RULE LEARNING

■ concept: rules & rule sets 分类问题

ordered rule set: a decision list

(rule i only applies if rules 1 to i-1 did not apply, "if - then - else if")

decision tree -> a set of rules

- sequential covering
 - "separate-and-conquer":

 每次separate一部分数据满足当前规则,再conquer剩下的数据
 - accuracy & coverage
 - general 算法:

```
Training set D is partitioned into Pos
                                                 (instances of class we want to predict)
function LearnRuleSet(Pos, Neg):
                                                 and Neg (all other instances)
    RuleSet = Ø
    while Pos not empty:
         R = learnOneRule(Pos, Neg)
         if R does not meet acceptance criteria: break
         add R to RuleSet
         remove instances covered by R from Pos
    return RuleSet
                                                    Assumes we go for 100% accuracy.
                                                    Other stopping criteria possible.
function LearnOneRule(Pos,Neg):
    Rule = if true then positive
    while Rule covers elements of Neg:
         C* = argmax<sub>C</sub>ecandidateConditions() heuristic(refine(Rule,C), Pos, Neg)
         Rule = refine(Rule,C*)
function refine(Rule, C):
    let Rule = if conditions then positive
    return if conditions and C then positive
                                                                      KIII FIIVEN
```

learning one rule: typically, greedy search

top-down:

start with maximally general rule, add conditions

bottom-up:

start with maximally specific rule, remove conditions

heuristic for selecting rules?

goal: high accuracy & reasonably high coverage

accuracy recall the cocktail example

accuracy 值相同的情况下,分母更大对应的rule更好(coverage)

m-estimate

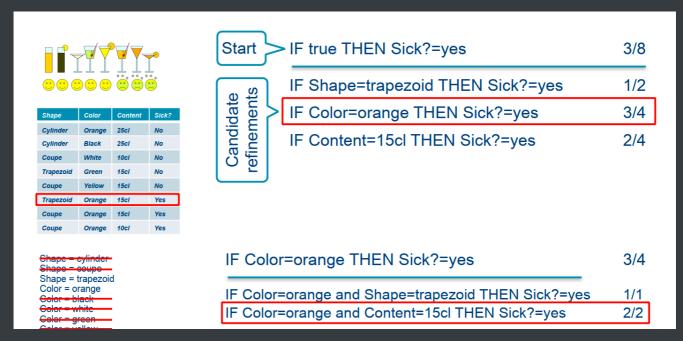
$$m\text{-estimate}(m,q) = \frac{p + mq}{p + n + m}$$

q is a prior estimate of accuracy, m is its weight

- when *m* is large, estimate is coser to *q* (more conservative)
- converges to accuracy as *p*+*n* grows
- 优化 1: example-driven

<u>Idea</u>: pick a not-yet-covered example & use as hypothesis space

e.g.



被圈出的example只有三个条件,以此作为搜索空间进行第一次搜索;

■ 优化 2: RIPPER

- Separate-and-conquer approach, with key modifications:
 - Prune each rule after learning it, using a separate pruning set (= "reduced error pruning", see also tree learning)
 - Learn rules for one class at a time, starting with the smallest classes (hence, ordered rule set)
 - Optimize the rule set afterwards, by *re-learning each rule* (in the order first learned) *within the context of the other rules*, and replacing the original rule by the new one when better
 - + carefully chosen heuristics and stopping criteria

association rules

vs. classification rules:

association rules are descriptive rules indicating patterns in data;

