

Before we begin: A quick visit to the behavioral economics literature

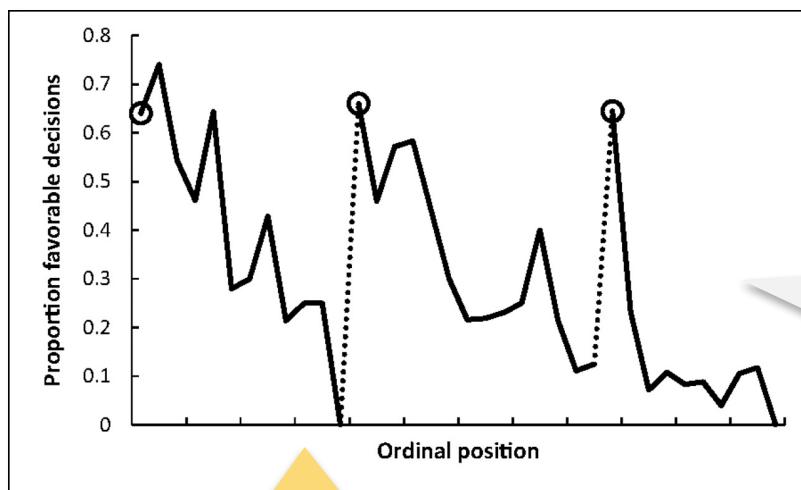
PNAS

Extraneous factors in judicial decisions

Shai Danziger^{a,1}, Jonathan Levav^{b,1,2}, and Liora Avnaim-Pesso^a

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Edited* by Daniel Kahneman, Princeton University, Princeton, NJ, and approved February 25, 2011 (received for review December 8, 2010)



“Proportion of rulings in favor of the prisoners by ordinal position... **dotted line denotes food break.**”

Time of this preliminary
oral exam-- oops





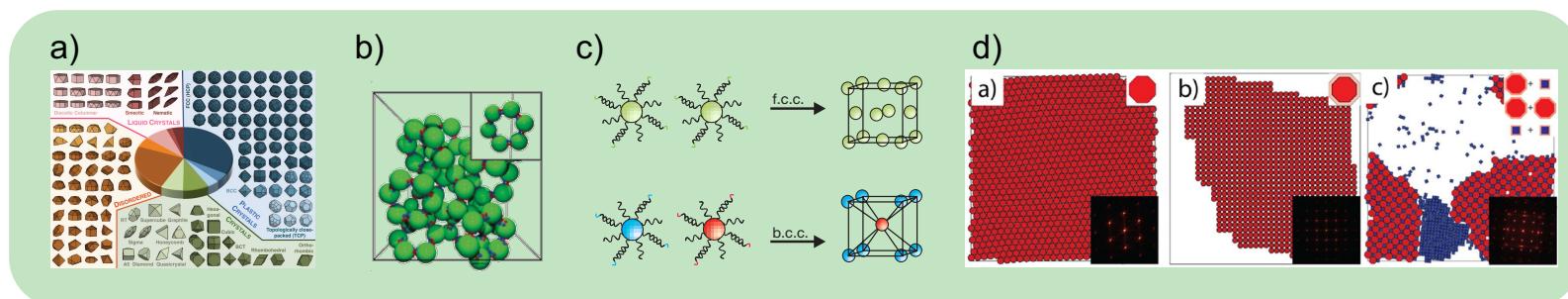
Designing an information-driven pathway approach for targeted self-assembly

Shannon Moran

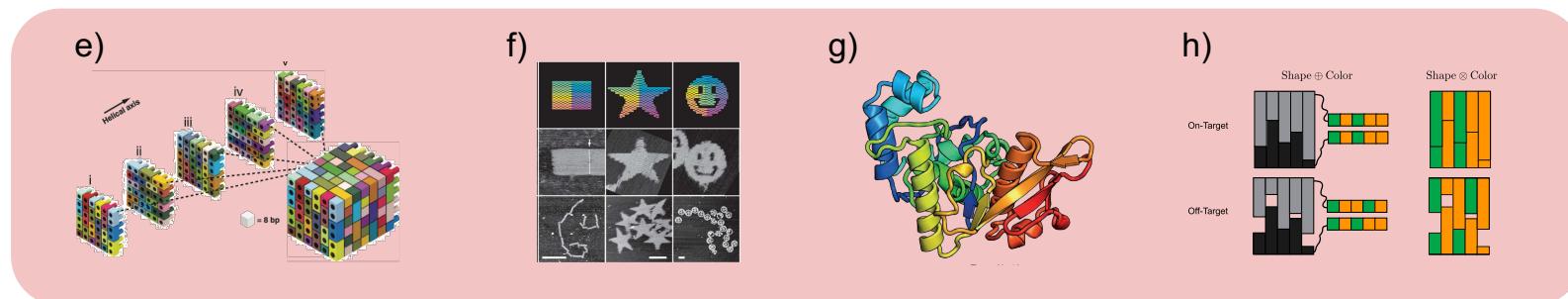
Research Proposal, Oral Presentation

February 21, 2018

Self-assembly: A challenge of specificity versus target complexity



Middle ground– minimizing instruction while maximizing complexity?



Source: (a) Damasceno et al, Science 2012; (b) Zhang et al, NanoLetters 2004; (c) Park et al, Nature 2008; (d) Millan et al, 2014 ACS Nano; (e) Ke et al, Science 2014; (f) Rothemund et al, Nature 2006; (h) Huntley et al, PNAS 2016; (g) Huang et al, Nature 2016

Understanding self-assembly: what approach to take?

“Different fields of science take different roads to understanding; each brings something to self-assembly.

Chemists and engineers tend to solve problems by designing and synthesizing (or fabricating, or building) new systems;
physicists observe existing systems;

biologists make modifications by mixing preexisting parts.”

Self-Assembly at All Scales

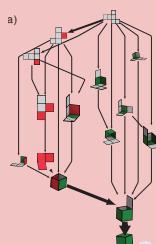
George M. Whitesides* and Bartosz Grzybowski



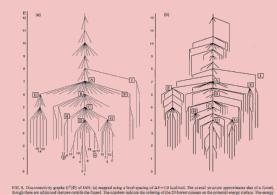
How can we tailor self-assembly?

Proposed work: What is the minimal set of instructions needed to achieve targeted, self-assembled complexity?

Project 1
Define measure
of pathway
information



Project 2
Develop energy
landscapes for
identifying kinetic
barriers to assembly

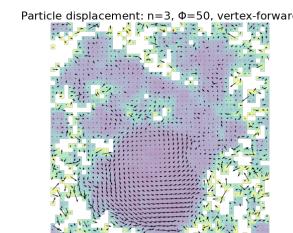


Project 3
Design pluripotent
materials using
minimal
instructions



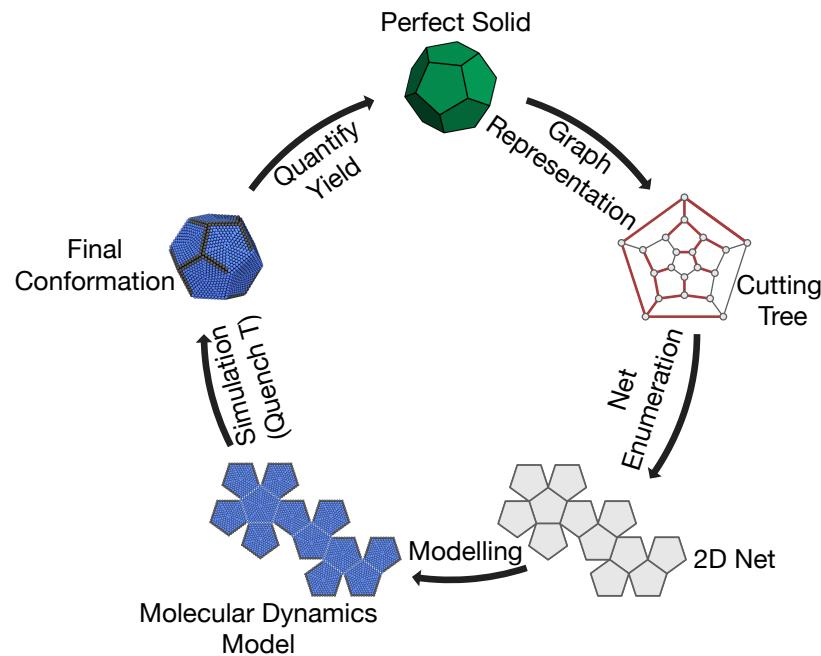
Prior work: How does shape impact assembly behavior in active systems?

Project 0
Define role of particle
anisotropy in a translationally-
driven system

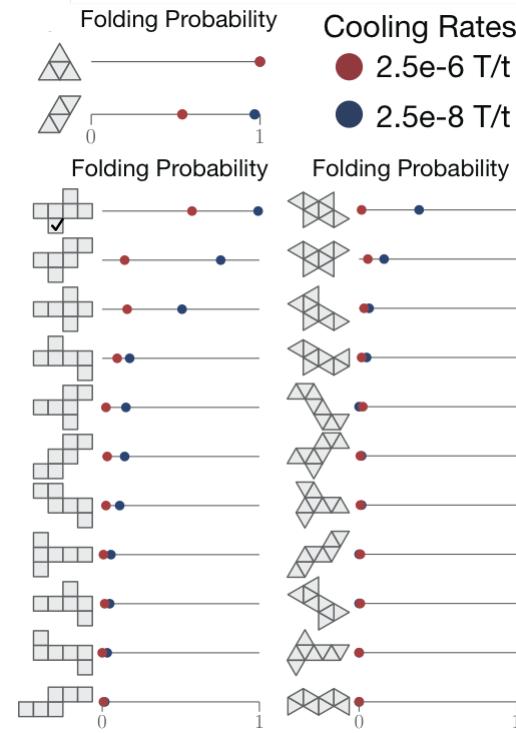


Proposed model: Nets of Platonic solids

Proposed system



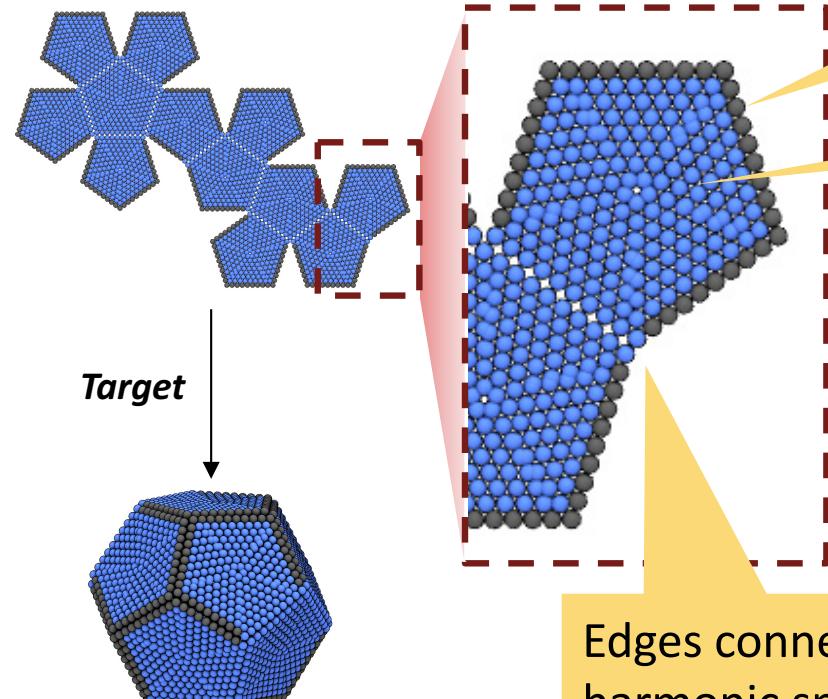
Folding propensity of nets



Compact,
many leaves

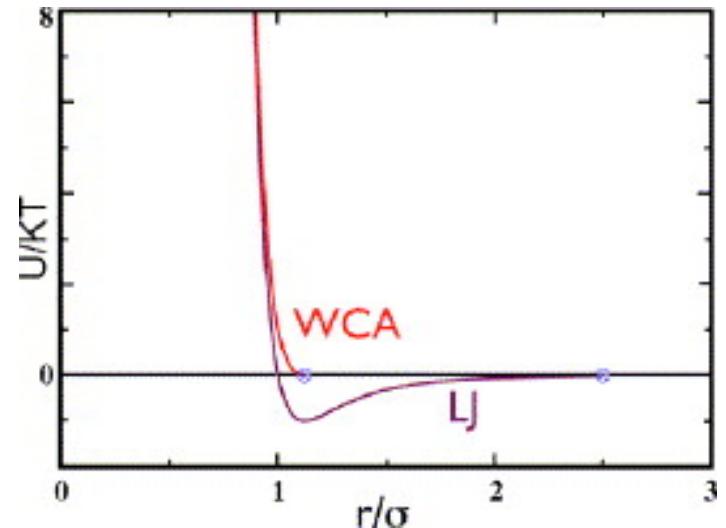
Nets are modelled as rigid bodies

Rigid body faces connected by harmonic springs



Lennard-Jones potential
on edges

Weeks-Chandler-Anderson
(WCA) potential on faces



Project 1: Define measure of pathway information

Task

1 Define a measure of information for interactions in an assembly pathway (bonds on net)

2 Identify “critical bonds” in assembly pathway

3 Demonstrate that poorly-folding nets fold with addition of n critical bonds

Goal

Measure correlation between an interaction and successful self-assembly to identify “critical bonds”

