

knn

why kNN is an important algorithm

instance-based learning

shares elements of human reasoning

how knn works

- lazy learning:
 - no explicit model, pushes work to prediction time

```
Let  $T = \{(x_j, y_j)\}$  where  $j \in \{1, \dots, n\}$   
Classify Example  $e$   
  prior queue  $pq$  of size  $k$   
  forall  $(x_j, y_j) \in T$   
    if  $(\text{dist}(e, x_j) < pq.\text{max})$  then  $pq.\text{enqueue}(x_j, y_j)$   
  prediction = combine( $y_j \in pq$ )  
  return prediction
```

- distance
 1. similarity vs. distance
 2. distance measures
 - hamming distance: # features examples differ on
 - manhattan
 - euclidean
 - value difference metric:

- **Value difference metric:** Attribute values are close if they make similar predictions

$$\text{vdm}(x_{i,k}, x_{j,k}) = \sum_{c=1}^{|Y|} |P(y_c|x_{i,k}) - P(y_c|x_{j,k})|$$

here $x_{i,k}$ means the value i of attribute k

- jaccard: set comparisons

- **Jaccard Similarity:** $\text{sim}(S_i, S_j) = \frac{S_i \cap S_j}{S_i \cup S_j}$

- **Jaccard Distance:** $1 - \text{sim}(S_i, S_j)$

- edit distance (for strings)
- cosine similarity (for vectors)

$$\text{sim}(x_i, x_j) = \frac{\sum_{k=1}^d x_{i,k} x_{j,k}}{\sqrt{\sum_{k=1}^d x_{i,k}^2} \sqrt{\sum_{k=1}^d x_{j,k}^2}}$$

- how to combine
 - for predicting classes

distance weighted kNN

$$f(x_q) = \underset{y}{\operatorname{argmax}} \sum_{i=1}^k w_i \mathbb{I}[y_j = y] \quad \text{where} \quad w_i = \frac{1}{\text{dist}(x_q, x_i)^2}$$

Weight of each neighbor
Indicator: 1 if $y_j = y$ else it is 0

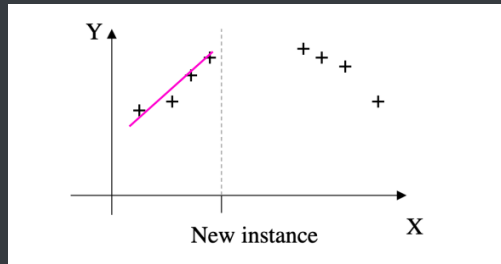
"argmax" means to find a y value which would be assigned to the sample, that maximizes this function;

- for predicting real values

depends.

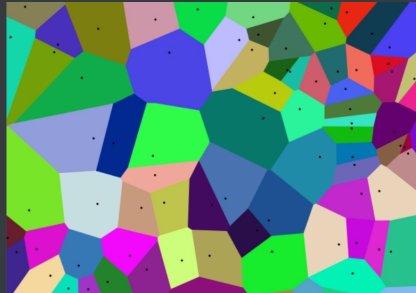
1. obvious choice would be average
2. could also build local model (learn model on k nearest neighbors),

for example, a new linear model would work in case of:

