



Machine Vision

Wu Wei



Image Enhancement

Images Enhancement



01

Gray Level
Transformations

02

Histogram
Processing

03

Arithmetic/Logical
Operation

04

Spatial Filtering

05

Frequency Filtering

Image Enhancement

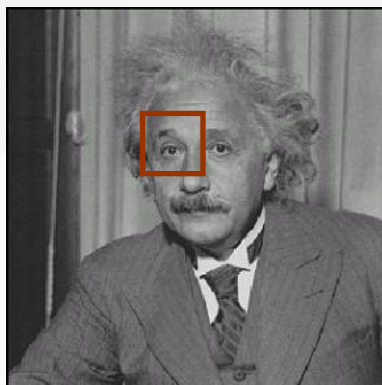
● Spatial Filtering

■ Smoothing



Original

0	0	0
0	1	0
0	0	0



Filtered (no change)

Image Enhancement

- Spatial Filtering

- Smoothing



Original

0	0	0
0	0	1
0	0	0

?

Image Enhancement

● Spatial Filtering

■ Smoothing



Original

0	0	0
0	0	1
0	0	0



Shifted *left* By 1 pixel

Image Enhancement

● Spatial Filtering

■ Smoothing



Original

$\frac{1}{9}$

1	1	1
1	1	1
1	1	1

?

Image Enhancement

● Spatial Filtering

■ Smoothing



Original

$$\frac{1}{9}$$

1	1	1
1	1	1
1	1	1



Blur (with a box filter)

Image Enhancement

● Spatial Filtering

■ Smoothing



Original

0	0	0
0	2	0
0	0	0

-

$\frac{1}{9}$

1	1	1
1	1	1
1	1	1

?

(Note that filter sums to 1)

● Spatial Filtering

- Fundamentals (Kernel, convolution, filtering)
- Smoothing (Linear / non-linear filters)
- Sharpening (The Laplacian-2ndorder derivatives, the gradient -first order derivatives)
- Combing Spatial Enhancement Methods



Image Enhancement

- Spatial Filtering

- Sharpening

- Principle objective

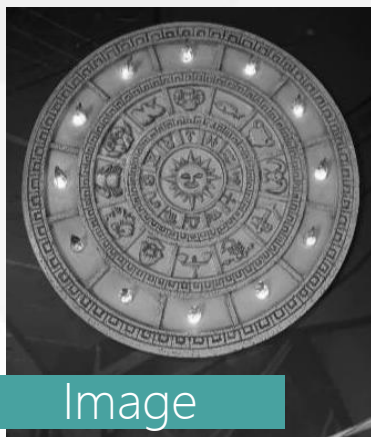
To **highlight fine detail** in an image or to **enhance detail** that has been blurred, either in error or as a natural effect of a particular method of image acquisition.

Image Enhancement

Spatial Filtering

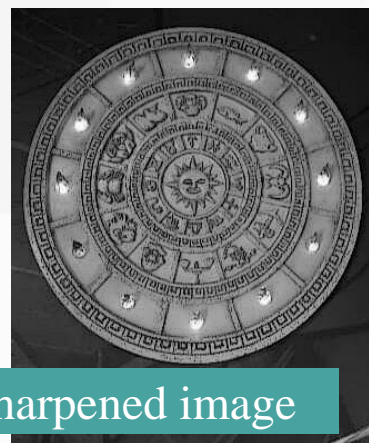
Sharpening

- Previously we have looked at smoothing filters which remove fine detail
- *Sharpening spatial filters* seek to highlight fine detail
 - Remove blurring from images
 - Highlight edges
- Sharpening filters are based on spatial differentiation



Image

$$\begin{bmatrix} -0.5 & 0 & -0.5 \\ 0 & 2 & 0 \\ -0.5 & 0 & -0.5 \end{bmatrix}$$



Sharpened image



Image Enhancement

- Spatial Filtering

- Sharpening

- Properties of 1st and 2nd-Order Derivatives
- Use of 2nd Derivatives for Enhancement- The Laplacian
- Use of 1st Derivatives for Enhancement - The Gradient



Image Enhancement

- Spatial Filtering

- Sharpening

- First order derivative for a discrete function

$$\frac{\partial f}{\partial x} = f(x+1) - f(x)$$

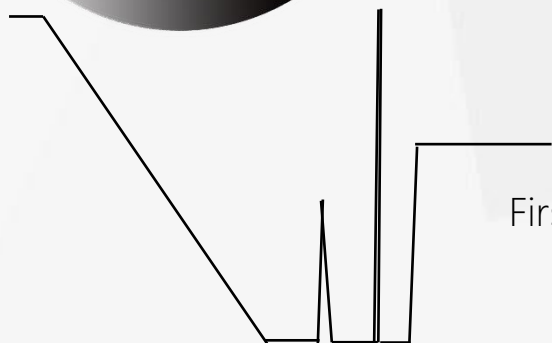
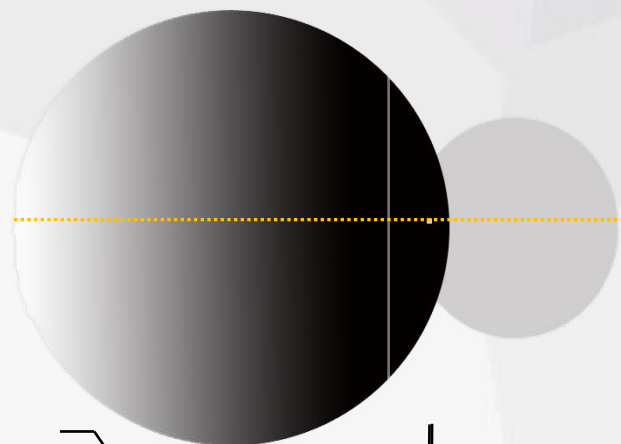
- Second order derivative for a discrete function

$$\frac{\partial^2 f}{\partial x^2} = f(x+1) + f(x-1) - 2f(x)$$

Image Enhancement

● Spatial Filtering

■ Sharpening



Gray level profile

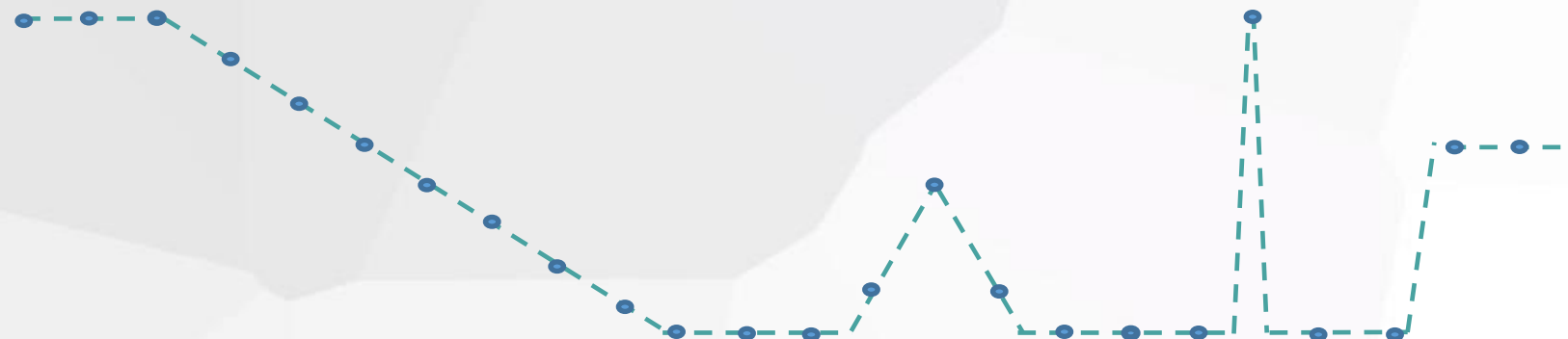


Image strip

8	8	8	7	6	5	4	3	2	1	0	0	0	1	4	1	0	0	0	9	0	0	5	5
	0	0	-1	-1	-1	-1	-1	-1	-1	-1	0	0	1	3	-3	-1	0	0	9	-9	0	5	0
	0	-1	0	0	0	0	0	0	0	1	0	1	2	-6	2	1	0	9	-18	9	5	-5	