Use critical bonds to bias assembly towards target structures

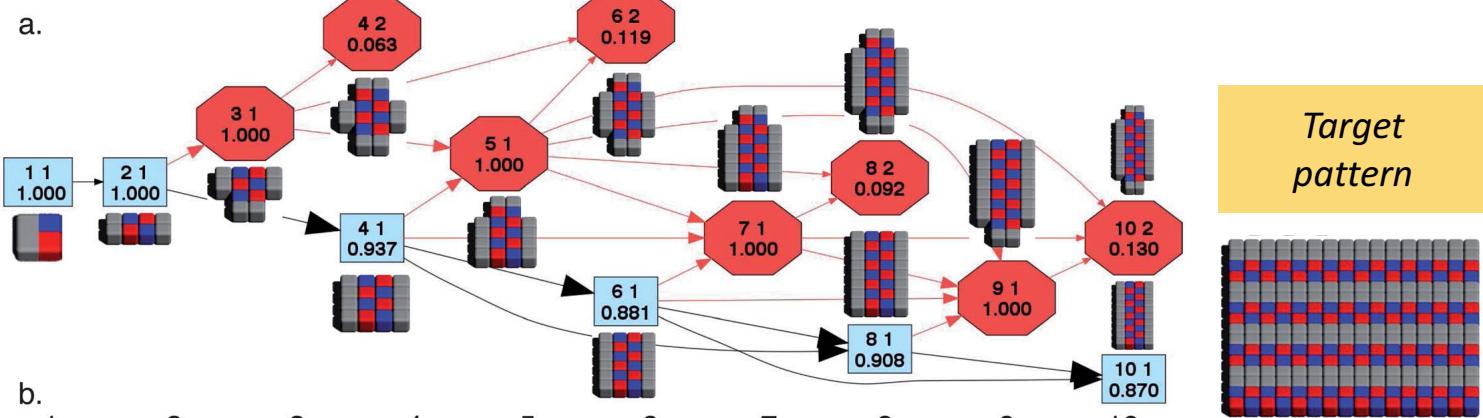
Demonstrate approach works to tailor self-assembly



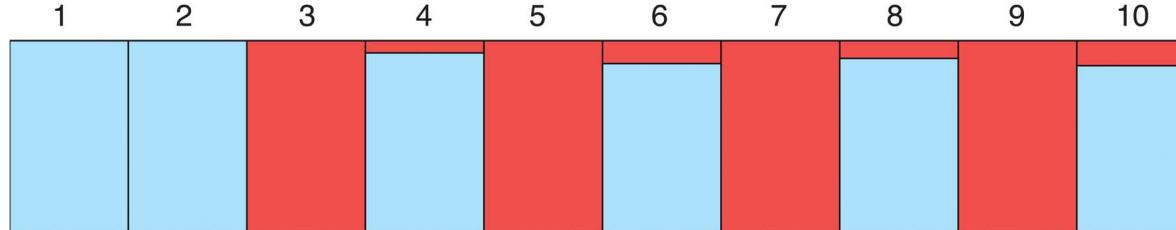
Transition state flux analysis to determine most important pathway intermediates

How compatible is an intermediate with assembly into a target pattern?

Self-assembly pathways



"Assembly fingerprint"



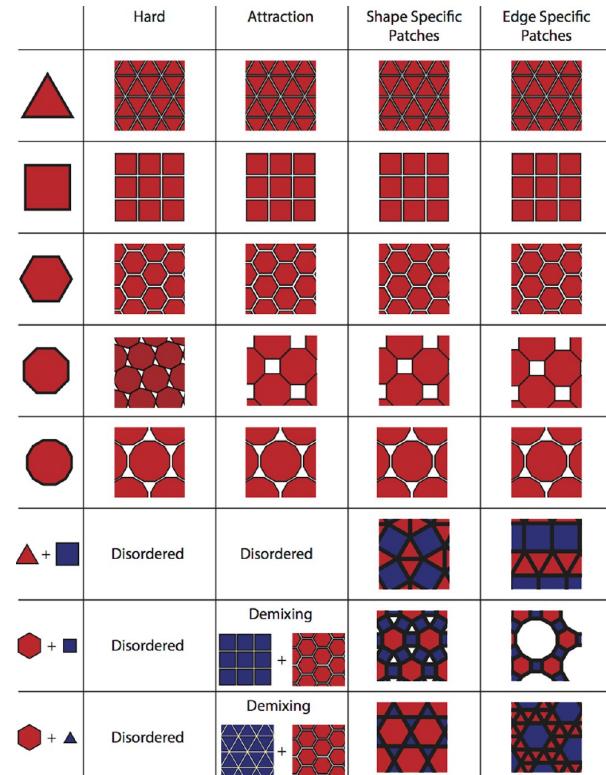
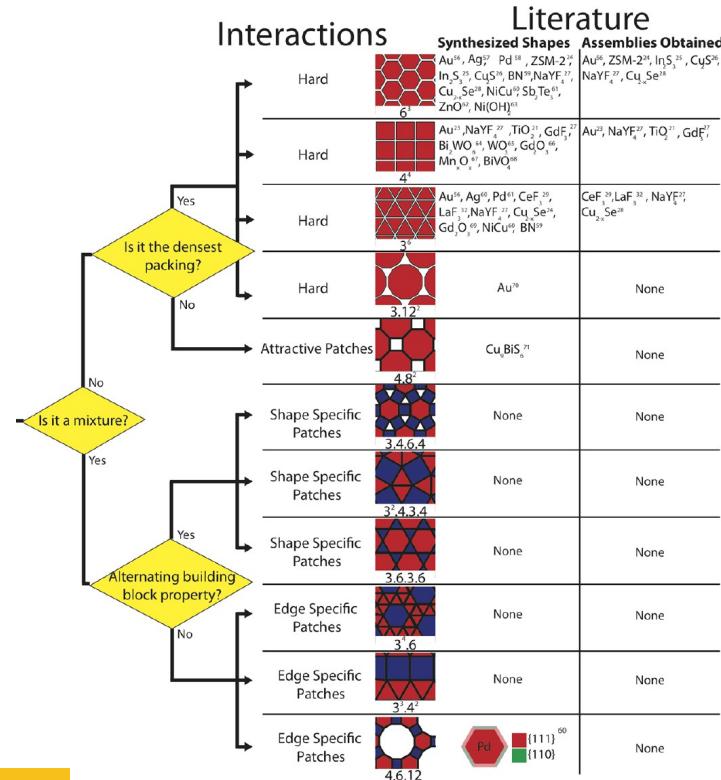
Citations: 35

Sources: Jankowski and Glotzer, Soft Matter 2012

Hierarchical assembly of Archimedean tilings with increasingly specific instructions

Flow chart heuristic to assign interactions...

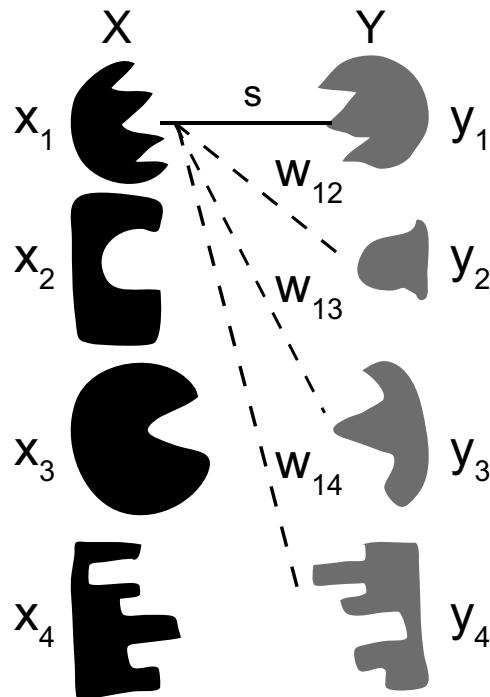
... increasing in instruction specificity and structure complexity



Citations: 41

Sources: Millan et al, ACS Nano 2014

Measuring mutual information in a lock and key pair (specificity)



$$\Delta_{ij} = s - w_{ij}$$

$$E_{ij} \equiv E(x_i, y_j)$$

How predictive is the identity of a lock x_i to the identity of a key y_j found bound to it?

Locks: $x_1, x_2, \dots, x_N \in X$

Keys: $y_1, y_2, \dots, y_N \in Y$

Probability of seeing x_i in a bound pair: $p(x_i)$

Probability of bound pair x_i, y_j :

$$p(x_i, y_j) = \frac{e^{-\beta E_{ij}}}{Z}$$

$$I(X; Y) = \sum_{x_i \in X, y_j \in Y} p(x_i, y_j) \log_2 \frac{p(x_i, y_j)}{p(x_i)p(y_j)}$$

Citations: 7

Sources: Huntley et al, PNAS 2016

Quick primer on information theory

$$I(x_i, y_j) = p(x_i, y_j) \log_2 \frac{p(x_i, y_j)}{p(x_i)p(y_j)}$$



Communication theory
Claude Shannon

Encoded message

Noise

Received message

Bond specificity
Huntley et al., PNAS 2016

Identity of lock

Thermal fluctuations

Identity of key

Self-assembly pathway
Proposed work

Presence of bond x_i

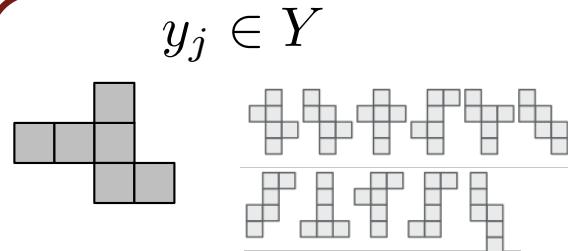
Thermal fluctuations

Yield of net y_j into target structure

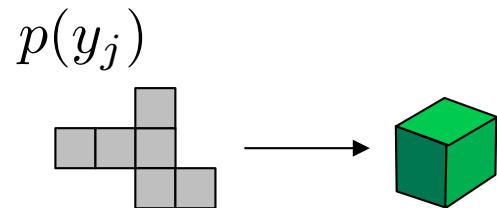


Task 1&2: Use transition pathways to measure which bonds are “most critical”

