

# Mathematics for Robotics

## ROB-GY 6103

### Homework 3 Answers

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**Question: 1.(a)**

**Answer:** Given,  $V = \mathbb{P}_2$  with the ordered basis  $\mathcal{S} = (p_0 = 1, p_1 = x, p_2 = x^2)$

And the given polynomial is  $r(x) = 2 + 3x - x^2$ .

$\therefore$  the components of  $r(x)$  in basis  $\mathcal{S}$  is

$$r_{\mathcal{S}} = \begin{bmatrix} 2 \\ 3 \\ -1 \end{bmatrix} \quad (1)$$

**Question: 1.(b)**

**Answer:** Given,  $V = \mathbb{P}_2$  with the ordered basis  $\mathcal{Q} = (q_0 = 1, q_1 = 1 - x, q_2 = x + x^2)$ .

From the definition of the basis  $\mathcal{Q}$ , we can rewrite it in terms of basis  $\mathcal{S}$  as,

$$q_{0\mathcal{S}} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, q_{1\mathcal{S}} = \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} \text{ and } q_{2\mathcal{S}} = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \Rightarrow Q_{\mathcal{S}} = \begin{bmatrix} 1 & 1 & 0 \\ 0 & -1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$$

And the given polynomial is  $r(x) = 2 + 3x - x^2$ .

$$\Rightarrow r_{\mathcal{S}} = \begin{bmatrix} 2 \\ 3 \\ -1 \end{bmatrix} \quad (1)$$

Now, we need to find numbers  $\tilde{r}_0, \tilde{r}_1$  and  $\tilde{r}_2$  such that,

$$r_{\mathcal{S}} = \tilde{r}_0 q_{0\mathcal{S}} + \tilde{r}_1 q_{1\mathcal{S}} + \tilde{r}_2 q_{2\mathcal{S}} \quad (2)$$

$$\Rightarrow \begin{bmatrix} 2 \\ 3 \\ -1 \end{bmatrix} = \tilde{r}_0 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + \tilde{r}_1 \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} + \tilde{r}_2 \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \quad (3)$$

$Eq^n$  can be rewritten as

$$\begin{bmatrix} 1 & 1 & 0 \\ 0 & -1 & 1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \tilde{r}_0 \\ \tilde{r}_1 \\ \tilde{r}_2 \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \\ -1 \end{bmatrix} \quad (4)$$

Applying the Gauss method,

$$\left[ \begin{array}{ccc|c} 1 & 1 & 0 & 2 \\ 0 & -1 & 1 & 3 \\ 0 & 0 & 1 & -1 \end{array} \right] \quad (5)$$

$$R_2 \rightarrow (-1)R_2$$

$$\left[ \begin{array}{ccc|c} 1 & 1 & 0 & 2 \\ 0 & 1 & -1 & -3 \\ 0 & 0 & 1 & -1 \end{array} \right] \quad (6)$$

$$R_1 \rightarrow R_1 + (-1)R_2$$

$$\left[ \begin{array}{ccc|c} 1 & 0 & 1 & 5 \\ 0 & 1 & -1 & -3 \\ 0 & 0 & 1 & -1 \end{array} \right] \quad (7)$$

$$R_2 \rightarrow R_2 + R_3$$

$$\left[ \begin{array}{ccc|c} 1 & 0 & 1 & 5 \\ 0 & 1 & 0 & -4 \\ 0 & 0 & 1 & -1 \end{array} \right] \quad (8)$$

$$R_1 \rightarrow R_1 + (-1)R_3$$

$$\left[ \begin{array}{ccc|c} 1 & 0 & 0 & 6 \\ 0 & 1 & 0 & -4 \\ 0 & 0 & 1 & -1 \end{array} \right] \quad (9)$$

Hence, the solution is,

$$r_q = \begin{bmatrix} 6 \\ -4 \\ -1 \end{bmatrix} \quad (10)$$

**Question: 2.**

**Answer:** Given the matrix,

$$A_3 = \begin{bmatrix} 1 & 4 & 10 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix} \quad (1)$$

