



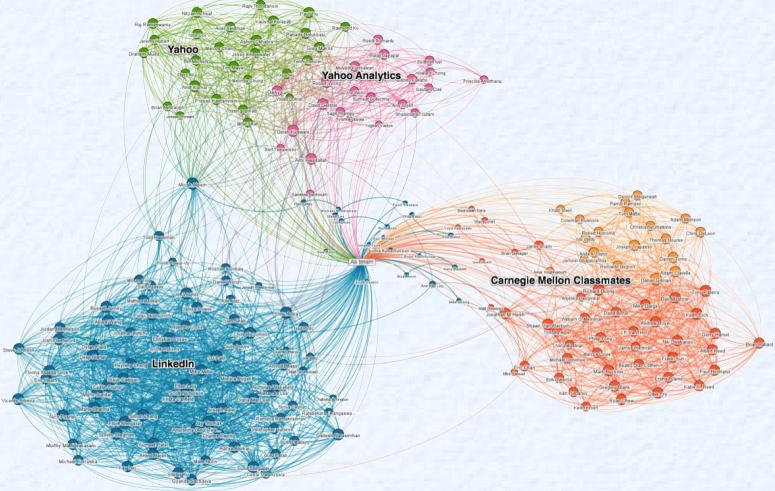
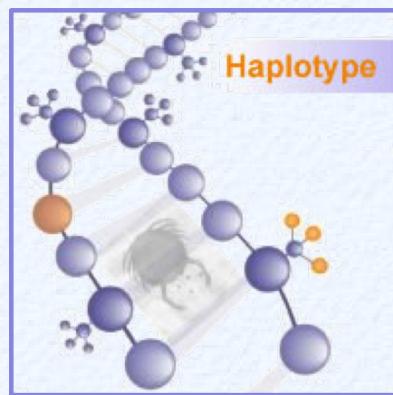
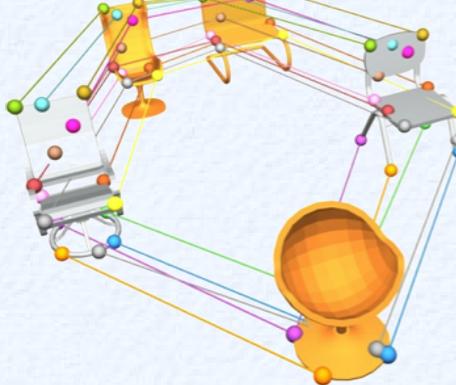
Information Recovery from Pairwise Measurements

A Shannon-Theoretic Approach

Yuxin Chen[†], Changho Suh^{*}, Andrea Goldsmith[†]
Stanford University[†] KAIST^{}*

Recovering data from correlation measurements

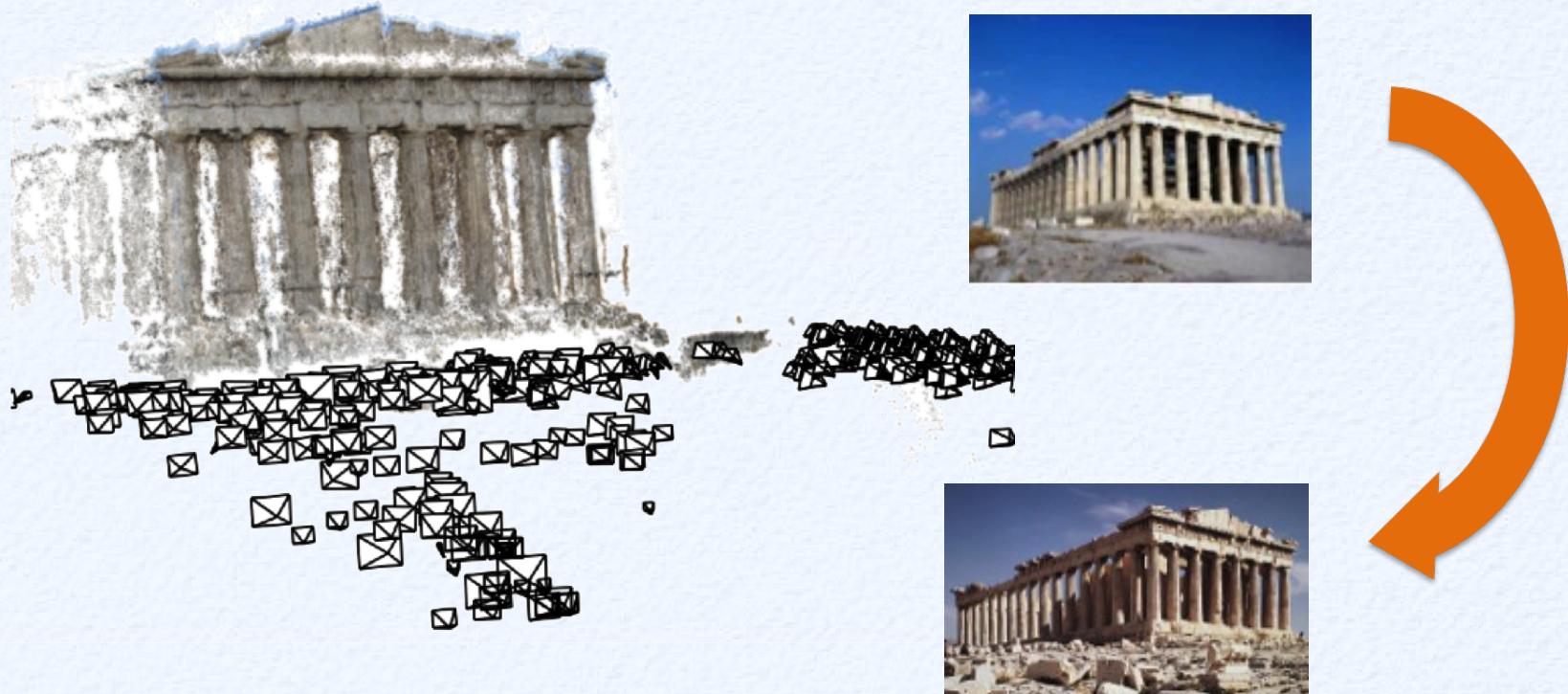
- A large collection of data instances



- In many applications, it is
 - difficult/infeasible to measure each variable directly
 - feasible to measure pairwise correlation

Motivating application: multi-image alignment

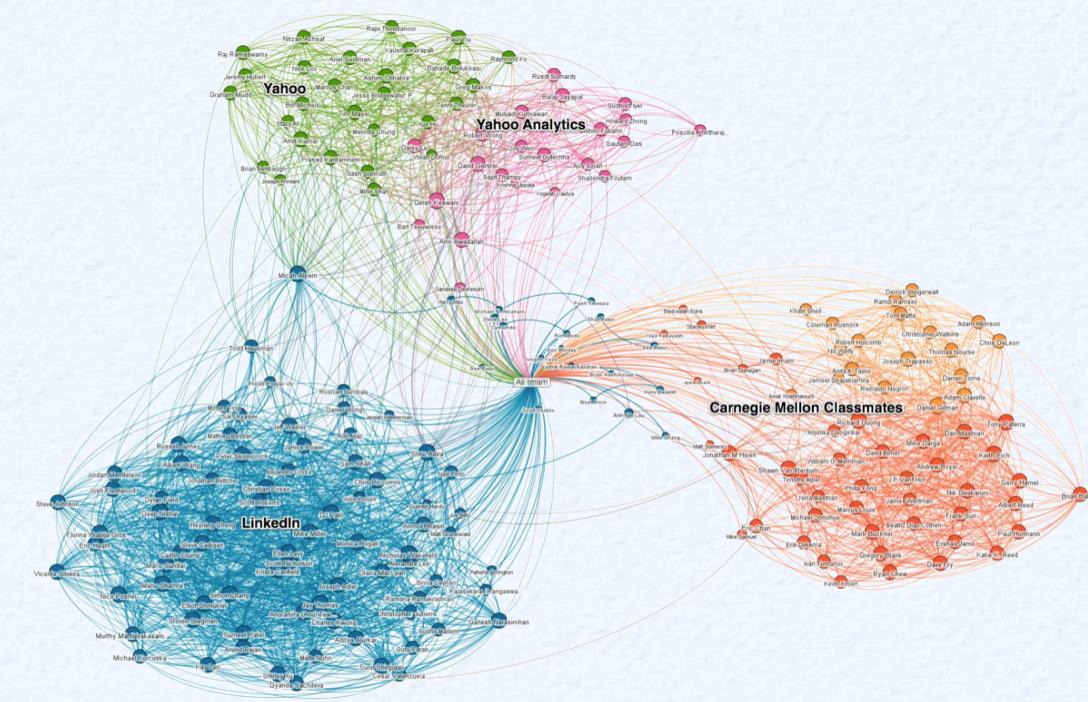
- **Structure from motion:** estimate 3D structures from 2D image sequences



- **Key step: joint alignment**
 - input: (noisy) estimates of relative camera poses
 - goal: jointly recover all camera poses

Motivating application: graph clustering

- Real-world networks exhibit community structures



- input: pairwise similarities between members
- goal: uncover hidden clusters

This talk: recovery from pairwise difference measurements

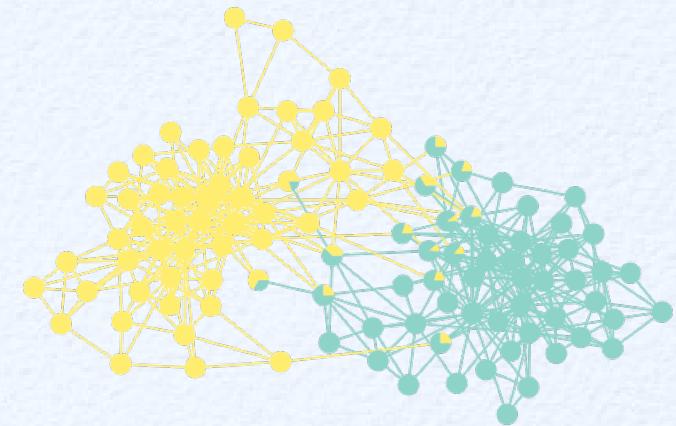
- Goal: recover a collection of variables $\{x_i\}$
- Can only measure several **pairwise difference** $x_i - x_j$ (broadly defined)

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 - x_i : (angle θ_i , position z_i)
 - relative rotation/translation ($\theta_i - \theta_j, z_i - z_j$)

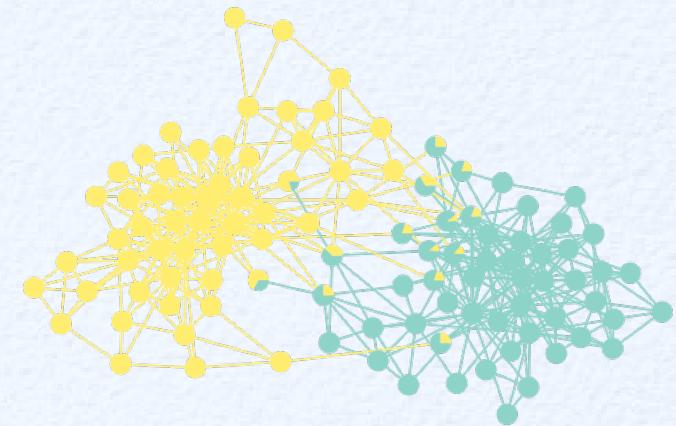
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 - x_i : membership (which partition it belongs to)
 - cluster agreement: $x_i - x_j = \begin{cases} 1, & \text{if } i, j \in \text{ same partition} \\ 0, & \text{else.} \end{cases}$



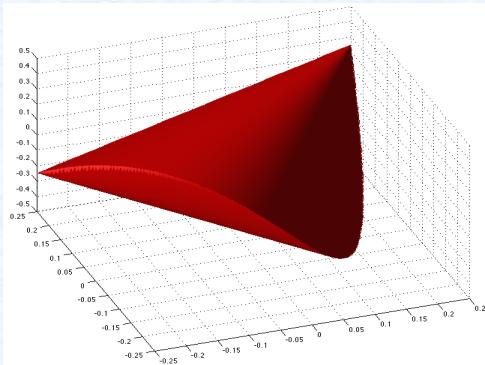
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 - **pairwise maps, parity reads, ...**

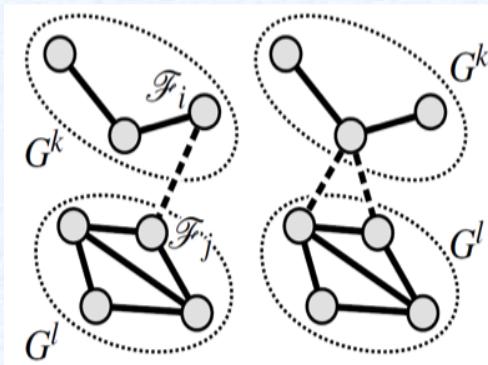


A fundamental-limit perspective?