Enumerate states



Measure probabilities

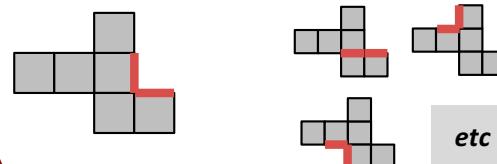


Define critical bonds

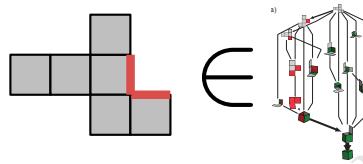
Define mutual information between each bond and target structure

$$I(x_i, y_j) = p(x_i, y_j) \log_2 \frac{p(x_i, y_j)}{p(x_i)p(y_j)}$$

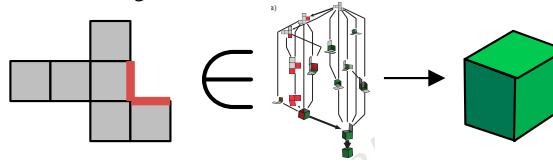
$x_i \in X$



$p(x_i)$



$p(x_i, y_j)$

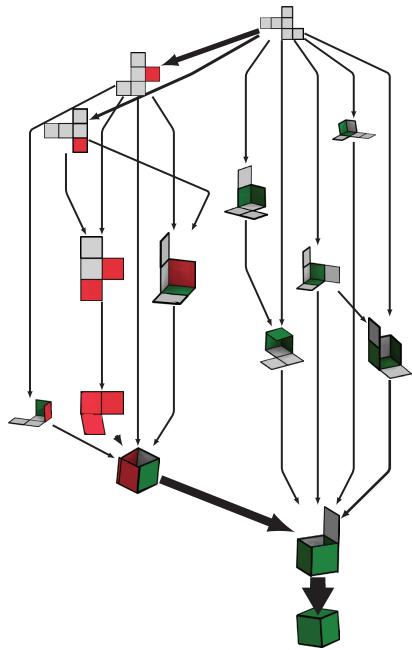


Hypothesis

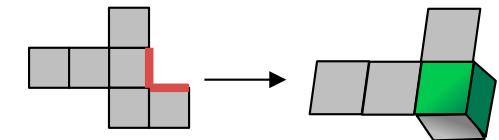
“Most critical bonds” are those with the highest mutual information to the target state



Task 3: Demonstrating the role of critical bonds in enabling self-assembly



Can we seed the net with a bond that will reliably lead to formation of the target structure?



Some nets may need more than one bond to fold properly—can we define an **efficiency** metric?

$$\eta = \frac{\text{instruction added}}{\text{target yield}}$$

How are these critical bonds related to the energetic landscape of the assembly?

Project 2: Develop energy landscapes for identifying kinetic barriers to assembly

Task

1

Develop disconnectivity graphs for folding pathways

2

Study favorable pathways identified from disconnectivity graphs

3

Identify which characteristics of a nets correspond to a narrower energetic funnel

Goal

Visualize and understand the energetics of system folding

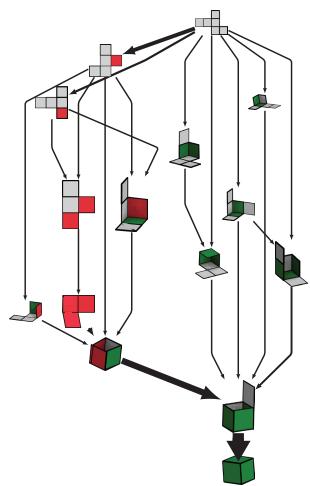
Identify commonalities between favorable paths (we expect that critical bonds would help assembly avoid kinetic traps)

Determine whether characteristics that correlate to higher yield (great leaves, compactness) correlate with narrower energetic funnel



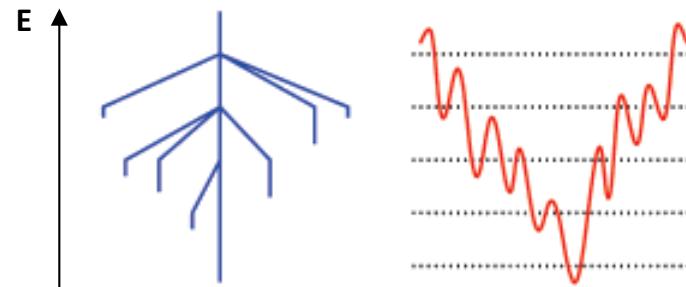
Task 1: Develop free energy disconnectivity graphs for folding pathways

Folding pathways with transition states...



Calculate energy for each transition state

... Mapped onto disconnectivity graph

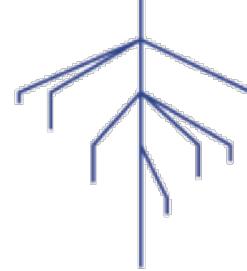
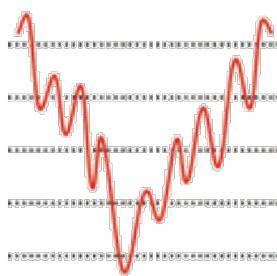


Will require significantly adapting existing code or writing our own methods for this

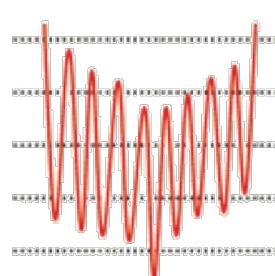
Tasks 2&3: What characteristics of a net correspond to a narrower energetic funnel?

Hypothesize that critical bonds prevent exploration of local minima

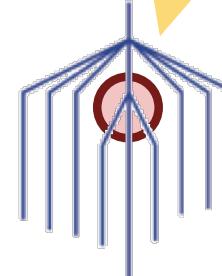
'palm tree'



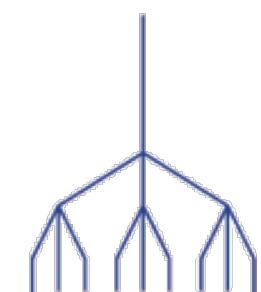
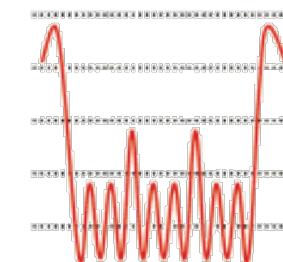
'weeping willow'



'weeping willow'



'banyan tree'



Can we find features of nets that make their energies look like this...

... Rather than this?

Knowing the energy landscape, can we hop from one minimum to another?

Project 3: Design pluripotent materials from minimal instructions

Task

1 Identify set of nets to test (multiple local minima of interest)

2 Develop minimal set of instructions (“critical bonds”) to fold into each

3 Seed pluripotent materials (nets) with critical bonds for target structure and test assembly

Goal

Assemble system into one local minima, then another, based on minimal programmed interactions

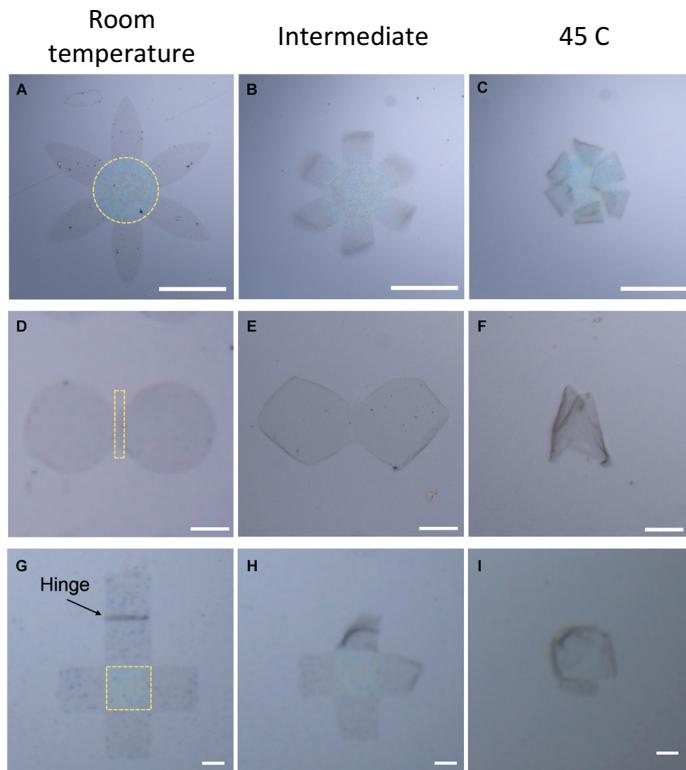
Apply approach from Project 1 to identifying critical bonds for a given target structure

Demonstrate that minimal instructions can be used to enable pluripotency

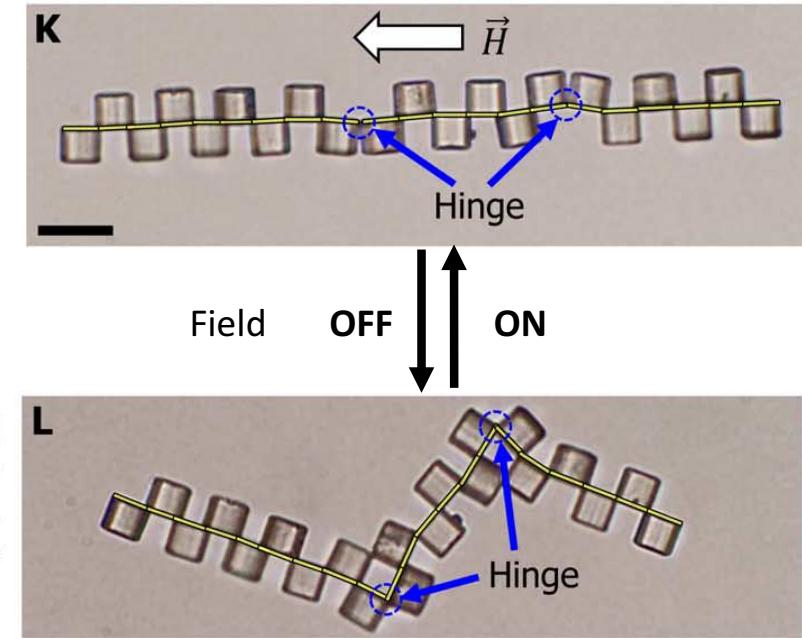


Folding is a demonstrated method of embedding pluripotency at microscale

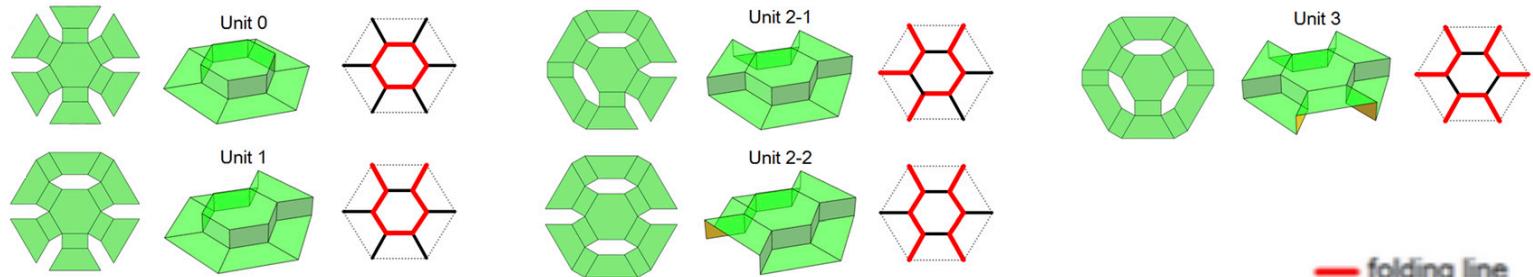
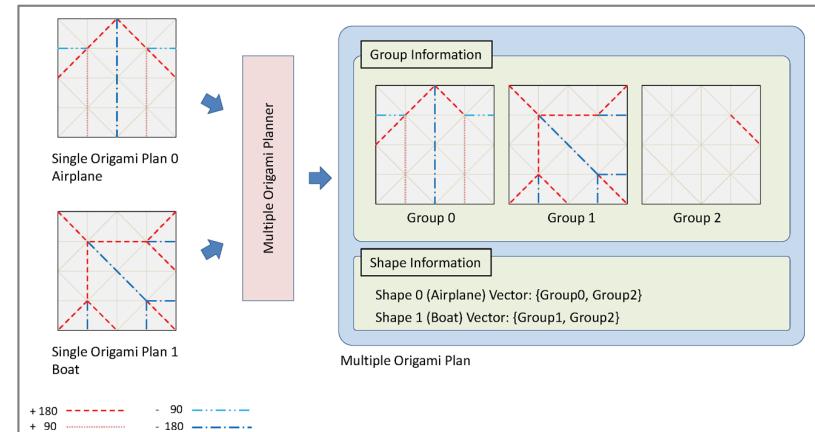
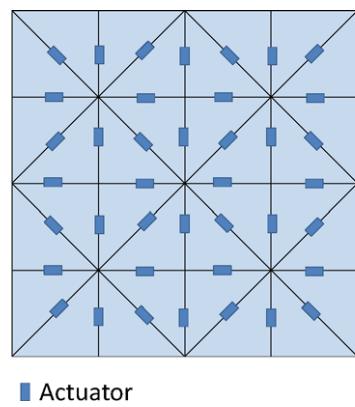
Thermo-responsive self-folding graphene sheets