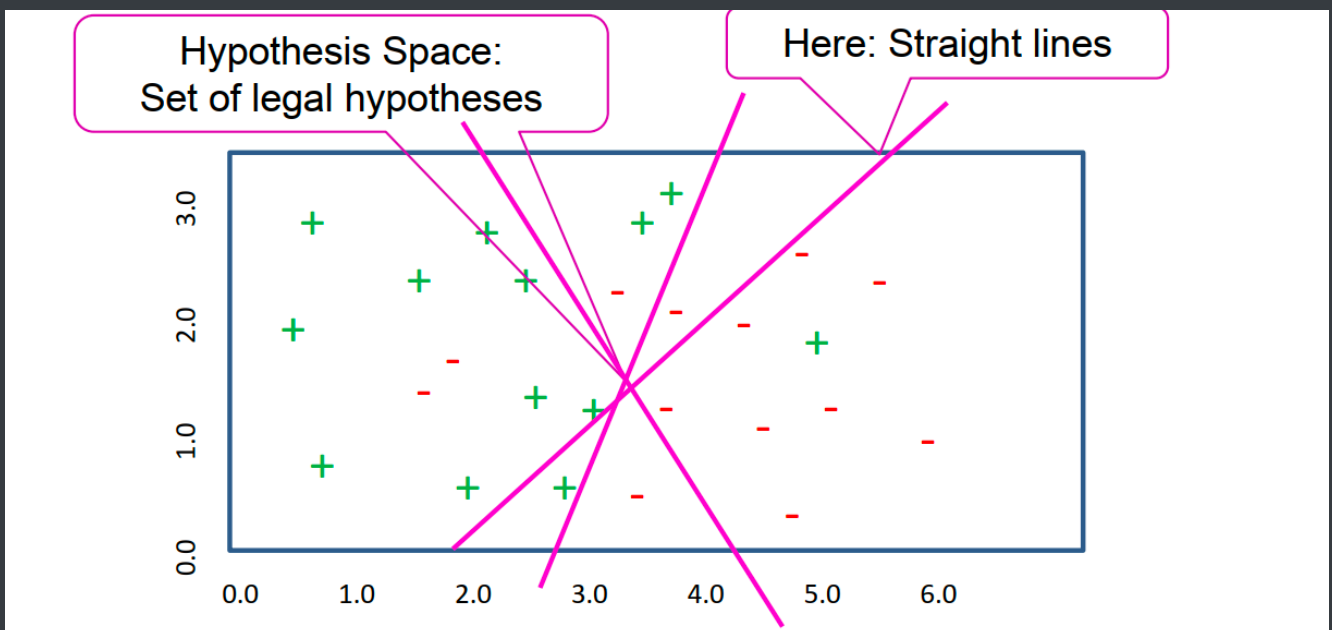


expressiveness

- voronoi diagram: understanding 1nn

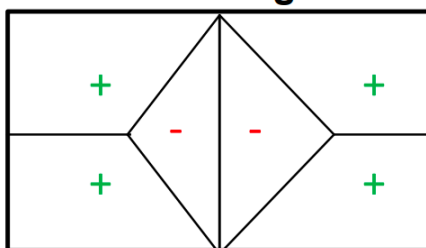


- hypothesis space: set of legal hypotheses

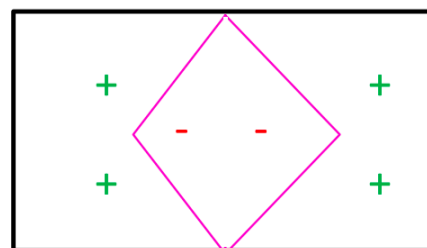


decision surface: separates regions that make different predictions

Voronoi Diagram



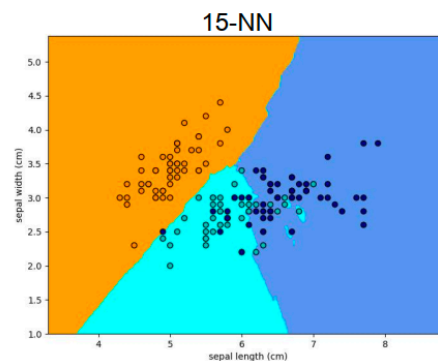
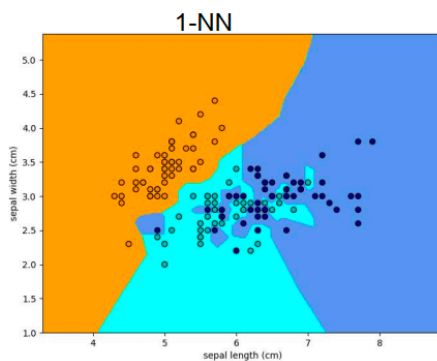
Decision surface



- effect of k

- **Small k:** Each example can have a large effect on prediction

- **Large k:** Averaging effect so each example has a more limited effect

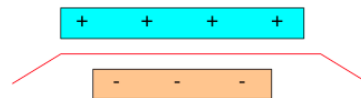


■ prototypes

motivation is **jagged decision surfaces**, which might lead to overfitting

solution is prototypes: representative of a group of instances

- Idea: Prototypes = representative of a group of instances
 - ▣ Single instance
 - ▣ Cluster
 - ▣ ...
- Need: Distance between example and prototype



potential pitfalls & how to address

1. different scales of feature values

e.g. one of the feature is price (like 10000euro), the other is weight (like 10kg)

solution: normalization

solution 1: min-max normalization (linear transformation)

solution 2: standardize (normal distribution)

2. irrelevant features

for example, whether an animal wears clothes

solution:

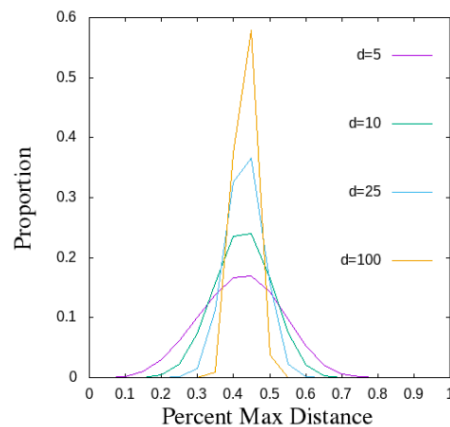
use domain language / weight the features in some way

3. in high-dimension

- in very high dimensions, basically all examples are equi-distant
- nearest neighbors are easily misled with high-dimensional spaces

Illustration Average Distances

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- Random instances
 - Dimension d
 - Each feature $U \sim [0, 1]$
- Max distance \sqrt{d}
- As d increases, distances concentrate!

Worrying? Yes and no.

yes:

"nearest neighbors" doesn't really make any difference

no:

this is happening under **uniform distribution**, but in reality there's always some correlation among features

4. prediction time

lots of data lead to slow execution

solutions:

solution 1: efficient retrieval structures (e.g. KD tree)

solution 2: locality sensitive hashing (but does not guarantee correct set)

solution 3: product quantization (compressed data & approximated distance)