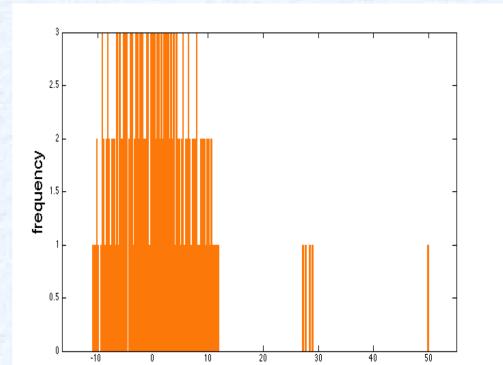
- A flurry of activity in recovery algorithm design



convex program



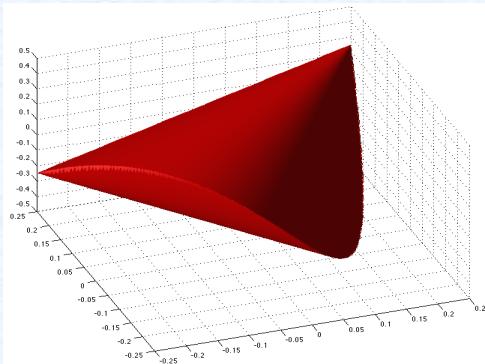
combinatorial



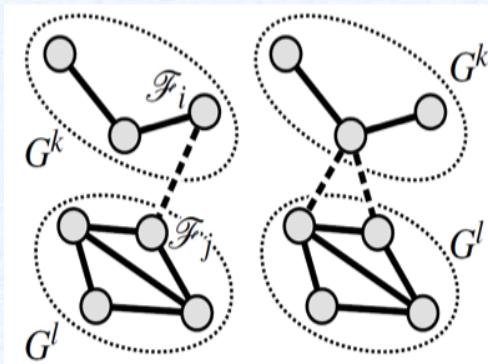
spectral method

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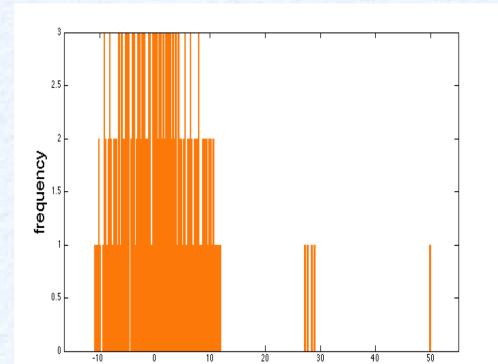
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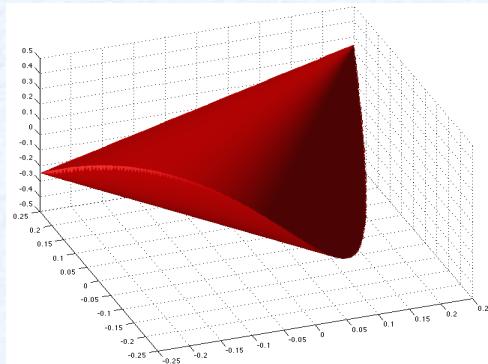
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- **What are the fundamental recovery limits?**

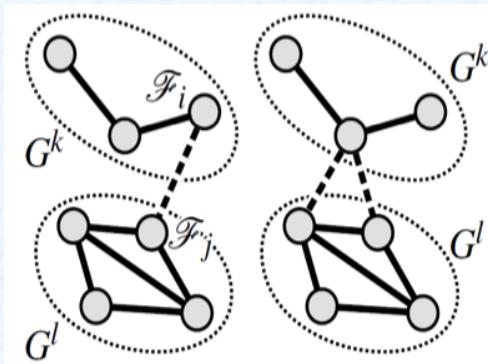
- min. sample complexity? how noisy the measurements can be?

A fundamental-limit perspective?

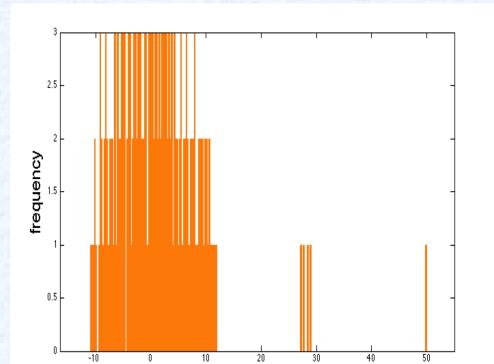
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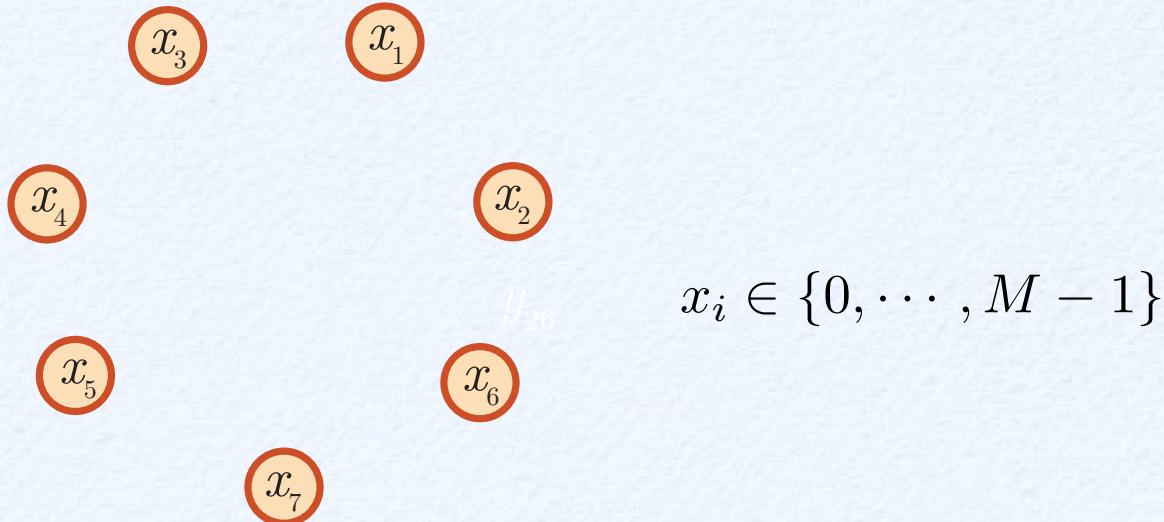
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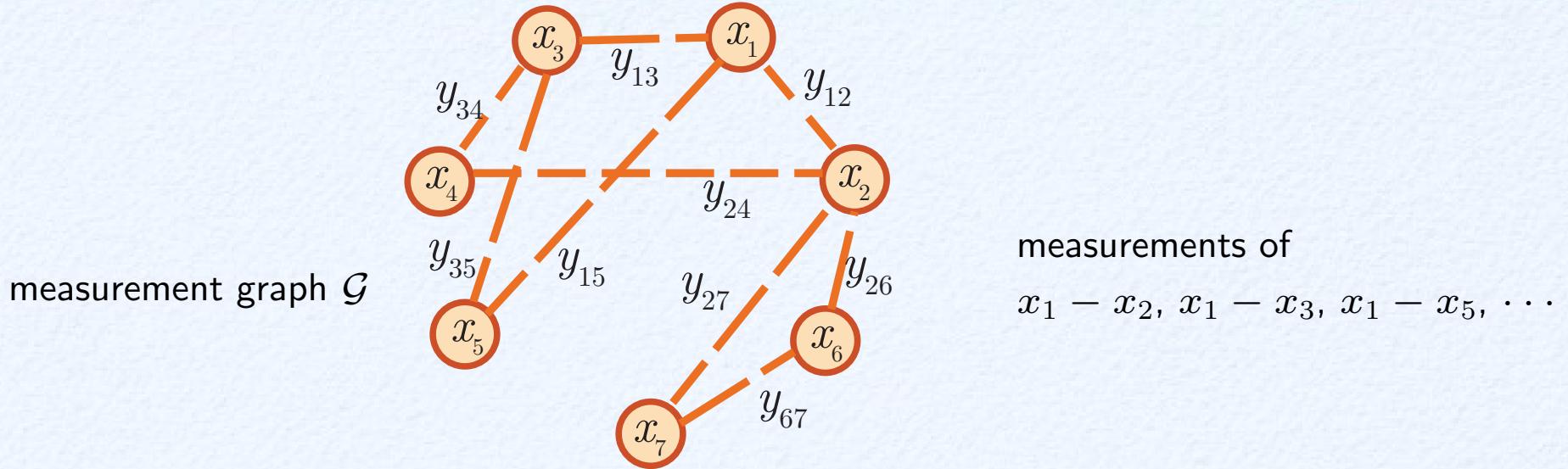
- **What are the fundamental recovery limits?**
 - min. sample complexity? how noisy the measurements can be?
- So far mostly studied in a model-specific manner
 - **Seek a more unified framework**

Problem setup: a Shannon-theoretic framework



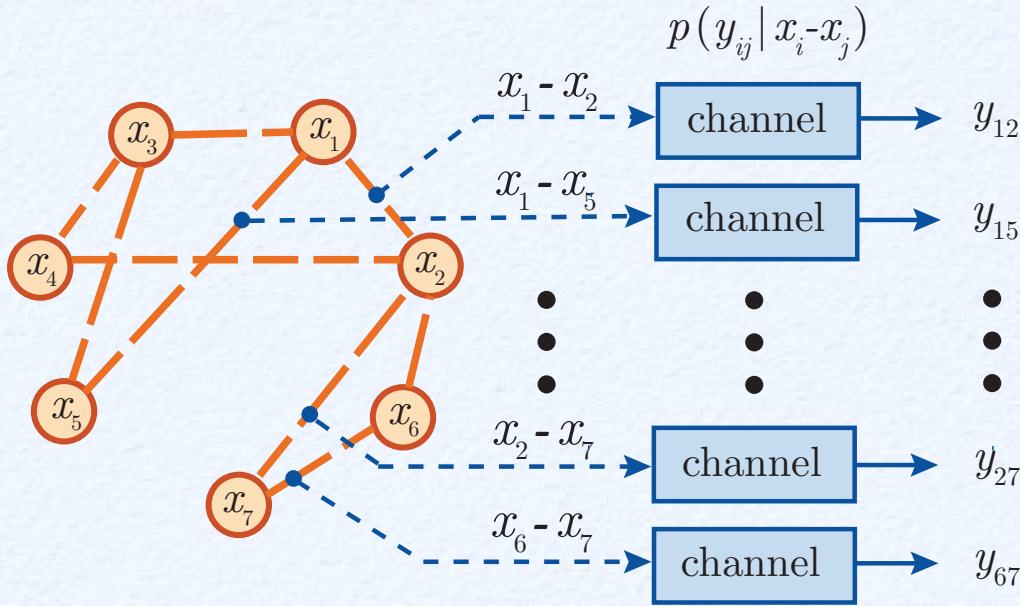
- **Information network**
 - n vertices
 - discrete inputs w/ **alphabet size:** M
 - could scale with n

Problem setup: a Shannon-theoretic framework

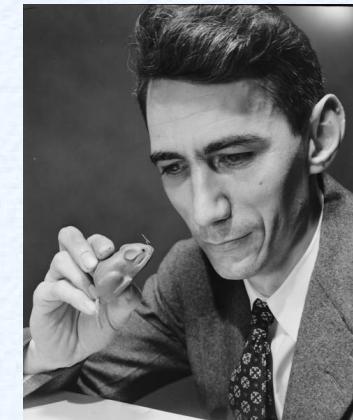


- **Pairwise difference measurements**
 - truth: $x_i - x_j$
 - measurements: y_{ij} (**arbitrary** alphabet)
 - * can be corrupted by noise, distortion, ...
- **Graphical representation**
 - observe $y_{ij} \iff (i, j) \in \mathcal{G}$