Patchy magnetic cubes



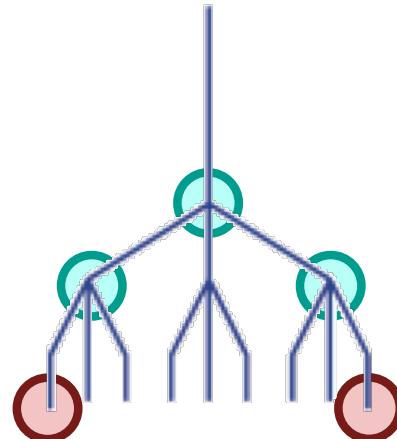
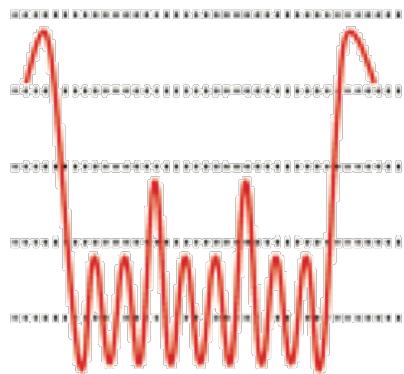
Macroscale folding pluripotency has been studied in origami, kirigami systems



Source: An et al, Robotica 2011; Sussman et al, PNAS 2015

Task 1&2: Identify target structures, critical bonds on disconnectivity graphs

Disconnectivity graph



Patchy magnetic cubes

Identify two target states
(Project 2)

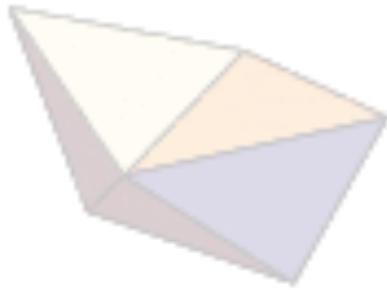
Find critical bonds to get to each
(Projects 1&2)

Find minimum set of interactions
that need to be programmed to
push material into either

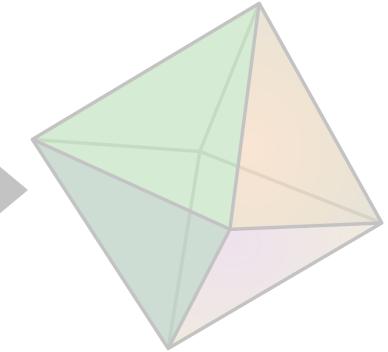


Example: Move between local minima in the energetic landscape of an octahedron

Poly-tetrahedron



Octahedron



HANDS-ON DEMO

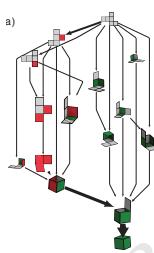
Lower free energy,
higher rotational
entropy

Higher free energy,
lower rotational
entropy

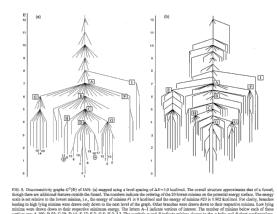
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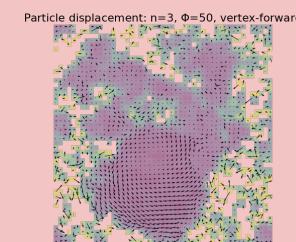


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Design pluripotent
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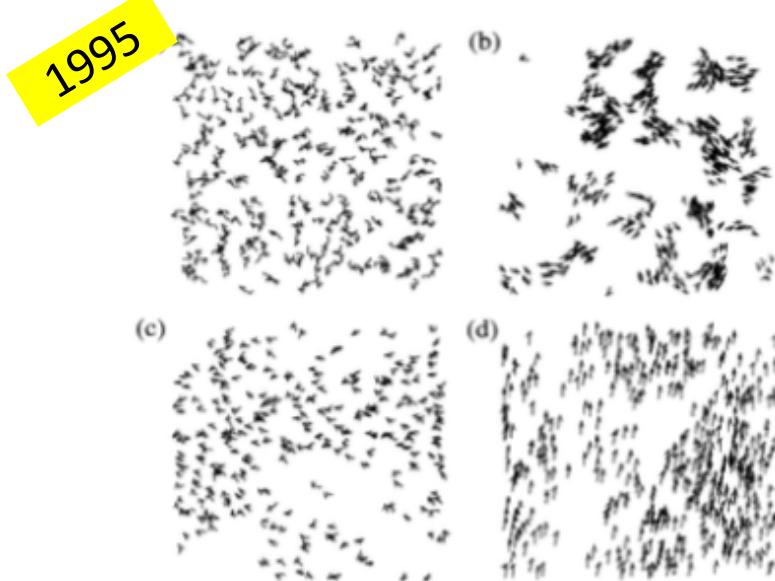
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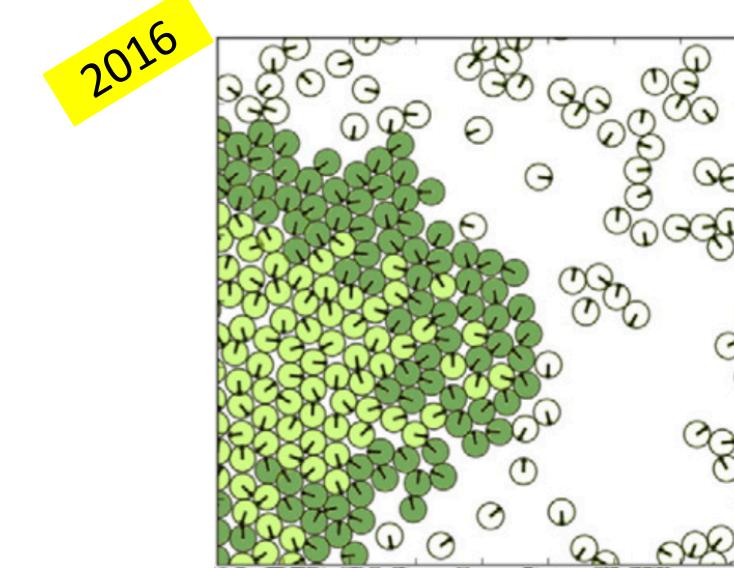


Active matter has been *active* for 20+ years, but the field is still establishing the basics

Particles with explicit alignment rules



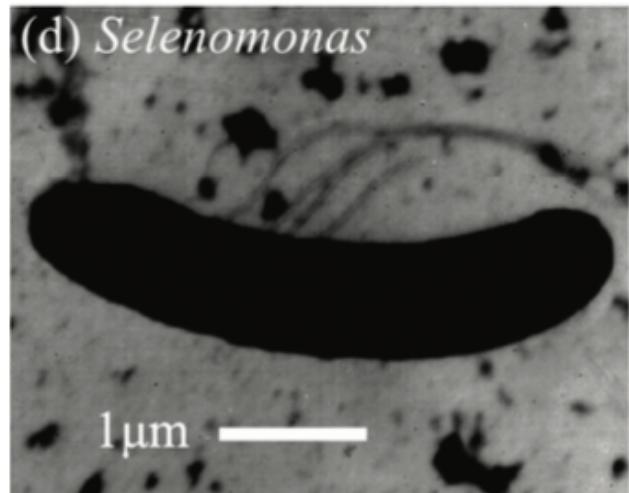
Isotropic particles



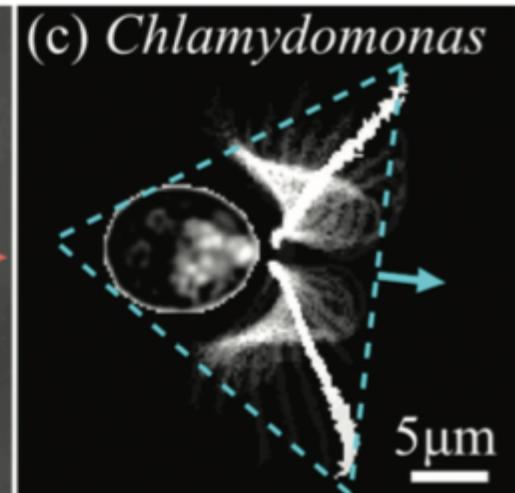
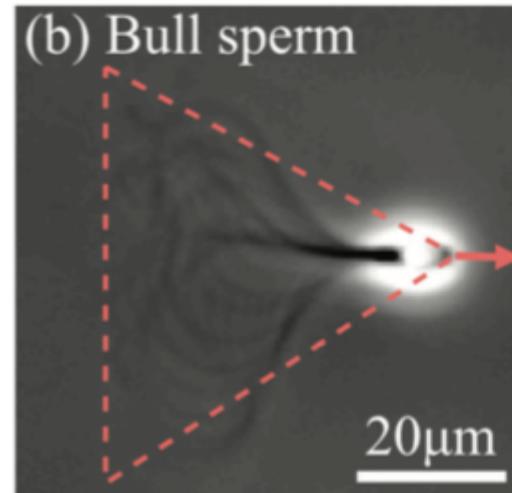
In nature, “particles” aren’t isotropic— that’s the exception rather than the norm

In nature, active *particle* anisotropy manifests itself two primary ways

Shape



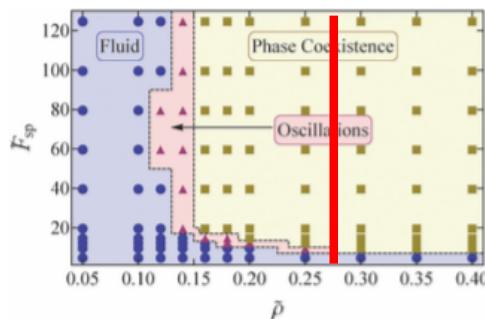
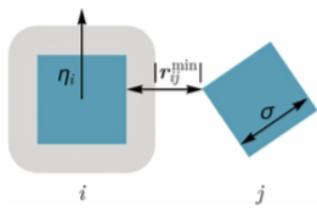
Force direction



The active matter community has also begun to study anisotropy in one-off experiments

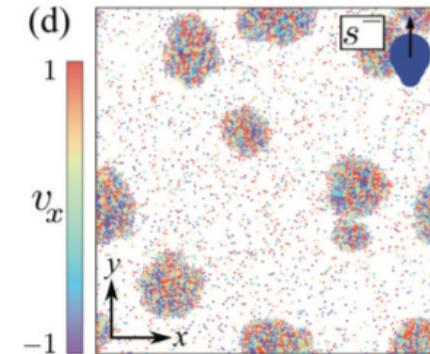
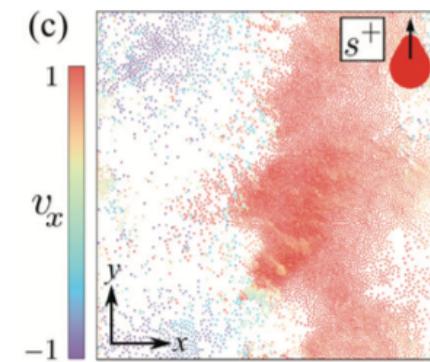
Shape

Critical density

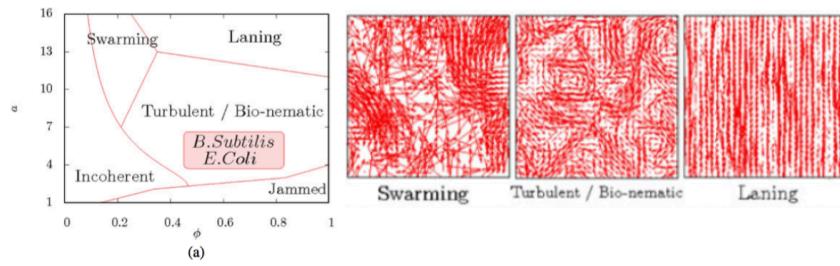


Force direction

Collective behavior



Collective behavior



Source: Prymidis et al, Soft Matter 2016; Wensink et al, EPJ 2013; Wensink et al, PRE 2014

Large open question: How/why does anisotropy allow for these different types of critical/collective behavior?