First Derivative

Second Derivative

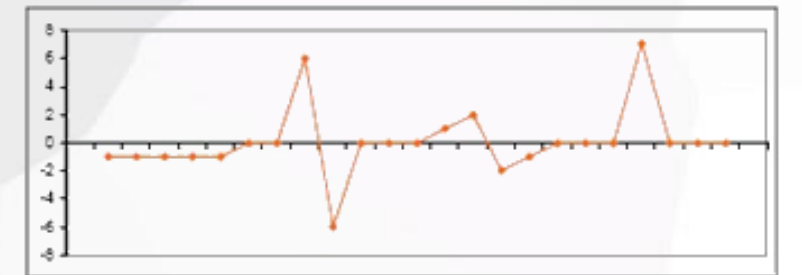
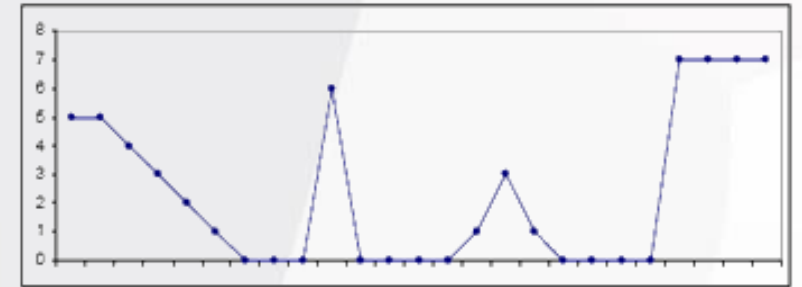
Image Enhancement

● Spatial Filtering

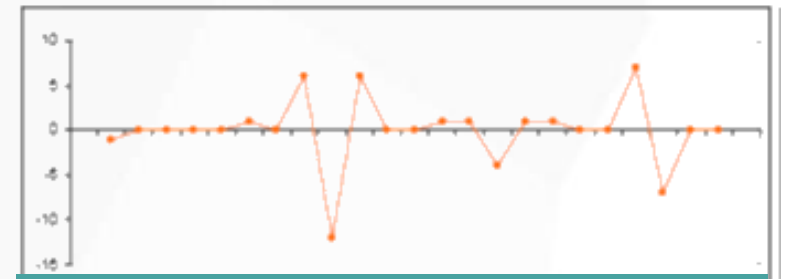
■ Sharpening

Definition:

- First derivative filter output
 - Zero at constant intensities
 - Non zero at the onset of a step or ramp
 - Non zero along ramps
- Second derivative filter output
 - Zero at constant intensities
 - Non zero at the onset of a step or ramp
 - Zero along ramps



First derivative filter output



Second derivative filter output



Image Enhancement

● Spatial Filtering

■ Sharpening

Conclusion:

- First-order derivatives generally produce thicker edges in an image.
- Second-order derivatives have a stronger response to fine detail, such as thin lines and isolated points.
- First order derivatives generally have a stronger response to a gray-level step.
- Second-order derivatives produce a double response at step changes in gray level.



Image Enhancement

- Spatial Filtering

- Sharpening

- Properties of 1st and 2nd-Order Derivatives
- Use of 2nd Derivatives for Enhancement- The Laplacian
- Use of 1st Derivatives for Enhancement - The Gradient



Image Enhancement

● Spatial Filtering

■ Sharpening

- A common second derivative sharpening filter is the **Laplacian**
 - Isotropic
 - Rotation invariant: Rotating the image and applying the filter is the same as applying the filter and then rotating the image.
 - One of the simplest sharpening filters

Image Enhancement


● Spatial Filtering

■ Sharpening

● The Laplacian

$$\nabla^2 f = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2}$$

$$\nabla^2 f = [f(x+1, y) + f(x-1, y) + f(x, y+1) + f(x, y-1)] - 4f(x, y)$$



0	1	0
1	-4	1
0	1	0

Image Enhancement

● Spatial Filtering

■ Sharpening

● The Laplacian

$$\begin{bmatrix} 0 & 1 & 0 \\ 1 & -4 & 1 \\ 0 & 1 & 0 \end{bmatrix}$$

1	1	1
1	-8	1
1	1	1

$$\begin{bmatrix} 0 & -1 & 0 \\ -1 & 4 & -1 \\ 0 & -1 & 0 \end{bmatrix}$$

$$\begin{bmatrix} -1 & -1 & -1 \\ -1 & 8 & -1 \\ -1 & -1 & -1 \end{bmatrix}$$

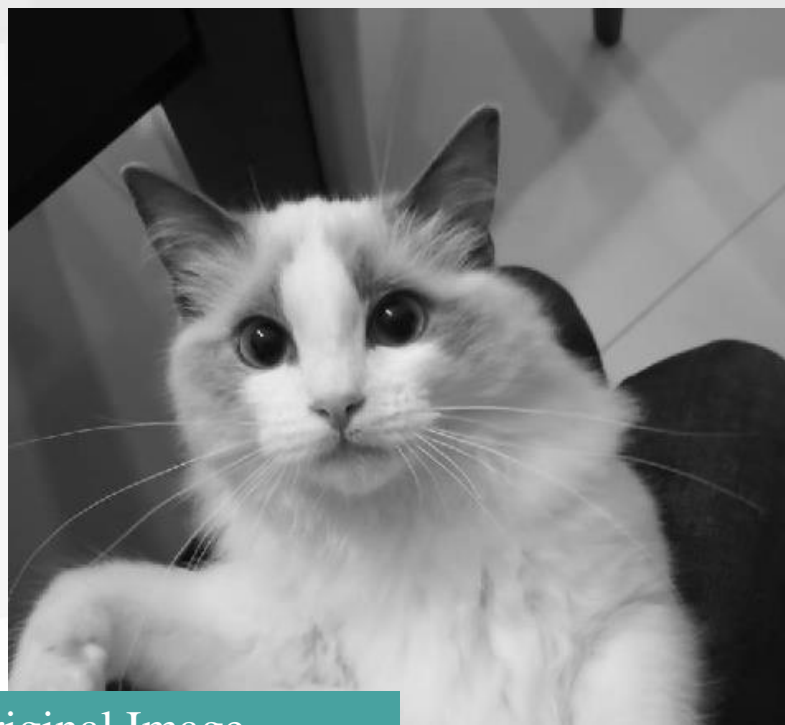
Image Enhancement

● Spatial Filtering

■ Sharpening

● The Laplacian

1	2	1
1	-10	1
1	2	1



Original Image



Laplacian Filtered Image



Image Enhancement

- Spatial Filtering

- Sharpening

- The **Laplacian**

The result of a Laplacian filtering is not an enhanced image

- We have to do more work
- Subtract the Laplacian result from the original image to
Laplacian Filtered Image generate our final sharpened enhanced
image

