink, blue) on a table. The scene is set in a bright, clean laboratory or classroom environment.

Part I: How Teachers Guide Infants'/Robots' Learning



Cognitive
Neuroscience
Robotics

From Attention to Learning



- Young infants learn based on **bottom-up attention**.

[Frank et al., 2009;
Golinkoff and Hirsh-Pasek, 2006]

- **Saliency-based** attention

[Itti et al., 1998; 2003]

- Saliency = difference from surroundings (e.g., color, edge, motion)
- No task or context knowledge
- Similar to young infants



Where Model Attends?

http://cnr.ams.eng.osaka-u.ac.jp/~yukie/Video/Motionese_saliency.mpg



Experiment [Nagai & Rohlfing, 2009]

Question:

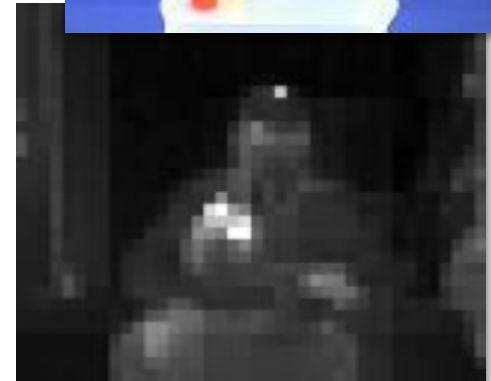
- When and what **caregivers emphasize?**
- Where the saliency model attends?

Method:

- Comparing attended locations in:
 - *Infant*-directed action
 - *Adult*-directed action

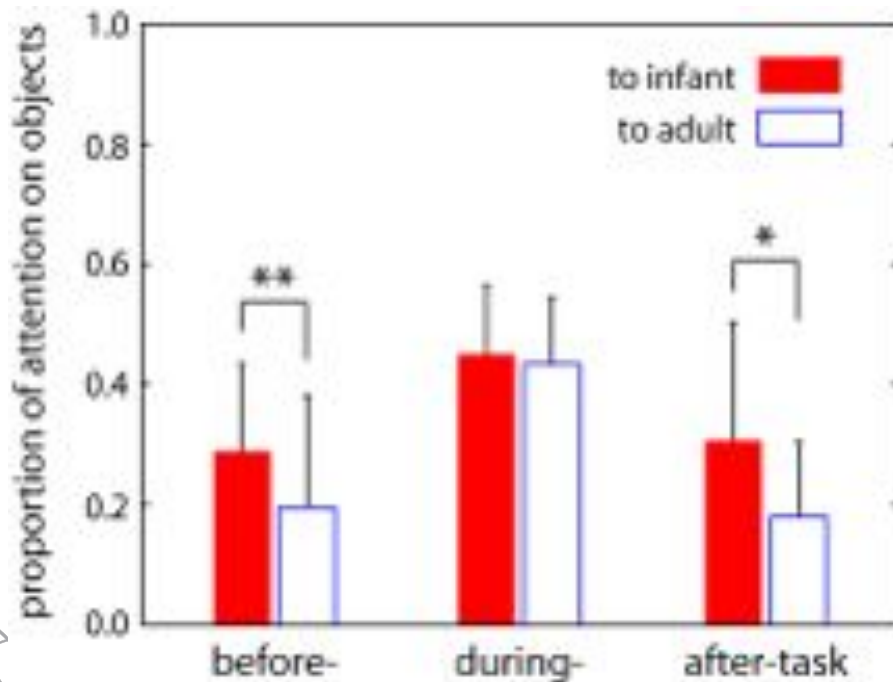
Subjects:

- 15 parents of 8- to 11-month-old infants



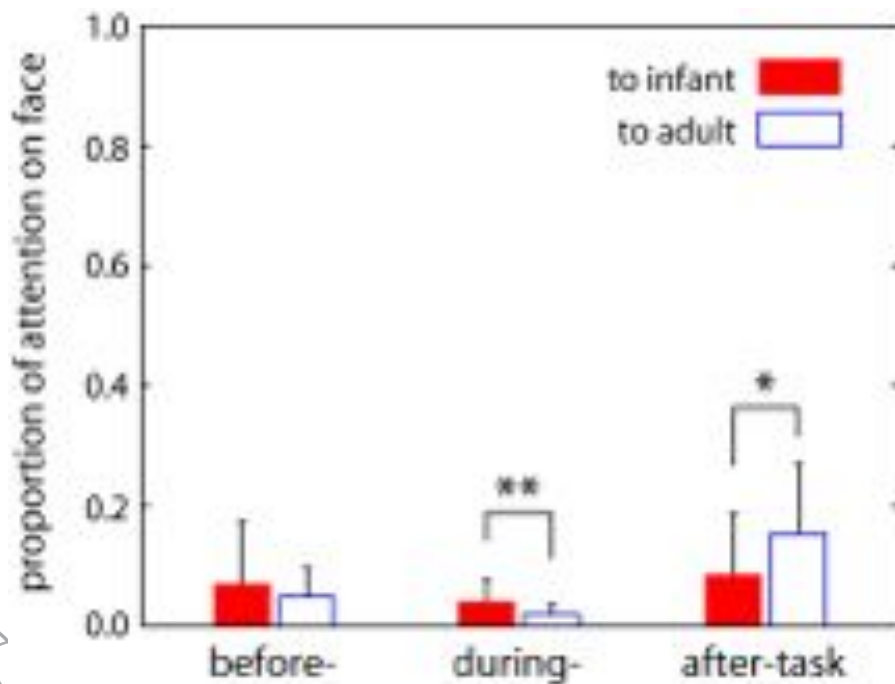
Result 1: Attention to Objects

- Highlight **initial and final states (i.e., goal)** of cups
 - Take long pause before and after task
 - Underline where cups are located



Result 2: Attention to Parent's Face

- **Frequent social signals** indicating significant events
 - Pause cup-handling movement
 - Talk to and smile at infants



Summary of Part I

- How teachers guide infants'/robots' learning

- Significantly **modify their actions**

- **Highlight important information** in the actions (e.g., goal and sub-goals)

- **Guide bottom-up attention** to the important information



A woman with long dark hair and large gold earrings is holding a yellow plastic cup. She is looking towards a robot on the right. The robot has a black head and a complex mechanical body. In the foreground, there are several colorful plastic cups (yellow, green, pink, blue) stacked or arranged. The background is a plain white wall.

Part 2: How Infants/Robots Elicit Teachers' Scaffolding



Factors Inducing Motionese



- Infant's **age**
 - 6-8 m > 11-13 m > Adult
[Brand et al., 2002]
 - His/her **appearance**
 - Simulation of baby-like face
[Muhl & Nagai, 2007; Nagai et al., 2008]
 - Baby-like face > infant > adult
[Vollmer et al., 2009]
- What about **feedback from a learner** (e.g., gaze, gesture)?



Experiment [Nagai et al., EpiRob2010]

Question:

- How **the visual attention** of a robot influences teachers' action?

Method:

- Comparing actions directed to a robot with:
 - *Bottom-up* attention
 - *Top-down* attention

Subjects:

- 16 university students



- 45 cm of tall
- A camera attached to the head



Two Conditions

http://cnr.ams.eng.osaka-u.ac.jp/~yukie/Video/Motionese_robot.mov

Bottom-up attention



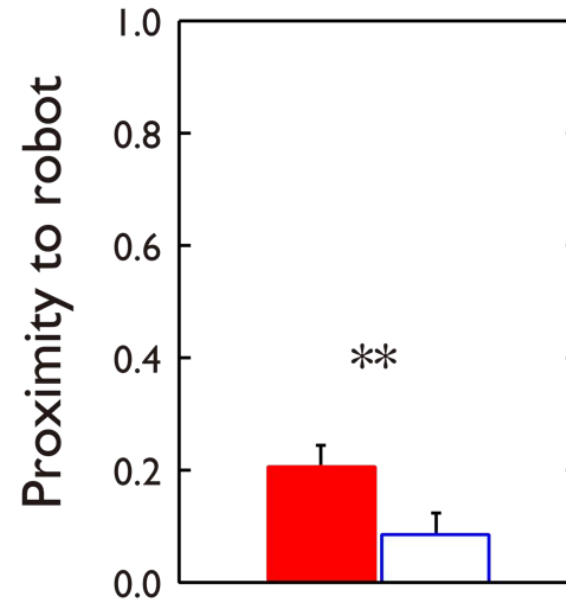
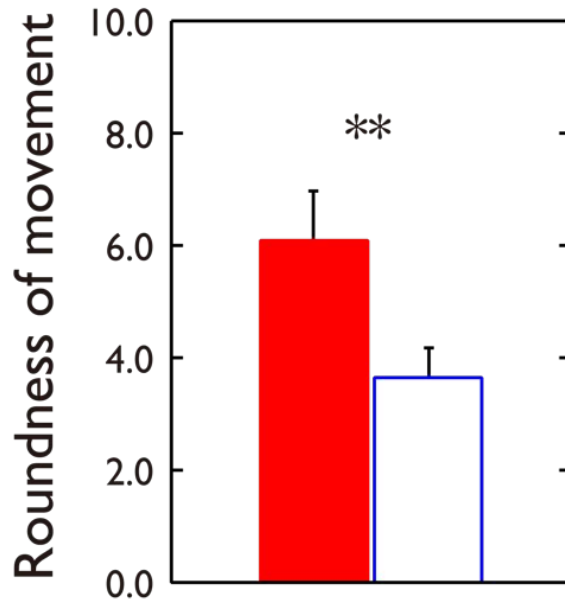
Top-down attention