More targeted question: Can we explain why anisotropy leads to different critical and collective behaviors in a specific system?



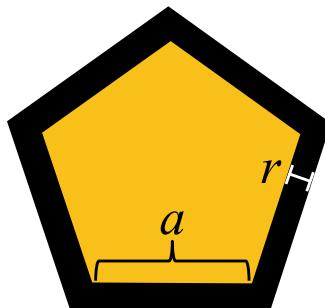
Methods: Excluded-volume particle interactions in the Brownian regime

Particle model

Shape

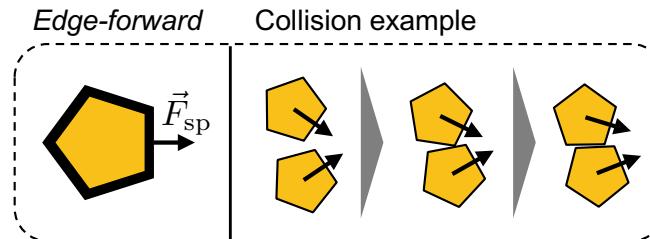
$$n = [3, 4, 5, 6, 7, 8]$$

$$0.9 = \frac{n \cdot a}{2\pi r}$$



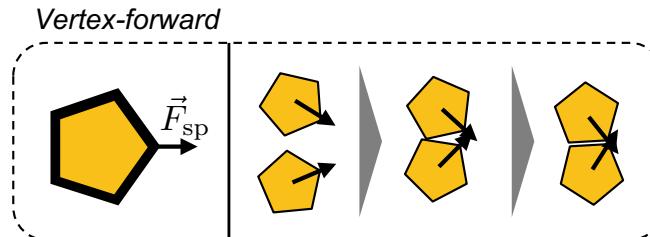
Force director

Edge-forward



Collision example

Vertex-forward



Langevin dynamics

$$m \frac{d\vec{v}}{dt} = \vec{F}_C - \gamma \cdot \vec{v} + \vec{F}_R$$

$$\langle \vec{F}_R \rangle = 0$$

$$\langle |\vec{F}_R|^2 \rangle = 2dkT\gamma/\delta t$$

Set mass equal to 1e-2 to approximate Brownian dynamics

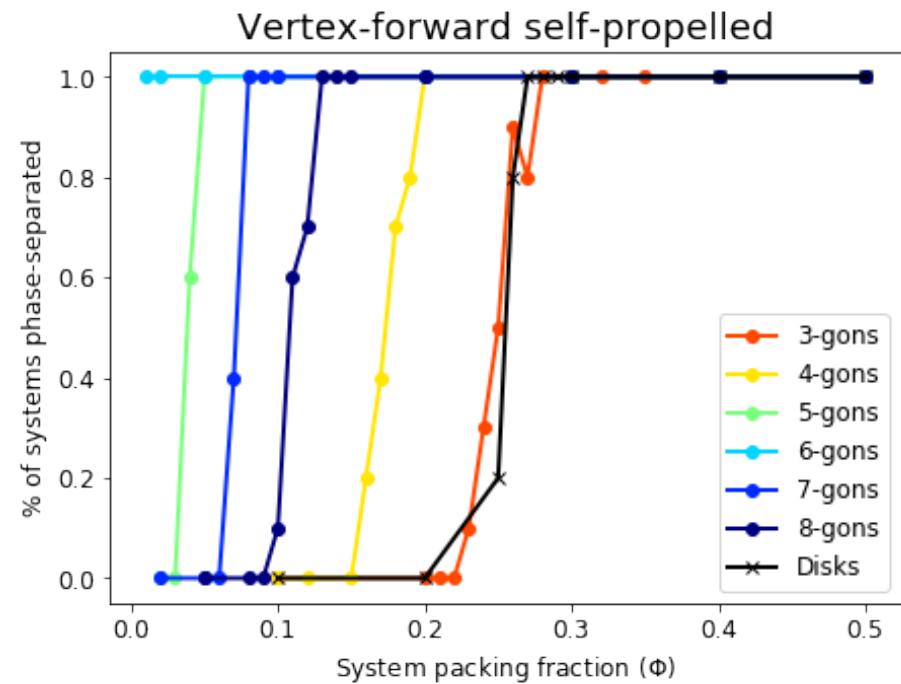
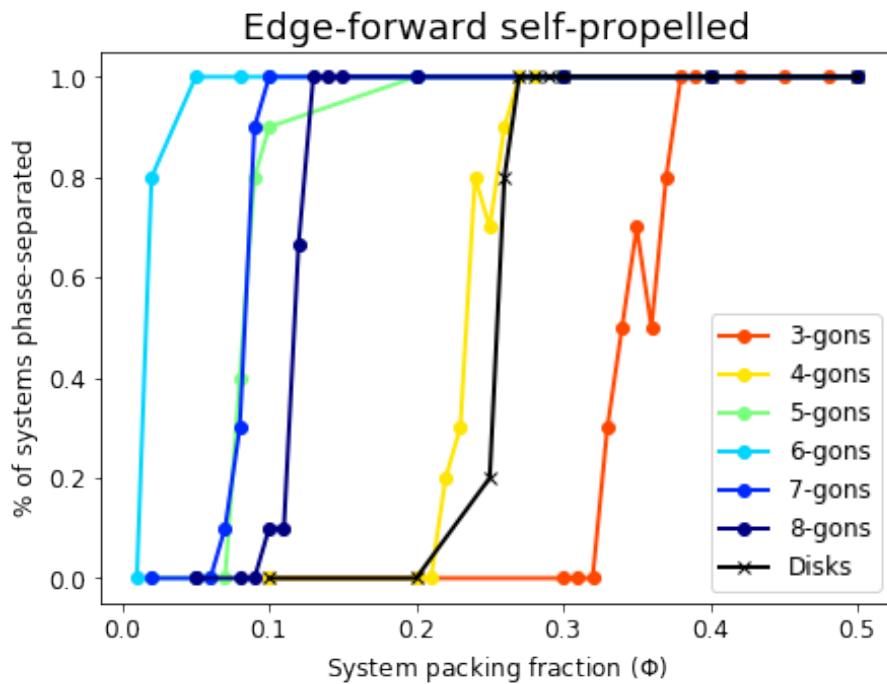
Weeks-Chandler-Anderson (WCA) inter-particle potential, simulated using the Discrete Element Method (DEM)

Project 0: Outline and hypotheses

Topic	Questions	Hypotheses
Critical density <i>Phase separation</i>	How does shape/force offset impact the critical density?	Anisotropy should depress critical density relative to that seen in disks
	Why does shape/force offset impact the critical density at all?	Should have “ more effective ” collisions—e.g. able to align with neighbors
Collective behavior <i>Nucleation</i>	How does shape/force offset impact nucleation behavior?	TBD
	Why does shape/force offset impact nucleation behavior?	Steric interactions between anisotropic particles are known to allow translation and rotation of clusters



Phase separation: Observe change in critical density, though not linearly with shape



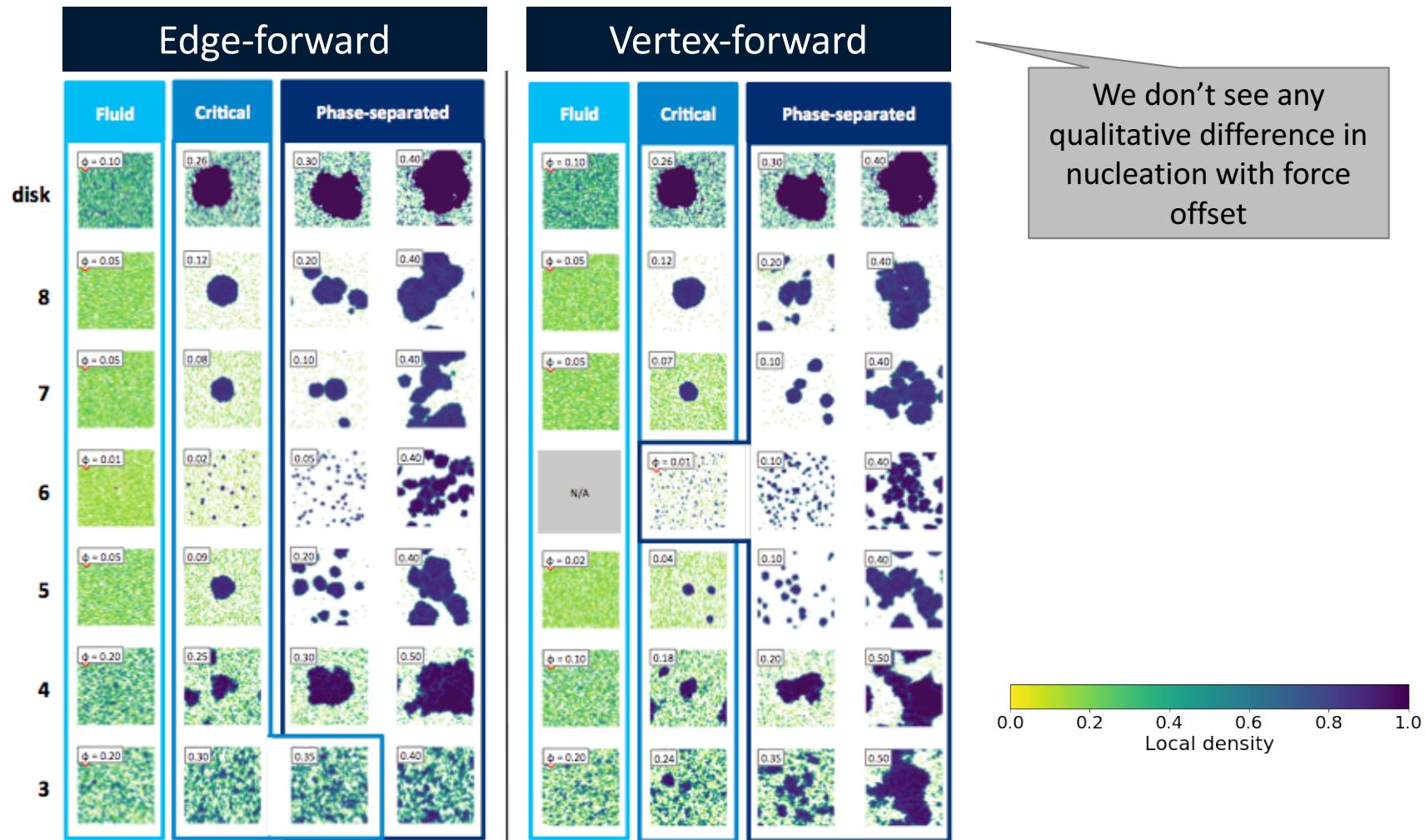
6 > 5/7 > 8 > 4 > disks > 3

6 > 5 > 7 > 8 > 4 > 3/disks

Notes: Phase separation determined by looking at local density histograms (looking for two density peaks) over 10 replicates—different from other studies, which have used “fraction of system in largest cluster”



Nucleation: Large clusters of shapes form through combinations from smaller clusters