$$g(x, y) = f(x, y) - \nabla^2 f(x, y)$$

Image Enhancement

● Spatial Filtering

■ Sharpening

● The Laplacian



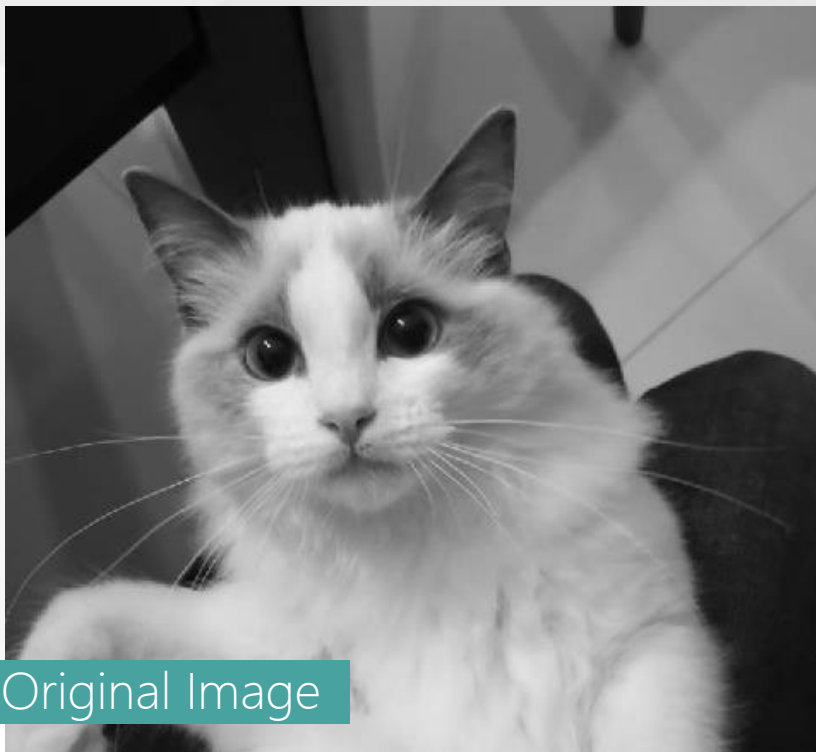
In the final, sharpened image, edges and fine detail are much more obvious

Image Enhancement

- Spatial Filtering

- Sharpening

- The Laplacian



Original Image



Enhanced Image

Image Enhancement

- Spatial Filtering

- Sharpening

- The Laplacian



Original Image



Enhanced Image

Image Enhancement

● Spatial Filtering

■ Sharpening

● The Laplacian

0	1	0	1	1	1
1	-4	1	1	-8	1
0	1	0	1	1	1
0	-1	0	-1	-1	-1
-1	4	-1	-1	8	-1
0	-1	0	-1	-1	-1

The composed *Laplacian* enhancement image is given by:

$$g(x, y) = \begin{cases} f(x, y) - \nabla^2 f(x, y) & \text{if the center coefficient of the Laplacian mask is negative} \\ f(x, y) + \nabla^2 f(x, y) & \text{if the center coefficient of the Laplacian mask is positive} \end{cases}$$

Image Enhancement

● Spatial Filtering

■ Sharpening

● The **Laplacian**

- The entire enhancement can be combined into a single filtering operation:

$$\begin{aligned} g(x, y) &= f(x, y) - [f(x+1, y) + f(x-1, y) \\ &\quad + f(x, y+1) + f(x, y-1)] + 4f(x, y) \\ &= 5f(x, y) - [f(x+1, y) + f(x-1, y) \\ &\quad + f(x, y+1) + f(x, y-1)] \end{aligned}$$

0	-1	0
-1	5	-1
0	-1	0

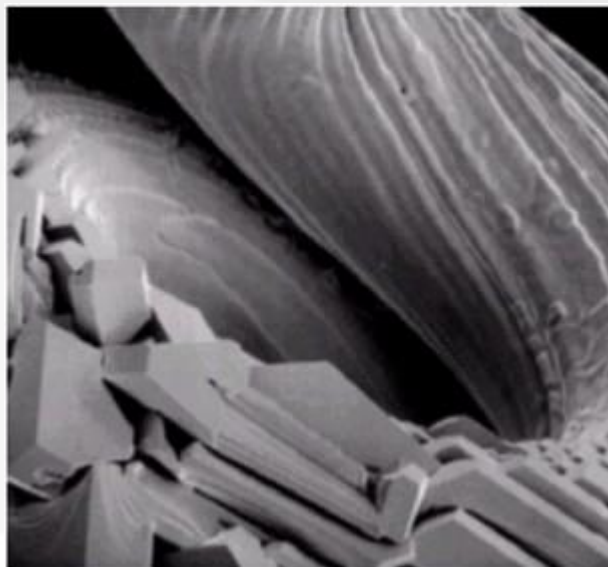
Image Enhancement

● Spatial Filtering

■ Sharpening

● The **Laplacian**

This gives us a new filter which does the whole job in one step



0	-1	0
-1	5	-1
0	-1	0

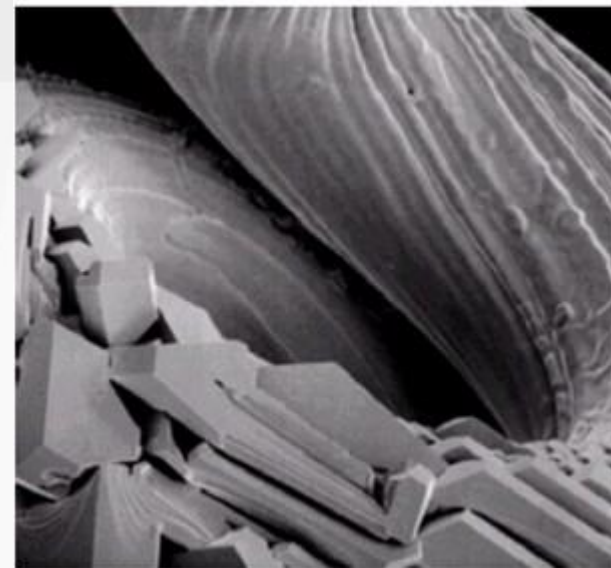


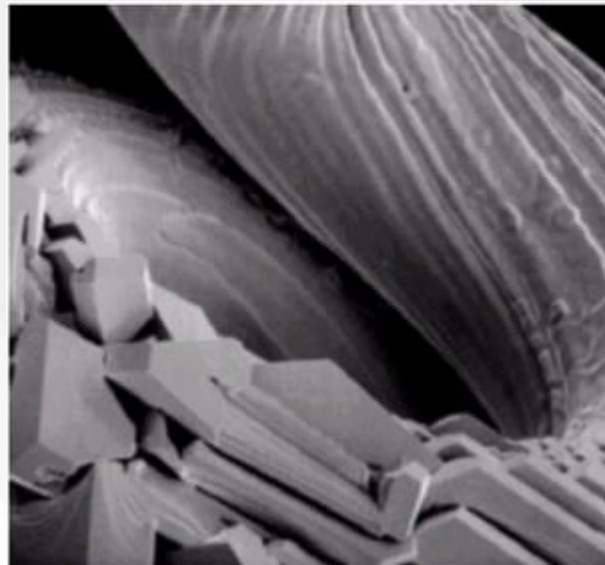
Image Enhancement

● Spatial Filtering

■ Sharpening

● The **Laplacian**

There are lots of slightly different versions of the Laplacian that can be used:



-1	-1	-1
-1	9	-1
-1	-1	-1

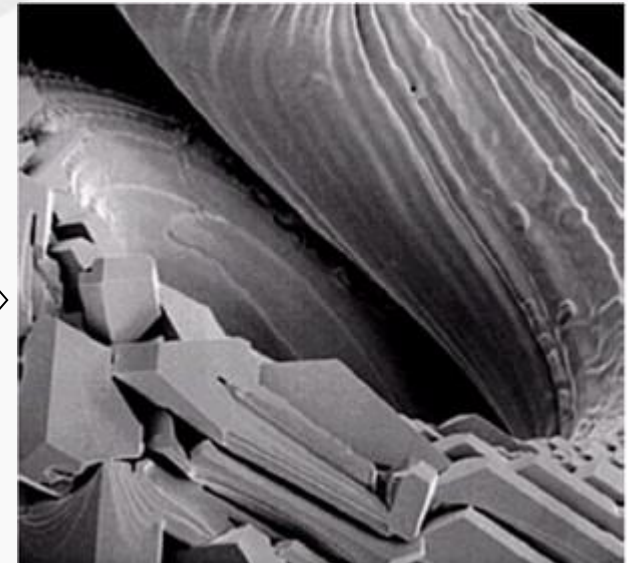


Image Enhancement

● Spatial Filtering

■ Sharpening

● The **Laplacian**



Original

$$\begin{bmatrix} 0 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 0 \end{bmatrix} - \frac{1}{9} \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$$

(Note that filter sums to 1)



Sharpening filter

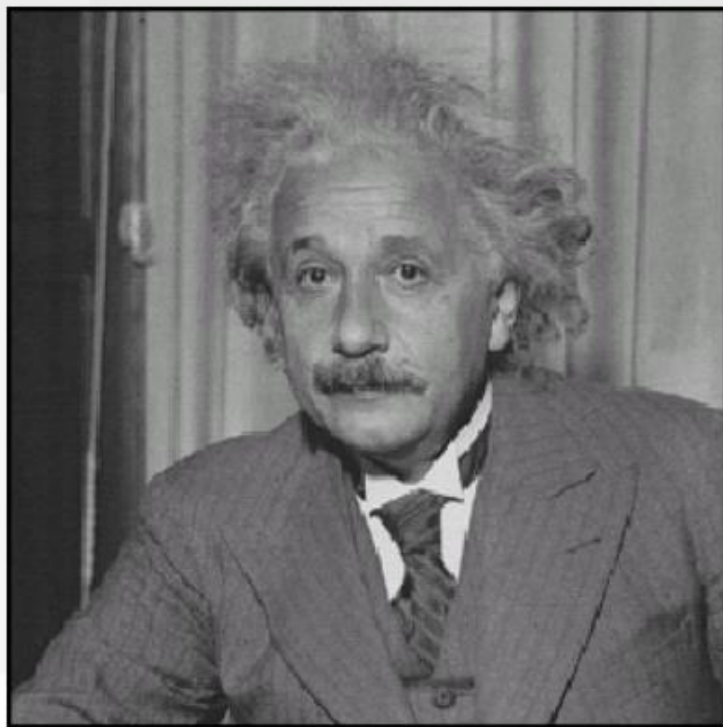
- Accentuates differences
with local average

Image Enhancement

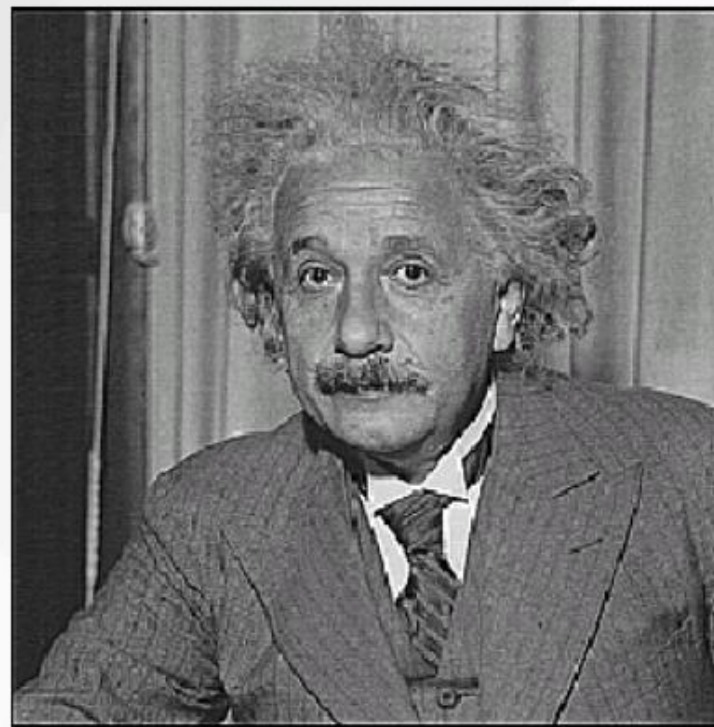
- Spatial Filtering

- Sharpening

- The Laplacian



Before



After

Image Enhancement

● Spatial Filtering

■ Sharpening

● The **Laplacian**

Unsharp Masking and High-Boost Filtering

- *Unsharp masking* is expressed as

$$f_s(x, y) = f(x, y) - \bar{f}(x, y)$$

where $\bar{f}(x, y)$ is a blurred version of $f(x, y)$

- *high-boost filtering* ---- a slight further generalization of unsharp masking

$$f_{\text{hb}}(x, y) = kf(x, y) - \bar{f}(x, y) \quad k > 1$$



Image Enhancement

- Spatial Filtering

- Sharpening

- Properties of 1st and 2nd-Order Derivatives
- Use of 2nd Derivatives for Enhancement- The Laplacian
- Use of 1st Derivatives for Enhancement - The Gradient

Image Enhancement

● Spatial Filtering

■ Sharpening

● The Gradient -Use of 1st Derivatives for Enhancement

They are implemented using the magnitude of the gradient

–Gradient definition

$$\nabla \mathbf{f} = \begin{bmatrix} G_x \\ G_y \end{bmatrix} = \begin{bmatrix} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \end{bmatrix}$$

–The magnitude of the Gradient

$$\nabla f = \text{mag}(\nabla \mathbf{f}) = \sqrt{G_x^2 + G_y^2}$$

$$= \sqrt{\left(\frac{\partial f}{\partial x}\right)^2 + \left(\frac{\partial f}{\partial y}\right)^2}$$