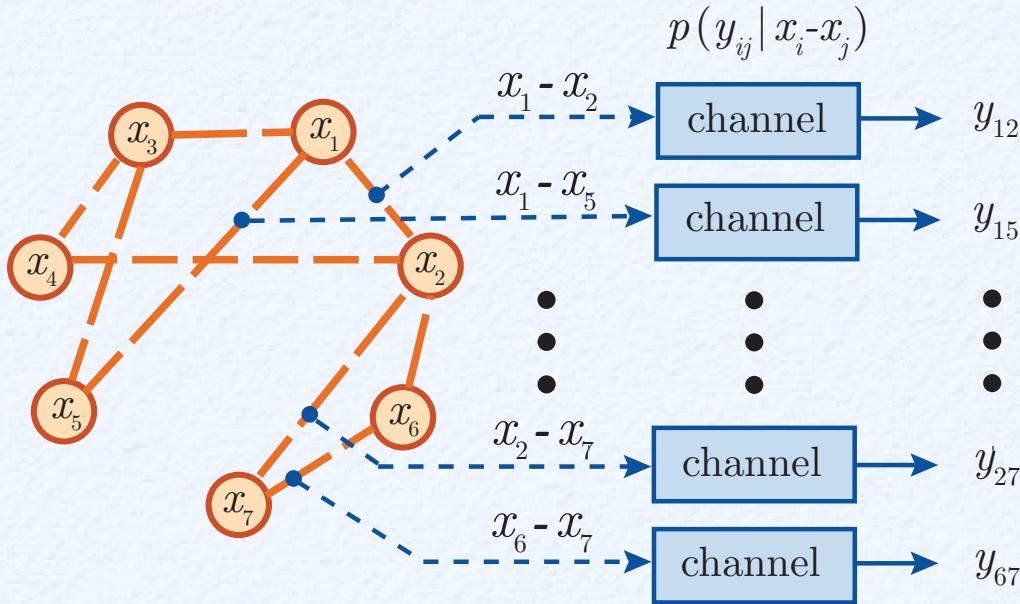
Problem setup: a Shannon-theoretic framework



- **Channel-decoding perspective**
 - each measurement is modeled by **an i.i.d. channel**
 - transition prob. $P(y_{ij} | x_i - x_j)$



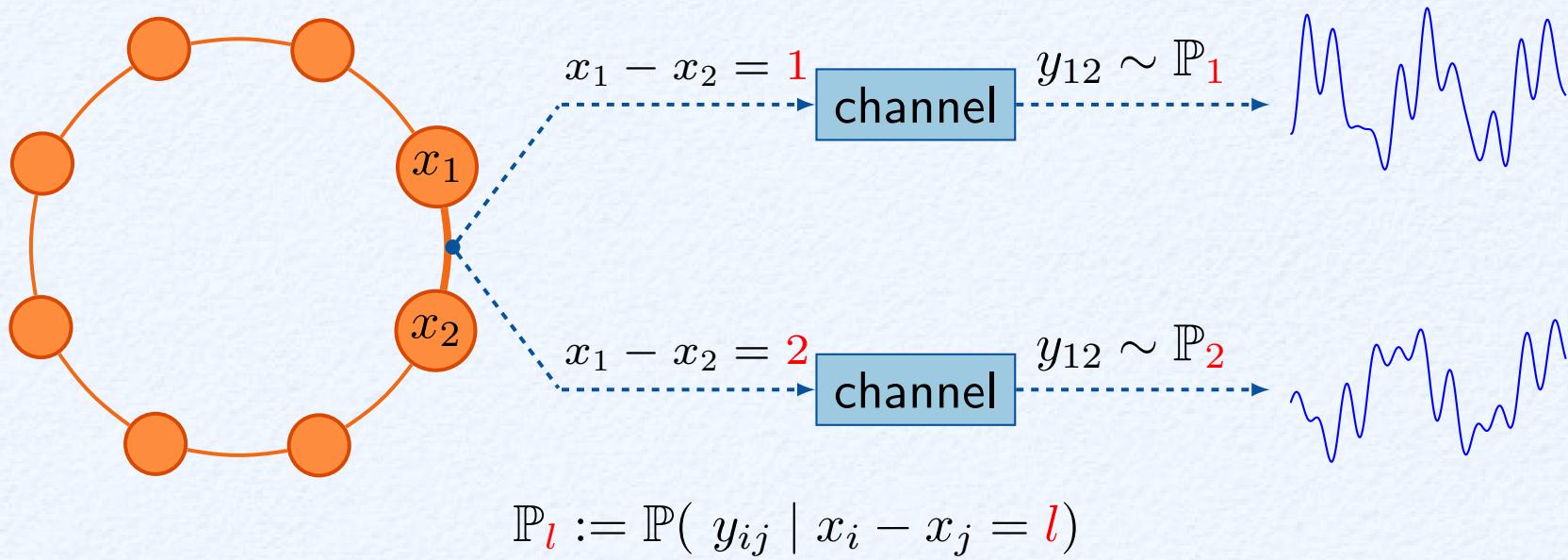
Problem setup: a Shannon-theoretic framework



- **Goal:** recover $\{x_i\}$ exactly (up to global offset)
- **Unified framework for decoding model**
 - *capture similarities among various applications*



What factors dictate hardness of recovery?

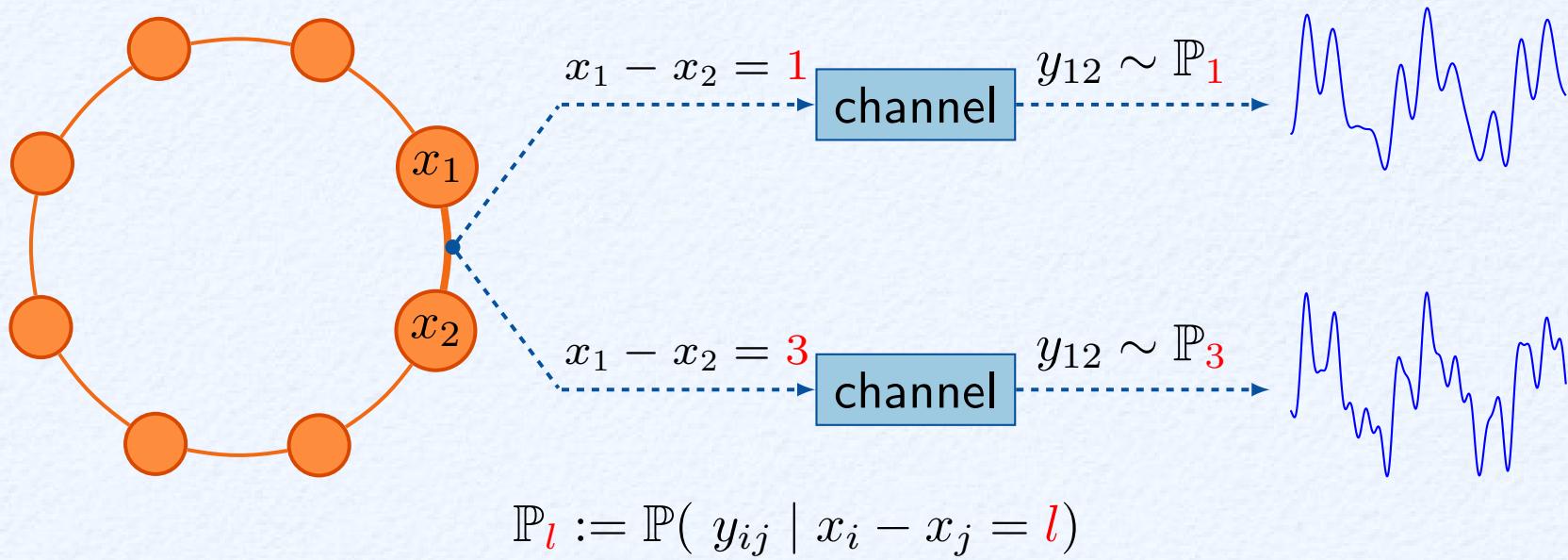


- **Channel distance/resolution**

- Captured by

$$\text{KL}(\mathbb{P}_l \parallel \mathbb{P}_k) \quad \text{or} \quad \text{Hellinger}(\mathbb{P}_l \parallel \mathbb{P}_k) \quad \text{or} \quad \dots$$

What factors dictate hardness of recovery?



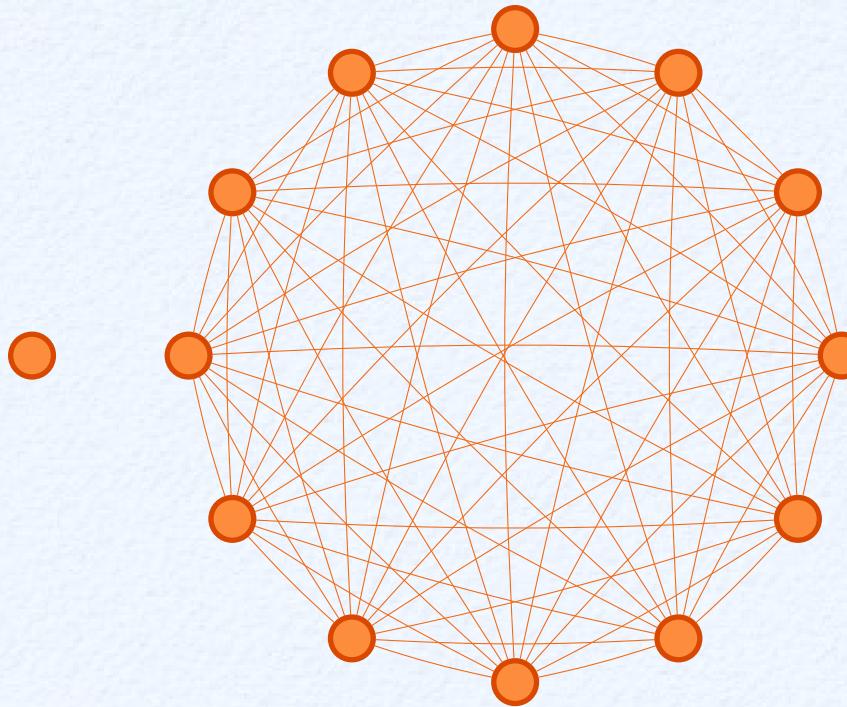
- **Minimum channel distance/resolution**

$$\min_{l \neq k} \text{KL}(\mathbb{P}_l \parallel \mathbb{P}_k) := \text{KL}^{\min} \quad \text{or}$$

$$\min_{l \neq k} \text{Hellinger}(\mathbb{P}_l \parallel \mathbb{P}_k) := \text{Hellinger}^{\min} \quad \text{or} \quad \dots$$

- Uncoded input

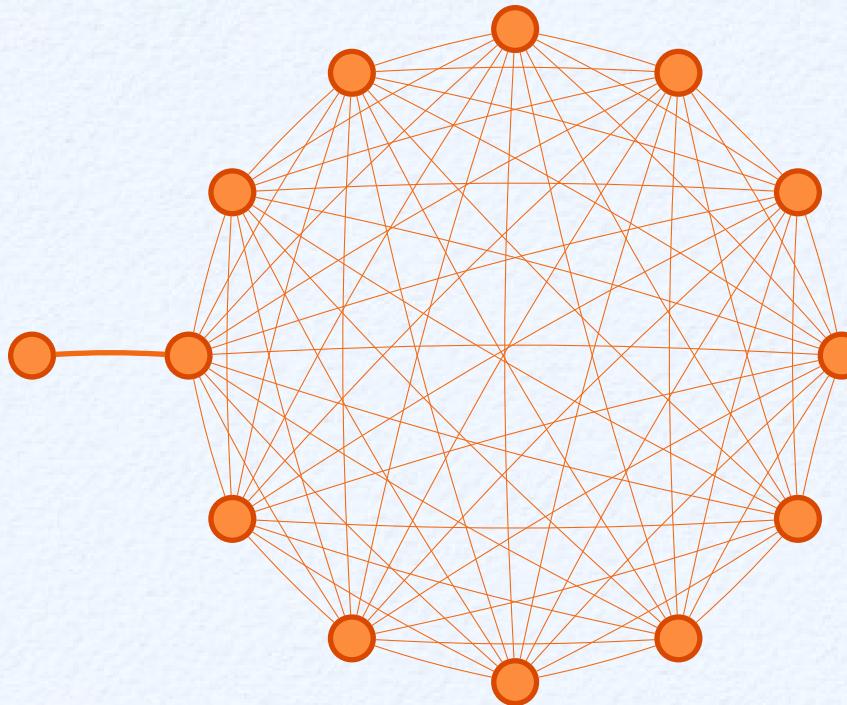
What factors dictate hardness of recovery?



