

# Mathematica Computations

## Sunder Sethuraman and Shankar Venkataramani

This is the accompanying Mathematica notebook for the computations supporting the paper “**COUPLED KPZ EQUATIONS AND THEIR DECOUPLEABILITY**” by Fu, Funaki, Sethuraman, and Venkataramani.

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### Section 2.2: ODE analysis of decoupleability for $n = 2$ .

```
In[1]:= n = 2;
vars = Table[x[i], {i, 1, n}];
ϵ = Table[0, {i, 1, n}, {j, 1, n}];
ϵ[[1, 2]] = -1; ϵ[[2, 1]] = 1;
```

We begin by defining the variables and constructing  $\epsilon$ , the permutation matrix/generator for rotations in the plane, as it is used in the Proof of Prop. 2.5.

```
In[5]:= f = a3 x[1]^3 + 3 a2 x[1]^2 x[2] + 3 a1 x[1] x[2]^2 + a0 x[2]^3
```

```
Out[5]= a3 x[1]^3 + 3 a2 x[1]^2 x[2] + 3 a1 x[1] x[2]^2 + a0 x[2]^3
```

```
In[6]:= r = Table[Simplify[D[f/6, x[i], x[j], x[k]]], {i, 1, n}, {j, 1, n}, {k, 1, n}];
```

```
In[7]:= dør =
Table[Sum[r[[m, j, k]] ϵ[[i, m]] + r[[i, m, k]] ϵ[[j, m]] + r[[i, j, m]] ϵ[[k, m]], {m, 1, n},
{i, 1, n}, {j, 1, n}, {k, 1, n}]
```

```
Out[7]= {{-3 a2, -2 a1 + a3}, {-2 a1 + a3, -a0 + 2 a2}}, {{-2 a1 + a3, -a0 + 2 a2}, {-a0 + 2 a2, 3 a1}}
```

We compute the derivative of the evolution of the tensor under rotations.

```
In[8]:= drvec = {dør[[2, 2, 2]], dør[[2, 2, 1]], dør[[2, 1, 1]], dør[[1, 1, 1]]}
```

```
Out[8]= {3 a1, -a0 + 2 a2, -2 a1 + a3, -3 a2}
```

The tensor and its derivative are represented as 4 by 1 column vectors.

```
In[9]:= L = Grad[drvec, {a0, a1, a2, a3}]
```

```
Out[9]= {{0, 3, 0, 0}, {-1, 0, 2, 0}, {0, -2, 0, 1}, {0, 0, -3, 0}}
```

Matrix representation of the rotation generator.

```
In[10]:= MatrixForm[L]
```

```
Out[10]//MatrixForm=
```

$$\begin{pmatrix} 0 & 3 & 0 & 0 \\ -1 & 0 & 2 & 0 \\ 0 & -2 & 0 & 1 \\ 0 & 0 & -3 & 0 \end{pmatrix}$$

```
In[11]:= {vals, vecs} = Eigensystem[L]
```

```
Out[11]=
```

$$\{\{3i, -3i, i, -i\}, \{i, -1, -i, 1\}, \{-i, -1, i, 1\}, \{-3i, 1, -i, 3\}, \{3i, 1, i, 3\}\}$$

```
In[12]:= Λ = DiagonalMatrix[vals]
```

```
Out[12]=
```

$$\{\{3i, 0, 0, 0\}, \{0, -3i, 0, 0\}, \{0, 0, i, 0\}, \{0, 0, 0, -i\}\}$$

If we treat vecs as a matrix instead of a list of vectors, each eigenvector will be treated as a row. To make them columns, as appropriate for a right eigenvector, we need to take a transpose.

```
In[13]:= L.Transpose[vecs] - Transpose[vecs].Λ
```

```
Out[13]=
```

$$\{\{0, 0, 0, 0\}, \{0, 0, 0, 0\}, \{0, 0, 0, 0\}, \{0, 0, 0, 0\}\}$$

Transpose[vecs] gives the right eigenvectors of  $\mathcal{L}$ . To get the Left eigenvectors as rows, we need to invert Transpose[vecs]. Below, we include an additional normalization to clear denominators.

```
In[14]:= Lvecs = Sqrt[Det[vecs]] Inverse[Transpose[vecs]]
```

```
Out[14]=
```

$$\{\{1, -3i, -3, i\}, \{-1, -3i, 3, i\}, \{-1, i, -1, i\}, \{1, i, 1, i\}\}$$

These are the left Eigenvectors of  $\mathcal{L}$  as can be checked:

```
In[15]:= Lvecs.L - Λ.Lvecs
```

```
Out[15]=
```

$$\{\{0, 0, 0, 0\}, \{0, 0, 0, 0\}, \{0, 0, 0, 0\}, \{0, 0, 0, 0\}\}$$

```
In[16]:= MatrixForm[Lvecs]
```

```
Out[16]//MatrixForm=
```

$$\begin{pmatrix} 1 & -3i & -3 & i \\ -1 & -3i & 3 & i \\ -1 & i & -1 & i \\ 1 & i & 1 & i \end{pmatrix}$$

This is the matrix E in Sec. 2.2 and the corresponding eigenvalues are  $\lambda_1=3i$ ,  $\lambda_2=-3i$ ,  $\lambda_3=i$ ,  $\lambda_4=-i$ .

For a decoupled tensor  $(\beta_1, 0, 0, \beta_2)$  we get  $v_i = \beta_1 + i\beta_2 = v_4$ . This gives  $\text{Exp}[4i\theta] = v_4(0) / v_1(0) = \frac{(a_0+a_2)+i(a_1+a_3)}{(a_0-3a_2)+i(-3a_1+a_3)}$ . Subject to the necessary condition  $(a_0 + a_2)^2 + (a_1 + a_3)^2 = (a_0 - 3a_2)^2 + (-3a_1 + a_3)^2$ , we get 4 solutions for  $\theta$ , say  $\varphi$ ,  $\varphi+\pi/2$ ,  $\varphi+\pi$  and  $\varphi+3\pi/2$ .

These solutions define  $\beta_1$  and  $\beta_2$  by  $\beta_1 + i\beta_2 = \text{Exp}[-i\varphi] ((a_0 + a_2) + i(a_1 + a_3))$ . The rotations  $\varphi+\pi/2$ ,  $\varphi+\pi$  and  $\varphi+3\pi/2$  then correspond to the fully decoupled tensors  $(\beta_2, 0, 0, -\beta_1)$ ,  $(-\beta_1, 0, 0, -\beta_2)$  and  $(-\beta_2, 0, 0, \beta_1)$  respectively.

## Section 4

We begin to compute  $\sigma_\theta \circ \Gamma$ , the action of a rotation on the space of tensors  $\mathcal{T}_2$ .

```
In[17]:= Clear[r];
n = 2;
vars = Table[x[i], {i, 1, n}];
rlist = Flatten[Table[r[i, j, k], {i, 1, n}, {j, 1, n}, {k, 1, n}]];
rename = Table[rlist[[m]] -> Subscript[a, 4 - m], {m, 1, 4}];
f =
  (Sum[r@@Sort[{i, j, k}] x[i] x[j] x[k], {i, 1, n}, {j, 1, n}, {k, 1, n}] /. rename)
Out[22]=
a3 x[1]^3 + 3 a2 x[1]^2 x[2] + 3 a1 x[1] x[2]^2 + a0 x[2]^3
```

The last line is the expression for the cubic polynomial associate to a tensor  $\Gamma$ . Note that the coordinates are  $x[1]$  and  $x[2]$  where the indices are arguments and not subscripts. We begin by defining a two dimensional rotation matrix  $\sigma[\theta]$ .

```
In[23]:= Clear[sigma];
sigma[theta_] = {{Cos[theta], -Sin[theta]}, {Sin[theta], Cos[theta]}};
MatrixForm[sigma[theta]]
Out[25]//MatrixForm=
  ( Cos[theta]  -Sin[theta] )
  ( Sin[theta]   Cos[theta] )
```

Multiplying by this rotation matrix on the left gives the action of  $SO(2)$  on  $\mathbb{R}^2$  where the elements are thought of a column vectors. The action corresponds to rotating 'counter-clockwise' by an angle  $\theta$ .

The action on tensors, or equivalently on polynomials, is given by  $\sigma \circ f(z) = f(\sigma^{-1} \cdot z)$  for  $z \in \mathbb{R}^2$ .

```
In[26]:= Substitution = Table[x[i] -> (sigma[-theta].{z[1], z[2]})[[i]], {i, 1, n}]
Out[26]=
{x[1] -> Cos[theta] z[1] + Sin[theta] z[2], x[2] -> -Sin[theta] z[1] + Cos[theta] z[2]}
```

```
In[27]:= Transformedf = f //. Substitution
Out[27]=
a0 (-Sin[theta] z[1] + Cos[theta] z[2])^3 +
  3 a1 (-Sin[theta] z[1] + Cos[theta] z[2])^2 (Cos[theta] z[1] + Sin[theta] z[2]) +
  3 a2 (-Sin[theta] z[1] + Cos[theta] z[2]) (Cos[theta] z[1] + Sin[theta] z[2])^2 +
  a3 (Cos[theta] z[1] + Sin[theta] z[2])^3
```