By definition, we know that,  $\exists v \neq 0$  s.t.  $Av = \lambda v \Rightarrow (\lambda I - A)v = 0 \Leftrightarrow \det(\lambda I - A) = 0$

$$\Rightarrow \lambda I - A = \begin{bmatrix} \lambda - 1 & -4 & -10 \\ 0 & \lambda - 2 & 0 \\ 0 & 0 & \lambda - 3 \end{bmatrix} \quad (2)$$

$$\Rightarrow \det(\lambda I - A) = (\lambda - 1) \cdot (\lambda - 2) \cdot (\lambda - 3) = 0 \quad (3)$$

$$\therefore \lambda_1 = 1, \lambda_2 = 2, \lambda_3 = 3 \quad (4)$$

Now, we shall apply the known relation  $Av^i = \lambda_i v^i \Rightarrow (A - \lambda_i I)v^i = 0$

$$\begin{bmatrix} 1 - \lambda_i & 4 & 10 \\ 0 & 2 - \lambda_i & 0 \\ 0 & 0 & 3 - \lambda_i \end{bmatrix} \begin{bmatrix} v_1^i \\ v_2^i \\ v_3^i \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \quad (5)$$

From  $Eq^n$  5, substituting  $\lambda_1 = 1$

$$\begin{bmatrix} 0 & 4 & 10 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{bmatrix} \begin{bmatrix} v_1^1 \\ v_2^1 \\ v_3^1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \Rightarrow \begin{array}{l} 4v_2^1 + 10v_3^1 = 0 \\ v_2^1 = 0 \\ 2v_3^1 = 0 \end{array} \Rightarrow \begin{array}{l} v_1^1 = \text{any value} \\ v_2^1 = 0 \\ v_3^1 = 0 \end{array} \Rightarrow v^1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \quad (6)$$

From  $Eq^n$  5, substituting  $\lambda_2 = 2$

$$\begin{bmatrix} -1 & 4 & 10 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} v_1^2 \\ v_2^2 \\ v_3^2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \Rightarrow \begin{array}{l} -v_1^2 + 4v_2^2 + 10v_3^2 = 0 \\ 0 = 0 \\ v_3^2 = 0 \end{array} \Rightarrow \begin{array}{l} v_1^2 = 4v_2^2 \\ v_2^2 = \text{any value} \\ v_3^2 = 0 \end{array} \Rightarrow v^2 = \begin{bmatrix} 4 \\ 1 \\ 0 \end{bmatrix} \quad (7)$$

From  $Eq^n$  5, substituting  $\lambda_3 = 3$

$$\begin{bmatrix} -2 & 4 & 10 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1^3 \\ v_2^3 \\ v_3^3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \Rightarrow \begin{array}{l} -2v_1^3 + 4v_2^3 + 10v_3^3 = 0 \\ -v_2^3 = 0 \\ 0 = 0 \end{array} \Rightarrow \begin{array}{l} v_1^3 = 5v_3^3 \\ v_2^3 = 0 \\ v_3^3 = \text{any value} \end{array} \Rightarrow v^3 = \begin{bmatrix} 5 \\ 0 \\ 1 \end{bmatrix} \quad (8)$$

Now we shall verify that  $v^1, v^2$  and  $v^3$  are *Linearly Independent*,

$$\alpha_1 v^1 + \alpha_2 v^2 + \alpha_3 v^3 = 0 \quad (9)$$

$$\alpha_1 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + \alpha_2 \begin{bmatrix} 4 \\ 1 \\ 0 \end{bmatrix} + \alpha_3 \begin{bmatrix} 5 \\ 0 \\ 1 \end{bmatrix} = 0 \quad (10)$$

$$\alpha_1 + 4\alpha_2 + 5\alpha_3 = 0 \quad (11)$$

$$\alpha_2 = 0 \quad (12)$$

$$\alpha_3 = 0 \quad (13)$$

Solving above system of equations gives us  $\alpha_1 = 0$ ,  $\alpha_2 = 0$  and  $\alpha_3 = 0$ .  
 $\therefore v^1, v^2$  and  $v^3$  are *Linearly Independent*.