measurement graph \mathcal{G}

- **Graph connectivity**
 - Impossible to recover isolated vertices

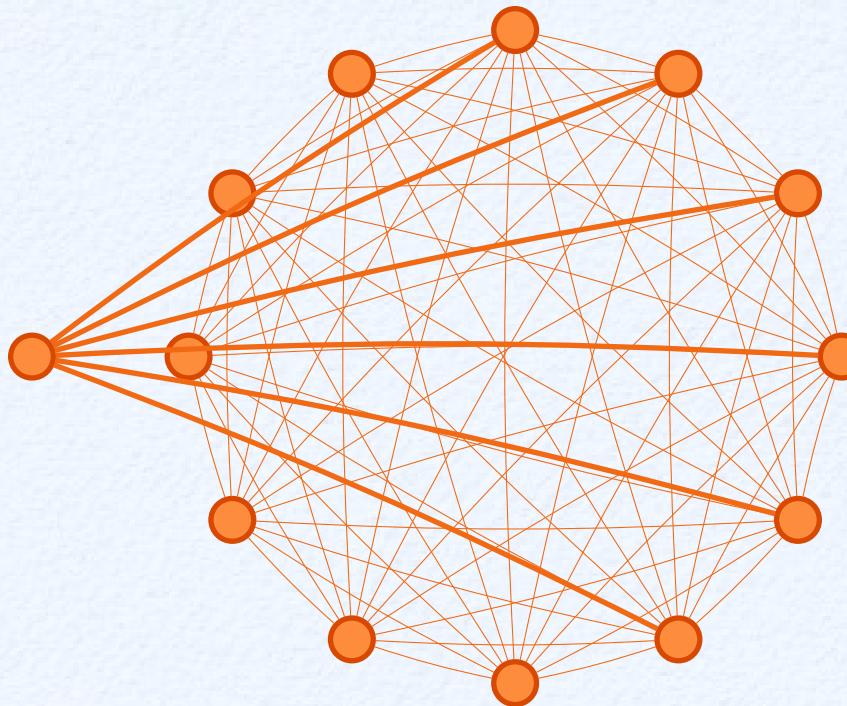
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measurement graph \mathcal{G}

- **Graph connectivity**
 - Over-sparse connectivity is fragile

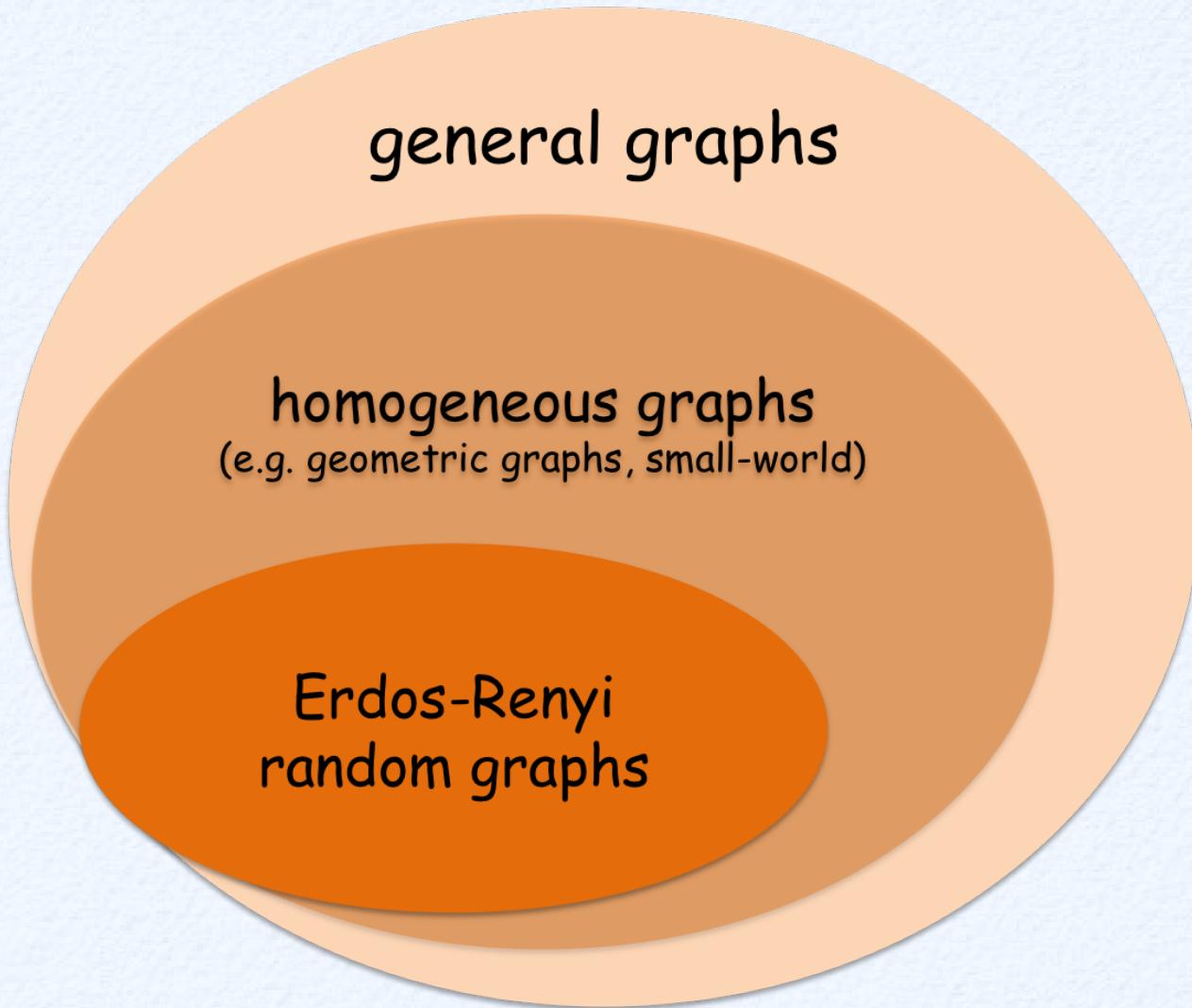
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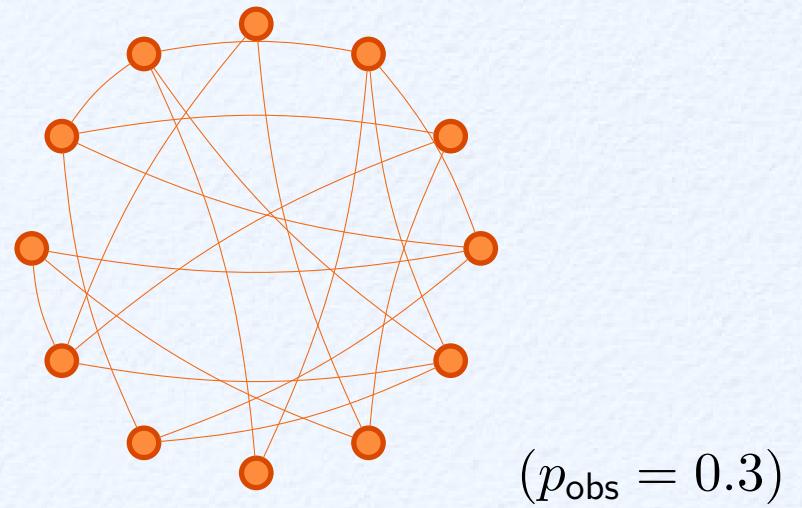
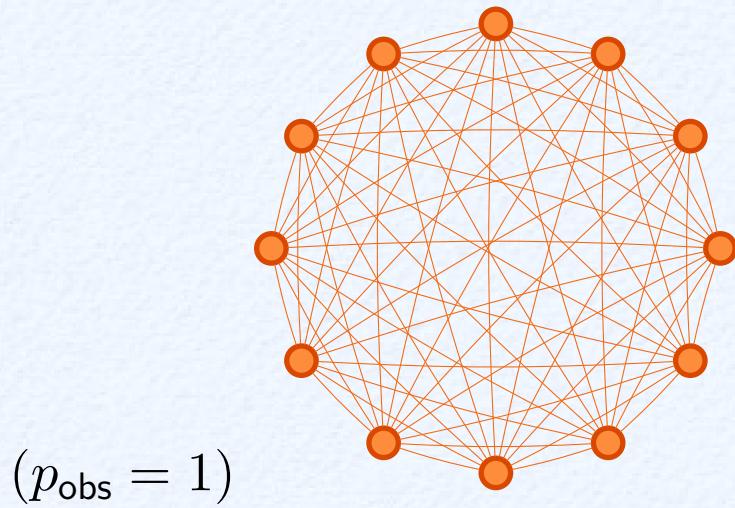
- **Graph connectivity**
 - Sufficient connectivity removes fragility!

Agenda



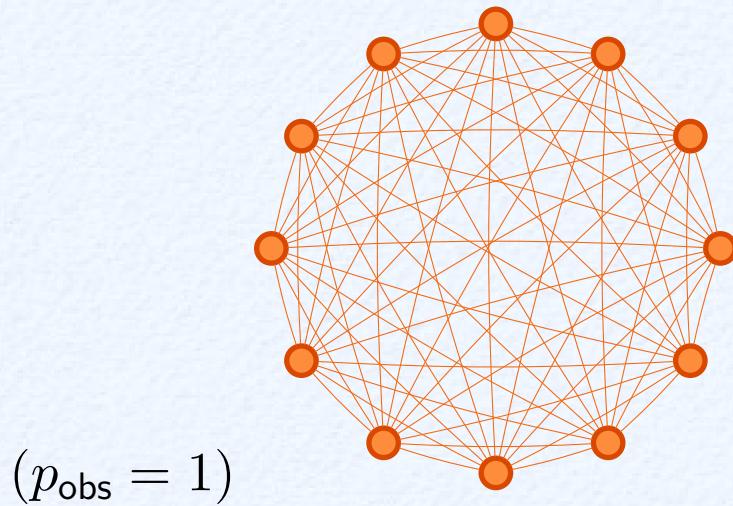
Main result: Erdos-Renyi random graph

Erdos-Renyi graph $\mathcal{G}(n, p_{\text{obs}})$. Each edge (i, j) is present independently w.p. p_{obs}

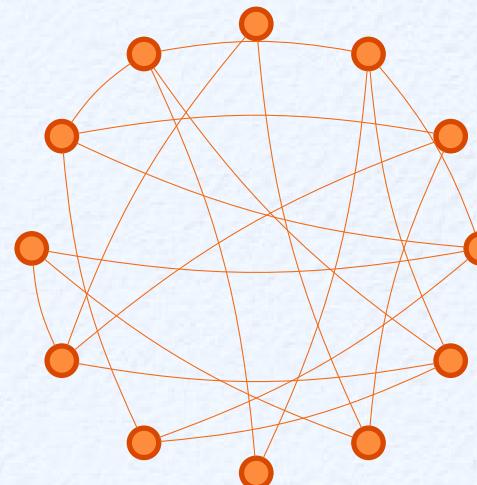


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$(p_{\text{obs}} = 1)$



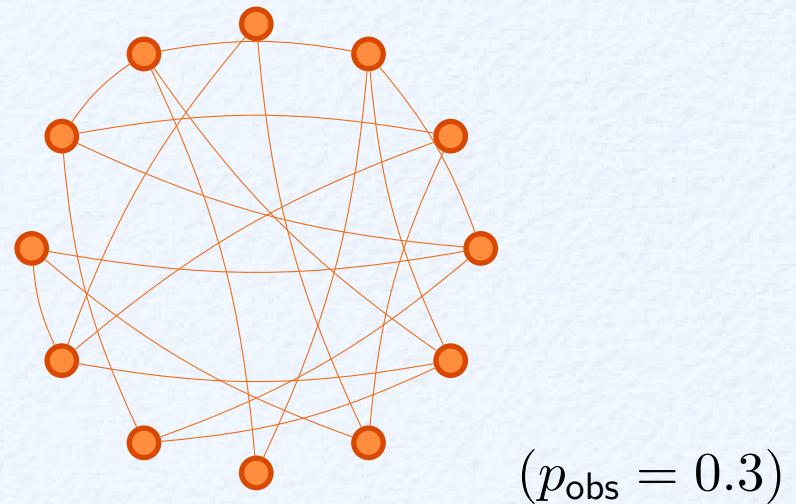
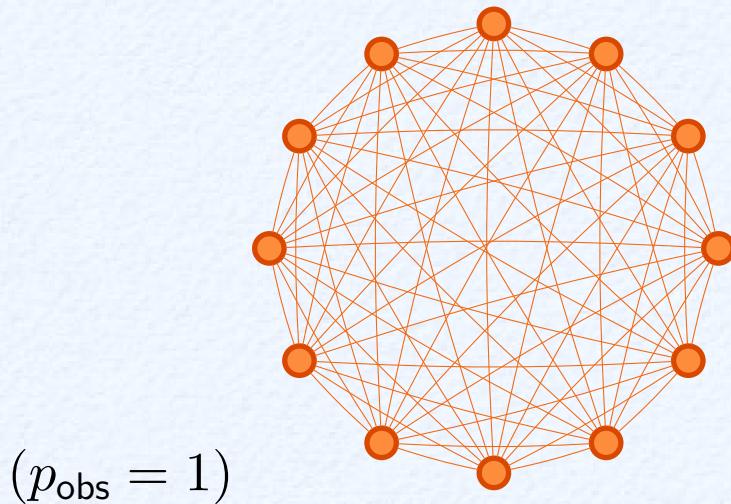
$(p_{\text{obs}} = 0.3)$

