# NEW YORK UNIVERSITY TANDON SCHOOL OF ENGINEERING Department of Mechanical and Aerospace Engineering

# Mathematics for Robotics (ROB-GY 6013)

Fall 2023 — Section A — 3.0 credits

William Z. Peng, Ph.D Office Hours Contact

Tuesdays 6:00 PM - 8:30 PMWeekly Schedule TBDwilliam.peng@nyu.edu6 MetroTech Center6 MetroTech CenterCourse WebpageJacobs Building, Room 475Rogers Hall, Room 501ANYU Brightspace

**Textbook** Grizzle, J., *ROB 501 Mathematics for Robotics*, University of Michigan, 2022.

■ Textbook posted on NYU Brightspace and github.com/michiganrobotics/rob501/tree/main

**Prerequisites** Graduate standing. Advisor's approval. Consent of instructor.

**Course Objectives** Students will gain familiarity with linear algebra, optimization, differential equations, and probability. They will be able to use mathematical tools and numerical methods for

formulating and solving the modeling, estimation, planning, optimization, and control  $% \left( 1\right) =\left( 1\right) \left( 1\right) \left($ 

problems related to robotic systems.

Topics Review of vectors and matrices (linear independence, rank, basis, subspaces, etc.); Matrix

operations and types (determinant, inverse, eigenvalues, matrix exponential, etc.); Matrix decompositions (SVD, Eigenvalues, Cholesky, LU, QR, etc.); Newton-Raphson method; Least-squares/pseudo-inverse; Linear, quadratic and nonlinear programming; ODEs with numerical

methods; Probability.

**Homework** Homework assignments will be posted by the instructor and submitted by the students through

NYU Brightspace. Clearly indicate answers by underlining or boxing them. Late assignments

will receive a 15% grade penalty for every day late.

Grading Policy Homework 25 pts + Midterm 30 pts + Final Exam 45 pts ± Extra Credits<sup>†</sup> 10 pts = Final Grade

#### Final to Letter Grade

Letter	A	<b>A</b> -	B+	В	В-	C+	C	F
Final Grade	≥95	≥90	≥87	≥83	≥80	≥75	≥70	<70

† Extra credits of up to +10 pts will be awarded for active and professional class participation (e.g., discussion and interactions during lecture), and up to -10 pts will be deducted for negative participation (e.g., disrupting instruction through excessive chatter). Note that there is no deduction of points for absences.

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Week	Date	Content
1	Sep 5	Lecture 1
2	Sep 12	Lecture 2
3	Sep 19	Lecture 3
4	Sep 26	Lecture 4
5	Oct 3	Lecture 5
6	Oct 10	Legislative Monday (No Class)
7	Oct 17	Midterm Exam*
8	Oct 24	Lecture 6
9	Oct 31	Lecture 7
10	Nov 7	Lecture 8
11	Nov 14	Lecture 9
12	Nov 21	Lecture 10
13	Nov 28	Lecture 11
14	Dec 5	Lecture 12
15	Dec 12	Lecture 13
16	Dec 19	Final Exam*

<sup>\*</sup>Exam dates are final.

#### **Exam Policy**

Exams are closed-book and closed-notes. Bring your own scientific calculator. Unexcused absences from an exam will result in a zero grade.

#### **Academic Integrity**

Refer to NYU Tandon Policies and Procedures on Academic Misconduct for the Student Code of Conduct (also uploaded to NYU Brightspace).

#### Other Resources

#### NYU's Moses Center for Students with Disabilities

726 Broadway, 2nd floor | www.nyu.edu/csd | 212-998-4980 | mosescsd@nyu.edu Students with disabilities must register with CSD to receive accommodations.

#### NYU's Wellness Exchange

Available via 24-hour hotline 212-443-9999, chat through the Wellness Exchange app, or appointment for mental health resources. Confidential and free of charge.

Inclusion Statement NYU values an inclusive and equitable environment for all our students. The instructor of this course hopes to foster a sense of community in this class and consider it a place where individuals of all backgrounds, beliefs, ethnicities, national origins, gender identities, sexual orientations, religious and political affiliations, and abilities will be treated with respect. It is this instructor's intent that all students' learning needs be addressed both in and out of class, and that the diversity that students bring to this class be viewed as a resource, strength, and benefit.

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#### **Additional Readings**

- Dingyü Xue and Yang Chen, *System Simulation Techniques with MATLAB and Simulink*, Wiley, (any edition).
  - Companion Website: https://mechatronics.ucmerced.edu/simubook2013wiley
- Peter Corke, *Robotics, Vision and Control: Fundamental Algorithms in MATLAB*, Springer, (any edition). Companion Website: Robot Academy <a href="https://robotacademy.net.au/">https://robotacademy.net.au/</a>