**Question: 3.**

**Answer:** Given the matrix,

$$A_4 = \begin{bmatrix} 3 & 1 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 2 \end{bmatrix} \quad (1)$$

By definition, we know that,  $\exists v \neq 0$  s.t.  $Av = \lambda v \Rightarrow (\lambda I - A)v = 0 \Leftrightarrow \det(\lambda I - A) = 0$

$$\Rightarrow \lambda I - A = \begin{bmatrix} \lambda - 3 & -1 & 0 \\ 0 & \lambda - 3 & 0 \\ 0 & 0 & \lambda - 2 \end{bmatrix} \quad (2)$$

$$\Rightarrow \det(\lambda I - A) = (\lambda - 3) \cdot (\lambda - 3) \cdot (\lambda - 2) = 0 \quad (3)$$

$$\therefore \lambda_1 = 3, \lambda_2 = 2 \quad (4)$$

Now, we shall apply the known relation  $Av^i = \lambda_i v^i \Rightarrow (A - \lambda_i I)v^i = 0$

$$\begin{bmatrix} 3 - \lambda_i & 1 & 0 \\ 0 & 3 - \lambda_i & 0 \\ 0 & 0 & 2 - \lambda_i \end{bmatrix} \begin{bmatrix} v_1^i \\ v_2^i \\ v_3^i \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \quad (5)$$

From  $Eq^n$  5, substituting  $\lambda_1 = 3$

$$\begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} v_1^1 \\ v_2^1 \\ v_3^1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \Rightarrow \begin{matrix} v_2^1 = 0 \\ 0 = 0 \\ -v_3^1 = 0 \end{matrix} \Rightarrow \begin{matrix} v_1^1 = \text{any value} \\ v_2^1 = 0 \\ v_3^1 = 0 \end{matrix} \Rightarrow v^1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \quad (6)$$

From  $Eq^n$  5, substituting  $\lambda_2 = 2$

$$\begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1^2 \\ v_2^2 \\ v_3^2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \Rightarrow \begin{matrix} v_1^2 = 0 \\ v_2^2 = 0 \\ 0 = 0 \end{matrix} \Rightarrow \begin{matrix} v_1^2 = 0 \\ v_2^2 = 0 \\ v_3^2 = \text{any value} \end{matrix} \Rightarrow v^2 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \quad (7)$$

Consider the set of eigenvectors  $\mathcal{V} = \{v^1, v^2\}$ . Firstly,

We know that any set of eigenvectors of a given matrix are Linearly Independent. So,  $v^1, v^2$  are *L.I.* (8)

Secondly, consider a linear combination  $x$  such that,

$$\{x \in \mathbb{R} \mid \exists \alpha_1, \alpha_2 \in \mathbb{R}, v^1, v^2 \in \mathcal{V} ; \text{ s.t. } x = \alpha_1 v^1 + \alpha_2 v^2\} \quad (9)$$

By observing above  $Eq^n$  9 we can see that the basis does not span the entire vector space.

$\therefore$  based on the  $Eq^n$  8 and 9 we can say that  $\mathcal{V}$  does not form a basis for  $\mathbb{R}^3$ .

**Question: 4.**

**Answer:** We are given two similar square matrices  $A$  and  $B$  such that,

$$B = P^{-1}AP \quad (1)$$

Consider the characteristic relation of matrix  $B$ ,

$$\det(\lambda I - B) \quad (2)$$

Apply Eq<sup>n</sup> 1 in Eq<sup>n</sup> ??,

$$\Rightarrow \det(\lambda I - B) = \det(\lambda I - P^{-1}AP) \quad (3)$$

The identity matrix  $I$  can also be written as  $P^{-1}IP$ . Substituting in Eq<sup>n</sup> 3,

$$\Rightarrow \det(\lambda I - B) = \det(\lambda P^{-1}IP - P^{-1}AP) \quad (4)$$

Now we shall take  $P^{-1}$  and  $P$  out common,

$$\Rightarrow \det(\lambda I - B) = \det(P^{-1}(\lambda I - A)P) \quad (5)$$

We know that for compatible square matrices  $A$  and  $B$ ,  $\det(AB) = \det(A)\det(B)$ . So Eq<sup>n</sup> 5 becomes,

$$\Rightarrow \det(\lambda I - B) = \det(P^{-1})\det(\lambda I - A)\det(P) \quad (6)$$