– For computational consideration, in practice

$$\nabla f \approx |G_x| + |G_y|$$

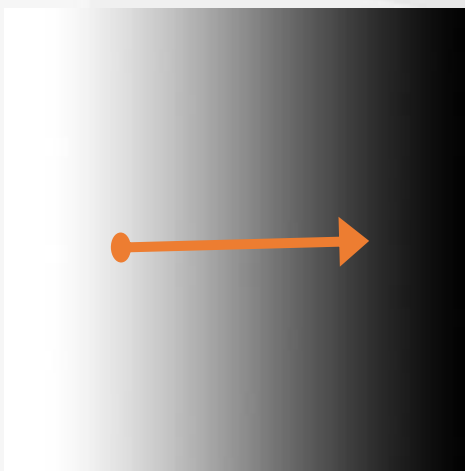
Image Enhancement

● Spatial Filtering

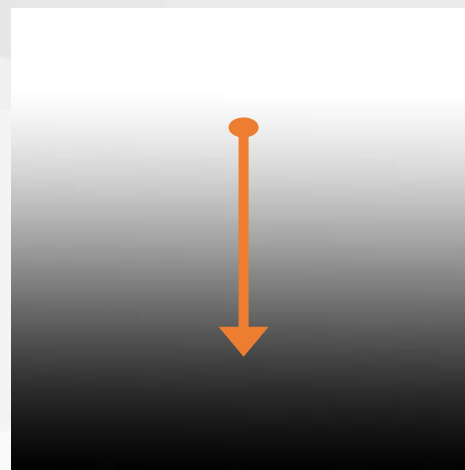
■ Sharpening

● The Gradient

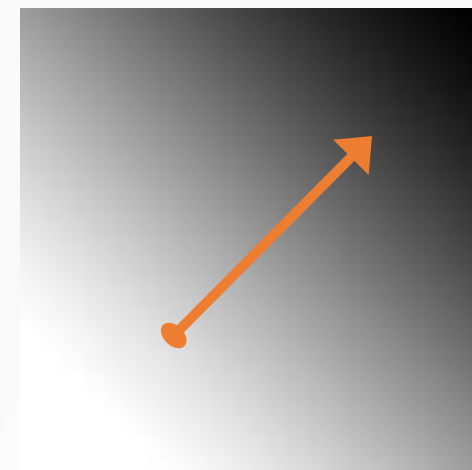
- The gradient points in the direction of most rapid increase in intensity.



$$\nabla f = \left[\frac{\partial f}{\partial x}, 0 \right]$$



$$\nabla f = \left[0, \frac{\partial f}{\partial y} \right]$$



$$\nabla f = \left[\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y} \right]$$

Image Enhancement

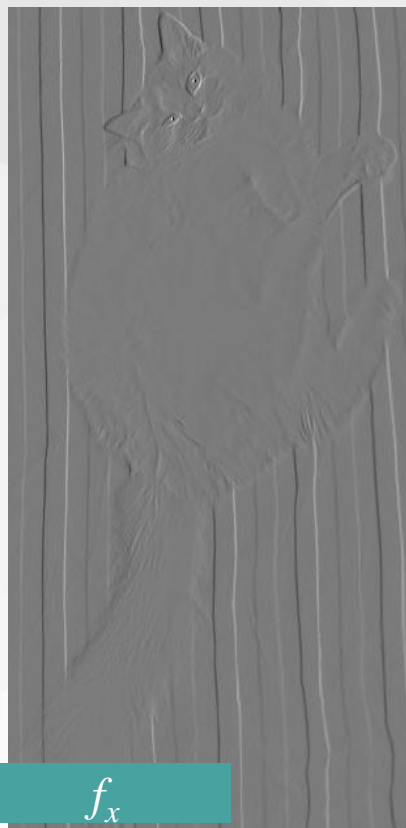
● Spatial Filtering

■ Sharpening

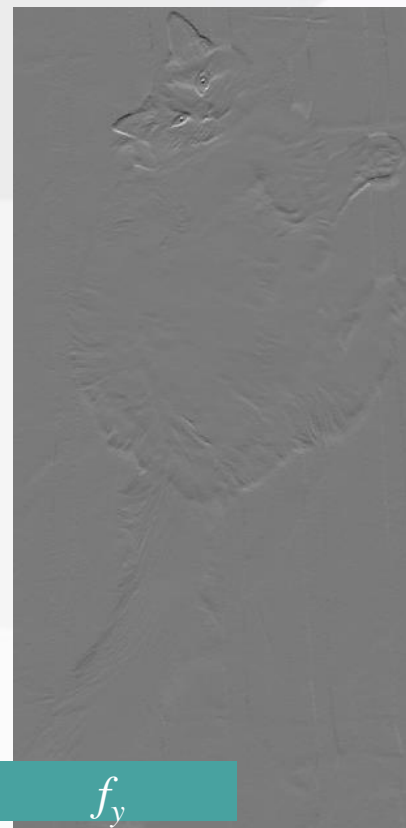
● The Gradient



Original Image



f_x



f_y

Which shows changes with respect to x?

Image Enhancement

Spatial Filtering

Sharpening

The Gradient

- Sobel operator (filter) is a popular discretization of the gradient

$$T_x = \begin{pmatrix} -1 & 0 & 1 \\ -2 & 0 & 2 \\ -1 & 0 & 1 \end{pmatrix} \quad T_y = \begin{pmatrix} -1 & -2 & -1 \\ 0 & 0 & 0 \\ 1 & 2 & 1 \end{pmatrix}$$

- $-f_x$ is calculated using T_x , and f_y using T_y
 - The magnitude of the gradient is then given by:

$$\nabla f \approx |f_x| + |f_y|$$

Image Enhancement

● Spatial Filtering

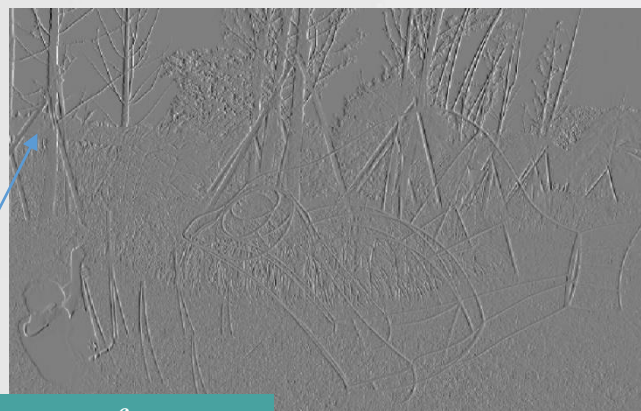
■ Sharpening

● The Gradient

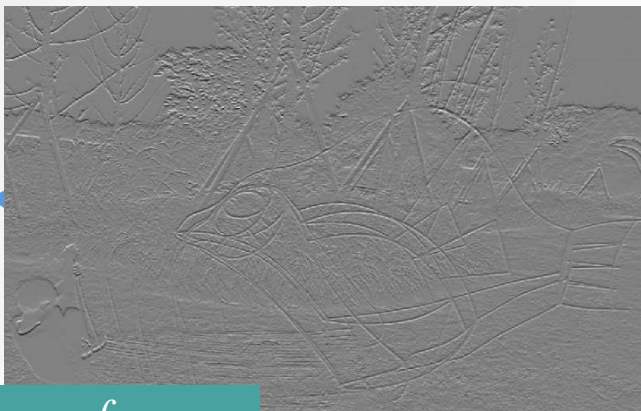


Original Image

$$T_x = \begin{pmatrix} -1 & 0 & 1 \\ -2 & 0 & 2 \\ -1 & 0 & 1 \end{pmatrix}$$

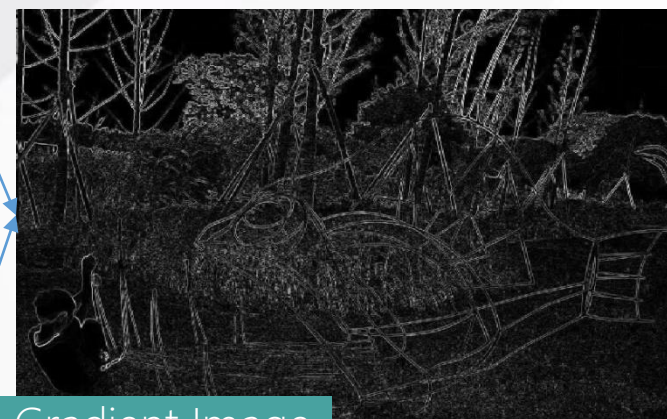


f_x



f_y

$$T_y = \begin{pmatrix} -1 & -2 & -1 \\ 0 & 0 & 0 \\ 1 & 2 & 1 \end{pmatrix}$$



Gradient Image

$$\nabla f \approx |f_x| + |f_y|$$

Image Enhancement

● Spatial Filtering

■ Sharpening

● The Gradient

$$T_x = \begin{pmatrix} -1 & 0 & 1 \\ -2 & 0 & 2 \\ -1 & 0 & 1 \end{pmatrix}$$



$$T_y = \begin{pmatrix} -1 & -2 & -1 \\ 0 & 0 & 0 \\ 1 & 2 & -1 \end{pmatrix}$$

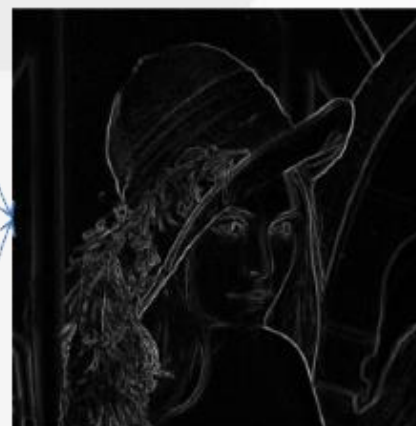
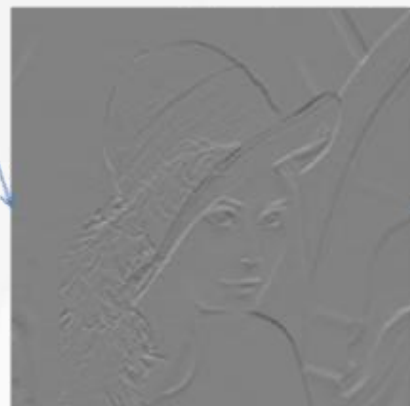
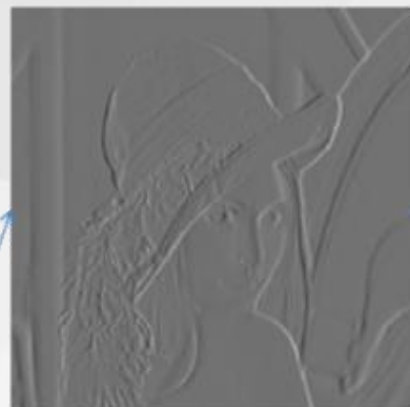


Image Enhancement

Spatial Filtering

Sharpening

The Gradient



Original Image

Sobel operator



$$\begin{bmatrix} 1 & 0 & -1 \\ 2 & 0 & -2 \\ 1 & 0 & -1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 1 \\ 0 & 0 & 0 \\ -1 & -2 & -1 \end{bmatrix}$$

Roberts Cross operator



$$\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$$

Gradient Image

Scharr operator



$$\begin{bmatrix} 3 & 0 & -3 \\ 10 & 0 & -10 \\ 3 & 0 & -3 \end{bmatrix} \begin{bmatrix} 3 & 10 & 3 \\ 0 & 0 & 0 \\ -3 & -10 & -3 \end{bmatrix}$$

Prewitt operator



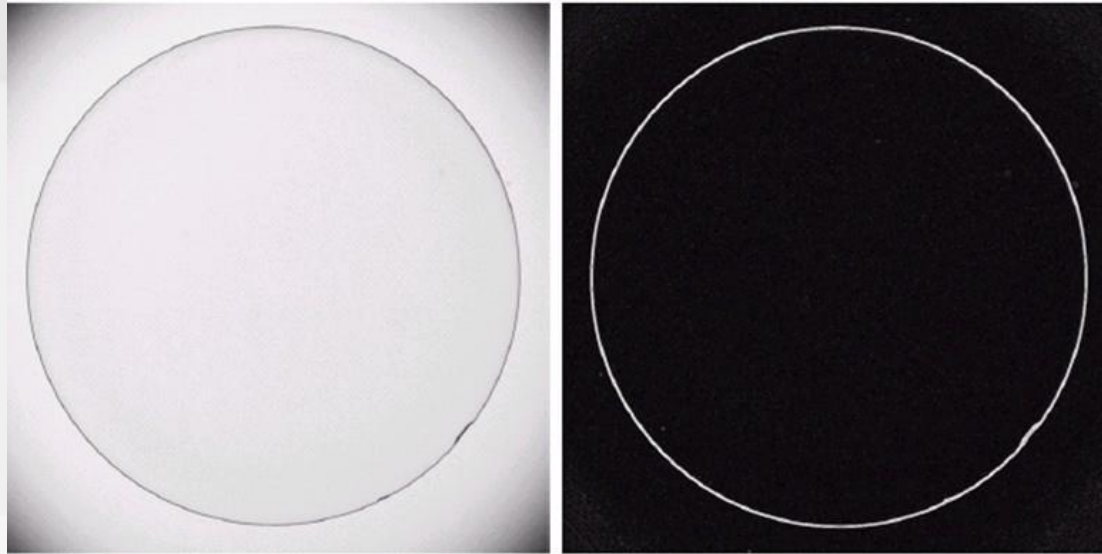
$$\begin{bmatrix} -1 & 0 & 1 \\ -1 & 0 & 1 \\ -1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 0 \\ -1 & -1 & -1 \end{bmatrix}$$

Image Enhancement

● Spatial Filtering

■ Sharpening

● The Gradient



Input image

Gradient magnitude

(at four
and five
o'clock
in the
image)

- Sobel gradient aids to eliminate constant or slowly varying shades of gray and assist automatic inspection.
- It also enhances small discontinuities in a flat gray field.

● Spatial Filtering

- Fundamentals (Kernel, convolution, filtering)
- Smoothing (Linear / non-linear filters)
- Sharpening (The Laplacian-2ndorder derivatives, the gradient -first order derivatives)
- Combing Spatial Enhancement Methods

Image Enhancement

● Spatial Filtering

■ Combining Spatial Enhancement

- Successful image enhancement is typically not achieved using a single operation
- Rather we combine a range of techniques in order to achieve a final result
- This example will focus on enhancing the bone scan to the right
- The narrow dynamic range of the low gray levels and high noise content make this image difficult to enhance.