- ML decoding works if

$$\text{Hellinger}^{\min} > \frac{2 \log n + 4 \log M}{p_{\text{obs}} n}$$

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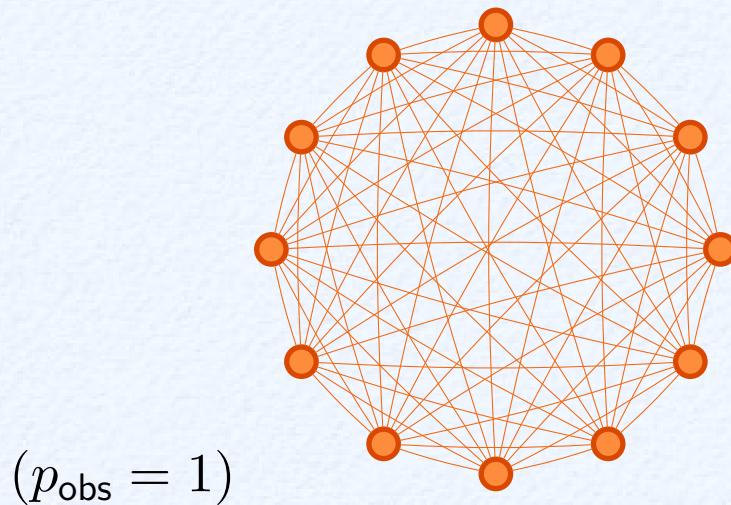
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- Converse: no method works if

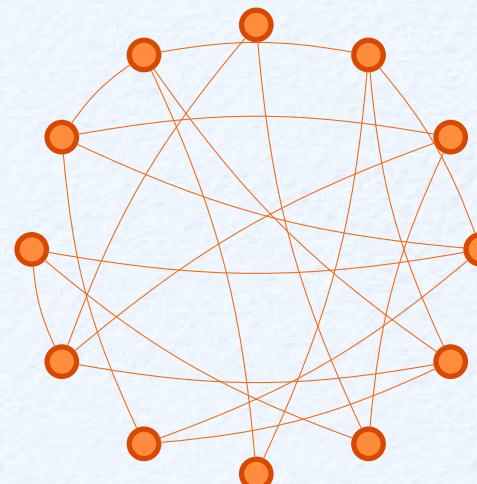
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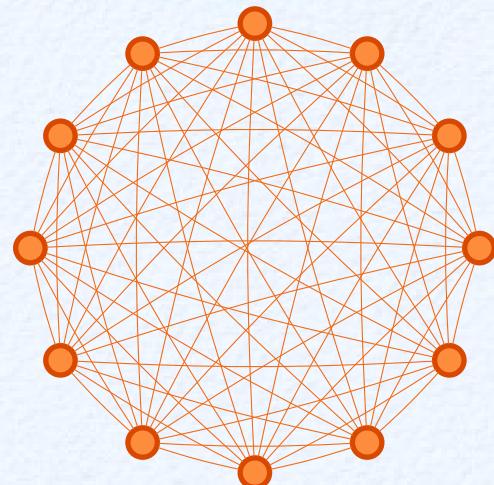
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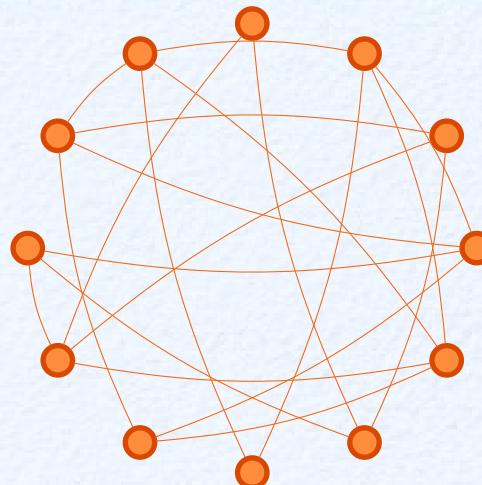
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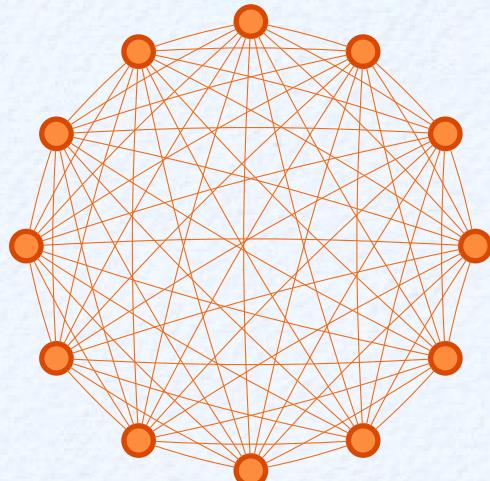


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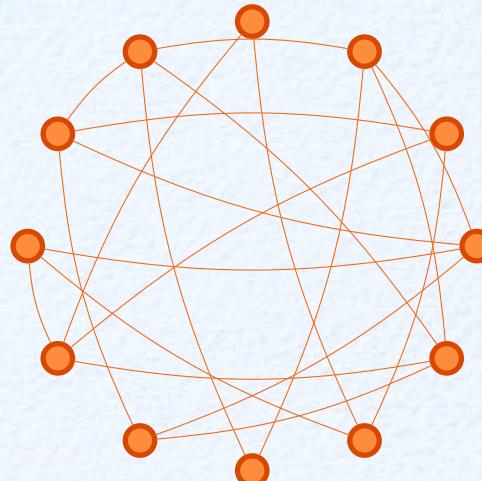


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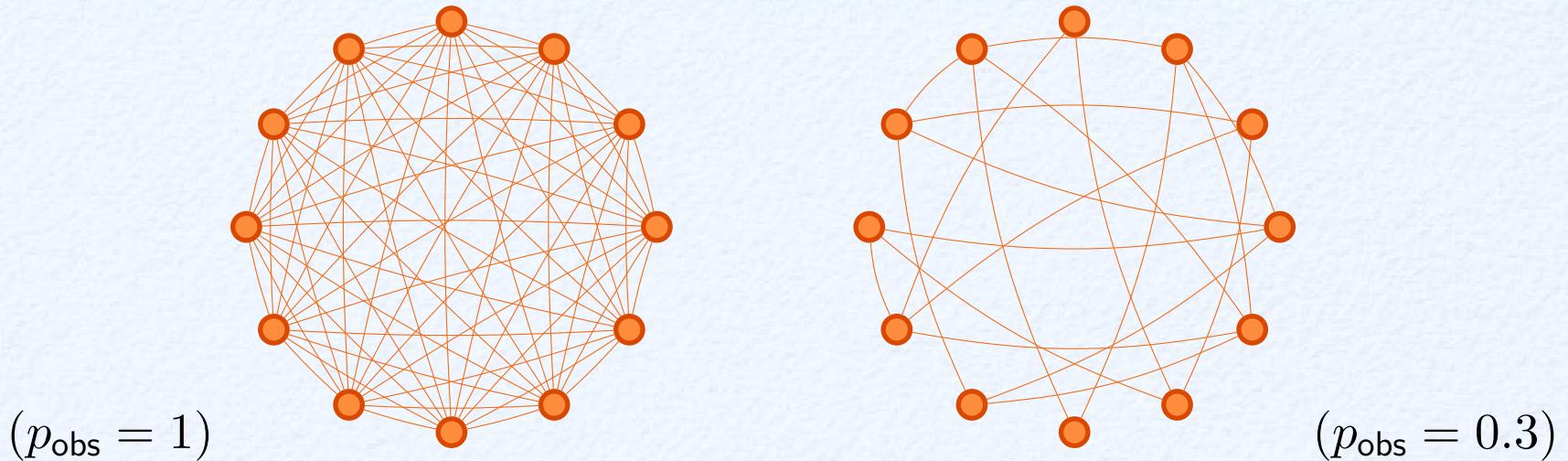


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- In the **hard regime** where $\frac{d\mathbb{P}_l}{d\mathbb{P}_k} \approx 1$:

