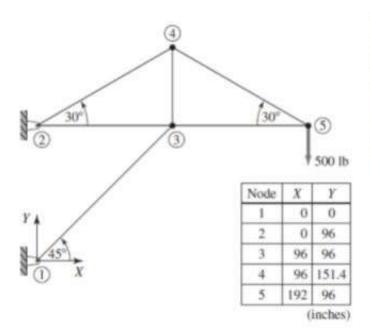
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Problem Statement



The cantilever truss shown here was constructed by a builder to support a winch and cable system to lift and lower construction materials. The truss members are 1.75x3.5in southern yellow pine. E=2x106 psi.

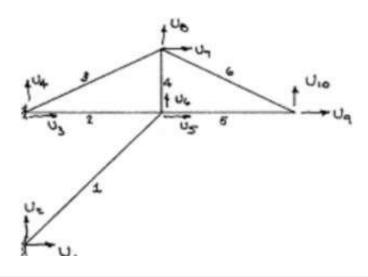
Part 1

Analyze the truss using Mathcad, Matlab, etc. calculate:

- A. The global displacement components of all unconstrained nodes.
- B. The axial stress and strain in each member.
- C. Reaction forces at the constrained nodes.

Please use the element numbering system shown below.

Part 2



clc
clear all

Connectivity table, node coordinate matricies, and problem setup

```
3 4;
3 5;
4 5]; %connectivity table defining 2d trusses

node_coordinates = [0 0;
0 96;
96 96;
96 151.4
192 96]; %coordinate table of node locations

stationary_DOF = [1 2 3 4]; %vector of constrained DOF numbers
F = [0 0 0 0 0 -500]'; %left DOFs 1-4 out since those are unknown reactions
scale = 150; %displacement scale so we can plot the results later

DOF = 2; %degrees of freedom per node
E = 2e6; %modulus of elasticity (Southern Pine)
A = 1.75*3.5; %cross-sectional area of a truss
```

Calculation of element stiffness matrix and population of global stiffness matrix

```
num nodes = size(node coordinates, 1);
k global = zeros(num nodes*DOF); %initialization of empty global stiffness matrix
T = zeros(size(connect, 1), 4);
DOF ids = zeros(4, size(connect, 1));
for i = 1:size(connect, 1)
    element node1 = connect(i, 1); %transforms global node into node numbers relative to elem
ent
    element_node2 = connect(i, 2);
    %pick x coordinates of truss out of node coordinate matrix
    x1 = node coordinates(element node1, 1);
    x2 = node coordinates (element node2, 1);
   %pick y coordinates of truss out of node coordinate matrix
    y1 = node coordinates(element node1, 2);
    y2 = node coordinates (element node2, 2);
    truss length = sqrt((x2-x1)^2 + (y2-y1)^2); %truss length
    C = (x2-x1)/truss length; %cosine of truss defining angle
    S = (y2-y1)/truss length; %sine of truss defining angle
    %DOF of nodes associated with truss
     \texttt{DOFaddress} = [(\texttt{element node1*2}) - 1 \ (\texttt{element node1*2}) \ (\texttt{element node2*2}) \ (\texttt{element node2*2}) \ ) 
];
    k local = (A*E/truss length)*[C^2 C*S -C^2 -C*S;
                                     C*S S^2 -C*S -S^2;
                                     -C^2 -C*S C^2 C*S;
                                     -C*S -S^2 C*S S^2]; %local stiffness matrix
    T(i,:) = E/truss length*[-C -S C S]; %rotation matrix for solving for stresses later
    DOF ids(:,i) = DOFaddress'; %ids of DOFs associated with this truss
    for i = 1:4 %adds local stiffness matrix to global stiffness matrix
```

Reducing global stiffness matrix

```
dim = num nodes*2-length(stationary DOF);
k reduced = zeros(dim); %initialized reduced stiffness matrix
DOFfree = ones(1, num nodes*2); %initialize mask indicating free DOFs
%populate mask as appropriate
for i = 1:length(stationary_DOF)
    DOFfree(stationary DOF) = 0;
end
a = 1;
b = 1;
%reduce global stiffness matrix according to mask
for i = 1:length(DOFfree)
    for j = 1:length(DOFfree)
        if (DOFfree(i) && DOFfree(j))
            k_reduced(a,b)=k_global(i,j);
            if (a == b)
                U label(a) = i;
            b = b+1;
            if (b > dim)
              b = 1;
              a = a+1;
            end
        end
    end
end
U label = U label';
k reduced
```

```
k reduced =
  1.0e+05 *
                  0 0 -1.2760
  3.0032 0.4511
                                       0
               0 -2.2112 0
  0.4511 2.6623
                      0 -0.8291 0.4785
      0
         0 1.6582
        -2.2112
               0
      0
                      2.7634 0.4785 -0.2761
  -1.2760
         0 -0.8291
                      0.4785 2.1051 -0.4785
           0
               0.4785 -0.2761 -0.4785
                                  0.2761
```

Solving simultaneous equations for unconstrained displacements

```
U = (inv(k_reduced)*F);
U = [0; 0; 0; 0; U]
```

Post-processing

-0.1016

Calculate force vector (including reactions)

```
force_vector = k_global*U
```

```
force_vector =

1.0e+03 *

1.0000
1.0000
-1.0000
-0.5000
0.0000
-0.0000
-0.0000
-0.0000
-0.5000
```

Calculate stress in each element

```
%displacements associated with each truss in matrix form
truss_displacements = zeros(4, 6);

%populate it according the the nodes each truss is connected to
for i=1:size(DOF_ids, 1)
    for j=1:size(DOF_ids, 2)
```

```
truss_displacements(i, j) = U(DOF_ids(i,j));
end
end
stress = diag(T*truss_displacements)
```

```
stress =

-230.8920
    21.8080
    163.3219
-163.2653
-141.4573
163.3219
```

Calculate strain in each element

```
strain = stress/E
```

```
strain =

1.0e-03 *

-0.1154
0.0109
0.0817
-0.0816
-0.0707
0.0817
```

Plot original and deformed structure

```
U = U(length(stationary_DOF)+1:end) * scale;
newNodeCo = node_coordinates;

%increment original node coordinates by displacements
for i = 1:length(U_label)
    if (~mod(U_label(i),2))
        node = U_label(i)/2;
        newNodeCo(node,2) = newNodeCo(node,2) + U(i);
    else
        node = ceil(U_label(i)/2);
        newNodeCo(node,1) = newNodeCo(node,1) + U(i);
    end
end
dotSize = 25;

%plot structures
pbaspect([1 1 1])
```

```
hold on
xlim([-10, 200])
ylim([-10, 200])
grid()
%plot nodes just for fun
scatter(node coordinates(:,1),node coordinates(:,2),dotSize,[1 0 0],'filled')
scatter(newNodeCo(:,1),newNodeCo(:,2),dotSize,[.49 .99 0],'filled')
%plot each truss
for i = 1:size(connect, 1)
   element node1 = connect(i, 1);
   element node2 = connect(i, 2);
   X = [node coordinates(element node1,1), node coordinates(element node2,1)];
   Y = [node coordinates(element node1,2), node coordinates(element node2,2)];
   line(X,Y,'Color', 'red')
   X = [newNodeCo(element_node1,1), newNodeCo(element_node2,1)];
   Y = [newNodeCo(element node1,2), newNodeCo(element node2,2)];
   line(X,Y,'Color', 'green')
end
quiver(node_coordinates(end, 1), node_coordinates(end, 2), 0, -30, 'Color', 'k', 'MaxHeadSize
', 0.75)
legend('original structure', 'deformed structure')
```