This is a cubic polynomial in  $z[1], z[2]$ . We can now read off the transformations of the coefficients from  $\sigma \circ f(z) = b_3 z[1]^3 + 3 b_2 z[1]^2 z[2] + 3 b_1 z[1] z[2]^2 + b_0 z[2]^3$ . We now account for the factors of 3 in the coefficients  $b[1]$  and  $b[2]$  and order the coefficients as a column vector from  $b_0$  to  $b_3$ .

```
In[28]:= newcoeffs = Simplify[DiagonalMatrix[{1, 1/3, 1/3, 1}].
      CoefficientList[Transformedf /. {z[2] → 1}, z[1]]]
```

```
Out[28]= {Cos[θ]3 a0 + Sin[θ] (3 Cos[θ]2 a1 + Sin[θ] (3 Cos[θ] a2 + Sin[θ] a3)),
      1/4 (-4 Cos[θ]2 Sin[θ] a0 + (Cos[θ] + 3 Cos[3 θ]) a1 +
      2 Sin[θ] (a2 + 3 Cos[2 θ] a2 + Sin[2 θ] a3), Cos[θ] Sin[θ]2 a0 +
      1/4 ((Sin[θ] - 3 Sin[3 θ]) a1 + 2 Cos[θ] ((-1 + 3 Cos[2 θ]) a2 + Sin[2 θ] a3)),
      -Sin[θ]3 a0 + Cos[θ] (3 Sin[θ]2 a1 + Cos[θ] (-3 Sin[θ] a2 + Cos[θ] a3))}
```

```
In[29]:= Lσ = Grad[newcoeffs, Table[ai-1, {i, 1, 4}]]
```

```
Out[29]= {{Cos[θ]3, 3 Cos[θ]2 Sin[θ], 3 Cos[θ] Sin[θ]2, Sin[θ]3},
      {-Cos[θ]2 Sin[θ], 1/4 (Cos[θ] + 3 Cos[3 θ]), 1/2 (1 + 3 Cos[2 θ]) Sin[θ], 1/2 Sin[θ] Sin[2 θ]},
      {Cos[θ] Sin[θ]2, 1/4 (Sin[θ] - 3 Sin[3 θ]), 1/2 Cos[θ] (-1 + 3 Cos[2 θ]), 1/2 Cos[θ] Sin[2 θ]},
      {-Sin[θ]3, 3 Cos[θ] Sin[θ]2, -3 Cos[θ]2 Sin[θ], Cos[θ]3}}
```

```
In[30]:= MatrixForm[Lσ]
```

```
Out[30]//MatrixForm=
      Cos[θ]3      3 Cos[θ]2 Sin[θ]      3 Cos[θ] Sin[θ]2      Sin[θ]3
      -Cos[θ]2 Sin[θ]  1/4 (Cos[θ] + 3 Cos[3 θ])  1/2 (1 + 3 Cos[2 θ]) Sin[θ]  1/2 Sin[θ] Sin[2 θ]
      Cos[θ] Sin[θ]2  1/4 (Sin[θ] - 3 Sin[3 θ])  1/2 Cos[θ] (-1 + 3 Cos[2 θ])  1/2 Cos[θ] Sin[2 θ]
      -Sin[θ]3      3 Cos[θ] Sin[θ]2      -3 Cos[θ]2 Sin[θ]      Cos[θ]3
```

This is the representation of SO(2) on the space of  $2 \times 2 \times 2$  symmetric tensors. We can also compute the generator for this action.

```
In[31]:= L = D[Lσ, θ] /. {θ → 0}
```

```
Out[31]= {{0, 3, 0, 0}, {-1, 0, 2, 0}, {0, -2, 0, 1}, {0, 0, -3, 0}}
```

```
In[32]:= MatrixForm[L]
```

```
Out[32]//MatrixForm=
      0  3  0  0
      -1 0  2  0
      0 -2  0  1
      0  0 -3  0
```

This is an alternate derivation to obtain the generator  $\mathcal{L}$  in the proof of Prop. 2.5.

## Molien's formula and Hilbert series for the SO(2) invariants.

In[33]:= **Simplify**[1 / (2  $\pi$ ) **Integrate**[1 / **Simplify**[**Det**[**IdentityMatrix**[4] -  $\lambda$  L $\sigma$ ]], { $\theta$ , 0, 2  $\pi$ }]]  
 Out[33]=

$$\left\{ \begin{array}{ll} \frac{1+\lambda^4}{(-1+\lambda^2)^3 (1+\lambda^2)} & \text{Abs}[\lambda] > 1 \\ \frac{2+\lambda^{2/3} (-1-\lambda^{2/3}+\lambda^{4/3}) (1+\lambda^{2/3}+\lambda^{4/3}+2\lambda^2)}{3 (-1+\lambda^2)^3 (1+\lambda^2)} & \frac{1}{\text{Abs}[\lambda]^{1/3}} < 1 \text{ if } \text{Abs}[\lambda]^{1/3} \neq 1 \\ -\frac{1+\lambda^4}{(-1+\lambda^2)^3 (1+\lambda^2)} & \text{True} \end{array} \right.$$

The result for  $\text{Abs}[\lambda] < 1$  corresponds to Molien's formula.

In[34]:=  **$\mathfrak{S}O_2$**  = **Simplify**  $\left[ -\frac{1+\lambda^4}{(-1+\lambda^2)^3 (1+\lambda^2)} \right]$

Out[34]=

$$-\frac{1+\lambda^4}{(-1+\lambda^2)^3 (1+\lambda^2)}$$

## Molien's formula and Hilbert series for the O(2) invariants.

We now compute the action of O(2) by incorporating a reflection operator corresponding to  $x[1] \rightarrow -x[1]$ ,  $x[2] \rightarrow -x[2]$ . In terms of the tensor coefficients, this action is given by the matrix:

In[35]:=  $\mathcal{N} = \{\{\theta, \theta, \theta, 1\}, \{\theta, \theta, 1, \theta\}, \{\theta, 1, \theta, \theta\}, \{1, \theta, \theta, \theta\}\};$

In[36]:= **Simplify**[**Det**[**IdentityMatrix**[4] -  $\lambda$   $\mathcal{N}$ .L $\sigma$ ]]

Out[36]=

$$(-1+\lambda^2)^2$$

This determinant does not depend explicitly on  $\theta$ . Therefore the integral of the reciprocal is as follows.

In[37]:=  **$\mathfrak{S}O_2$**  = **Simplify**[(1 / **Det**[**IdentityMatrix**[4] -  $\lambda$   $\mathcal{N}$ .L $\sigma$ ] +  **$\mathfrak{S}O_2$** ) / 2]

Out[37]=

$$-\frac{1}{(-1+\lambda^2)^3 (1+\lambda^2)}$$

## Computation of the invariants when n=2

In[38]:= **u** = **Simplify**[**Grad**[**Laplacian**[f, vars], vars] / 6]

Out[38]=

$$\{a_1 + a_3, a_0 + a_2\}$$

This is the trace vector.

In[39]:= **u.u**

Out[39]=

$$(a_0 + a_2)^2 + (a_1 + a_3)^2$$

We will denote this O(2) invariant by  $j_2$ . We can 'lift' this vector u to form the cubic polynomial  $f_1$ .

```
In[40]:= f1 = 3 u.vars (vars.vars) / (n + 2)
```

```
Out[40]=
```

$$\frac{3}{4} \left( (a_1 + a_3) x[1] + (a_0 + a_2) x[2] \right) \left( x[1]^2 + x[2]^2 \right)$$

```
In[41]:= B = Table[D[f1/6, x[i], x[j], x[k]], {i, 1, n}, {j, 1, n}, {k, 1, n}];
```

```
In[42]:= Table[MatrixForm[B[[i]]], {i, 1, n}]
```

```
Out[42]=
```

$$\left\{ \begin{pmatrix} \frac{3}{4} (a_1 + a_3) & \frac{1}{4} (a_0 + a_2) \\ \frac{1}{4} (a_0 + a_2) & \frac{1}{4} (a_1 + a_3) \end{pmatrix}, \begin{pmatrix} \frac{1}{4} (a_0 + a_2) & \frac{1}{4} (a_1 + a_3) \\ \frac{1}{4} (a_1 + a_3) & \frac{3}{4} (a_0 + a_2) \end{pmatrix} \right\}$$

$\mathcal{B}$  is the tensor corresponding to the trace part. With our normalization, the trace-free part is given by  $f_3 = (n+2)f - f_1$ .

```
In[43]:= f3 = Collect[Expand[(n + 2) (f - f1)], vars]
```

```
Out[43]=
```

$$(-3 a_1 + a_3) x[1]^3 + (-3 a_0 + 9 a_2) x[1]^2 x[2] + (9 a_1 - 3 a_3) x[1] x[2]^2 + (a_0 - 3 a_2) x[2]^3$$

$f_3$  corresponds to a trace-free  $2 \times 2 \times 2$  symmetric tensor  $\mathcal{D}$ . To eliminate denominators, we multiply by a factor of  $(n+2)$ , which equals 4 in the case  $n=2$ .

```
In[44]:= D = Table[Simplify[D[f3/6, x[i], x[j], x[k]]], {i, 1, n}, {j, 1, n}, {k, 1, n}];
```

```
In[45]:= Table[MatrixForm[D[[i]]], {i, 1, n}]
```

```
Out[45]=
```

$$\left\{ \begin{pmatrix} -3 a_1 + a_3 & -a_0 + 3 a_2 \\ -a_0 + 3 a_2 & 3 a_1 - a_3 \end{pmatrix}, \begin{pmatrix} -a_0 + 3 a_2 & 3 a_1 - a_3 \\ 3 a_1 - a_3 & a_0 - 3 a_2 \end{pmatrix} \right\}$$

```
In[46]:= Dstarsqrd = Simplify[TensorContract[D⊗D, {{1, 4}, {2, 5}}]]
```

```
Out[46]=
```

$$\left\{ \left\{ 2 \left( (a_0 - 3 a_2)^2 + (-3 a_1 + a_3)^2 \right), 0 \right\}, \left\{ 0, 2 \left( (a_0 - 3 a_2)^2 + (-3 a_1 + a_3)^2 \right) \right\} \right\}$$

This is  $\mathcal{D}^{*2}$ .

```
In[47]:= w = Expand[D.u.u]
```

```
Out[47]=
```

$$\left\{ a_0^2 a_1 - 3 a_1^3 + 10 a_0 a_1 a_2 + 9 a_1 a_2^2 - 3 a_0^2 a_3 - 5 a_1^2 a_3 + 2 a_0 a_2 a_3 + 5 a_2^2 a_3 - a_1 a_3^2 + a_3^3, \right. \\ \left. a_0^3 + 5 a_0 a_1^2 - a_0^2 a_2 + 9 a_1^2 a_2 - 5 a_0 a_2^2 - 3 a_2^3 + 2 a_0 a_1 a_3 + 10 a_1 a_2 a_3 - 3 a_0 a_3^2 + a_2 a_3^2 \right\}$$

This is the vector  $w$  defined right after (4.4).

```
In[48]:= Tr[Dstarsqrd]
```

```
Out[48]=
```

$$4 \left( (a_0 - 3 a_2)^2 + (-3 a_1 + a_3)^2 \right)$$

This is another  $O(2)$  invariant which we denote by  $h_2$ .

```
In[49]:= Simplify[u.w]
```

```
Out[49]=
```

$$a_0^4 - 3 a_1^4 - 3 a_2^4 - 8 a_1^3 a_3 + 24 a_1 a_2^2 a_3 + 6 a_2^2 a_3^2 + a_3^4 - \\ 8 a_0 a_2 \left( -3 a_1^2 + a_2^2 - 3 a_1 a_3 \right) + 6 a_0^2 \left( a_1^2 - a_2^2 - a_3^2 \right) + 6 a_1^2 \left( 3 a_2^2 - a_3^2 \right)$$

This defines the  $O(2)$  invariant  $l_4$ .

```
In[50]:= Simplify[Det[{u, w}]]
```

```
Out[50]=
```

$$4 \left( -3 a_0^2 a_1 a_2 + a_0^3 a_3 + a_2 \left( 3 a_1^3 + 6 a_1^2 a_3 - 2 a_2^2 a_3 - 3 a_1 (a_2^2 - a_3^2) \right) + a_0 \left( 2 a_1^3 - 6 a_1 a_2^2 + 3 a_1^2 a_3 - a_3 (3 a_2^2 + a_3^2) \right) \right)$$

This defines the invariant  $m_4$ .