Cancelling out  $\det(P^{-1})$  by  $\det(P)$

$$\Rightarrow \det(\lambda I - B) = \det(\lambda I - A) \quad (7)$$

When the relation in Eq<sup>n</sup> 8 is equated to zero, we prove that the two matrices have the same eigenvalues as well as the characteristic equations. I.E.,

$$\Rightarrow \det(\lambda I - B) = \det(\lambda I - A) = 0 \quad (8)$$

**Q.E.D.**

**Question: 5.**

**Answer:** Given a matrix  $A_3$  such that,

$$A_3 = \begin{bmatrix} 1 & 4 & 10 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix} \quad (1)$$

From Question: 2. We found the eigenvalues to be  $\lambda_1 = 1$ ,  $\lambda_2 = 2$ ,  $\lambda_3 = 3$ .

Using these eigenvalues, we can create the diagonal matrix,  $\Lambda = \text{diag}(\lambda_1, \lambda_2, \lambda_3)$ ,

$$\Lambda = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix} \quad (2)$$

To show similarity between  $A$  and  $\Lambda$ , we need to find a matrix  $P$  such that  $\Lambda = PAP^{-1}$

Consider a matrix  $P = [v^1 \ v^2 \ v^3]$  where  $v^1, v^2$  and  $v^3$  are the eigenvectors of  $A$ .

$$P = \begin{bmatrix} 1 & 4 & 5 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad (3)$$

Testing for invertibility,  $\det(P) = 1$ . As the determinant is non-zero, we can conclude that  $P$  is invertible.

In Question: 2. we already proved that  $v^1, v^2$  and  $v^3$  are *Linearly Independent*.

As these two conditions are satisfied, we can therefore test for similarity,

$$A_3 = P\Lambda P^{-1} \quad (4)$$

$$A_3 = \begin{bmatrix} 1 & 4 & 5 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix} \begin{bmatrix} 1 & 4 & 5 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}^{-1} \quad (5)$$

$$= \begin{bmatrix} 1 & 4 & 5 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0.5 & 0 \\ 0 & 0 & 0.333 \end{bmatrix} \quad (6)$$

$$= \begin{bmatrix} 1 & 8 & 15 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0.5 & 0 \\ 0 & 0 & 0.333 \end{bmatrix} \quad (7)$$

$$= \begin{bmatrix} 1 & 4 & 10 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix} \quad (8)$$

$\therefore \text{LHS} = \text{RHS}$

Thus, we can say that matrix  $A$  is similar to a diagonal matrix  $\Lambda$ . **Q.E.D.**

**Question: 6.(a)**

**Answer:** Given, a vector space  $(\mathcal{X}, \mathbb{R})$  where  $\mathcal{X}$  is a set of  $2 \times 2$  matrices with real coefficients.

An operation is defined  $L : \mathcal{X} \rightarrow \mathcal{X}$  by

$$L(M) = \frac{1}{2}(M + M^T) \quad (1)$$

Where  $M \in \mathcal{X}$  is a  $2 \times 2$  real matrix

The operator  $L$  will be considered a *Linear Operator* if,

$$\forall x, y \in \mathcal{X}, \alpha, \beta \in \mathbb{R} \mid L(\alpha x + \beta y) = \alpha L(x) + \beta L(y) \quad (2)$$

Applying above Statement 2 to Eq<sup>n</sup> 1,

$$L(\alpha x + \beta y) = \frac{1}{2}((\alpha x + \beta y) + (\alpha x + \beta y)^T) \quad (3)$$

Applying the property of sum of transpose of two matrices  
(i.e. for two matrices  $A$  and  $B \rightarrow (A + B)^T = A^T + B^T$ )

$$L(\alpha x + \beta y) = \frac{1}{2}(\alpha x + \beta y + \alpha x^T + \beta y^T) \quad (4)$$

$$= \frac{1}{2}(\alpha x + \alpha x^T + \beta y + \beta y^T) \quad (5)$$

$$= \alpha\left(\frac{1}{2}(x + x^T)\right) + \beta\left(\frac{1}{2}(y + y^T)\right) \quad (6)$$

$$= \alpha L(x) + \beta L(y) \quad (7)$$

Thus, Eq<sup>n</sup> 7 proves Statement 2.  $\therefore$  the given operator  $L$  is actually a *Linear Operator*.

**Q.E.D.**