Videos and displacement field images available in back-up material, if there's interest



Other active matter theories don't work well to explain the behavior we see here

Theory

Kinetic theory

Redner et al, PRL 2013

Motility-induced phase separation (MIPS)

Tailleur and Cates, PRL 2008

Collision theory

Bruss and Glotzer, arxiv 2017

Schematic

Based on the assumptions that:

- Particles can diffuse and escape clusters (WRONG)
- System forms one large cluster which nucleates and grows (WRONG)

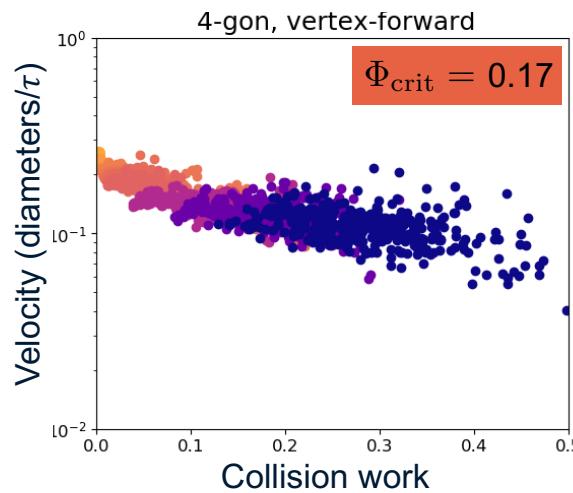
We can extend this to say:

- “More effective” collisions are those that are more effective at slowing particles down → i.e. **some shapes have more efficient collisions than others**
- **Novel:** Explanation that shape can be used to tune phase separation by increasing “effectiveness” of interactions

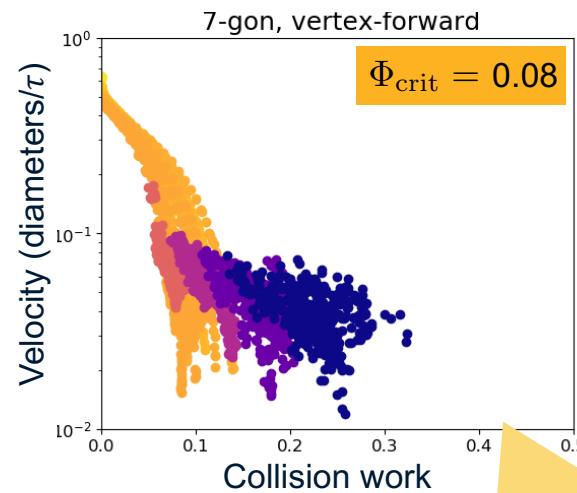
Based on free time, triangles should phase separate most easily (highest cross section to area ratio)
→ **Reinforces that our observations must be explained by collision time-scale!**

“More efficient” shape collisions slow velocity more with less work done by collisions

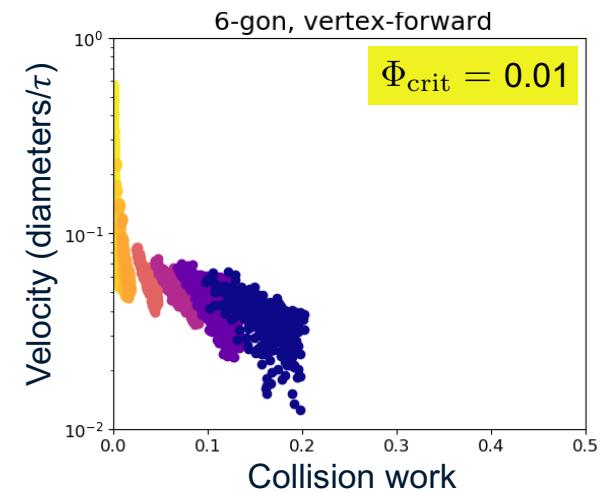
3 and 4-gons



5/7/8-gons



6-gons



$$W = \frac{1}{2} \sum_i \sum_{j \neq i} \vec{F}_{ij} \cdot \vec{r}_{ij}$$

Currently working to clarify behavior in critical regime



Near-term next steps

- Project 0: Particle anisotropy in active system
 - Solidify “collision efficiency” metric
 - Finalize and submit paper for publication
- Project 1: Pathway information
 - Analyzing data already available from in-preparation paper on folding nets
 - How accurate is the first approximation at a mutual information between edge bonds and net folding?
- Project 2: Energy landscapes
 - Restart collaboration between Wales group alum and Glotzer lab



Thank you in advance for your questions and feedback!

How can we tailor self-assembly?

Proposed work: What is the minimal set of instructions needed to achieve targeted, self-assembled complexity?

Prior work: How does shape impact assembly behavior in active systems?

Project 1
Define measure of pathway information

Project 2
Develop energy landscapes for identifying kinetic barriers to assembly

Project 3
Design pluripotent materials using minimal instructions

Project 0
Define role of particle anisotropy in a translationally-driven system



Reference slides



Integration methods

- Langevin implemented using a velocity verlet algorithm (same as the NVE)
- Brownian: Nose Hoover, have to solve for using predictor corrector method (slower, have to use smaller time step)



Planned timeline

Project	Status	Description	2017				2018				2019				2020	
			Q1	Q2	Q3	Q4	Q1	Q2	Q3	Q4	Q1	Q2	Q3	Q4	Q1	Q2
Project 0 <i>Active shapes</i>	100%	Data collection														
	90%	Analysis														
	75%	Writing														
	0%	Submit, revisions														
Project 1 <i>Information metrics</i>	0%	Data collection														
	0%	Analysis														
	0%	Writing														
	0%	Submit, revisions														
Project 2 <i>Energy landscapes</i>	0%	Develop code														
	0%	Data collection														
	0%	Analysis														
	0%	Writing														
Project 3 <i>Pluripotent materials</i>	0%	Submit, revisions														
	0%	Data collection														
	0%	Analysis														
	0%	Writing														
Thesis	0%	Submit, revisions														
	0%	Data meeting														
	0%	Defense														



While info. theory struggles to catch on in assembly, in non-eq stat mech it is gaining

nature
physics

INSIGHT | REVIEW ARTICLES
PUBLISHED ONLINE: 3 FEBRUARY 2015 | DOI: 10.1038/NPHYS3230

Thermodynamics of information

Juan M. R. Parrondo^{1*}, Jordan M. Horowitz² and Takahiro Sagawa³

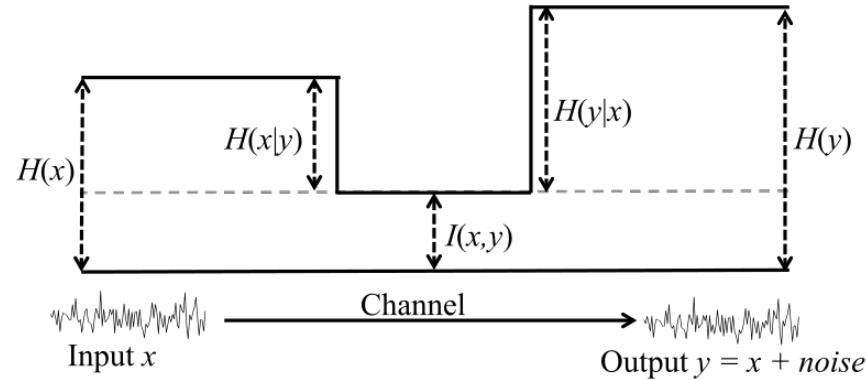
By its very nature, the second law of thermodynamics is probabilistic, in that its formulation requires a probabilistic description of the state of a system. This raises questions about the objectivity of the second law: does it depend, for example, on what we know about the system? For over a century, much effort has been devoted to incorporating information into thermodynamics and assessing the entropic and energetic costs of manipulating information. More recently, this historically theoretical pursuit has become relevant in practical situations where information is manipulated at small scales, such as in molecular and cell biology, artificial nano-devices or quantum computation. Here we give an introduction to a novel theoretical framework for the thermodynamics of information based on stochastic thermodynamics and fluctuation theorems, review some recent experimental results, and present an overview of the state of the art in the field.

Citations: 292

38



Quick primer on information theory (cont.)