We can now write down the definitions of the  $SO(2)$  invariants and the ideal generated by these definitions, using the labels  $j_2, h_2, l_4$  and  $m_4$  as slack variables.

```
In[51]:= Clear[j, h, l, m]
```

```
Invariants = {j2 - u.u, h2 - Tr[Dstarsqrd], l4 - w.u, m4 - Det[{u, w}]}
```

```
Out[52]=
```

$$\begin{aligned} & \left\{ - (a_0 + a_2)^2 - (a_1 + a_3)^2 + j_2, -4 \left( (a_0 - 3 a_2)^2 + (-3 a_1 + a_3)^2 \right) + h_2, \right. \\ & - \left( (a_0 + a_2) \left( a_0^3 + 5 a_0 a_1^2 - a_0^2 a_2 + 9 a_1^2 a_2 - 5 a_0 a_2^2 - 3 a_2^3 + 2 a_0 a_1 a_3 + 10 a_1 a_2 a_3 - 3 a_0 a_3^2 + a_2 a_3^2 \right) - \right. \\ & \left. (a_1 + a_3) \left( a_0^2 a_1 - 3 a_1^3 + 10 a_0 a_1 a_2 + 9 a_1 a_2^2 - 3 a_0^2 a_3 - 5 a_1^2 a_3 + 2 a_0 a_2 a_3 + 5 a_2^2 a_3 - a_1 a_3^2 + a_3^3 \right) + \right. \\ & \left. l_4, -8 a_0 a_1^3 + 12 a_0^2 a_1 a_2 - 12 a_1^3 a_2 + 24 a_0 a_1 a_2^2 + 12 a_1 a_2^3 - 4 a_0^3 a_3 - \right. \\ & \left. 12 a_0 a_1^2 a_3 - 24 a_1^2 a_2 a_3 + 12 a_0 a_2^2 a_3 + 8 a_2^3 a_3 - 12 a_1 a_2 a_3^2 + 4 a_0 a_3^3 + m_4 \right\} \end{aligned}$$

This is the basis for the ideal of polynomials on  $\mathbb{R}^8$ , corresponding to the 4 coefficients  $a_0, a_1, a_2, a_3$  and the 4 invariants  $j_2, h_2, l_4, m_4$

We seek potential relations among the invariants by finding a basis for the ideal generated by the definitions of the invariants intersected with the polynomials in  $j_2, h_2, l_4, m_4$  that do not depend on  $a_0, a_1, a_2, a_3$ , that is, we are eliminating the coefficients between the relations defining the invariants.

```
In[53]:= GroebnerBasis[Invariants, {m4, l4, h2, j2},
```

```
{a0, a1, a2, a3}, MonomialOrder -> EliminationOrder]
```

```
Out[53]=
```

$$\{h_2 j_2^3 - 4 l_4^2 - 4 m_4^2\}$$

We see that there is one identity that allows us to replace  $m_4^2$  by an expression in the other invariants. There are no further relations, so this implies  $l_4, h_2$  and  $j_2$  are algebraically independent.

Alternate choices for the fundamental invariants are the trace and determinant of  $\Gamma^{*2}$ , which are themselves  $O(2)$  invariants.

```
In[54]:= r = Table[D[f/6, x[i], x[j], x[k]], {i, 1, n}, {j, 1, n}, {k, 1, n}];
```

```
Q = Simplify[TensorContract[r \otimes r, {{1, 4}, {2, 5}}]];
```

```
MatrixForm[Q]
```

```
Out[55]//MatrixForm=
```

$$\begin{pmatrix} a_1^2 + 2 a_2^2 + a_3^2 & a_0 a_1 + a_2 (2 a_1 + a_3) \\ a_0 a_1 + a_2 (2 a_1 + a_3) & a_0^2 + 2 a_1^2 + a_2^2 \end{pmatrix}$$

This is the matrix  $\Gamma^{*2}$ .

```
In[56]:= NewInvariants = {τ - Tr[Q], δ - Det[Q]}
```

```
Out[56]=
```

$$\left\{ \tau - a_0^2 - 3 a_1^2 - 3 a_2^2 - a_3^2, \right. \\ \left. \delta - 2 a_1^4 + 4 a_0 a_1^2 a_2 - 2 a_0^2 a_2^2 - a_1^2 a_2^2 - 2 a_2^4 + 2 a_0 a_1 a_2 a_3 + 4 a_1 a_2^2 a_3 - a_0^2 a_3^2 - 2 a_1^2 a_3^2 \right\}$$

These are the trace  $\tau$  and the determinant  $\delta$  of  $\Gamma^{*2}$ , used in the general framework for fully decoupled tensors in Sec. 6 when  $n=2$ . We now express  $\tau$  and  $\delta$  in terms of the fundamental invariants  $j_2, h_2$  and  $l_4$ , the  $O(2)$  invariants found earlier.

```
In[57]:= GroebnerBasis[Join[NewInvariants, Invariants],
  {τ, δ, l4, h2, j2}, {m4, a0, a1, a2, a3}, MonomialOrder → EliminationOrder]
```

```
Out[57]=
```

$$\{16 \tau - h_2 - 12 j_2, -1024 \delta + h_2^2 + 8 h_2 j_2 + 80 j_2^2 - 128 l_4\}$$

These are the relations at the end of section 4:  $\text{Tr}[\Gamma^{*2}] = \frac{h_2 + 12 j_2}{16}$ ,  $\text{Det}[\Gamma^{*2}] = \frac{h_2^2 + 8 h_2 j_2 + 80 j_2^2 - 128 l_4}{1024}$ .

## Section 7.2

### Fully decoupleable $3 \times 3 \times 3$ tensors

```
In[58]:= n = 3; vars = Table[x[i], {i, 1, n}]; f = Sum[βi x[i]^3, {i, 1, n}]
```

```
Out[58]=
```

$$\beta_1 x[1]^3 + \beta_2 x[2]^3 + \beta_3 x[3]^3$$

This is the cubic polynomial corresponding to a fully decoupleable tensor when  $n=3$ . We now compute the tracial and trace-free parts of  $\Gamma$ .

```
In[59]:= Γ = Simplify[Table[D[f, x[i], x[j], x[k]], {k, 1, n}, {j, 1, n}, {i, 1, n}] / 6];
u = Simplify[Table[D[Laplacian[f, vars], x[i]], {i, 1, n}] / 6];
f3 = (n + 2) f - 3 (u.vars) (vars.vars)
```

```
Out[61]=
```

$$-3 (\beta_1 x[1] + \beta_2 x[2] + \beta_3 x[3]) (x[1]^2 + x[2]^2 + x[3]^2) + 5 (\beta_1 x[1]^3 + \beta_2 x[2]^3 + \beta_3 x[3]^3)$$

This is the trace-free part.

```
In[62]:= D = Simplify[Table[D[f3, x[i], x[j], x[k]], {k, 1, n}, {j, 1, n}, {i, 1, n}] / 6];
v = Simplify[TensorContract[(D ⊗ D) ⊗ D, {{1, 4}, {2, 5}, {3, 7}, {6, 8}}]];
w = Simplify[D.u.u];
```

We have now computed the vectors  $u, v$  and  $w$  and the trace-free tensor  $\mathcal{D}$ , which are the ingredients needed to compute the Integrity basis given by Olive and Auffray as follows.



```

In[65]:= Clear[H, J, K, L, M, Q];
Q = Simplify[TensorContract[D⊗D, {{1, 4}, {2, 5}}]];
γuu = w;
Coeffs = Table[βi, {i, 1, n}];
Trivialize = Table[Coeffs[[j]] → 0, {j, 1, Length[Coeffs]}];
IntegrityPolys =
  {H[2] - Simplify[Tr[Q]], H[4] - Simplify[Tr[Q.Q]], J[2] - Simplify[u.u],
    L[4] - Simplify[γuu.u], H[6] - Simplify[v.v], H[10] - Simplify[D.v.v.v],
    J[4] - Simplify[u.Q.u], K[4] - Simplify[Tr[Q.(D.u)]],
    J[6] - Simplify[(u.Q).γuu], K[6] - Simplify[v.w], L[6] - Simplify[(u.Q).v],
    M[6] - Simplify[γuu.γuu], H[8] - Simplify[(u.Q).(Q.v)]};
OAINvariants = IntegrityPolys /. Trivialize;

```

The Ideal IntegrityPolys is generated by the polynomials defining the Integrity basis elements in terms of the coefficients of a fully decoupled tensor, with diagonal entries  $\beta_1$ ,  $\beta_2$  and  $\beta_3$ , and with the labels of the Integrity invariants as the slack variables.

```

In[71]:= IntegrityPolys

```

```

Out[71]= {H[2] - 10 (β12 + β22 + β32), H[4] - 44 β14 - 44 β24 - 58 β22 β32 - 44 β34 - 58 β12 (β22 + β32),
  J[2] - β12 - β22 - β32, L[4] - 2 (β14 + β24 - 3 β22 β32 + β34 - 3 β12 (β22 + β32)),
  H[6] - 4 (β32 (β12 + β22 - 4 β32)2 + β22 (β12 - 4 β22 + β32)2 + β12 (-4 β12 + β22 + β32)2),
  H[10] - 8 (128 β110 + 128 β210 - 60 β28 β32 - 95 β26 β34 - 95 β24 β36 -
    60 β22 β38 + 128 β310 - 60 β18 (β22 + β32) + β16 (-95 β24 + 60 β22 β32 - 95 β34) +
    β14 (-95 β26 + 90 β24 β32 + 90 β22 β34 - 95 β36) - 30 β12 (2 β28 - 2 β26 β32 - 3 β24 β34 - 2 β22 β36 + 2 β38),
  J[4] - 2 (3 β14 + 3 β24 + β22 β32 + 3 β34 + β12 (β22 + β32)), K[4] - 8 β14 - 8 β24 + 4 β22 β32 - 8 β34 + 4 β12 (β22 + β32),
  J[6] - 12 β16 - 12 β26 + 19 β24 β32 + 19 β22 β34 - 12 β36 + 19 β14 (β22 + β32) + β12 (19 β24 + 18 β22 β32 + 19 β34),
  K[6] - 2 (8 β16 + 8 β26 - 11 β24 β32 - 11 β22 β34 + 8 β36 - 11 β14 (β22 + β32) + β12 (-11 β24 + 18 β22 β32 - 11 β34),
  L[6] - 6 (8 β16 + 8 β26 - β24 β32 - β22 β34 + 8 β36 - β14 (β22 + β32) - β12 (β22 + β32)2),
  M[6] - β32 (3 β12 + 3 β22 - 2 β32)2 - β22 (3 β12 - 2 β22 + 3 β32)2 - (2 β13 - 3 β1 (β22 + β32))2,
  H[8] - 4 (72 β18 + 18 β16 (β22 + β32) - 11 β14 (3 β24 + β22 β32 + 3 β34) +
    β12 (18 β26 - 11 β24 β32 - 11 β22 β34 + 18 β36) + 3 (24 β28 + 6 β26 β32 - 11 β24 β34 + 6 β22 β36 + 24 β38)) }

