

What is Kinematics?

- **Kinematics** is the branch of physics that describes the **motion of objects** without considering the forces that cause the motion.
 - It answers: "**How does an object move?**" rather than "**Why does it move?**"
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Key Quantities in Kinematics

1. Displacement (s or x):

- The change in position of an object.
- It's a vector (has magnitude and direction).
- Example: If you walk 3 m east, displacement = **3 m east**.

2. Velocity (v):

- The rate of change of displacement.
- **$v = \Delta s / \Delta t$** .
- It's a vector (direction matters).
- Example: A car moving 60 km/h east has velocity = **60 km/h east**.

3. Speed:

- How fast an object moves (scalar).
- **Speed = distance / time**.

4. Acceleration (a):

- The rate of change of velocity.
- **$a = \Delta v / \Delta t$** .

- Example: A bike increasing speed from 0 to 20 m/s in 4 seconds has **$a = 5 \text{ m/s}^2$** .

5. **Time (t):**

- The duration over which motion happens.
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Equations of Motion (for constant acceleration)

There are 3 famous kinematic equations:

1. **$v = u + at$**
2. **$s = ut + \frac{1}{2}at^2$**
3. **$v^2 = u^2 + 2as$**

- Where:

- **u** = initial velocity
 - **v** = final velocity
 - **a** = acceleration
 - **s** = displacement
 - **t** = time
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Types of Motion

1. **Linear motion:** Motion along a straight line.
 2. **Circular motion:** Motion along a circular path.
 3. **Projectile motion:** Motion under gravity with a curved path (like a ball being thrown).
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Example Problem

A car starts from rest ($u=0$) and accelerates at 2 m/s^2 for 5 seconds.

- **Find final velocity (v):**

$$v = u + at = 0 + 2 \times 5 = 10 \text{ m/s. } v = u + at = 0 + 2 \times 5 = 10 \text{ m/s.}$$

- **Find displacement (s):**

$$s = ut + \frac{1}{2}at^2 = 0 + \frac{1}{2} \times 2 \times 25 = 25 \text{ m. } s = ut + \frac{1}{2}at^2 = 0 + \frac{1}{2} \times 2 \times 25 = 25$$

$$\text{m. } s = ut + \frac{1}{2}at^2 = 0 + \frac{1}{2} \times 2 \times 25 = 25 \text{ m.}$$

Why is Kinematics Important?

- It helps in understanding and predicting how objects move.
- It's widely used in engineering, robotics, vehicle motion, and even space science.