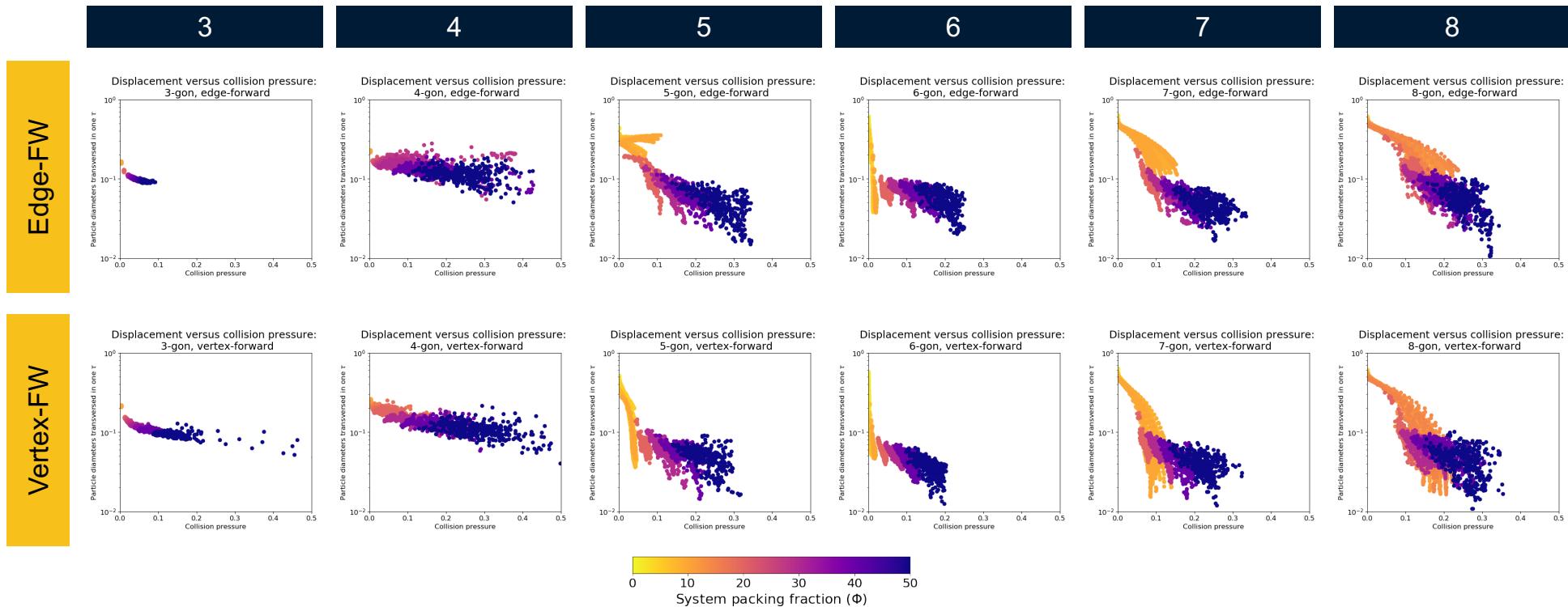


$$H(X) = - \sum_x p(x) \log_2 p(x)$$

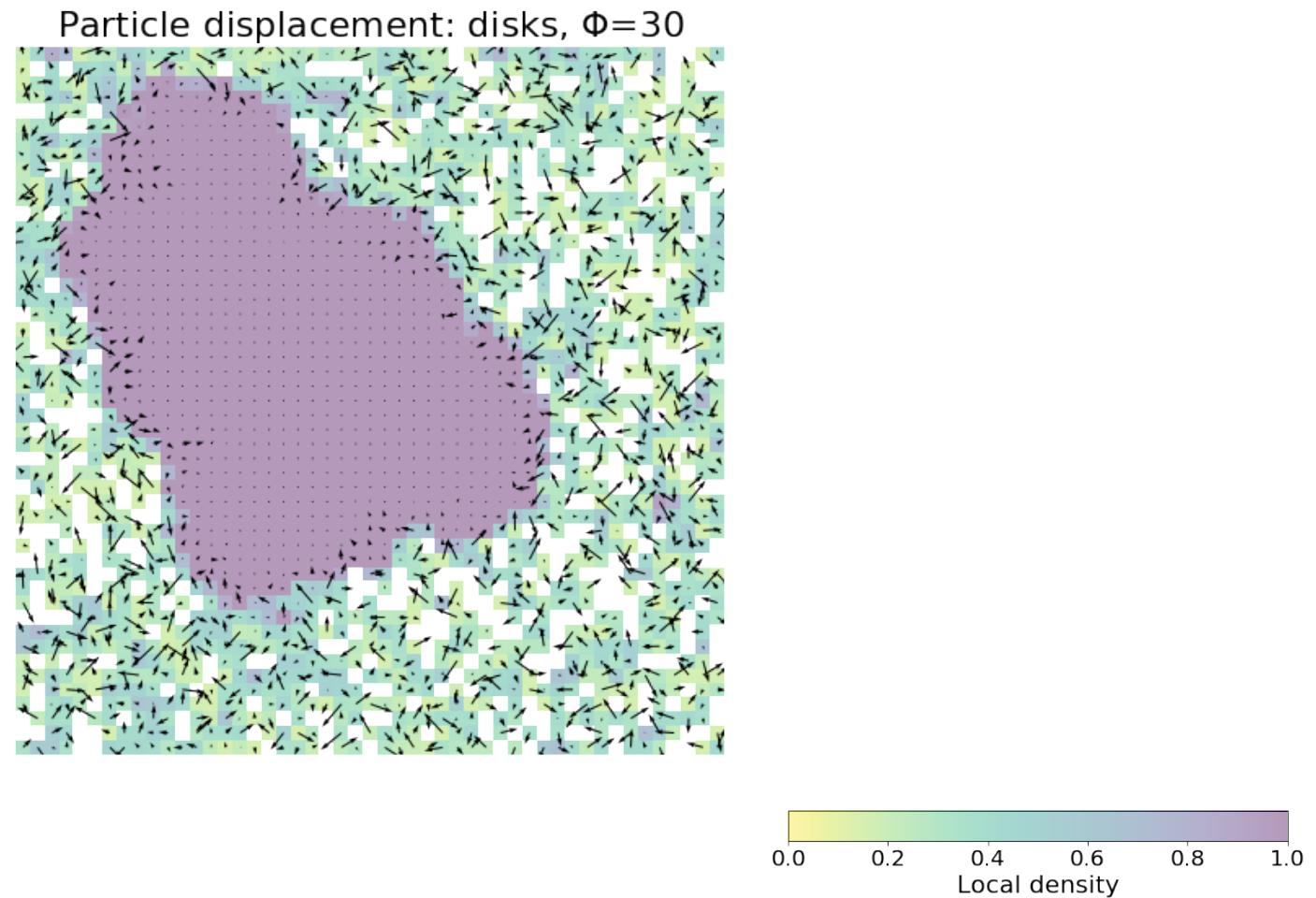
$$I(X;Y) = H(X) + H(Y) - H(X,Y)$$

$$\begin{aligned} I(X;Y) &= H(X) - H(X|Y) \\ &= H(Y) - H(Y|X) \end{aligned}$$

Shapes with lower critical densities have steeper change in velocity versus pressure



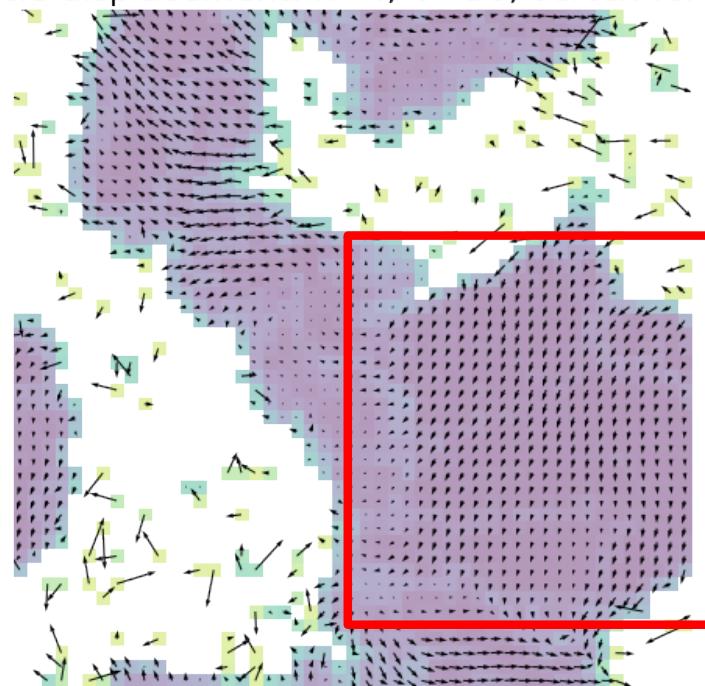
Clusters of disks do not have translational or rotational motion



Clusters of shapes can sustain both translational and rotational motion

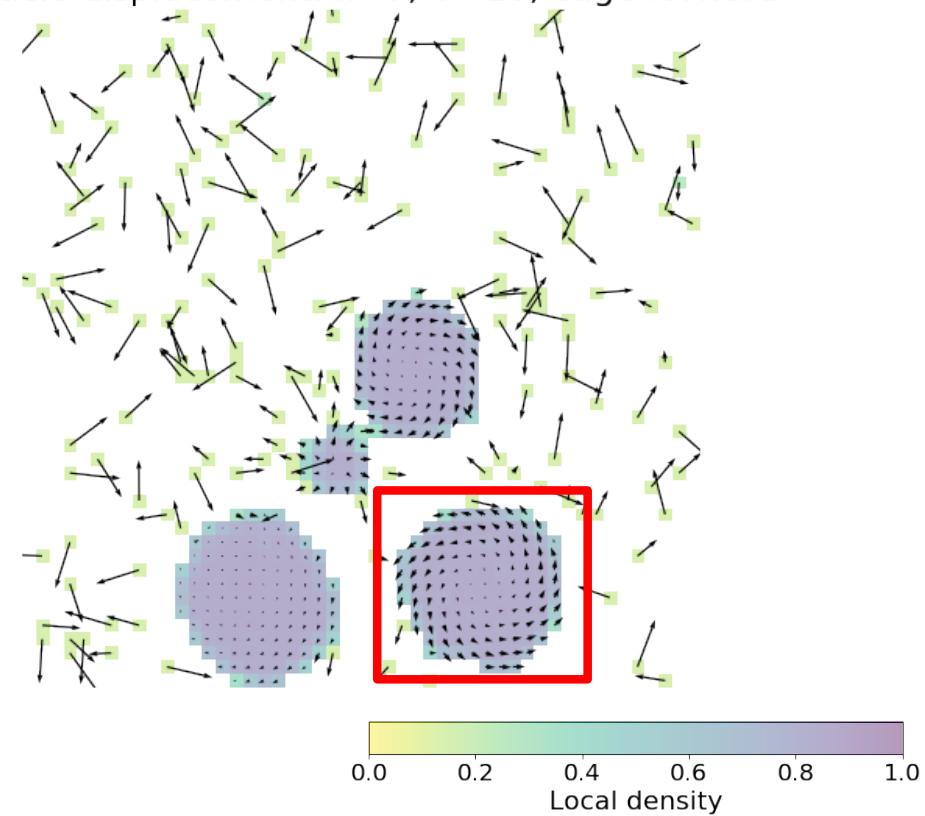
Example: Translational motion

Particle displacement: $n=4$, $\Phi=50$, vertex-forward



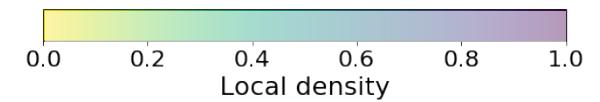
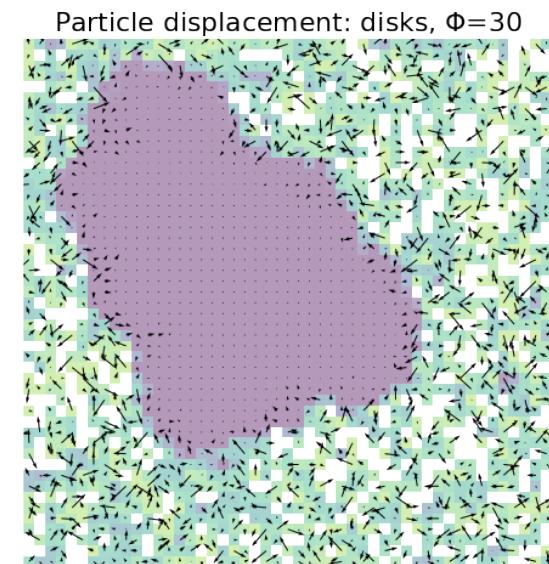
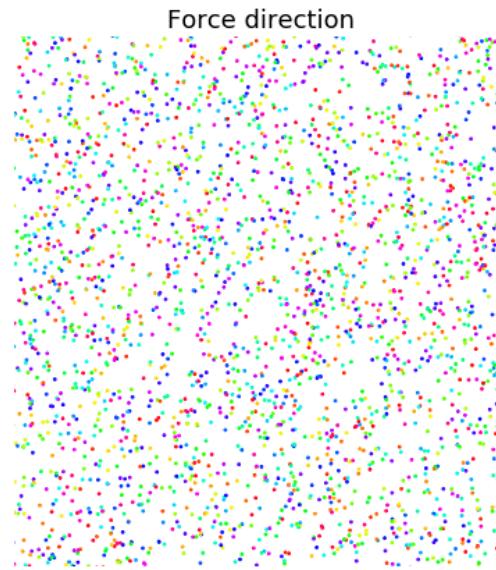
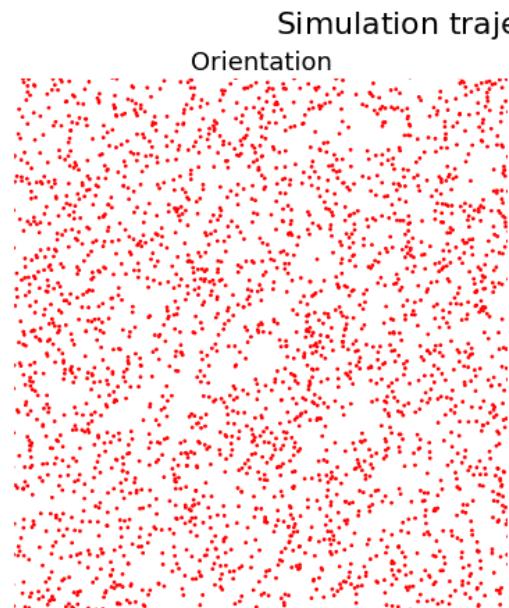
Example: Rotational motion