```

Express in terms of the q's

## Characteristic Polynomial coefficients of $\Gamma^{*2}$

```

In[72]:= rstarsqr = Simplify[TensorContract[Γ⊗Γ, {{1, 4}, {2, 5}}]];
In[73]:= Clear[q, g];
g = Rest[Reverse[CoefficientList[Simplify[Det[λ IdentityMatrix[3] + rstarsqr]], λ]]]
Out[73]= {β12 + β22 + β32, β12 β22 + β12 β32 + β22 β32, β12 β22 β32}

```

As expected, these coefficients are the elementary symmetric polynomials of the quantities  $\beta_i^2$ .

```
In[74]:= DiagInvars = Table[qi -  $\xi$ [[i]], {i, 1, 3}]
```

```
Out[74]= {q1 -  $\beta_1^2$  -  $\beta_2^2$  -  $\beta_3^2$ , q2 -  $\beta_1^2 \beta_2^2$  -  $\beta_1^2 \beta_3^2$  -  $\beta_2^2 \beta_3^2$ , q3 -  $\beta_1^2 \beta_2^2 \beta_3^2$ }
```

This is the basis of invariants for the stabilizer group  $G_R = S_3 \times (\mathbb{Z}_2)^3$  with respect to fully decoupled reduced form tensors. Since all the Olive and Auffray invariants, when restricted to fully decoupled tensors, are also  $G_R$  invariants, we can express them in terms of the quantities  $q_i$ .

```
In[75]:= Table[GroebnerBasis[Join[{IntegrityPolys[[i]]}, DiagInvars],
  Join[{OAIInvariants[[i]]}, {q1, q2, q3}], { $\beta_1$ ,  $\beta_2$ ,  $\beta_3$ },
  MonomialOrder  $\rightarrow$  EliminationOrder] [[1]], {i, 1, Length[OAIInvariants]}]
```

```
Out[75]= {H[2] - 10 q1, -H[4] + 44 q12 - 30 q2, J[2] - q1,
  -L[4] + 2 q12 - 10 q2, -H[6] + 64 q13 - 220 q1 q2 + 300 q3,
  -H[10] + 1024 q15 - 5600 q13 q2 + 5800 q1 q22 + 7600 q12 q3 - 7000 q2 q3,
  -J[4] + 6 q12 - 10 q2, -K[4] + 8 q12 - 20 q2, -J[6] + 12 q13 - 55 q1 q2 + 75 q3,
  -K[6] + 16 q13 - 70 q1 q2 + 150 q3, -L[6] + 48 q13 - 150 q1 q2 + 150 q3,
  -M[6] + 4 q13 - 15 q1 q2 + 75 q3, -H[8] + 288 q14 - 1080 q12 q2 + 300 q22 + 1300 q1 q3}
```

These are the relations in Eq. (7.4).

## Section 7.3

### Partially decoupleable $3 \times 3 \times 3$ tensors

```
In[76]:= n = 3;
vars = Table[x[i], {i, 1, n}];
f = 3  $\alpha$  x[1] (x[1]^2 + x[2]^2) +
   $\gamma_1$  (3 x[2]^2  $\times$  x[1] - x[1]^3) +  $\gamma_2$  (3 x[1]^2  $\times$  x[2] - x[2]^3) +  $\beta_3$  x[3]^3
```

```
Out[76]= 3  $\alpha$  x[1] (x[1]^2 + x[2]^2) +  $\gamma_1$  (-x[1]^3 + 3 x[1] x[2]^2) +  $\gamma_2$  (3 x[1]^2 x[2] - x[2]^3) +  $\beta_3$  x[3]^3
```

This is the canonical form R corresponding to a partially decoupleable tensor when n=3.

```
In[77]:= Coeffs = { $\alpha$ ,  $\gamma_1$ ,  $\gamma_2$ ,  $\beta_3$ };
```

This is the list of the tensor parameters in the canonical form.

```
In[78]:=  $\Gamma$  = Simplify[Table[D[f, x[i], x[j], x[k]], {k, 1, n}, {j, 1, n}, {i, 1, n}] / 6]
```

```
Out[78]= {{3  $\alpha$  -  $\gamma_1$ ,  $\gamma_2$ , 0}, { $\gamma_2$ ,  $\alpha$  +  $\gamma_1$ , 0}, {0, 0, 0}},
  {{ $\gamma_2$ ,  $\alpha$  +  $\gamma_1$ , 0}, { $\alpha$  +  $\gamma_1$ , - $\gamma_2$ , 0}, {0, 0, 0}}, {{0, 0, 0}, {0, 0, 0}, {0, 0,  $\beta_3$ }}}
```

```
In[79]:= Table[MatrixForm[ $\Gamma$ [[i]], {i, 1, n}]
```

```
Out[79]= {
  (3  $\alpha$  -  $\gamma_1$     $\gamma_2$    0), (    $\gamma_2$     $\alpha$  +  $\gamma_1$    0), (0 0 0)
  (    $\gamma_2$     $\alpha$  +  $\gamma_1$    0), (    $\alpha$  +  $\gamma_1$    - $\gamma_2$    0), (0 0 0)
  (0   0   0), (0   0    $\beta_3$ )
}
```

```
In[80]:= u = Simplify[Table[D[Laplacian[f, vars], x[i]], {i, 1, n}]/6];
f3 = (n + 2) f - 3 (u.vars) (vars.vars)
```

```
Out[81]= -3 (4 α x[1] + β3 x[3]) (x[1]^2 + x[2]^2 + x[3]^2) +
5 (3 α x[1] (x[1]^2 + x[2]^2) + γ1 (-x[1]^3 + 3 x[1] x[2]^2) + γ2 (3 x[1]^2 x[2] - x[2]^3) + β3 x[3]^3)
```

This is the trace-free part.

```
In[82]:= D = Simplify[Table[D[f3, x[i], x[j], x[k]], {k, 1, n}, {j, 1, n}, {i, 1, n}]/6];
v = Simplify[TensorContract[(D⊗D)⊗D, {{1, 4}, {2, 5}, {3, 7}, {6, 8}}]];
w = Simplify[D.u.u];
```

The calculations follow the same steps as in the fully decoupled case.

```
In[85]:= Clear[H, J, K, L, M, Q];
v = Simplify[TensorContract[(D⊗D)⊗D, {{1, 4}, {2, 5}, {3, 7}, {6, 8}}]];
w = Simplify[D.u.u];
Q = Simplify[TensorContract[D⊗D, {{1, 4}, {2, 5}}]];
γuu = w;
Trivialize = Table[Coeffs[[j]] → 0, {j, 1, Length[Coeffs]}];
```

In what follows, we use the decomposition  $\mathcal{I} = \mathcal{I}^+ \cup \mathcal{I}'$ . We will call  $\mathcal{I}^+$  as ‘Fundamental’ and  $\mathcal{I}'$  as ‘Secondary’ in the following.

```
In[91]:= FundamentalRelations = {H[2] - Simplify[Tr[Q]],
H[4] - Simplify[Tr[Q.Q]], J[2] - Simplify[u.u], L[4] - Simplify[γuu.u]};
FundamentalInvariants = FundamentalRelations /. Trivialize;
SecondaryRelations = {H[6] - Simplify[v.v], H[10] - Simplify[D.v.v.v],
J[4] - Simplify[u.Q.u], K[4] - Simplify[Tr[Q.(D.u)]],
J[6] - Simplify[(u.Q).γuu], K[6] - Simplify[v.w], L[6] - Simplify[(u.Q).v],
M[6] - Simplify[γuu.γuu], H[8] - Simplify[(u.Q).(Q.v)]};
SecondaryInvariants = SecondaryRelations /. Trivialize;
PartialDecoupleRelations = Join[FundamentalRelations, SecondaryRelations];
```

```
In[96]:= G = Table[Tr[[i, j, k]], {i, 1, 2}, {j, 1, 2}, {k, 1, 2}]
```

```
Out[96]= {{ {3 α - γ1, γ2}, {γ2, α + γ1}}, {{γ2, α + γ1}, {α + γ1, -γ2}}}
```

This is the  $2 \times 2 \times 2$  block of R.

```
In[97]:= GStarSqrD = Expand[TensorContract[G⊗G, {{1, 4}, {2, 5}}]]
```

```
Out[97]= {{ {10 α^2 - 4 α γ1 + 2 γ1^2 + 2 γ2^2, 4 α γ2}, {4 α γ2, 2 α^2 + 4 α γ1 + 2 γ1^2 + 2 γ2^2}}}
```

```
In[98]:= MatrixForm[GStarSqrD]
```

```
Out[98]//MatrixForm=
( 10 α^2 - 4 α γ1 + 2 γ1^2 + 2 γ2^2      4 α γ2
  4 α γ2      2 α^2 + 4 α γ1 + 2 γ1^2 + 2 γ2^2 )
```

```
In[99]:= ured = TensorContract[G, {1, 2}]
```

```
Out[99]= {4 α, 0}
```

This is the trace of the  $2 \times 2 \times 2$  block of R.

```
In[100]:=
```

```
Clear[q];
defns = {q1 - β3^2, q2 - ured.ured, q4 - Tr[GStarSqr], q3 - Det[GStarSqr]}
```

```
Out[101]=
```

```
{q1 - β3^2, -16 α^2 + q2, -12 α^2 + q4 - 4 γ1^2 - 4 γ2^2,
-20 α^4 + q3 - 32 α^3 γ1 - 8 α^2 γ1^2 - 4 γ1^4 - 8 α^2 γ2^2 - 8 γ1^2 γ2^2 - 4 γ2^4}
```

