

HJD Type Crane PLC transformation in control circuit

HJD型克令吊控制电路的PLC改造

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Abstract

Background. HJD type crane is widely used in domestic ships. Traditional HJD type crane adopts relays and contactors for secondary circuit control. The coils and contacts are easily burned after long-term use, frequently causing accidents.

Aims and Approach. The chief aim of the present work is provide an available way shifting to PLC control and reducing the use of coils and contacts. PLC, namely, programmable logic controller, is a digital computer used for automation and control. PLCs support multiple analogue and digital inputs and outputs arrangements, with extended temperature ranges, immunity to electrical noise, and resistance to vibration and impact. PLC used in this paper is Siemens S7-200.

Conclusion. In this paper, The PLC transformation, including basic protection control process, rose and fall process, brake process, low/medium/high-speed process, has been supplied after analyzing the principle of control circuits. There are no failures in experiment after long-term usage.

Outline

Thesis Sentence: The PLC transformations and the method of implementation, including basic protection control process, rose and fall process, brake process, low/medium/high-speed process, list below.

I. Reconstruction of basic protection control process

A. Overload protection of fan motor and crane motor

1. Fan motor overload protection is achieved by fan thermal relay FR2.
2. Crane motor overload protection is achieved by crane motor thermal relay FR1.

B. Motor windings overheating protection is achieved by motor temperature controller ST.

C. Power supply missing phase and circuit break protection are achieved by zero-voltage relay KA1.

D. Emergency forced running is achieved by the contactor SB.

II. Reconstruction of rose and fall process

A. Rose process is achieved by steering control contactor Q0.2.

B. Fall process is achieved by steering control contactor Q0.3.

C. DC delay time relay is required in reversing at high speed.

III. Reconstruction of brake process

A. In normal rise or fall state, parking brake coil pulls in,mechanical parking brake operates.

B. In medium/high gear, DC master switch disconnect, low speed winding connects realizing automatic grade braking.

IV. Reconstruction of low/medium/high-speed process

A. Low-speed process

1. The crane will run in operational status by releasing rise or fall contactor and the braking contactor.
2. The shift from low-speed to medium-speed is achieved by energize medium-speed winding power.

B. Medium-speed process

1. Medium speed contactor is self-locking and interlocking with low/high speed contactor.
 2. Braking contactor and fan contactor make sure the Motor does not run at medium speed.
- C. High-speed process
1. Motor should not run in high speed when heavy loaded.
 - a. The detection of load is achieved by load relay.
 - b. The protection of overload is achieved by load contactors.
 2. The diagram of wiring and control logic has been uploaded to PLC

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