- Saliency model [Itti et al., 2003]
 - Look at **the most conspicuous** location
 - Don't know the goal
 - **Younger** infants (8-11M)
- Wizard of Oz
 - Anticipate **the goal** and **the next action**
 - Know the goal
 - **Older** infants (12-24M)

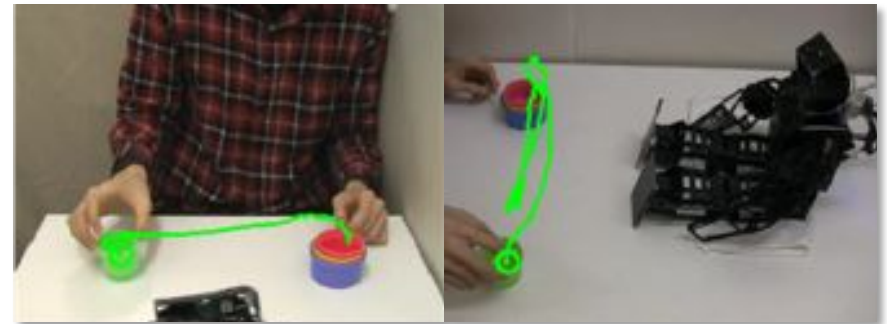


Result I: Spatial Action Modifications

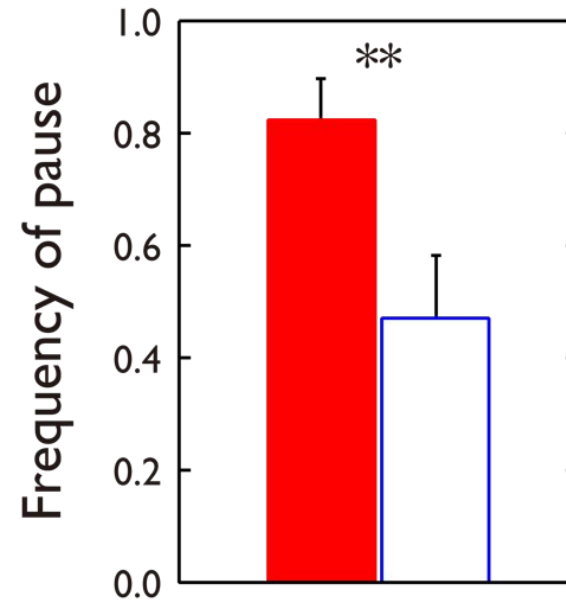
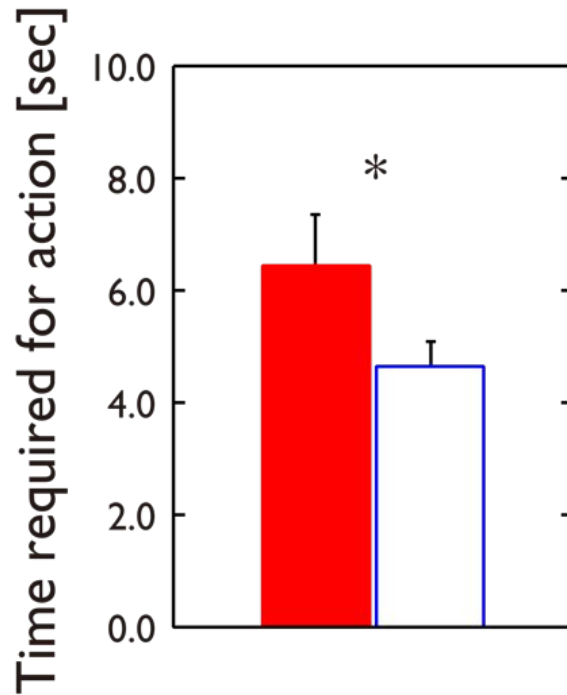