The quantities  $q_1, q_2, q_3, q_4$  are  $O(2) \times \mathbb{Z}_2$  invariants in terms of the parameters defining the Canonical form.

```
In[102]:=
```

```
EliminateCoeffs = Table[
  GroebnerBasis[Join[{FundamentalRelations[i]}, defns], Join[FundamentalInvariants,
    {q3, q4, q2, q1}], Coeffs, MonomialOrder → EliminationOrder][[1], {i, 1, 4}]
```

```
Out[102]=
```

```
{H[2] - 10 q1 + 15 q2 - 25 q4,
-H[4] + 44 q1^2 - 42 q1 q2 + 144 q2^2 - 30 q3 + 100 q1 q4 - 420 q2 q4 + 320 q4^2,
J[2] - q1 - q2, -2 L[4] + 4 q1^2 - 12 q1 q2 + 4 q2^2 - 20 q3 - 5 q2 q4 + 5 q4^2}
```

Since there are no relations only involving  $q_i$  they are independent. Moreover, this is Eq. (7.8) expressing the elements in  $\mathcal{I}^+$  in terms of the  $O(2) \times \mathbb{Z}_2$  invariants  $q_i$ . We can invert these relations and solve for the quantities  $q_i$ .

```
In[103]:=
```

```
TriangularSystem =
  GroebnerBasis[EliminateCoeffs, {q4, q3, q2, q1, H[2], H[4], J[2], L[4]}]
```

```
Out[103]=
```

```
{-H[2]^2 + 2 H[4] + 3 H[2] × J[2] - 6 J[2]^2 - 6 L[4] + 9 H[2] q1 - 90 J[2] q1,
-J[2] + q1 + q2, 8 H[2]^2 - 25 H[4] - 60 H[2] × J[2] - 1500 J[2]^2 + 1200 L[4] +
11 250 J[2] q1 - 11 250 q1^2 + 11 250 q3, -H[2] - 15 J[2] + 25 q1 + 25 q4}
```

```
In[104]:=
```

```
Substitutions = Table[Solve[TriangularSystem[i] == 0, qi][[1, 1]], {i, 1, 4}]
```

```
Out[104]=
```

```
{q1 → (H[2]^2 - 2 H[4] - 3 H[2] × J[2] + 6 J[2]^2 + 6 L[4]) / (9 (H[2] - 10 J[2])), q2 → J[2] - q1,
q3 → (-8 H[2]^2 + 25 H[4] + 60 H[2] × J[2] + 1500 J[2]^2 - 1200 L[4] - 11 250 J[2] q1 + 11 250 q1^2) / 11 250,
q4 → (1 / 25) (H[2] + 15 J[2] - 25 q1)}
```

These are the substitutions implied by Eq. (7.9).

## Theorem 7.2: Expressing the invariants in $\mathcal{I}'$ in terms of $\mathcal{I}^+$

In[105]:=

**Eliminated** = { $\alpha$ ,  $\gamma_1$ ,  $\gamma_2$ } ;

We make a choice to include  $\beta_3$  in defining the necessary/sufficient conditions and only eliminate  $\alpha$ ,  $\gamma_1$  and  $\gamma_2$ . The rationale is that among all the relations between the parameters of the canonical form and the invariants, the only relation which is not a polynomial is the relation for  $\beta_3^2$  in terms of the OA invariants. So, we can get more compact expressions without denominators if we also include it in the set of 'basic' quantities for expressing the rest of the invariants.

In[106]:=

**GroebnerBasis[FundamentalRelations, FundamentalInvariants, Eliminated]**

Out[106]=

$$\{H[2]^2 - 2H[4] - 3H[2] \times J[2] + 6J[2]^2 + 6L[4] - 9H[2]\beta_3^2 + 90J[2]\beta_3^2\}$$

This is the relation for  $\beta_3^2$  in terms of the OA invariants. Inverting gives a rational function for  $\beta_3^2$  which is uniquely defined only if  $H[2] \neq 10J[2]$ . This will give  $\beta_3^2 = \frac{H[2]^2 - 2H[4] - 3H[2] \times J[2] + 6J[2]^2 + 6L[4]}{9(H[2] - 10J[2])}$ . We now calculate the polynomial expressions for the Secondary invariants in terms of the Fundamental invariants and  $\beta_3^2$  with an ordering that promotes low order polynomials in  $\beta_3$ .

In[107]:=

NeccSuffRelations =

```
Join[GroebnerBasis[FundamentalRelations, FundamentalInvariants, Eliminated],
  Table[GroebnerBasis[Join[{SecondaryRelations[[i]]}, FundamentalRelations], Join[
    {SecondaryInvariants[[i]]}, FundamentalInvariants], Eliminated][[2]], {i, 1, 9}]]
```

Out[107]=

$$\begin{aligned} & \{H[2]^2 - 2H[4] - 3H[2] \times J[2] + 6J[2]^2 + 6L[4] - 9H[2] \beta_3^2 + 90J[2] \beta_3^2, \\ & H[6] - 2H[4] \times J[2] + 8H[2] J[2]^2 - 24J[2]^3 - 4H[2] \times L[4] + 24J[2] \times L[4] - \\ & 15H[2] \times J[2] \beta_3^2 + 90J[2]^2 \beta_3^2 + 30L[4] \beta_3^2 + 39H[2] \beta_3^4 - 90J[2] \beta_3^4 - 300\beta_3^6, \\ & H[10] - 3H[2] \times H[4] J[2]^2 + 40H[4] J[2]^3 - 63H[2] J[2]^4 + 114J[2]^5 - \\ & 2H[2] \times H[4] \times L[4] + 6H[4] \times J[2] \times L[4] + 42H[2] J[2]^2 L[4] - 246J[2]^3 L[4] - \\ & 4H[2] L[4]^2 + 24J[2] L[4]^2 - 6H[2] \times H[4] \times J[2] \beta_3^2 - 36H[4] J[2]^2 \beta_3^2 + \\ & 485H[2] J[2]^3 \beta_3^2 - 2442J[2]^4 \beta_3^2 + 30H[4] \times L[4] \beta_3^2 - 72H[2] \times J[2] \times L[4] \beta_3^2 + \\ & 348J[2]^2 L[4] \beta_3^2 - 20L[4]^2 \beta_3^2 + 17H[2] \times H[4] \beta_3^4 + 36H[4] \times J[2] \beta_3^4 - \\ & 363H[2] J[2]^2 \beta_3^4 + 2002J[2]^3 \beta_3^4 + 70H[2] \times L[4] \beta_3^4 - 618J[2] \times L[4] \beta_3^4 - 280H[4] \beta_3^6 + \\ & 807H[2] \times J[2] \beta_3^6 - 3630J[2]^2 \beta_3^6 + 140L[4] \beta_3^6 - 210H[2] \beta_3^8 + 2100J[2] \beta_3^8, \\ & -H[2] \times J[2] + 2J[2]^2 + 2J[4] - 2L[4] + H[2] \beta_3^2 - 10J[2] \beta_3^2, \\ & -H[2] \times J[2] + 6J[2]^2 + K[4] - 2L[4] + 2H[2] \beta_3^2 - 20J[2] \beta_3^2, \\ & -H[2] J[2]^2 + 6J[2]^3 + 4J[6] - 2H[2] \times L[4] - 2J[2] \times L[4] - \\ & 4H[2] \times J[2] \beta_3^2 - 20J[2]^2 \beta_3^2 + 30L[4] \beta_3^2 + 9H[2] \beta_3^4 + 210J[2] \beta_3^4 - 300\beta_3^6, \\ & -H[2] J[2]^2 + 6J[2]^3 + 2K[6] - 2H[2] \times L[4] + 6J[2] \times L[4] - 10H[2] \times J[2] \beta_3^2 + \\ & 40J[2]^2 \beta_3^2 + 30L[4] \beta_3^2 + 19H[2] \beta_3^4 + 110J[2] \beta_3^4 - 300\beta_3^6, \\ & -H[4] \times J[2] + 2H[2] J[2]^2 - 2H[2] \times L[4] + 8J[2] \times L[4] + L[6] + H[4] \beta_3^2 - \\ & 11H[2] \times J[2] \beta_3^2 + 42J[2]^2 \beta_3^2 + 12L[4] \beta_3^2 + 19H[2] \beta_3^4 - 40J[2] \beta_3^4 - 150\beta_3^6, \\ & -H[2] J[2]^2 + 6J[2]^3 - 6J[2] \times L[4] + 4M[6] + 2H[2] \times J[2] \beta_3^2 - \\ & 80J[2]^2 \beta_3^2 + 30L[4] \beta_3^2 - H[2] \beta_3^4 + 310J[2] \beta_3^4 - 300\beta_3^6, \\ & 2H[8] - H[2] \times H[4] \times J[2] + 4H[4] J[2]^2 + 9H[2] J[2]^3 - 30J[2]^4 - 6H[4] \times L[4] + \\ & 4H[2] \times J[2] \times L[4] + 14J[2]^2 L[4] + 12L[4]^2 + H[2] \times H[4] \beta_3^2 - 32H[4] \times J[2] \beta_3^2 + \\ & 36H[2] J[2]^2 \beta_3^2 - 44J[2]^3 \beta_3^2 + 10H[2] \times L[4] \beta_3^2 + 226J[2] \times L[4] \beta_3^2 + 40H[4] \beta_3^4 + \\ & 69H[2] \times J[2] \beta_3^4 + 390J[2]^2 \beta_3^4 - 120L[4] \beta_3^4 - 70H[2] \beta_3^6 - 1900J[2] \beta_3^6\} \end{aligned}$$

The first relation defines  $\beta_3$ . We only need consider the rest of the relations since we allow  $\beta_3^2$  as a 'variable'.