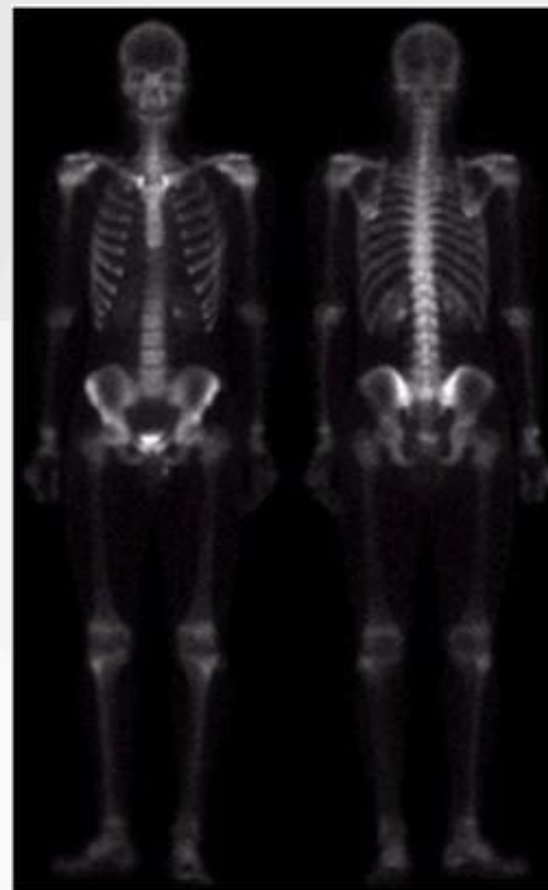




Image Enhancement

● Spatial Filtering

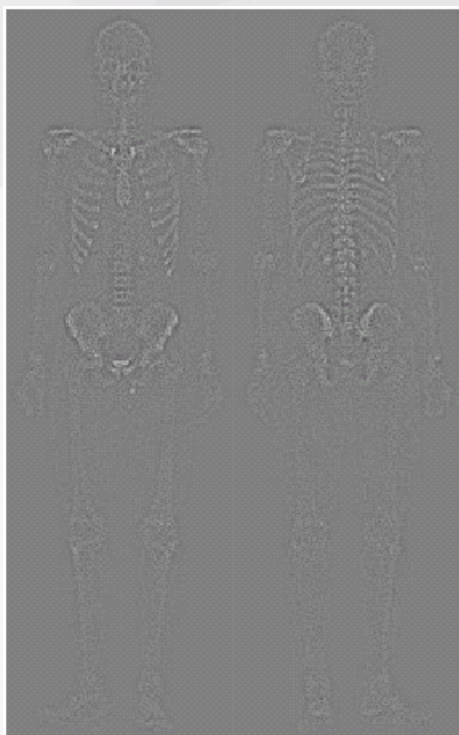
■ Combining Spatial Enhancement

- Utilize the *Laplacian* to highlight fine detail
- Utilize the *gradient* to enhance prominent edges
- Combine *Laplacian* and smoothed *gradient* to get the detail-enhanced and noise-compressed image
- Increase the contrast of low gray levels by using a gray-level transformation.

Image Enhancement

● Spatial Filtering

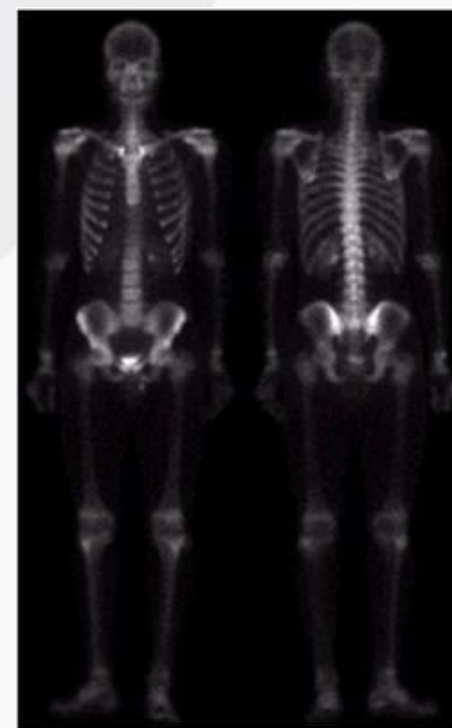
■ Combining Spatial Enhancement



$$f(x, y) + \nabla^2 f(x, y)$$



A rather noisy sharpened image is expected.