 Saliency model

 Wizard of Oz

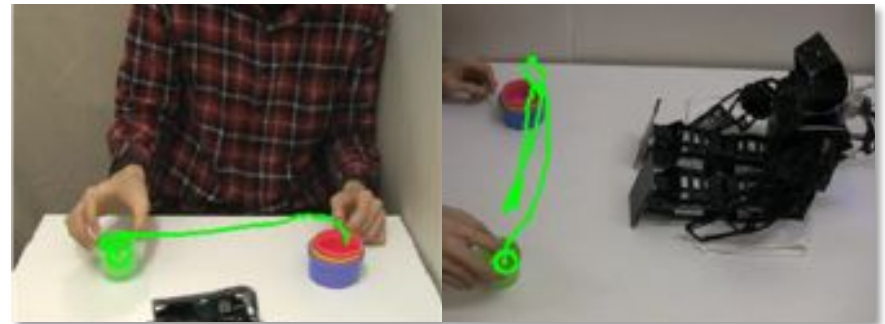


Result 2: Temporal Action Modifications



 Saliency model

 Wizard of Oz



Summary of Part 2

- How infants/robots elicit teachers' scaffolding
 - Respond with **immature attention**
 - Exhibit **undifferentiated (or no)categories** of actions
 - **Induce** teachers to **exaggerate actions**





Conclusion



Cognitive
Neuroscience
Robotics

Take Home Message

1. Teachers' exaggeration of actions guides infants'/robots' attention and thus learning.

Both a teacher and a learner mutually shape interaction.

2. Immature attention of infants/robots elicit teachers' exaggeration of actions.



The Power of Scaffolding!

<http://cnr.ams.eng.osaka-u.ac.jp/~yukie/Video/Scaffolding.mov>



Achieve the goal with
appropriate scaffolding 😊



Puzzled by
inappropriate scaffolding ☹️

(Videos adapted from YouTube)



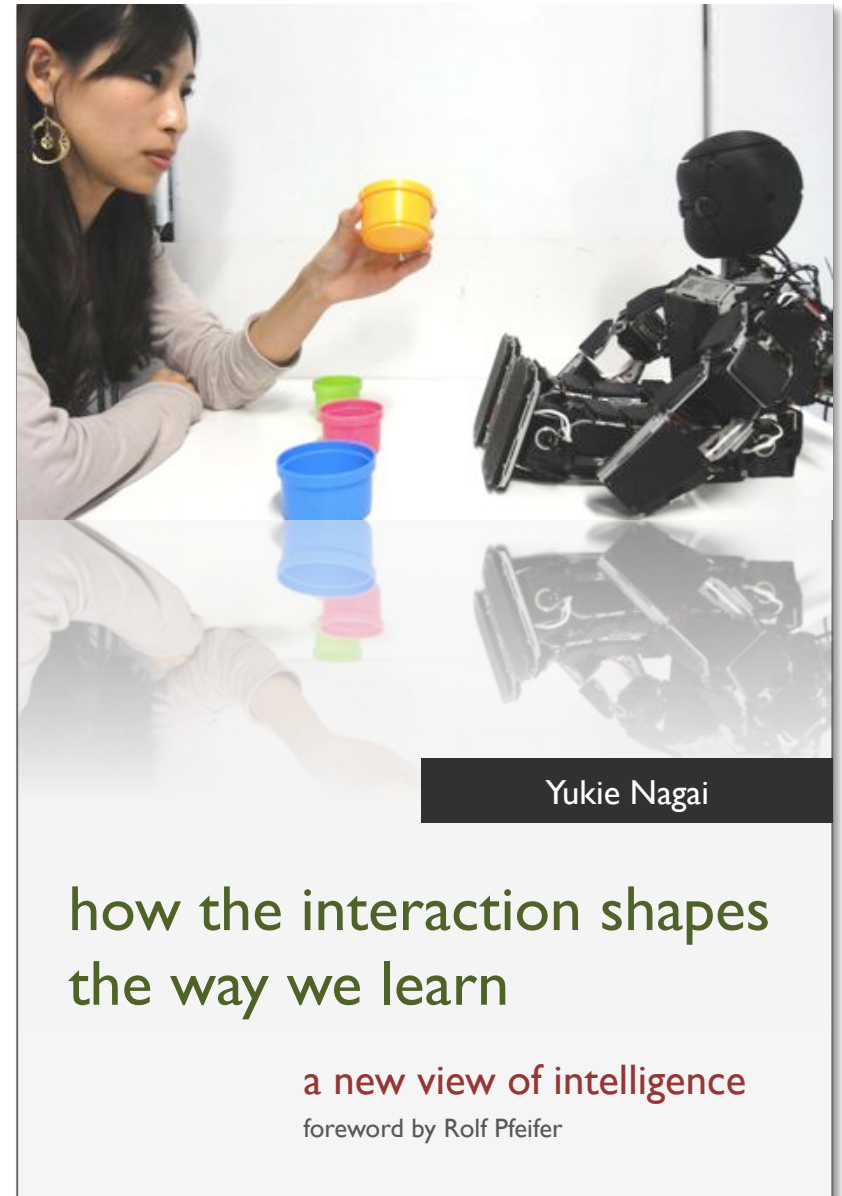
Thank you!

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To be UNpublished...



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