In[108]:=

**NeccSuffRelations = Rest[NeccSuffRelations]**

Out[108]=

$$\begin{aligned}
& \{ H[6] - 2 H[4] \times J[2] + 8 H[2] J[2]^2 - 24 J[2]^3 - 4 H[2] \times L[4] + 24 J[2] \times L[4] - \\
& \quad 15 H[2] \times J[2] \beta_3^2 + 90 J[2]^2 \beta_3^2 + 30 L[4] \beta_3^2 + 39 H[2] \beta_3^4 - 90 J[2] \beta_3^4 - 300 \beta_3^6, \\
& H[10] - 3 H[2] \times H[4] J[2]^2 + 40 H[4] J[2]^3 - 63 H[2] J[2]^4 + 114 J[2]^5 - \\
& \quad 2 H[2] \times H[4] \times L[4] + 6 H[4] \times J[2] \times L[4] + 42 H[2] J[2]^2 L[4] - 246 J[2]^3 L[4] - \\
& \quad 4 H[2] L[4]^2 + 24 J[2] L[4]^2 - 6 H[2] \times H[4] \times J[2] \beta_3^2 - 36 H[4] J[2]^2 \beta_3^2 + \\
& \quad 485 H[2] J[2]^3 \beta_3^2 - 2442 J[2]^4 \beta_3^2 + 30 H[4] \times L[4] \beta_3^2 - 72 H[2] \times J[2] \times L[4] \beta_3^2 + \\
& \quad 348 J[2]^2 L[4] \beta_3^2 - 20 L[4]^2 \beta_3^2 + 17 H[2] \times H[4] \beta_3^4 + 36 H[4] \times J[2] \beta_3^4 - \\
& \quad 363 H[2] J[2]^2 \beta_3^4 + 2002 J[2]^3 \beta_3^4 + 70 H[2] \times L[4] \beta_3^4 - 618 J[2] \times L[4] \beta_3^4 - 280 H[4] \beta_3^6 + \\
& \quad 807 H[2] \times J[2] \beta_3^6 - 3630 J[2]^2 \beta_3^6 + 140 L[4] \beta_3^6 - 210 H[2] \beta_3^8 + 2100 J[2] \beta_3^8, \\
& -H[2] \times J[2] + 2 J[2]^2 + 2 J[4] - 2 L[4] + H[2] \beta_3^2 - 10 J[2] \beta_3^2, \\
& -H[2] \times J[2] + 6 J[2]^2 + K[4] - 2 L[4] + 2 H[2] \beta_3^2 - 20 J[2] \beta_3^2, \\
& -H[2] J[2]^2 + 6 J[2]^3 + 4 J[6] - 2 H[2] \times L[4] - 2 J[2] \times L[4] - \\
& \quad 4 H[2] \times J[2] \beta_3^2 - 20 J[2]^2 \beta_3^2 + 30 L[4] \beta_3^2 + 9 H[2] \beta_3^4 + 210 J[2] \beta_3^4 - 300 \beta_3^6, \\
& -H[2] J[2]^2 + 6 J[2]^3 + 2 K[6] - 2 H[2] \times L[4] + 6 J[2] \times L[4] - 10 H[2] \times J[2] \beta_3^2 + \\
& \quad 40 J[2]^2 \beta_3^2 + 30 L[4] \beta_3^2 + 19 H[2] \beta_3^4 + 110 J[2] \beta_3^4 - 300 \beta_3^6, \\
& -H[4] \times J[2] + 2 H[2] J[2]^2 - 2 H[2] \times L[4] + 8 J[2] \times L[4] + L[6] + H[4] \beta_3^2 - \\
& \quad 11 H[2] \times J[2] \beta_3^2 + 42 J[2]^2 \beta_3^2 + 12 L[4] \beta_3^2 + 19 H[2] \beta_3^4 - 40 J[2] \beta_3^4 - 150 \beta_3^6, \\
& -H[2] J[2]^2 + 6 J[2]^3 - 6 J[2] \times L[4] + 4 M[6] + 2 H[2] \times J[2] \beta_3^2 - \\
& \quad 80 J[2]^2 \beta_3^2 + 30 L[4] \beta_3^2 - H[2] \beta_3^4 + 310 J[2] \beta_3^4 - 300 \beta_3^6, \\
& 2 H[8] - H[2] \times H[4] \times J[2] + 4 H[4] J[2]^2 + 9 H[2] J[2]^3 - 30 J[2]^4 - 6 H[4] \times L[4] + \\
& \quad 4 H[2] \times J[2] \times L[4] + 14 J[2]^2 L[4] + 12 L[4]^2 + H[2] \times H[4] \beta_3^2 - 32 H[4] \times J[2] \beta_3^2 + \\
& \quad 36 H[2] J[2]^2 \beta_3^2 - 44 J[2]^3 \beta_3^2 + 10 H[2] \times L[4] \beta_3^2 + 226 J[2] \times L[4] \beta_3^2 + 40 H[4] \beta_3^4 + \\
& \quad 69 H[2] \times J[2] \beta_3^4 + 390 J[2]^2 \beta_3^4 - 120 L[4] \beta_3^4 - 70 H[2] \beta_3^6 - 1900 J[2] \beta_3^6 \}
\end{aligned}$$

In[109]:=

**Normalizations = Table[D[NeccSuffRelations[[i]], SecondaryInvariants[[i]], {i, 1, 9}]**

Out[109]=

{1, 1, 2, 1, 4, 2, 1, 4, 2}

These relations are linear in the Secondary invariants. We compute the coefficients to ensure they are nonzero constants. This also identifies the denominators that we will get in solving for the Secondary invariants.

The next step solves for the Secondary invariants and replaces  $\beta_3^2$  by  $q_1$ .

In[110]:=

**SolveNeccSuff =**

**Table[Solve[NeccSuffRelations[[i]] == 0, SecondaryInvariants[[i]]][[1, 1]], {i, 1, 9}] /.  
 $\{\beta_3^k \rightarrow q_1^{k/2}\}$**

Out[110]=

$$\begin{aligned}
 &\left\{ \begin{aligned}
 &H[6] \rightarrow 2 H[4] \times J[2] - 8 H[2] J[2]^2 + 24 J[2]^3 + 4 H[2] \times L[4] - 24 J[2] \times L[4] + \\
 &15 H[2] \times J[2] q_1 - 90 J[2]^2 q_1 - 30 L[4] q_1 - 39 H[2] q_1^2 + 90 J[2] q_1^2 + 300 q_1^3, \\
 &H[10] \rightarrow 3 H[2] \times H[4] J[2]^2 - 40 H[4] J[2]^3 + 63 H[2] J[2]^4 - 114 J[2]^5 + \\
 &2 H[2] \times H[4] \times L[4] - 6 H[4] \times J[2] \times L[4] - 42 H[2] J[2]^2 L[4] + 246 J[2]^3 L[4] + \\
 &4 H[2] L[4]^2 - 24 J[2] L[4]^2 + 6 H[2] \times H[4] \times J[2] q_1 + 36 H[4] J[2]^2 q_1 - \\
 &485 H[2] J[2]^3 q_1 + 2442 J[2]^4 q_1 - 30 H[4] \times L[4] q_1 + 72 H[2] \times J[2] \times L[4] q_1 - \\
 &348 J[2]^2 L[4] q_1 + 20 L[4]^2 q_1 - 17 H[2] \times H[4] q_1^2 - 36 H[4] \times J[2] q_1^2 + \\
 &363 H[2] J[2]^2 q_1^2 - 2002 J[2]^3 q_1^2 - 70 H[2] \times L[4] q_1^2 + 618 J[2] \times L[4] q_1^2 + 280 H[4] q_1^3 - \\
 &807 H[2] \times J[2] q_1^3 + 3630 J[2]^2 q_1^3 - 140 L[4] q_1^3 + 210 H[2] q_1^4 - 2100 J[2] q_1^4, \\
 &J[4] \rightarrow \frac{1}{2} (H[2] \times J[2] - 2 J[2]^2 + 2 L[4] - H[2] q_1 + 10 J[2] q_1), \\
 &K[4] \rightarrow H[2] \times J[2] - 6 J[2]^2 + 2 L[4] - 2 H[2] q_1 + 20 J[2] q_1, \\
 &J[6] \rightarrow \frac{1}{4} (H[2] J[2]^2 - 6 J[2]^3 + 2 H[2] \times L[4] + 2 J[2] \times L[4] + \\
 &4 H[2] \times J[2] q_1 + 20 J[2]^2 q_1 - 30 L[4] q_1 - 9 H[2] q_1^2 - 210 J[2] q_1^2 + 300 q_1^3), \\
 &K[6] \rightarrow \frac{1}{2} (H[2] J[2]^2 - 6 J[2]^3 + 2 H[2] \times L[4] - 6 J[2] \times L[4] + 10 H[2] \times J[2] q_1 - \\
 &40 J[2]^2 q_1 - 30 L[4] q_1 - 19 H[2] q_1^2 - 110 J[2] q_1^2 + 300 q_1^3), \\
 &L[6] \rightarrow H[4] \times J[2] - 2 H[2] J[2]^2 + 2 H[2] \times L[4] - 8 J[2] \times L[4] - H[4] q_1 + \\
 &11 H[2] \times J[2] q_1 - 42 J[2]^2 q_1 - 12 L[4] q_1 - 19 H[2] q_1^2 + 40 J[2] q_1^2 + 150 q_1^3, \\
 &M[6] \rightarrow \frac{1}{4} (H[2] J[2]^2 - 6 J[2]^3 + 6 J[2] \times L[4] - 2 H[2] \times J[2] q_1 + \\
 &80 J[2]^2 q_1 - 30 L[4] q_1 + H[2] q_1^2 - 310 J[2] q_1^2 + 300 q_1^3), \\
 &H[8] \rightarrow \frac{1}{2} (H[2] \times H[4] \times J[2] - 4 H[4] J[2]^2 - 9 H[2] J[2]^3 + 30 J[2]^4 + 6 H[4] \times L[4] - \\
 &4 H[2] \times J[2] \times L[4] - 14 J[2]^2 L[4] - 12 L[4]^2 - H[2] \times H[4] q_1 + 32 H[4] \times J[2] q_1 - \\
 &36 H[2] J[2]^2 q_1 + 44 J[2]^3 q_1 - 10 H[2] \times L[4] q_1 - 226 J[2] \times L[4] q_1 - 40 H[4] q_1^2 - \\
 &69 H[2] \times J[2] q_1^2 - 390 J[2]^2 q_1^2 + 120 L[4] q_1^2 + 70 H[2] q_1^3 + 1900 J[2] q_1^3) \}
 \end{aligned} \right.
 \end{aligned}$$

Multiplying out the denominators to get relations with integer coefficients.