$$\text{KL}^{\min} \approx 2 \cdot \text{Hellinger}^{\min}$$

Main result: Erdos-Renyi random graph



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- **Recovery conditions**

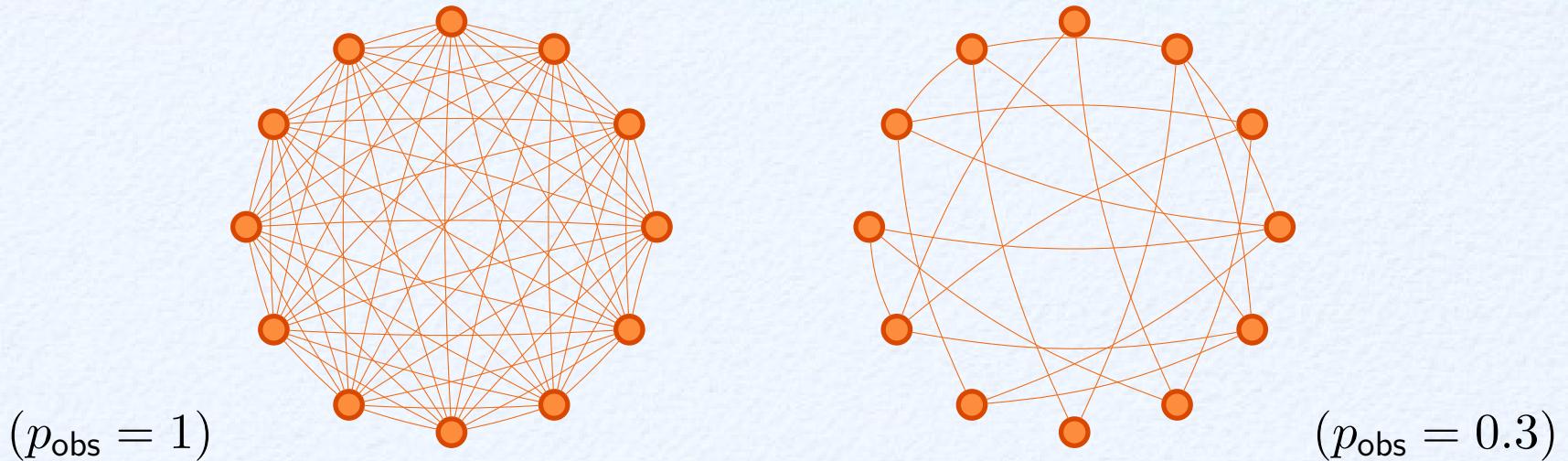
ML works if

$$\text{Hellinger}^{\min} > \frac{2 \log n + 4 \log M}{p_{\text{obs}} n}$$

Impossible if

$$\text{Hellinger}^{\min} < \frac{\log n}{2p_{\text{obs}} n}$$

Main result: Erdos-Renyi random graph



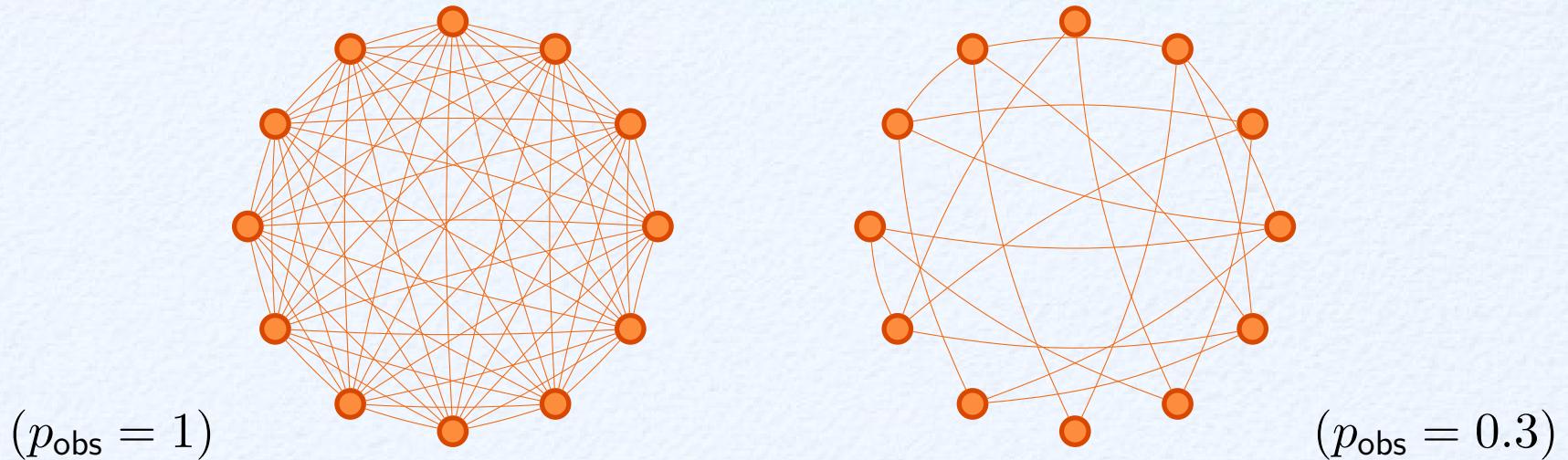
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- **Fundamental recovery condition (assuming $M \lesssim \text{poly}(n)$)**

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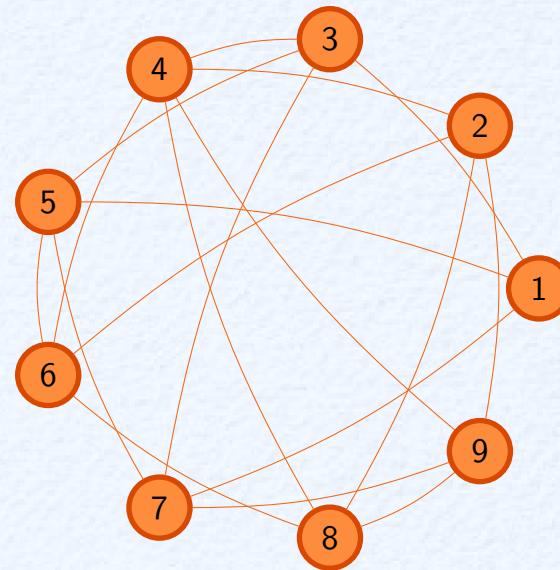
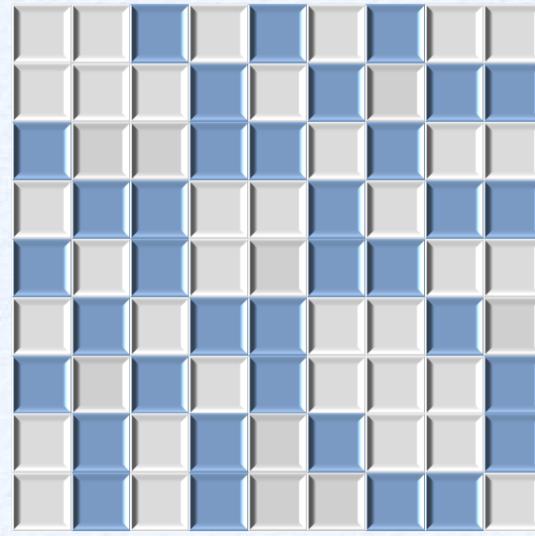
$$\text{Hellinger}^{\min} \gtrsim \frac{\log n}{p_{\text{obs}} n} \quad \iff \quad \text{avg-degree} \times \text{Hellinger}^{\min} \gtrsim \log n$$

Intuition

Fundamental recovery condition (Erdos-Renyi graphs).

$$\text{avg-degree} \times \text{Hellinger}^{\min} \gtrsim \log n$$

$$[x_i - x_j]_{1 \leq i, j \leq n}$$

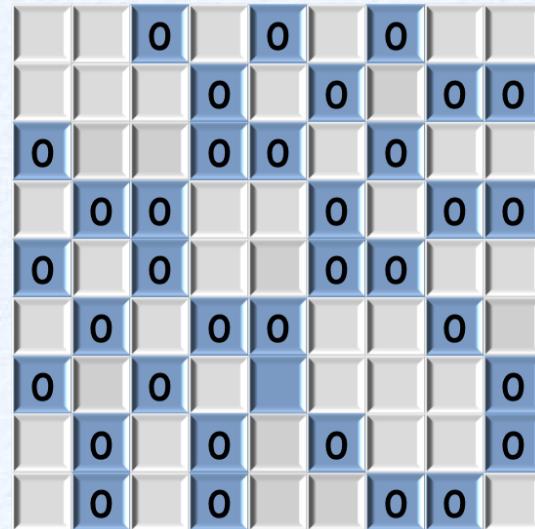


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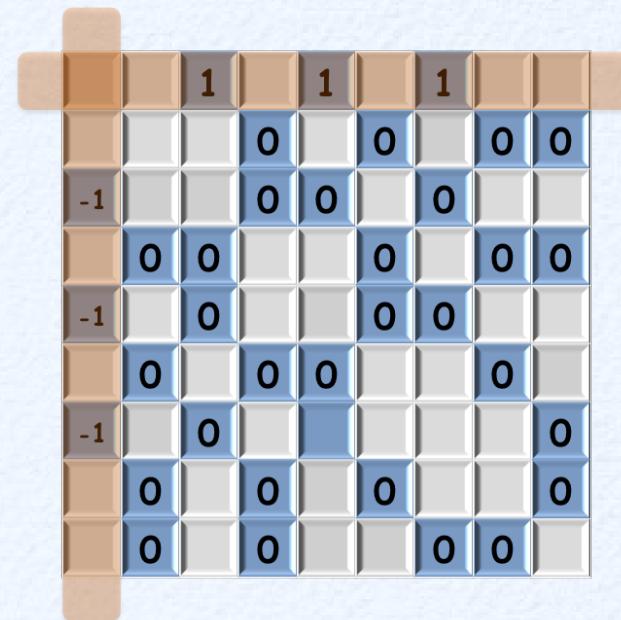
$$\text{avg-degree} \times \text{Hellinger}^{\min} \gtrsim \log n$$

$$[x_i - x_j]_{1 \leq i, j \leq n}$$



hypotheses:

$$H_0: \mathbf{x} = [0, 0, \dots, 0]$$



$$H_1: \mathbf{x} = [1, 0, \dots, 0]$$

- H_0 and H_1 differ only at the highlighted region (\approx avg-degree pieces of info)

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Fundamental recovery condition (Erdos-Renyi graphs).

$$\text{avg-degree} \times \text{Hellinger}^{\min} \gtrsim \log n$$

$$[x_i - x_j]_{1 \leq i, j \leq n}$$

| | | | | | |
|---|---|---|---|---|---|
| | 0 | 0 | 0 | | |
| 0 | | 0 | 0 | 0 | 0 |
| 0 | 0 | 0 | | 0 | 0 |
| 0 | 0 | | 0 | 0 | 0 |
| 0 | 0 | 0 | 0 | | 0 |
| 0 | 0 | | | | 0 |
| 0 | 0 | 0 | 0 | | 0 |
| 0 | 0 | | | | 0 |

hypotheses:

$$H_0: \mathbf{x} = [0, 0, \dots, 0]$$

| | | | | | |
|---|----|---|---|---|---|
| | 0 | 0 | 0 | | |
| 0 | | 1 | 1 | 1 | 1 |
| 0 | 0 | 0 | 0 | 0 | 0 |
| 0 | -1 | 0 | 0 | 0 | 0 |
| 0 | 0 | 0 | 0 | 0 | 0 |
| 0 | -1 | 0 | 0 | 0 | 0 |
| 0 | 0 | 0 | 0 | 0 | 0 |
| 0 | -1 | 0 | 0 | 0 | 0 |
| 0 | -1 | 0 | 0 | 0 | 0 |

$$H_2: \mathbf{x} = [0, 1, \dots, 0]$$

- H_0 and H_2 differ only at the highlighted region (\approx avg-degree pieces of info)

Intuition

Fundamental recovery condition (Erdos-Renyi graphs).

$$\text{avg-degree} \times \text{Hellinger}^{\min} \gtrsim \log n \quad (1)$$

$[x_i - x_j]_{1 \leq i, j \leq n}$

| | | | | |
|---|---|---|---|---|
| | 0 | 0 | 0 | |
| 0 | | 0 | 0 | 0 |
| 0 | 0 | | 0 | 0 |
| 0 | 0 | 0 | | 0 |
| 0 | 0 | 0 | 0 | |
| 0 | 0 | | | 0 |
| 0 | 0 | 0 | 0 | |
| 0 | 0 | | | 0 |

| | | | | | |
|----|----|----|----|----|----|
| | 0 | 0 | 0 | | |
| 0 | | 0 | 0 | 0 | 1 |
| 0 | 0 | | 0 | 0 | 1 |
| 0 | 0 | 0 | | 0 | 1 |
| 0 | 0 | 0 | 0 | | 0 |
| 0 | 0 | | | | 1 |
| 0 | 0 | 0 | 0 | | 1 |
| -1 | -1 | -1 | -1 | -1 | -1 |

hypotheses:

$$H_0: \mathbf{x} = [0, 0, \dots, 0]$$

$$H_n: \mathbf{x} = [0, 0, \dots, 1]$$

- n minimally-separated hypotheses \Rightarrow needs at least $\log n$ bits
 - the consequence of **uncoded inputs**

Minimal sample complexity

Fundamental recovery condition (Erdos-Renyi graphs).

$$\text{avg-degree} \times \text{Hellinger}^{\min} \gtrsim \log n$$

- Sample complexity: $n \cdot \text{avg-degree}$

Minimal sample complexity

Fundamental recovery condition (Erdos-Renyi graphs).

$$\text{avg-degree} \times \text{Hellinger}^{\min} \gtrsim \log n$$

- Sample complexity: $n \cdot \text{avg-degree}$

$$\text{Min sample complexity} \asymp \frac{n \log n}{\text{Hellinger}^{\min}}$$

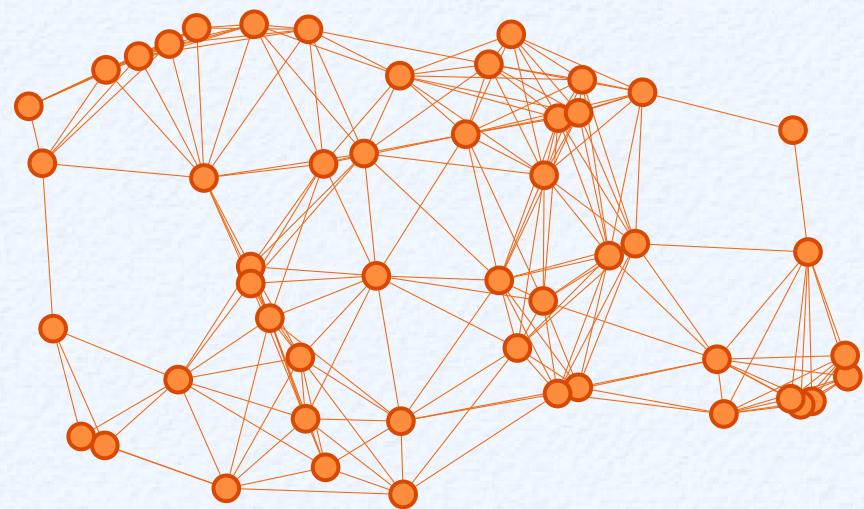
How general this limit is?

