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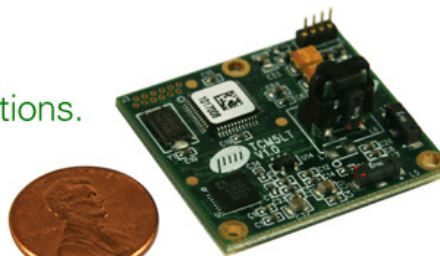


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**Full-tilt accuracy in  
real-world conditions.**

## TCM 5LT

360° tilt-compensated heading module



### TCM 5LT

The TCM5LT combines a full 360 degrees of tilt compensation with transistor-to-transistor level (TTL) output — providing ultra-precise digital compass heading information and magnetometer measurements while using less power than any other tilt-compensated compass module.

The TCM5LT combines PNI's patented magneto-inductive sensors with a 3-axis MEMS accelerometer in a single temperature- and noise-stabilized ASIC that's inherently free of offset drift. And using its included hard- and soft-iron correction algorithms, the TCM5LT calibrates out most magnetic anomalies for repeatable, high-resolution measurement across a wide range of navigation and tracking applications.

3-AXIS MEASUREMENT

3D ORIENTATION

HARD-IRON CORRECTION

HIGH-RESOLUTION/ACCURACY

INTEGRATED PROCESSOR

MODULE

SOFT IRON CORRECTION

### Purchase Options

**TCM 5LT**  
Module only

**\$1,849.00**



### Product Information

[Specifications](#)

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### Flexible Mounting Options

Horizontal or vertical

### Hard and Soft Iron Calibration

Customizable by user

### High Resolution

Compass heading 0.1°

### High Tilt Repeatability

0.05°

### Low Power

7.2 to 11.5 mA typical draw;  
85 to 220 µA in sleep mode

### Wide Temperature Range

-40 to 85 °C (operational)

### Compact Size

3.33 × 3.1 × 1.35 cm

### RoHS Compliant

### Full Tilt Compensation

± 90° pitch; ± 180° roll

### High Precision

Heading accuracy 0.3°

### High Resolution Field Measurement

0.05 µT (0.0005 Gauss)

### Instant Startup

40 to 70 ms from power down for valid  
measurement;  
10 to 25 ms from power down to power up ackn

### Ultra-Compact Size

3.3 × 3.1 × 1.3 cm

### Wide Field Measurement Range

± 80 µT (± 0.8 Gauss)

### Binary Digital Interface

LVC MOS (UART)

### Digital Interface

Binary

### Heading Specifications

Accuracy (RMS)	0.5° (Tilt > 70°) 0.3° (Tilt < 70°)
Max Dip Angle	85°
Repeatability (RMS) <sup>1</sup>	0.05°
Resolution	0.1°

### Magnetometer Specifications

Calibrated Field Measurement Range	± 80 µT
Magnetic Repeatability	± 0.1 µT

Magnetic Resolution	± 0.05 µT
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**Tilt Specifications**

Pitch Accuracy	0.2° RMS
Roll Accuracy (RMS)	0.2° (Pitch < 65°) 0.5° (Pitch < 80°) 1.0° (Pitch < 86°)
Tilt Range	± 90° Pitch ± 180° Roll
Tilt Repeatability <sup>2</sup>	0.1°
Tilt Resolution	0.1°

**Calibration**

Hard Iron Calibration	Yes
Soft Iron Calibration	Yes

**Mechanical Specifications**

Connector for RS-232 Interface	4-Pin
Dimensions (L × W × H)	3.3 × 3.1 × 1.3 cm
Mounting Options	Screw Mounts/Standoffs Horizontal
Weight	10 grams

**I/O Specifications**

Communication Rate	300 to 115200 baud
Latency from Power-On	≤ 25 ms
Latency from Sleep Mode	≤ 70 ms valid measure
Maximum Sample Rate	20 samples/sec
Output Formats	Binary High Performance Protocol

**Power Specifications**

Idle Mode	7.2 mA RMS (push mode) 11.5 mA RMS (poll mode)
Sleep Mode Current Draw	85 to 220 µA
Supply Voltage (VDC)	3.6 to 5 V (Unregulated)
Typical Current Draw (Continuous Output)	Maximum: 22 mA Typical: < 20 mA

**Environmental Specifications**

Humidity	Non-condensing / Qualified to MIL-STD-810F
Operating Temperature Range	-40 to 85 °C
Shock	2500 g, per MIL-STD-810F
Storage Temperature Range	-40 to 125 °C
Vibration	Qualified to MIL-STD-810F

<sup>1</sup> Repeatability is based on statistical data at ± 3 sigma limit about the mean.

<sup>2</sup> Repeatability is based on statistical data at ± 3 sigma limit about the mean.