In[111]:=

```
FormatAsEquations = Table[Normalizations[[i]] × SecondaryInvariants[[i]] → Collect[
  (Normalizations[[i]] × SecondaryInvariants[[i]] /. SolveNeccSuff), q1], {i, 1, 9}]
```

Out[111]=

```
{H[6] → 2 H[4] × J[2] - 8 H[2] J[2]2 + 24 J[2]3 + 4 H[2] × L[4] - 24 J[2] × L[4] +
  (15 H[2] × J[2] - 90 J[2]2 - 30 L[4]) q1 + (-39 H[2] + 90 J[2]) q12 + 300 q13,
  H[10] → 3 H[2] × H[4] J[2]2 - 40 H[4] J[2]3 + 63 H[2] J[2]4 - 114 J[2]5 + 2 H[2] × H[4] × L[4] -
  6 H[4] × J[2] × L[4] - 42 H[2] J[2]2 L[4] + 246 J[2]3 L[4] + 4 H[2] L[4]2 - 24 J[2] L[4]2 +
  (6 H[2] × H[4] × J[2] + 36 H[4] J[2]2 - 485 H[2] J[2]3 + 2442 J[2]4 - 30 H[4] × L[4] +
  72 H[2] × J[2] × L[4] - 348 J[2]2 L[4] + 20 L[4]2) q1 + (-17 H[2] × H[4] -
  36 H[4] × J[2] + 363 H[2] J[2]2 - 2002 J[2]3 - 70 H[2] × L[4] + 618 J[2] × L[4]) q12 +
  (280 H[4] - 807 H[2] × J[2] + 3630 J[2]2 - 140 L[4]) q13 + (210 H[2] - 2100 J[2]) q14,
  2 J[4] → H[2] × J[2] - 2 J[2]2 + 2 L[4] + (-H[2] + 10 J[2]) q1,
  K[4] → H[2] × J[2] - 6 J[2]2 + 2 L[4] + (-2 H[2] + 20 J[2]) q1,
  4 J[6] → H[2] J[2]2 - 6 J[2]3 + 2 H[2] × L[4] + 2 J[2] × L[4] +
  (4 H[2] × J[2] + 20 J[2]2 - 30 L[4]) q1 + (-9 H[2] - 210 J[2]) q12 + 300 q13,
  2 K[6] → H[2] J[2]2 - 6 J[2]3 + 2 H[2] × L[4] - 6 J[2] × L[4] +
  (10 H[2] × J[2] - 40 J[2]2 - 30 L[4]) q1 + (-19 H[2] - 110 J[2]) q12 + 300 q13,
  L[6] → H[4] × J[2] - 2 H[2] J[2]2 + 2 H[2] × L[4] - 8 J[2] × L[4] +
  (-H[4] + 11 H[2] × J[2] - 42 J[2]2 - 12 L[4]) q1 + (-19 H[2] + 40 J[2]) q12 + 150 q13,
  4 M[6] → H[2] J[2]2 - 6 J[2]3 + 6 J[2] × L[4] +
  (-2 H[2] × J[2] + 80 J[2]2 - 30 L[4]) q1 + (H[2] - 310 J[2]) q12 + 300 q13,
  2 H[8] → H[2] × H[4] × J[2] - 4 H[4] J[2]2 - 9 H[2] J[2]3 + 30 J[2]4 +
  6 H[4] × L[4] - 4 H[2] × J[2] × L[4] - 14 J[2]2 L[4] - 12 L[4]2 +
  (-H[2] × H[4] + 32 H[4] × J[2] - 36 H[2] J[2]2 + 44 J[2]3 - 10 H[2] × L[4] - 226 J[2] × L[4])
  q1 + (-40 H[4] - 69 H[2] × J[2] - 390 J[2]2 + 120 L[4]) q12 + (70 H[2] + 1900 J[2]) q13}
```

### Calculations with respect to Lemma 7.3

The presentation in the paper summarizes the main points in the following systematic analysis.

In[112]:=

```
GroebnerBasis[defns, Join[{β3}, Table[qi, {i, 1, 4}]], {α, γ1, γ2}]
```

Out[112]=

```
{-q1 + β32}
```

We first eliminate  $\alpha$ ,  $\gamma_1$  and  $\gamma_2$ . We find that  $q_1 \geq 0$  is necessary to solve for a real  $\beta_3$ . Also,  $q_1 > 0$  is 'generic' while  $q_1 = 0$  is 'degenerate' and a case we should look at further. The degenerate case corresponds to  $\beta_3 = 0$ . We first look at the 'generic' case, then we will return to the case  $\beta_3 = 0$ .

In[113]:=

```
GenericBeta = GroebnerBasis[defns, Join[Table[qi, {i, 1, 4}], {α, γ1, γ2}], {β3}]
```

Out[113]=

```
{-12 α2 + q4 - 4 γ12 - 4 γ22, -20 α4 + q3 - 32 α3 γ1 - 8 α2 γ12 - 4 γ14 - 8 α2 γ22 - 8 γ12 γ22 - 4 γ24, -16 α2 + q2}
```

In the generic case  $q_1 > 0$ , we have three relations for the remaining parameters in terms of the quantities  $q_i$ . We note that there is one equation isolating  $\alpha$ , so we solve for  $\alpha$  first. Also note that,  $\alpha^2$  is deter-

mined by  $q_2$  but not  $\alpha$  itself. In this system, the terms involving  $y_2$  only have even powers of  $\alpha$ , so they are completely determined by the  $q_i$ . There however are terms in  $y_1$  that involve odd powers of  $\alpha$ . Here, we should not eliminate  $\alpha$  when we are trying to solve for  $y_1$ .

```
In[114]:= GroebnerBasis[GenericBeta, Join[{ $\alpha$ }, Table[ $q_i$ , {i, 1, 4}]], { $y_1$ ,  $y_2$ }]
```

```
Out[114]= {16  $\alpha^2 - q_2$ }
```

We find that  $q_2 \geq 0$  is necessary for a real solution  $\alpha$ . The case  $q_2 > 0$  is 'generic', and the case  $q_2 = 0$  is 'degenerate'.

```
In[115]:= Generic $\alpha\beta$  = GroebnerBasis[GenericBeta, Join[{ $y_1$ ,  $y_2$ }, Table[ $q_i$ , {i, 1, 4}]], { $\alpha$ }]
```

```
Out[115]= { $q_2^4 - 4 q_2^2 q_3 + 16 q_3^2 - 2 q_2^3 q_4 + 8 q_2 q_3 q_4 + 2 q_2^2 q_4^2 - 8 q_3 q_4^2 - 2 q_2 q_4^3 + q_4^4 + 4 q_2^3 y_2^2$ ,  
3  $q_2 - 4 q_4 + 16 y_1^2 + 16 y_2^2$ }
```

This is a triangular system with two equations for  $y_1$  and  $y_2$ . We can solve them in turn to find  $y_2$  and  $y_1$

```
In[116]:=  $y_2eqn$  = GroebnerBasis[Generic $\alpha\beta$ , Join[{ $y_2$ }, Table[ $q_i$ , {i, 1, 4}]], { $y_1$ }]
```

```
Out[116]= { $q_2^4 - 4 q_2^2 q_3 + 16 q_3^2 - 2 q_2^3 q_4 + 8 q_2 q_3 q_4 + 2 q_2^2 q_4^2 - 8 q_3 q_4^2 - 2 q_2 q_4^3 + q_4^4 + 4 q_2^3 y_2^2$ }
```

We isolate  $y_2$ . This equation has a unique solution for  $y_2^2$  provided  $q_2 \neq 0$ , which is true in the generic case  $q_2 > 0$ .

```
In[117]:= Solve[{ $y_2eqn /. \{y_2^2 \rightarrow y_2sqrd\}$ } == 0,  $y_2sqrd$ ]][1]
```

```
Out[117]= { $y_2sqrd \rightarrow \frac{-q_2^4 + 4 q_2^2 q_3 - 16 q_3^2 + 2 q_2^3 q_4 - 8 q_2 q_3 q_4 - 2 q_2^2 q_4^2 + 8 q_3 q_4^2 + 2 q_2 q_4^3 - q_4^4}{4 q_2^3}$ }
```

Still in the generic case  $q_2 > 0$  and so  $\alpha > 0$ , we may solve for  $y_1$  below.

```
In[118]:=  $y_1eqns$  = GroebnerBasis[GenericBeta, Join[{ $y_1$ ,  $\alpha$ }, Table[ $q_i$ , {i, 1, 4}]], { $y_2$ }]
```

```
Out[118]= {16  $\alpha^2 - q_2$ ,  $\alpha q_2^2 - 8 \alpha q_3 - 2 \alpha q_2 q_4 + 2 \alpha q_4^2 + q_2^2 y_1$ ,  $q_2^2 - 8 q_3 - 2 q_2 q_4 + 2 q_4^2 + 16 \alpha q_2 y_1$ }
```

```
In[119]:= Solve[ $y_1eqns$ ][3] == 0,  $y_1$ ][1]
```

```
Out[119]= { $y_1 \rightarrow \frac{-q_2^2 + 8 q_3 + 2 q_2 q_4 - 2 q_4^2}{16 \alpha q_2}$ }
```

This concludes the discussion of the generic case,  $q_2 \neq 0$ ,  $q_1 \neq 0$ .

We next specialize to the case  $q_2 = 0$  which implies  $\alpha = 0$ .

In[120]:=

**Specialized $\alpha$ eq0 = GenericBeta /. { $\alpha \rightarrow 0$ ,  $q_2 \rightarrow 0$ }**

Out[120]=

$$\{q_4 - 4 \gamma_1^2 - 4 \gamma_2^2, q_3 - 4 \gamma_1^4 - 8 \gamma_1^2 \gamma_2^2 - 4 \gamma_2^4, 0\}$$

We obtain two equations for  $\gamma_1$  and  $\gamma_2$ . We check for any additional necessary conditions for solvability by eliminating  $\gamma_1$  and  $\gamma_2$ .

In[121]:=

**GroebnerBasis[Specialized $\alpha$ eq0, Join[Table[ $q_i$ , { $i$ , 1, 4}]], { $\gamma_1$ ,  $\gamma_2$ }]**

Out[121]=

$$\{4 q_3 - q_4^2\}$$

We do obtain an additional solvability condition. In the case that  $q_2 = 0$ , we also need  $q_3 = \frac{q_4^2}{4}$ . We redefined the specialization to include this condition.

In[122]:=

**Specialized $\alpha$ eq0 = GenericBeta /. { $\alpha \rightarrow 0$ ,  $q_2 \rightarrow 0$ ,  $q_3 \rightarrow q_4^2/4$ }**

Out[122]=

$$\{q_4 - 4 \gamma_1^2 - 4 \gamma_2^2, \frac{q_4^2}{4} - 4 \gamma_1^4 - 8 \gamma_1^2 \gamma_2^2 - 4 \gamma_2^4, 0\}$$

In[123]:=

**GroebnerBasis[Specialized $\alpha$ eq0, { $q_4$ ,  $\gamma_1$ ,  $\gamma_2$ }]**

Out[123]=

$$\{q_4 - 4 \gamma_1^2 - 4 \gamma_2^2\}$$

We obtain a single equation for  $\gamma_1^2 + \gamma_2^2$ . This equation is solvable if  $q_4 \geq 0$ . We have a continuum of solutions in this case. This concludes the discussion of the case  $q_1 > 0$ ,  $q_2 = 0$ , where we have the additional solvability conditions  $4 q_3 = q_4^2$  and  $q_4 \geq 0$ . The full solution is  $\beta_3 = \sqrt{q_1}$ ,  $\alpha = 0$ ,  $\gamma_1^2 + \gamma_2^2 = \frac{q_4}{4}$ .