Fundamental recovery condition (Erdos-Renyi graphs).

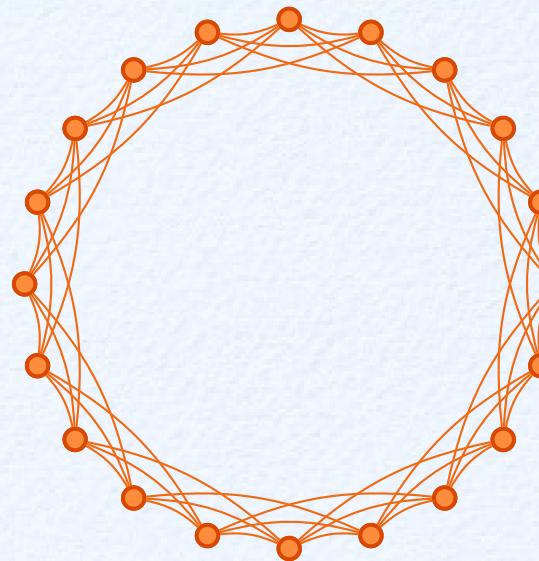
$$\text{avg-degree} \times \text{Hellinger}^{\min} \gtrsim \log n$$

- Can we go beyond Erdos-Renyi graphs?

Main results: homogeneous graphs

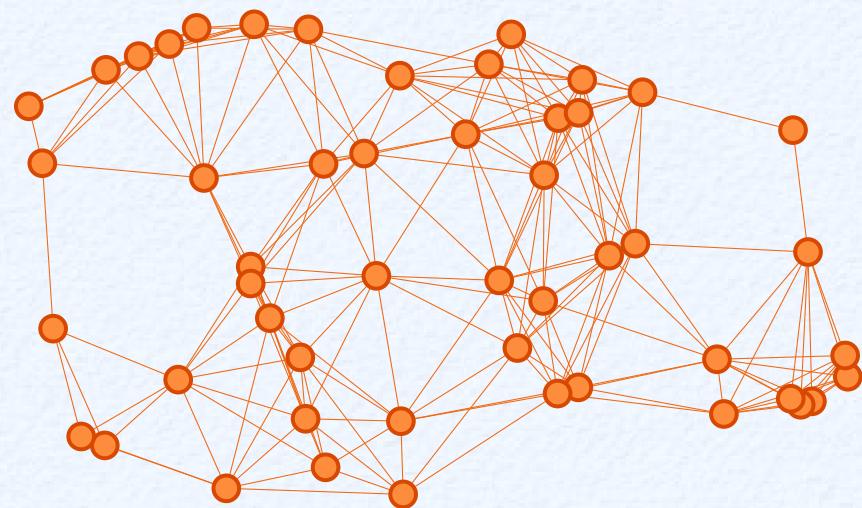


random geometric graph

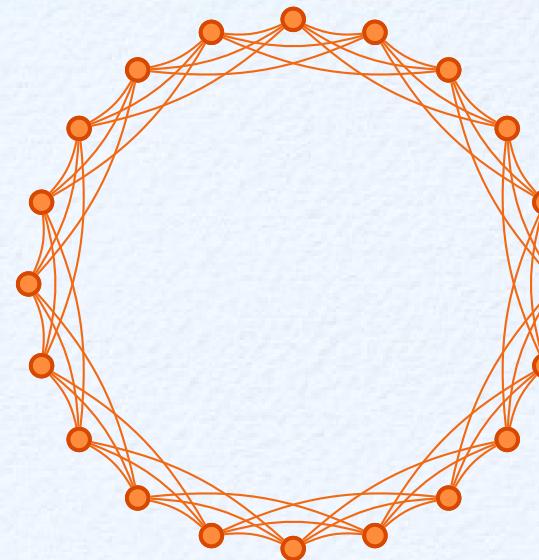


(generalized) ring

Main results: homogeneous graphs



random geometric graph



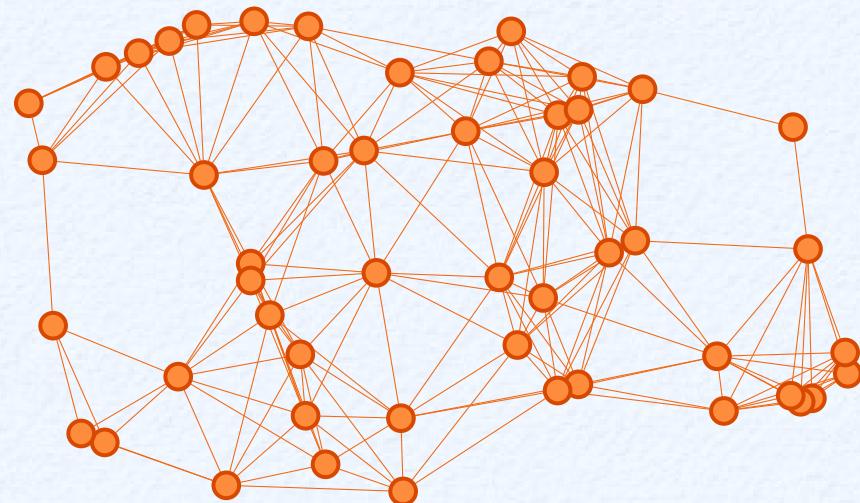
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Fundamental recovery condition (various homogeneous graphs).

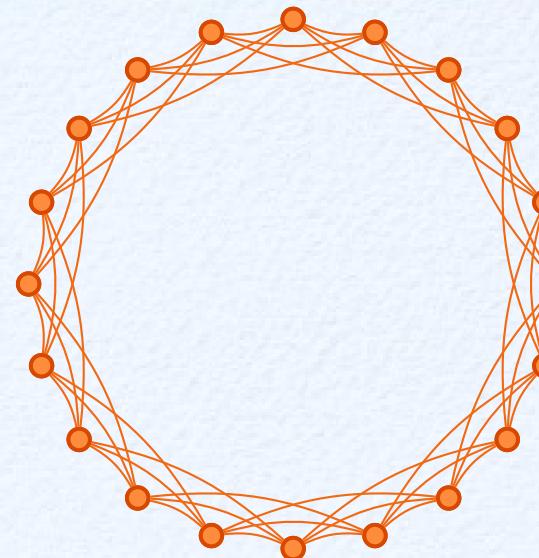
$$\text{avg-degree} \times \text{Hellinger}^{\min} \gtrsim \log n$$

- Homogeneous graphs:
 - min-degree \asymp max-degree \asymp mincut
 - *balanced cut-set distributions*

Main results: homogeneous graphs



random geometric graph



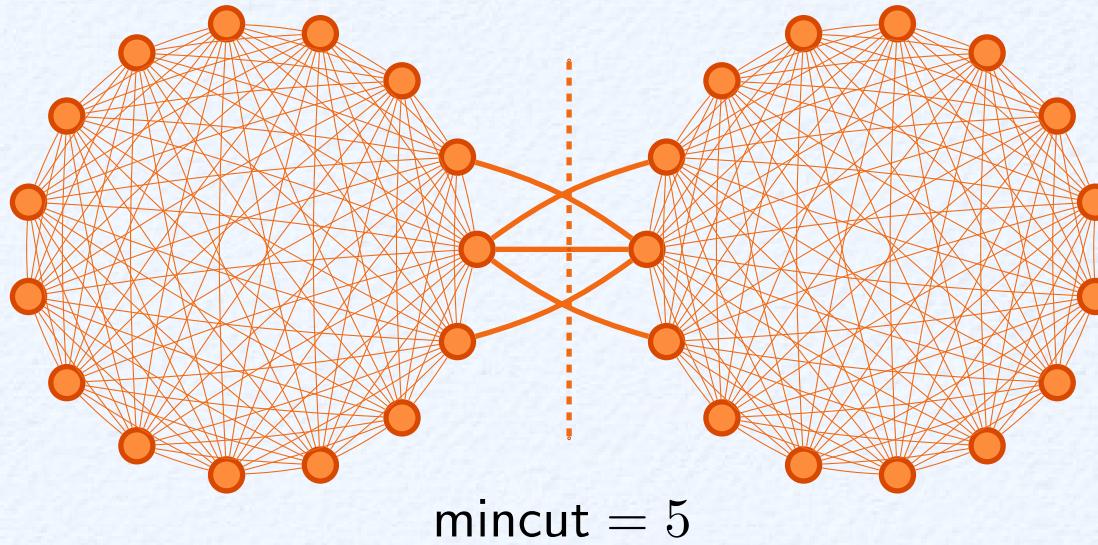
(generalized) ring

Fundamental recovery condition (various homogeneous graphs).

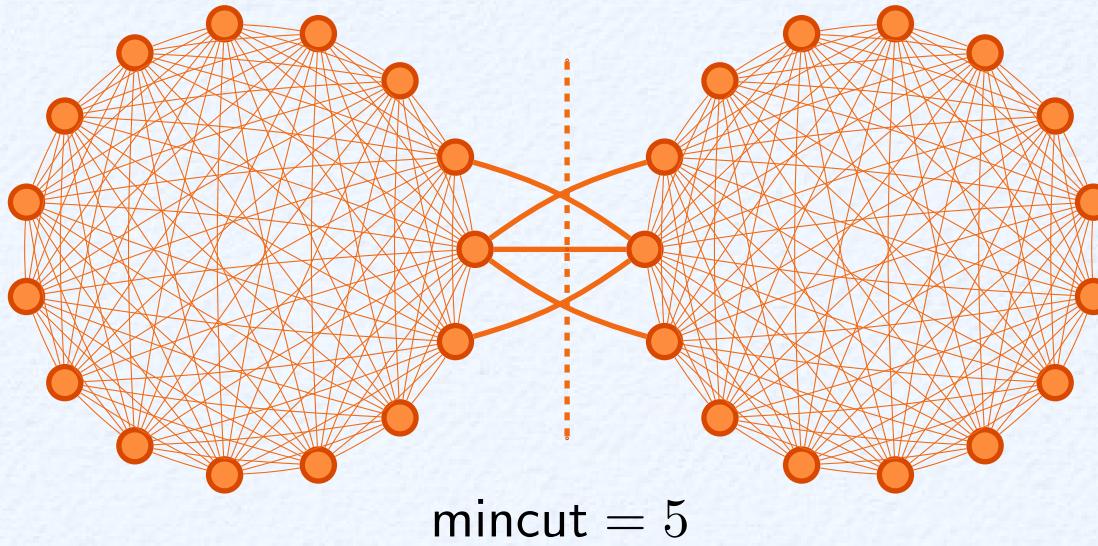
$$\text{avg-degree} \times \text{Hellinger}^{\min} \gtrsim \log n$$