Particle displacement: $n=7$, $\Phi=10$, edge-forward

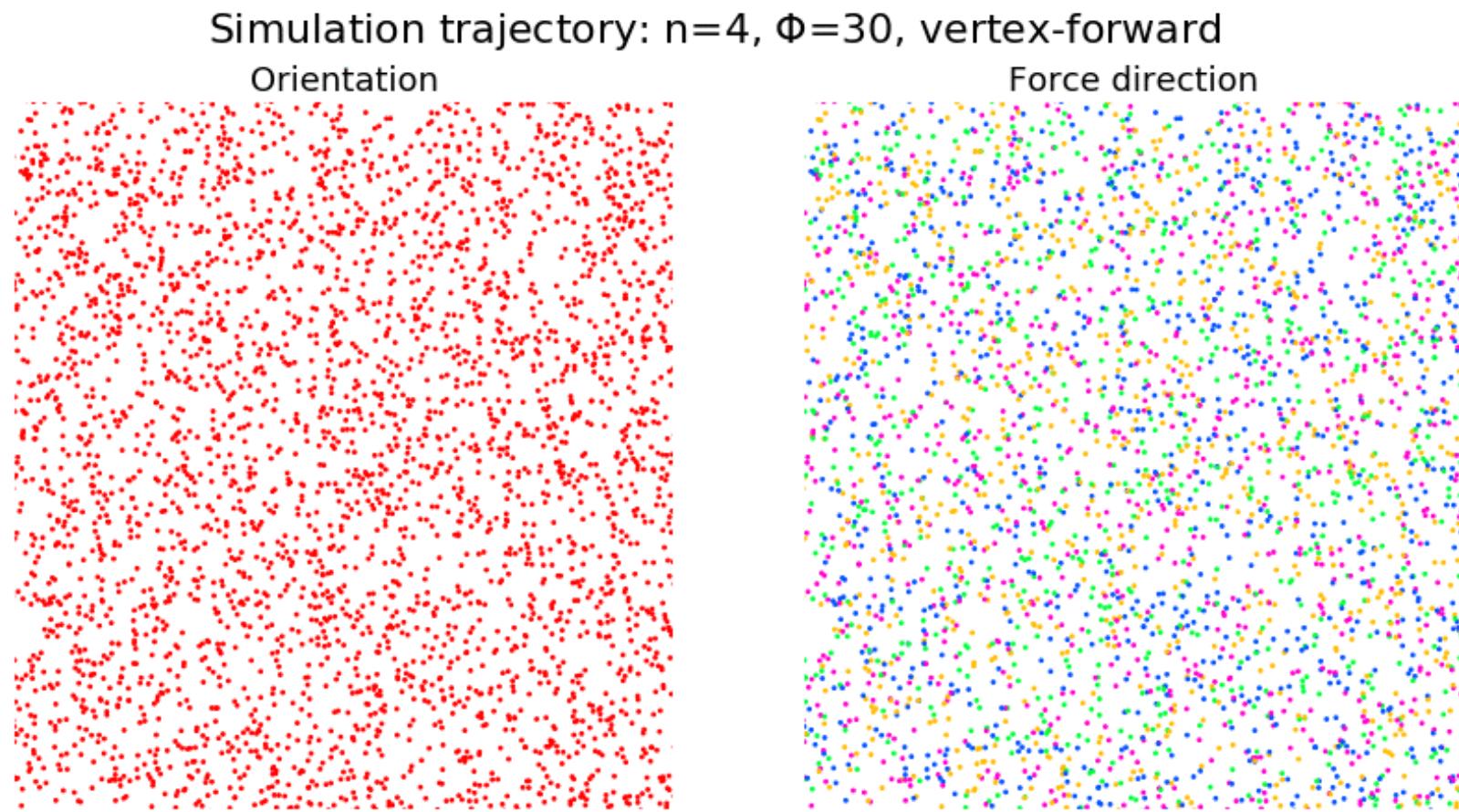


In disks, large clusters form via *merging*,
rather than colliding)

Disks



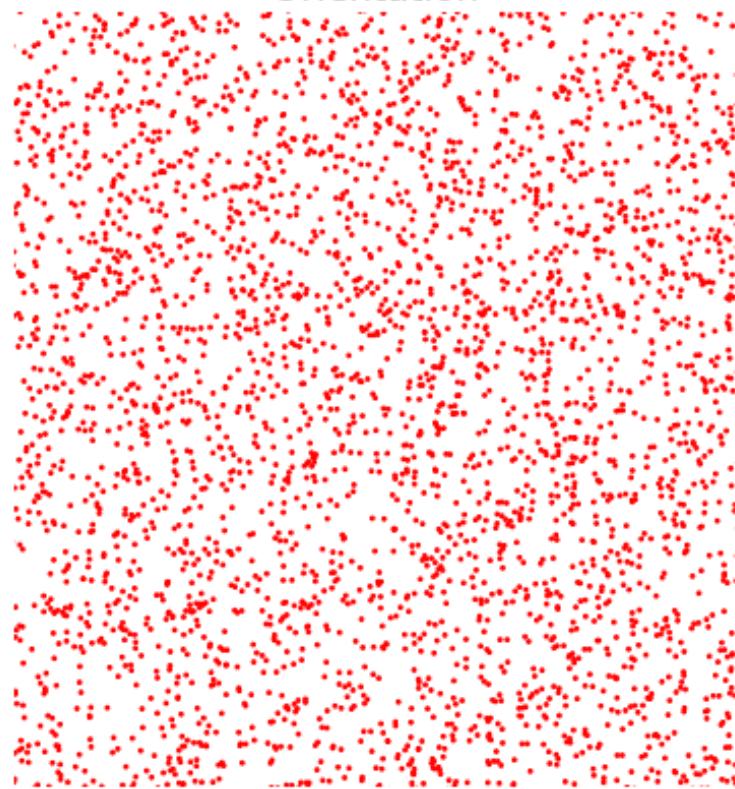
Video: 3 and 4-gons have shear planes, can't stabilize stresses



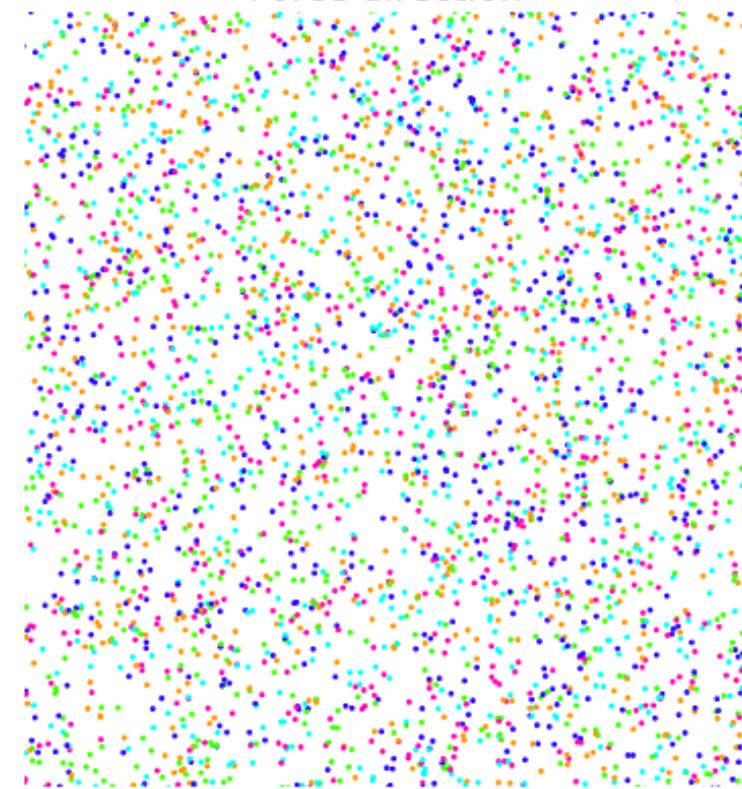
Video: 5/7/8-gons pack, but not perfectly

Simulation trajectory: $n=5, \Phi=30$, vertex-forward

Orientation



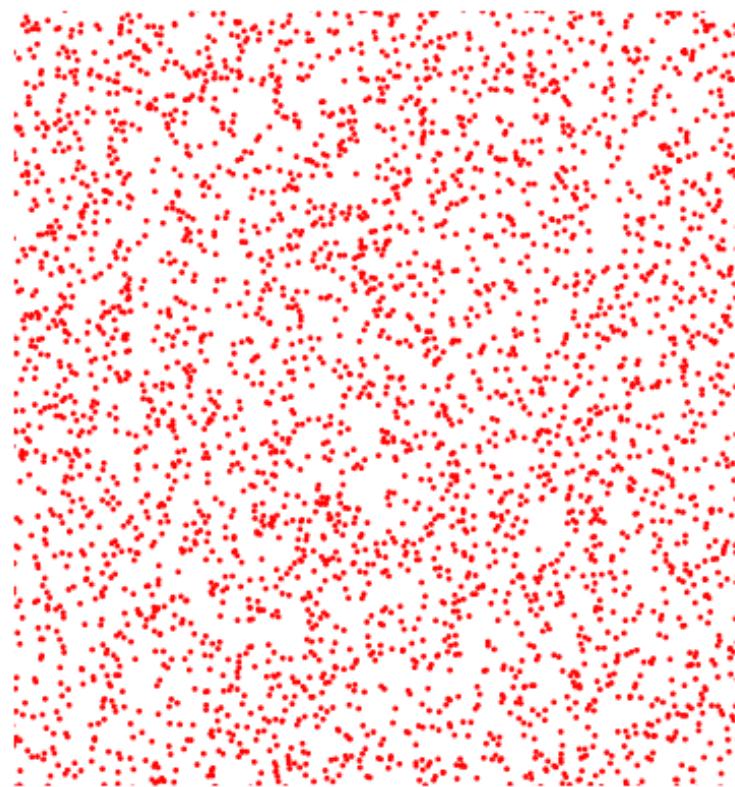
Force direction



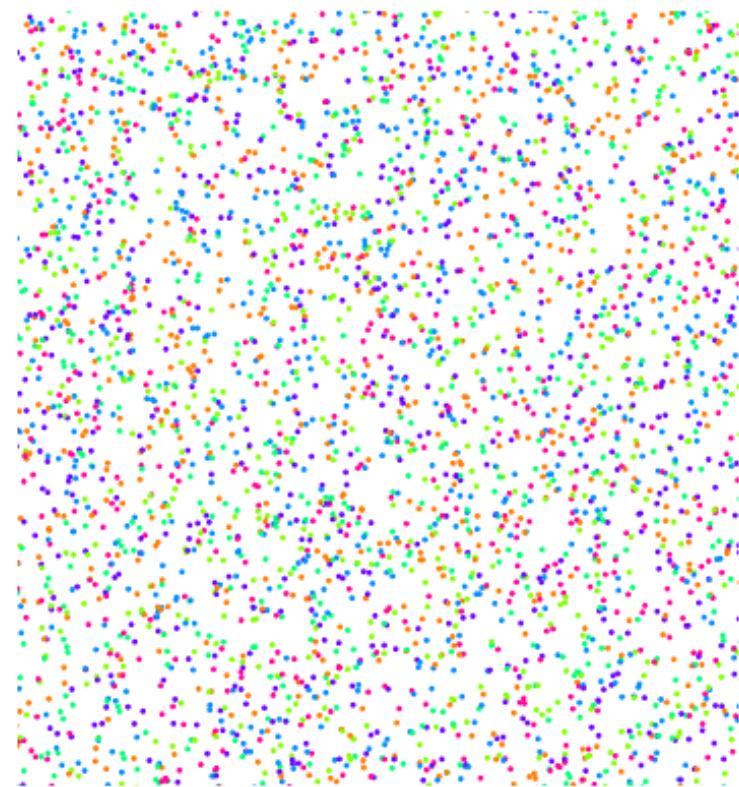
Video: 6-gons tile space

Simulation trajectory: $n=6$, $\Phi=30$, vertex-forward

Orientation



Force direction



*Could envision modeling a 4-fold pentile to test whether
the density of the packing/lack of shear planes matters*



In conclusion: Shape matters

Topic	Questions	Findings
Critical density <i>Phase separation</i>	<p>1 How does shape/force offset impact the critical density?</p> <p>2 Why does shape/force offset impact the critical density at all?</p>	<p>Shape can enable lower (or higher!) critical densities than disks</p> <p>Shape and force offset can work together to change the efficiency of collision, i.e. the change in velocity due to collision</p>
Collective behavior <i>Nucleation</i>	<p>3 How does shape/force offset impact nucleation behavior?</p> <p>4 Why does shape/force offset impact nucleation behavior?</p>	<p>Shapes cluster through an initial arrested phase separation (?) then combination/relaxation, rather than a cluster percolation model (disks)</p> <p>Steric interactions between anisotropic particles allow translation and rotation of clusters; ability of densest packing can stabilize shear may come into play</p>



Statistical mechanics

Boltzman distribution law:

$$p_i = \frac{e^{-\beta E_i}}{Z}$$

Partition function:

$$Z = \sum_{i=1}^N e^{-\beta E_i}$$



Ensembles