We consider the last remaining case, the specialization  $q_1 = 0$ ,  $\beta_3 = 0$ .

In[124]:=

**$\beta$ 3eq0 = defns /. { $\beta_3 \rightarrow 0$ ,  $q_1 \rightarrow 0$ }**

Out[124]=

$$\{0, -16 \alpha^2 + q_2, -12 \alpha^2 + q_4 - 4 \gamma_1^2 - 4 \gamma_2^2, -20 \alpha^4 + q_3 - 32 \alpha^3 \gamma_1 - 8 \alpha^2 \gamma_1^2 - 4 \gamma_1^4 - 8 \alpha^2 \gamma_2^2 - 8 \gamma_1^2 \gamma_2^2 - 4 \gamma_2^4\}$$

We now specialize to the degenerate case  $\beta_3 = 0$ .

In[125]:=

**GroebnerBasis[ $\beta$ 3eq0, { $\alpha$ ,  $\gamma_1$ ,  $\gamma_2$ }, { $q_1$ ,  $q_2$ ,  $q_3$ ,  $q_4$ }, MonomialOrder  $\rightarrow$  EliminationOrder]**

Out[125]=

$$\{\}$$

We first check that setting  $\beta_3 = 0$  does not impose conditions among the 'independent' quantities  $\alpha$ ,  $\gamma_1$  and  $\gamma_2$  which define R.

```
In[126]:= GroebnerBasis[β3eq0, {q1, q2, q3, q4}, {α, γ1, γ2}, MonomialOrder → EliminationOrder]
Out[126]= {}
```

We determine all the consequences of having  $\beta_3 = 0$ . The only relation is  $q_1 = 0$  and there are no additional solvability conditions from imposing  $\beta_3 = 0$ .

```
In[127]:= GroebnerBasis[β3eq0, Join[{α}, Table[q_i, {i, 1, 4}]], {γ1, γ2}]
Out[127]= {16 α^2 - q2}
```

$\alpha$  is given by  $16 \alpha^2 = q_2$ . We can solve this for a real  $\alpha$  if  $q_2 \geq 0$ . The degenerate case is  $\alpha=0, q_2=0$ . We first consider the generic case  $q_2 > 0$ . We begin by eliminating  $\alpha$ , which now has a generic value.

```
In[128]:= Genericαβeq0 = GroebnerBasis[β3eq0, Join[{γ1, γ2}, Table[q_i, {i, 1, 4}]], {α}]
Out[128]= {q2^4 - 4 q2^2 q3 + 16 q3^2 - 2 q2^3 q4 + 8 q2 q3 q4 + 2 q2^2 q4^2 - 8 q3 q4^2 + 2 q2 q4^3 + q4^4 + 4 q2^3 γ2^2,
3 q2 - 4 q4 + 16 γ1^2 + 16 γ2^2}
```

This is the same triangular system as before with two equations for  $\gamma_1$  and  $\gamma_2$  and the solutions are still the same. We get  $\gamma_2^2 = \frac{-q_2^4 + 4 q_2^2 q_3 - 16 q_3^2 + 2 q_2^3 q_4 - 8 q_2 q_3 q_4 - 2 q_2^2 q_4^2 + 8 q_3 q_4^2 + 2 q_2 q_4^3 - q_4^4}{4 q_2^3}$ ,  $\gamma_1 = \frac{-q_2^2 + 8 q_3 + 2 q_2 q_4 - 2 q_4^2}{16 \alpha q_2}$ .

We now consider the ‘doubly degenerate’ case  $q_1 = q_2 = 0$  which implies  $\alpha = \beta_3 = 0$ .

```
In[129]:= αeq0βeq0 = defs /. {α → 0, β3 → 0, q1 → 0, q2 → 0}
Out[129]= {0, 0, q4 - 4 γ1^2 - 4 γ2^2, q3 - 4 γ1^4 - 8 γ1^2 γ2^2 - 4 γ2^4}
In[130]:= GroebnerBasis[αeq0βeq0, {q1, q2, q3, q4}, {γ1, γ2}, MonomialOrder → EliminationOrder]
Out[130]= {-4 q3 + q4^2}
```

Just as before, we get the additional solvability condition  $4 q_3 = q_4^2$ . We now find the equations for  $\gamma_1$  and  $\gamma_2$  by imposing this additional condition.

```
In[131]:= αeq0βeq0 /. {q3 → q4^2 / 4}
Out[131]= {0, 0, q4 - 4 γ1^2 - 4 γ2^2, q4^2 / 4 - 4 γ1^4 - 8 γ1^2 γ2^2 - 4 γ2^4}
In[132]:= GroebnerBasis[{0, 0, q4 - 4 γ1^2 - 4 γ2^2, q4^2 / 4 - 4 γ1^4 - 8 γ1^2 γ2^2 - 4 γ2^4}, {q4, γ1, γ2}]
Out[132]= {q4 - 4 γ1^2 - 4 γ2^2}
```

We again get a continuum of solutions contingent on  $q_4 \geq 0$ .

In summary, in both cases  $q_1 > 0$  and  $q_1 = 0$ , we get  $\beta_3 = \sqrt{q_1}$  and we get the same set of equations for the parameters  $\alpha, \gamma_1$  and  $\gamma_2$ .

If  $q_2 > 0$ , we get the solvability condition

$$-q_2^4 + 4 q_2^2 q_3 - 16 q_3^2 + 2 q_2^3 q_4 - 8 q_2 q_3 q_4 - 2 q_2^2 q_4^2 + 8 q_3 q_4^2 + 2 q_2 q_4^3 - q_4^4 = 0. \text{ The parameters are given by } \alpha = \frac{\sqrt{q_2}}{4}, \gamma_2^2 = \frac{-q_2^4 + 4 q_2^2 q_3 - 16 q_3^2 + 2 q_2^3 q_4 - 8 q_2 q_3 q_4 - 2 q_2^2 q_4^2 + 8 q_3 q_4^2 + 2 q_2 q_4^3 - q_4^4}{4 q_2^3},$$

$$\gamma_1 = \frac{-q_2^2 + 8 q_3 + 2 q_2 q_4 - 2 q_4^2}{16 \alpha q_2}.$$

If  $q_2 = 0$ , we get the solvability condition  $q_4^2 = 4 q_3$  and the parameters are given by  $\alpha = 0$ ,

$$\gamma_1^2 + \gamma_2^2 = \frac{q_4}{4}.$$

## Example 7.4

In[133]:=

```
n = 3;
vars = Table[x[i], {i, 1, n}];
f = Sum[2 i x[i]^3, {i, 1, n}] + (3 x[1]^2 x[2] - x[2]^3) - 12 x[1] x[2] x[3]
```

Out[133]=

$$2 x[1]^3 + 3 x[1]^2 x[2] + 3 x[2]^3 - 12 x[1] x[2] x[3] + 6 x[3]^3$$

This is an explicit numerical example.

In[134]:=

```
r = Simplify[Table[D[f, x[i], x[j], x[k]], {k, 1, n}, {j, 1, n}, {i, 1, n}] / 6];
u = Simplify[Table[D[Laplacian[f, vars], x[i]], {i, 1, n}] / 6];
f3 = (n + 2) f - 3 (u.vars) (vars.vars);
d = Simplify[Table[D[f3, x[i], x[j], x[k]], {k, 1, n}, {j, 1, n}, {i, 1, n}] / 6];
Clear[H, J, K, L, M, Q];
v = Simplify[TensorContract[(d ⊗ d) ⊗ d, {{1, 4}, {2, 5}, {3, 7}, {6, 8}}]];
w = Simplify[d.u.u];
Q = Simplify[TensorContract[d ⊗ d, {{1, 4}, {2, 5}}]];
γuu = w;
FundamentalValues = {H[2] → Simplify[Tr[Q]],
  H[4] → Simplify[Tr[Q.Q]], J[2] → Simplify[u.u], L[4] → Simplify[γuu.u]};
SecondaryValues =
  {H[6] → Simplify[v.v], H[10] → Simplify[d.v.v.v], J[4] → Simplify[u.Q.u],
    K[4] → Simplify[Tr[Q.(d.u)]], J[6] → Simplify[(u.Q).γuu], K[6] → Simplify[v.w],
    L[6] → Simplify[(u.Q).v], M[6] → Simplify[γuu.γuu], H[8] → Simplify[(u.Q).(Q.v)]};
```

In[145]:=

```
FundamentalValues
```

Out[145]=

$$\{H[2] \rightarrow 1060, H[4] \rightarrow 518384, J[2] \rightarrow 56, L[4] \rightarrow -4528\}$$

In[146]:=

**Specialization = FundamentalRelations /. FundamentalValues**

Out[146]=

$$\left\{ 1060 - 10 \left( 6 \alpha^2 + \beta_3^2 + 10 \gamma_1^2 + 10 \gamma_2^2 \right), 518384 - 32 \alpha^2 \beta_3^2 - \left( 32 \alpha^2 + 6 \beta_3^2 \right)^2 - \right. \\ \left. 800 \alpha^2 \gamma_2^2 - 4 \left( 13 \alpha^2 + \beta_3^2 - 10 \alpha \gamma_1 + 25 \gamma_1^2 + 25 \gamma_2^2 \right)^2 - 4 \left( \beta_3^2 + (\alpha + 5 \gamma_1)^2 + 25 \gamma_2^2 \right)^2, \right. \\ \left. 56 - 16 \alpha^2 - \beta_3^2, -4528 - 2 \left( -48 \alpha^2 \beta_3^2 + \beta_3^4 + 32 \alpha^3 (3 \alpha - 5 \gamma_1) \right) \right\}$$

In[147]:=

**GroebnerBasis[Specialization, Coeffs]**

Out[147]=

$$\left\{ 332 + 15 \beta_3^2, 3173103609 + 125768785 \gamma_2^2, \right. \\ \left. -52993421209 + 1509225420 \gamma_1^2, 230203 \alpha - 85849 \gamma_1 \right\}$$