- Depend almost only on **graph sparsity**

Main results: general graphs



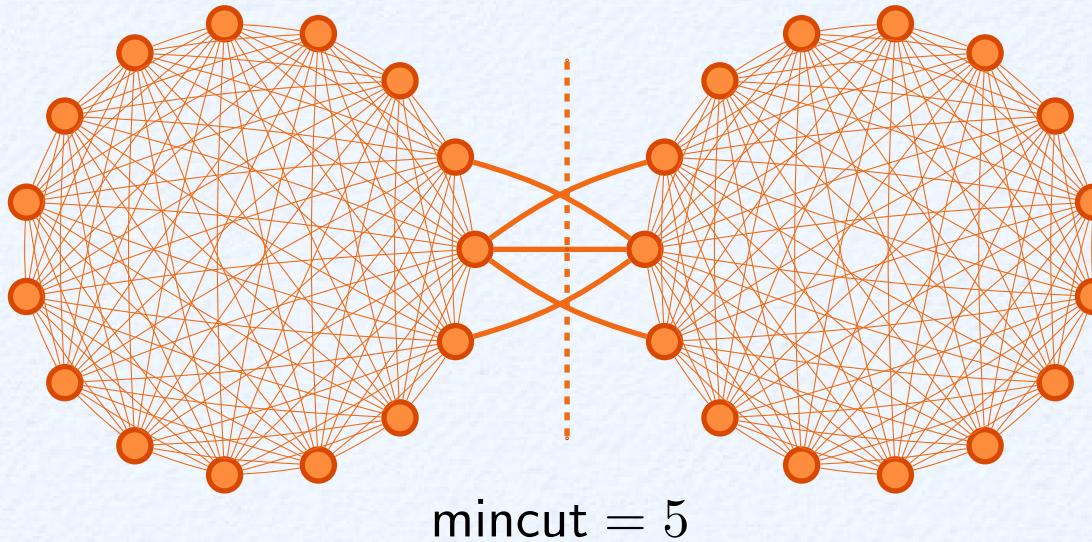
Main results: general graphs



- Information across the minimum cut set:

$$\text{mincut} \cdot \text{Hellinger}^{\text{min}}$$

Main results: general graphs



- **Recovery conditions**

ML works if

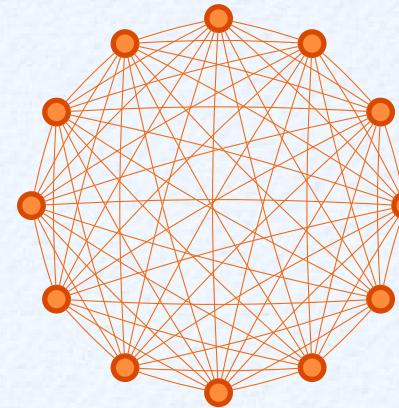
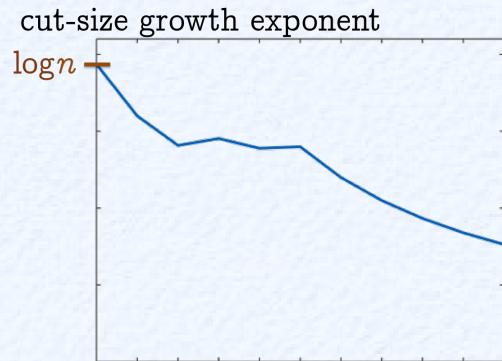
$$\text{mincut} \cdot \text{Hellinger}^{\min} \gtrsim \tau^{\text{cut}} + \log n + \log M$$

Impossible if

$$\text{mincut} \cdot \text{Hellinger}^{\min} \lesssim \tau^{\text{cut}} + \frac{\text{mincut}}{\text{max-degree}} \log n$$

Cut-homogeneity exponent

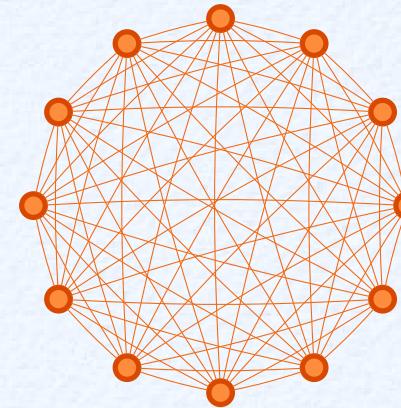
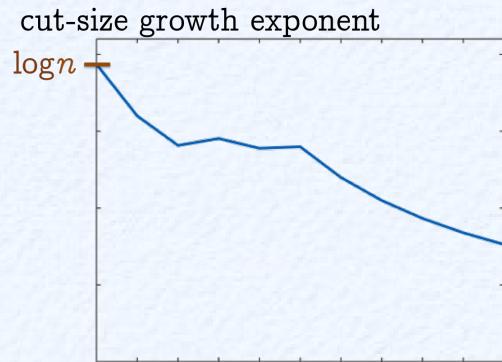
- τ^{cut} captures¹
 - growth rate of the cut-set distribution
 - the ratio $\frac{\text{mincut}}{\text{avg-degree}}$



¹ $\tau^{\text{cut}} := \max_k \frac{1}{k} |\mathcal{N}(k \cdot \text{mincut})|$, where $\mathcal{N}(K) := |\{\text{cut} : \text{cut-size} \leq K\}|$

Cut-homogeneity exponent

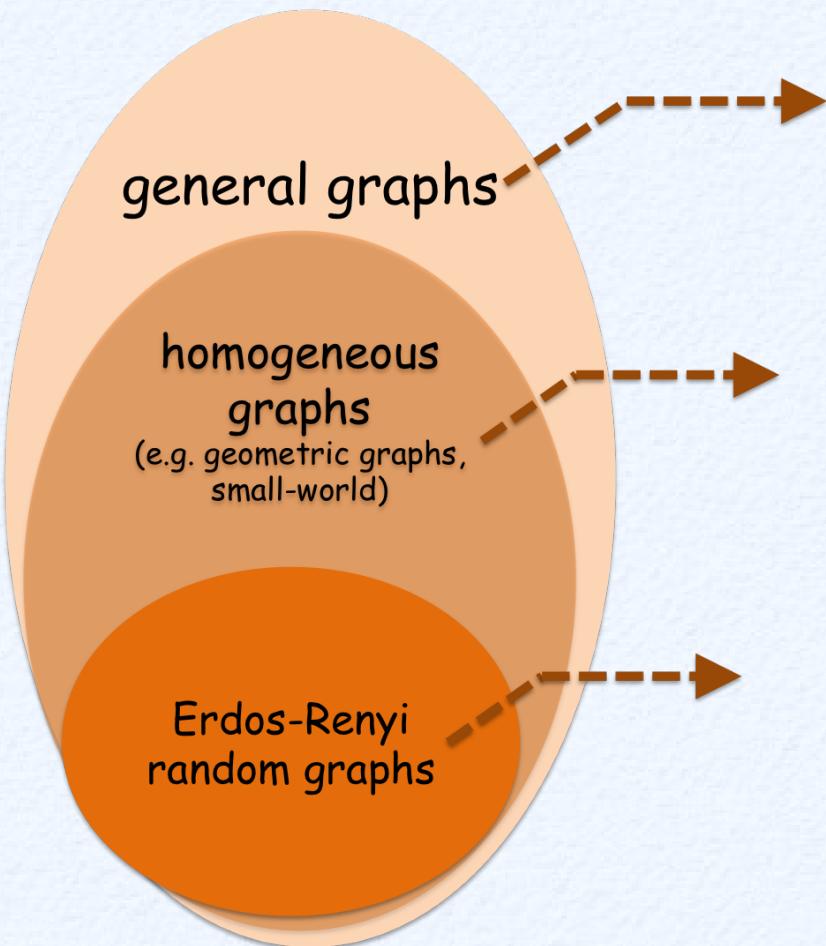
- τ^{cut} captures¹
 - growth rate of the cut-set distribution
 - the ratio $\frac{\text{mincut}}{\text{avg-degree}}$



- In general: $\tau^{\text{cut}} \gtrsim 1$
- For homogeneous graphs: $\tau^{\text{cut}} \lesssim \log n$

¹ $\tau^{\text{cut}} := \max_k \frac{1}{k} |\mathcal{N}(k \cdot \text{mincut})|$, where $\mathcal{N}(K) := |\{\text{cut} : \text{cut-size} \leq K\}|$

Summary of main results



$$\text{mincut} \times \text{Hellinger}^{\min} \gtrsim (1 \sim \log n)$$

$$\text{gap} \lesssim \log n$$

$$\text{avg-deg} \times \text{Hellinger}^{\min} \gtrsim \log n$$

$$\text{gap} \asymp 1$$

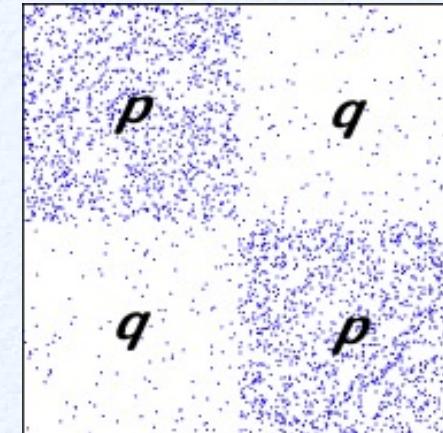
$$\text{avg-deg} \times \text{Hellinger}^{\min} \gtrsim \log n$$

$$\text{gap} \leq 4\left(1 + \frac{2 \log M}{\log n}\right)$$

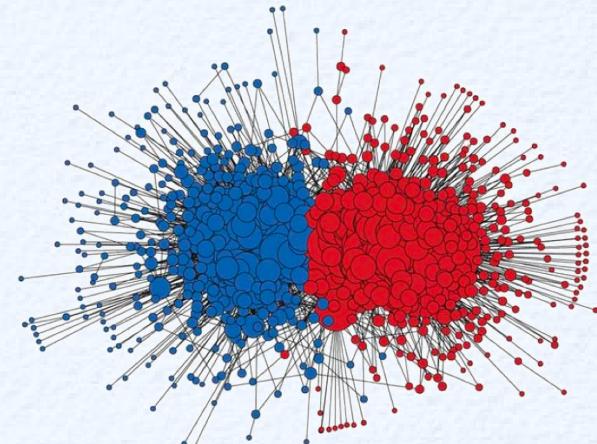
Concrete application: stochastic block model

- **Stochastic block model:**

- 2 clusters
- edge densities:
 - within-cluster: $p = \frac{\alpha \log n}{n}$
 - across-cluster: $q = \frac{\beta \log n}{n}$ ($q < p$)



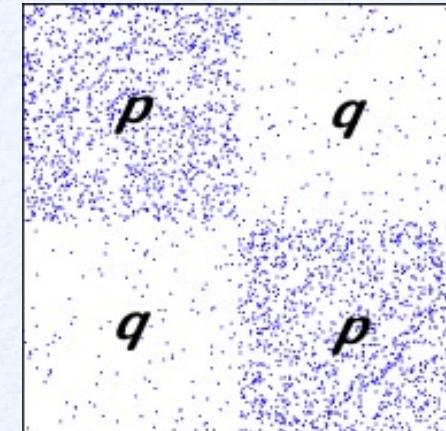
adjacency matrix



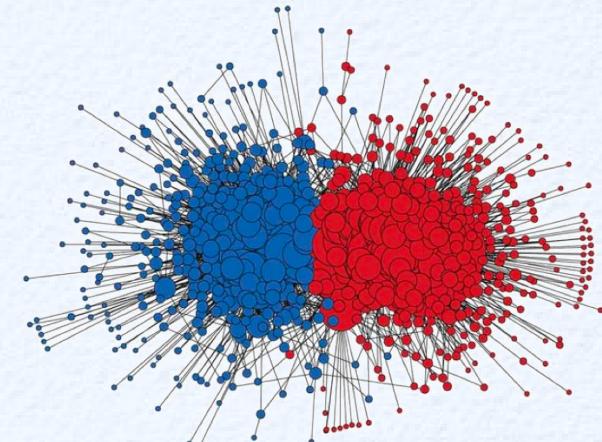
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adjacency matrix



- Our theory:

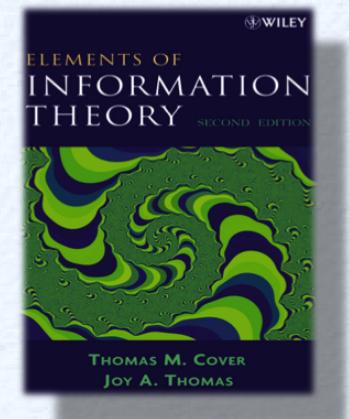
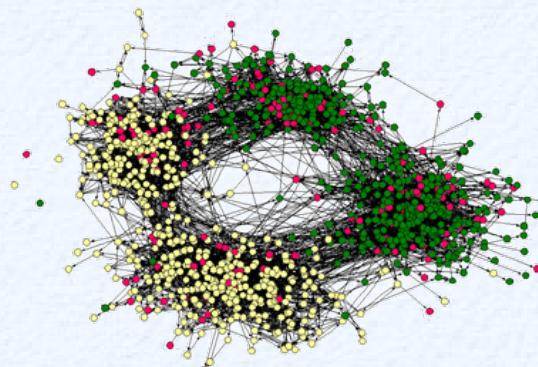
feasible if $\sqrt{\alpha} - \sqrt{\beta} > \sqrt{2}$

impossible if $\sqrt{\alpha} - \sqrt{\beta} < 1/2$

- Fundamental limit (Abbe et al. and Mossel et al.): $\sqrt{\alpha} - \sqrt{\beta} > \sqrt{2}$

Concluding remarks

- A unified framework to determine recovery limits
- Interplay between IT and graph theory
- Tighten the pre-constants?



Arxiv: <http://arxiv.org/abs/1504.01369>