Original image

-1	-1	-1
-1	8	-1
-1	-1	-1

Laplace operator

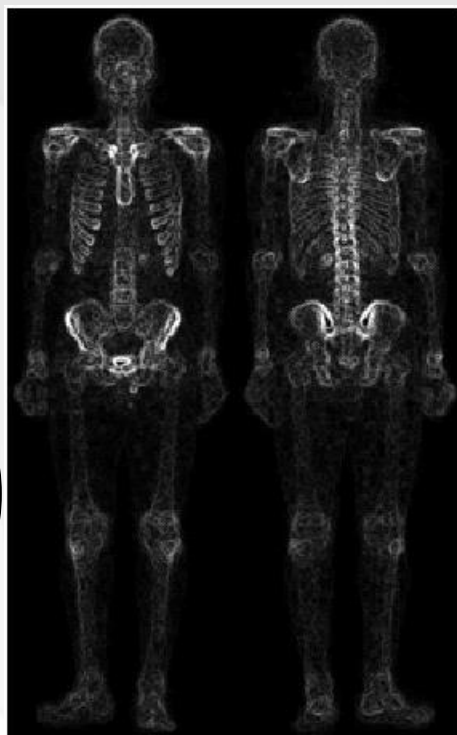
Image Enhancement

● Spatial Filtering

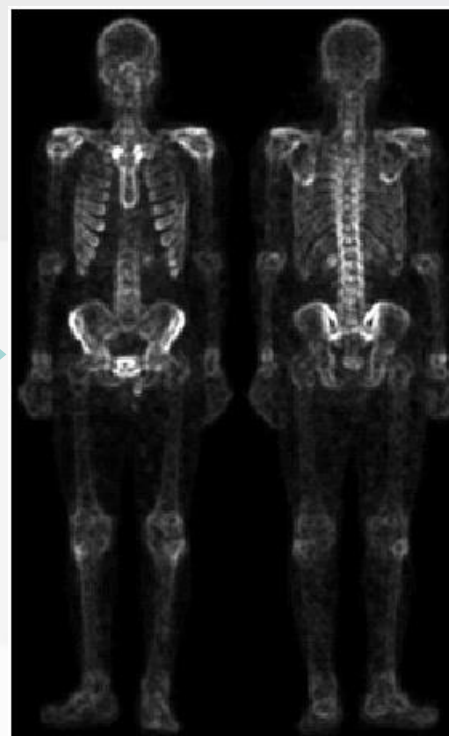
■ Combining Spatial Enhancement

$$T_x = \begin{pmatrix} -1 & 0 & 1 \\ -2 & 0 & 2 \\ -1 & 0 & 1 \end{pmatrix}$$

$$T_y = \begin{pmatrix} -1 & -2 & -1 \\ 0 & 0 & 0 \\ 1 & 2 & 1 \end{pmatrix}$$



5 x 5 box smooth

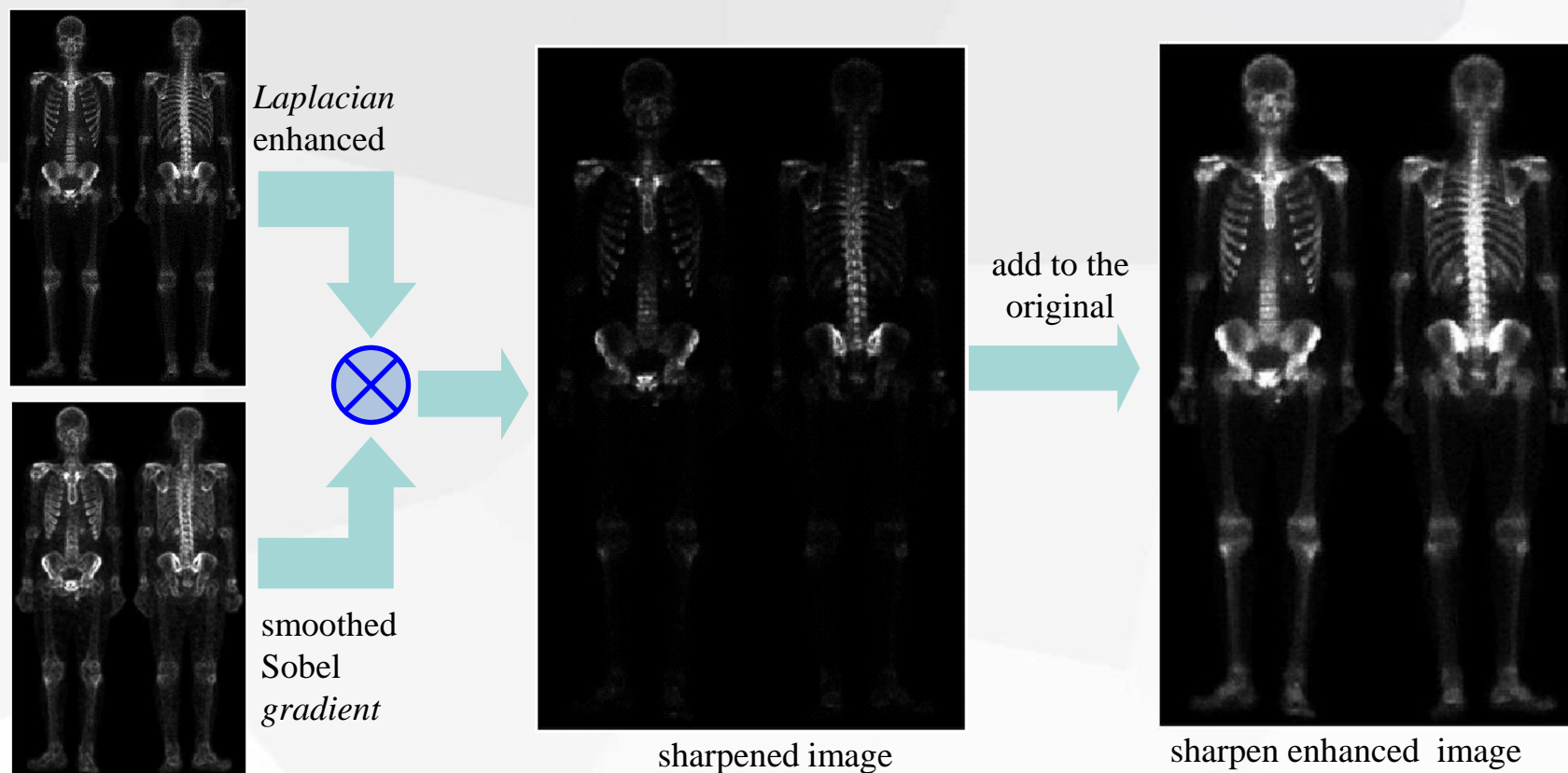


mask image

Image Enhancement

● Spatial Filtering

■ Combining Spatial Enhancement



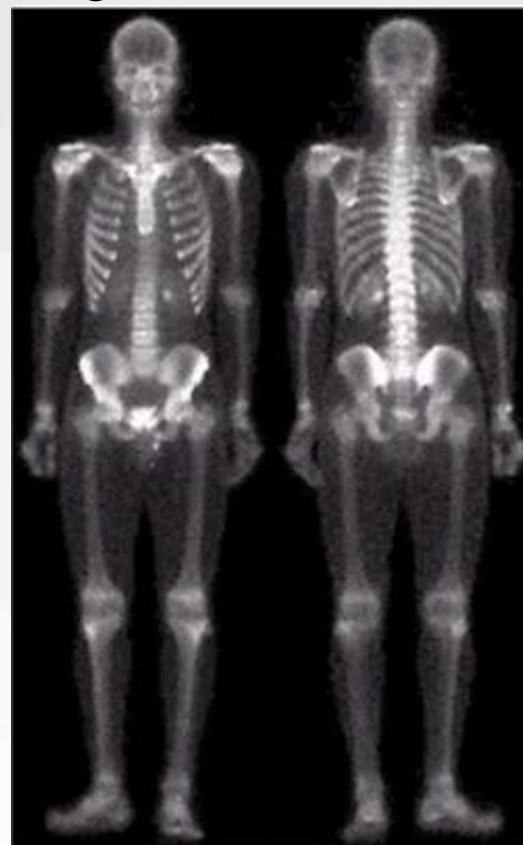
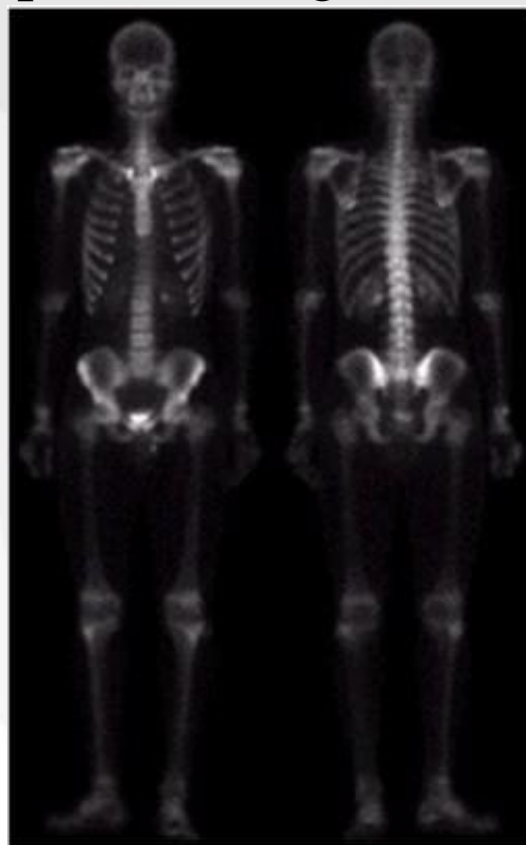
strong edges and the relative lack of visible noise

Image Enhancement

● Spatial Filtering

■ Combing Spatial Enhancement

- Compare the original and final images



$\gamma=0.5$ $c=1$

Image Enhancement

— **Thanks** —

